Independence Measures and Testing

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Contents

- Examples.
- Independence measures based on
 - copula,
 - maximum correlation,
 - distance,
 - kernel.

- ullet $X=(X_1,\ldots,X_M)\in imes_{m\in[M]}\mathfrak{X}_m.$ X_m : m^{th} 'coordinate' of X. $X\sim\mathbb{P}.$
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$$\|\phi - \prod_{m \in [M]} \phi_m\|_{L^2(w)}$$
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4 Kernel: $C = \text{covariance of } X \text{ under some feature } \varphi$.

$$\|C\|_{\mathsf{HS}} = D(\mathbb{P}, \otimes_{m \in [M]} \mathbb{P}_m)$$
.

Our questions

- Validness.
- (Statistical) properties.
- Stimation.
- 4 Applications.

Code (Python)

- Information theoretical estimators (ITE) toolbox:
 - 53 entropy, independence, divergence, association measures and kernels of probability distributions,
 - (by at least an order) the largest package in the domain,
 - ullet \sim 80 successful projects worldwide.
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- Independence testing toolbox:

```
https://github.com/wittawatj/fsic-test
```

Examples

Independent subspace analysis [Cardoso, 1998]

Cocktail party problem:

- independent groups of people / music bands,
- observation = mixed sources.



ISA equations

Observation:

$$\mathbf{x}_t = \mathbf{A}\mathbf{s}_t, \qquad \qquad \mathbf{s} = \left[\mathbf{s}^1; \dots; \mathbf{s}^M\right].$$

Goal: $\hat{\mathbf{s}}$ from $\{\mathbf{x}_1, \dots, \mathbf{x}_T\}$. Assumptions:

- ullet independent groups: $I\left(\mathbf{s}^{1},\ldots,\mathbf{s}^{M}
 ight)=0$,
- **s**^m-s: non-Gaussian,
- A: invertible.

ISA solution

Find **W** which makes the estimated components independent:

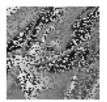
$$\mathbf{y} = \mathbf{W}\mathbf{x} = \left[\mathbf{y}^1; \dots; \mathbf{y}^M\right],$$

$$J(\mathbf{W}) = I\left(\mathbf{y}^1, \dots, \mathbf{y}^M\right) \to \min_{\mathbf{W}}.$$

Outlier-robust image registration [Kybic, 2004, Neemuchwala et al., 2007]

Given two images:

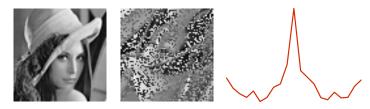




Goal: find the transformation which takes the right one to the left.

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Outlier-robust image registration: equations

- Reference image: y_{ref},
- test image: y_{test},
- possible transformations: Θ.

Objective:

$$J(\theta) = \underbrace{J(\mathbf{y}_{\mathsf{ref}}, \mathbf{y}_{\mathsf{test}}(\theta))}_{\mathsf{similarity}} o \max_{\theta \in \mathbf{\Theta}},$$

Feature selection

- Goal: find
 - the feature subset (# of rooms, criminal rate, local taxes)
 - most relevant for house price prediction (y).



Feature selection: equations

- Features: x^1, \ldots, x^F . Subset: $S \subseteq \{1, \ldots, F\}$.
- MaxRelevance MinRedundancy principle [Peng et al., 2005]:

$$J(S) = \frac{1}{|S|} \sum_{i \in S} I\left(x^i, y\right) - \frac{1}{|S|^2} \sum_{i, j \in S} I\left(x^i, x^j\right) \to \max_{S \subseteq \{1, \dots, F\}}.$$

Independence testing: translation

- How do we detect dependency? (paired samples)
- x₁: Honourable senators, I have a question for the Leader of the Government in the Senate with regard to the support funding to farmers that has been announced. Most farmers have not received any money yet.
- x2: No doubt there is great pressure on provincial and municipal governments in relation to the issue of child care, but the reality is that there have been no cuts to child care funding from the federal government to the provinces. In fact, we have increased federal investments for early childhood development.

. . .

- y₁: Honorables sénateurs, ma question s'adresse au leader du gouvernement au Sénat et concerne l'aide financiére qu'on a annoncée pour les agriculteurs. La plupart des agriculteurs n'ont encore rien reu de cet argent.
- y₂: Il est évident que les ordres de gouvernements provinciaux et municipaux subissent de fortes pressions en ce qui concerne les services de garde, mais le gouvernement n'a pas réduit le financement qu'il verse aux provinces pour les services de garde. Au contraire, nous avons augmenté le financement fédéral pour le développement des jeunes enfants.

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Are the French paragraphs translations of the English ones, or have nothing to do with it, i.e. $\mathbb{P}_{XY} = \mathbb{P}_X \otimes \mathbb{P}_Y$?

Dependency testing of media annotations

- We are given paired samples. Task: test independence.
- Examples:
 - (song, year of release) pairs



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 $\bullet \ \{(\mathbf{x}_n, y_n)\}_{n \in [N]} \xrightarrow{?} H_0 : \mathbb{P}_{XY} = \mathbb{P}_X \otimes \mathbb{P}_Y, \ H_1 : \mathbb{P}_{XY} \neq \mathbb{P}_X \otimes \mathbb{P}_Y.$

Copula

Setting, Sklar's theorem [Nelsen, 2006]

- Setting: $\mathbf{X} = [X_m]_{m \in [M]} \in \mathbb{R}^M$.
- Cdf of **X** and X_m -s:

$$F(\mathbf{x}) = \mathbb{P}(\mathbf{X} \leq \mathbf{x}), \qquad F_m(x) = \mathbb{P}(X_m \leq x).$$

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• Sklar's theorem: $\exists !$ a function (copula) $C: [0,1]^M \to [0,1]$ s.t.

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• C: It represents the joint distribution of $U_m = F_m(X_m)$

$$C(\mathbf{u}) = \mathbb{P}(\mathbf{U} \leq \mathbf{u}), \quad \mathbf{U} = [F_m(X_m)]_{m \in [M]}, \quad \mathbf{u} \in [0, 1]^M.$$



Copula bounds

For any copula C

$$W(\mathbf{u}) \leq C(\mathbf{u}) \leq M(\mathbf{u}), \quad \forall \mathbf{u} \in [0,1]^M,$$

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• W: Fréchet-Hoeffding lower bound. Copula for M=2 only.

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$$M(\mathbf{u}) = \min_{m \in [M]} u_m.$$

- W: Fréchet-Hoeffding lower bound. Copula for M=2 only.
- M:
 - Fréchet-Hoeffding upper bound (comonotonicity copula).
 - Strictly increasing functional relation between X_i and X_j .

Copula: independence

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, $\Pi(u_1, \ldots, u_M) = \prod_{m \in [M]} u_m$.

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• L^p distance of C and Π :

$$I_p(C) = [h_p(M)]^{\frac{1}{p}} \|C - \Pi\|_{L^p([0,1]^M)}, \quad p \in [1,\infty].$$

Normalizing constant $h_p(M)$: to ensure $I_p(C) \in [0,1]$.

For $p \in \{1, 2, \infty\}$

• p = 2: Hoeffding's Φ [Gaißer et al., 2010, Schmid et al., 2010],

$$\Phi^{2}(C) = h_{2}(M) \int_{[0,1]^{M}} [C(\mathbf{u}) - \Pi(\mathbf{u})]^{2} d\mathbf{u},$$
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$$= \frac{2}{(M+1)(M+2)} - \frac{1}{2^{M}} \frac{M!}{\prod_{i=0}^{M} (i+\frac{1}{2})} + \frac{1}{3^{M}}.$$

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• For p=1 and $p=\infty$: Schweizer-Wolff's σ and κ [Schweizer and Wolff, 1981] (M=2).

Properties

Normalization:

$$\Phi^{2}(C) \in [0,1], \quad \forall C,$$

$$\Phi^{2}(C) = 0 \Leftrightarrow C = \Pi,$$

$$\Phi^{2}(C) = 1 \Leftrightarrow C = M \qquad (M \ge 3),$$

$$\Leftrightarrow C = M \text{ or } C = W \qquad (M = 2).$$

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2 Invariance w.r.t. permutations: for any π permutation

$$\Phi^2(\mathbf{X}) = \Phi^2(\pi(\mathbf{X})).$$

Properties – continued

3 Monotonicity: For any C_1 , C_2 , C_3 , C_4 copula for which

$$W \preccurlyeq C_1 \preccurlyeq C_2 \preccurlyeq \square \preccurlyeq C_3 \preccurlyeq C_4 \preccurlyeq M$$

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 - $M \ge 2$: strictly increasing transformation of the coordinates.
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Properties - continued

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Approaching Π , the value of Φ^2 is decreasing.

- Invariance under strictly monotone transformations:
 - $M \ge 2$: strictly increasing transformation of the coordinates.
 - M = 2: strictly decreasing transformation of one/both coordinates.
- Continuity:

$$(C_n)_{n\in\mathbb{N}}\xrightarrow{n\to\infty} C$$
 pointwise $\Rightarrow \Phi^2(C_n)\xrightarrow{n\to\infty} \Phi^2(C)$.



Estimation of Φ^2

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$$\hat{U}_{m,n} = \hat{F}_m(X_{m,n}) = \frac{1}{N} (\text{rank of } X_{m,n} \text{ in } X_{m,1}, \dots, X_{m,N}).$$

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Empirical copula:

$$\hat{C}_{N}(\mathbf{u}) = \frac{1}{N} \sum_{n \in [N]} \prod_{m \in [M]} \mathbb{I}_{\left\{\hat{U}_{m,n} \leq u_{m}\right\}}, \, \mathbf{u} \in [0,1]^{M}.$$

Estimation of Φ^2 – continued

Recall:

$$\begin{split} \Phi^2(C) &= h_2(M) \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u})]^2 \mathrm{d}\mathbf{u}, \\ [h_2(M)]^{-1} &= \frac{2}{(M+1)(M+2)} - \frac{1}{2^M} \frac{M!}{\prod_{i=0}^M \left(i + \frac{1}{2}\right)} + \frac{1}{3^M}. \end{split}$$

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Estimator:

$$\widehat{\Phi_N^2}(\mathit{C}) = \Phi^2\left(\hat{\mathit{C}}_N\right) = \mathit{h}_2(\mathit{M}) \underbrace{\int_{[0,1]^\mathit{M}} \left[\hat{\mathit{C}}_N(\mathbf{u}) - \Pi(\mathbf{u})\right]^2 \mathrm{d}\mathbf{u}}_{=:(*)}.$$

Estimation of Φ^2 – continued

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Good news

(*) can also be computed analytically!

Computation of (*)

$$\int_{[0,1]^M} \left[\hat{C}_N(\mathbf{u}) - \prod_m u_m \right]^2 d\mathbf{u} = \int_{[0,1]^M} \left[\frac{1}{N} \sum_n \prod_m \mathbb{I}_{\left\{ \hat{U}_{m,n} \leq u_m \right\}} - \prod_m u_m \right]^2 d\mathbf{u}$$

(i):
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Computation of (*)

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$$\stackrel{(i)}{=} \int_{[0,1]^M} \left[\frac{1}{N} \sum_n \underbrace{\left(\prod_m \mathbb{I}_{\left\{ \hat{U}_{m,n} \leq u_m \right\}} - \prod_m u_m \right)}_{h_n} \right]^2 d\mathbf{u}$$

(i):
$$\frac{1}{N} \sum_{n \in [N]} \mathbf{a} = \mathbf{a}$$
, (ii) $\left(\frac{1}{N} \sum_{n \in [N]} \mathbf{b}_n\right)^2 = \frac{1}{N^2} \sum_{j,k \in [N]} \mathbf{b}_j \mathbf{b}_k$, $\int \leftrightarrow \sum$.

Computation of (*)

$$\begin{split} &\int_{[0,1]^M} \left[\hat{\mathcal{C}}_{N}(\mathbf{u}) - \prod_{m} u_{m} \right]^{2} \mathrm{d}\mathbf{u} = \int_{[0,1]^M} \left[\frac{1}{N} \sum_{n} \prod_{m} \mathbb{I}_{\left\{ \hat{U}_{m,n} \leq u_{m} \right\}} - \prod_{m} u_{m} \right]^{2} \mathrm{d}\mathbf{u} \\ &\stackrel{(i)}{=} \int_{[0,1]^M} \left[\frac{1}{N} \sum_{n} \underbrace{\left(\prod_{m} \mathbb{I}_{\left\{ \hat{U}_{m,n} \leq u_{m} \right\}} - \prod_{m} u_{m} \right)}_{b_{n}} \right]^{2} \mathrm{d}\mathbf{u} \\ &\stackrel{(ii)}{=} \frac{1}{N^{2}} \sum_{j,k \in [N]} \int_{[0,1]^M} \underbrace{\left(\prod_{m} \mathbb{I}_{\left\{ \hat{U}_{m,j} \leq u_{m} \right\}} - \prod_{m} u_{m} \right)}_{b_{n}} \underbrace{\left(\prod_{m} \mathbb{I}_{\left\{ \hat{U}_{m,k} \leq u_{m} \right\}} - \prod_{m} u_{m} \right)}_{d} \mathrm{d}\mathbf{u}. \end{split}$$

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$$\frac{1}{N^2} \sum_{j,k \in [N]} \int_{[0,1]^M} \left(\prod_m \mathbb{I}_{\left\{\hat{U}_{m,j} \leq u_m\right\}} - \prod_m u_m \right) \left(\prod_m \mathbb{I}_{\left\{\hat{U}_{m,k} \leq u_m\right\}} - \prod_m u_m \right)$$

