

# Foundations of Machine Learning (ST510)

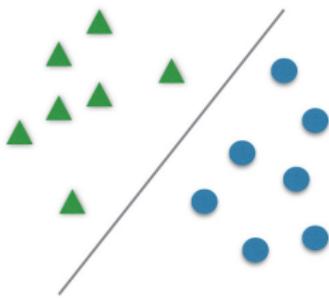
Zoltán Szabó

LSE

# Motivating examples

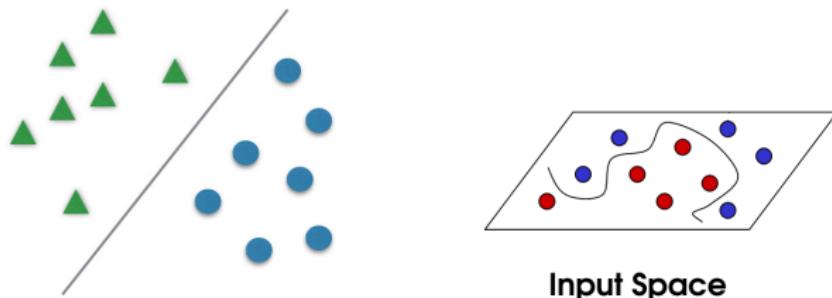
## Example-1: non-linear (large-margin) classification

- Given:  $\{(\mathbf{x}_i, y_i)\}_{i=1}^n$ ,  $y_i \in \{-1, 1\}$ .
- Goal: find an  $f$  classifier such that  $f(\mathbf{x}) \approx y$ .



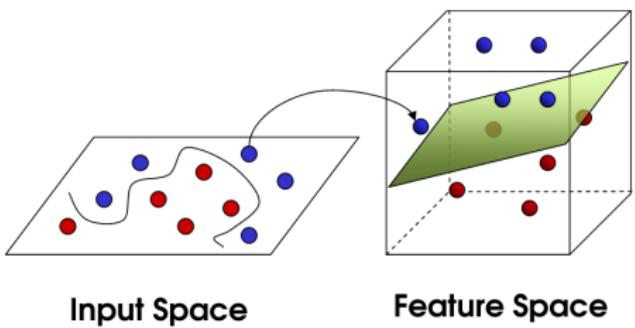
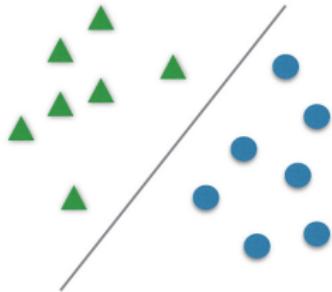
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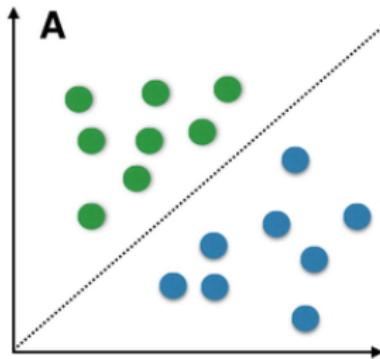
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## Example-1: continued – linear separability

Idealized situation

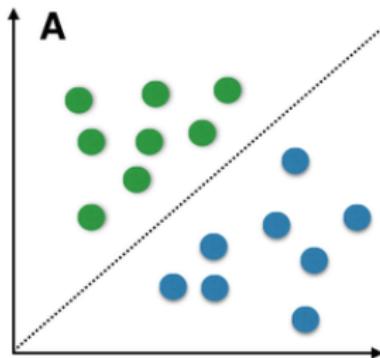


Decision surface:

$$\{\mathbf{x} : \langle \mathbf{w}, \mathbf{x} \rangle = 0\}$$

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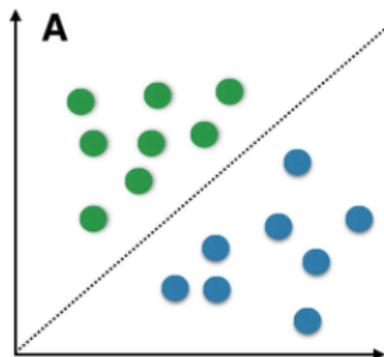
classes:

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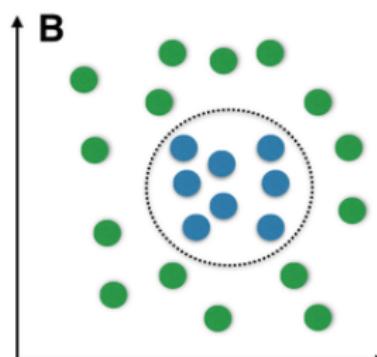
$$\{\mathbf{x} : \langle \mathbf{w}, \mathbf{x} \rangle < 0\}$$

## Example-1: continued – non-linear separability

Idealized situation



Real world



Decision surface (left):

$$\{\mathbf{x} : \langle \mathbf{w}, \mathbf{x} \rangle = 0\} \Rightarrow$$

classes:

$$\{\mathbf{x} : \langle \mathbf{w}, \mathbf{x} \rangle \geq 0\}$$

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## Example-1: non-linear separability – continued

On the ellipse

$$\left\{ \mathbf{x} : \frac{(x_1 - c_1)^2}{a^2} + \frac{(x_2 - c_2)^2}{b^2} = 1 \right\}$$

## Example-1: non-linear separability – continued

On the **ellipse**, outside

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$$\left\{ \mathbf{x} : \frac{(x_1 - c_1)^2}{a^2} + \frac{(x_2 - c_2)^2}{b^2} > 1 \right\}$$

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On the **ellipse**, **outside**, **inside**:

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With polynomial feature:  $\varphi(\mathbf{x}) = (x_1^2, x_1, 1, x_2^2, x_2)$ :

- Decision surface:  $\{\mathbf{x} : \langle \mathbf{w}, \varphi(\mathbf{x}) \rangle = 0\}$ .

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- Classes:  $\{\mathbf{x} : \langle \mathbf{w}, \varphi(\mathbf{x}) \rangle > 0\}$ ,  $\{\mathbf{x} : \langle \mathbf{w}, \varphi(\mathbf{x}) \rangle < 0\}$ .

## Example-1: quadratic & polynomial features

Still in  $\mathbb{R}^2$ :

$$\varphi(\mathbf{x}) = \left( x_1^2, \sqrt{2}x_1x_2, x_2^2 \right),$$

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$\langle \mathbf{x}, \mathbf{x}' \rangle^d = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle$ :  $\varphi(\mathbf{x})$  =  $d$ -order polynomial.  $\Rightarrow$  Explicit computation would be heavy!

## Example-2: characterizing distributions / independence

- Given: random variable  $(X, Y) \in \mathcal{X} \times \mathcal{Y}$ ,  $(X, Y) \sim \mathbb{P}_{XY}$ .
- Goal:** to measure the dependence of  $X$  and  $Y$ .

