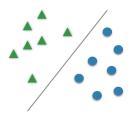
Foundations of Machine Learning (ST510)

Zoltán Szabó

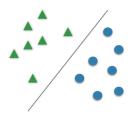
LSE, Feb. 5, 2024

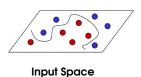
Motivating examples

- Given: $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$, $y_i \in \{-1, 1\}$.
- Goal: find an f classifier such that $f(\mathbf{x}) \approx y$.



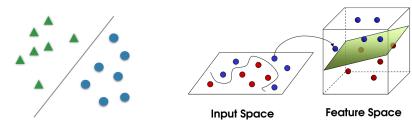
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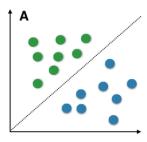
Example-1: non-linear (large-margin) classification

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Example-1: continued – linear separability

Idealized situation

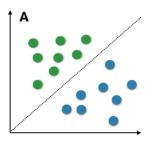


Decision surface:

$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle = 0\}$$

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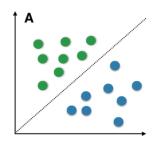
$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle = 0\} \Rightarrow$$

classes:

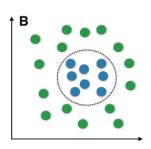
$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle \ge 0\}$$
 $\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle < 0\}$

Example-1: continued – non-linear separability

Idealized situation



Real world



Decision surface (left):

$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle = 0\} \Rightarrow$$

classes:

$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle \geq 0\}$$

$$\{\mathbf{x}: \langle \mathbf{w}, \mathbf{x} \rangle < 0\}$$
.

On the ellipse

$$\left\{\mathbf{x}: \frac{(x_1-c_1)^2}{a^2} + \frac{(x_2-c_2)^2}{b^2} = 1\right\}$$

On the ellipse, outside

$$\left\{\mathbf{x}: \frac{(x_1-c_1)^2}{a^2} + \frac{(x_2-c_2)^2}{b^2} = 1\right\},$$

$$\left\{\mathbf{x}: \frac{(x_1-c_1)^2}{a^2} + \frac{(x_2-c_2)^2}{b^2} > 1\right\}$$

On the ellipse, outside, inside:

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With polynomial feature: $\varphi(\mathbf{x}) = (x_1^2, x_1, 1, x_2^2, x_2)$:

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$$\varphi(\mathbf{x}) = \left(x_1^2, \sqrt{2}x_1x_2, x_2^2\right),\,$$

$$\langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle = ?$$

$$\varphi(\mathbf{x}) = \begin{pmatrix} x_1^2, \sqrt{2}x_1x_2, x_2^2 \end{pmatrix},$$

$$\langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle = \left\langle \begin{bmatrix} x_1^2 \\ \sqrt{2}x_1x_2 \\ x_2^2 \end{bmatrix}, \begin{bmatrix} (x_1')^2 \\ \sqrt{2}(x_1')(x_2') \\ (x_2')^2 \end{bmatrix} \right\rangle$$

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$$\langle \mathbf{x}, \mathbf{x}' \rangle^d = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle$$
: $\varphi(\mathbf{x}) = d$ -order polynomial. \Rightarrow

Still in \mathbb{R}^2 :

$$\varphi(\mathbf{x}) = \begin{pmatrix} x_1^2, \sqrt{2}x_1x_2, x_2^2 \end{pmatrix},
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 $\langle \mathbf{x}, \mathbf{x}' \rangle^d = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle$: $\varphi(\mathbf{x}) = d$ -order polynomial. \Rightarrow Explicit computation would be heavy!

Example-2: characterizing distributions / independence

- Given: random variable $(X, Y) \in \mathcal{X} \times \mathcal{Y}$, $(X, Y) \sim \mathbb{P}_{XY}$.
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- Goal: measure the dependence of X and Y.
- Desiderata for a $Q(\mathbb{P}_{XY})$ independence measure [Rényi, 1959]:
 - 1. $Q(\mathbb{P}_{XY})$ is well-defined,
 - 2. $Q(\mathbb{P}_{XY}) \in [0,1]$,
 - 3. $Q(\mathbb{P}_{XY}) = 0$ iff. $X \perp Y$.
 - 4. $Q(\mathbb{P}_{XY}) = 1$ iff. Y = f(X) or X = g(Y).

Example-2: continued

• He showed:

$$Q(\mathbb{P}_{XY}) = \sup_{f,g: \text{ measurable}} \operatorname{corr}(f(X), g(Y)),$$

satisfies 1-4.

- Too ambitious:
 - computationally intractable.
 - many measurable functions.

Example-2: continued; measurable \rightarrow continuous

- $C_b(\mathfrak{X}) = \{f : \mathfrak{X} \text{ metric} \to \mathbb{R}, \text{ bounded continuous}\}$ would also work.
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Key: balance

denseness \rightarrow universality, computation \rightarrow RKHS.



Motivation: kernels = generalized inner product

- Various data types.
- **2** RKHS: flexible ($\stackrel{1:1}{\longleftrightarrow}$ probability measures).
- **3** Still computationally tractable: $k(x_i, x_i) \in \mathbb{R}$.
- **9** RKHS: Hilbert \Rightarrow statistical analysis.
- v-RKHS $[k(x, x') \in \mathcal{L}(Y)]$: dependency among output coordinates.

Kernel, RKHS: definition, kernel factory

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• Def-2 (reproducing kernel):

$$k(\cdot, x) \in \mathcal{H}, \qquad f(x) = \langle f, k(\cdot, x) \rangle_{\mathcal{H}}.$$

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- All these definitions are equivalent, $k \stackrel{1:1}{\leftrightarrow} \mathcal{H}_k$.
- Examples on \mathbb{R}^d ($\gamma > 0$, $p \in \mathbb{Z}^+$): $k_p(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle + \gamma)^p$, $k_G(\mathbf{x}, \mathbf{y}) = e^{-\gamma ||\mathbf{x} \mathbf{y}||_2^2}$, $k_e(\mathbf{x}, \mathbf{y}) = e^{-\gamma ||\mathbf{x} \mathbf{y}||_2}$.