(i)
$$(a - b)(c - d) = ac + bd - ad - bc$$

$$\frac{1}{N^2} \sum_{j,k \in [N]} \int_{[0,1]^M} \left(\prod_{m} \mathbb{I}_{\left\{\hat{U}_{m,j} \leq u_m\right\}} - \prod_{m} u_m \right) \left(\prod_{m} \mathbb{I}_{\left\{\hat{U}_{m,k} \leq u_m\right\}} - \prod_{m} u_m \right) \\
\stackrel{(i)}{=} \frac{1}{N^2} \sum_{j,k \in [N]} \int_{[0,1]^M} \left[\left(\prod_{m} \mathbb{I}_{\left\{\max(\hat{U}_{m,j},\hat{U}_{m,k}) \leq u_m\right\}} + \prod_{m \in [M]} u_m^2 \right) \\
- \prod_{m} u_m \mathbb{I}_{\left\{\hat{U}_{m,j} \leq u_m\right\}} - \prod_{m} u_m \mathbb{I}_{\left\{\hat{U}_{m,k} \leq u_m\right\}} \right] d\mathbf{u}.$$
(i) $(a-b)(c-d) = ac + bd - ad - bc$

$$\int_{[0,1]^M} \prod_{m} \mathbb{I}_{\left\{\max(\hat{\boldsymbol{U}}_{m,j},\hat{\boldsymbol{U}}_{m,k}) \leq u_m\right\}} \mathrm{d}\mathbf{u} \stackrel{(i)}{=} \prod_{m} \int_{[0,1]} \mathbb{I}_{\left\{\max(\hat{\boldsymbol{U}}_{m,j},\hat{\boldsymbol{U}}_{m,k}) \leq u_m\right\}} \mathrm{d}u_m$$

(i)
$$\int_{[0,1]^M} \prod_m \frac{f_m(u_m)}{du} du = \prod_m \int_{[0,1]} f_m(u_m) du_m$$

$$\begin{split} \int_{[0,1]^M} \prod_{m} \mathbb{I}_{\left\{\max(\hat{U}_{m,j},\hat{U}_{m,k}) \leq u_m\right\}} \mathrm{d}\mathbf{u} &\stackrel{\text{(i)}}{=} \prod_{m} \int_{[0,1]} \mathbb{I}_{\left\{\max(\hat{U}_{m,j},\hat{U}_{m,k}) \leq u_m\right\}} \mathrm{d}u_m \\ &\stackrel{\text{(ii)}}{=} \prod_{m} \left[1 - \max(\hat{U}_{m,j},\hat{U}_{m,k})\right], \end{split}$$

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$$\int_{[0,1]^M} \prod_m f_m(u_m) \mathrm{d} \mathbf{u} = \prod_m \int_{[0,1]} f_m(u_m) \mathrm{d} u_m$$
 , (ii) $\int_{[0,1]} \mathbb{I}_{\{a \leq u\}} \mathrm{d} u = 1 - a$

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$$\begin{split} \int_{[0,1]^{M}} \prod_{m} & \mathbb{I}_{\left\{ \max(\hat{U}_{m,j}, \hat{U}_{m,k}) \leq u_{m} \right\}} \mathrm{d}\mathbf{u} \overset{(i)}{=} \prod_{m} \int_{[0,1]} \mathbb{I}_{\left\{ \max(\hat{U}_{m,j}, \hat{U}_{m,k}) \leq u_{m} \right\}} \mathrm{d}u_{m} \\ & \overset{(ii)}{=} \prod_{m} \left[1 - \max(\hat{U}_{m,j}, \hat{U}_{m,k}) \right], \\ & \int_{[0,1]^{M}} \prod_{m} u_{m}^{2} \mathrm{d}\mathbf{u} \overset{(i)}{=} \prod_{m} \int_{[0,1]} u_{m}^{2} \mathrm{d}\mathbf{u} = \prod_{m} \left[\frac{u_{m}^{3}}{3} \right]_{0}^{1} = \frac{1}{3^{M}}, \\ & \int_{[0,1]^{M}} \prod_{m} u_{m} \mathbb{I}_{\left\{ \hat{U}_{m,j} \leq u_{m} \right\}} \mathrm{d}\mathbf{u} \overset{(i)}{=} \prod_{m} \int_{[0,1]} u_{m} \mathbb{I}_{\left\{ \hat{U}_{m,j} \leq u_{m} \right\}} \mathrm{d}u_{m} \\ & \overset{(iii)}{=} \frac{1}{2^{M}} \prod_{m} \left(1 - \hat{U}_{m,j}^{2} \right). \end{split}$$

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$$\int_{[0,1]^M} \prod_m f_m(u_m) d\mathbf{u} = \prod_m \int_{[0,1]} f_m(u_m) du_m$$
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(*): collecting the terms

$$(*) = \frac{1}{N^2} \sum_{j,k \in [N]} \prod_{m} \left[1 - \max \left(\hat{U}_{m,j}, \hat{U}_{m,k} \right) \right] + \frac{1}{3^M} - \frac{2}{N} \frac{1}{2^M} \sum_{j \in [N]} \prod_{m} \left(1 - \hat{U}_{m,j}^2 \right).$$

Easiness came from

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Next step

application in independence testing.

- Given $\prod_{m \in [M]} \mathfrak{X}_m \ni (\mathbf{X}_n)_{n \in [N]} \sim \mathbb{P}$ samples, level $\alpha \in (0,1)$.
- Goal: to check if

$$H_0: \mathbb{P} = \otimes_{m \in [M]} \mathbb{P}_m, \qquad \quad H_1: \mathbb{P} \neq \otimes_{m \in [M]} \mathbb{P}_m.$$

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- Decision:
 - compute a test statistic: $T(\mathbf{X}_1, \dots, \mathbf{X}_N)$. Example: $\hat{\Phi}_N^2$.
 - $F_T := \operatorname{cdf} \operatorname{of} T(\mathbf{X}_1, \dots, \mathbf{X}_N)$ under H_0 : null distribution.
 - $q := its (1 \alpha)$ -quantile.
 - reject H_0 if $T(\mathbf{X}_1,\ldots,\mathbf{X}_N) > q$.

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 - $q := its (1 \alpha)$ -quantile.
 - reject H_0 if $T(\mathbf{X}_1, \dots, \mathbf{X}_N) > q$.
- Good to have F_T , and the distribution of $T(\mathbf{X}_1, \dots, \mathbf{X}_N)$ under the alternative (power).

Towards the null distribution for Φ^2

Warm-up: recall that $C \in L^{\infty}\left([0,1]^{M}\right)$. $\Rightarrow \hat{C}_{N}$: $L^{\infty}\left([0,1]^{M}\right)$ -valued r.v.

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Theorem (Asymptotic behaviour of the empirical copula process)

Assume that $\partial^m C$ continuous for all $m \in [M]$. Then

$$\sqrt{N} \left(\hat{C}_N - C \right) \xrightarrow{w} \mathbb{G}_C,$$

$$\mathbb{G}_C(\mathbf{u}) = \mathbb{B}_C(\mathbf{u}) - \sum_{m \in [M]} \partial^m C(\mathbf{u}) \mathbb{B}_C \left(\mathbf{u}^{(m)} \right),$$

$$\mathbf{u}^{(m)} = [1; \dots; 1; u_m; 1; \dots; 1],$$

where \mathbb{B}_C is a (tight) centered GP on $[0,1]^M$ with covariance function, \wedge acts coordinate-wise,

$$\mathbb{E}\left[\mathbb{B}_{C}(\mathbf{u})\mathbb{B}_{C}(\mathbf{v})\right] = C(\mathbf{u} \wedge \mathbf{v}) - C(\mathbf{u})C(\mathbf{v}).$$

 \mathbb{B}_{C} : is the so-called M-dimensional Brownian bridge.

• If $C \neq \Pi$ (see H_1):

$$\begin{split} \sqrt{N} \left(\hat{\Phi}_N^2 - \Phi^2 \right) & \xrightarrow{w} N \left(0, \sigma^2 \right), \\ \sigma^2 &= \left[2h_2(M) \right]^2 \int_{[0,1]^M} \int_{[0,1]^M} \left[C(\mathbf{u}) - \Pi(\mathbf{u}) \right] \\ &\times \mathbb{E}[\mathbb{G}_C(\mathbf{u}) \mathbb{G}_C(\mathbf{v})] \left[C(\mathbf{v}) - \Pi(\mathbf{v}) \right] \mathrm{d}\mathbf{u} \mathrm{d}\mathbf{v}. \end{split}$$

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• If $C = \Pi$ (see H_0):

$$\sqrt{N}(\hat{C}_N-\Pi)\xrightarrow{w}\mathbb{G}_\Pi,\quad N\hat{\Phi}_N^2=\mathit{h}_2(M)\int_{[0,1]^M}N[\hat{C}_N(u)-\Pi(u)]^2\mathrm{d}\boldsymbol{u}$$

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asymptotic null distribution (simulation)

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asymptotic null distribution (simulation)

How was the $C \neq \Pi$ case obtained?

The delta method: idea

 $\bullet \ \, \text{We know} \, \sqrt{N} [\hat{C}_N - C] \xrightarrow{w} T := \mathbb{G}_C.$

The delta method: idea

- We know $\sqrt{N}[\hat{C}_N C] \xrightarrow{w} T := \mathbb{G}_C$.
- Let $\varphi(C) := \Phi^2(C)$. One expects that

$$\sqrt{N}[\varphi(\hat{C}_N) - \varphi(C)] \approx \sqrt{N}\varphi'_C(\hat{C}_N - C)$$

$$\xrightarrow{w} \varphi'_C(T).$$

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Good news

This heuristic goes through with the <u>right</u> notion of differentiability [van der Vaart, 1998, Chapter 18, 20].

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Good news

This heuristic goes through with the <u>right</u> notion of differentiability [van der Vaart, 1998, Chapter 18, 20].

• $\varphi: L^{\infty}\left([0,1]^{M}\right) \to \mathbb{R}$. Gateaux (directional) / Hadamard / Fréchet (classical). On \mathbb{R}^{d} : Hadamard = Fréchet.

Hadamard differentiability

- $\varphi: L^{\infty}\left([0,1]^{M}\right) \to \mathbb{R}.$
- Its derivative at copula $C \in L^{\infty}\left([0,1]^{M}\right)$, shortly φ'_{C} , is a continuous linear functional for which

$$\left|\frac{\varphi(C+t_nD_n)-\varphi(C)}{t_n}-\varphi'_C(D)\right|\xrightarrow{n\to\infty}0$$

for all $t_n \xrightarrow{n \to \infty} 0$, $D_n \xrightarrow{n \to \infty} D$. Note: direction D_n might change with n, but eventually converge.

Computing the Hadamard derivative

$$\frac{\varphi(C + t_n D_n) - \varphi(C)}{t_n} = \frac{h_2(M) \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u}) + t_n D_n(\mathbf{u})]^2 d\mathbf{u}}{t_n} - \frac{h_2(M) \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u})]^2 d\mathbf{u}}{t_n}$$

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$$(a + b)^2 - a^2 = 2ab + b^2$$
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$$- \frac{h_2(M) \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u})]^2 d\mathbf{u}}{t_n}$$

$$\stackrel{\text{(i)}}{=} \frac{2h_2(M) t_n \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u})] D_n(\mathbf{u}) d\mathbf{u}}{t_n} + \underbrace{\frac{t_n^2 \int_{[0,1]^M} [D_n(\mathbf{u})]^2 d\mathbf{u}}{t_n}}_{\to 0}$$

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\stackrel{\text{(i)}}{=} \frac{2h_2(M) t_n \int_{[0,1]^M} [C(\mathbf{u}) - \Pi(\mathbf{u})] D_n(\mathbf{u}) d\mathbf{u}}{t_n} + \underbrace{\frac{t_n^2 \int_{[0,1]^M} [D_n(\mathbf{u})]^2 d\mathbf{u}}{t_n}}_{\to 0} \\
\rightarrow \int_{[0,1]^M} \underbrace{2h_2(M) [C(\mathbf{u}) - \Pi(\mathbf{u})] D(\mathbf{u})}_{f_{C,D}(\mathbf{u})} d\mathbf{u} = \underbrace{\varphi'_C(D)}_{C(D)}.$$
(i) $(\mathbf{a} + \mathbf{b})^2 - \mathbf{a}^2 = 2\mathbf{a}\mathbf{b} + \mathbf{b}^2$.

Hadamard derivative: wrap up

We got that

$$\sqrt{N}[\varphi(\hat{C}_N) - \varphi(C)] \xrightarrow{w} \varphi'_C(\mathbb{G}_C)$$

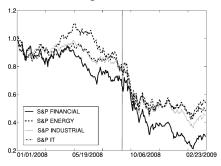
Using that $\mathbb{G}_{\mathcal{C}}$ is a tight GP, with Lemma 3.9.8 [van der Vaart and Wellner, 2000] implies

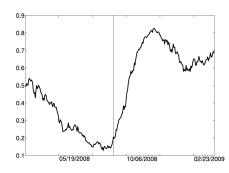
$$\begin{split} \varphi_{C}'(\mathbb{G}_{C}) &= \textit{N}\left(0,\sigma^{2}\right), \\ \sigma^{2} &= \int_{[0,1]^{M}} \int_{[0,1]^{M}} \mathbb{E}[\textit{f}_{C,\mathbb{G}_{C}}(\textbf{u})\textit{f}_{C,\mathbb{G}_{C}}(\textbf{v})] \mathrm{d}\textbf{u} \mathrm{d}\textbf{v} \end{split}$$

as claimed.

A financial application [Gaißer et al., 2010]

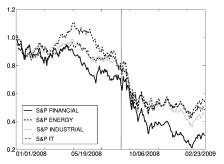
• We consider 4 global sector indices.

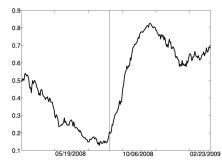




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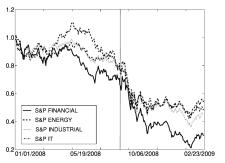


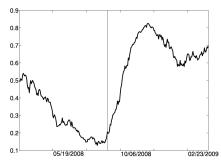


• Sept. 15, 2008: bankrupcy of Lehman Brothers Inc.

