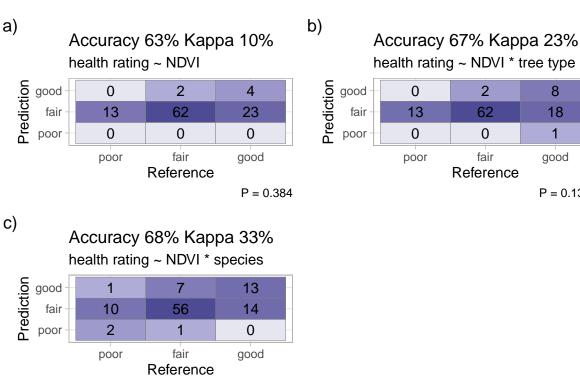
## LiDAR method



P = 0.09396

8

18

good

P = 0.1334