

# A Linear-Time Kernel Goodness-of-Fit Test

Wittawat Jitkrittum<sup>1</sup>

Wenkai Xu<sup>1</sup>

Zoltán Szabó<sup>2</sup>

Kenji Fukumizu<sup>3</sup>

Arthur Gretton<sup>1</sup>



wittawat@gatsby.ucl.ac.uk

<sup>1</sup>Gatsby Unit, University College London

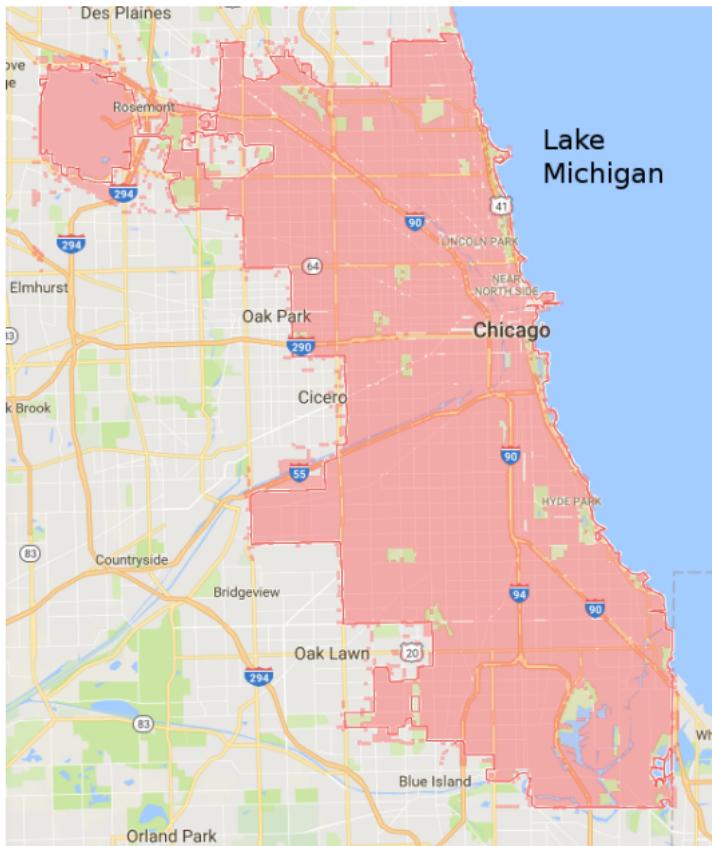
<sup>2</sup>CMAP, École Polytechnique

<sup>3</sup>The Institute of Statistical Mathematics, Tokyo

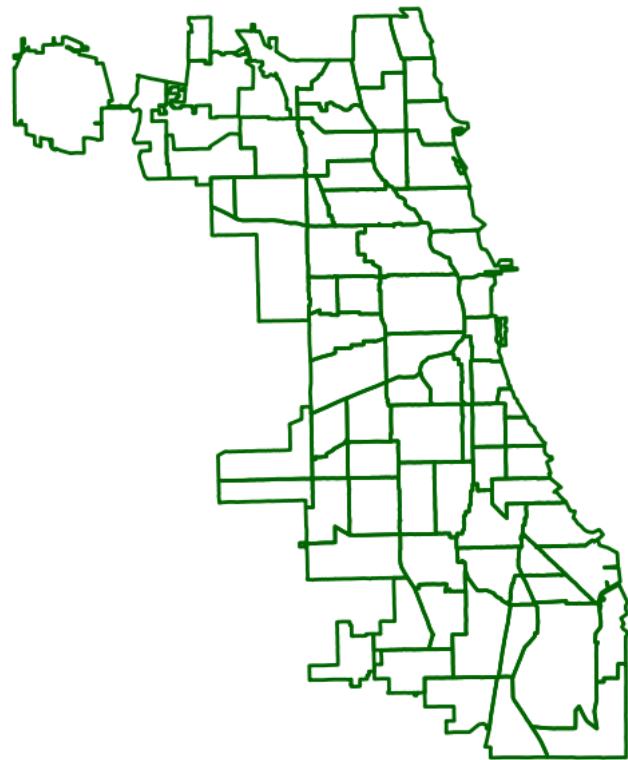
NIPS 2017, Long Beach

5 December 2017

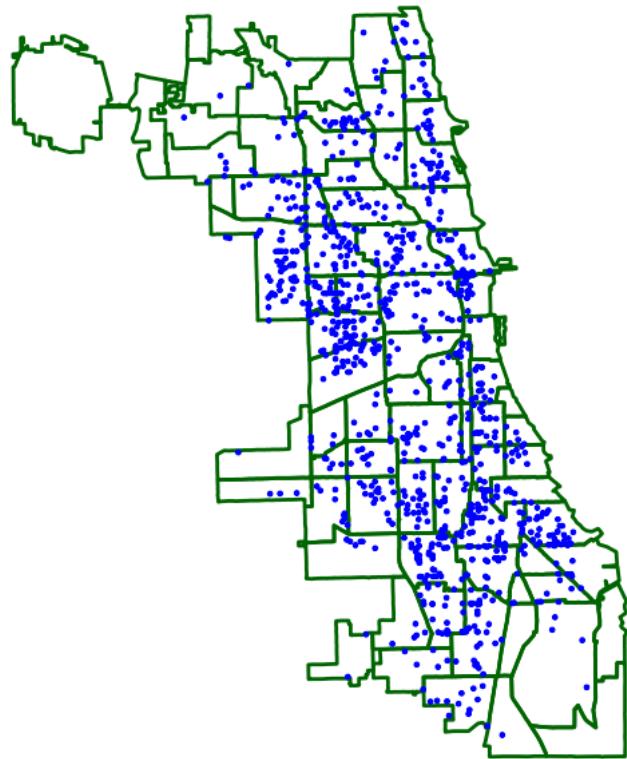
# Model Criticism



## Model Criticism

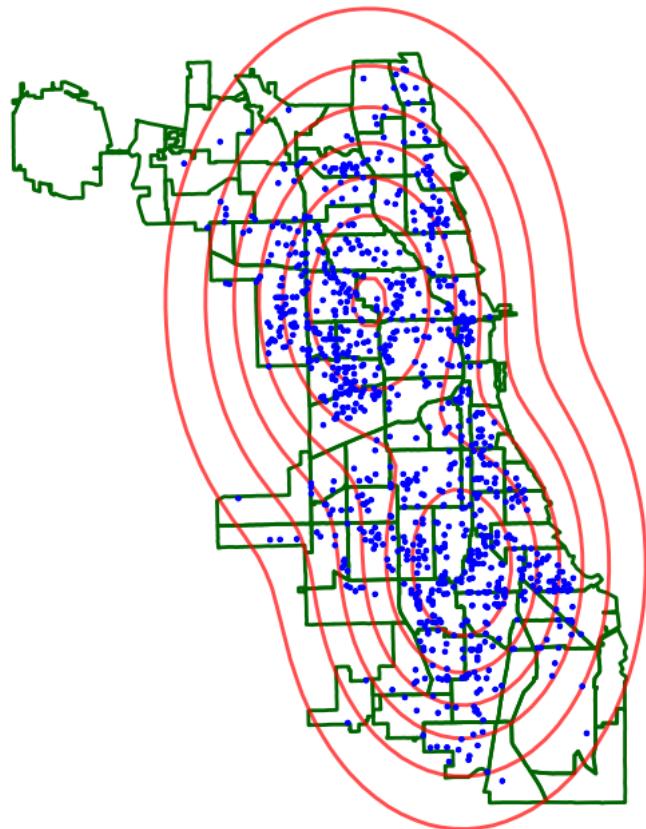


## Model Criticism



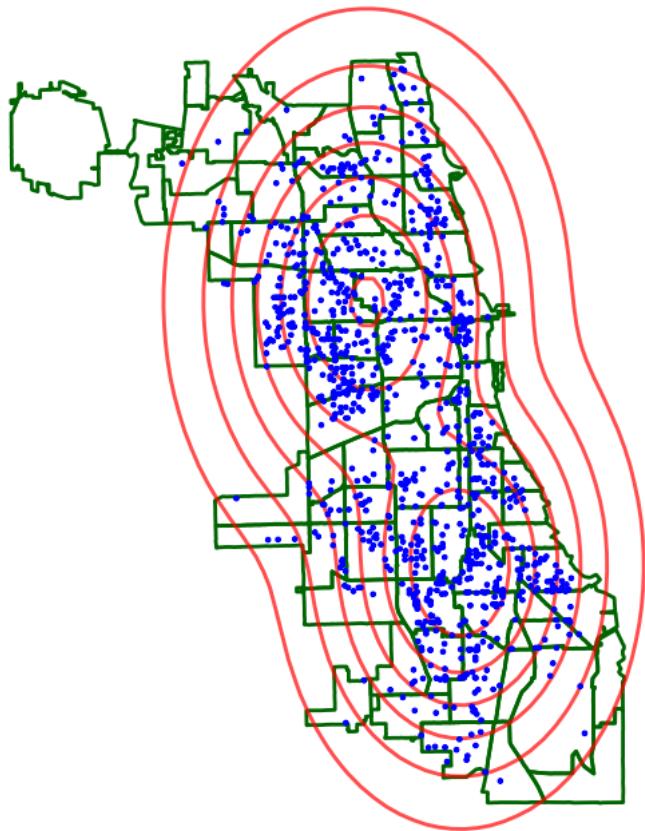
Data = robbery events in Chicago in 2016.

## Model Criticism



Is this a good **model**?

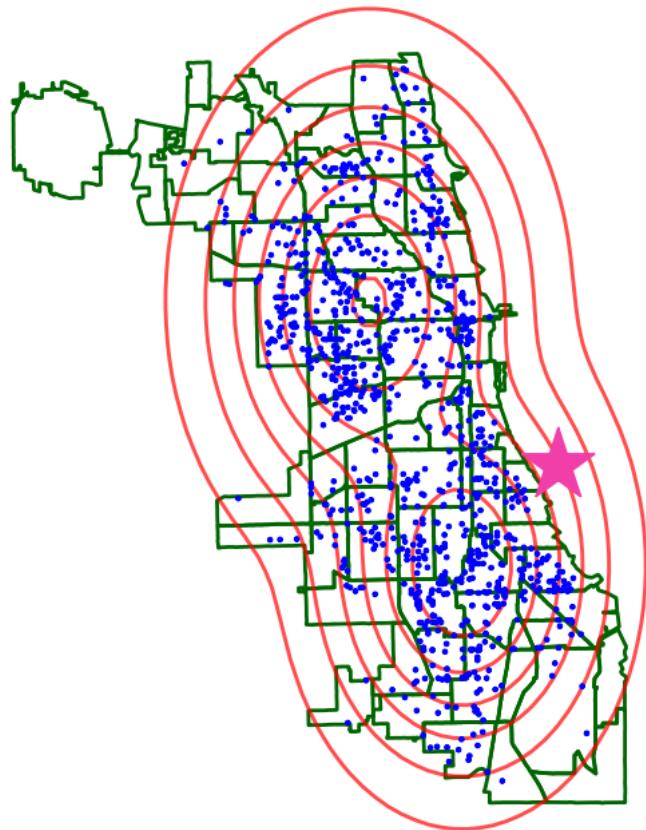
## Model Criticism



### Goals:

- 1 Test if a (complicated) **model** fits the **data**.
- 2 If it does not, show a **location** where it fails.

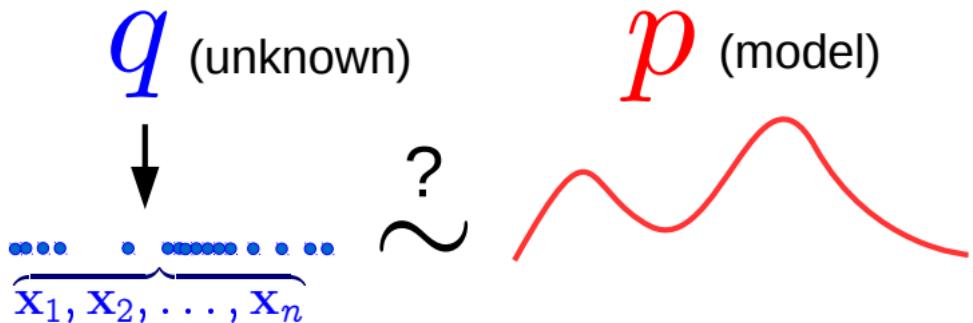
## Model Criticism



### Goals:

- 1 Test if a (complicated) **model** fits the **data**.
- 2 If it does not, show a **location** where it fails.

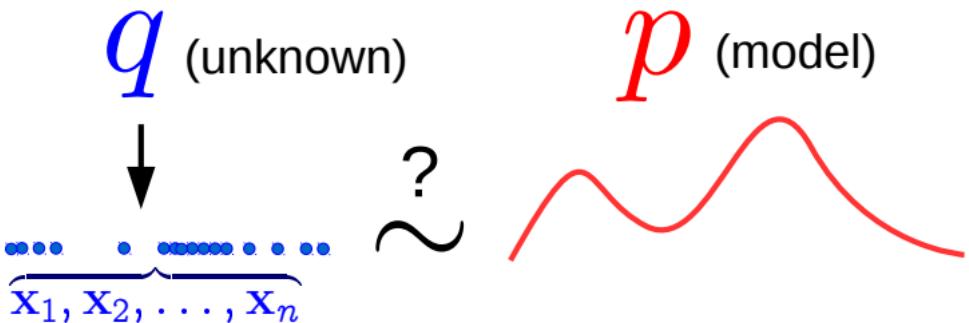
## Problem Setting: Goodness-of-Fit Test



Test goal: Are data from the model  $p$ ?

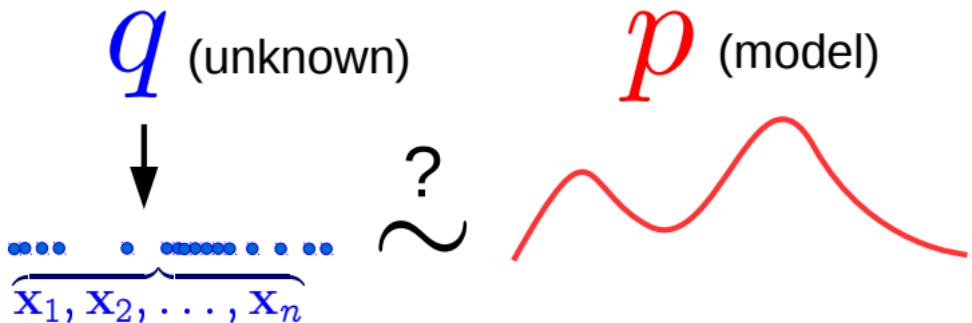
- 1 Nonparametric.
- 2 Linear-time. Runtime is  $\mathcal{O}(n)$ . Fast.
- 3 Interpretable. Model criticism by finding .

## Problem Setting: Goodness-of-Fit Test



Test goal: Are **data** from the **model  $p$** ?

## Problem Setting: Goodness-of-Fit Test



Test goal: Are data from the model  $p$ ?

- 1 Nonparametric.
  - 2 Linear-time. Runtime is  $\mathcal{O}(n)$ . Fast.
  - 3 Interpretable. Model criticism by finding 

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $\mathbf{q}$  and  $\mathbf{p}$  differ most [Jitkrittum et al., 2016].

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[k_{\mathbf{v}}(\mathbf{x})] - \mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\mathbf{v}] - \mathbb{E}_{\mathbf{y} \sim p}[\mathbf{v}]$$

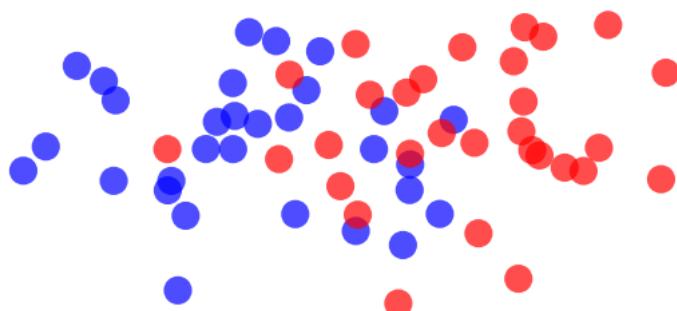
## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].


$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\mathbf{x}] - \mathbb{E}_{\mathbf{y} \sim p}[\mathbf{y}]$$
$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].