A financial application [Gaißer et al., 2010]

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- Sept. 15, 2008: bankrupcy of Lehman Brothers Inc.
- ullet Left: steep decay. Right: high dependency captured by $\hat{\Phi}_N^2$.

Hoeffding Φ^2 : summary

- Valid independence measure: $\mathfrak{X}_m = \mathbb{R}$, $M \geq 2$.
- Various favorable properties.
- Estimator: plug-in, analytic formula.
- Null distribution: continuous mapping theorem (Brownian bridge, simulation),
- Alternative: normal (delta method, Hadamard derivative).

Maximum correlation

Independence measures

- Given: random variable $(X, Y) \in \mathcal{X} \times \mathcal{Y}$, $(X, Y) \sim \mathbb{P}_{XY}$.
- Goal: measure the dependence of X and Y.

Independence measures

- Given: random variable $(X, Y) \in \mathfrak{X} \times \mathfrak{Y}$, $(X, Y) \sim \mathbb{P}_{XY}$.
- Goal: measure the dependence of X and Y.
- Desiderata for a $Q(\mathbb{P}_{XY})$ independence measure [Rényi, 1959]:
 - 1. $Q(\mathbb{P}_{XY})$ is well-defined,
 - 2. $Q(\mathbb{P}_{XY}) \in [0,1],$
 - 3. $Q(\mathbb{P}_{XY}) = 0$ iff. $X \perp Y$.
 - 4. $Q(\mathbb{P}_{XY}) = 1$ iff. Y = f(X) or X = g(Y).

Independence measures

• He showed:

$$Q(\mathbb{P}_{XY}) = \sup_{f,g: \text{ measurable}} \operatorname{corr}(f(X), g(Y)),$$

satisfies 1-4.

- Too ambitious:
 - computationally intractable.
 - many measurable functions.

Independence measures: measurable \rightarrow continuous

- $C_b(\mathfrak{X}) = \{f : \mathfrak{X} \text{ metric} \to \mathbb{R}, \text{ bounded continuous}\}$ would also work.
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 - dense in $C_b(\mathfrak{X})$,
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Key: Balance

denseness \rightarrow universality, computation \rightarrow RKHS.

• Def-1 (feature space):

$$k(x, y) = \langle \varphi(x), \varphi(y) \rangle_{\mathcal{H}} \quad x, y \in \mathcal{X}.$$

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Constructively, $\mathcal{H}_k = \overline{\{\sum_{i=1}^n \alpha_i k(\cdot, x_i)\}}$.

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- Def-4 (evaluation): $\delta_x(f) = f(x)$ is continuous for all x.
- All these definitions are equivalent, $k \stackrel{1:1}{\leftrightarrow} \mathcal{H}_k$.
- Examples on \mathbb{R}^d ($\gamma > 0$, $p \in \mathbb{Z}^+$): $k_p(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle + \gamma)^p$, $k_G(\mathbf{x}, \mathbf{y}) = e^{-\gamma ||\mathbf{x} \mathbf{y}||_2^2}$, $k_e(\mathbf{x}, \mathbf{y}) = e^{-\gamma ||\mathbf{x} \mathbf{y}||_2}$.

Kernels [Steinwart and Christmann, 2008, Saitoh and Sawano, 2016]: various data types

- strings
 - [Watkins, 1999, Lodhi et al., 2002, Leslie et al., 2002, Kuang et al., 2004, Leslie and Kuang, 2004, Saigo et al., 2004, Cuturi and Vert, 2005],
- time series
 [Rüping, 2001, Cuturi et al., 2007, Cuturi, 2011, Király and Oberhauser, 2019],
- trees [Collins and Duffy, 2001, Kashima and Koyanagi, 2002],
- groups and specifically rankings [Cuturi et al., 2005, Jiao and Vert, 2016],
- sets [Haussler, 1999, Gärtner et al., 2002],
- various generative models [Jaakkola and Haussler, 1999, Tsuda et al., 2002, Seeger, 2002, Jebara et al., 2004],
- fuzzy domains [Guevara et al., 2017], or
- graphs [Kondor and Lafferty, 2002, Gärtner et al., 2003, Kashima et al., 2003, Borgwardt and Kriegel, 2005, Shervashidze et al., 2009, Vishwanathan et al., 2010, Kondor and Pan, 2016, Draief et al., 2018, Bai et al., 2020, Borgwardt et al., 2020].

KCCA: definition

- Given: $k: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}, \ell: \mathfrak{Y} \times \mathfrak{Y} \to \mathbb{R}$.
- Associated:
 - feature maps $\varphi(x) = k(\cdot, x)$, $\psi(y) = \ell(\cdot, y)$,
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 - RKHS-s \mathcal{H}_k , \mathcal{H}_ℓ .
- KCCA measure of $(X, Y) \in \mathfrak{X} \times \mathfrak{Y}$

$$\rho_{\mathsf{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell) = \sup_{f \in \mathcal{H}_k, g \in \mathcal{H}_\ell} \operatorname{corr}(f(X), g(Y)),$$
$$\operatorname{corr}(f(X), g(Y)) = \frac{\operatorname{cov}(f(X), g(Y))}{\sqrt{\operatorname{var}[f(X)] \operatorname{var}[g(Y)]}}.$$

KCCA: notes

- Optimization domain: $\mathcal{H}_k \times \mathcal{H}_\ell \ni (f,g)$.
- By reproducing property: we will get a finite-D task.
- k,ℓ linear: traditional CCA.
- In practice: we have $\{(x_n, y_n)\}_{n=1}^N$ samples from (X, Y).

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- Optimization domain: $\mathcal{H}_k \times \mathcal{H}_\ell \ni (f,g)$.
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- In practice: we have $\{(x_n, y_n)\}_{n=1}^N$ samples from (X, Y).

Recall the reproducing property

$$f(x) = \langle f, k(\cdot, x) \rangle_{\mathcal{H}_k} \quad \forall f \in \mathcal{H}_k, x \in \mathcal{X}.$$

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^{N} \left[\underbrace{f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i)}_{} \right] \left[\underbrace{g(y_n) - \frac{1}{N} \sum_{i=1}^{N} g(y_i)}_{} \right] \left\langle f, \varphi(x_n) - \frac{1}{N} \sum_{i=1}^{N} \varphi(x_i) \right\rangle_{\mathcal{H}_{\delta}} \left\langle g, \psi(y_n) - \frac{1}{N} \sum_{i=1}^{N} \psi(y_i) \right\rangle_{\mathcal{H}_{\delta}}$$

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$$= \frac{1}{N} \sum_{n=1}^{N} \left\langle f, \widetilde{\varphi}(x_n) \right\rangle_{\mathfrak{R}_{\ell}} \left\langle g, \widetilde{\psi}(y_n) \right\rangle_{\mathfrak{R}_{\ell}},$$

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\left\langle f, \varphi(x_n) - \frac{1}{N} \sum_{i=1}^{N} \varphi(x_i) \right\rangle_{\mathfrak{R}_k} \left\langle g, \psi(y_n) - \frac{1}{N} \sum_{i=1}^{N} \psi(y_i) \right\rangle_{\mathfrak{R}_\ell} \\
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Similarly:

$$\widehat{\text{var}}[f(X)] = \frac{1}{N} \sum_{n=1}^{N} \left[f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i) \right]^2$$

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$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^{N} \left[\underbrace{f(x_n) - \frac{1}{N} \sum_{i=1}^{N} f(x_i)}_{} \right] \left[\underbrace{g(y_n) - \frac{1}{N} \sum_{i=1}^{N} g(y_i)}_{} \right] \left(\underbrace{f, \varphi(x_n) - \frac{1}{N} \sum_{i=1}^{N} \varphi(x_i)}_{} \right) \left(\underbrace{g, \psi(y_n) - \frac{1}{N} \sum_{i=1}^{N} \psi(y_i)}_{} \right)_{\mathfrak{R}_{\ell}}$$

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$$\widehat{\operatorname{var}}[g(Y)] = \frac{1}{N} \sum_{i=1}^{N} \langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell}^2.$$

• f: appears only as $\langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k}$ [similarly: g in $\langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_s}$]. \Rightarrow

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- \forall component of $f \perp$

$$span\left(\{\tilde{\varphi}(x_n)\}_{n=1}^N\right) = \left\{\sum_{n=1}^N c_n \tilde{\varphi}(x_n), \mathbf{c} = [c_n] \in \mathbb{R}^N\right\}$$

has no affect in the objective.

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has no affect in the objective.

Key idea

Enough to consider
$$f = \sum_{i=1}^{N} c_i \tilde{\varphi}(x_i)$$
, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$.

Using that
$$f = \sum_{i=1}^{N} c_i \tilde{\varphi}(x_i)$$
, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$:
$$\langle f, \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} = \sum_{i=1}^{N} c_i \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k}$$

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Using that $f = \sum_{i=1}^{N} c_i \tilde{\varphi}(x_i)$, $g = \sum_{i=1}^{N} d_i \tilde{\psi}(y_i)$:

$$\begin{split} \langle f, \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} &= \sum_{i=1}^N c_i \, \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} \, = \sum_{i=1}^N c_i \tilde{k}(x_i, x_n) = (\mathbf{c}^T \tilde{\mathbf{G}}_X)_n, \\ \langle g, \tilde{\psi}(y_n) \rangle_{\mathfrak{H}_\ell} &= (\mathbf{d}^T \tilde{\mathbf{G}}_Y)_n, \end{split}$$

with the centered kernels $(\tilde{k}, \tilde{\ell})$ and Gram matrices $(\tilde{\mathbf{G}}_X, \tilde{\mathbf{G}}_Y)$.

Until now

All the objective terms can be expressed by \mathbf{c} , \mathbf{d} , $\tilde{\mathbf{G}}_X$, $\tilde{\mathbf{G}}_Y$.

$$\begin{split} \widehat{\operatorname{cov}}(f(X), g(Y)) &= \frac{1}{N} \sum_{n=1}^{N} \langle f, \widetilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} \langle g, \widetilde{\psi}(y_n) \rangle_{\mathfrak{H}_\ell}, \\ \widehat{\operatorname{var}}[f(X)] &= \frac{1}{N} \sum_{n=1}^{N} \langle f, \widetilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k}^2, \widehat{\operatorname{var}}[g(Y)] &= \frac{1}{N} \sum_{n=1}^{N} \langle g, \widetilde{\psi}(y_n) \rangle_{\mathfrak{H}_\ell}^2, \end{split}$$

and we have

$$\langle f, \tilde{\varphi}(\mathbf{x}_n) \rangle_{\mathfrak{H}_k} = (\mathbf{c}^T \tilde{\mathbf{G}}_X)_n, \qquad \langle g, \tilde{\psi}(\mathbf{y}_n) \rangle_{\mathfrak{H}_\ell} = (\mathbf{d}^T \tilde{\mathbf{G}}_Y)_n.$$

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and we have

$$\langle f, \tilde{\varphi}(x_n) \rangle_{\mathfrak{H}_k} = (\mathbf{c}^T \tilde{\mathbf{G}}_X)_n, \qquad \langle g, \tilde{\psi}(y_n) \rangle_{\mathfrak{H}_\ell} = (\mathbf{d}^T \tilde{\mathbf{G}}_Y)_n.$$

Thus,

$$\widehat{\operatorname{cov}}(f(X), g(Y)) = \frac{1}{N} \mathbf{c}^{T} \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \mathbf{d},$$

$$\widehat{\operatorname{var}}[f(X)] = \frac{1}{N} \mathbf{c}^{T} (\tilde{\mathbf{G}}_{X})^{2} \mathbf{c}, \quad \widehat{\operatorname{var}}[g(Y)] = \frac{1}{N} \mathbf{d}^{T} (\tilde{\mathbf{G}}_{Y})^{2} \mathbf{d}.$$

KCCA: finite-D form

Empirical estimate of KCCA:

$$\widehat{\rho_{\mathsf{KCCA}}}^{\mathsf{temp}}(X,Y;\mathcal{H}_k,\mathcal{H}_\ell) = \sup_{\mathbf{c} \in \mathbb{R}^N, \mathbf{d} \in \mathbb{R}^N} \frac{\mathbf{c}^T \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}}{\sqrt{\mathbf{c}^T (\tilde{\mathbf{G}}_X)^2 \mathbf{c}} \sqrt{\mathbf{d}^T (\tilde{\mathbf{G}}_Y)^2 \mathbf{d}}}.$$

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In practice ($\kappa > 0$):

$$\widehat{\rho}_{\mathsf{KCCA}}(X,Y) := \widehat{\rho}_{\mathsf{KCCA}}(X,Y;\mathcal{H}_{k},\mathcal{H}_{\ell},\kappa)
= \sup_{\mathbf{c} \in \mathbb{R}^{N}, \mathbf{d} \in \mathbb{R}^{N}} \frac{\mathbf{c}^{T} \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \mathbf{d}}{\sqrt{\mathbf{c}^{T} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} \mathbf{c} \sqrt{\mathbf{d}^{T} (\tilde{\mathbf{G}}_{Y} + \kappa \mathbf{I}_{N})^{2} \mathbf{d}}}}$$

Question

How do we solve it?

