



Project 3 notes

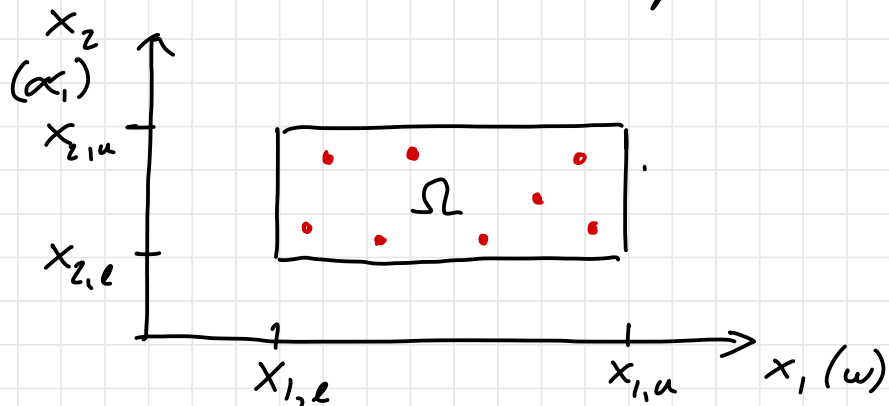


High-level Steps

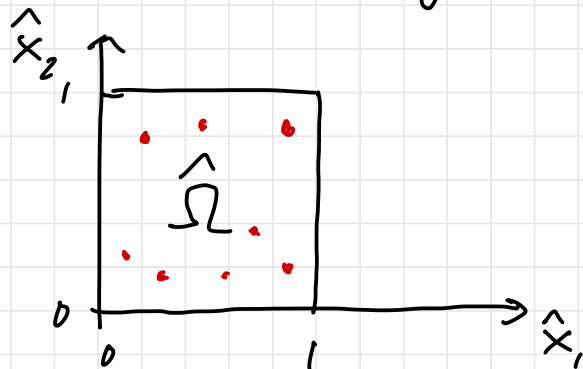
- 1) make a function that, given $[w, \alpha, r_z]$, solves ODE (Eq 27) and returns $\sigma\left(\frac{d\phi}{dt}\right)$
→ And Verify it!!
- 2) In a script, generate samples of the design vars. (w, α, r_z) and evaluate obj. 
- 3) Use GPML to create the surrogate
- 4) Use surrogate in optimization

Sampling

Method 1: samples are scaled to lie within the true (physical) feasible space



Method 2: samples are in uniform $[0, 1]^3$ space and they are transformed inside the objective.

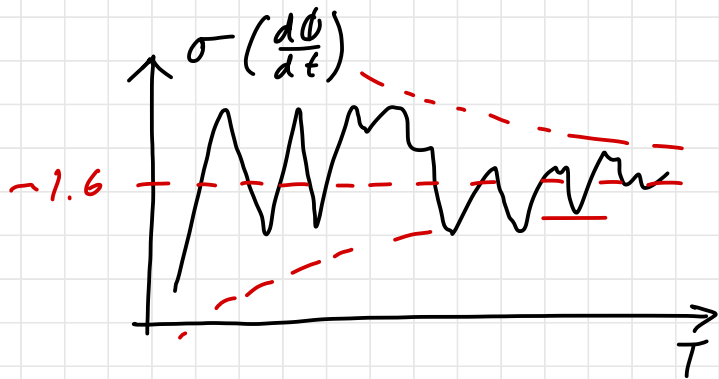


Example of how to transform between the two feasible spaces:

$$\hat{x}_1 = \frac{(x_1 - x_{1,e})}{(x_{1,u} - x_{1,e})}, \quad x_1 = \hat{x}_1 (x_{1,u} - x_{1,e}) + x_{1,e}$$

How do I choose T ?

Simulate the nominal design for a range of T .



How do I choose the initial values for the GPML hyperparameters?

