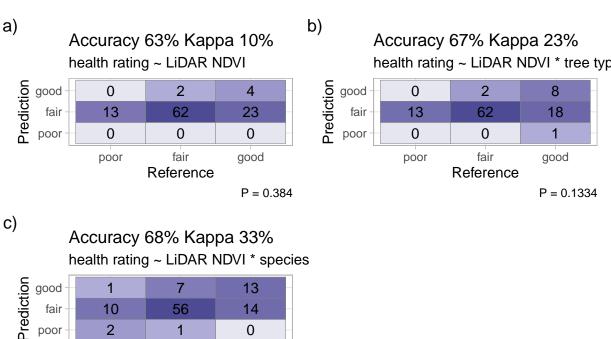
## Confusion Matrixes for LiDAR Method NDVI Models



$$P = 0.09396$$

good

fair

Reference

poor