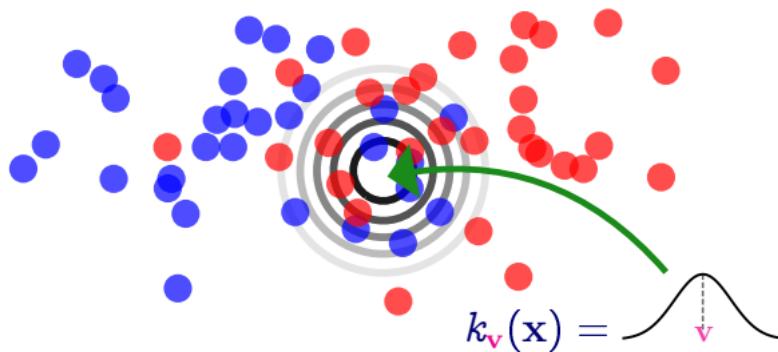
$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\text{bell curve}] - \mathbb{E}_{\mathbf{y} \sim p}[\text{bell curve}]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

score: 0.008



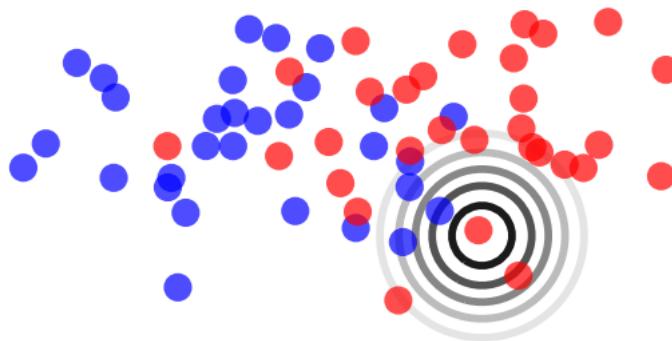
$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\mathbf{x}] - \mathbb{E}_{\mathbf{y} \sim p}[\mathbf{y}]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

score: 1.6



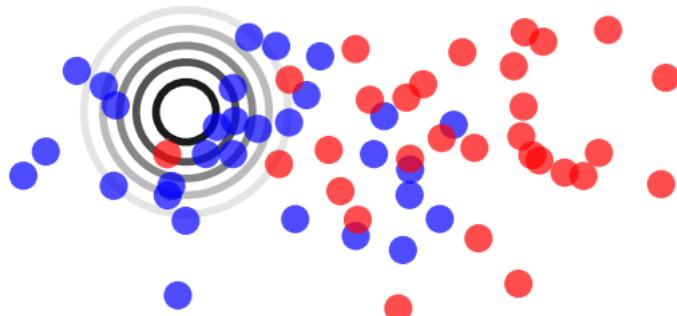
$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\text{PDF}_q(\mathbf{v})] - \mathbb{E}_{\mathbf{y} \sim p}[\text{PDF}_p(\mathbf{v})]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

score: 13



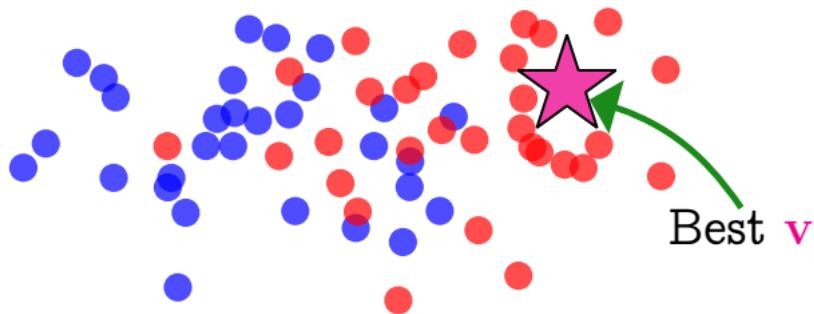
$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\text{wedge function}] - \mathbb{E}_{\mathbf{y} \sim p}[\text{wedge function}]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

score: 25



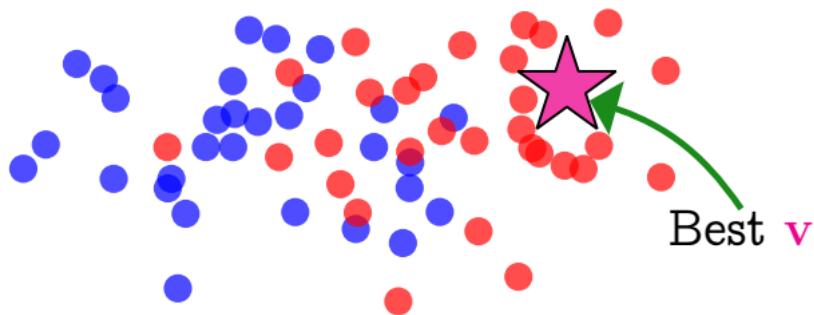
$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\text{peak}_q(\mathbf{v})] - \mathbb{E}_{\mathbf{y} \sim p}[\text{peak}_p(\mathbf{v})]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Model Criticism by Maximum Mean Discrepancy [Gretton et al., 2012]

- Find a location  $\mathbf{v}$  at which  $q$  and  $p$  differ most [Jitkrittum et al., 2016].

score: 25



$$\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\text{peak at } \mathbf{v}] - \mathbb{E}_{\mathbf{y} \sim p}[\text{peak at } \mathbf{v}]$$

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

No sample from  $p$ .  
Difficult to generate.

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\quad T_p k_{\mathbf{v}}(\mathbf{x}) \quad] - \mathbb{E}_{\mathbf{y} \sim p}[\quad T_p k_{\mathbf{v}}(\mathbf{y}) \quad]$$

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[T_p] - \mathbb{E}_{\mathbf{y} \sim p}[T_p]$$


## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q} [$$



$$] - \mathbb{E}_{\mathbf{y} \sim p} [$$



## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

(Stein) witness( $\mathbf{v}$ ) =  $\mathbb{E}_{\mathbf{x} \sim q}[$



Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

(Stein) witness( $\mathbf{v}$ ) =  $\mathbb{E}_{\mathbf{x} \sim q}[$



Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[\quad T_p k_{\mathbf{v}}(\mathbf{x}) \quad]$$

Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q} [ T_p k_{\mathbf{v}}(\mathbf{x}) ]$$

Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

Proposal: Good  $\mathbf{v}$  should have high

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[T_p k_{\mathbf{v}}(\mathbf{x})]$$

Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

Proposal: Good  $\mathbf{v}$  should have high

signal-to-noise  
ratio

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## The Stein Witness Function [Liu et al., 2016, Chwialkowski et al., 2016]

Problem: No sample from  $p$ . Cannot estimate  $\mathbb{E}_{\mathbf{y} \sim p}[k_{\mathbf{v}}(\mathbf{y})]$ .

$$(\text{Stein}) \text{ witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}[T_p k_{\mathbf{v}}(\mathbf{x})]$$

Idea: Define  $T_p$  such that  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ , for any  $\mathbf{v}$ .

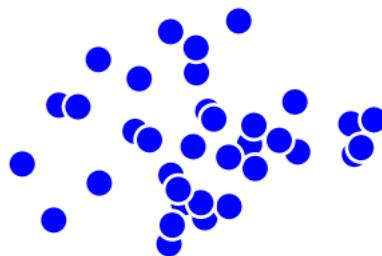
Proposal: Good  $\mathbf{v}$  should have high

signal-to-noise  
ratio

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

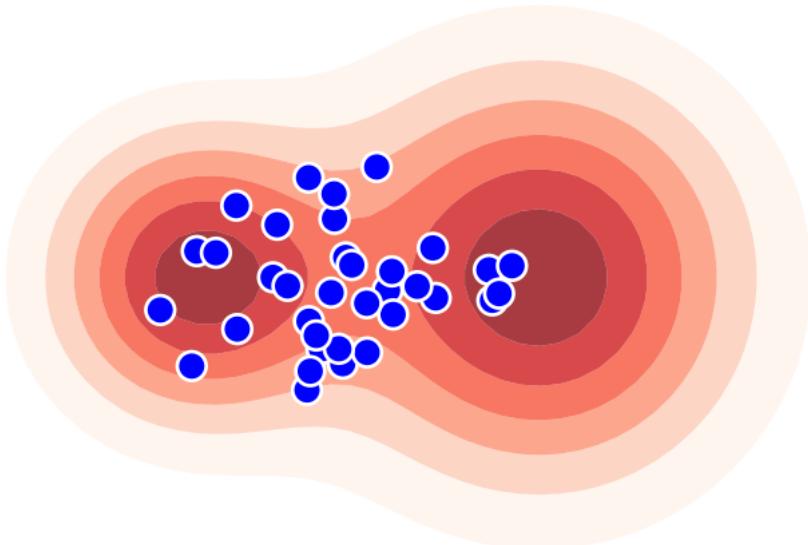
- $\text{witness}(\mathbf{v})$  and  $\text{standard deviation}(\mathbf{v})$  can be estimated in linear-time.

## Proposal: Model Criticism with the Stein Witness



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

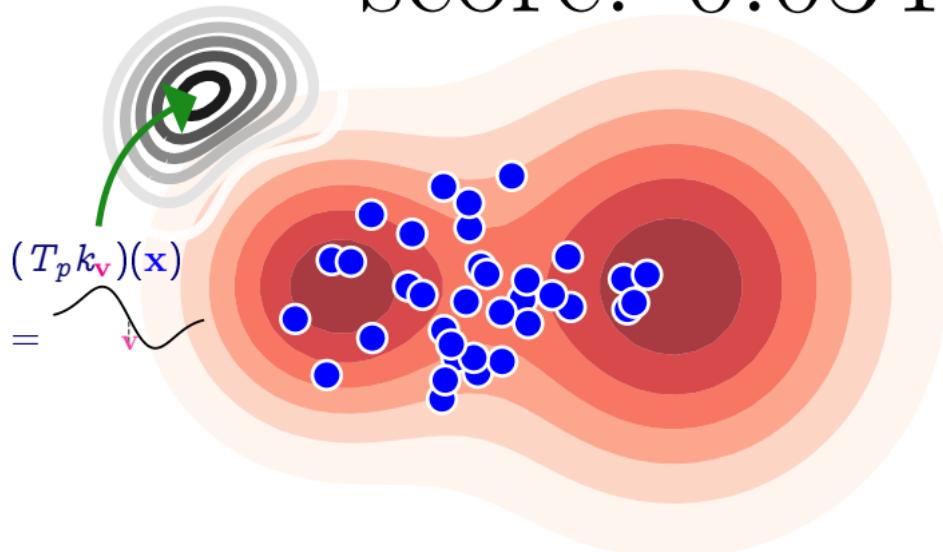
## Proposal: Model Criticism with the Stein Witness