KCCA: solution

Stationary points of $\widehat{\rho_{\mathsf{KCCA}}}(X,Y)$:

$$\mathbf{0} = \frac{\partial \widehat{\rho_{\mathsf{KCCA}}}(X,Y)}{\partial \mathbf{c}}, \qquad \qquad \mathbf{0} = \frac{\partial \widehat{\rho_{\mathsf{KCCA}}}(X,Y)}{\partial \mathbf{d}},$$

which simplifies to

$$\tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y}\mathbf{d} = \frac{(\mathbf{c}^{T}\tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y}\mathbf{d})(\tilde{\mathbf{G}}_{X} + \kappa\mathbf{I}_{N})^{2}\mathbf{c}}{\mathbf{c}^{T}(\tilde{\mathbf{G}}_{X} + \kappa\mathbf{I}_{N})^{2}\mathbf{c}}, \ \tilde{\mathbf{G}}_{Y}\tilde{\mathbf{G}}_{X}\mathbf{c} = \frac{(\mathbf{d}^{T}\tilde{\mathbf{G}}_{Y}\tilde{\mathbf{G}}_{X}\mathbf{c})(\tilde{\mathbf{G}}_{Y} + \kappa\mathbf{I}_{N})^{2}\mathbf{d}}{\mathbf{d}^{T}(\tilde{\mathbf{G}}_{Y} + \kappa\mathbf{I}_{N})^{2}\mathbf{d}}$$

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Normalization:

- (\mathbf{c}, \mathbf{d}) : solution $\Rightarrow (a\mathbf{c}, b\mathbf{d})$: solution $a, b \in \mathbb{R}, \neq 0$.
- \bullet denominators := 1.

KCCA: final task

Find the maximal eigenvalue, $\lambda := \mathbf{c}^T \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}$, of the generalized eigenvalue problem:

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^T \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

$$\mathbf{A}\mathbf{z} = \lambda \mathbf{B}\mathbf{z}.$$

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$$\mathbf{A}\mathbf{z} = \lambda \mathbf{B}\mathbf{z}.$$

Questions

- Is KCCA an independence measure? (

 universality)
- **2** Meaning/handling of the regularization (κ) .
- **3** $M \ge 2$ components.
- **3** Computation of $\tilde{\mathbf{G}}_X$, $\tilde{\mathbf{G}}_Y$.

Q1 (indep. measure) \Leftarrow universal k, ℓ

If $X \perp Y$, then $\rho_{KCCA}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) = 0$. Opposite direction:

• For 'rich' \mathcal{H}_k , \mathcal{H}_ℓ [Bach and Jordan, 2002, Gretton et al., 2005b].

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- Enough: universal kernel on a compact metric domain.
- Example $(\gamma > 0)$:
 - Gaussian: $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} \mathbf{x}'\|_2^2}$.
 - Laplacian kernel: $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} \mathbf{x}'\|_2}$.

Definition

Assume:

- χ : compact metric space.
- k: continuous kernel on \mathfrak{X} .

k is called *(c)-universal* [Steinwart, 2001] if \mathcal{H}_k is dense in $(C(X), \|\cdot\|_{\infty})$.

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- k: continuous, bounded $\Rightarrow \mathcal{H}_k \subset C(\mathfrak{X})$ [Steinwart and Christmann, 2008].
- Extensions of c-universality to non-compact spaces:
 - c₀-universality, cc-universality,
 ... [Carmeli et al., 2010, Sriperumbudur et al., 2010b,
 Simon-Gabriel and Schölkopf, 2018].

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• The normalized kernel (recall: corr)

$$\tilde{k}(x,y) := \frac{k(x,y)}{\sqrt{k(x,x)k(y,y)}}$$

is universal.

Q1: universal Taylor kernels [Steinwart, 2001, Steinwart and Christmann, 2008]

ullet For an $C^\infty \ni f: (-r,r) \to \mathbb{R}$

$$f(t) = \sum_{n=0}^{\infty} a_n t^n \quad t \in (-r, r), \ r \in (0, \infty].$$

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• If $a_n > 0 \ \forall n$, then

$$k(\mathbf{x}, \mathbf{y}) = f(\langle \mathbf{x}, \mathbf{y} \rangle)$$

is universal on $\mathfrak{X}:=\left\{\mathbf{x}\in\mathbb{R}^{d}:\left\Vert \mathbf{x}\right\Vert _{2}\leq\sqrt{r}\right\}$.

Q1: universal kernels on compact subsets of \mathbb{R}^d , $\alpha > 0$

• $k(\mathbf{x}, \mathbf{y}) = e^{\alpha(\mathbf{x}, \mathbf{y})}$: previous result with $f(t) = e^{\alpha t} \Rightarrow a_n = \frac{\alpha^n}{n!}$.

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- $k(\mathbf{x}, \mathbf{y}) = e^{\alpha \langle \mathbf{x}, \mathbf{y} \rangle}$: previous result with $f(t) = e^{\alpha t} \Rightarrow a_n = \frac{\alpha^n}{n!}$.
- $k(\mathbf{x}, \mathbf{y}) = e^{-\alpha \|\mathbf{x} \mathbf{y}\|_2^2}$: exp. kernel & normalization.

Q1: universal kernels on compact subsets of \mathbb{R}^d , $\alpha > 0$

- $k(\mathbf{x}, \mathbf{y}) = (1 \langle \mathbf{x}, \mathbf{y} \rangle)^{-\alpha}$ binomial kernel
 - $\bullet \ \ \text{on} \ \ \mathfrak{X} \ \text{compact} \ \subset \{\mathbf{x} \in \mathbb{R}^d: \|\mathbf{x}\|_2 < 1\}.$

•
$$f(t) = (1-t)^{-\alpha} = \sum_{n=0}^{\infty} \frac{\binom{-\alpha}{n}(-1)^n t^n}{\binom{-1}{n}t^n} (|t| < 1),$$

where
$$\binom{b}{n} = \sum_{i=1}^{n} \frac{b-i+1}{i}$$
.

Q2 (κ)

In fact, we estimated

$$\rho_{\mathsf{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) = \sup_{f \in \mathcal{H}_k, g \in \mathcal{H}_\ell} \operatorname{corr}(f(X), g(Y); \kappa),$$

$$\operatorname{corr}(f(X), g(Y); \kappa) = \frac{\operatorname{cov}(f(X), g(Y))}{\sqrt{\operatorname{var}[f(X)] + \kappa \|f\|_{\mathcal{H}_k}^2} \sqrt{\operatorname{var}[g(Y)] + \kappa \|g\|_{\mathcal{H}_\ell}^2}}.$$

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For consistent KCCA estimate:

- $\kappa_N \to 0$ [Leurgans et al., 1993](spline-RKHS), [Fukumizu et al., 2007] (general RKHS).
- analysis: covariance operators.

Q3 ($M \ge 2$): symmetry, other form

For

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y} \\ \tilde{\mathbf{G}}_{Y}\tilde{\mathbf{G}}_{X} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^{T}\tilde{\mathbf{G}}_{X}\tilde{\mathbf{G}}_{Y}\mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_{X} + \kappa\mathbf{I}_{N})^{2} & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_{Y} + \kappa\mathbf{I}_{N})^{2} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

 $([\mathbf{c}, \mathbf{d}], \lambda)$ solution $\Rightarrow ([-\mathbf{c}; \mathbf{d}], -\lambda)$: solution. Thus, eigenvalues:

$$\{\lambda_1, -\lambda_1, \ldots, \lambda_N, -\lambda_N\}.$$

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Adding the r.h.s. to both sides:

$$\begin{bmatrix} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} & \tilde{\mathbf{G}}_{X} \tilde{\mathbf{G}}_{Y} \\ \tilde{\mathbf{G}}_{Y} \tilde{\mathbf{G}}_{X} & (\tilde{\mathbf{G}}_{Y} + \kappa \mathbf{I}_{N})^{2} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_{X} + \kappa \mathbf{I}_{N})^{2} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

with eigenvalues $\{1 + \lambda_1, 1 - \lambda_1, \dots, 1 + \lambda_N, 1 - \lambda_N\}$.

Q3
$$(M \ge 2)$$

2-variables [(X, Y)]:

$$\begin{bmatrix} (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 & \tilde{\mathbf{G}}_{\mathsf{X}} \tilde{\mathbf{G}}_{\mathsf{Y}} \\ \tilde{\mathbf{G}}_{\mathsf{Y}} \tilde{\mathbf{G}}_{\mathsf{X}} & (\tilde{\mathbf{G}}_{\mathsf{Y}} + \kappa \mathbf{I}_{\mathsf{N}})^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_{\mathsf{X}} + \kappa \mathbf{I}_{\mathsf{N}})^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

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For M-variables (pairwise dependence):

$$\begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_2 & \dots & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_M \\ \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_1 & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_M \\ \vdots & \vdots & & \vdots \\ \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_1 & \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_2 & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix} = \\ \gamma \begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \mathbf{0} \\ \vdots & & \vdots & & \\ \mathbf{0} & \mathbf{0} & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix}.$$

$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H}$$
 with $\mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}$; \mathbf{H} ; $\mathbf{E}_N \in \mathbb{R}^{N \times N}$.

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In short

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H: symmetric ($\mathbf{H} = \mathbf{H}^T$), idempotent ($\mathbf{H}^2 = \mathbf{H}$).

Maximal correlation: summary

- Independence measure (M = 2): with universal kernels.
- $M \ge 2$: pairwise independence.
- Universal kernels: various examples & constructions.
- Consistent estimation: √
- Computation: generalized eigenvalue task (almost closed-form).
- Image registration: it was KCCA.

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Questions

- Analytic estimators (distance / kernel evaluations)?
- Other usage of covariance?

Distances

Setting

- In this part: $X \in \mathbb{R}^{d_1}$, $Y \in \mathbb{R}^{d_2}$ (M = 2).
- Characteristic function $(\exists, X \xrightarrow{1:1} \phi_X)$:

$$\phi_{X}(\mathbf{t}) = \mathbb{E}\left[e^{i\langle \mathbf{t}, X \rangle}\right], \qquad \phi_{Y}(\mathbf{s}) = \mathbb{E}\left[e^{i\langle \mathbf{s}, Y \rangle}\right],$$

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• X and Y are independent iff.

$$\phi_{XY}(\mathbf{t}, \mathbf{s}) = \phi_X(\mathbf{t})\phi_Y(\mathbf{s}) \quad \forall \mathbf{s} \in \mathbb{R}^{d_1}, \mathbf{t} \in \mathbb{R}^{d_2}.$$



• Idea:

$$dCov^{2}(X, Y) = \|\phi_{XY} - \phi_{X}\phi_{Y}\|_{L^{2}(w)}^{2}$$
$$= \int_{\mathbb{R}^{d_{1}+d_{2}}} [\phi_{XY}(\mathbf{s}, \mathbf{t}) - \phi_{X}(\mathbf{s})\phi_{Y}(\mathbf{t})]^{2} w(\mathbf{s}, \mathbf{t}) d\mathbf{s} d\mathbf{t},$$

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By construction

X and Y are independent iff. dCov(X, Y) = 0.

Estimator

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• Estimator (plug-in):

$$\widehat{\mathsf{dCov}}_N^2(X,Y) = \left\| \phi_{XY}^N - \phi_X^N \phi_Y^N \right\|_{L^2(w)}^2.$$



Estimator - continued

$$\begin{split} \left\| \phi_{XY}^{N} - \phi_{X}^{N} \phi_{Y}^{N} \right\|_{L^{2}(w)}^{2} &= \frac{1}{N^{2}} \sum_{k,l \in [N]} A_{kl} B_{kl}, \\ a_{kl} &= \left\| X_{k} - X_{l} \right\|_{2}, \\ \bar{a}_{k.} &= \frac{1}{N} \sum_{l \in [N]} a_{kl}, \ \bar{a}_{.l} &= \frac{1}{N} \sum_{k \in [N]} a_{kl}, \\ \bar{a}_{..} &= \frac{1}{N^{2}} \sum_{k,l \in [N]} a_{kl}, \\ A_{kl} &= a_{kl} - \bar{a}_{k.} - \bar{a}_{.l} + \bar{a}_{..}, \end{split}$$

 B_{kl} is defined similarly from $b_{kl} = ||Y_k - Y_l||_2$.

The careful choice of w results in a pairwise distance based estimator.

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• Extension [Lyons, 2013]:

$$\begin{split} \mathsf{dCov}^2(X,Y) &= \mathbb{E}_{XY} \mathbb{E}_{X'Y'} \rho_1 \left(X, X' \right) \rho_2 \left(Y, Y' \right) \\ &+ \mathbb{E}_{XX'} \left(X, X' \right) \mathbb{E}_{YY'} \left(Y, Y' \right) \\ &- 2 \mathbb{E}_{XY} \left[\mathbb{E}_{X'} \rho_1 \left(X, X' \right) \mathbb{E}_{Y'} \rho_2 \left(Y, Y' \right) \right]. \end{split}$$

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Questions (answer ∈ next section)

Asymptotic null distribution? Valid choices of (ρ_1, ρ_2) ? $M \ge 2$?

Summary: dCov

- Formulation: factorization of the joint characteristic function.
- dCov: $L^2(w)$ -distance.
- Smart choice of $w \Rightarrow$ pairwise distance based estimator.
- Almost sure convergence of the plug-in estimator.
- Extendable to metric spaces.

Setting, mean embedding

- In this part:
 - $X = (X_m)_{m \in [M]} \in \times_{m \in [M]} \mathfrak{X}_m$, $k_m : \mathfrak{X}_m \times \mathfrak{X}_m \to \mathbb{R}$ kernel.

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- Common trick: feature of P,

$$\mathbb{P} \mapsto \mu_{\mathbb{P}} = \int_{\mathcal{X}} \underbrace{\varphi(\mathbf{x})}_{\mathbf{d} \mathbb{P}(\mathbf{x})} d\mathbb{P}(\mathbf{x}).$$
example: $\mathbb{I}_{(-\infty,\cdot)}(\mathbf{x}), e^{i\langle\cdot,\mathbf{x}\rangle}, e^{\langle\cdot,\mathbf{x}\rangle}$ in \mathbb{R}^d

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• Mean embedding [Berlinet and Thomas-Agnan, 2004], [Smola et al., 2007]: $\varphi(x) := k(\cdot, x)$.

Characteristic property, universality

• Characteristic k [Fukumizu et al., 2008, Sriperumbudur et al., 2010a]: if $\mathbb{P} \mapsto \mu_k(\mathbb{P})$ is injective.

