Confusion Matrixes for Point Method NDVI Models

0

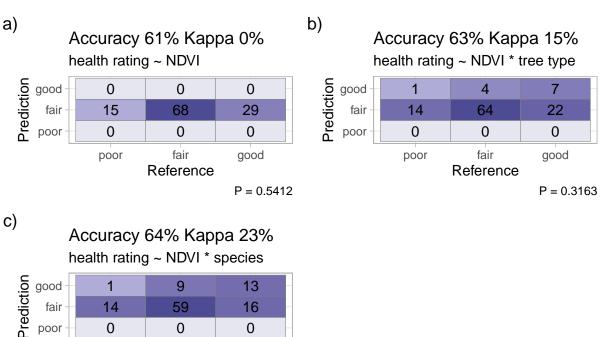
poor

poor -

0

fair

Reference



$$P = 0.2504$$

0

good