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

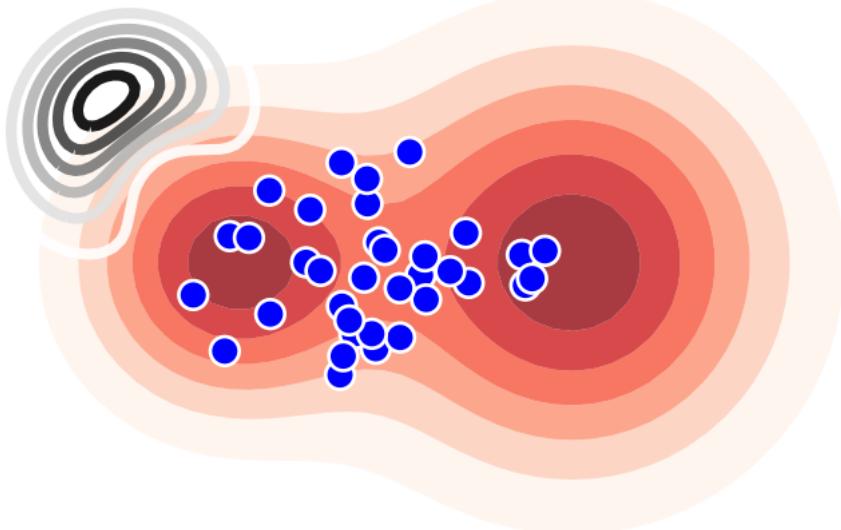
score: 0.034



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

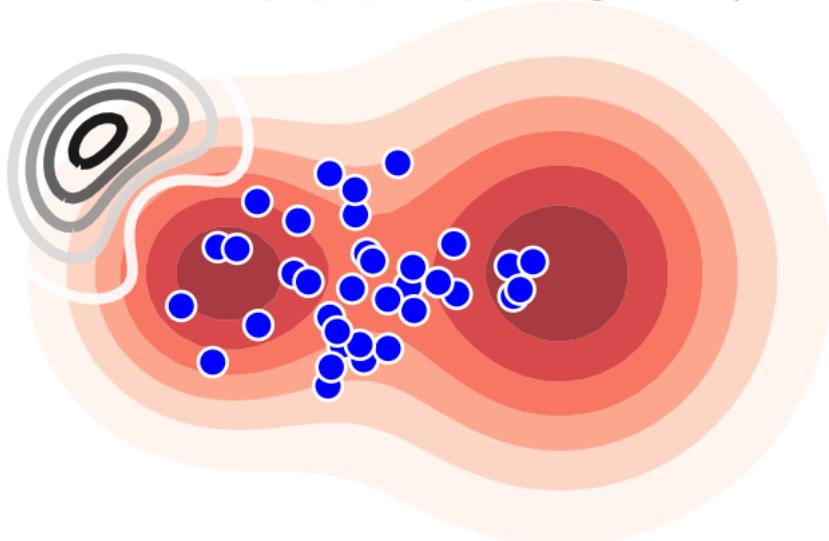
score: 0.089



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

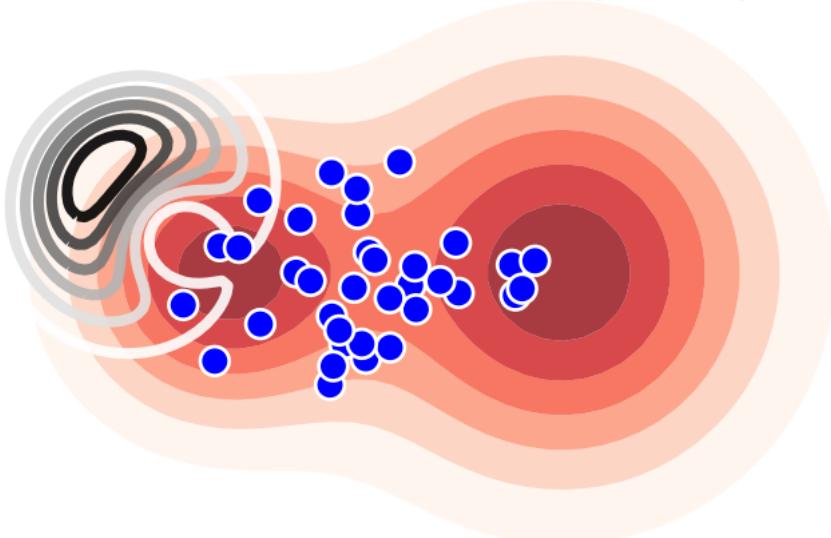
score: 0.17



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

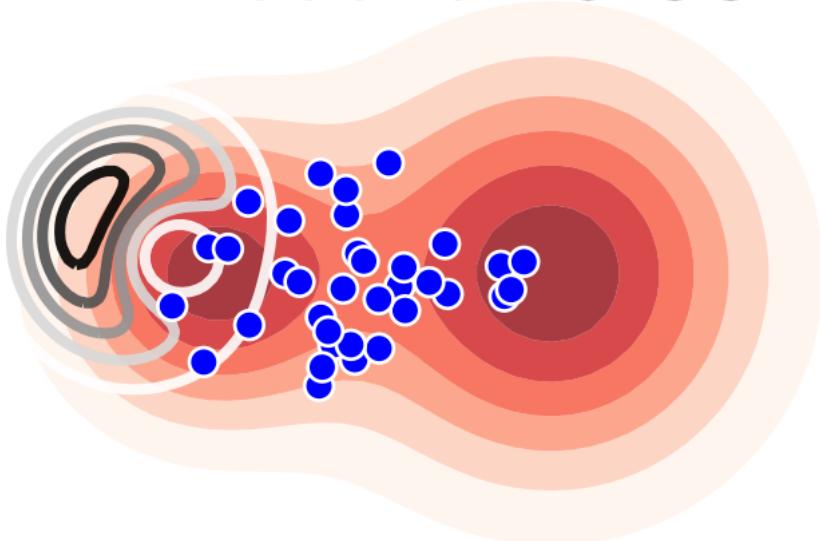
score: 0.26



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

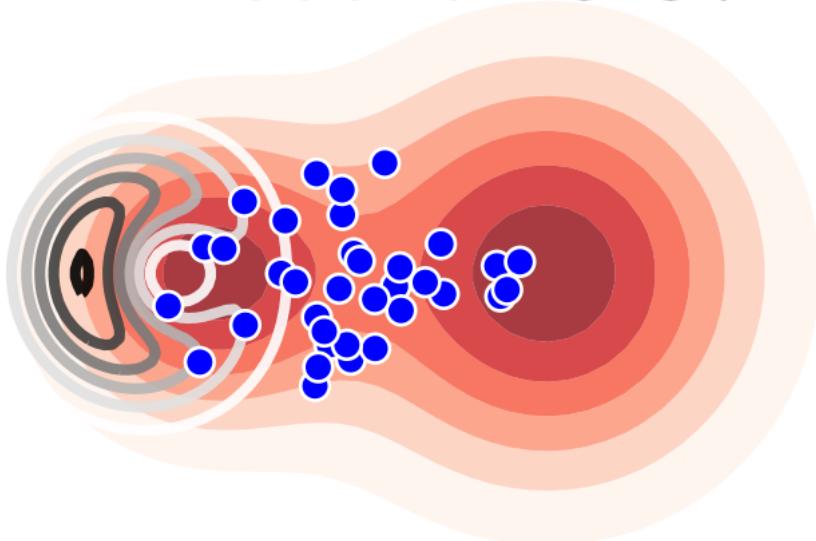
score: 0.33



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

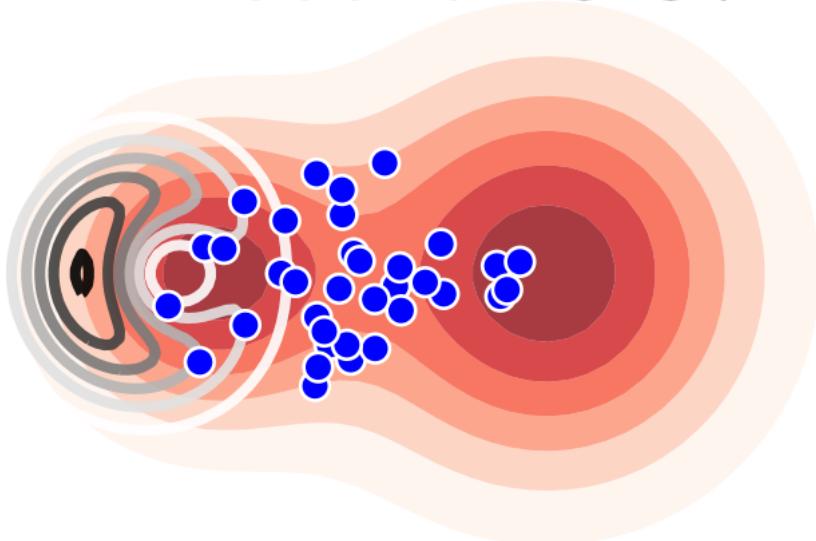
score: 0.37



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

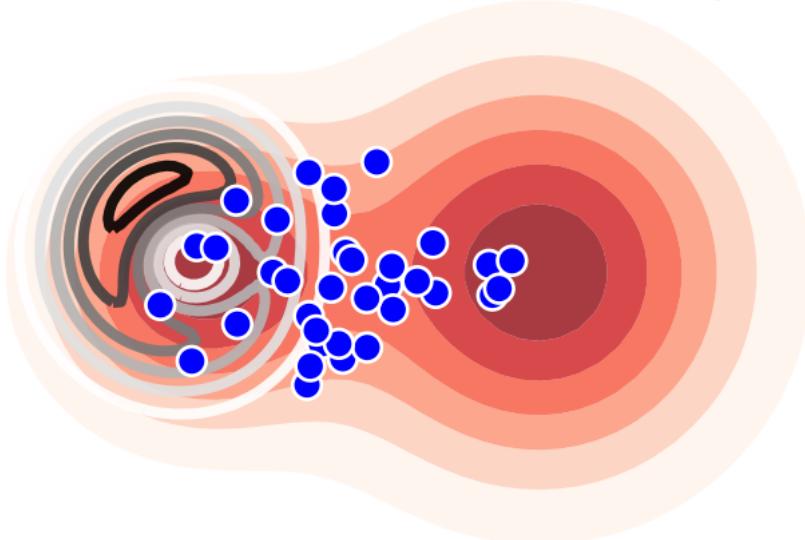
score: 0.37



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

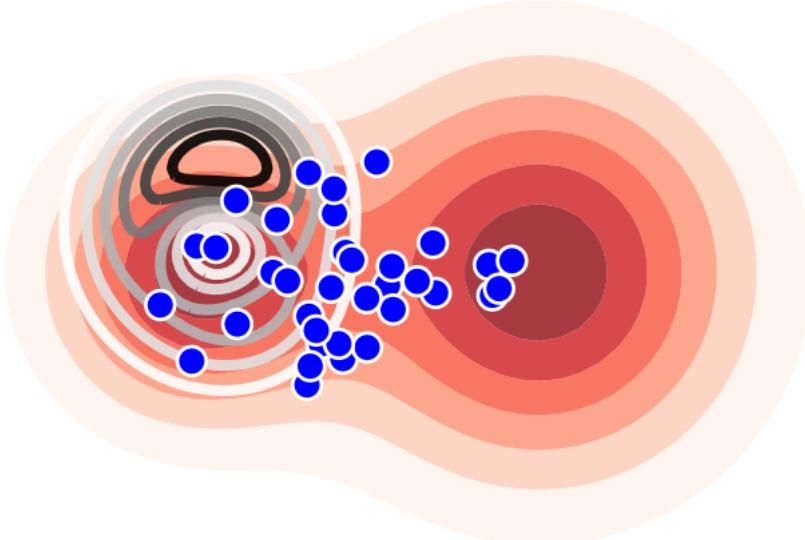
score: 0.45



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

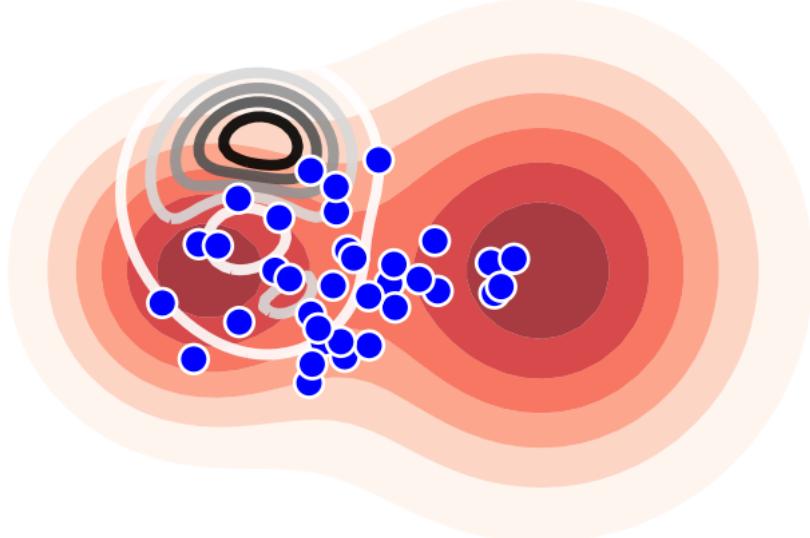
score: 0.44



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

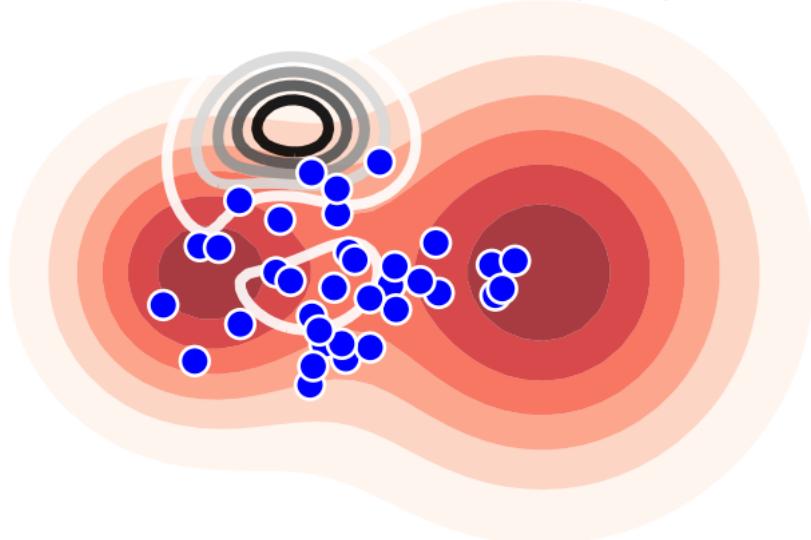
score: 0.39



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

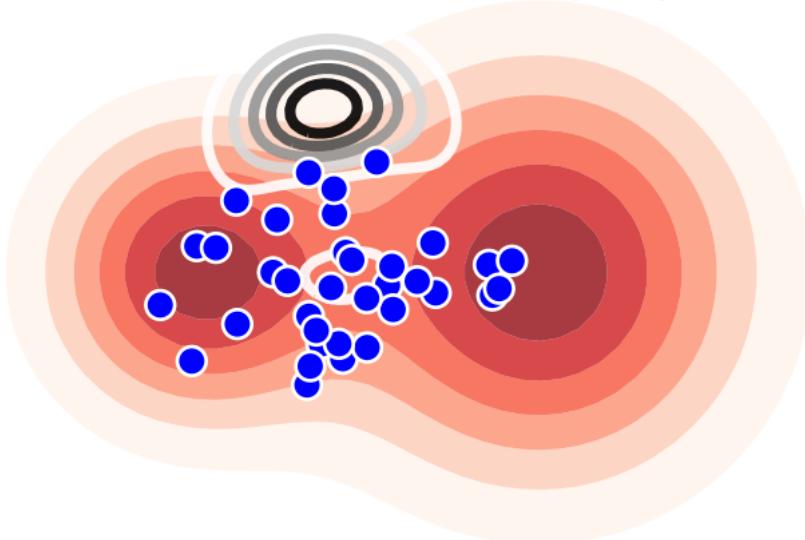
score: 0.31



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

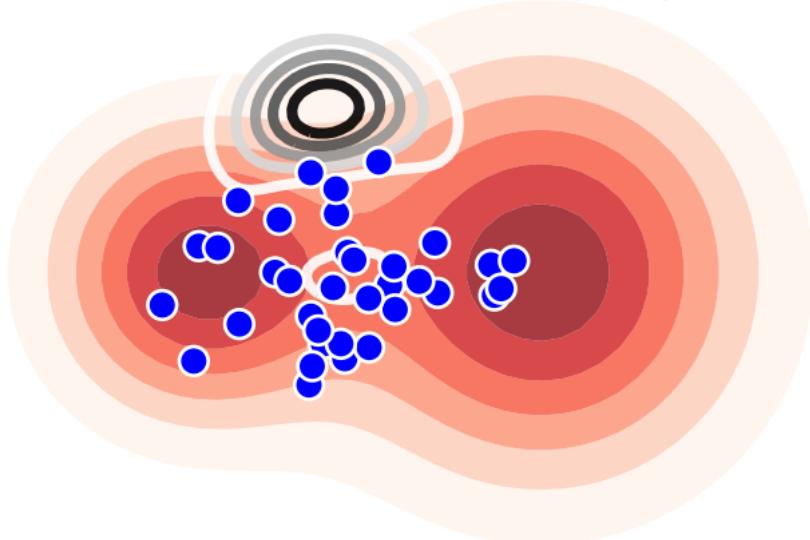
score: 0.32



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

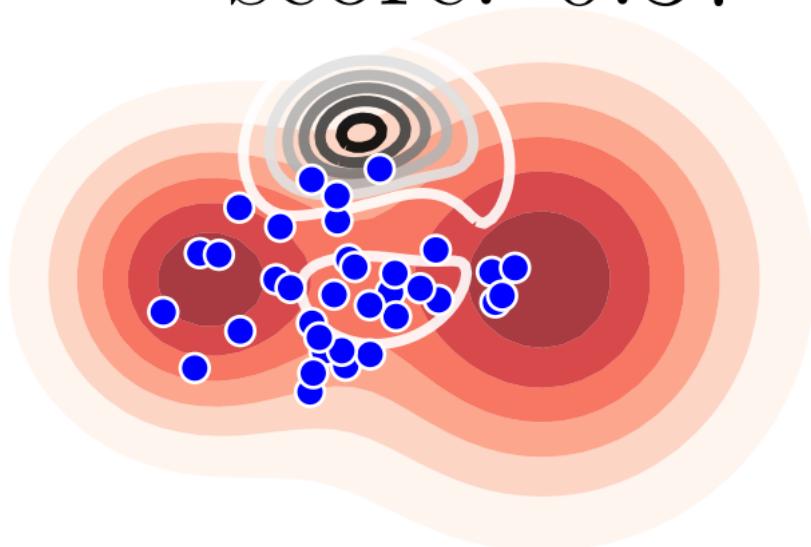
score: 0.32



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

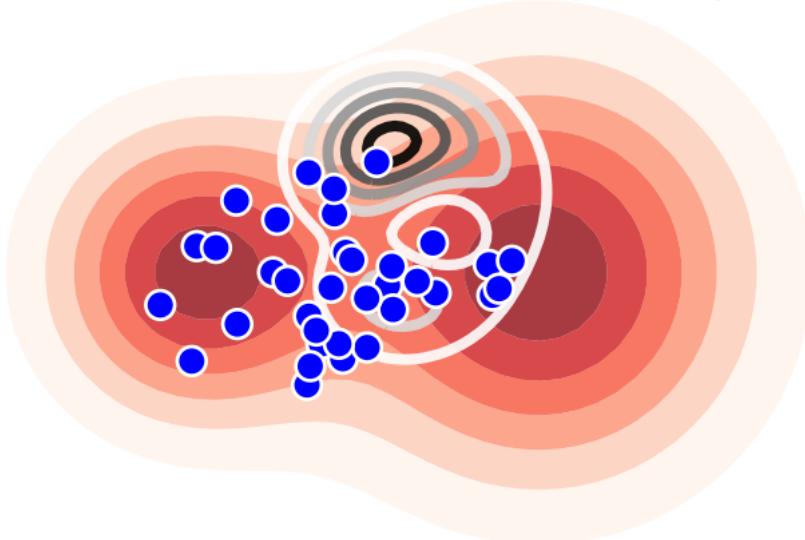
score: 0.37



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

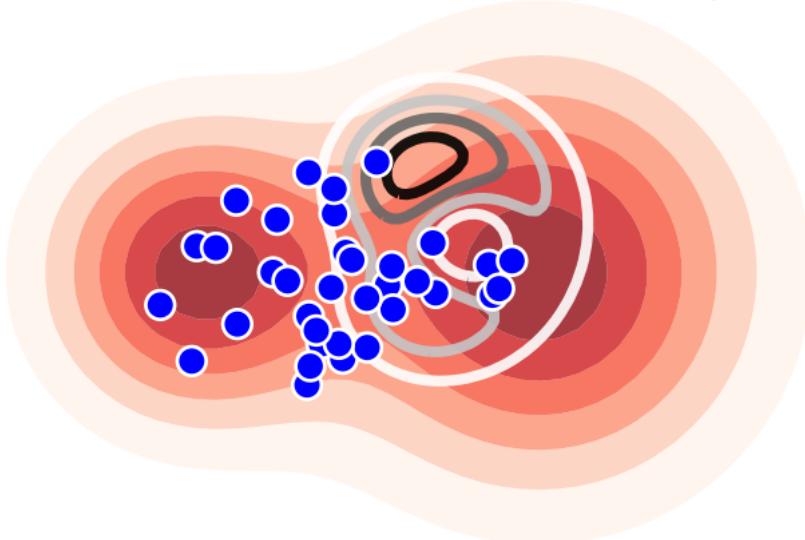
score: 0.48



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

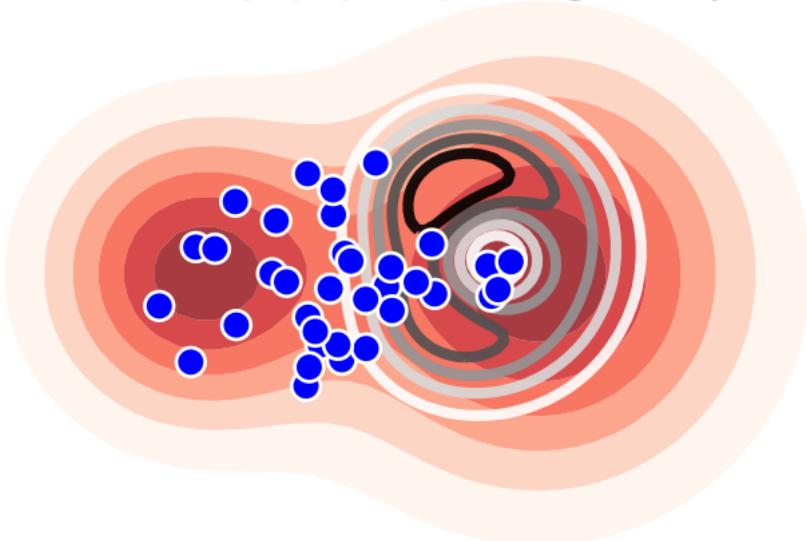
score: 0.49



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

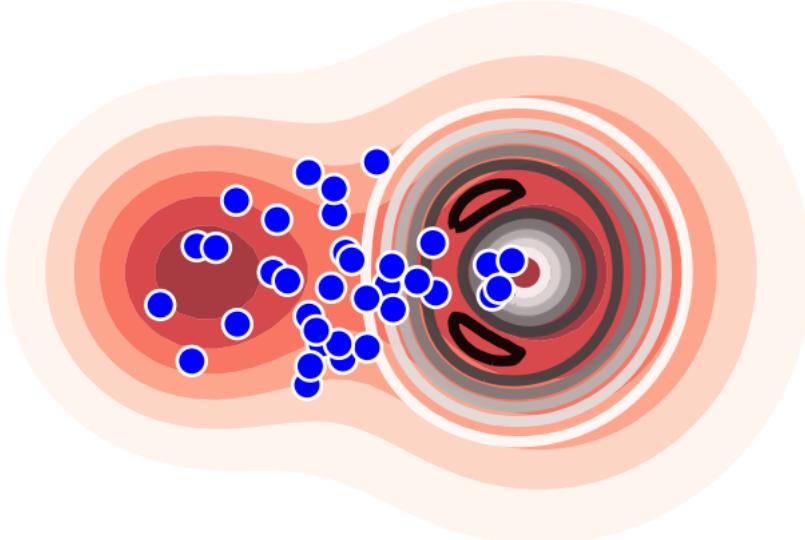
score: 0.47



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

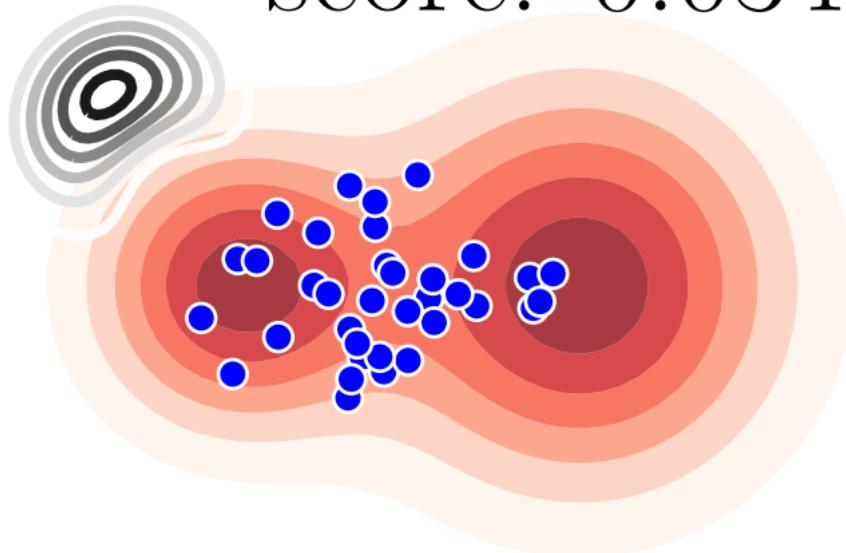
score: 0.44



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

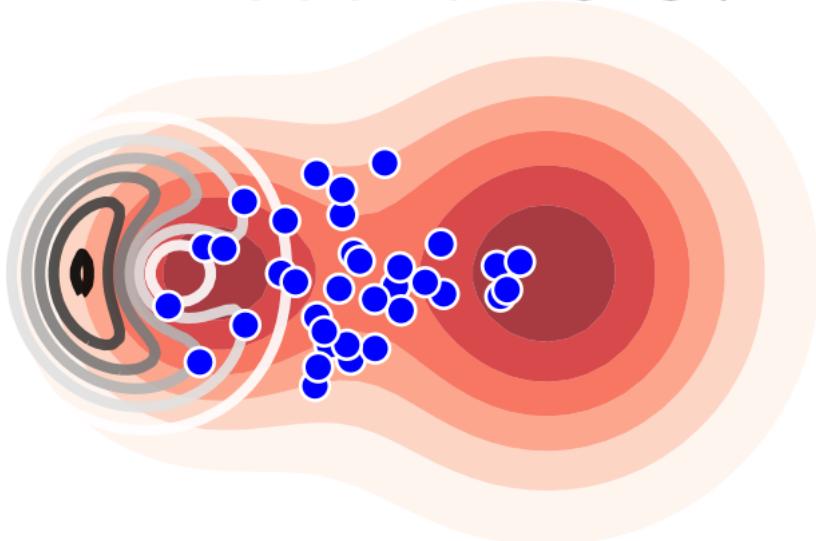
score: 0.034



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

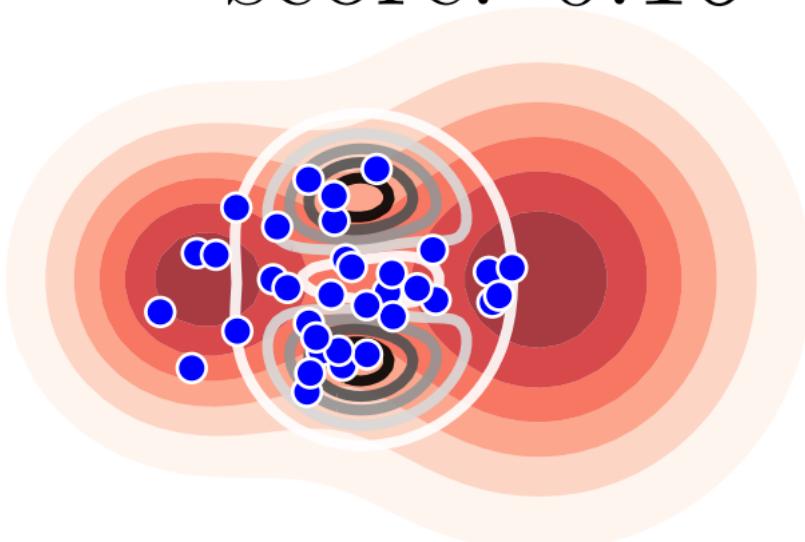
score: 0.37



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

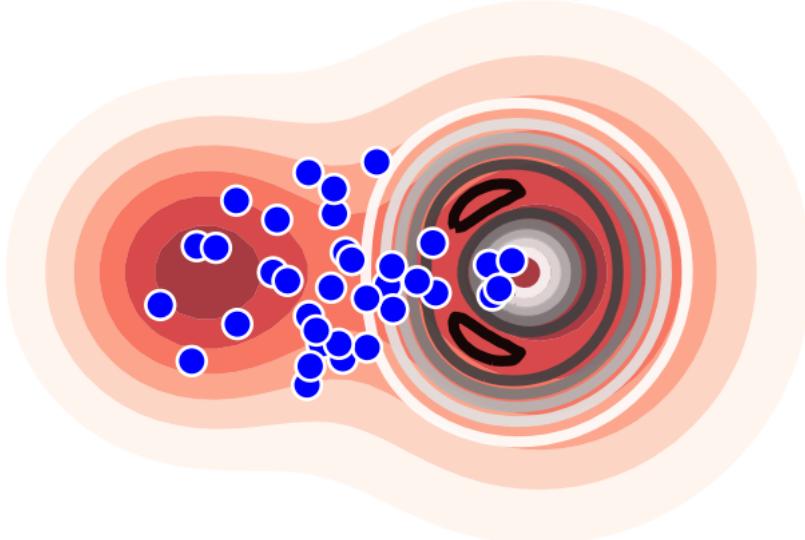
score: 0.16