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- Goal:** to measure the dependence of  $X$  and  $Y$ .
- Desiderata** for a  $Q(\mathbb{P}_{XY})$  independence measure [Rényi, 1959]:
  - $Q(\mathbb{P}_{XY})$  is well-defined,
  - $Q(\mathbb{P}_{XY}) \in [0, 1]$ ,
  - $Q(\mathbb{P}_{XY}) = 0$  iff.  $X \perp Y$ .
  - $Q(\mathbb{P}_{XY}) = 1$  iff.  $Y = f(X)$  or  $X = g(Y)$ .

## Example-2: continued

- He showed:

$$Q(\mathbb{P}_{XY}) = \sup_{f,g: \text{ measurable}} \text{corr}(f(X), g(Y)),$$

satisfies 1-4.

- Too ambitious:
  - computationally intractable.
  - many measurable functions.

## Example-2: continued; measurable $\rightarrow$ continuous

- $C_b(\mathcal{X}) = \{f : \mathcal{X} \text{ metric} \rightarrow \mathbb{R}, \text{ bounded continuous}\}$  would also work.
- Still too large!

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Key: balance

density  $\rightarrow$  universality, computation  $\rightarrow$  RKHS.



## Motivation : kernels = generalized inner product

- ① Various data types.
- ② RKHS: flexible ( $\overset{1:1}{\longleftrightarrow}$  probability measures).
- ③ Still computationally tractable: enough  $k(x_i, x_j) \in \mathbb{R}$ .
- ④ RKHS: Hilbert  $\Rightarrow$  statistical analysis.
- ⑤  $v$ -RKHS [ $k(x, x') \in \mathcal{L}(Y)$ ]: dependency among output coordinates.

# Kernel, RKHS: definition, kernel factory

- Def-1 (feature space):

$$k(x, y) = \langle \varphi(x), \varphi(y) \rangle_{\mathcal{H}} \quad x, y \in \mathcal{X}.$$

## Kernel, RKHS : generalized inner product, -linear methods

- Def-1 (feature space):

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- Def-2 (reproducing kernel):

$$k(\cdot, x) \in \mathcal{H}, \quad f(x) = \langle f, k(\cdot, x) \rangle_{\mathcal{H}}.$$

Constructively,  $\mathcal{H}_k = \overline{\{\sum_{i=1}^n \alpha_i k(\cdot, x_i)\}}.$

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- Def-3 (**Gram matrix**):  $\mathbf{G} = [k(x_i, x_j)]_{i,j=1}^n \in \mathbb{R}^{n \times n} \succeq 0.$

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- All these definitions are equivalent,  $k \overset{1:1}{\leftrightarrow} \mathcal{H}_k$ .
- Examples on  $\mathbb{R}^d$  ( $\gamma > 0$ ,  $p \in \mathbb{Z}^+$ ):  $k_p(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle + \gamma)^p$ ,  
 $k_G(\mathbf{x}, \mathbf{y}) = e^{-\gamma \|\mathbf{x} - \mathbf{y}\|_2^2}$ ,  $k_e(\mathbf{x}, \mathbf{y}) = e^{-\gamma \|\mathbf{x} - \mathbf{y}\|_2}$ .

# Some kernel-enriched domains : $(\mathcal{X}, k)$

- **Strings** [Watkins, 1999, Lodhi et al., 2002, Leslie et al., 2002, Kuang et al., 2004, Leslie and Kuang, 2004, Saigo et al., 2004, Cuturi and Vert, 2005],
- **time series** [Rüping, 2001, Cuturi et al., 2007, Cuturi, 2011, Király and Oberhauser, 2019],
- **trees** [Collins and Duffy, 2001, Kashima and Koyanagi, 2002],
- **groups** and specifically **rankings** [Cuturi et al., 2005, Jiao and Vert, 2016],
- **sets** [Haussler, 1999, Gärtner et al., 2002, Balanca and Herbin, 2012, Fellmann et al., 2023], **probability distributions** [Berlinet and Thomas-Agnan, 2004, Hein and Bousquet, 2005, Smola et al., 2007, Sriperumbudur et al., 2010a],
- various **generative models** [Jaakkola and Haussler, 1999, Tsuda et al., 2002, Seeger, 2002, Jebara et al., 2004],
- **fuzzy domains** [Guevara et al., 2017], or
- **graphs** [Kondor and Lafferty, 2002, Gärtner et al., 2003, Kashima et al., 2003, Borgwardt and Kriegel, 2005, Shervashidze et al., 2009, Vishwanathan et al., 2010, Kondor and Pan, 2016, Bai et al., 2020, Borgwardt et al., 2020, Schulz et al., 2022, Nikolentzos and Vazirgiannis, 2023].

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- A few useful rules :
  - ➊ Non-negative shift.  $k$ : kernel  $\Rightarrow k + \gamma$ : kernel ( $\gamma \in \mathbb{R}^{\geq 0}$ ). Why?

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② Cone. If  $k_m : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$  kernel,  $\alpha_m \geq 0$  ( $m = 1, \dots, M$ ), then

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Example:  $\bigoplus_{m=1}^M \mathbb{R} = \mathbb{R}^M$ .

- ④ **Product.** If  $(k_m)_{m=1}^M$  are kernels on  $\mathcal{X}_m$ , then

$$(\otimes_{m=1}^M k_m) ((x_1, \dots, x_M), (x'_1, \dots, x'_M)) = \prod_{m=1}^M k_m (x_m, x'_m).$$

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- Consequence ( $\gamma \geq 0, p \in \mathbb{Z}^+$ ):

$$k(\mathbf{x}, \mathbf{y}) = (\langle \mathbf{x}, \mathbf{y} \rangle_2 + \gamma)^p$$

is a **kernel**.

## Kernel factory : product indeed

Let  $M = 2$  and assume that  $\varphi_m(x) \in \mathbb{R}^{d_m}$ :

$$(\textcolor{red}{k}_1 \otimes \textcolor{blue}{k}_2)((x, y), (x', y')) = \textcolor{red}{k}_1(x, x') \textcolor{blue}{k}_2(y, y')$$

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where  $\langle \mathbf{A}, \mathbf{B} \rangle_F = \text{tr}(\mathbf{A}^\top \mathbf{B}) = \sqrt{\sum_{ij} A_{ij} B_{ij}}$  is the Frobenius inner product.

- ⑥ **Limit.** If  $(k_n)_{n \in \mathbb{N}}$  are kernels on  $\mathcal{X}$ , then

$$k(x, x') := \lim_{n \rightarrow \infty} k_n(x, x')$$

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$$k(\mathbf{x}, \mathbf{y}) = e^{\gamma \langle \mathbf{x}, \mathbf{y} \rangle_2} = \sum_{n \in \mathbb{N}} \frac{(\gamma \langle \mathbf{x}, \mathbf{y} \rangle_2)^n}{n!}$$

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Reason: polynomial kernel & limit rule.