Some kernel-enriched domains : (\mathfrak{X}, k)

- Strings
 - [Watkins, 1999, Lodhi et al., 2002, Leslie et al., 2002, Kuang et al., 2004, Leslie and Kuang, 2004, Saigo et al., 2004, Cuturi and Vert, 2005],
- time series [Rüping, 2001, Cuturi et al., 2007, Cuturi, 2011, Király and Oberhauser, 2019],
- trees [Collins and Duffy, 2001, Kashima and Koyanagi, 2002],
- groups and specifically rankings [Cuturi et al., 2005, Jiao and Vert, 2016],
- sets [Haussler, 1999, Gärtner et al., 2002, Balanca and Herbin, 2012, Fellmann et al., 2023], probability distributions
 [Berlinet and Thomas-Agnan, 2004, Hein and Bousquet, 2005, Smola et al., 2007, Sriperumbudur et al., 2010a],
- various generative models [Jaakkola and Haussler, 1999, Tsuda et al., 2002, Seeger, 2002, Jebara et al., 2004],
- fuzzy domains [Guevara et al., 2017], or
- graphs [Kondor and Lafferty, 2002, Gärtner et al., 2003, Kashima et al., 2003, Borgwardt and Kriegel, 2005, Shervashidze et al., 2009, Vishwanathan et al., 2010, Kondor and Pan, 2016, Bai et al., 2020, Borgwardt et al., 2020, Schulz et al., 2022, Nikolentzos and Vazirgiannis, 2023].

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 - **2** Cone. If $k_m: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$ kernel, $\alpha_m \geq 0$ (m = 1, ..., M), then

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Example: $\bigoplus_{m=1}^{M} \mathbb{R} = \mathbb{R}^{M}$.

• Product. If $(k_m)_{m=1}^M$ are kernels on \mathfrak{X}_m , then

$$(\otimes_{m=1}^{M} k_m) ((x_1, \ldots, x_M), (x'_1, \ldots, x'_M)) = \prod_{m=1}^{M} k_m (x_m, x'_m).$$

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- Thus, $(k_m)_{m=1}^M: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$ kernels $\Rightarrow \prod_{m=1}^M k_m(x, x')$: kernel on \mathfrak{X} .
- Consequence $(\gamma \geq 0, p \in \mathbb{Z}^+)$:

$$k(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle_2 + \gamma)^p$$

is a kernel.

$$(k_1 \otimes k_2)((x,y),(x',y')) = k_1(x,x')k_2(y,y')$$

$$\begin{aligned} \left(\mathbf{k_1} \otimes \mathbf{k_2} \right) \left((x, y), (x', y') \right) &= \mathbf{k_1}(x, x') \mathbf{k_2}(y, y') \\ &= \left\langle \varphi_1(x), \varphi_1(x') \right\rangle_{\mathfrak{H}_1} \left\langle \varphi_2(y), \varphi_2(y') \right\rangle_{\mathfrak{H}_2} \\ &= \varphi_1(x)^\top \varphi_1(x') \varphi_2\left(y'\right)^\top \varphi_2(y) \end{aligned}$$

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Let M=2 and assume that $\varphi_m(x) \in \mathbb{R}^{d_m}$:

$$\begin{split} \left(k_{1} \otimes k_{2} \right) \left((x,y), (x',y') \right) &= k_{1}(x,x')k_{2}(y,y') \\ &= \left\langle \varphi_{1}(x), \varphi_{1}(x') \right\rangle_{\mathcal{H}_{1}} \left\langle \varphi_{2}(y), \varphi_{2}(y') \right\rangle_{\mathcal{H}_{2}} \\ &= \varphi_{1}(x)^{\top} \varphi_{1}(x') \varphi_{2} \left(y' \right)^{\top} \varphi_{2}(y) \\ &= \operatorname{tr} \left(\varphi_{1}(x)^{\top} \varphi_{1}(x') \varphi_{2} \left(y' \right)^{\top} \varphi_{2}(y) \right) \\ &= \operatorname{tr} \left(\varphi_{2}(y) \varphi_{1}(x)^{\top} \varphi_{1}(x') \varphi_{2}(y')^{\top} \right) \\ &= \left\langle \underbrace{\varphi_{1}(x) \varphi_{2}(y)^{\top}}_{\in \mathbb{R}^{d_{1} \times d_{2}}}, \underbrace{\varphi_{1}(x') \varphi_{2}(y')^{\top}}_{\in \mathbb{R}^{d_{1} \times d_{2}}} \right\rangle_{F} , \end{split}$$

where $\langle \mathbf{A}, \mathbf{B} \rangle_{\mathsf{F}} = \operatorname{tr} \left(\mathbf{A}^{\top} \mathbf{B} \right) = \sqrt{\sum_{ij} A_{ij} B_{ij}}$ is the Frobenius inner product.

6 Limit. If $(k_n)_{n\in\mathbb{N}}$ are kernels on \mathfrak{X} , then

$$k(x,x') := \lim_{n\to\infty} k_n(x,x')$$

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$$k(\mathbf{x}, \mathbf{y}) = e^{\gamma \langle \mathbf{x}, \mathbf{y} \rangle_2} = \sum_{n \in \mathbb{N}} \frac{\left(\gamma \langle \mathbf{x}, \mathbf{y} \rangle_2\right)^n}{n!}$$

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Reason: polynomial kernel & limit rule.

O Pre-post multiplication. k kernel on \mathfrak{X} , $f: \mathfrak{X} \to \mathbb{R}$, then

$$\tilde{k}(x,y) = f(x)k(x,y)f(y)$$

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Example (Gaussian kernel, $\gamma > 0$): previous example & new rule

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Properties of \mathcal{H}_k , computational tractability

Properties of k control that of \mathcal{H}_k

[Steinwart and Christmann, 2008, Chapter 4]:

• k: bounded $[\sup_{x,y\in\mathcal{X}} k(x,y) \leq C] \Rightarrow \forall f\in\mathcal{H}_k$ is bounded

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- k: analytic $\Rightarrow \forall f \in \mathcal{H}_k$ is analytic.

Representer theorem

[Schölkopf et al., 2001, Yu et al., 2013]

- Given: $\{(x_i, y_i)\}_{i=1}^n$, say classification/regression.
- Goal:

$$J(f) = V(x_1, y_1, f(x_1), \dots, x_n, y_n, f(x_n)) + r(\|f\|_{\mathcal{H}_k}^2) \to \min_{\mathcal{H}_k},$$

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r: monotonically increasing.