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## Proposal: Model Criticism with the Stein Witness

score: 0.44



$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{standard deviation}(\mathbf{v})}.$$

## What is $T_p k_{\mathbf{v}}$ ?

Recall  $\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}(T_p k_{\mathbf{v}})(\mathbf{x}) - \mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y})$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)].$$

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

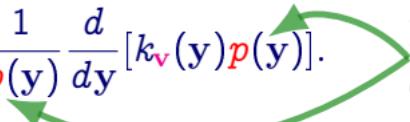
[Liu et al., 2016, Chwialkowski et al., 2016]

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)].$$

Normalizer  
cancels



Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

## Technical Details

---

**Theorem:** Maximizing

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{uncertainty}(\mathbf{v})}$$

- increases true positive rate  
 $= \mathbb{P}(\text{detect difference when } p \neq q),$
  - does not affect false positive rate.
- 
- General form of  $\text{score}(\dots)$  can consider more than one location  $\mathbf{v}$ .

## Technical Details

---

**Theorem:** Maximizing

$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{uncertainty}(\mathbf{v})}$$

- increases true positive rate  
 $= \mathbb{P}(\text{detect difference when } p \neq q),$
  - does not affect false positive rate.
- 

- General form of  $\text{score}(\dots)$  can consider more than one location  $\mathbf{v}$ .

## Technical Details

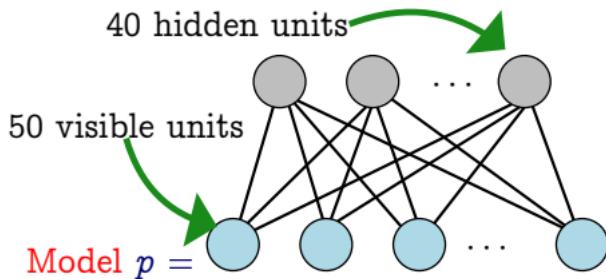
---

**Theorem:** Maximizing

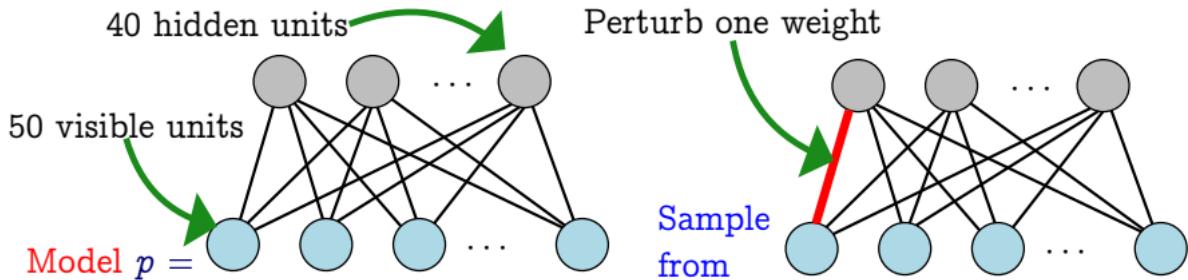
$$\text{score}(\mathbf{v}) = \frac{|\text{witness}(\mathbf{v})|}{\text{uncertainty}(\mathbf{v})}$$

- increases true positive rate  
 $= \mathbb{P}(\text{detect difference when } p \neq q),$
  - does not affect false positive rate.
- 
- General form of  $\text{score}(\dots)$  can consider more than one location  $\mathbf{v}$ .

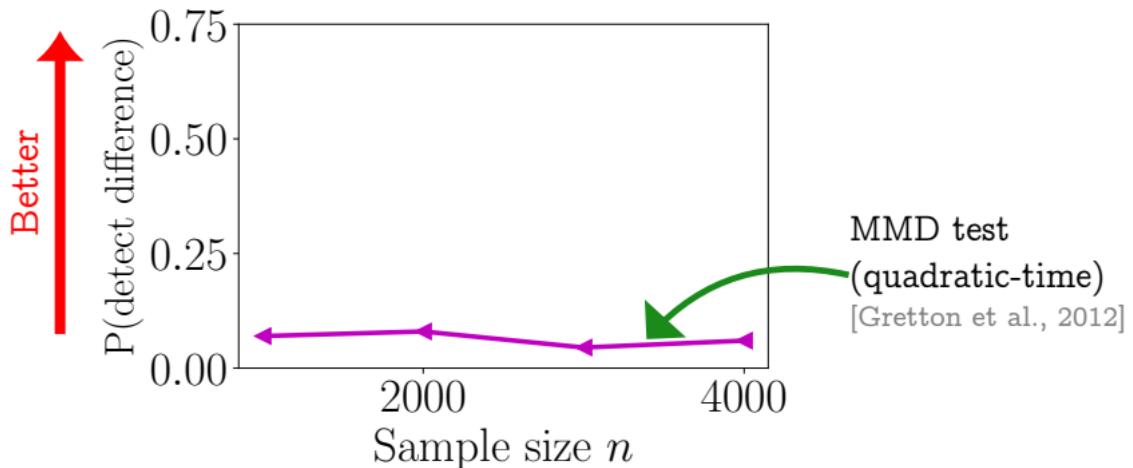
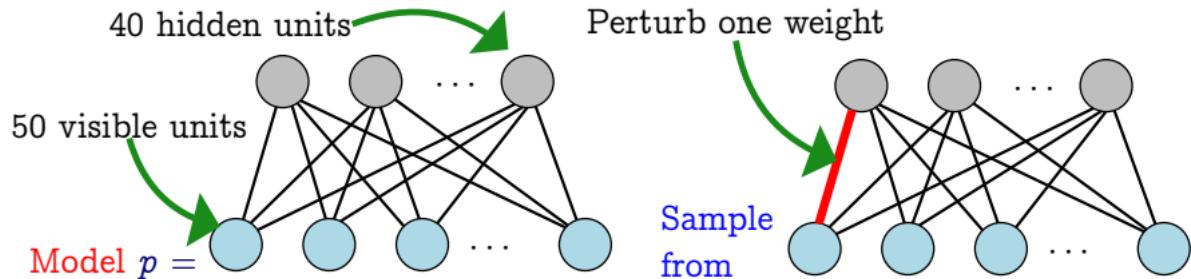
## Experiment: Restricted Boltzmann Machine (RBM)



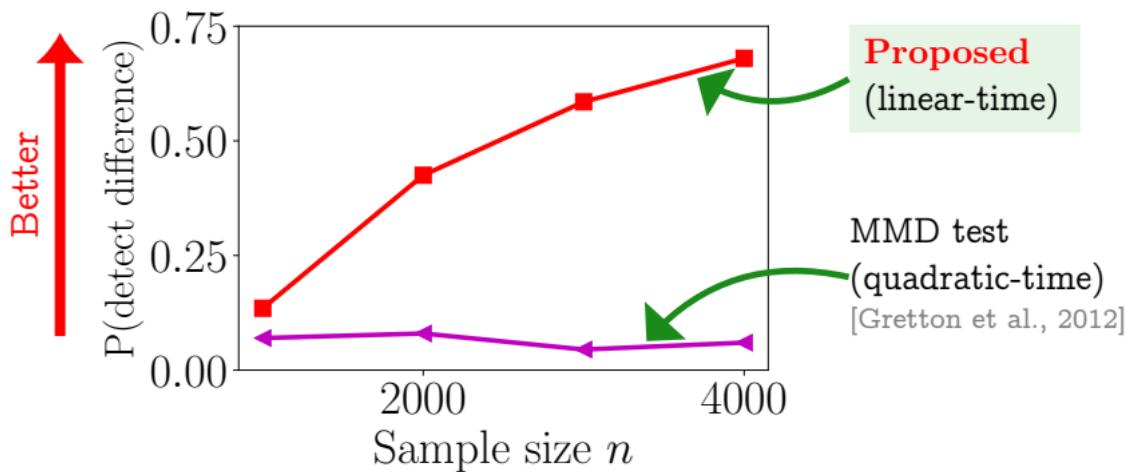
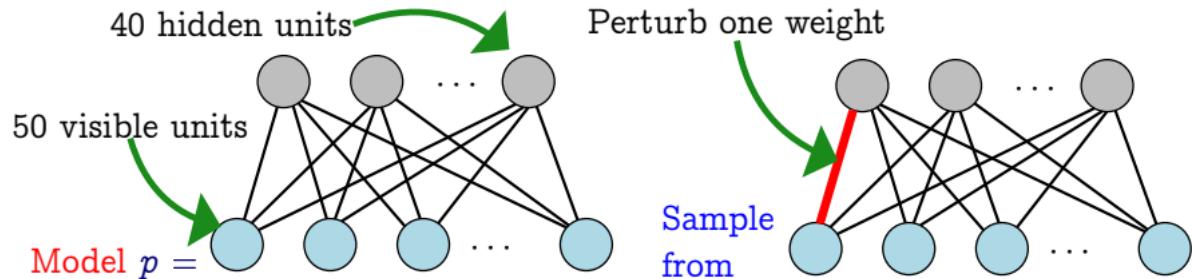
## Experiment: Restricted Boltzmann Machine (RBM)



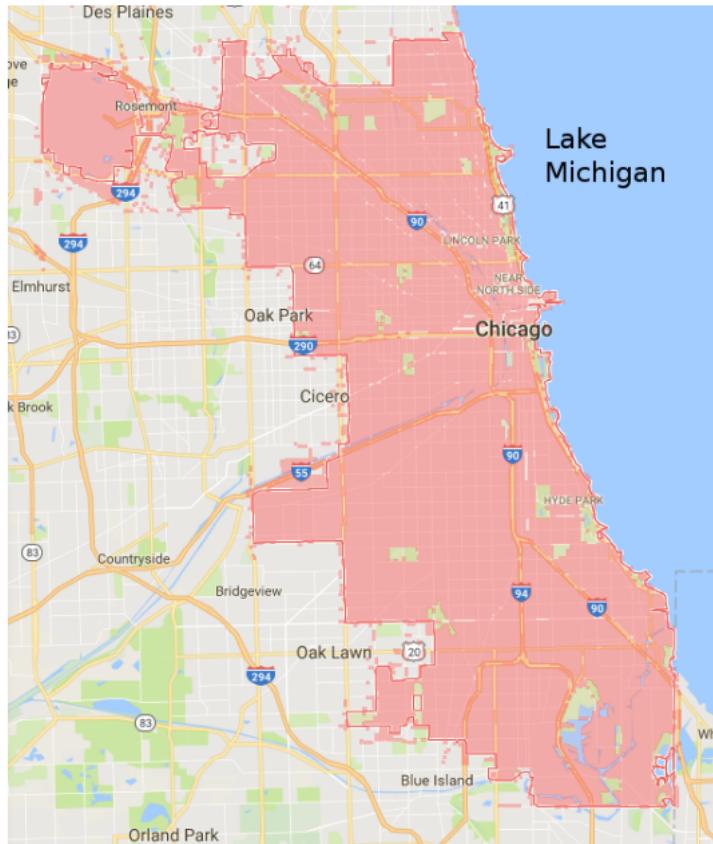
## Experiment: Restricted Boltzmann Machine (RBM)



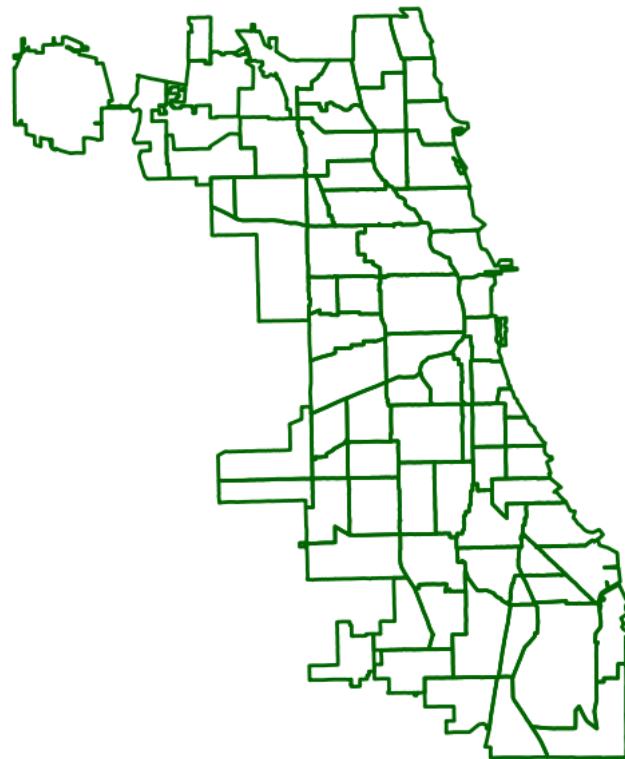
## Experiment: Restricted Boltzmann Machine (RBM)