## Kernel factory – continued

- ⑦ Pre-post multiplication.  $k$  kernel on  $\mathcal{X}$ ,  $f : \mathcal{X} \rightarrow \mathbb{R}$ , then

$$\tilde{k}(x, y) = f(x)k(x, y)f(y)$$

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## Properties of $\mathcal{H}_k$ , computational tractability

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[Steinwart and Christmann, 2008, Chapter 4]:

- $k$ : bounded  $[\sup_{x,y \in \mathcal{X}} k(x, y) \leq C] \Rightarrow \forall f \in \mathcal{H}_k$  is bounded

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- $k$ : analytic  $\Rightarrow \forall f \in \mathcal{H}_k$  is analytic.

## Representer theorem

[Schölkopf et al., 2001, Yu et al., 2013]

- Given:  $\{(x_i, y_i)\}_{i=1}^n$ , say classification/regression.
- Goal:

$$J(f) = V(x_1, y_1, f(x_1), \dots, x_n, y_n, f(x_n)) + r(\|f\|_{\mathcal{H}_k}^2) \rightarrow \min_{f \in \mathcal{H}_k},$$

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$r$ : monotonically increasing.

- Example:

$$V(\dots) = \frac{1}{n} \sum_{i=1}^n \max(1 - y_i f(x_i), 0) \quad (\text{soft classification}),$$

$$V(\dots) = \frac{1}{n} \sum_{i=1}^n [f(x_i) - y_i]^2 \quad (\text{regression}).$$

## Representer theorem – continued

... then

- $\exists$  solution in the form:

$$f^* = \sum_{i=1}^n \alpha_i k(\cdot, x_i), \quad \alpha_i \in \mathbb{R}.$$

- $r$ : strictly increasing  $\Rightarrow \forall$  solution is of this form.
- Example:  $r(z) = \lambda z$ ,  $\lambda > 0$ .

# Representer theorem – proof

Objective

$$J(f) = V(x_1, y_1, f(x_1), \dots, x_n, y_n, f(x_n)) + r(\|f\|_{\mathcal{H}_k}^2) \rightarrow \min_{f \in \mathcal{H}_k} .$$

Decompose & Pythagorean theorem:

$$S = \text{span}(k(\cdot, x_i) : i \in [n]),$$

$$f = f_S + f_{\perp},$$

$$\|f\|_{\mathcal{H}_k}^2 = \|f_S\|_{\mathcal{H}_k}^2 + \underbrace{\|f_{\perp}\|_{\mathcal{H}_k}^2}_{\geq 0} \geq \|f_S\|_{\mathcal{H}_k}^2.$$

# Representer theorem – proof

## Objective

$$J(f) = \mathcal{V}(x_1, y_1, f(x_1), \dots, x_n, y_n, f(x_n)) + r\left(\|f\|_{\mathcal{H}_k}^2\right) \rightarrow \min_{f \in \mathcal{H}_k} .$$

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In  $J$

- 1st term: depends on  $f_S$  only,  $f(x_i) = \langle f, k(\cdot, x_i) \rangle_{\mathcal{H}_k}$ .

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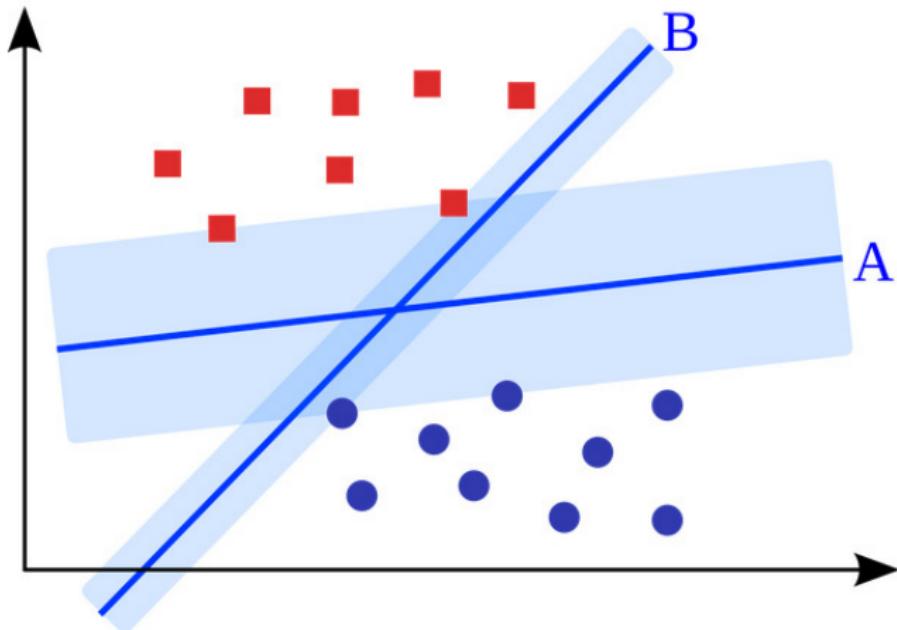
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- **1st term:** depends on  $f_S$  only,  $f(x_i) = \langle f, k(\cdot, x_i) \rangle_{\mathcal{H}_k}$ .
- **2nd term:** can only decrease by neglecting  $f_{\perp}$  ( $r \nearrow$ ).

# Classification: SVMC

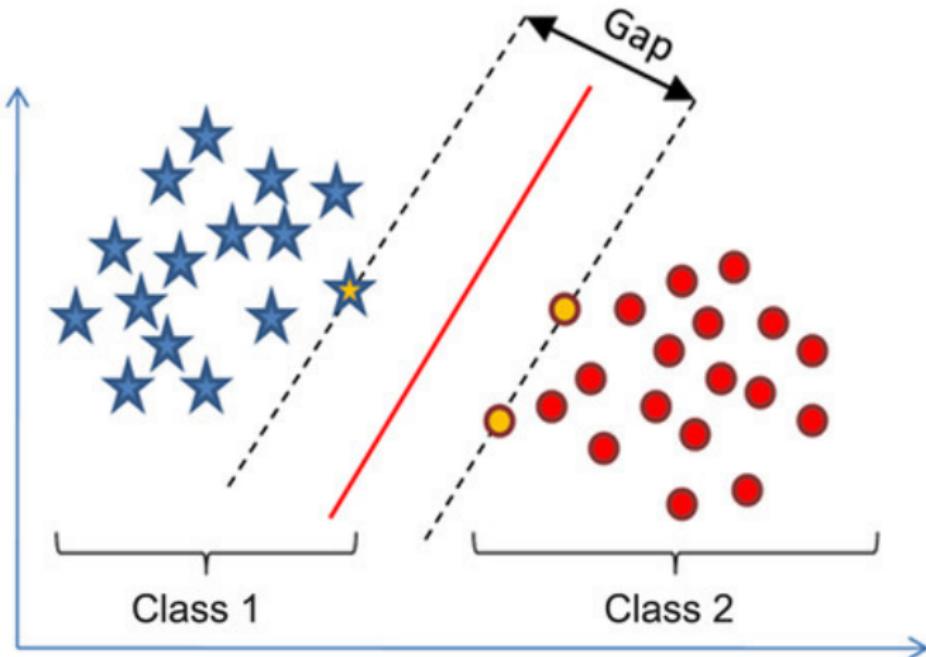
# Support vector machine for classification: SVMC

Which separating line is the 'best'?