Example:

$$V(\ldots) = \frac{1}{n} \sum_{i=1}^{n} \max(1 - y_i f(x_i), 0) \quad \text{(soft classification)},$$

$$V(\ldots) = \frac{1}{n} \sum_{i=1}^{n} [f(x_i) - y_i]^2 \quad \text{(regression)}.$$

Representer theorem - continued

. . . then

• ∃ solution in the form:

$$f^* = \sum_{i=1}^n \alpha_i k(\cdot, x_i), \quad \alpha_i \in \mathbb{R}.$$

- r: strictly increasing $\Rightarrow \forall$ solution is of this form.
- Example: $r(z) = \lambda z$, $\lambda > 0$.

Representer theorem – proof

Objective

$$J(f) = V(x_1, y_1, f(x_1), \dots, x_n, y_n, f(x_n)) + r\left(\|f\|_{\mathcal{H}_k}^2\right) \to \min_{f \in \mathcal{H}_k}.$$

Decompose & Pythagorean theorem:

$$S = \operatorname{span}(k(\cdot, x_i), i \in [n]),$$

$$f = f_S + f_{\perp},$$

$$\|f\|_{\mathcal{H}_k}^2 = \|f_S\|_{\mathcal{H}_k}^2 + \underbrace{\|f_{\perp}\|_{\mathcal{H}_k}^2}_{>0} \ge \|f_S\|_{\mathcal{H}_k}^2.$$

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ln J

• 1st term: depends on f_S only, $f(x_i) = \langle f, k(\cdot, x_i) \rangle_{\mathcal{H}_k}$.

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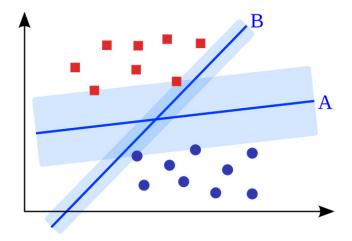
In J

- 1st term: depends on f_S only, $f(x_i) = \langle f, k(\cdot, x_i) \rangle_{\mathcal{H}_k}$.
- 2nd term: can only decrease by neglecting f_{\perp} $(r \nearrow)$.

Classification: SVMC

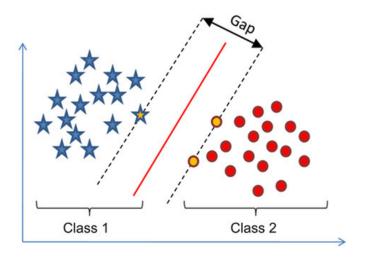
Support vector machine for classification: SVMC

Which separating line is the 'best'?



SVMC

Answer: the one with the largest margin.



- Hyperplane: $f_{\mathbf{w},b}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle + b$,
 - w: normal vector, b: offset.

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Shortly,

$$\min_{\mathbf{w},b} \|\mathbf{w}\|_2^2$$
, s.t. $y_i(\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1, \forall i$.

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Shortly,

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• Decision: $\hat{y}(\mathbf{x}) = \text{sign}(\langle \mathbf{w}, \mathbf{x} \rangle + b)$.

SVM formulation: soft classification

• Hard classification objective:

$$\min_{\mathbf{w},b} \|\mathbf{w}\|_2^2 \text{ s.t. } y_i \left(\langle \mathbf{w}, \mathbf{x}_i \rangle + b \right) \geq 1, \forall i.$$

There might not be solution! (non-linearly separable case)

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Soft classification objective:

$$\min_{\mathbf{w},b,\xi} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} \text{ s.t. } y_{i} (\langle \mathbf{w}, \mathbf{x}_{i} \rangle + b) \geq 1 - \xi_{i}, \, \xi_{i} \geq 0, \, \forall i.$$

Linear penalty on misclassification.

Note on the soft objective of SVMC

$$\min_{\mathbf{w},b,\xi} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} \text{ s.t. } y_{i} (\langle \mathbf{w}, \mathbf{x}_{i} \rangle + b) \ge 1 - \xi_{i}, \, \xi_{i} \ge 0, \, \forall i$$

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, \min_{\mathbf{w},b,\xi} \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \max \left(1 - y_{i} \left(\underbrace{\langle \mathbf{w}, \mathbf{x}_{i} \rangle + b}_{=f(\mathbf{x}_{i})} \right), 0 \right),
=: h(y_{i}f(\mathbf{x}_{i}))$$

where $h(u) = \max(1 - u, 0)$ is the hinge loss.

Note on the soft objective of SVMC – continued

The hinge loss is the convex envelope of the zero-one loss:

$$z(u) = \mathbb{I}_{u<0},$$

$$h(u) = \max(1-u,0).$$

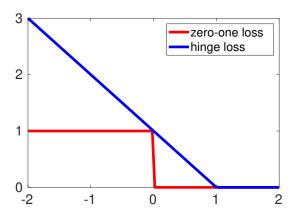
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Lagrangian function: with $\alpha_i \geq 0, \beta_i \geq 0 \ (\forall i)$

$$L(\mathbf{w}, b, \boldsymbol{\xi}; \alpha, \beta) = \text{objective} - \text{Lagrangian multipliers} \times \text{conditions}$$

$$= \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} - \sum_{i=1}^{n} \alpha_{i} [y_{i} (\langle \mathbf{w}, \mathbf{x}_{i} \rangle + b) - 1 + \xi_{i}] - \sum_{i=1}^{n} \beta_{i} \xi_{i}.$$

Solving for $\frac{\partial L}{\partial primal} = 0$, we get . . .