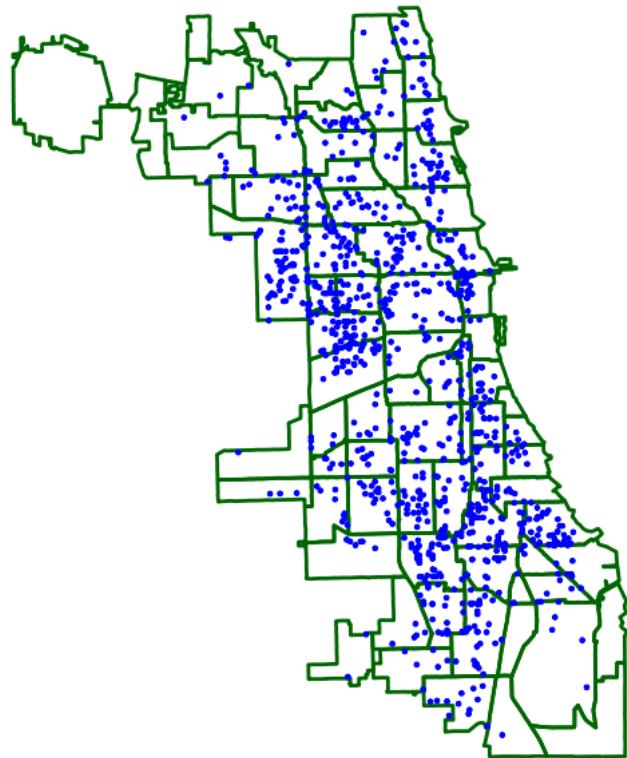
# Interpretable Features: Chicago Crime



## Interpretable Features: Chicago Crime

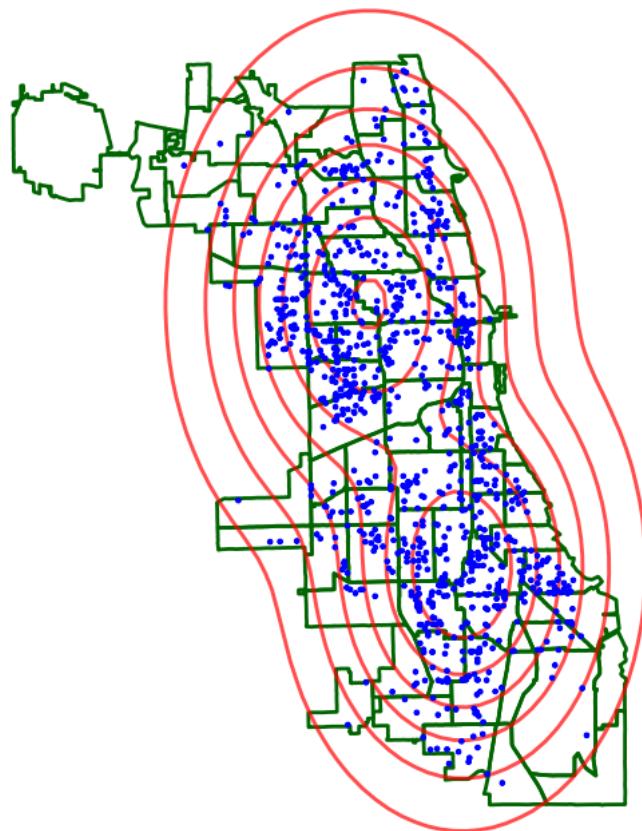


## Interpretable Features: Chicago Crime



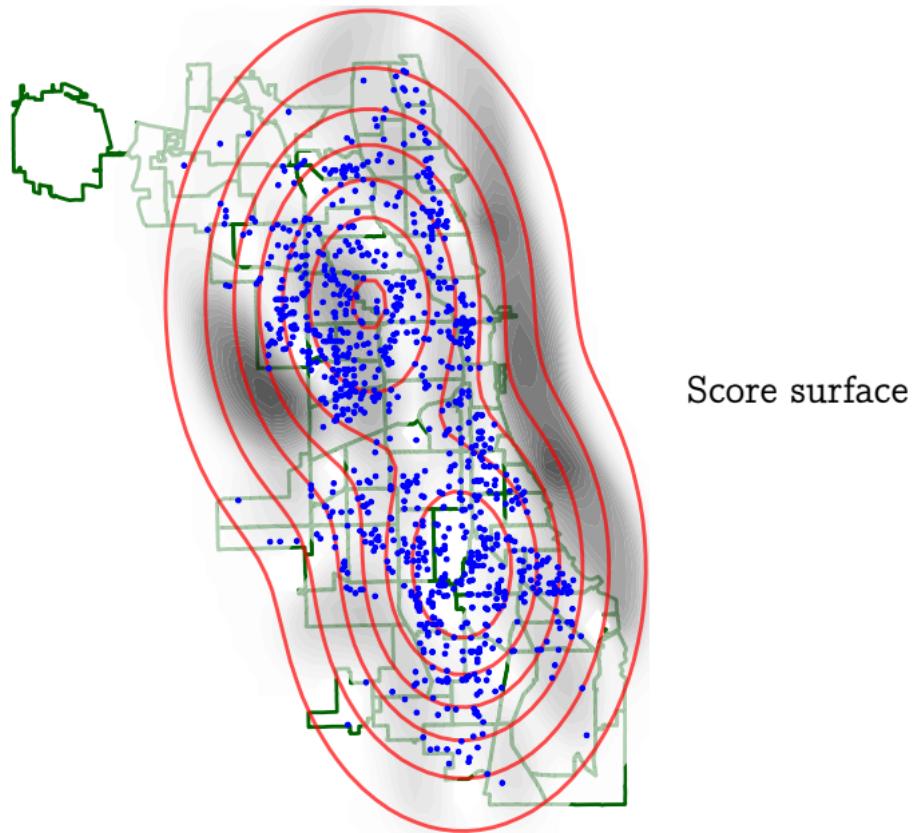
- $n = 11957$  robbery events in Chicago in 2016.
  - lat/long coordinates = sample from  $q$ .
- Model spatial density with Gaussian mixtures.

## Interpretable Features: Chicago Crime



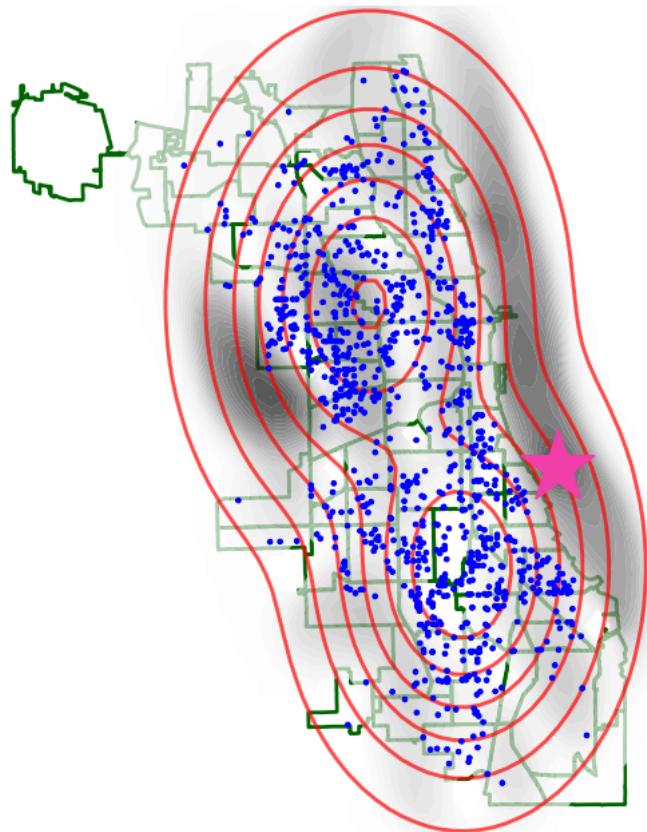
Model  $p$  = 2-component Gaussian mixture.

## Interpretable Features: Chicago Crime



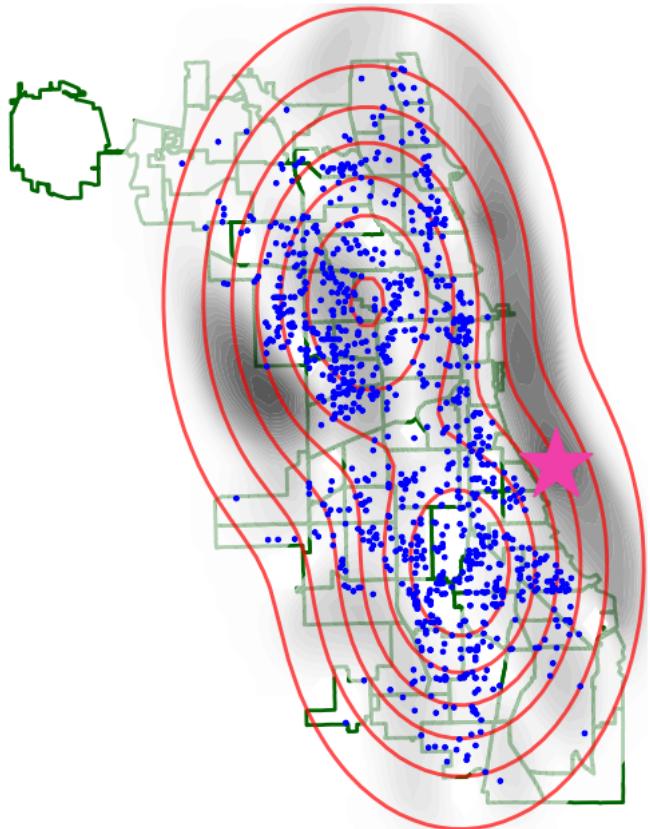
Score surface

## Interpretable Features: Chicago Crime



★ = optimized  $v$ .

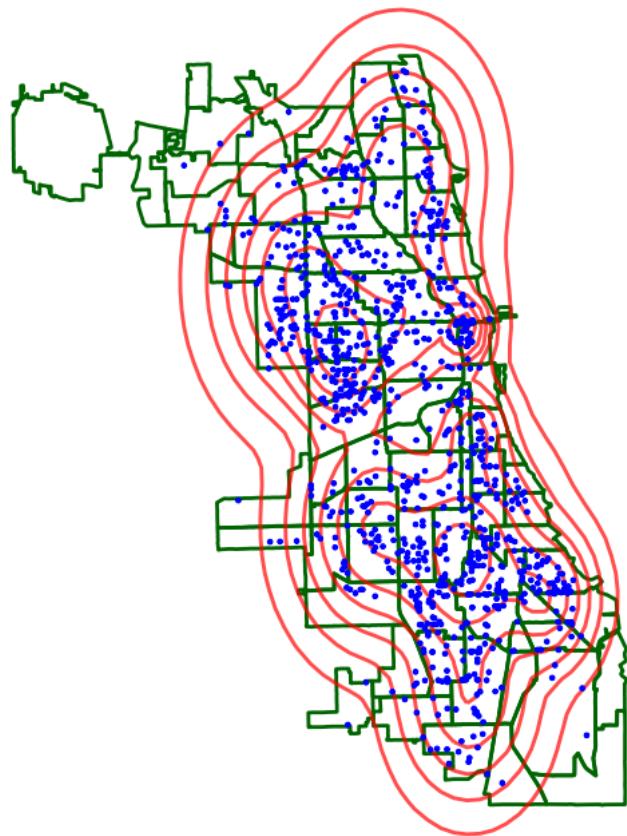
## Interpretable Features: Chicago Crime



★ = optimized v.  
No robbery in Lake Michigan.

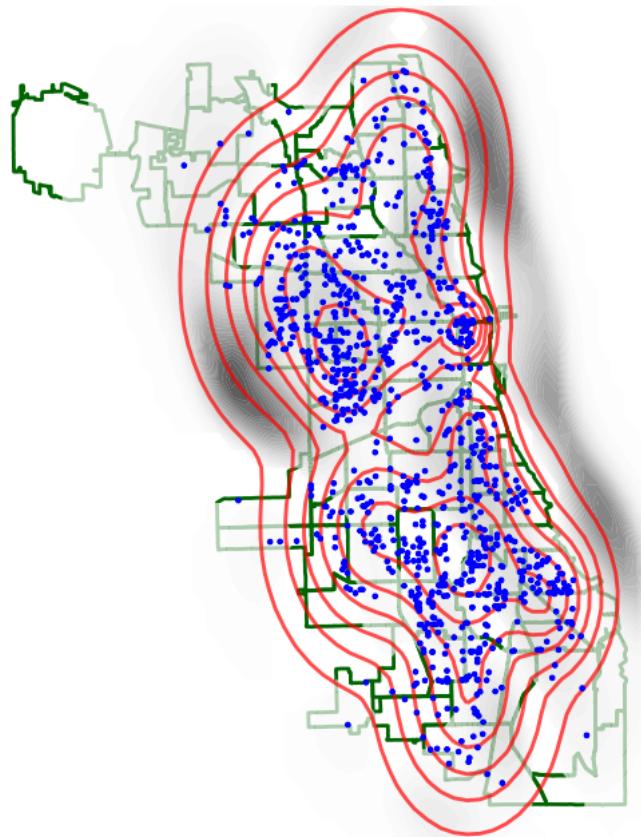


## Interpretable Features: Chicago Crime



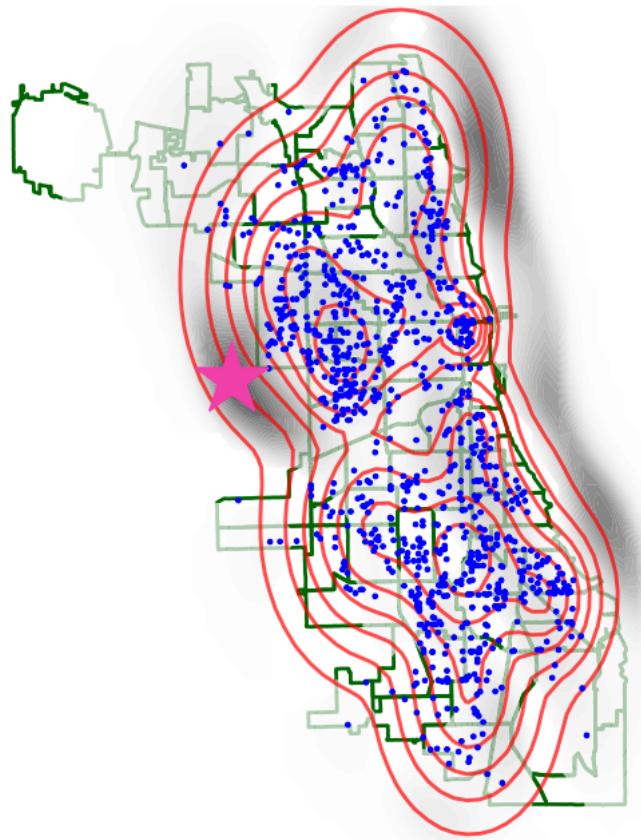
Model  $p = 10$ -component Gaussian mixture.

## Interpretable Features: Chicago Crime



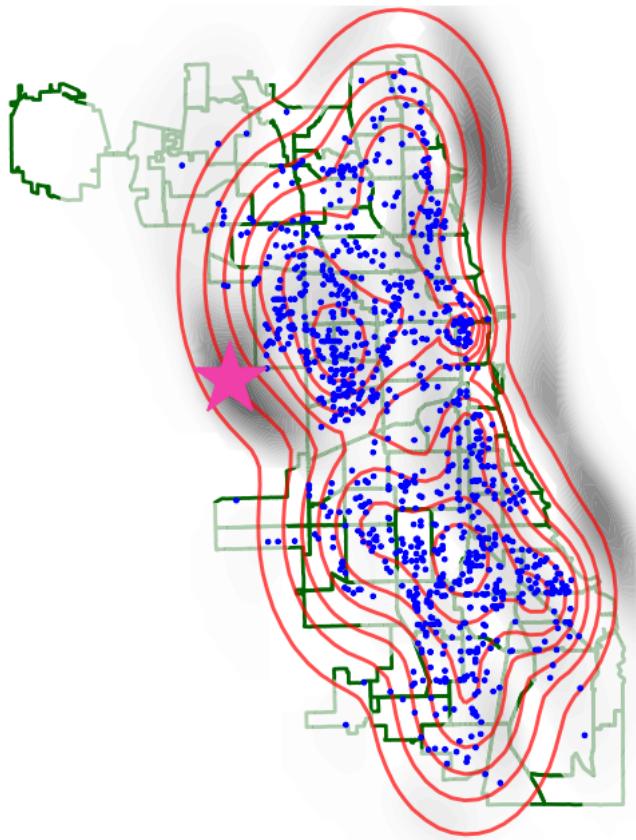
Capture the right tail better.

## Interpretable Features: Chicago Crime



Still, does not capture the left tail.