# SVMC

Answer / intuition: the one with the largest margin.



## SVM formulation: hard classification

- Hyperplane:  $f_{\mathbf{w}, b}(\mathbf{x}) = \langle \mathbf{w}, \mathbf{x} \rangle + b$ ,
  - $\mathbf{w}$ : normal vector,  $b$ : offset.

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- Goal:

$$\max_{\mathbf{w}, b} \underbrace{\frac{2}{\|\mathbf{w}\|_2}}_{\text{margin}} \Leftrightarrow \min_{\mathbf{w}, b} \|\mathbf{w}\|_2^2, \text{ s.t. } \underbrace{\begin{cases} \langle \mathbf{w}, \mathbf{x}_i \rangle + b \geq 1 & \text{if } y_i = 1, \\ \langle \mathbf{w}, \mathbf{x}_i \rangle + b \leq -1 & \text{otherwise.} \end{cases}}_{\text{correction classification}}$$

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- Shortly,

$$\min_{\mathbf{w}, b} \|\mathbf{w}\|_2^2, \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1, \forall i.$$

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- Decision:  $\hat{y}(\mathbf{x}) = \text{sign}(\langle \mathbf{w}, \mathbf{x} \rangle + b)$ .

- Hard classification objective:

$$\min_{\mathbf{w}, b} \|\mathbf{w}\|_2^2 \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1, \forall i.$$

There might not be solution! (non-linearly separable case)

## SVM formulation: soft classification

- Hard classification objective:

$$\min_{\mathbf{w}, b} \|\mathbf{w}\|_2^2 \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1, \forall i.$$

There might not be solution! (non-linearly separable case)

- Soft classification objective ( $C > 0$ ):

$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^n \xi_i \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i, \xi_i \geq 0, \forall i.$$

Linear penalty on misclassification.

# Note on the soft objective of SVM

$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^n \xi_i \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i, \quad \xi_i \geq 0, \quad \forall i$$

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where  $h(u) = \max(1 - u, 0)$  is the hinge loss.

## Note on the soft objective of SVM – continued

The hinge loss is the convex envelope of the zero-one loss:

$$\textcolor{red}{z}(u) = \mathbb{I}_{\{u < 0\}}, \quad u = y_i f(x_i),$$

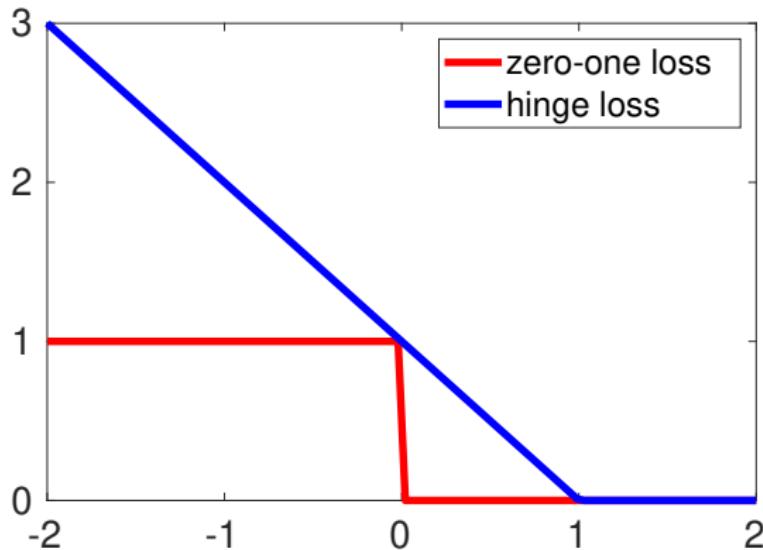
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## Soft classification – back to optimization

Soft classification objective:

$$\min_{\mathbf{w}, b, \xi} \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^n \xi_i, \text{ s.t. } y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) \geq 1 - \xi_i, \xi_i \geq 0 \quad (\forall i).$$

Lagrangian function: with  $\alpha_i \geq 0, \beta_i \geq 0 \ (\forall i)$

$L(\mathbf{w}, b, \xi; \alpha, \beta) = \text{objective} - \text{Lagrangian multipliers} \times \text{conditions}$

$$= \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^n \xi_i - \sum_{i=1}^n \alpha_i [y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) - 1 + \xi_i] - \sum_{i=1}^n \beta_i \xi_i.$$

Solving for  $\frac{\partial L}{\partial \text{primal}} = 0$ , we get ...

## SVM formulation: soft classification

$$L(\mathbf{w}, b, \xi; \alpha, \beta) =$$

$$= \frac{1}{2} \|\mathbf{w}\|_2^2 + C \sum_{i=1}^n \xi_i - \sum_{i=1}^n \alpha_i [y_i (\langle \mathbf{w}, \mathbf{x}_i \rangle + b) - 1 + \xi_i] - \sum_{i=1}^n \beta_i \xi_i.$$

Optimality equations:

$$\mathbf{0} = \frac{\partial L}{\partial \mathbf{w}} = \mathbf{w} - \sum_{i=1}^n \alpha_i y_i \mathbf{x}_i \quad (\mathbf{w} \leftrightarrow \alpha),$$

$$0 = \frac{\partial L}{\partial b} = \sum_{i=1}^n \alpha_i y_i,$$

$$0 = \frac{\partial L}{\partial \xi_i} = C - \alpha_i - \beta_i.$$

Plugging these equations back to  $L$ , we have ...

## SVM formulation: soft classification

Dual form:

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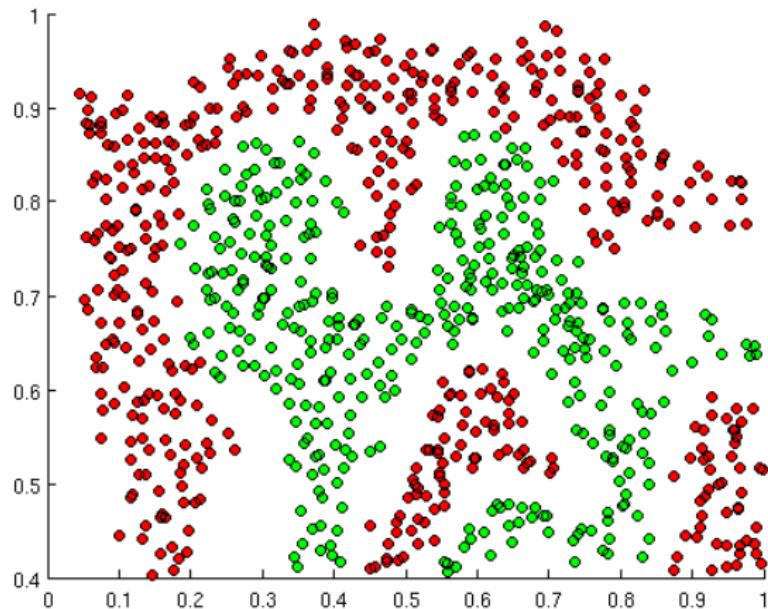
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- QP: solvers are available.