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- Universal k: same but on finite signed measures ($\mathbb{F}=c_1\mathbb{P}_1-c_2\mathbb{P}_2$, $c_1,c_2\in\mathbb{R}^{\geq 0}$). Recall:
 - denseness in $C_b(\mathfrak{X})$,
 - Taylor construction.

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Universal \Rightarrow characteristic.

Maximum mean discrepancy

M MD [Gretton et al., 2012]:

$$\mathsf{MMD}_k(\mathbb{P},\mathbb{Q}) := \|\mu_k(\mathbb{P}) - \mu_k(\mathbb{Q})\|_{\mathcal{H}_k}$$

$$\stackrel{(*)}{=} \sup_{f \in B_k} \underbrace{\langle f, \mu_k(\mathbb{P}) - \mu_k(\mathbb{Q}) \rangle_{\mathcal{H}_k}}_{\mathbb{E}_{X \sim \mathbb{P}} f(X) - \mathbb{E}_{X \sim \mathbb{Q}} f(X)}.$$

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- MMD_k is metric $\Leftrightarrow k$: characteristic.
- (*): $\mathsf{MMD}_k \in \mathsf{IPM} \ (\mathsf{sup}_{f \in \mathcal{F}} \mathbb{P}f \mathbb{Q}f)$ [Zolotarev, 1983, Müller, 1997], an easy-to-estimate one!
- Mean trick: $\langle \mu_k(\mathbb{P}), \mu_k(\mathbb{Q}) \rangle_{\mathcal{H}_k} = \mathbb{E}_{X \sim \mathbb{P}, X' \sim \mathbb{Q}} k(X, X')$.

μ_k , MMD_k

Applications:

- two-sample testing
 - [Baringhaus and Franz, 2004, Székely and Rizzo, 2004, Székely and Rizzo, 2005, Borgwardt et al., 2006, Harchaoui et al., 2007, Gretton et al., 2012, Jitkrittum et al., 2016], and its differential private variant [Raj et al., 2019]; independence [Gretton et al., 2008, Pfister et al., 2018, Jitkrittum et al., 2017a] and goodness-of-fit testing [Jitkrittum et al., 2017b, Balasubramanian et al., 2021], causal discovery [Mooij et al., 2016, Pfister et al., 2018],
- domain adaptation [Zhang et al., 2013], -generalization [Blanchard et al., 2017], change-point detection [Harchaoui and Cappé, 2007], post selection inference [Yamada et al., 2018],
- kernel Bayesian inference [Song et al., 2011, Fukumizu et al., 2013], approximate Bayesian computation [Park et al., 2016], probabilistic programming [Schölkopf et al., 2015], model criticism [Lloyd et al., 2014, Kim et al., 2016],
- topological data analysis [Kusano et al., 2016],
- distribution classification
 [Muandet et al., 2011, Lopez-Paz et al., 2015, Zaheer et al., 2017], distribution regression
 [Szabó et al., 2016, Law et al., 2018],
- generative adversarial networks
 [Dziugaite et al., 2015, Li et al., 2015, Binkowski et al., 2018], understanding the dynamics of complex dynamical systems [Klus et al., 2018, Klus et al., 2019], . . .

Hilbert-Schmidt independence criterion [Gretton et al., 2005a]

 $M \geq$ 2: [Quadrianto et al., 2009, Sejdinovic et al., 2013a, Pfister et al., 2018, Szabó and Sriperumbudur, 2018]):

$$\begin{aligned} & \mathsf{HSIC}_{\pmb{k}}\left(\mathbb{P}\right) := \mathsf{MMD}_{\pmb{k}}\left(\mathbb{P}, \otimes_{m=1}^{M} \mathbb{P}_{m}\right), \\ & & \quad \pmb{k}\left(x, x'\right) := \prod_{m=1}^{M} k_{m}\left(x_{m}, x'_{m}\right), \quad \mathfrak{X} = \times_{m \in [M]} \mathfrak{X}_{m}. \end{aligned}$$

Shorthand: $k = \bigotimes_m k_m$.

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Shorthand: $k = \bigotimes_m k_m$.

Alternative view of HSIC (naming from M=2)

$$\begin{aligned} \mathsf{HSIC}_{\pmb{k}}\left(\mathbb{P}\right) &= \left\|C\right\|_{\mathsf{HS}}, \\ C &= \mathbb{E}\left[\otimes_{m \in [M]} \varphi_m(X_m)\right] - \otimes_{m \in [M]} \mathbb{E}[\varphi_m(X_m)]. \end{aligned}$$

Note: $ab^T \leftrightarrow a \otimes b$.

Intuition of
$$a \otimes b$$
, goal: $a := \varphi(x) \in \mathcal{H}_k$, $b := \psi(y) \in \mathcal{H}_\ell$

• If $a \in \mathbb{R}^{d_1}$, $b \in \mathbb{R}^{d_2}$, then $ab^{\mathsf{T}} \in \mathbb{R}^{d_1 \times d_2}$.

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 $ab^T: \mathbb{R}^{d_2} \to \mathbb{R}^{d_1}$ linear mapping.

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Alternatively

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- Given: \mathcal{H}_1 , \mathcal{H}_2 Hilbert spaces.
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• Finite linear combinations of $a \otimes b$ -s:

$$\mathcal{L} := \left\{ \sum_{i=1}^n c_i(extbf{a}_i \otimes extbf{b}_i), c_i \in \mathbb{R}, extbf{a}_i \in \mathcal{H}_1, extbf{b}_i \in \mathcal{H}_2, extbf{n} \in \mathbb{Z}^+
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• $\mathcal{H}_1 \otimes \mathcal{H}_2$: completion of \mathcal{L} .



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 \Rightarrow HSIC for *M*-variables: \checkmark

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Also known for RKHS-s [Berlinet and Thomas-Agnan, 2004]

$$\mathfrak{H}_k = \otimes_{m \in [M]} \mathfrak{H}_{k_m}, \ k = \otimes_{m \in [M]} k_m.$$

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$$\mathcal{H}_k = \otimes_{m \in [M]} \mathcal{H}_{k_m}, \ k = \otimes_{m \in [M]} k_m.$$

HS link:
$$HS(\mathfrak{H}_2,\mathfrak{H}_1)\cong \mathfrak{H}_1\otimes \mathfrak{H}_2$$

$$h_1 \otimes h_2 \in \mathit{HS}(\mathfrak{H}_2,\mathfrak{H}_1), \ \langle a_1 \otimes b_1, a_2 \otimes b_2 \rangle_{\mathit{HS}} = \langle a_1, a_2 \rangle_{\mathfrak{H}_1} \langle b_1, b_2 \rangle_{\mathfrak{H}_2}.$$

Let
$$k: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$$
 and $\ell: \mathfrak{Y} \times \mathfrak{Y} \to \mathbb{R}$, $f \in \mathcal{H}_k$, $g \in \mathcal{H}_\ell$.
$$C = \mathbb{E}[k(\cdot, X) \otimes \ell(\cdot, Y)] - \underbrace{\mathbb{E}[k(\cdot, X)]}_{=:\mu_X} \otimes \underbrace{\mathbb{E}[\ell(\cdot, Y)]}_{=:\mu_Y},$$

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$$\underbrace{(i)}$$

(i):
$$\mathbb{E} \leftrightarrow \langle f, \cdot \rangle_{\mathcal{H}_{\nu}}$$

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$$\stackrel{(i)}{=} \mathbb{E}\langle f, \underbrace{[k(\cdot, X) \otimes \ell(\cdot, Y)]g}_{k(\cdot, X) \langle \ell(\cdot, Y)], g \rangle_{\mathcal{H}_k}}_{\mathcal{H}_k} - \langle f, (\mu_X \otimes \mu_Y) g \rangle_{\mathcal{H}_k}$$

(i):
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$$C = \mathbb{E}[k(\cdot, X) \otimes \ell(\cdot, Y)] - \mathbb{E}[k(\cdot, X)] \otimes \mathbb{E}[\ell(\cdot, Y)],$$

$$=: \mu_X = : \mu_Y$$

$$\langle f, Cg \rangle_{\mathcal{H}_k} = \langle f, \mathbb{E}[k(\cdot, X) \otimes \ell(\cdot, Y)]g \rangle_{\mathcal{H}_k} - \langle f, (\mu_X \otimes \mu_Y)g \rangle_{\mathcal{H}_k}$$

$$\stackrel{(i)}{=} \mathbb{E}\langle f, [k(\cdot, X) \otimes \ell(\cdot, Y)]g \rangle_{\mathcal{H}_k} - \langle f, (\mu_X \otimes \mu_Y)g \rangle_{\mathcal{H}_k}$$

$$\stackrel{(iii)}{=} \mathbb{E}[f(X)g(Y)] - \mathbb{E}[f(X)]\mathbb{E}[g(Y)].$$

(i): $\mathbb{E} \leftrightarrow \langle f, \cdot \rangle_{\mathcal{H}_k}$, (ii) $(a \otimes b)c = a \langle b, c \rangle$,(iii) (mean) reproducing property.

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Basis of the KCCA consistency proof [Fukumizu et al., 2007].

Questions

- Easy-to-check descriptions of being characteristic?
- 4 HSIC demo: cocktail party.
- 4 HSIC estimation.
- **5** HSIC vs distance covariance?
- When is HSIC a valid independence measure?
- Application in hypothesis testing.

Bochner integral [Diestel and Uhl, 1977, Dinculeanu, 2000, Steinwart and Christmann, 2008]

- Given:
 - $(\mathfrak{X}, \mathcal{A}, \mu)$: σ -finite measure space,
 - $f:(\mathfrak{X},\mathcal{A}) \to \mathfrak{H}$ -valued function.

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- For $f = \sum_{i=1}^{n} c_i \chi_{A_i}$ $(A_i \in \mathcal{A}, c_i \in \mathcal{H})$ step functions

$$\int_{\mathfrak{X}}f\mathrm{d}\mu:=\sum_{i=1}^nc_i\mu(A_i)\in\mathfrak{H}.$$

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$$\int_{\mathfrak{X}} f d\mu := \sum_{i=1}^{n} c_{i} \mu(A_{i}) \in \mathfrak{H}.$$

- f measurable function is Bochner μ -integrable if
 - $\exists (f_n)_{n \in \mathbb{N}}$ step functions: $\lim_{n \to \infty} \int_{\mathcal{X}} \|f f_n\|_{\mathcal{H}} d\mu = 0$.
 - In this case $\lim_{n\to\infty} \int_{\mathcal{X}} f_n d\mu$ exists, $=: \int_{\mathcal{X}} f d\mu$.

• $f: \mathcal{X} \to \mathcal{H}$ is Bochner integrable $\Leftrightarrow \int_{\mathcal{X}} \|f\|_{\mathcal{H}} d\mu < \infty$.

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- In our context :

$$\mu_k(\mathbb{P})$$
 exists iff. $\int_{\mathfrak{X}} \underbrace{\|k(\cdot,x)\|_{\mathfrak{H}_k}}_{\sqrt{k(x,x)}} d\mathbb{P}(x) < \infty.$

Specifically: for bounded kernel $(\sup_{x,x'\in\mathcal{X}} k(x,x') < \infty)$ \checkmark .

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Specifically: for bounded kernel $(\sup_{x,x'\in\mathcal{X}} k(x,x') < \infty)$ \checkmark .

Next step

When is k characteristic (i.e. MMD_k metric)?

Non -characteristic kernel examples

Polynomial kernels [Sriperumbudur et al., 2010a]:

•
$$k(x,y) = \langle x,y \rangle$$
: linear kernel $(L=1)$.

$$\mathsf{MMD}_k^2(\mathbb{P},\mathbb{Q}) = \| m_{\mathbb{P}} - m_{\mathbb{Q}} \|_2^2, \qquad m_{\mathbb{P}} = \int_{\mathfrak{X}} x \mathrm{d}\mathbb{P}(x).$$

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• $k(x,y) = (\langle x,y \rangle + 1)^2 (L=2)$:

$$\mathsf{MMD}_{k}^{2}(\mathbb{P},\mathbb{Q}) = 2 \|m_{\mathbb{P}} - m_{\mathbb{Q}}\|_{2}^{2} + \left\| \Sigma_{\mathbb{P}} - \Sigma_{\mathbb{Q}} + m_{\mathbb{P}} m_{\mathbb{P}}^{T} - m_{\mathbb{Q}} m_{\mathbb{Q}}^{T} \right\|_{F}^{2},$$

where $\|\cdot\|_F$: Frobenius norm; $\Sigma_{\mathbb{P}}$: cov. matrix w.r.t. \mathbb{P} .

Characteristic property of k

We focus on continuous bounded shift-invariant kernels:

Bochner's theorem [Wendland, 2005]

$$k(\mathbf{x}, \mathbf{y}) = k_0(\mathbf{x} - \mathbf{y}) = \int_{\mathbb{R}^d} e^{i\langle \mathbf{x} - \mathbf{y}, \boldsymbol{\omega} \rangle} d\Lambda(\boldsymbol{\omega}),$$

where Λ is a finite Borel measure (w.l.o.g. probability).

We expect it to be encoded in Λ ! First, examples.

Shift-invariant kernels on \mathbb{R} [Sriperumbudur et al., 2010a]

For Poisson kernel: $\sigma \in (0,1)$.