SVM formulation: soft classification

$$L(\mathbf{w}, b, \boldsymbol{\xi}; \boldsymbol{\alpha}, \boldsymbol{\beta}) =$$

$$= \frac{1}{2} \|\mathbf{w}\|_{2}^{2} + C \sum_{i=1}^{n} \xi_{i} - \sum_{i=1}^{n} \alpha_{i} \left[y_{i} \left(\langle \mathbf{w}, \mathbf{x}_{i} \rangle + b \right) - 1 + \xi_{i} \right] - \sum_{i=1}^{n} \beta_{i} \xi_{i}.$$

Optimality equations:

$$\mathbf{0} = \frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_{i=1}^{n} \alpha_{i} y_{i} \mathbf{x}_{i} \quad (\mathbf{w} \leftrightarrow \alpha),$$

$$0 = \frac{\partial L}{\partial b} = \sum_{i=1}^{n} \alpha_{i} y_{i},$$

$$0 = \frac{\partial L}{\partial \varepsilon} = C - \alpha_{i} - \beta_{i}.$$

Plugging these equations back to L, we have . . .

SVM formulation: soft classification

Dual form:

$$\max_{\alpha} \underbrace{\sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} \langle \mathbf{x}_{i}, \mathbf{x}_{j} \rangle}_{\text{quadratic in } \alpha}, \text{ s.t. } \underbrace{0 \leq \alpha_{i} \leq C, \sum_{i=1}^{n} \alpha_{i} y_{i} = 0}_{\text{linear in } \alpha}.$$

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• $b \leftarrow y_i(\langle \mathbf{w}, \mathbf{x}_i \rangle + b) = 1 \leftarrow \alpha_i > 0$ [complementary slackness].

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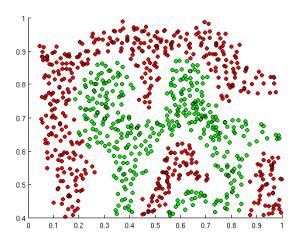
- $b \Leftarrow y_i(\langle \mathbf{w}, \mathbf{x}_i \rangle + b) = 1 \Leftarrow \alpha_i > 0$ [complementary slackness].
- QP: solvers are available.

If linear separability does not hold

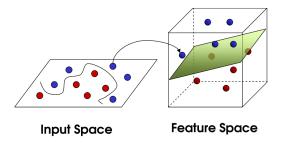
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- Until this point:
 - (almost) linearly separable case.
- Now:



If linear separability does not hold: kernel trick



Nonlinear SVM

• Linear SVM (dual):

$$\max_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} \langle \mathbf{x}_{i}, \mathbf{x}_{j} \rangle, \text{ s.t. } \sum_{i=1}^{n} \alpha_{i} y_{i} = 0, \ 0 \leq \alpha_{i} \leq C \ (\forall i).$$

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$$\max_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_{i} \alpha_{j} y_{i} y_{j} \frac{k(x_{i}, x_{j})}{k(x_{i}, x_{j})}, \text{ s.t. } \sum_{i=1}^{n} \alpha_{i} y_{i} = 0, \ 0 \leq \alpha_{i} \leq C \ (\forall i).$$

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Nonlinear SVM (dual):

$$\max_{\alpha} \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_i \alpha_j y_i y_j k(x_i, x_j), \text{ s.t. } \sum_{i=1}^{n} \alpha_i y_i = 0, \ 0 \le \alpha_i \le C \ (\forall i).$$

Nonlinear SVM (primal):

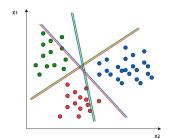
$$\min_{f \in \mathcal{H}_k, \xi} \frac{1}{2} \|f\|_{\mathcal{H}_k}^2 + C \sum_{i=1}^n \xi_i, \text{ s.t. } y_i f(x_i) \ge 1 - \xi_i, \ \xi_i \ge 0, \ \forall i.$$

Multiclass (say M) classification with SVM

Idea

Break down the problem to multiple binary classification problems.

- one-to-one approach:
 - $\frac{M(M-1)}{2}$ SVMC-s, i vs. j ($i \neq j$),
 - on new input x: the class with the most votes is predicted.

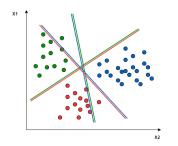


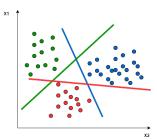
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- 2 one-to-rest approach:
 - M SVMC-s, each predicts one class.
 - Classifiers give real-valued confidence scores: $f_m(x)$, $m \in [M]$.
 - Decision: $\hat{m} = \arg \max_{m \in [M]} f_m(x)$.





- Split data:
 - training set (X_{tr}, Y_{tr}) : $X_{val,m}, Y_{val,m}, m \in [M]$.
 - test set: X_{te} , Y_{te} .

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- **1** Report: performance of θ^* on X_{te} , Y_{te} .

Regression: kernel ridge regression

Kernel ridge regression (KRR)

- Given: $\{(x_i, y_i)\}_{i=1}^n$, $\mathcal{H} := \mathcal{H}_k$, $y_i \in \mathbb{R}$.
- Task $(\lambda > 0)$:

$$J(f) = \frac{1}{n} \sum_{i=1}^{n} [y_i - f(x_i)]^2 + \lambda \|f\|_{\mathcal{H}}^2 \to \min_{f \in \mathcal{H}}.$$

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Analytical solution:

$$f(x) = [k(x_1, x), \dots, k(x_n, x)] (\mathbf{G} + \lambda n \mathbf{I}_n)^{-1} [y_1; \dots; y_n],$$

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Question

How do we get this solution?

By the representer theorem

$$f=\sum_{i=1}^n a_i k(\cdot,x_i), \quad (a_i\in\mathbb{R}).$$

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Multiplying the objective by n, using the reproducing property:

$$J(f) = \sum_{j=1}^{n} [y_j - \langle f, k(\cdot, x_j) \rangle_{\mathfrak{H}}]^2 + \lambda n \|f\|_{\mathfrak{H}}^2$$

= $\|\mathbf{y} - \mathbf{G}\mathbf{a}\|_2^2 + (\lambda n)\mathbf{a}^{\mathsf{T}}\mathbf{G}\mathbf{a}$
= $\mathbf{y}^{\mathsf{T}}\mathbf{y} - 2\mathbf{y}^{\mathsf{T}}\mathbf{G}\mathbf{a} + \mathbf{a}^{\mathsf{T}}[\mathbf{G}^2 + (\lambda n)\mathbf{G}]\mathbf{a}$.