## If linear separability does not hold

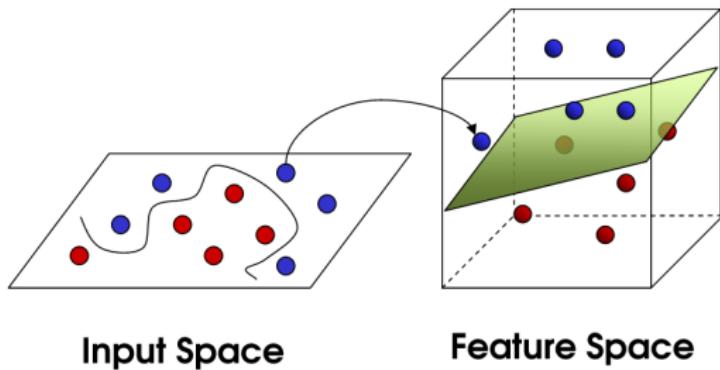
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## If linear separability does not hold

- Until this point:
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- Now:



If linear separability does not hold: **kernel trick**



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- Nonlinear SVM (primal):

$$\min_{f \in \mathcal{H}_k, \xi} \frac{1}{2} \|f\|_{\mathcal{H}_k}^2 + C \sum_{i=1}^n \xi_i, \text{ s.t. } y_i f(x_i) \geq 1 - \xi_i, \xi_i \geq 0, \forall i.$$

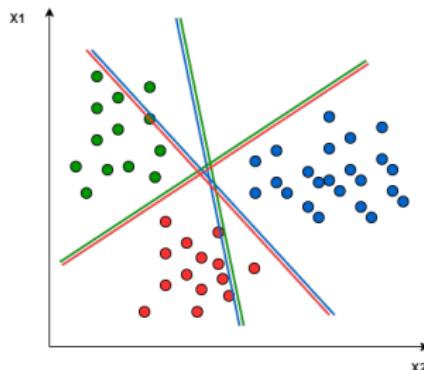
# Multiclass (say $M$ ) classification with SVM

## Idea

Break down the problem to multiple binary classification problems.

### ① one-to-one approach:

- $\frac{M(M-1)}{2}$  SVMCs,  $i$  vs.  $j$  ( $i \neq j$ ),
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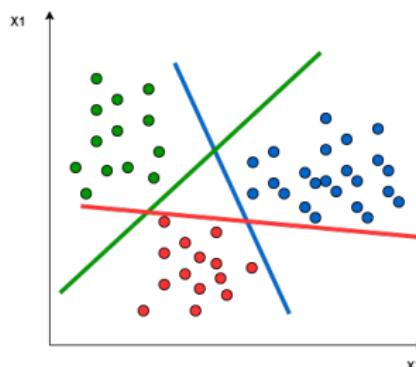
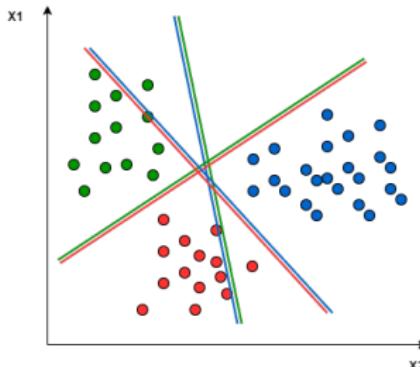
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### ② one-to-rest approach:

- $M$  SVMCs, each predicts one class.
- Classifiers give real-valued confidence scores:  $f_m(x)$ ,  $m \in [M]$ .
- Decision:  $\hat{m} = \arg \max_{m \in [M]} f_m(x)$ .



$M$ -fold cross-validation [ $\theta := (C, \sigma)$ ]:

① Split data:

- training set  $(X_{\text{tr}}, Y_{\text{tr}})$ :  $X_{\text{val},m}, Y_{\text{val},m}$ ,  $m \in [M]$ .
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# Regression: kernel ridge regression

## Kernel ridge regression (KRR)

- Given:  $\{(x_i, y_i)\}_{i=1}^n$ ,  $\mathcal{H} := \mathcal{H}_k$ ,  $y_i \in \mathbb{R}$ .
- Task ( $\lambda > 0$ ):

$$J(f) = \frac{1}{n} \sum_{i=1}^n [y_i - f(x_i)]^2 + \lambda \|f\|_{\mathcal{H}}^2 \rightarrow \min_{f \in \mathcal{H}}.$$

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- Analytical solution:

$$f(x) = [k(x_1, x), \dots, k(x_n, x)] (\mathbf{G} + \lambda n \mathbf{I}_n)^{-1} [y_1; \dots; y_n],$$
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Question

How do we get this solution?

# Kernel ridge regression

By the representer theorem

$$f = \sum_{i=1}^n a_i k(\cdot, x_i), \quad (a_i \in \mathbb{R}).$$

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# Kernel machines: a simple algorithm = SGD [Kivinen et al., 2004]

Empirical regularized risk:

$$\min_{f \in \mathcal{H}_k} J(f) = \frac{1}{n} \sum_{i=1}^n \ell(f(x_i), y_i) + \frac{\lambda}{2} \|f\|_{\mathcal{H}_k}^2 \quad (\lambda > 0).$$

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Update (learning rate:  $\eta_t > 0$ ):

$$f_{t+1} = f_t - \underbrace{\eta_t \left. \frac{\partial J_{\text{inst}}(f, (x_t, y_t))}{\partial f} \right|_{f=f_t}}_{\frac{\partial \ell(z, y)}{\partial z} \Big|_{z=f_t(x_t), y=y_t} k(\cdot, x_t) + \lambda f_t}.$$

Note: if  $\ell$  is non-differentiable, subgradient is taken.

## SGD implementation

- ① Initialization:  $f_1 = 0$ .
- ② By the representer theorem:

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- ④  $\Leftrightarrow$  Update (in terms of coefficients): For  $i \in [t]$ ,

$$\alpha_i := \begin{cases} -\eta_t \ell'(f_t(x_t), y_t) & \text{if } i = t, \\ (1 - \eta_t \lambda) \alpha_i & \text{if } i < t. \end{cases}$$

# Optimizers+

- ➊ Recall the dual problem:

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- ③ For large-scale classification (+recent survey), see [Tanji et al., 2023]:

- Nyström technique + accelerated stochastic subgradient descent.

# Maximal correlation: KCCA

## KCCA: definition

- Given:  $k : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ ,  $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow \mathbb{R}$ .
- Associated:
  - feature maps  $\varphi(x) = k(\cdot, x)$ ,  $\psi(y) = \ell(\cdot, y)$ ,
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  - RKHS-s  $\mathcal{H}_k$ ,  $\mathcal{H}_\ell$ .
- KCCA measure of  $(\mathcal{X}, \mathcal{Y}) \in \mathcal{X} \times \mathcal{Y}$

$$\rho_{\text{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell) = \sup_{f \in \mathcal{H}_k, g \in \mathcal{H}_\ell} \text{corr}(f(X), g(Y)),$$

$$\text{corr}(f(X), g(Y)) = \frac{\text{cov}(f(X), g(Y))}{\sqrt{\text{var}[f(X)] \text{var}[g(Y)]}}.$$

- Optimization domain:  $\mathcal{H}_k \times \mathcal{H}_\ell \ni (f, g)$ .
- By **reproducing property**: we will get a **finite-D task**.
- $k, \ell$  linear: traditional CCA.
- In **practice**: we have  $\{(x_n, y_n)\}_{n=1}^N$  **samples** from  $(X, Y)$ .