Gaussian $e^{-\frac{x^2}{2\sigma^2}}$ $\sigma e^{-\frac{\sigma^2 \omega^2}{2}}$	
Gaussian e 26- 0 e 2	
Laplacian $e^{-\sigma x }$ $\sqrt{rac{2}{\pi}}rac{\sigma}{\sigma^2+\omega^2}$	
$B_{2n+1}\text{-spline } *^{2n+2}\chi_{\left[-\frac{1}{2},\frac{1}{2}\right]}(x) \frac{4^{n+1}}{\sqrt{2\pi}} \frac{\sin^{2n+2}\left(\frac{\omega}{2}\right)}{\omega^{2n+2}}$ $S:= \frac{\sin(\sigma x)}{\sigma^{2n+2}} (x)$	
Sinc $\sqrt{\frac{2}{2}}\chi_{[-\sigma,\sigma]}(\omega)$	
Poisson $\frac{1-\sigma^2}{\sigma^2 - 2\sigma\cos(x) + 1} \sqrt{2\pi} \sum_{j=-\infty}^{\infty} \sigma^{ j } \delta(\omega - j)$	
Dirichlet $\frac{\sin\left(\frac{(2n+1)x}{2}\right)}{\sin\left(\frac{x}{2}\right)}$ $\sqrt{2\pi}\sum_{j=-n}^{n}\delta(\omega-j)$	
Fejér $\frac{1}{n+1} \frac{\sin^2 \frac{(n+1)x}{2}}{\sin^2 \left(\frac{x}{2}\right)}$ $\sqrt{2\pi} \sum_{j=-n}^n \left(1 - \frac{ j }{n+1}\right) \delta(\omega - 1)$	- j)
Cosine $\cos(\sigma x)$ $\sqrt{\frac{\pi}{2}} \left[\delta(\omega - \sigma) + \delta(\omega + \sigma)\right]$	

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For Poisson kernel: $\sigma \in (0,1)$.

	kernel name	<i>k</i> ₀	$\widehat{k_0}(\omega)$
	Gaussian	$e^{-\frac{x^2}{2\sigma^2}}$	$\sigma e^{-\frac{\sigma^2 \omega^2}{2}}$
	Laplacian	$e^{-\sigma x }$	$\sqrt{\frac{2}{\pi}} \frac{\sigma}{\sigma^2 + \omega^2}$
	B_{2n+1} -spline	$*^{2n+2}\chi_{\left[-\frac{1}{2},\frac{1}{2}\right]}(x)$	$\frac{4^{n+1}}{\sqrt{2\pi}} \frac{\sin^{2n+2}\left(\frac{\omega}{2}\right)}{\omega^{2n+2}}$
	Sinc	$\frac{\sin(\sigma x)}{x}$	$\sqrt{\frac{\pi}{2}}\chi_{[-\sigma,\sigma]}(\omega)$
	Poisson	$\frac{1-\sigma^2}{\sigma^2-2\sigma\cos(x)+1}$	$\sqrt{2\pi}\sum_{j=-\infty}^{\infty}\sigma^{ j }\delta(\omega-j)$
	Dirichlet	$\frac{\sin\left(\frac{(2n+1)x}{2}\right)}{\sin\left(\frac{x}{2}\right)}$	$\sqrt{2\pi}\sum_{j=-n}^{n}\delta(\omega-j)$
	Fejér	$\frac{1}{n+1} \frac{\sin^2 \frac{(n+1)x}{2}}{\sin^2 \left(\frac{x}{2}\right)}$	$\sqrt{2\pi} \sum_{j=-n}^{n} \left(1 - \frac{ j }{n+1}\right) \delta(\omega - j)$
_	Cosine	$\cos(\sigma x)$	$\sqrt{\frac{\pi}{2}} \left[\delta(\omega - \sigma) + \delta(\omega + \sigma) \right]$

For
$$\mathbf{x} \in \mathbb{R}^d$$
: $k_0(\mathbf{x}) = \prod_{j=1}^d k_0(x_j)$, $\widehat{k_0}(\boldsymbol{\omega}) = \prod_{j=1}^d \widehat{k_0}(\omega_j)$.

$$\mathsf{MMD}_{k}^{2}(\mathbb{P}, \mathbb{Q}) = \|\mu_{k}(\mathbb{P}) - \mu_{k}(\mathbb{Q})\|_{\mathcal{H}_{k}}^{2}$$
$$= \left\| \int_{\mathfrak{X}} k(\cdot, x) d\mathbb{P}(x) - \int_{\mathfrak{X}} k(\cdot, y) d\mathbb{Q}(y) \right\|_{\mathcal{H}_{k}}^{2}$$

$$\begin{aligned} \mathsf{MMD}_{k}^{2}(\mathbb{P}, \mathbb{Q}) &= \|\mu_{k}(\mathbb{P}) - \mu_{k}(\mathbb{Q})\|_{\mathcal{H}_{k}}^{2} \\ &= \left\| \int_{\mathcal{X}} k(\cdot, x) \mathrm{d}\mathbb{P}(x) - \int_{\mathcal{X}} k(\cdot, y) \mathrm{d}\mathbb{Q}(y) \right\|_{\mathcal{H}_{k}}^{2} \\ &= \langle \mathbf{a} - \mathbf{b}, \mathbf{a} - \mathbf{b} \rangle_{\mathcal{H}_{k}} \end{aligned}$$

$$\begin{aligned} \mathsf{MMD}_{k}^{2}(\mathbb{P}, \mathbb{Q}) &= \|\mu_{k}(\mathbb{P}) - \mu_{k}(\mathbb{Q})\|_{\mathcal{H}_{k}}^{2} \\ &= \left\| \int_{\mathfrak{X}} k(\cdot, x) \mathrm{d}\mathbb{P}(x) - \int_{\mathfrak{X}} k(\cdot, y) \mathrm{d}\mathbb{Q}(y) \right\|_{\mathcal{H}_{k}}^{2} \\ &= \langle a - b, a - b \rangle_{\mathcal{H}_{k}} \\ &= \langle \mu_{k}(\mathbb{P}), \mu_{k}(\mathbb{P}) \rangle_{\mathcal{H}_{k}} + \langle \mu_{k}(\mathbb{Q}), \mu_{k}(\mathbb{Q}) \rangle_{\mathcal{H}_{k}} - 2 \langle \mu_{k}(\mathbb{P}), \mu_{k}(\mathbb{Q}) \rangle_{\mathcal{H}_{k}} \end{aligned}$$

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$$\begin{split} \mathsf{MMD}_{k}^{2}(\mathbb{P},\mathbb{Q}) &= \|\mu_{k}(\mathbb{P}) - \mu_{k}(\mathbb{Q})\|_{\mathcal{H}_{k}}^{2} \\ &= \left\| \int_{\mathfrak{X}} k(\cdot,x) \mathrm{d}\mathbb{P}(x) - \int_{\mathfrak{X}} k(\cdot,y) \mathrm{d}\mathbb{Q}(y) \right\|_{\mathcal{H}_{k}}^{2} \\ &= \langle a - b, a - b \rangle_{\mathcal{H}_{k}} \\ &= \langle \mu_{k}(\mathbb{P}), \mu_{k}(\mathbb{P}) \rangle_{\mathcal{H}_{k}} + \langle \mu_{k}(\mathbb{Q}), \mu_{k}(\mathbb{Q}) \rangle_{\mathcal{H}_{k}} - 2 \langle \mu_{k}(\mathbb{P}), \mu_{k}(\mathbb{Q}) \rangle_{\mathcal{H}_{k}} \\ &= \int_{\mathfrak{X}} \int_{\mathfrak{X}} k(x,x') \mathrm{d}\mathbb{P}(x) \mathrm{d}\mathbb{P}(x') + \int_{\mathfrak{X}} \int_{\mathfrak{X}} k(y,y') \mathrm{d}\mathbb{Q}(y) \mathrm{d}\mathbb{Q}(y') \\ &- 2 \int_{\mathfrak{X}} \int_{\mathfrak{X}} k(x,y) \mathrm{d}\mathbb{P}(x) \mathrm{d}\mathbb{Q}(y) \\ &=: \int_{\mathfrak{X}} \int_{\mathfrak{X}} k(x,y) \mathrm{d}(\mathbb{P} - \mathbb{Q})(x) \mathrm{d}(\mathbb{P} - \mathbb{Q})(y) \,. \end{split}$$

Using Bochner's theorem $(\mathfrak{X} = \mathbb{R}^d)$:

$$\mathsf{MMD}^2_k(\mathbb{P},\mathbb{Q}) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} k(\mathbf{x},\mathbf{y}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y})$$

$$\begin{split} \mathsf{MMD}_{k}^{2}(\mathbb{P},\mathbb{Q}) &= \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} k(\mathbf{x},\mathbf{y}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y}) \\ &= \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} e^{-i\langle \mathbf{x} - \mathbf{y}, \boldsymbol{\omega} \rangle} \mathrm{d}\Lambda(\boldsymbol{\omega}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y}) \end{split}$$

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$$&= \int_{\mathbb{R}^{d}} |c_{\mathbb{P}}(\boldsymbol{\omega}) - c_{\mathbb{Q}}(\boldsymbol{\omega})|^{2} \mathrm{d}\Lambda(\boldsymbol{\omega})$$

$$\begin{split} \mathsf{MMD}_{k}^{2}(\mathbb{P},\mathbb{Q}) &= \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} k(\mathbf{x},\mathbf{y}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y}) \\ &= \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} e^{-i\langle \mathbf{x} - \mathbf{y}, \boldsymbol{\omega} \rangle} \mathrm{d}\Lambda(\boldsymbol{\omega}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y}) \\ &= \int_{\mathbb{R}^{d}} \underbrace{\left[\int_{\mathbb{R}^{d}} e^{-i\langle \mathbf{x}, \boldsymbol{\omega} \rangle} \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{x}) \right]}_{c_{\mathbb{P}}(\boldsymbol{\omega}) - c_{\mathbb{Q}}(\boldsymbol{\omega})} \underbrace{\left[\int_{\mathbb{R}^{d}} e^{i\langle \mathbf{y}, \boldsymbol{\omega} \rangle} \mathrm{d}(\mathbb{P} - \mathbb{Q})(\mathbf{y}) \right]}_{c_{\mathbb{P}}(\boldsymbol{\omega}) - c_{\mathbb{Q}}(\boldsymbol{\omega})} \mathrm{d}\Lambda(\boldsymbol{\omega}) \\ &= \int_{\mathbb{R}^{d}} |c_{\mathbb{P}}(\boldsymbol{\omega}) - c_{\mathbb{Q}}(\boldsymbol{\omega})|^{2} \, \mathrm{d}\Lambda(\boldsymbol{\omega}) = \|c_{\mathbb{P}} - c_{\mathbb{Q}}\|_{L^{2}(\Lambda)}^{2}. \end{split}$$

Simple description for shift-invariant kernels on \mathbb{R}^d

Theorem ([Sriperumbudur et al., 2010a])

k is characteristic iff. $supp(\Lambda) = \mathbb{R}^d$.

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Example on \mathbb{R} :

kernel name	k ₀	$\widehat{k_0}(\omega)$	$suppig(\widehat{k_0}ig)$
Gaussian	$e^{-\frac{x^2}{2\sigma^2}}$	$\sigma e^{-\frac{\sigma^2\omega^2}{2}}$	\mathbb{R}
Laplacian	$e^{-\sigma x }$	$\sqrt{\frac{2}{\pi}} \frac{\sigma}{\sigma^2 + \omega^2}$	\mathbb{R}
B_{2n+1} -spline	$*^{2n+2}\chi_{\left[-\frac{1}{2},\frac{1}{2}\right]}(x)$ $\underline{\sin(\sigma x)}$	$ \sqrt{\frac{2}{\pi}} \frac{\sigma}{\sigma^2 + \omega^2} $ $ \frac{4^{n+1}}{\sqrt{2\pi}} \frac{\sin^{2n+2} \left(\frac{\omega}{2}\right)}{\omega^{2n+2}} $	\mathbb{R}
Sinc	$\frac{\sin(\sigma x)}{x}$	$\sqrt{\frac{\pi}{2}}\chi_{[-\sigma,\sigma]}(\omega)$	$[-\sigma,\sigma]$

or the Matérn kernel (next slide).

$$k(\mathbf{x}, \mathbf{y}) = k_0(\mathbf{x} - \mathbf{y}) = \frac{2^{1-\nu}}{\Gamma(\nu)} \left(\frac{\sqrt{2\nu} \|\mathbf{x} - \mathbf{y}\|_2}{\sigma} \right)^{\nu} K_{\nu} \left(\frac{\sqrt{2\nu} \|\mathbf{x} - \mathbf{y}\|_2}{\sigma} \right),$$

where K_v : modified Bessel function of the second kind of order v

$$k(\mathbf{x}, \mathbf{y}) = k_0(\mathbf{x} - \mathbf{y}) = \frac{2^{1-v}}{\Gamma(v)} \left(\frac{\sqrt{2v} \|\mathbf{x} - \mathbf{y}\|_2}{\sigma} \right)^v K_v \left(\frac{\sqrt{2v} \|\mathbf{x} - \mathbf{y}\|_2}{\sigma} \right),$$

$$\widehat{k_0}(\omega) = \frac{2^{d+v} \pi^{\frac{d}{2}} \Gamma(v + d/2) v^v}{\Gamma(v) \sigma^{2v}} \left(\frac{2v}{\sigma^2} + 4\pi^2 \|\omega\|_2^2 \right)^{-(v+d/2)} > 0 \quad \forall \omega \in \mathbb{R}^d,$$

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• For $v = \frac{1}{2}$: one gets $k(\mathbf{x}, \mathbf{y}) = e^{-\frac{\|\mathbf{x} - \mathbf{y}\|_2}{\sigma}}$.

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$$\widehat{k_0}(\omega) = \frac{2^{d+v} \pi^{\frac{d}{2}} \Gamma(v + d/2) v^{v}}{\Gamma(v) \sigma^{2v}} \left(\frac{2v}{\sigma^2} + 4\pi^2 \|\omega\|_2^2 \right)^{-(v+d/2)} > 0 \quad \forall \omega \in \mathbb{R}^d,$$

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- For $v = \frac{1}{2}$: one gets $k(\mathbf{x}, \mathbf{y}) = e^{-\frac{\|\mathbf{x} \mathbf{y}\|_2}{\sigma}}$.
- Gaussian kernel: $v \to \infty$.