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, one gets $\mathbf{a}^*=(\mathbf{G}+\lambda n\mathbf{I}_n)^{-1}\mathbf{y}$ by

$$\frac{\partial \mathbf{a}^{\top} \mathbf{B} \mathbf{a}}{\partial \mathbf{a}} = \left(\mathbf{B} + \mathbf{B}^{\top} \right) \mathbf{a}, \ \frac{\partial \mathbf{c}^{\top} \mathbf{a}}{\partial \mathbf{a}} = \mathbf{c}.$$

Kernel machines: a simple algorithm = SGD [Kivinen et al., 2004]

Empirical regularized risk:

$$\min_{f \in \mathcal{H}_k} J(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i) + \frac{\lambda}{2} \|f\|_{\mathcal{H}_k}^2 \quad (\lambda > 0).$$

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Update (learning rate: $\eta_t > 0$):

$$f_{t+1} = f_t - \eta_t \underbrace{\frac{\partial J_{\text{inst}}(f, (x_t, y_t))}{\partial f}\Big|_{f = f_t}}_{\frac{\partial \ell(z, y)}{\partial z}\Big|_{z = f_t(x_t), y = y_t} k(\cdot, x_t) + \lambda f_t}.$$

Note: if ℓ is non-differentiable, subgradient is taken.

- Initialization: $f_1 = 0$.
- ② By the representer theorem:

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Update (from the previous slide):

$$f_{t+1} = f_t - \eta_t \left[\ell'(f_t(x_t), y_t) k(\cdot, x_t) + \lambda f_t \right]$$

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• \Leftrightarrow Update (in terms of coefficients): For $i \in [t]$,

$$\alpha_i := \begin{cases} -\eta_t \ell'(f_t(x_t), y_t) & \text{if } i = t, \\ (1 - \eta_t \lambda)\alpha_i & \text{if } i < t. \end{cases}$$

Optimizers+

Recall the dual problem:

$$\max_{\alpha} \sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} \alpha_i \alpha_j y_i y_j \mathbf{k}(\mathbf{x}_i, \mathbf{x}_j), \text{ s.t. } \sum_{i=1}^{n} \alpha_i y_i = 0, \ 0 \le \alpha_i \le C(\forall i).$$

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- For KRR:
 - scaling to billions of points [Meanti et al., 2020],
 - \bullet idea: Nyström method + pre-conditioned conjugate gradient solver + GPU.
- For large-scale classification (+recent survey), see [Tanji et al., 2023]:
 - ullet Nyström technique + accelerated stochastic subgradient descent.

Maximal correlation: KCCA

KCCA: definition

- Given: $k: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}, \ \ell: \mathfrak{Y} \times \mathfrak{Y} \to \mathbb{R}.$
- Associated:
 - feature maps $\varphi(x) = k(\cdot, x), \ \psi(y) = \ell(\cdot, y),$
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 - RKHS-s \mathcal{H}_k , \mathcal{H}_ℓ .
- KCCA measure of $(X, Y) \in X \times Y$

$$\rho_{\mathsf{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell) = \sup_{f \in \mathcal{H}_k, \mathbf{g} \in \mathcal{H}_\ell} \operatorname{corr}(f(X), \mathbf{g}(Y)),$$
$$\operatorname{corr}(f(X), \mathbf{g}(Y)) = \frac{\operatorname{cov}(f(X), \mathbf{g}(Y))}{\sqrt{\operatorname{var}[f(X)] \operatorname{var}[\mathbf{g}(Y)]}}.$$

KCCA: notes

- Optimization domain: $\mathcal{H}_k \times \mathcal{H}_\ell \ni (f,g)$.
- By reproducing property: we will get a finite-D task.
- k,ℓ linear: traditional CCA.
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Recall the reproducing property

$$f(x) = \langle f, k(\cdot, x) \rangle_{\mathcal{H}_k} \quad \forall f \in \mathcal{H}_k, x \in \mathcal{X}.$$

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^{N} \left[\underbrace{f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i)}_{} \right] \left[\underbrace{g(y_n) - \frac{1}{N} \sum_{i=1}^{N} g(y_i)}_{} \right] \left[\underbrace{f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i)}_{} \right] \left[\underbrace{g(y_n) - \frac{1}{N} \sum_{i=1}^{N} g(y_i)}_{} \right] \left[\underbrace{g(y_n) - \frac{1}{N} \sum_{i=1}^{N$$

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$$= \frac{1}{N} \sum_{n=1}^{N} \left\langle f, \tilde{\varphi}(x_n) \right\rangle_{\mathfrak{R}_k} \left\langle g, \tilde{\psi}(y_n) \right\rangle_{\mathfrak{R}_\ell},$$

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Similarly:

$$\widehat{\text{var}}[f(X)] = \frac{1}{N} \sum_{n=1}^{N} \left[f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i) \right]^2$$

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has no affect in the objective.

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Key idea

Enough to consider
$$f = \sum_{i=1}^{N} c_i \tilde{\varphi}(x_i)$$
, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$.

Using that
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, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$:

$$\langle f, \tilde{\varphi}(\mathbf{x}_n) \rangle_{\mathfrak{H}_k} = \sum_{i=1}^N c_i \langle \tilde{\varphi}(\mathbf{x}_i), \tilde{\varphi}(\mathbf{x}_n) \rangle_{\mathfrak{H}_k} = \sum_{i=1}^N c_i \tilde{k}(\mathbf{x}_i, \mathbf{x}_n) = (\mathbf{c}^\top \tilde{\mathbf{G}}_X)_n,$$

Using that $f = \sum_{i=1}^{N} c_i \tilde{\varphi}(x_i)$, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$:

$$\begin{split} \langle f, \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} &= \sum_{i=1}^N c_i \, \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} \, = \sum_{i=1}^N c_i \tilde{k}(x_i, x_n) = (\mathbf{c}^\top \tilde{\mathbf{G}}_X)_n, \\ \langle g, \tilde{\psi}(y_n) \rangle_{\mathfrak{H}_s} &= (\mathbf{d}^\top \tilde{\mathbf{G}}_Y)_n, \end{split}$$

with the centered kernels $(\tilde{k}, \tilde{\ell})$ and Gram matrices $(\tilde{\mathbf{G}}_X, \tilde{\mathbf{G}}_Y)$.

Until now

All the objective terms can be expressed by \mathbf{c} , \mathbf{d} , $\tilde{\mathbf{G}}_X$, $\tilde{\mathbf{G}}_Y$.