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Recall the reproducing property

$$f(x) = \langle f, k(\cdot, x) \rangle_{\mathcal{H}_k} \quad \forall f \in \mathcal{H}_k, x \in \mathcal{X}.$$

## KCCA: empirical estimate

$$\widehat{\text{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^N \underbrace{\left[ f(x_n) - \frac{1}{N} \sum_{i=1}^N f(x_i) \right]}_{\left\langle f, \varphi(x_n) - \frac{1}{N} \sum_{i=1}^N \varphi(x_i) \right\rangle_{\mathcal{H}_k}} \underbrace{\left[ g(y_n) - \frac{1}{N} \sum_{i=1}^N g(y_i) \right]}_{\left\langle g, \psi(y_n) - \frac{1}{N} \sum_{i=1}^N \psi(y_i) \right\rangle_{\mathcal{H}_\ell}}$$

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$$\begin{aligned}\widehat{\text{cov}}(f(X), g(Y)) &= \frac{1}{N} \sum_{n=1}^N \underbrace{\left[ f(x_n) - \frac{1}{N} \sum_{i=1}^N f(x_i) \right]}_{\left\langle f, \varphi(x_n) - \frac{1}{N} \sum_{i=1}^N \varphi(x_i) \right\rangle_{\mathcal{H}_k}} \underbrace{\left[ g(y_n) - \frac{1}{N} \sum_{i=1}^N g(y_i) \right]}_{\left\langle g, \psi(y_n) - \frac{1}{N} \sum_{i=1}^N \psi(y_i) \right\rangle_{\mathcal{H}_\ell}} \\ &= \frac{1}{N} \sum_{n=1}^N \langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} \langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell},\end{aligned}$$

Similarly:

$$\begin{aligned}\widehat{\text{var}}[f(X)] &= \frac{1}{N} \sum_{n=1}^N \left[ f(x_n) - \frac{1}{N} \sum_{i=1}^N f(x_i) \right]^2 = \frac{1}{N} \sum_{n=1}^N \langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k}^2, \\ \widehat{\text{var}}[g(Y)] &= \frac{1}{N} \sum_{n=1}^N \langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell}^2.\end{aligned}$$

## KCCA: empirical estimate

- $f$ : appears only as  $\langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k}$  [similarly:  $g$  in  $\langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell}$ ].  $\Rightarrow$

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- $\forall$  component of  $f \perp$

$$\text{span} \left( \{\tilde{\varphi}(x_n)\}_{n=1}^N \right) = \left\{ \sum_{n=1}^N c_n \tilde{\varphi}(x_n), \mathbf{c} = [c_n] \in \mathbb{R}^N \right\}$$

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has no effect in the objective.

### Key idea

Enough to consider  $f = \sum_{i=1}^N c_i \tilde{\varphi}(x_i)$ ,  $g = \sum_{i=1}^N d_i \tilde{\psi}(y_i)$ .

## KCCA: empirical estimate

Using that  $f = \sum_{i=1}^N c_i \tilde{\varphi}(x_i)$ ,  $g = \sum_{i=1}^N d_i \tilde{\psi}(y_i)$ :

$$\langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} = \sum_{i=1}^N c_i \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k}$$

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$$\langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell} = (\mathbf{d}^\top \tilde{\mathbf{G}}_Y)_n,$$

with the centered kernels  $(\tilde{k}, \tilde{\ell})$  and Gram matrices  $(\tilde{\mathbf{G}}_X, \tilde{\mathbf{G}}_Y)$ .

Until now

All the objective terms can be expressed by  $\mathbf{c}$ ,  $\mathbf{d}$ ,  $\tilde{\mathbf{G}}_X$ ,  $\tilde{\mathbf{G}}_Y$ .

## KCCA: empirical estimate

$$\widehat{\text{cov}}(f(X), g(Y)) = \frac{1}{N} \sum_{n=1}^N \langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} \langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell},$$

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and we have

$$\langle f, \tilde{\varphi}(x_n) \rangle_{\mathcal{H}_k} = (\mathbf{c}^\top \tilde{\mathbf{G}}_X)_n, \quad \langle g, \tilde{\psi}(y_n) \rangle_{\mathcal{H}_\ell} = (\mathbf{d}^\top \tilde{\mathbf{G}}_Y)_n.$$

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Thus,

$$\widehat{\text{cov}}(f(X), g(Y)) = \frac{1}{N} \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d},$$

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## KCCA: finite-D form

Empirical estimate of KCCA:

$$\widehat{\rho_{\text{KCCA}}}^{\text{temp}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell) = \sup_{\mathbf{c} \in \mathbb{R}^N, \mathbf{d} \in \mathbb{R}^N} \frac{\mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}}{\sqrt{\mathbf{c}^\top (\tilde{\mathbf{G}}_X)^2 \mathbf{c}} \sqrt{\mathbf{d}^\top (\tilde{\mathbf{G}}_Y)^2 \mathbf{d}}}.$$

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In practice ( $\kappa > 0$ ):

$$\begin{aligned}\widehat{\rho_{\text{KCCA}}}(X, Y) &:= \widehat{\rho_{\text{KCCA}}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) \\ &= \sup_{\mathbf{c} \in \mathbb{R}^N, \mathbf{d} \in \mathbb{R}^N} \frac{\mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}}{\sqrt{\mathbf{c}^\top (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 \mathbf{c}} \sqrt{\mathbf{d}^\top (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \mathbf{d}}}.\end{aligned}$$

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Question

How do we solve it?

## KCCA: solution

Stationary points of  $\widehat{\rho_{\text{KCCA}}}(X, Y)$ :

$$\mathbf{0} = \frac{\partial \widehat{\rho_{\text{KCCA}}}(X, Y)}{\partial \mathbf{c}}, \quad \mathbf{0} = \frac{\partial \widehat{\rho_{\text{KCCA}}}(X, Y)}{\partial \mathbf{d}},$$

which simplifies to

$$\tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} = \frac{(\mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d})(\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 \mathbf{c}}{\mathbf{c}^\top (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 \mathbf{c}}, \quad \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X \mathbf{c} = \frac{(\mathbf{d}^\top \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X \mathbf{c})(\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \mathbf{d}}{\mathbf{d}^\top (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \mathbf{d}}$$

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Normalization:

- $(\mathbf{c}, \mathbf{d})$ : solution  $\Rightarrow (a\mathbf{c}, b\mathbf{d})$ : solution  $a, b \in \mathbb{R} \setminus \{0\}$ .
- denominators := 1.