- **1** B-spline kernel type kernels on \mathbb{R}^d :
 - k: still continuous, bounded, shift-invariant.
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2 Radial, bounded, continuous kernels on \mathbb{R}^d :

$$k(\mathbf{x}, \mathbf{y}) = k_0(\frac{\|\mathbf{x} - \mathbf{y}\|_2}{\|\mathbf{x} - \mathbf{y}\|_2}), \quad k_0(z) = \int_{[0,\infty)} e^{-tz^2} d\nu(t).$$

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We are switching to HSIC, demo first.

Cocktail party: HSIC demo



ISA reminder

$$\mathbf{x} = \mathbf{A}\mathbf{s}, \qquad \qquad \mathbf{s} = \left[\mathbf{s}^1; \dots; \mathbf{s}^M\right],$$

where \mathbf{s}^m -s are non-Gaussian & independent.

$$\bullet \; \; \mathsf{Goal} \colon \, \{\mathbf{x}_t\}_{t=1}^T \to \mathbf{W} = \mathbf{A}^{-1}, \{\mathbf{s}_t\}_{t=1}^T \text{,}$$

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- $\bullet \; \; \mathsf{Goal} \colon \, \{ \mathbf{x}_t \}_{t=1}^T \to \mathbf{W} = \mathbf{A}^{-1}, \{ \mathbf{s}_t \}_{t=1}^T \text{,}$
- Objective function:

$$\hat{\mathbf{s}} = \mathbf{W}\mathbf{x},$$
 $J(\mathbf{W}) = I\left(\hat{\mathbf{s}}^1, \dots, \hat{\mathbf{s}}^M\right)
ightarrow \min_{\mathbf{W}}.$

ISA: source, observation

• Hidden sources (s):



ISA: source, observation

• Hidden sources (s):



• Observation (x):



ISA: estimated sources using HSIC, ambiguity

• Estimated sources (ŝ):

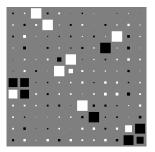


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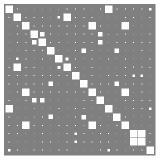


• Performance (**ŴA**), ambiguity:

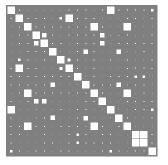


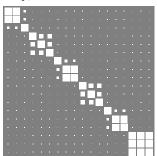
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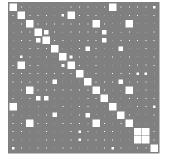


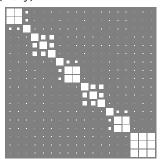
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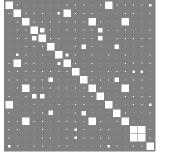
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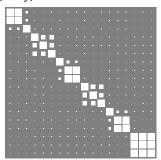




Basis of the state-of-the-art ISA solvers.

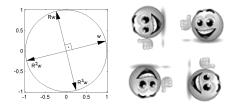
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- Basis of the state-of-the-art ISA solvers.
- Sufficient conditions [Szabó et al., 2012]:
 - **s**^m: spherical [Fang et al., 1990].

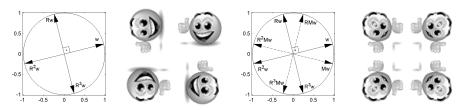
ISA separation theorem \rightarrow for $dim(\mathbf{s}^m) = 2$ less is enough.



Invariance to

• 90° rotation: $f(u_1, u_2) = f(-u_2, u_1) = f(-u_1, -u_2) = f(u_2, -u_1)$.

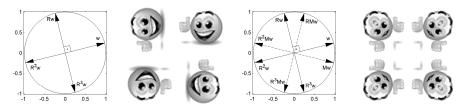
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- permutation and sign: $f(\pm u_1, \pm u_2) = f(\pm u_2, \pm u_1)$.
- L^p -spherical: $f(u_1, u_2) = h(\sum_i |u_i|^p) \quad (p > 0)$.

Intuition of HSIC estimator follows.

HSIC: intuition. X: images, Y: descriptions.



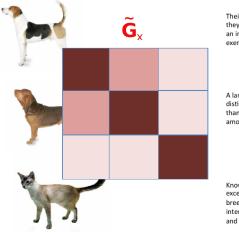
Text from dogtime.com and petfinder.com

Their noses guide them through life, and they're never happier than when following an interesting scent. They need plenty of exercise, about an hour a day if possible.

A large animal who slings slobber, exudes a distinctive houndy odor, and wants nothing more than to follow his nose. They need a significant amount of exercise and mental stimulation.

Known for their curiosity, intelligence, and excellent communication skills, the Javanese breed is perfect if you want a responsive, interactive pet, one that will blow in your ear and follow you everwhere.

HSIC intuition: Gram matrices

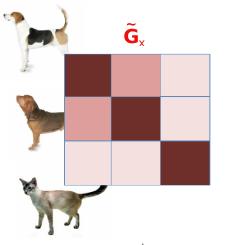


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Empirical estimate†: easy, KCCA alternative,

$$\widehat{\mathsf{HSIC}^2}(X,Y) = rac{1}{N^2} \left\langle \mathbf{\tilde{G}}_X, \mathbf{\tilde{G}}_Y \right\rangle_F.$$

†: Illustration credit (Arthur Gretton).

HSIC in terms of kernel evaluations

$$\mathsf{HSIC}^2(X,Y) = \|C_{XY}^c\|_{HS}^2 = \|C_{XY}^u - \mu_X \otimes \mu_Y\|_{HS}^2$$

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First term:

$$\|C_{XY}^{u}\|_{HS}^{2} = \langle \mathbb{E}_{XY} \left[\varphi(X) \otimes \psi(Y) \right], \mathbb{E}_{X'Y'} \left[\varphi(X') \otimes \psi(Y') \right] \rangle_{HS}$$

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$$\langle e_1 \otimes f_1, e_2 \otimes f_2 \rangle_{HS(\mathcal{H}_2,\mathcal{H}_1)} = \langle e_1, e_2 \rangle_{\mathcal{H}_1} \langle f_1, f_2 \rangle_{\mathcal{H}_2}.$$

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Now

Distance covariance vs. HSIC.

Distance covariance vs. HSIC

Using metric ρ_{χ} and ρ_{y} :

$$\begin{split} \mathsf{dCov}^2(X,Y) &= \mathbb{E}_{XY} \mathbb{E}_{X'Y'} \rho_{\mathcal{X}} \left(X, X' \right) \rho_{\mathcal{Y}} \left(Y, Y' \right) \\ &+ \mathbb{E}_{XX'} \rho_{\mathcal{X}} \left(X, X' \right) \mathbb{E}_{YY'} \rho_{\mathcal{Y}} \left(Y, Y' \right) \\ &- 2 \mathbb{E}_{XY} \left[\mathbb{E}_{X'} \rho_{\mathcal{X}} \left(X, X' \right) \mathbb{E}_{Y'} \rho_{\mathcal{Y}} \left(Y, Y' \right) \right]. \end{split}$$

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Using kernel k_{χ} and k_{y} :

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This suggests some relation: $k\chi \leftrightarrow \rho\chi$, $ky \leftrightarrow \rho\gamma$?

HSIC vs dCov [Sejdinovic et al., 2013b]

High-level preview

• Distance and kernel techniques can be related:

```
(set of) kernel(s) \Leftrightarrow semi-metric of negative type \ni \|\cdot\|_2, characteristic kernel \Leftrightarrow semi-metric of strong negative type.
```

• Consequence:

```
energy distance \Leftrightarrow MMD, HSIC (M = 2) \Leftrightarrow dCov.
```

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- Triangle inequality: $\rho(x, z) \le \rho(x, y) + \rho(y, z)$ for $\forall x, y, z \in \mathcal{X}$.
- semi-metric: triange inequality is dropped.
- semi-metric of negative type: if in addition

$$\sum_{i,j\in[N]}a_ia_j\rho(x_i,x_j)\leq 0$$

for
$$\forall N \geq 2$$
, $\forall (x_n)_{n \in [N]} \subset \mathcal{X}$ and $\forall (a_n)_{n \in [N]} \subset \mathbb{R}$ with $\sum_{n \in [N]} a_n = 0$.

[Berg et al., 1984]:

• $\rho: \checkmark \Rightarrow \rho^a: \checkmark$ for $\forall a \in (0,1)$.

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- Specifically: $\rho(\mathbf{x}, \mathbf{y}) = \|\mathbf{x} \mathbf{y}\|_2$ is OK.
- Other example (metric space of negative type): $L^p[0,1]$ ($p \in [1,2]$), hyperbolic space [Meckes, 2013].

Semi-metric of negative type vs kernel

[Berg et al., 1984]

 (\mathcal{Z}, ρ) : semi-metric space, $z_0 \in \mathcal{Z}$. Let

$$k(z,z') := \rho(z,z_0) + \rho(z',z_0) - \rho(z,z').$$

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Distance kernels induced by such ρ -s, scaled by 2, with z_0 varying:

$$\mathfrak{K}_{\rho} := \left\{ k \ : \ k(z,z') = \frac{1}{2} \left[\rho(z,z_0) + \rho(z',z_0) - \rho(z,z') \right], \ z_0 \in \mathcal{Z} \right\}.$$

Properties

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- $\bullet \quad \text{For } k \in K_{\rho},$
 - **1** $\exists z_0 \in \mathbb{Z} \text{ s.t. } k(z_0, z_0) = 0. \text{ Note: } \not\ni k(z, z') = e^{-\gamma \|z z'\|_2^2}.$
 - 2 $z \mapsto \varphi(z) := k(\cdot, z)$ is injective (=:non-degenerate kernel), and
 - **3** k generates ρ :

$$\rho(\mathbf{z}, \mathbf{z}') = \|\varphi(\mathbf{z}) - \varphi(\mathbf{z}')\|_{\mathcal{H}_k}^2 = k(\mathbf{z}, \mathbf{z}) + k(\mathbf{z}', \mathbf{z}') - 2k(\mathbf{z}, \mathbf{z}').$$

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② Flipping the roles: if a kernel $k: \mathbb{Z} \times \mathbb{Z} \to \mathbb{R}$ is non-generate, then

$$\rho(z, z') = k(z, z) + k(z', z') - 2k(z, z')$$

generates a semi-metric of negative type. In addition, $k \in \mathcal{K}_{\rho}$ iff. $k(z_0, z_0) = 0$ for some $z_0 \in \mathcal{Z}$.

Examples : $\mathcal{Z} = \mathbb{R}^d$

Let $\rho_q(\mathbf{z},\mathbf{z}') = \|\mathbf{z} - \mathbf{z}'\|_2^q$, $q \in (0,2]$. Then the generated distance kernel

$$k_q(\mathbf{z}, \mathbf{z}') = \|\mathbf{z}\|_2^q + \|\mathbf{z}'\|_2^q - \|\mathbf{z} - \mathbf{z}'\|_2^q$$

is the fractional Brownian motion kernel.

Examples – continued

For the Gaussian kernel $k(\mathbf{z}, \mathbf{z}') = e^{-\sigma \|\mathbf{z} - \mathbf{z}'\|_2^2}$, the induced semimetric is

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But the ρ -induced kernel (centered at zero)

$$\tilde{k}(\mathbf{z}, \mathbf{z}') = e^{-\sigma \|\mathbf{z} - \mathbf{z}'\|_2^2} + 1 - e^{-\sigma \|\mathbf{z}\|_2^2} - e^{-\sigma \|\mathbf{z}'\|_2^2}.$$

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There can be a lot of k-s generating ρ , but

k and \tilde{k} generates ρ iff. $\tilde{k}(z,z')=k(z,z')+f(z)+f(z')$ for some shift function.



Equivalence

- Let $(\mathfrak{X}, \rho_{\mathfrak{X}})$ and $(\mathfrak{Y}, \rho_{\mathfrak{Y}})$ be semi-metric spaces of negative type, $(X, Y) \in \mathfrak{X} \times \mathfrak{Y}$. $\mathbb{P}_X \in \mathcal{M}^2_{\rho_{\mathfrak{X}}}$, $\mathbb{P}_Y \in \mathcal{M}^2_{\rho_{\mathfrak{Y}}}$ (2nd moments $< \infty$).
- Let the corresponding distance covariance

$$\begin{split} \mathsf{dCov}_{\rho_{\mathfrak{X}},\rho_{\mathfrak{Y}}}(X,Y) &:= \mathbb{E}_{XY} \mathbb{E}_{X'Y'} \rho_{\mathfrak{X}}\left(X,X'\right) \rho_{\mathfrak{Y}}\left(Y,Y'\right) \\ &+ \mathbb{E}_{XX'} \rho_{\mathfrak{X}}\left(X,X'\right) \mathbb{E}_{YY'} \rho_{\mathfrak{Y}}\left(Y,Y'\right) \\ &- 2 \mathbb{E}_{XY}\left[\mathbb{E}_{X'} \rho_{\mathfrak{X}}\left(X,X'\right) \mathbb{E}_{Y'} \rho_{\mathfrak{Y}}\left(Y,Y'\right)\right]. \end{split}$$

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Then
$$dCov^2_{\rho_X,\rho_Y}(X,Y) = 4HSIC^2_k(X,Y)$$
.