## Interpretable Features: Chicago Crime



Still, does not capture the left tail.

Learned test locations are interpretable.

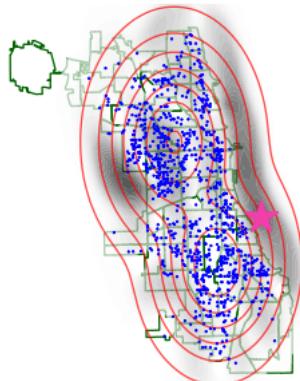
## Conclusions

Proposed a new goodness-of-fit test.

- 1 Nonparametric. Normalizer not needed.
- 2 Linear-time
- 3 Interpretable

**Poster #57** at Pacific Ballroom tonight.

Python code: <https://github.com/wittawatj/kernel-gof>



Questions?

Thank you

## FSSD and KSD in 1D Gaussian Case

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(\mu_q, \sigma_q^2)$ .

- Assume  $J = 1$  feature for  $n\widehat{\text{FSSD}}^2$ . Gaussian kernel (bandwidth =  $\sigma_k^2$ ).

$$\text{FSSD}^2 = \frac{\sigma_k^2 e^{-\frac{(v-\mu_q)^2}{\sigma_k^2 + \sigma_q^2}} ((\sigma_k^2 + 1) \mu_q + v (\sigma_q^2 - 1))^2}{(\sigma_k^2 + \sigma_q^2)^3}.$$

- If  $\mu_q \neq 0, \sigma_q^2 \neq 1$ , and  $v = -\frac{(\sigma_k^2 + 1)\mu_q}{(\sigma_q^2 - 1)}$ , then  $\text{FSSD}^2 = 0$ !
  - This is why  $v$  should be drawn from a distribution with a density.
- For KSD, Gaussian kernel (bandwidth =  $\kappa^2$ ).

$$S^2 = \frac{\mu_q^2 (\kappa^2 + 2\sigma_q^2) + (\sigma_q^2 - 1)^2}{(\kappa^2 + 2\sigma_q^2) \sqrt{\frac{2\sigma_q^2}{\kappa^2} + 1}}.$$

## FSSD and KSD in 1D Gaussian Case

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(\mu_q, \sigma_q^2)$ .

- Assume  $J = 1$  feature for  $n\widehat{\text{FSSD}}^2$ . Gaussian kernel (bandwidth =  $\sigma_k^2$ ).

$$\text{FSSD}^2 = \frac{\sigma_k^2 e^{-\frac{(v-\mu_q)^2}{\sigma_k^2 + \sigma_q^2}} ((\sigma_k^2 + 1) \mu_q + v (\sigma_q^2 - 1))^2}{(\sigma_k^2 + \sigma_q^2)^3}.$$

- If  $\mu_q \neq 0, \sigma_q^2 \neq 1$ , and  $v = -\frac{(\sigma_k^2 + 1)\mu_q}{(\sigma_q^2 - 1)}$ , then  $\text{FSSD}^2 = 0$ !
  - This is why  $v$  should be drawn from a distribution with a density.
- For KSD, Gaussian kernel (bandwidth =  $\kappa^2$ ).

$$S^2 = \frac{\mu_q^2 (\kappa^2 + 2\sigma_q^2) + (\sigma_q^2 - 1)^2}{(\kappa^2 + 2\sigma_q^2) \sqrt{\frac{2\sigma_q^2}{\kappa^2} + 1}}.$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{\cancel{y \sim p}}(\cancel{T_p k_v})(\cancel{y})$

## What is $T_p k_v$ ?

Recall  $\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}(T_p k_{\mathbf{v}})(\mathbf{x}) - \mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y})$

$$(T_p k_{\mathbf{v}})(\mathbf{y}) = \frac{1}{p(\mathbf{y})} \frac{d}{d\mathbf{y}} [k(\mathbf{y}, \mathbf{v}) p(\mathbf{y})].$$

Then,  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\mathbb{E}_{y \sim p} [(T_p k_v)(y)]$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\mathbb{E}_{y \sim p} [(T_p k_v)(y)] = \int_{-\infty}^{\infty} [(T_p k_v)(y)] p(y) dy$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\mathbb{E}_{y \sim p} [(T_p k_v)(y)] = \int_{-\infty}^{\infty} \left[ \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)] \right] p(y) dy$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\mathbb{E}_{y \sim p} [(T_p k_v)(y)] = \int_{-\infty}^{\infty} \left[ \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)] \right] p(y) dy$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k_v(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\begin{aligned}\mathbb{E}_{y \sim p} [(T_p k_v)(y)] &= \int_{-\infty}^{\infty} \left[ \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)] \right] p(y) dy \\ &= \int_{-\infty}^{\infty} \frac{d}{dy} [k_v(y) p(y)] dy\end{aligned}$$

## What is $T_p k_v$ ?

Recall  $\text{witness}(v) = \mathbb{E}_{x \sim q}(T_p k_v)(x) - \mathbb{E}_{y \sim p}(T_p k_v)(y)$

$$(T_p k_v)(y) = \frac{1}{p(y)} \frac{d}{dy} [k_v(y, v) p(y)].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{y \sim p}(T_p k_v)(y) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\begin{aligned}\mathbb{E}_{y \sim p} [(T_p k_v)(y)] &= \int_{-\infty}^{\infty} \left[ \frac{1}{p(y)} \frac{d}{dy} [k_v(y) p(y)] \right] p(y) dy \\ &= \int_{-\infty}^{\infty} \frac{d}{dy} [k_v(y) p(y)] dy \\ &= [k_v(y) p(y)]_{y=-\infty}^{y=\infty}\end{aligned}$$

## What is $T_p k_{\mathbf{v}}$ ?

Recall  $\text{witness}(\mathbf{v}) = \mathbb{E}_{\mathbf{x} \sim q}(T_p k_{\mathbf{v}})(\mathbf{x}) - \mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y})$

$$(T_p k_{\mathbf{v}})(\mathbf{y}) = \frac{1}{p(\mathbf{y})} \frac{d}{d\mathbf{y}} [k(\mathbf{y}, \mathbf{v}) p(\mathbf{y})].$$

Normalizer  
cancels

Then,  $\mathbb{E}_{\mathbf{y} \sim p}(T_p k_{\mathbf{v}})(\mathbf{y}) = 0$ .

[Liu et al., 2016, Chwialkowski et al., 2016]

**Proof:**

$$\begin{aligned}\mathbb{E}_{\mathbf{y} \sim p} [(T_p k_{\mathbf{v}})(\mathbf{y})] &= \int_{-\infty}^{\infty} \left[ \frac{1}{p(\mathbf{y})} \frac{d}{d\mathbf{y}} [k_{\mathbf{v}}(\mathbf{y}) p(\mathbf{y})] \right] p(\mathbf{y}) d\mathbf{y} \\ &= \int_{-\infty}^{\infty} \frac{d}{d\mathbf{y}} [k_{\mathbf{v}}(\mathbf{y}) p(\mathbf{y})] d\mathbf{y} \\ &= [k_{\mathbf{v}}(\mathbf{y}) p(\mathbf{y})]_{\mathbf{y}=-\infty}^{\mathbf{y}=\infty} \\ &= 0\end{aligned}$$

(assume  $\lim_{|\mathbf{y}| \rightarrow \infty} k(\mathbf{y}, \mathbf{v}) p(\mathbf{y}) = 0$ )

## FSSD is a Discrepancy Measure

### Theorem 1.

Let  $V = \{\mathbf{v}_1, \dots, \mathbf{v}_J\} \subset \mathbb{R}^d$  be drawn i.i.d. from a distribution  $\eta$  which has a density. Let  $\mathcal{X}$  be a connected open set in  $\mathbb{R}^d$ . Assume

- 1 (*Nice RKHS*) Kernel  $k: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$  is  $C_0$ -universal, and real analytic.
- 2 (*Stein witness not too rough*)  $\|g\|_k^2 < \infty$ .
- 3 (*Finite Fisher divergence*)  $\mathbb{E}_{\mathbf{x} \sim q} \|\nabla_{\mathbf{x}} \log \frac{p(\mathbf{x})}{q(\mathbf{x})}\|^2 < \infty$  .
- 4 (*Vanishing boundary*)  $\lim_{\|\mathbf{x}\| \rightarrow \infty} p(\mathbf{x})g(\mathbf{x}) = 0$ .

Then, for any  $J \geq 1$ ,  $\eta$ -almost surely

$$\text{FSSD}^2 = 0 \text{ if and only if } p = q.$$

- Gaussian kernel  $k(\mathbf{x}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{x}-\mathbf{v}\|_2^2}{2\sigma_k^2}\right)$  works.
- In practice,  $J = 1$  or  $J = 5$ .

## What Are “Blind Spots”?

$$\begin{aligned}\mathbf{g}(\mathbf{v}) &:= \mathbb{E}_{\mathbf{x} \sim q} \left[ \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x}) p(\mathbf{x})] \right] \\ &= \mathbb{E}_{\mathbf{x} \sim q} \left[ \left( \frac{d}{d\mathbf{x}} \log p(\mathbf{x}) \right) k_{\mathbf{v}}(\mathbf{x}) + \partial_{\mathbf{x}} k_{\mathbf{v}}(\mathbf{x}) \right] \in \mathbb{R}^d.\end{aligned}$$

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(0, \sigma_q^2)$ . Use unit-width Gaussian kernel.

$$g(v) = \frac{v \exp\left(-\frac{v^2}{2+2\sigma_q^2}\right) (\sigma_q^2 - 1)}{(1 + \sigma_q^2)^{3/2}}$$

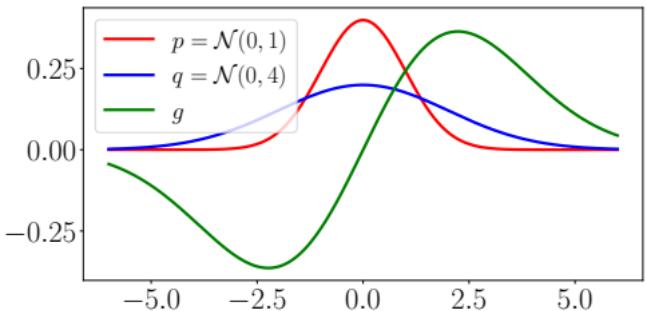
- If  $v = 0$ , then  $\text{FSSD}^2 = g^2(v) = 0$  regardless of  $\sigma_q^2$ .
- If  $g \neq 0$ , and  $k$  is real analytic,  $R = \{v \mid g(v) = 0\}$  (blind spots) has 0 Lebesgue measure.
- So, if  $v \sim$  a distribution with a density, then  $v \notin R$ .

## What Are “Blind Spots”?

$$\begin{aligned} g(\mathbf{v}) &:= \mathbb{E}_{\mathbf{x} \sim q} \left[ \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x}) p(\mathbf{x})] \right] \\ &= \mathbb{E}_{\mathbf{x} \sim q} \left[ \left( \frac{d}{d\mathbf{x}} \log p(\mathbf{x}) \right) k_{\mathbf{v}}(\mathbf{x}) + \partial_{\mathbf{x}} k_{\mathbf{v}}(\mathbf{x}) \right] \in \mathbb{R}^d. \end{aligned}$$

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(0, \sigma_q^2)$ . Use unit-width Gaussian kernel.

$$g(v) = \frac{v \exp \left( -\frac{v^2}{2+2\sigma_q^2} \right) (\sigma_q^2 - 1)}{(1 + \sigma_q^2)^{3/2}}$$



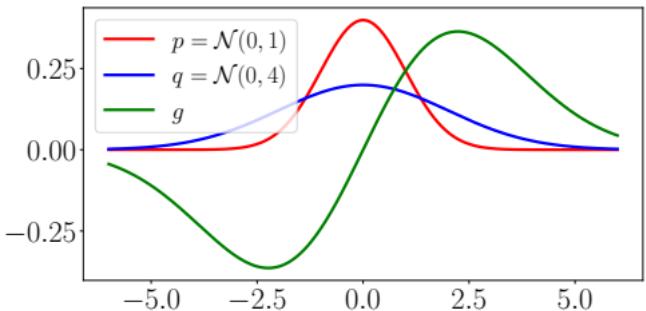
- If  $v = 0$ , then  $\text{FSSD}^2 = g^2(v) = 0$  regardless of  $\sigma_q^2$ .
- If  $g \neq 0$ , and  $k$  is real analytic,  $R = \{v \mid g(v) = 0\}$  (blind spots) has 0 Lebesgue measure.
- So, if  $v \sim$  a distribution with a density, then  $v \notin R$ .

## What Are “Blind Spots”?

$$\begin{aligned} g(\mathbf{v}) &:= \mathbb{E}_{\mathbf{x} \sim q} \left[ \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x}) p(\mathbf{x})] \right] \\ &= \mathbb{E}_{\mathbf{x} \sim q} \left[ \left( \frac{d}{d\mathbf{x}} \log p(\mathbf{x}) \right) k_{\mathbf{v}}(\mathbf{x}) + \partial_{\mathbf{x}} k_{\mathbf{v}}(\mathbf{x}) \right] \in \mathbb{R}^d. \end{aligned}$$

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(0, \sigma_q^2)$ . Use unit-width Gaussian kernel.

$$g(\mathbf{v}) = \frac{\mathbf{v} \exp \left( -\frac{\mathbf{v}^2}{2+2\sigma_q^2} \right) (\sigma_q^2 - 1)}{(1 + \sigma_q^2)^{3/2}}$$



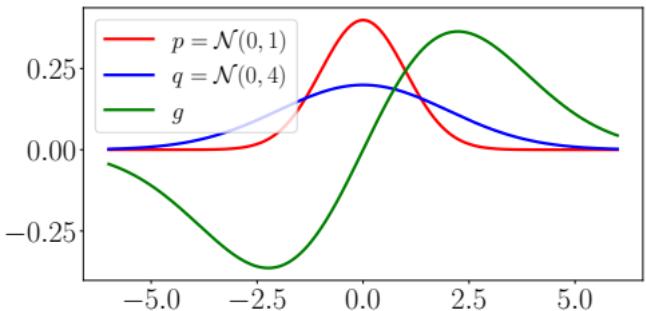
- If  $\mathbf{v} = 0$ , then  $\text{FSSD}^2 = g^2(\mathbf{v}) = 0$  regardless of  $\sigma_q^2$ .
- If  $g \neq 0$ , and  $k$  is real analytic,  $R = \{\mathbf{v} \mid g(\mathbf{v}) = 0\}$  (blind spots) has 0 Lebesgue measure.
- So, if  $\mathbf{v} \sim$  a distribution with a density, then  $\mathbf{v} \notin R$ .

## What Are “Blind Spots”?

$$\begin{aligned} g(\mathbf{v}) &:= \mathbb{E}_{\mathbf{x} \sim q} \left[ \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x}) p(\mathbf{x})] \right] \\ &= \mathbb{E}_{\mathbf{x} \sim q} \left[ \left( \frac{d}{d\mathbf{x}} \log p(\mathbf{x}) \right) k_{\mathbf{v}}(\mathbf{x}) + \partial_{\mathbf{x}} k_{\mathbf{v}}(\mathbf{x}) \right] \in \mathbb{R}^d. \end{aligned}$$

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(0, \sigma_q^2)$ . Use unit-width Gaussian kernel.

$$g(\mathbf{v}) = \frac{\mathbf{v} \exp \left( -\frac{\mathbf{v}^2}{2+2\sigma_q^2} \right) (\sigma_q^2 - 1)}{(1 + \sigma_q^2)^{3/2}}$$



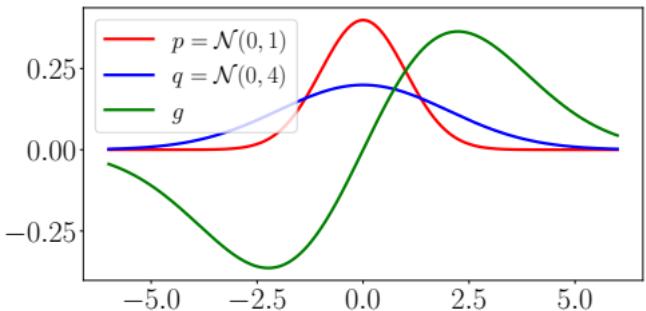
- If  $\mathbf{v} = 0$ , then  $\text{FSSD}^2 = g^2(\mathbf{v}) = 0$  regardless of  $\sigma_q^2$ .
- If  $g \neq 0$ , and  $k$  is real analytic,  $R = \{\mathbf{v} \mid g(\mathbf{v}) = 0\}$  (blind spots) has 0 Lebesgue measure.
- So, if  $\mathbf{v} \sim$  a distribution with a density, then  $\mathbf{v} \notin R$ .

## What Are “Blind Spots”?

$$\begin{aligned} g(\mathbf{v}) &:= \mathbb{E}_{\mathbf{x} \sim q} \left[ \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k_{\mathbf{v}}(\mathbf{x}) p(\mathbf{x})] \right] \\ &= \mathbb{E}_{\mathbf{x} \sim q} \left[ \left( \frac{d}{d\mathbf{x}} \log p(\mathbf{x}) \right) k_{\mathbf{v}}(\mathbf{x}) + \partial_{\mathbf{x}} k_{\mathbf{v}}(\mathbf{x}) \right] \in \mathbb{R}^d. \end{aligned}$$

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(0, \sigma_q^2)$ . Use unit-width Gaussian kernel.

$$g(\mathbf{v}) = \frac{\mathbf{v} \exp \left( -\frac{\mathbf{v}^2}{2+2\sigma_q^2} \right) (\sigma_q^2 - 1)}{(1 + \sigma_q^2)^{3/2}}$$



- If  $\mathbf{v} = 0$ , then  $\text{FSSD}^2 = g^2(\mathbf{v}) = 0$  regardless of  $\sigma_q^2$ .
- If  $g \neq 0$ , and  $k$  is real analytic,  $R = \{\mathbf{v} \mid g(\mathbf{v}) = 0\}$  (blind spots) has 0 Lebesgue measure.
- So, if  $\mathbf{v} \sim$  a distribution with a density, then  $\mathbf{v} \notin R$ .