## KCCA: final task

Find the maximal eigenvalue,  $\lambda := \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d}$ , of the generalized eigenvalue problem:

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$
$$\mathbf{A}\mathbf{z} = \lambda \mathbf{B}\mathbf{z}.$$

Note: Python implementation in the **ITE** toolbox ( $M \geq 2$ , with acceleration).

# Summary

- Kernel, RKHS: generalized inner product, - linear methods.
- Computational tractability: representer theorem.
- Classification: SVMC.
- Regression: kernel ridge regression.
- Maximal correlation: KCCA.

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# Contents (KCCA: questions)

- 1 Is KCCA an independence measure? ( $\Leftarrow$  universality)
- 2 Meaning/handling of the regularization  $(\kappa)$ .
- 3  $M \geq 2$  components
- 4 Computation of  $\tilde{\mathbf{G}}_X$ ,  $\tilde{\mathbf{G}}_Y$

## Q1 (independence measure) $\Leftarrow$ universal $k, \ell$

If  $X \perp Y$ , then  $\rho_{\text{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) = 0$ . Opposite direction:

- For 'rich'  $\mathcal{H}_k, \mathcal{H}_\ell$   
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[Bach and Jordan, 2002, Gretton et al., 2005].
- Enough: **universal kernel** on a compact metric domain.
- **Example** ( $\gamma > 0$ ):
  - Gaussian:  $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} - \mathbf{x}'\|_2^2}$ .
  - Laplacian kernel:  $k(\mathbf{x}, \mathbf{x}') = e^{-\gamma \|\mathbf{x} - \mathbf{x}'\|_2}$ .

Q1: universal kernel,  $C(\mathcal{X}) = \{f : \mathcal{X} \rightarrow \mathbb{R} \text{ continuous}\}$

### Definition

Assume:

- $\mathcal{X}$ : compact metric space.
- $k$ : continuous kernel on  $\mathcal{X}$ .

$k$  is called *(c)-universal* [Steinwart, 2001] if  $\mathcal{H}_k$  is dense in  $(C(\mathcal{X}), \|\cdot\|_\infty)$ .

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[Steinwart and Christmann, 2008].
- Extensions of c-universality to non-compact spaces:
  - $c_0$ -universality, cc-universality,  
... [Carmeli et al., 2010, Sriperumbudur et al., 2010b,  
Simon-Gabriel and Schölkopf, 2018].

## Q1: properties of universal kernels

[Steinwart, 2001, Steinwart and Christmann, 2008]

If  $k$  is universal, then

- $k(x, x) > 0$  for all  $x \in \mathcal{X}$ .

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is a **metric**.

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is a metric.

- The normalized kernel (recall: corr)

$$\tilde{k}(x, y) := \frac{k(x, y)}{\sqrt{k(x, x)k(y, y)}}$$

is universal.

## Q1: universal Taylor kernels

[Steinwart, 2001, Steinwart and Christmann, 2008]

- For an  $C^\infty \ni f : (-r, r) \rightarrow \mathbb{R}$

$$f(t) = \sum_{n=0}^{\infty} \textcolor{blue}{a_n} t^n \quad t \in (-r, r), \quad r \in (0, \infty].$$

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$$f(t) = \sum_{n=0}^{\infty} \textcolor{blue}{a_n} t^n \quad t \in (-r, r), \quad r \in (0, \infty].$$

- If  $a_n > 0 \ \forall n$ , then

$$k(\mathbf{x}, \mathbf{y}) = f(\langle \mathbf{x}, \mathbf{y} \rangle)$$

is **universal** on  $\mathcal{X} := \left\{ \mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\|_2 \leq \sqrt{r} \right\}$ .

## Q1: universal kernels on compact subsets of $\mathbb{R}^d$ , $\alpha > 0$

- $k(\mathbf{x}, \mathbf{y}) = e^{\alpha \langle \mathbf{x}, \mathbf{y} \rangle}$ : previous result with  $f(t) = e^{\alpha t} \Rightarrow a_n = \frac{\alpha^n}{n!}$ .

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- $k(\mathbf{x}, \mathbf{y}) = e^{-\alpha \|\mathbf{x} - \mathbf{y}\|_2^2}$ : exp. kernel & normalization.

# Q1: universal kernels on compact subsets of $\mathbb{R}^d$ , $\alpha > 0$

- $k(\mathbf{x}, \mathbf{y}) = (1 - \langle \mathbf{x}, \mathbf{y} \rangle)^{-\alpha}$  binomial kernel
    - on  $\mathcal{X}$  compact  $\subset \{\mathbf{x} \in \mathbb{R}^d : \|\mathbf{x}\|_2 < 1\}$ .
    - $f(t) = (1 - t)^{-\alpha} = \sum_{n=0}^{\infty} \underbrace{\binom{-\alpha}{n}}_{>0} (-1)^n t^n \quad (|t| < 1),$
- where  $\binom{b}{n} = \sum_{i=1}^n \frac{b-i+1}{i}$ .

Contents

## Q2 ( $\kappa$ )

In fact, we estimated

$$\begin{aligned}\rho_{\text{KCCA}}(X, Y; \mathcal{H}_k, \mathcal{H}_\ell, \kappa) &= \sup_{f \in \mathcal{H}_k, g \in \mathcal{H}_\ell} \text{corr}(f(X), g(Y); \kappa), \\ \text{corr}(f(X), g(Y); \kappa) &= \frac{\text{cov}(f(X), g(Y))}{\sqrt{\text{var}[f(X)] + \kappa \|f\|_{\mathcal{H}_k}^2} \sqrt{\text{var}[g(Y)] + \kappa \|g\|_{\mathcal{H}_\ell}^2}}.\end{aligned}$$

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$$\text{corr}(f(X), g(Y); \kappa) = \frac{\text{cov}(f(X), g(Y))}{\sqrt{\text{var}[f(X)] + \kappa \|f\|_{\mathcal{H}_k}^2} \sqrt{\text{var}[g(Y)] + \kappa \|g\|_{\mathcal{H}_\ell}^2}}.$$

For consistent KCCA estimate:

- $\kappa_N \rightarrow 0$  [Leurgans et al., 1993] (spline-RKHS),  
[Fukumizu et al., 2007] (general RKHS).
- analysis: covariance operators.

Contents

### Q3 ( $M \geq 2$ ): symmetry, other form

For

$$\begin{bmatrix} 0 & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & 0 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & 0 \\ 0 & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

$([\mathbf{c}, \mathbf{d}], \lambda)$  solution  $\Rightarrow$   $([-\mathbf{c}; \mathbf{d}], -\lambda)$ : solution. Thus, eigenvalues:

$$\{\lambda_1, -\lambda_1, \dots, \lambda_N, -\lambda_N\}.$$

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For

$$\begin{bmatrix} \mathbf{0} & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = \mathbf{c}^\top \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \mathbf{d} \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

$([\mathbf{c}, \mathbf{d}], \lambda)$  solution  $\Rightarrow$   $([-\mathbf{c}; \mathbf{d}], -\lambda)$ : solution. Thus, eigenvalues:

$$\{\lambda_1, -\lambda_1, \dots, \lambda_N, -\lambda_N\}.$$

Adding the r.h.s. to both sides:

$$\begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

with eigenvalues  $\{1 + \lambda_1, 1 - \lambda_1, \dots, 1 + \lambda_N, 1 - \lambda_N\}$ .