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^{N} \langle f, \widetilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} \langle g, \widetilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell},$$

$$\widehat{\operatorname{var}}[f(X)] = \frac{1}{N} \sum_{n=1}^{N} \langle f, \widetilde{\varphi}(x_n) \rangle_{\mathcal{H}_k}^2, \widehat{\operatorname{var}}[g(Y)] = \frac{1}{N} \sum_{n=1}^{N} \langle g, \widetilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell}^2,$$

and we have

$$\langle f, \tilde{\varphi}(\mathsf{x}_n) \rangle_{\mathfrak{H}_k} = (\mathbf{c}^{\top} \tilde{\mathbf{G}}_X)_n, \qquad \langle g, \tilde{\psi}(\mathsf{y}_n) \rangle_{\mathfrak{H}_{\ell}} = (\mathbf{d}^{\top} \tilde{\mathbf{G}}_Y)_n.$$

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^{N} \langle f, \widetilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} \langle g, \widetilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell},$$

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and we have

$$\langle f, \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} = (\mathbf{c}^{\top} \tilde{\mathbf{G}}_X)_n, \qquad \langle g, \tilde{\psi}(y_n) \rangle_{\mathfrak{H}_{\ell}} = (\mathbf{d}^{\top} \tilde{\mathbf{G}}_Y)_n.$$

Thus,

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \mathbf{c}^{\top} \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \mathbf{d},$$

$$\widehat{\operatorname{var}}[f(X)] = \frac{1}{N} \mathbf{c}^{\top} (\tilde{\mathbf{G}}_{X})^{2} \mathbf{c}, \quad \widehat{\operatorname{var}}[g(Y)] = \frac{1}{N} \mathbf{d}^{\top} (\tilde{\mathbf{G}}_{Y})^{2} \mathbf{d}.$$

KCCA: finite-D form

Empirical estimate of KCCA:

$$\widehat{\rho_{\mathsf{KCCA}}}^{\mathsf{temp}}(X,Y;\mathcal{H}_k,\mathcal{H}_\ell) = \sup_{\mathbf{c} \in \mathbb{R}^N, \mathbf{d} \in \mathbb{R}^N} \frac{\mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}}{\sqrt{\mathbf{c}^\top (\tilde{\mathbf{G}}_X)^2 \mathbf{c}} \sqrt{\mathbf{d}^\top (\tilde{\mathbf{G}}_Y)^2 \mathbf{d}}}.$$

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In practice ($\kappa > 0$):

$$\begin{split} \widehat{\rho_{\mathsf{KCCA}}}(X,Y) &:= \widehat{\rho_{\mathsf{KCCA}}}(X,Y;\mathcal{H}_{k},\mathcal{H}_{\ell},\kappa) \\ &= \sup_{\mathbf{c} \in \mathbb{R}^{N}, \mathbf{d} \in \mathbb{R}^{N}} \frac{\mathbf{c}^{\top} \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \mathbf{d}}{\sqrt{\mathbf{c}^{\top} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} \mathbf{c}} \sqrt{\mathbf{d}^{\top} (\tilde{\mathbf{G}}_{Y} + \kappa \mathbf{I}_{N})^{2} \mathbf{d}}}. \end{split}$$

Question

How do we solve it?

KCCA: solution

Stationary points of $\widehat{\rho_{\mathsf{KCCA}}}(X,Y)$:

$$\boldsymbol{0} = \frac{\partial \widehat{\rho_{\text{KCCA}}}(\boldsymbol{X}, \boldsymbol{Y})}{\partial \boldsymbol{c}}, \qquad \qquad \boldsymbol{0} = \frac{\partial \widehat{\rho_{\text{KCCA}}}(\boldsymbol{X}, \boldsymbol{Y})}{\partial \boldsymbol{d}},$$

which simplifies to

$$\tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y}\mathbf{d} = \frac{(\mathbf{c}^{\top}\tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y}\mathbf{d})(\tilde{\mathbf{G}}_{X} + \kappa\mathbf{I}_{N})^{2}\mathbf{c}}{\mathbf{c}^{\top}(\tilde{\mathbf{G}}_{X} + \kappa\mathbf{I}_{N})^{2}\mathbf{c}}, \ \tilde{\mathbf{G}}_{Y}\tilde{\mathbf{G}}_{X}\mathbf{c} = \frac{(\mathbf{d}^{\top}\tilde{\mathbf{G}}_{Y}\tilde{\mathbf{G}}_{X}\mathbf{c})(\tilde{\mathbf{G}}_{Y} + \kappa\mathbf{I}_{N})^{2}\mathbf{d}}{\mathbf{d}^{\top}(\tilde{\mathbf{G}}_{Y} + \kappa\mathbf{I}_{N})^{2}\mathbf{d}}$$

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Normalization:

- (\mathbf{c}, \mathbf{d}) : solution $\Rightarrow (a\mathbf{c}, b\mathbf{d})$: solution $a, b \in \mathbb{R} \setminus \{0\}$.
- denominators := 1.

KCCA: final task

Find the maximal eigenvalue, $\lambda := \mathbf{c}^{\top} \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \mathbf{d}$, of the generalized eigenvalue problem:

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

$$\mathbf{A}\mathbf{z} = \lambda \mathbf{B}\mathbf{z}.$$

Note: Python implementation in the ITE toolbox ($M \ge 2$, with acceleration).

Summary

- Kernel, RKHS: generalized inner product, linear methods.
- Computational tractability: representer theorem.
- Classification: SVMC.
- Regression: kernel ridge regression.
- Maximal correlation: KCCA.

Summary

- Kernel, RKHS: generalized inner product, linear methods.
- Computational tractability: representer theorem.
- Classification: SVMC.
- Regression: kernel ridge regression.
- Maximal correlation: KCCA.