## Asymptotic Distributions of $\widehat{\text{FSSD}}^2$

- Recall  $\xi(\mathbf{x}, \mathbf{v}) := \frac{1}{\mathbf{p}(\mathbf{x})} \frac{d}{d\mathbf{x}} [k(\mathbf{x}, \mathbf{v}) \mathbf{p}(\mathbf{x})] \in \mathbb{R}^d$ .
- $\tau(\mathbf{x}) :=$  vertically stack  $\xi(\mathbf{x}, \mathbf{v}_1), \dots, \xi(\mathbf{x}, \mathbf{v}_J) \in \mathbb{R}^{dJ}$ . Features of  $\mathbf{x}$ .
- Mean feature:  $\mu := \mathbb{E}_{\mathbf{x} \sim q}[\tau(\mathbf{x})]$ .
- $\Sigma_r := \text{cov}_{\mathbf{x} \sim r}[\tau(\mathbf{x})] \in \mathbb{R}^{dJ \times dJ}$  for  $r \in \{p, q\}$

**Proposition 1** (Asymptotic distributions).

Let  $Z_1, \dots, Z_{dJ} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$ , and  $\{\omega_i\}_{i=1}^{dJ}$  be the eigenvalues of  $\Sigma_p$ .

- 1 Under  $H_0 : p = q$ , asymptotically  $n\widehat{\text{FSSD}}^2 \xrightarrow{d} \sum_{i=1}^{dJ} (Z_i^2 - 1)\omega_i$ .
  - Simulation cost independent of  $n$ .
- 2 Under  $H_1 : p \neq q$ , we have  $\sqrt{n}(\widehat{\text{FSSD}}^2 - \text{FSSD}^2) \xrightarrow{d} \mathcal{N}(0, \sigma_{H_1}^2)$  where  $\sigma_{H_1}^2 := 4\mu^\top \Sigma_q \mu$ . Implies  $\mathbb{P}(\text{reject } H_0) \rightarrow 1$  as  $n \rightarrow \infty$ .

**But**, how to estimate  $\Sigma_p$ ? No sample from  $p$ !

- Theorem: Using  $\hat{\Sigma}_q$  (computed with  $\{\mathbf{x}_i\}_{i=1}^n \sim q$ ) still leads to a consistent test.

## Asymptotic Distributions of $\widehat{\text{FSSD}}^2$

- Recall  $\xi(\mathbf{x}, \mathbf{v}) := \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k(\mathbf{x}, \mathbf{v}) p(\mathbf{x})] \in \mathbb{R}^d$ .
- $\tau(\mathbf{x}) :=$  vertically stack  $\xi(\mathbf{x}, \mathbf{v}_1), \dots, \xi(\mathbf{x}, \mathbf{v}_J) \in \mathbb{R}^{dJ}$ . Features of  $\mathbf{x}$ .
- Mean feature:  $\mu := \mathbb{E}_{\mathbf{x} \sim q} [\tau(\mathbf{x})]$ .
- $\Sigma_r := \text{cov}_{\mathbf{x} \sim r} [\tau(\mathbf{x})] \in \mathbb{R}^{dJ \times dJ}$  for  $r \in \{p, q\}$

**Proposition 1 (Asymptotic distributions).**

Let  $Z_1, \dots, Z_{dJ} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$ , and  $\{\omega_i\}_{i=1}^{dJ}$  be the eigenvalues of  $\Sigma_p$ .

- 1 Under  $H_0 : p = q$ , asymptotically  $n \widehat{\text{FSSD}}^2 \xrightarrow{d} \sum_{i=1}^{dJ} (Z_i^2 - 1) \omega_i$ .
  - Simulation cost independent of  $n$ .
- 2 Under  $H_1 : p \neq q$ , we have  $\sqrt{n} (\widehat{\text{FSSD}}^2 - \text{FSSD}^2) \xrightarrow{d} \mathcal{N}(0, \sigma_{H_1}^2)$  where  $\sigma_{H_1}^2 := 4\mu^\top \Sigma_q \mu$ . Implies  $\mathbb{P}(\text{reject } H_0) \rightarrow 1$  as  $n \rightarrow \infty$ .

**But**, how to estimate  $\Sigma_p$ ? No sample from  $p$ !

- Theorem: Using  $\hat{\Sigma}_q$  (computed with  $\{\mathbf{x}_i\}_{i=1}^n \sim q$ ) still leads to a consistent test.

## Asymptotic Distributions of $\widehat{\text{FSSD}}^2$

- Recall  $\xi(\mathbf{x}, \mathbf{v}) := \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k(\mathbf{x}, \mathbf{v}) p(\mathbf{x})] \in \mathbb{R}^d$ .
- $\tau(\mathbf{x}) :=$  vertically stack  $\xi(\mathbf{x}, \mathbf{v}_1), \dots, \xi(\mathbf{x}, \mathbf{v}_J) \in \mathbb{R}^{dJ}$ . Features of  $\mathbf{x}$ .
- Mean feature:  $\mu := \mathbb{E}_{\mathbf{x} \sim q} [\tau(\mathbf{x})]$ .
- $\Sigma_r := \text{cov}_{\mathbf{x} \sim r} [\tau(\mathbf{x})] \in \mathbb{R}^{dJ \times dJ}$  for  $r \in \{p, q\}$

**Proposition 1 (Asymptotic distributions).**

Let  $Z_1, \dots, Z_{dJ} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$ , and  $\{\omega_i\}_{i=1}^{dJ}$  be the eigenvalues of  $\Sigma_p$ .

- 1 Under  $H_0 : p = q$ , asymptotically  $n \widehat{\text{FSSD}}^2 \xrightarrow{d} \sum_{i=1}^{dJ} (Z_i^2 - 1) \omega_i$ .
  - Simulation cost independent of  $n$ .
- 2 Under  $H_1 : p \neq q$ , we have  $\sqrt{n} (\widehat{\text{FSSD}}^2 - \text{FSSD}^2) \xrightarrow{d} \mathcal{N}(0, \sigma_{H_1}^2)$  where  $\sigma_{H_1}^2 := 4\mu^\top \Sigma_q \mu$ . Implies  $\mathbb{P}(\text{reject } H_0) \rightarrow 1$  as  $n \rightarrow \infty$ .

**But**, how to estimate  $\Sigma_p$ ? No sample from  $p$ !

- Theorem: Using  $\hat{\Sigma}_q$  (computed with  $\{\mathbf{x}_i\}_{i=1}^n \sim q$ ) still leads to a consistent test.

## Asymptotic Distributions of $\widehat{\text{FSSD}}^2$

- Recall  $\xi(\mathbf{x}, \mathbf{v}) := \frac{1}{p(\mathbf{x})} \frac{d}{d\mathbf{x}} [k(\mathbf{x}, \mathbf{v}) p(\mathbf{x})] \in \mathbb{R}^d$ .
- $\tau(\mathbf{x}) :=$  vertically stack  $\xi(\mathbf{x}, \mathbf{v}_1), \dots, \xi(\mathbf{x}, \mathbf{v}_J) \in \mathbb{R}^{dJ}$ . Features of  $\mathbf{x}$ .
- Mean feature:  $\mu := \mathbb{E}_{\mathbf{x} \sim q} [\tau(\mathbf{x})]$ .
- $\Sigma_r := \text{cov}_{\mathbf{x} \sim r} [\tau(\mathbf{x})] \in \mathbb{R}^{dJ \times dJ}$  for  $r \in \{p, q\}$

**Proposition 1 (Asymptotic distributions).**

Let  $Z_1, \dots, Z_{dJ} \stackrel{i.i.d.}{\sim} \mathcal{N}(0, 1)$ , and  $\{\omega_i\}_{i=1}^{dJ}$  be the eigenvalues of  $\Sigma_p$ .

- 1 Under  $H_0 : p = q$ , asymptotically  $n \widehat{\text{FSSD}}^2 \xrightarrow{d} \sum_{i=1}^{dJ} (Z_i^2 - 1) \omega_i$ .
  - Simulation cost independent of  $n$ .
- 2 Under  $H_1 : p \neq q$ , we have  $\sqrt{n} (\widehat{\text{FSSD}}^2 - \text{FSSD}^2) \xrightarrow{d} \mathcal{N}(0, \sigma_{H_1}^2)$  where  $\sigma_{H_1}^2 := 4\mu^\top \Sigma_q \mu$ . Implies  $\mathbb{P}(\text{reject } H_0) \rightarrow 1$  as  $n \rightarrow \infty$ .

**But**, how to estimate  $\Sigma_p$ ? No sample from  $p$ !

- **Theorem:** Using  $\widehat{\Sigma}_q$  (computed with  $\{\mathbf{x}_i\}_{i=1}^n \sim q$ ) still leads to a consistent test.

## Bahadur Slope and Bahadur Efficiency

- Bahadur slope  $\approx$  rate of p-value  $\rightarrow 0$  under  $H_1$  as  $n \rightarrow \infty$ .
- Measure a test's sensitivity to the departure from  $H_0$ .

$$H_0: \theta = 0,$$

$$H_1: \theta \neq 0.$$

- Typically  $pval_n \approx \exp\left(-\frac{1}{2}c(\theta)n\right)$  where  $c(\theta) > 0$  under  $H_1$ , and  $c(0) = 0$  [Bahadur, 1960].
- $c(\theta)$  higher  $\implies$  more sensitive. Good.

### Bahadur slope

$$c(\theta) := -2 \operatorname{plim}_{n \rightarrow \infty} \frac{\log(1 - F(T_n))}{n},$$

where  $F(t) = \text{CDF of } T_n \text{ under } H_0$ .

- Bahadur efficiency = ratio of slopes of two tests.

## Bahadur Slope and Bahadur Efficiency

- Bahadur slope  $\approx$  rate of p-value  $\rightarrow 0$  under  $H_1$  as  $n \rightarrow \infty$ .
- Measure a test's sensitivity to the departure from  $H_0$ .

$$H_0: \theta = 0,$$

$$H_1: \theta \neq 0.$$

- Typically  $pval_n \approx \exp\left(-\frac{1}{2}c(\theta)n\right)$  where  $c(\theta) > 0$  under  $H_1$ , and  $c(0) = 0$  [Bahadur, 1960].
- $c(\theta)$  higher  $\implies$  more sensitive. Good.

### Bahadur slope

$$c(\theta) := -2 \operatorname{plim}_{n \rightarrow \infty} \frac{\log(1 - F(T_n))}{n},$$

where  $F(t) = \text{CDF of } T_n \text{ under } H_0$ .

- Bahadur efficiency = ratio of slopes of two tests.

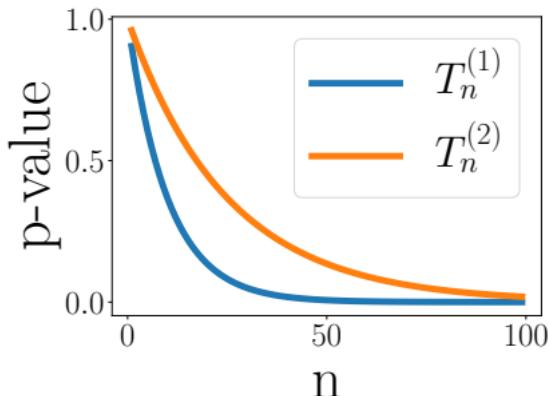
## Bahadur Slope and Bahadur Efficiency

- Bahadur slope  $\approx$  rate of p-value  $\rightarrow 0$  under  $H_1$  as  $n \rightarrow \infty$ .
- Measure a test's sensitivity to the departure from  $H_0$ .

$$H_0: \theta = 0,$$

$$H_1: \theta \neq 0.$$

- Typically  $pval_n \approx \exp\left(-\frac{1}{2}c(\theta)n\right)$  where  $c(\theta) > 0$  under  $H_1$ , and  $c(0) = 0$  [Bahadur, 1960].
- $c(\theta)$  higher  $\implies$  more sensitive. Good.



Bahadur slope

$$c(\theta) := -2 \operatorname{plim}_{n \rightarrow \infty} \frac{\log(1 - F(T_n))}{n},$$

where  $F(t) = \text{CDF of } T_n \text{ under } H_0$ .

- Bahadur efficiency = ratio of slopes of two tests.

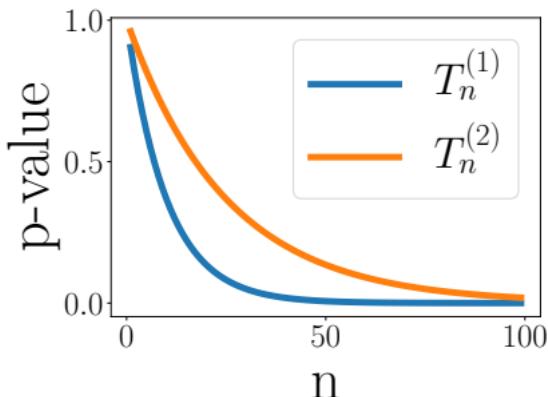
## Bahadur Slope and Bahadur Efficiency

- Bahadur slope  $\approx$  rate of p-value  $\rightarrow 0$  under  $H_1$  as  $n \rightarrow \infty$ .
- Measure a test's sensitivity to the departure from  $H_0$ .

$$H_0: \theta = 0,$$

$$H_1: \theta \neq 0.$$

- Typically  $pval_n \approx \exp\left(-\frac{1}{2}c(\theta)n\right)$  where  $c(\theta) > 0$  under  $H_1$ , and  $c(0) = 0$  [Bahadur, 1960].
- $c(\theta)$  higher  $\implies$  more sensitive. Good.



Bahadur slope

$$c(\theta) := -2 \operatorname{plim}_{n \rightarrow \infty} \frac{\log(1 - F(T_n))}{n},$$

where  $F(t) = \text{CDF of } T_n \text{ under } H_0$ .

- Bahadur efficiency = ratio of slopes of two tests.

## Gaussian Mean Shift Problem

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(\mu_q, 1)$ .

- Assume  $J = 1$  location for  $n\widehat{\text{FSSD}}^2$ . Gaussian kernel (bandwidth =  $\sigma_k^2$ )

$$c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2) = \frac{\sigma_k^2 (\sigma_k^2 + 2)^3 \mu_q^2 e^{\frac{v^2}{\sigma_k^2+2} - \frac{(v-\mu_q)^2}{\sigma_k^2+1}}}{\sqrt{\frac{2}{\sigma_k^2} + 1} (\sigma_k^2 + 1) (\sigma_k^6 + 4\sigma_k^4 + (v^2 + 5)\sigma_k^2 + 2)}.$$

- For LKS, Gaussian kernel (bandwidth =  $\kappa^2$ ).

$$c^{(\text{LKS})}(\mu_q, \kappa^2) = \frac{(\kappa^2)^{5/2} (\kappa^2 + 4)^{5/2} \mu_q^4}{2(\kappa^2 + 2)(\kappa^8 + 8\kappa^6 + 21\kappa^4 + 20\kappa^2 + 12)}.$$

Theorem 2 (FSSD is at least two times more efficient).

Fix  $\sigma_k^2 = 1$  for  $n\widehat{\text{FSSD}}^2$ . Then,  $\forall \mu_q \neq 0$ ,  $\exists v \in \mathbb{R}$ ,  $\forall \kappa^2 > 0$ , we have Bahadur efficiency

$$\frac{c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2)}{c^{(\text{LKS})}(\mu_q, \kappa^2)} > 2.$$

## Gaussian Mean Shift Problem

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(\mu_q, 1)$ .

- Assume  $J = 1$  location for  $n\widehat{\text{FSSD}}^2$ . Gaussian kernel (bandwidth =  $\sigma_k^2$ )

$$c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2) = \frac{\sigma_k^2 (\sigma_k^2 + 2)^3 \mu_q^2 e^{\frac{v^2}{\sigma_k^2+2}} - \frac{(v - \mu_q)^2}{\sigma_k^2+1}}{\sqrt{\frac{2}{\sigma_k^2} + 1} (\sigma_k^2 + 1) (\sigma_k^6 + 4\sigma_k^4 + (v^2 + 5)\sigma_k^2 + 2)}.$$

- For LKS, Gaussian kernel (bandwidth =  $\kappa^2$ ).

$$c^{(\text{LKS})}(\mu_q, \kappa^2) = \frac{(\kappa^2)^{5/2} (\kappa^2 + 4)^{5/2} \mu_q^4}{2(\kappa^2 + 2)(\kappa^8 + 8\kappa^6 + 21\kappa^4 + 20\kappa^2 + 12)}.$$

Theorem 2 (FSSD is at least two times more efficient).