Indeed

Let
$$\nu = \mathbb{P}_{XY} - \mathbb{P}_Y \otimes \mathbb{P}_Y$$
. Notice: $\nu(\mathfrak{X} \times \mathfrak{Y}) = 1 - 1 = 0$.

$$dCov_{\rho_{\mathcal{X}},\rho_{\mathcal{Y}}}^{2}(X,Y) = \mathbb{E}_{XY}\mathbb{E}_{X'Y'}\rho_{\mathcal{X}}(X,X') \rho_{\mathcal{Y}}(Y,Y') + \mathbb{E}_{XX'}\rho_{\mathcal{X}}(X,X') \mathbb{E}_{YY'}\rho_{\mathcal{Y}}(Y,Y') - 2\mathbb{E}_{XY}\left[\mathbb{E}_{X'}\rho_{\mathcal{X}}(X,X') \mathbb{E}_{Y'}\rho_{\mathcal{Y}}(Y,Y')\right]$$

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$$= \int_{\mathfrak{X}\times\mathfrak{Y}} \int_{\mathfrak{X}\times\mathfrak{Y}} \left[k_{\mathfrak{X}}(x,x) + k_{\mathfrak{X}}(x',x') - \frac{2k_{\mathfrak{X}}(x,x')}{2k_{\mathfrak{Y}}(y,y')}\right] d\nu(x,y)d\nu(x',y')$$

$$\times \left[k_{\mathfrak{Y}}(y,y) + k_{\mathfrak{Y}}(y',y') - \frac{2k_{\mathfrak{Y}}(y,y')}{2k_{\mathfrak{Y}}(y,y')}\right] d\nu(x,y)d\nu(x',y')$$

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$$\stackrel{(*)}{=} 4 \int_{\mathfrak{X} \times \mathfrak{Y}} \int_{\mathfrak{X} \times \mathfrak{Y}} k_{\mathfrak{X}}(x, x') k_{\mathfrak{Y}}(y, y') d\nu(x, y) d\nu(x', y')$$

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Energy distance

[Baringhaus and Franz, 2004, Székely and Rizzo, 2004, Székely and Rizzo, 2005, Sejdinovic et al., 2013b] or N-distance [Zinger et al., 1992, Klebanov, 2005]

- (\mathfrak{X}, ρ) : semi-metric space of negative type.
- Kernel $k: \mathfrak{X} \times \mathfrak{X} \to \mathbb{R}$.
- Finite a-moment w.r.t. ρ and k (a > 0):

$$\mathcal{M}_{\rho}^{a}(\mathcal{X}) = \left\{ \mathbb{P} \in \mathcal{M}_{b}(\mathcal{X}) : \exists x_{0} \in \mathcal{X} \text{ s.t. } \int_{\mathcal{X}} \rho^{a}(x, x_{0}) d\mathbb{P}(x) < \infty \right\},$$

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• Recall: $\exists \mu_k(\mathbb{P}) \Leftrightarrow \mathbb{P} \in \mathcal{M}_k^{\frac{1}{2}}(\mathcal{X})$.

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Moments comparison

Let k generate ρ and $n \in \mathbb{N}$. Then $\mathcal{M}_{\rho}^{\frac{n}{2}}(\mathfrak{X}) = \mathcal{M}_{k}^{\frac{n}{2}}(\mathfrak{X})$.

Let $\mathbb{P}, \mathbb{Q} \in \mathcal{M}^1_{\rho}(\mathfrak{X})$, $X, X' \sim \mathbb{P}$ and $Y, Y' \sim \mathbb{Q}$. Energy distance of \mathbb{P} and \mathbb{Q} [Sejdinovic et al., 2013b]:

$$D^2_{E,\rho}(\mathbb{P},\mathbb{Q}) = 2\mathbb{E}_{X,Y}\rho(X,Y) - \mathbb{E}_{X,X'}\rho(X,X') - \mathbb{E}_{Y,Y'}\rho(Y,Y').$$

- ρ : negative type $\Rightarrow D_{E,\rho}(\mathbb{P},\mathbb{Q}) \geq 0$.
- ρ : strong negative type if for $\forall \mathbb{P}, \mathbb{Q} \in \mathcal{M}^1(\mathfrak{X})$:

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- $\Rightarrow D_{E,\rho}$ can distinguish probability measures.
- Example [Lyons, 2013]: every separable Hilbert space.
- $dCov_{\rho_{\mathfrak{X}},\rho_{\mathfrak{Y}}}$ is a valid independence measure $\Leftrightarrow \rho_{\mathfrak{X}}$ and $\rho_{\mathfrak{Y}}$: metric of negative type [Lyons, 2013].

Energy distance ⇔ MMD

[Sejdinovic et al., 2013b]

Let (\mathcal{X}, ρ) be a semi-metric space of negative type, $k : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ any kernel that generates ρ , and $\mathbb{P}, \mathbb{Q} \in \mathcal{M}^1_{\rho}(\mathcal{X})$. Then

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Consequence

Let k any kernel that generates ρ . Then

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Validness of HSIC and MMD follow.

Central in applications

characteristic / \mathcal{I} -characteristic property!

• HSIC: $k = \bigotimes_{m=1}^{M} k_m$ will be called \mathcal{I} -characteristic if

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- Known (M = 2, [Blanchard et al., 2011, Lyons, 2013]):

 $k_1\&k_2$: universal $\Rightarrow k_1\otimes k_2$: universal ($\Rightarrow \mathcal{I}$ -characteristic).

 $k_1 \& k_2$: characteristic $\Leftrightarrow k_1 \otimes k_2$: \mathcal{I} -characteristic.

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$$\forall \mathbb{F} \in \underbrace{\mathfrak{M}_b(\mathfrak{X})} \setminus \{0\} \& \mathbb{F}(\mathfrak{X}) = 0 \Rightarrow \underbrace{\|\mu_k(\mathbb{F})\|_{\mathfrak{H}_k}^2} > 0.$$
 finite signed measures on \mathfrak{X}
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• Witness construction :

$$\exists \mathbb{F} \in \mathcal{M}_b(\mathcal{X}) \setminus \{0\} \& \mathbb{F}(\mathcal{X}) = 0 \text{ for which } \|\mu_k(\mathbb{F})\|_{\mathcal{H}_k}^2 = 0.$$

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$$\mathbb{P}_1 - \mathbb{P}_2 \neq 0 \Rightarrow \mu_k(\mathbb{P}_1 - \mathbb{P}_2) \neq 0.$$

• Observation [Sriperumbudur et al., 2010a]: k is characteristic iff.

$$\forall \mathbb{F} \in \underbrace{\mathcal{M}_b(\mathcal{X})}_{b} \setminus \{0\} \& \mathbb{F}(\mathcal{X}) = 0 \Rightarrow \underbrace{\|\mu_k(\mathbb{F})\|_{\mathcal{H}_k}^2}_{\int_{\mathcal{X}} \int_{\mathcal{X}} k(x,x') \mathrm{d}\mathbb{F}(x) \mathrm{d}\mathbb{F}(x')}$$
 finite signed measures on \mathcal{X}

Witness construction :

$$\exists \underbrace{\mathbb{F} \in \mathfrak{M}_b(\mathfrak{X})}_{\mathbf{A}:=(a_{ij})} \setminus \{0\} \ \& \ \underbrace{\underbrace{\mathbb{F}(\mathfrak{X}) = \mathbf{0}}_{eq_1(\mathbf{A}) = \mathbf{0}}} \text{ for which } \underbrace{\|\mu_{\mathbb{F}}\|_{\mathcal{H}_k}^2 = \mathbf{0}}_{eq_2(\mathbf{A}) = \mathbf{0}}.$$

Example: $\mathfrak{X}_m = \{1, 2\}$, $k_m(x, x') = 2\delta_{x, x'} - 1$ (solvable for $\mathbf{A} \neq \mathbf{0}$).

Results [Szabó and Sriperumbudur, 2018]

Theorem (characteristic property)

- $\bigotimes_{m=1}^{M} k_m$: characteristic $\Rightarrow (k_m)_{m=1}^{M}$ are characteristic.
- $|X_m| = 2, k_m(x, x') = 2\delta_{x,x'} 1$

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Theorem (\mathcal{I} -characteristic property)

- k_1, k_2 : characteristic $\Rightarrow k_1 \otimes k_2$: \mathcal{I} -characteristic.
- \leftarrow : for $\forall M \geq 2$.
- k_1, k_2, k_3 : characteristic $\implies \bigotimes_{m=1}^3 k_m$: \mathcal{I} -characteristic [Ex].
- k_1, k_2 : universal, k_3 : char $\Rightarrow \bigotimes_{m=1}^3 k_m$: \mathcal{I} -characteristic [Ex].

Results - continued

Theorem $(\mathfrak{X}_m = \mathbb{R}^{d_m}, k_m:$ continuous, bounded, shift-invariant)

The followings are equivalent:

- (i) $(k_m)_{m=1}^M$ -s are characteristic.
- (ii) $\otimes_{m=1}^{M} k_m$: \mathcal{I} -characteristic.
- (iii) $\otimes_{m=1}^{M} k_m$: characteristic.

Results - continued

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These results settle MMD and HSIC. Now: hypothesis testing.

• Domain: $\mathfrak{X} = \times_{m \in [M]} \mathfrak{X}_m$.

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- T_{h_2} : integral operator associated to h_2

$$(T_{h_2}f)(x) := \int_{\mathfrak{X}} h_2(x,y)f(y)d\mathbb{P}(y), \quad f \in L^2(\mathbb{P}).$$

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Then

$$\widehat{NHSIC}_N \xrightarrow{w} {\binom{2M}{2}} \sum_{n \in \mathbb{N}} \lambda_n Z_n^2$$
 as $N \to \infty$.

3 commonly applied null approximations

- Permutation.
- Bootstrap.
- Gamma:
 - motivated by the form of the asymptotic null.
 - fast, but no guarantee.

Resampling schemes

∋ permutation, bootstrap.

Accept/reject the null

• Observation: $\{\mathbf{x}_n\}_{n\in[N]}\stackrel{\text{i.i.d.}}{\sim}\mathbb{P}$. Null and alternative:

$$H_0: \mathbb{P} = \bigotimes_{m \in [M]} \mathbb{P}_m, \qquad H_1: \mathbb{P} \neq \bigotimes_{m \in [M]} \mathbb{P}_m.$$

• Decision function: reject the null if

$$\varphi_{\mathit{N}}(\mathbf{x}_{1},\ldots,\mathbf{x}_{\mathit{N}}) := \mathbb{I}_{\{\widehat{\mathsf{NHSIC}}_{\mathit{N}}(\mathbf{x}_{1},\ldots,\mathbf{x}_{\mathit{N}}) > c_{\mathit{N}}(\mathbf{x}_{1},\ldots,\mathbf{x}_{\mathit{N}})\}}.$$

• Threshold $c_N(\mathbf{x}_1,\ldots,\mathbf{x}_N)$: to be specified (later).

Desired guarantees

- Level: let $\alpha \in (0,1)$ fixed.
 - ullet Ideally: the test has (valid) level lpha , i.e. for all $\mathbb{P} \in \mathcal{H}_0$ and $\mathcal{N} \in \mathbb{Z}^+$

$$\underbrace{\mathbb{P}(\varphi(\mathbf{X}_1,\dots,\mathbf{X}_N)=1)}_{\mathbb{P}(\text{reject }H_0\mid H_0)} \leq \alpha.$$

• 'OK': the test respects the level asymptotically (it has pointwise asymptotic level), i.e. for every $\mathbb{P} \in H_0$

$$\limsup_{N\to\infty} \mathbb{P}(\varphi(\mathbf{X}_1,\ldots,\mathbf{X}_N)=1) \leq \alpha.$$

• Pointwise consistency : If for all $\mathbb{P} \in H_1$

$$\lim_{N o \infty} \underbrace{\mathbb{P}(arphi(\mathbf{X}_1, \dots, \mathbf{X}_N) = 1)}_{\mathbb{P}(ext{reject } H_0 \, | \, H_1)} = 1.$$



Resampling schemes

• Goal: approximate the

distribution of
$$\widehat{\mathsf{HSIC}}_{N}(\mathbf{X}_{1},\ldots,\mathbf{X}_{N})$$

using the available data $\{\mathbf{x}_n\}_{n\in[N]}$.

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- Resampling trick:
 - 'shuffling' functions: $\psi_m \in B_N := \{[N] \to [N] \text{ functions}\}, m \in [M].$

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 - 'shuffling' functions: $\psi_m \in B_N := \{[N] \to [N] \text{ functions}\}, m \in [M]$. Effect of ψ_m :

$$X_{m,1},\ldots,X_{m,N}\xrightarrow{\psi_m}X_{m,\psi_m(1)},\ldots,X_{m,\psi_m(N)}.$$

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• shuffled samples: $g_{N,\psi}(\mathbf{x}_1,\ldots,\mathbf{x}_N)$, $\psi:=(\psi_m)_{m\in[M]}$.

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- shuffled samples: $g_{N,\psi}(\mathbf{x}_1,\ldots,\mathbf{x}_N),\; \psi:=(\psi_m)_{m\in[M]}.$
- Resampling method: $g := (g_{N,\psi})_{\psi \in A_N}, A_N \subseteq B_N^M$.

Permutation and bootstrap

- Permutation: $A_N = (S_N)^M$, $S_N = \text{permutations of } [N]$, $|A_N| = (N!)^M$.
- Bootstrap: $A_N = B_N^M$, $|A_N| = N^{NM}$.

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- In both cases:
 - estimated cdf

$$\hat{R}_N(\mathbf{x}_1,\ldots,\mathbf{x}_N)(t) := \frac{1}{|A_N|} \sum_{\psi \in A_N} \mathbb{I}_{\{N \widehat{\mathsf{HSIC}}_N(g_{N,\psi}(\mathbf{x}_1,\ldots,\mathbf{x}_N)) \leq t\}}.$$

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ullet estimated threshold: (1-lpha)-quantile of \hat{R}_{N} , i.e.

$$c_N(\mathbf{x}_1,\ldots,\mathbf{x}_N) := \hat{R}_N(\mathbf{x}_1,\ldots,\mathbf{x}_N)^{-1}(1-\alpha).$$

Level & consistency:

Independence test	level	consistency
permutation	valid	pointwise

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Notes (in practice): as $|A_N|$ can be large

- B shuffling are generated instead of $|A_N|$. Optimal B: open.
- permutation test: still has valid level.

Summary

- Focus: independence measures & testing.
- Applications.
- Techniques:
 - copula,
 - maximum correlation,
 - distance,
 - kernel.

Thank you for the attention!



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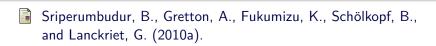
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