### Q3 ( $M \geq 2$ )

2-variables  $[(X, Y)]$ :

$$\begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \tilde{\mathbf{G}}_X \tilde{\mathbf{G}}_Y \\ \tilde{\mathbf{G}}_Y \tilde{\mathbf{G}}_X & (\tilde{\mathbf{G}}_Y + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} = (1 + \lambda) \begin{bmatrix} (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_X + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

### Q3 ( $M \geq 2$ )

2-variables  $[(X, Y)]$ :

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For  $M$ -variables (pairwise dependence):

$$\begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_2 & \dots & \tilde{\mathbf{G}}_1 \tilde{\mathbf{G}}_M \\ \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_1 & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \tilde{\mathbf{G}}_2 \tilde{\mathbf{G}}_M \\ \vdots & \vdots & & \vdots \\ \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_1 & \tilde{\mathbf{G}}_M \tilde{\mathbf{G}}_2 & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix} =$$

$$\gamma \begin{bmatrix} (\tilde{\mathbf{G}}_1 + \kappa \mathbf{I}_N)^2 & \mathbf{0} & \dots & \mathbf{0} \\ \mathbf{0} & (\tilde{\mathbf{G}}_2 + \kappa \mathbf{I}_N)^2 & \dots & \mathbf{0} \\ \vdots & \vdots & & \vdots \\ \mathbf{0} & \mathbf{0} & \dots & (\tilde{\mathbf{G}}_M + \kappa \mathbf{I}_N)^2 \end{bmatrix} \begin{bmatrix} \mathbf{c}_1 \\ \mathbf{c}_2 \\ \vdots \\ \mathbf{c}_M \end{bmatrix}.$$

## Q4: Centered Gram matrix

In short

$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H} \text{ with } \mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}; \quad \mathbf{H}, \mathbf{E}_N \in \mathbb{R}^{N \times N}.$$

$$(\tilde{\mathbf{G}}_X)_{ij} = \tilde{k}(x_i, x_j) = \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_j) \rangle_{\mathcal{H}_k}$$

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$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H} \text{ with } \mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}; \mathbf{H}, \mathbf{E}_N \in \mathbb{R}^{N \times N}.$$

$$\begin{aligned}(\tilde{\mathbf{G}}_X)_{ij} &= \tilde{k}(x_i, x_j) = \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_j) \rangle_{\mathcal{H}_k} \\&= \langle \varphi(x_i) - \frac{1}{N} \sum_{n=1}^N \varphi(x_n), \varphi(x_j) - \frac{1}{N} \sum_{m=1}^N \varphi(x_m) \rangle_{\mathcal{H}_k}\end{aligned}$$

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$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H} \text{ with } \mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}; \mathbf{H}, \mathbf{E}_N \in \mathbb{R}^{N \times N}.$$

$$\begin{aligned}(\tilde{\mathbf{G}}_X)_{ij} &= \tilde{k}(x_i, x_j) = \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_j) \rangle_{\mathcal{H}_k} \\&= \langle \varphi(x_i) - \frac{1}{N} \sum_{n=1}^N \varphi(x_n), \varphi(x_j) - \frac{1}{N} \sum_{m=1}^N \varphi(x_m) \rangle_{\mathcal{H}_k} \\&= (\mathbf{G}_X)_{ij} - \frac{1}{N} \sum_{m=1}^N (\mathbf{G}_X)_{im} - \frac{1}{N} \sum_{n=1}^N (\mathbf{G}_X)_{nj} - \frac{1}{N^2} \sum_{n,m=1}^N (\mathbf{G}_X)_{nm}\end{aligned}$$

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$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H} \text{ with } \mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}; \mathbf{H}, \mathbf{E}_N \in \mathbb{R}^{N \times N}.$$

$$\begin{aligned}(\tilde{\mathbf{G}}_X)_{ij} &= \tilde{k}(x_i, x_j) = \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_j) \rangle_{\mathcal{H}_k} \\&= \langle \varphi(x_i) - \frac{1}{N} \sum_{n=1}^N \varphi(x_n), \varphi(x_j) - \frac{1}{N} \sum_{m=1}^N \varphi(x_m) \rangle_{\mathcal{H}_k} \\&= (\mathbf{G}_X)_{ij} - \frac{1}{N} \sum_{m=1}^N (\mathbf{G}_X)_{im} - \frac{1}{N} \sum_{n=1}^N (\mathbf{G}_X)_{nj} - \frac{1}{N^2} \sum_{n,m=1}^N (\mathbf{G}_X)_{nm} \\&= \left( \mathbf{G}_X - \mathbf{G}_X \frac{\mathbf{E}_N}{N} - \frac{\mathbf{E}_N}{N} \mathbf{G}_X - \frac{\mathbf{E}_N}{N} \mathbf{G}_X \frac{\mathbf{E}_N}{N} \right)_{ij},\end{aligned}$$

## Q4: Centered Gram matrix

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$$\tilde{\mathbf{G}}_X = \mathbf{H}\mathbf{G}_X\mathbf{H} \text{ with } \mathbf{H} = \mathbf{I}_N - \frac{\mathbf{E}_N}{N}; \mathbf{H}, \mathbf{E}_N \in \mathbb{R}^{N \times N}.$$

$$\begin{aligned}(\tilde{\mathbf{G}}_X)_{ij} &= \tilde{k}(x_i, x_j) = \langle \tilde{\varphi}(x_i), \tilde{\varphi}(x_j) \rangle_{\mathcal{H}_k} \\&= \langle \varphi(x_i) - \frac{1}{N} \sum_{n=1}^N \varphi(x_n), \varphi(x_j) - \frac{1}{N} \sum_{m=1}^N \varphi(x_m) \rangle_{\mathcal{H}_k} \\&= (\mathbf{G}_X)_{ij} - \frac{1}{N} \sum_{m=1}^N (\mathbf{G}_X)_{im} - \frac{1}{N} \sum_{n=1}^N (\mathbf{G}_X)_{nj} - \frac{1}{N^2} \sum_{n,m=1}^N (\mathbf{G}_X)_{nm} \\&= \left( \mathbf{G}_X - \mathbf{G}_X \frac{\mathbf{E}_N}{N} - \frac{\mathbf{E}_N}{N} \mathbf{G}_X - \frac{\mathbf{E}_N}{N} \mathbf{G}_X \frac{\mathbf{E}_N}{N} \right)_{ij}, \\&= (\mathbf{H}\mathbf{G}_X\mathbf{H})_{ij},\end{aligned}$$

$\mathbf{H}$ : symmetric ( $\mathbf{H} = \mathbf{H}^\top$ ), idempotent ( $\mathbf{H}^2 = \mathbf{H}$ ). [Contents](#)

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