Fix  $\sigma_k^2 = 1$  for  $n\widehat{\text{FSSD}}^2$ . Then,  $\forall \mu_q \neq 0$ ,  $\exists v \in \mathbb{R}$ ,  $\forall \kappa^2 > 0$ , we have Bahadur efficiency

$$\frac{c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2)}{c^{(\text{LKS})}(\mu_q, \kappa^2)} > 2.$$

## Gaussian Mean Shift Problem

Consider  $p = \mathcal{N}(0, 1)$  and  $q = \mathcal{N}(\mu_q, 1)$ .

- Assume  $J = 1$  location for  $n\widehat{\text{FSSD}}^2$ . Gaussian kernel (bandwidth =  $\sigma_k^2$ )

$$c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2) = \frac{\sigma_k^2 (\sigma_k^2 + 2)^3 \mu_q^2 e^{\frac{v^2}{\sigma_k^2+2}} - \frac{(v-\mu_q)^2}{\sigma_k^2+1}}{\sqrt{\frac{2}{\sigma_k^2} + 1} (\sigma_k^2 + 1) (\sigma_k^6 + 4\sigma_k^4 + (v^2 + 5)\sigma_k^2 + 2)}.$$

- For LKS, Gaussian kernel (bandwidth =  $\kappa^2$ ).

$$c^{(\text{LKS})}(\mu_q, \kappa^2) = \frac{(\kappa^2)^{5/2} (\kappa^2 + 4)^{5/2} \mu_q^4}{2(\kappa^2 + 2)(\kappa^8 + 8\kappa^6 + 21\kappa^4 + 20\kappa^2 + 12)}.$$

**Theorem 2** (FSSD is at least two times more efficient).

Fix  $\sigma_k^2 = 1$  for  $n\widehat{\text{FSSD}}^2$ . Then,  $\forall \mu_q \neq 0$ ,  $\exists v \in \mathbb{R}$ ,  $\forall \kappa^2 > 0$ , we have Bahadur efficiency

$$\frac{c^{(\text{FSSD})}(\mu_q, v, \sigma_k^2)}{c^{(\text{LKS})}(\mu_q, \kappa^2)} > 2.$$

## Linear-Time Kernel Stein Discrepancy (LKS)

- [Liu et al., 2016] also proposed a linear version of KSD.
- For  $\{\mathbf{x}_i\}_{i=1}^n \sim q$ , KSD test statistic is

$$\frac{2}{n(n-1)} \sum_{i < j} h_p(\mathbf{x}_i, \mathbf{x}_j).$$

	1	2	3	4	5	6	7	8
1								
2								
3								
4								
5								
6								
7								
8								

- LKS test statistic is a “running average”

$$\frac{2}{n} \sum_{i=1}^{n/2} h_p(\mathbf{x}_{2i-1}, \mathbf{x}_{2i}).$$

	1	2	3	4	5	6	7	8
1								
2								
3								
4								
5								
6								
7								
8								

- Both unbiased. LKS has  $\mathcal{O}(d^2 n)$  runtime.
- **X** LKS has high variance. Poor test power.

## Bahadur Slopes of FSSD and LKS

### Theorem 3.

The Bahadur slope of  $n\widehat{\text{FSSD}}^2$  is

$$c^{(\text{FSSD})} := \text{FSSD}^2 / \omega_1,$$

where  $\omega_1$  is the maximum eigenvalue of  $\Sigma_p := \text{cov}_{\mathbf{x} \sim p}[\tau(\mathbf{x})]$ .

The Bahadur slope of the linear-time kernel Stein (LKS) statistic  $\sqrt{n}\widehat{S}_l^2$  is

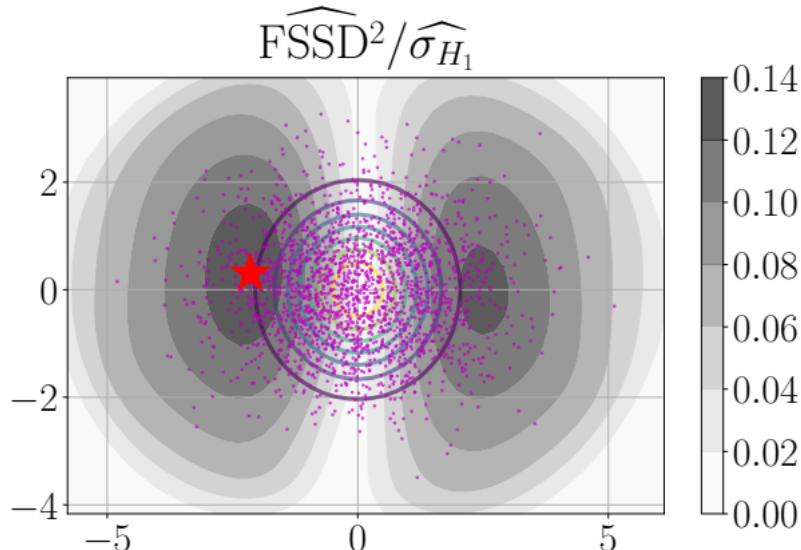
$$c^{(\text{LKS})} = \frac{1}{2} \frac{\left[ \mathbb{E}_q h_p(\mathbf{x}, \mathbf{x}') \right]^2}{\mathbb{E}_p [h_p^2(\mathbf{x}, \mathbf{x}')]},$$

where  $h_p$  is the U-statistic kernel of the KSD statistic.

## Illustration: Optimization Objective

- Consider  $J = 1$  location.
- Training objective  $\frac{\text{FSSD}^2(\mathbf{v})}{\widehat{\sigma}_{H_1}(\mathbf{v})}$  (gray),  $p$  in wireframe,  $\{\mathbf{x}_i\}_{i=1}^n \sim q$  in purple,  $\star$  = best  $\mathbf{v}$ .

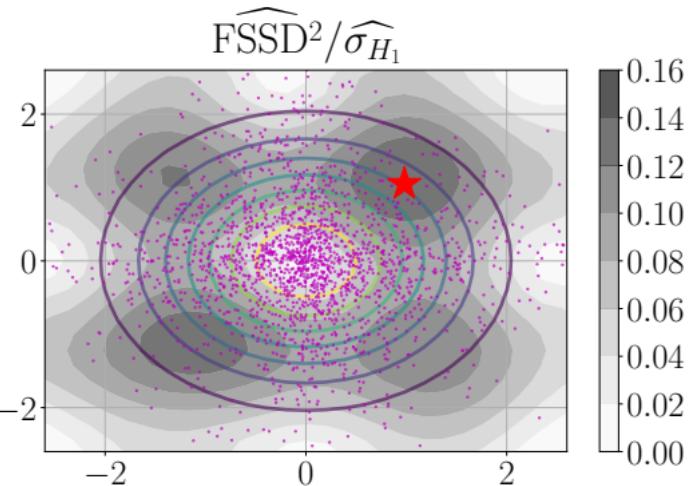
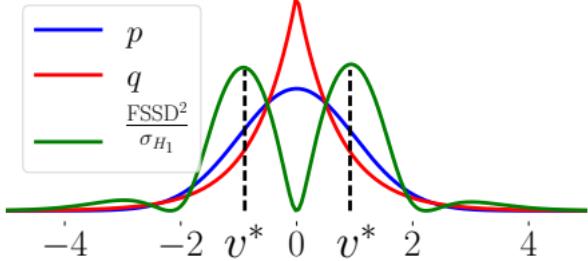
$$p = \mathcal{N} \left( \mathbf{0}, \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) \text{ vs. } q = \mathcal{N} \left( \mathbf{0}, \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \right).$$



## Illustration: Optimization Objective

- Consider  $J = 1$  location.
- Training objective  $\frac{\widehat{\text{FSSD}}^2(\mathbf{v})}{\widehat{\sigma}_{H_1}(\mathbf{v})}$  (gray),  $p$  in wireframe,  $\{\mathbf{x}_i\}_{i=1}^n \sim q$  in purple,  $\star$  = best  $\mathbf{v}$ .

$p = \mathcal{N}(\mathbf{0}, \mathbf{I})$  vs.  $q = \text{Laplace}$  with same mean & variance.



## Simulation Settings

■ Gaussian kernel  $k(\mathbf{x}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{x}-\mathbf{v}\|_2^2}{2\sigma_k^2}\right)$

	Method	Description
1	FSSD-opt	Proposed. With optimization. $J = 5$ .
2	FSSD-rand	Proposed. Random test locations.
3	KSD	Quadratic-time kernel Stein discrepancy [Liu et al., 2016, Chwialkowski et al., 2016]
4	LKS	Linear-time running average version of KSD.
5	MMD-opt	MMD two-sample test [Gretton et al., 2012]. With optimization.
6	ME-test	Mean Embeddings two-sample test [Jitkrittum et al., 2016]. With optimization.

- Two-sample tests need to draw sample from  $p$ .
- Tests with optimization use 20% of the data.
- $\alpha = 0.05$ . 200 trials.

## Simulation Settings

■ Gaussian kernel  $k(\mathbf{x}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{x}-\mathbf{v}\|_2^2}{2\sigma_k^2}\right)$

	Method	Description
1	FSSD-opt	Proposed. With optimization. $J = 5$ .
2	FSSD-rand	Proposed. Random test locations.
3	KSD	Quadratic-time kernel Stein discrepancy [Liu et al., 2016, Chwialkowski et al., 2016]
4	LKS	Linear-time running average version of KSD.
5	MMD-opt	MMD two-sample test [Gretton et al., 2012]. With optimization.
6	ME-test	Mean Embeddings two-sample test [Jitkrittum et al., 2016]. With optimization.

- Two-sample tests need to draw sample from  $p$ .
- Tests with optimization use 20% of the data.
- $\alpha = 0.05$ . 200 trials.

## Simulation Settings

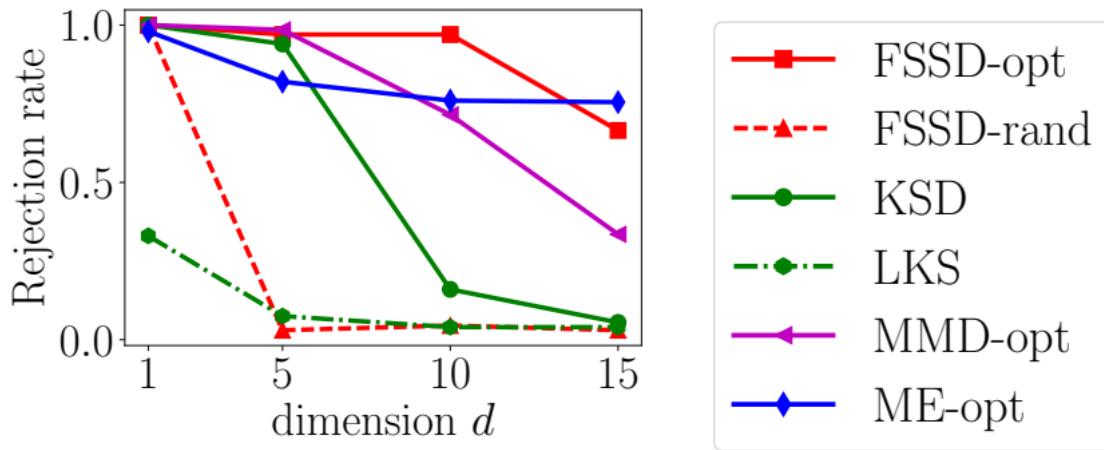
■ Gaussian kernel  $k(\mathbf{x}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{x}-\mathbf{v}\|_2^2}{2\sigma_k^2}\right)$

	Method	Description
1	FSSD-opt	Proposed. With optimization. $J = 5$ .
2	FSSD-rand	Proposed. Random test locations.
3	KSD	Quadratic-time kernel Stein discrepancy [Liu et al., 2016, Chwialkowski et al., 2016]
4	LKS	Linear-time running average version of KSD.
5	MMD-opt	MMD two-sample test [Gretton et al., 2012]. With optimization.
6	ME-test	Mean Embeddings two-sample test [Jitkrittum et al., 2016]. With optimization.

- Two-sample tests need to draw sample from  $p$ .
- Tests with optimization use 20% of the data.
- $\alpha = 0.05$ . 200 trials.

## Gaussian Vs. Laplace

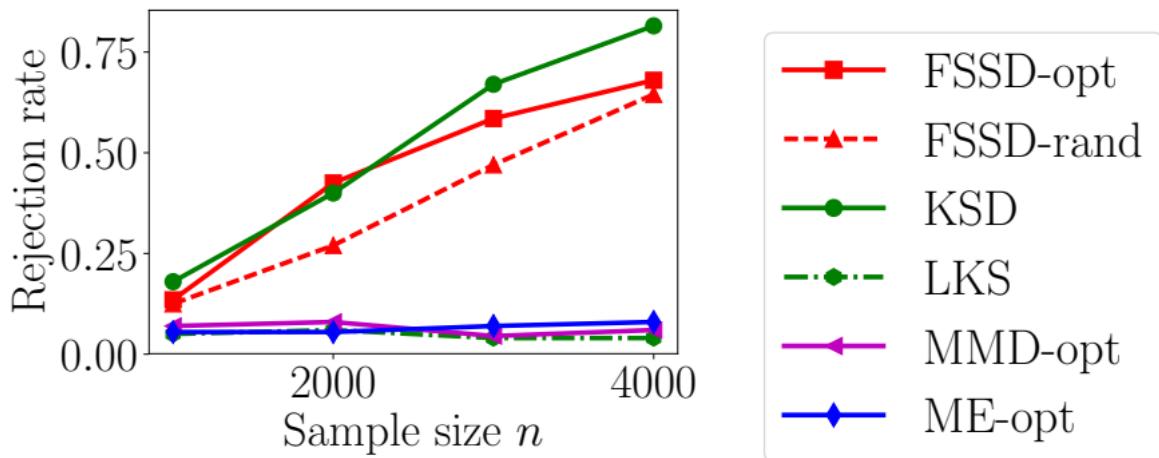
- $p = \text{Gaussian}$ .  $q = \text{Laplace}$ . Same mean and variance. High-order moments differ.
- Sample size  $n = 1000$ .



- Optimization increases the power.
- Two-sample tests can perform well in this case ( $p, q$  clearly differ).

## Harder RBM Problem

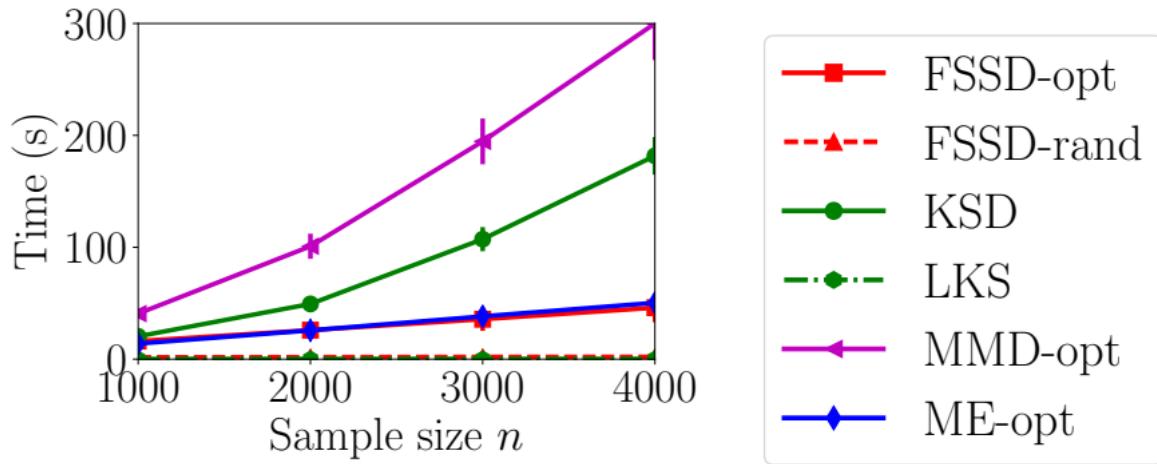
- Perturb only one entry of  $\mathbf{B} \in \mathbb{R}^{50 \times 40}$  (in the RBM).
- $B_{1,1} \leftarrow B_{1,1} + \mathcal{N}(0, \sigma_{per}^2 = 0.1^2)$ .



- Two-sample tests fail. Samples from  $p, q$  look roughly the same.
- FSSD-opt is comparable to KSD at low  $n$ . One order of magnitude faster.

## Harder RBM Problem

- Perturb only one entry of  $\mathbf{B} \in \mathbb{R}^{50 \times 40}$  (in the RBM).
- $B_{1,1} \leftarrow B_{1,1} + \mathcal{N}(0, \sigma_{per}^2 = 0.1^2)$ .



- Two-sample tests fail. Samples from  $p, q$  look roughly the same.
- FSSD-opt is comparable to KSD at low  $n$ . One order of magnitude faster.

## References I

-  Bahadur, R. R. (1960).  
Stochastic comparison of tests.  
*The Annals of Mathematical Statistics*, 31(2):276–295.
-  Chwialkowski, K., Strathmann, H., and Gretton, A. (2016).  
A kernel test of goodness of fit.  
In *ICML*, pages 2606–2615.
-  Gretton, A., Borgwardt, K. M., Rasch, M. J., Schölkopf, B., and Smola, A. (2012).  
A kernel two-sample test.  
*JMLR*, 13:723–773.

## References II

-  Jitkrittum, W., Szabó, Z., Chwialkowski, K. P., and Gretton, A. (2016). Interpretable Distribution Features with Maximum Testing Power. In *NIPS*, pages 181–189.
-  Liu, Q., Lee, J., and Jordan, M. (2016). A kernelized Stein discrepancy for goodness-of-fit tests. In *ICML*, pages 276–284.