Contents (KCCA: questions)

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1 (Is KCCA an independence measure? (\Leftarrow universality)
2 (Meaning/handling of the regularization) (\kappa).
3 (M \ge 2 components).
4 (Computation of \tilde{\mathbf{G}}_X, \tilde{\mathbf{G}}_Y).
```

Q1 (independence measure) \leftarrow universal k, ℓ

If $X \perp Y$, then $\rho_{KCCA}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) = 0$. Opposite direction:

• For 'rich' \mathcal{H}_k , \mathcal{H}_ℓ [Bach and Jordan, 2002, Gretton et al., 2005].

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- For 'rich' \mathcal{H}_k , \mathcal{H}_ℓ [Bach and Jordan, 2002, Gretton et al., 2005].
- Enough: universal kernel on a compact metric domain.
- Example $(\gamma > 0)$:
 - Gaussian: $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} \mathbf{x}'\|_2^2}$.
 - \bullet Laplacian kernel: $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} \mathbf{x}'\|_2}$.

Definition

Assume:

- \mathfrak{X} : compact metric space.
- k: continuous kernel on \mathfrak{X} .

k is called (c)-universal [Steinwart, 2001] if \mathcal{H}_k is dense in $(C(X), \|\cdot\|_{\infty})$.

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Assumptions

- \mathcal{X} assumption $\Rightarrow C(\mathcal{X}) = C_b(\mathcal{X})$.
- k: continuous, X: compact $\Rightarrow k$: bounded.
- k: continuous, bounded $\Rightarrow \mathcal{H}_k \subset C(\mathfrak{X})$ [Steinwart and Christmann, 2008].
- Extensions of c-universality to non-compact spaces:
 - c₀-universality, cc-universality,
 ... [Carmeli et al., 2010, Sriperumbudur et al., 2010b,
 Simon-Gabriel and Schölkopf, 2018].

If k is universal, then

•
$$k(x,x) > 0$$
 for all $x \in \mathcal{X}$.

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$$\rho_k(x,y) = \|\varphi(x) - \varphi(y)\|_{\mathcal{H}_k}$$

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is a metric.

• The normalized kernel (recall: corr)

$$\tilde{k}(x,y) := \frac{k(x,y)}{\sqrt{k(x,x)k(y,y)}}$$

is universal.

Q1: universal Taylor kernels [Steinwart, 2001, Steinwart and Christmann, 2008]

ullet For an $C^\infty \ni f: (-r,r) \to \mathbb{R}$

$$f(t) = \sum_{n=0}^{\infty} a_n t^n \quad t \in (-r, r), \ r \in (0, \infty].$$

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$$f(t) = \sum_{n=0}^{\infty} a_n t^n \quad t \in (-r, r), \ r \in (0, \infty].$$

• If $a_n > 0 \ \forall n$, then

$$k(\mathbf{x}, \mathbf{y}) = f(\langle \mathbf{x}, \mathbf{y} \rangle)$$

is universal on
$$\mathfrak{X}:=\left\{\mathbf{x}\in\mathbb{R}^{d}:\left\Vert \mathbf{x}\right\Vert _{2}\leq\sqrt{r}\right\}$$
.

Q1: universal kernels on compact subsets of \mathbb{R}^d , $\alpha > 0$

• $k(\mathbf{x}, \mathbf{y}) = e^{\alpha(\mathbf{x}, \mathbf{y})}$: previous result with $f(t) = e^{\alpha t} \Rightarrow a_n = \frac{\alpha^n}{n!}$.

Q1: universal kernels on compact subsets of \mathbb{R}^d , $\alpha > 0$

- $k(\mathbf{x}, \mathbf{y}) = e^{\alpha \langle \mathbf{x}, \mathbf{y} \rangle}$: previous result with $f(t) = e^{\alpha t} \Rightarrow a_n = \frac{\alpha^n}{n!}$.
- $k(\mathbf{x}, \mathbf{y}) = e^{-\alpha \|\mathbf{x} \mathbf{y}\|_2^2}$: exp. kernel & normalization.

Q1: universal kernels on compact subsets of \mathbb{R}^d , $\alpha > 0$

- $k(\mathbf{x}, \mathbf{y}) = (1 \langle \mathbf{x}, \mathbf{y} \rangle)^{-\alpha}$ binomial kernel
 - $\bullet \ \ \text{on} \ \ \mathfrak{X} \ \text{compact} \subset \{\mathbf{x} \in \mathbb{R}^d: \left\|\mathbf{x}\right\|_2 < 1\}.$

•
$$f(t) = (1-t)^{-\alpha} = \sum_{n=0}^{\infty} \frac{\binom{-\alpha}{n} (-1)^n}{\binom{n}{n}} t^n \quad (|t| < 1),$$

where
$$\binom{b}{n} = \sum_{i=1}^{n} \frac{b-i+1}{i}$$
.

Contents

Q2 (κ)

In fact, we estimated

$$\begin{split} \rho_{\mathsf{KCCA}}(X,Y;\mathcal{H}_k,\mathcal{H}_\ell,\kappa) &= \sup_{f \in \mathcal{H}_k, g \in \mathcal{H}_\ell} \mathrm{corr}(f(X),g(Y);\kappa), \\ &\mathrm{corr}(f(X),g(Y);\kappa) = \frac{\mathrm{cov}(f(X),g(Y))}{\sqrt{\mathrm{var}[f(X)] + \kappa \|f\|_{\mathcal{H}_k}^2} \sqrt{\mathrm{var}[g(Y)] + \kappa \|g\|_{\mathcal{H}_\ell}^2}} \end{split}$$

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For consistent KCCA estimate:

- $\kappa_N \to 0$ [Leurgans et al., 1993](spline-RKHS), [Fukumizu et al., 2007] (general RKHS).
- analysis: covariance operators.

Contents

Q3 ($M \ge 2$): symmetry, other form

For

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

 $([\mathbf{c}, \mathbf{d}], \lambda)$ solution $\Rightarrow ([-\mathbf{c}; \mathbf{d}], -\lambda)$: solution. Thus, eigenvalues:

$$\{\lambda_1, -\lambda_1, \ldots, \lambda_N, -\lambda_N\}.$$

Q3 (
$$M \ge 2$$
): symmetry, other form

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 $([\mathbf{c}, \mathbf{d}], \lambda)$ solution $\Rightarrow ([-\mathbf{c}; \mathbf{d}], -\lambda)$: solution. Thus, eigenvalues:

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Adding the r.h.s. to both sides:

$$\begin{bmatrix} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} & \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \\ \tilde{\mathbf{G}}_{Y} \tilde{\mathbf{G}}_{X} & (\tilde{\mathbf{G}}_{Y} + \kappa \mathbf{I}_{N})^{2} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

with eigenvalues $\{1 + \lambda_1, 1 - \lambda_1, \dots, 1 + \lambda_N, 1 - \lambda_N\}$.

Q3
$$(M \ge 2)$$

2-variables [(X, Y)]:

$$\begin{bmatrix} (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 & \tilde{\mathbf{G}}_{\mathsf{X}} \tilde{\mathbf{G}}_{\mathsf{Y}} \\ \tilde{\mathbf{G}}_{\mathsf{Y}} \tilde{\mathbf{G}}_{\mathsf{X}} & (\tilde{\mathbf{G}}_{\mathsf{Y}} + \kappa \mathbf{I}_{\mathsf{N}})^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

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For *M*-variables (pairwise dependence):

$$\begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_2 & \dots & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_M \\ \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_1 & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_M \\ \vdots & \vdots & & \vdots \\ \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_1 & \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_2 & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix} = \\ \gamma \begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \mathbf{0} \\ \vdots & & \vdots & & \\ \mathbf{0} & \mathbf{0} & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix}.$$

$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H}$$
 with $\mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}$; \mathbf{H} ; $\mathbf{E}_N \in \mathbb{R}^{N \times N}$.

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$$\begin{split} (\tilde{\mathbf{G}}_{X})_{ij} &= \tilde{k}(x_{i}, x_{j}) = \langle \tilde{\varphi}(x_{i}), \tilde{\varphi}(x_{j}) \rangle_{\mathcal{H}_{k}} \\ &= \langle \varphi(x_{i}) - \frac{1}{N} \sum_{n=1}^{N} \varphi(x_{n}), \varphi(x_{j}) - \frac{1}{N} \sum_{m=1}^{N} \varphi(x_{m}) \rangle_{\mathcal{H}_{k}} \end{split}$$

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$$\begin{aligned} (\tilde{\mathbf{G}}_{X})_{ij} &= \tilde{k}(x_{i}, x_{j}) = \langle \tilde{\varphi}(x_{i}), \tilde{\varphi}(x_{j}) \rangle_{\mathcal{H}_{k}} \\ &= \langle \varphi(x_{i}) - \frac{1}{N} \sum_{n=1}^{N} \varphi(x_{n}), \varphi(x_{j}) - \frac{1}{N} \sum_{m=1}^{N} \varphi(x_{m}) \rangle_{\mathcal{H}_{k}} \\ &= (\mathbf{G}_{X})_{ij} - \frac{1}{N} \sum_{m=1}^{N} (\mathbf{G}_{X})_{im} - \frac{1}{N} \sum_{n=1}^{N} (\mathbf{G}_{X})_{ni} - \frac{1}{N^{2}} \sum_{n,m=1}^{N} (\mathbf{G}_{X})_{nm} \end{aligned}$$

$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H}$$
 with $\mathbf{H} = \mathbf{I}_N - rac{\mathbf{E}_N}{N}$; \mathbf{H} ; $\mathbf{E}_N \in \mathbb{R}^{N \times N}$.

$$\begin{split} (\tilde{\mathbf{G}}_{X})_{ij} &= \tilde{k}(x_{i}, x_{j}) = \langle \tilde{\varphi}(x_{i}), \tilde{\varphi}(x_{j}) \rangle_{\mathcal{H}_{k}} \\ &= \langle \varphi(x_{i}) - \frac{1}{N} \sum_{n=1}^{N} \varphi(x_{n}), \varphi(x_{j}) - \frac{1}{N} \sum_{m=1}^{N} \varphi(x_{m}) \rangle_{\mathcal{H}_{k}} \\ &= (\mathbf{G}_{X})_{ij} - \frac{1}{N} \sum_{m=1}^{N} (\mathbf{G}_{X})_{im} - \frac{1}{N} \sum_{n=1}^{N} (\mathbf{G}_{X})_{ni} - \frac{1}{N^{2}} \sum_{n,m=1}^{N} (\mathbf{G}_{X})_{nm} \\ &= \left(\mathbf{G}_{X} - \mathbf{G}_{X} \frac{\mathbf{E}_{N}}{N} - \frac{\mathbf{E}_{N}}{N} \mathbf{G}_{X} - \frac{\mathbf{E}_{N}}{N} \mathbf{G}_{X} \frac{\mathbf{E}_{N}}{N} \right)_{ij}, \end{split}$$

In short

$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H}$$
 with $\mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}$; \mathbf{H} ; $\mathbf{E}_N \in \mathbb{R}^{N \times N}$.

$$\begin{split} (\tilde{\mathbf{G}}_{X})_{ij} &= \tilde{k}(x_{i}, x_{j}) = \left\langle \tilde{\varphi}(x_{i}), \tilde{\varphi}(x_{j}) \right\rangle_{\mathfrak{H}_{k}} \\ &= \left\langle \varphi(x_{i}) - \frac{1}{N} \sum_{n=1}^{N} \varphi(x_{n}), \varphi(x_{j}) - \frac{1}{N} \sum_{m=1}^{N} \varphi(x_{m}) \right\rangle_{\mathfrak{H}_{k}} \\ &= (\mathbf{G}_{X})_{ij} - \frac{1}{N} \sum_{m=1}^{N} (\mathbf{G}_{X})_{im} - \frac{1}{N} \sum_{n=1}^{N} (\mathbf{G}_{X})_{ni} - \frac{1}{N^{2}} \sum_{n,m=1}^{N} (\mathbf{G}_{X})_{nm} \\ &= \left(\mathbf{G}_{X} - \mathbf{G}_{X} \frac{\mathbf{E}_{N}}{N} - \frac{\mathbf{E}_{N}}{N} \mathbf{G}_{X} - \frac{\mathbf{E}_{N}}{N} \mathbf{G}_{X} \frac{\mathbf{E}_{N}}{N} \right)_{ij}, \\ &= (\mathbf{H}\mathbf{G}_{X}\mathbf{H})_{ij}, \end{split}$$

 \mathbf{H} : symmetric ($\mathbf{H} = \mathbf{H}^{\top}$), idempotent ($\mathbf{H}^2 = \mathbf{H}$). Contents

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