UCLA Math151A Fall 2021 Lecture 24 2021/11/17

Gaussian Elimination

Equivalent statements

- A is invertible
- Determinant of A is nonzero
- Null space of A is $\{0\}$ (trivial null space)
- Columns of A are linearly independent
- Rows of A are linearly independent
- and so on

We study direct methods for solving the matrix equation Ax = b for x.

Two basic issues in direct methods are:

- How do we construct a solution method for solving Ax = b?
- What is the computational complexity (is the method efficient)?

Gaussian Elimination

To find x s.t. Ax = b.

- 1. Form augmented matrix : [A|b]
- 2. Use row reduction to transform into upper triangular form $[A|b] \to [U|y]$

where U is upper triangular.

3. Solve Ux = y using back substitution.

Example 23.1.
$$\begin{pmatrix} 4 & 1 & 1 \\ 1 & 4 & 1 \\ 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$(1)*(-1/4)+(2)$$

$$(1)*(-1/4)+(3)$$

$$egin{pmatrix} 4 & 1 & 1 & 1 \ 1 & 4 & 1 & 0 \ 1 & 1 & 3 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 4 & 1 & 1 & 1 \\ 1 & 4 & 1 & 0 \\ 1 & 1 & 3 & 0 \end{pmatrix} \qquad \begin{pmatrix} 4 & 1 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} & \frac{-1}{4} \\ 1 & 1 & 3 & 0 \end{pmatrix} \qquad \begin{pmatrix} 4 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} \\ 0 & \frac{3}{4} & \frac{11}{4} \end{pmatrix}$$

$$\begin{pmatrix} 4 & 1 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} & \frac{-1}{4} \\ 0 & \frac{3}{4} & \frac{11}{4} & \frac{-1}{4} \end{pmatrix}$$

$$(2)*(-1/5)+(3)$$

$$\begin{pmatrix} 4 & 1 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} & \frac{-1}{4} \\ 0 & 0 & \frac{13}{5} & -\frac{1}{5} \end{pmatrix}$$

$$\begin{bmatrix} Ux = y \\ \begin{pmatrix} 4 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} \\ 0 & 0 & \frac{13}{5} \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -\frac{1}{4} \\ -\frac{1}{5} \end{bmatrix}$$

$$x_{3} = \frac{y_{3}}{U_{33}}$$

$$x_{2} = \frac{1}{U_{22}} (y_{2} - U_{23}x_{3})$$

$$x_{1} = \frac{1}{U_{11}} (y_{1} - U_{12}x_{2} - U_{13}x_{3})$$

General description:

n rows, n+1 columns.

(1) Forming augmented matrix.

If
$$A \in \mathbb{R}^{n \times n}$$
, and $x, b \in \mathbb{R}^n$, then $[A|b] \in \mathbb{R}^{n \times (n+1)}$

- (2) Use row reduction to transform into upper triangular form.
 - (non-zero) scalar multiplication: if we scale with zero the matrix is no longer invertible.
- scalar multiplicatation plus row addition.
- row swap.

These elemenmetrary row operations are invertible.

Because they are reversible!

 $-1/4E_1 + E_2 \rightarrow E_2$:

$$\begin{pmatrix} 1 & 0 & 0 \\ -1/4 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4 & 1 & 1 \\ 1 & 4 & 1 \\ 1 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 4 & 1 & 1 \\ 0 & 15/4 & 3/4 \\ 1 & 1 & 3 \end{pmatrix} = PA$$

Swap(i,j)
$$T_{ij}^{-1} = T_{ij}.$$

$$0 1 ...$$

$$1 0 ...$$

So $D_i(m)A$ is the matrix produced from A by multiplying row i by m.

So, row reduction on augmented matrix can be represented as

$$P_1(Ax) = P_1b$$

$$P_2(P_1Ax) = P_2P_1b$$

. . .

$$P_n P_{n-1} \dots P_2 P_1 A x = P_n P_{n-1} \dots P_2 P_1 b$$
$$U x = y$$

(3) Solve Ux = y using back substitution: Solution has analytic form:

$$x_{3} = \frac{y_{3}}{U_{33}} \qquad x_{n} = y_{n}/u_{nn}$$

$$x_{2} = \frac{1}{U_{22}} (y_{2} - U_{23}x_{3}) \qquad x_{n-1} = \frac{1}{u_{n-1,n-1}} (y_{n-1} - u_{n-1,n}x_{n})$$

$$x_{1} = \frac{1}{U_{11}} (y_{1} - U_{12}x_{2} - U_{13}x_{3}) \qquad x_{i} = \frac{1}{u_{ii}} (y_{i} - \sum_{j=i+1}^{n} u_{i,j}x_{j})$$

how to choose the elementary operations.

For a 3 by 3 A, "knock out" a_{21} and a_{31} .

$$\begin{pmatrix} 4 & 1 & 1 \\ 1 & 4 & 1 \\ 1 & 1 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

The coresponding E.R.O. s are

$$\lambda E_1 + E_2 \rightarrow E_2$$

$$\mu E_1 + E_3 \rightarrow E_3$$

where we chosoe λ, μ to "knock out" a_{21} and a_{31} .

To do taht we can do
$$\lambda = -\frac{1}{a_{11}}a_{21}, \mu = -\frac{1}{a_{11}}a_{31}$$

The resulting matrix is P_1A

$$\begin{bmatrix}
4 & 1 & 1 & 1 \\
1 & 4 & 1 & 0 \\
1 & 1 & 3 & 0
\end{bmatrix}$$

$$A$$

$$\begin{vmatrix}
4 & 1 & 1 & 1 \\
0 & \frac{15}{4} & \frac{3}{4} & \frac{-1}{4} \\
0 & \frac{3}{4} & \frac{11}{4} & \frac{-1}{4}
\end{vmatrix}$$

$$P_1 A$$

 P_1 is a matrix that includes multiple E.R.Os.

Then we just need to knock out the element below the diagonal 22,

Failure

Clearly it can fail if elements along diagonal are zero.

$$\begin{bmatrix} 4 & 1 & 1 & 1 & 1 \\ 1 & 4 & 1 & 1 & 0 \\ 1 & 1 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 1 & 1 & 1 & 1 \\ 0 & \frac{15}{4} & \frac{3}{4} & \frac{-1}{4} \\ 0 & \frac{3}{4} & \frac{11}{4} & \frac{-1}{4} \end{bmatrix}$$

$$P_1 A$$

what if we got a zero here?

In this case we can pivot to a new diagonal element by performing row swapping (which is an E.R.O.).

Fancy word for row swapping: pivoting.

Gauss-Jordan Elimination

Use the *i*th equation to eliminate not only x_i from the equations $E_{i+1}, E_{i+2}, \ldots, E_n$, but also from $E_1, E_2, \ldots, E_{i-1}$

$$\begin{bmatrix}
1 & 1 & 1 & 5 \\
2 & 3 & 5 & 8 \\
4 & 0 & 5 & 2
\end{bmatrix}
\xrightarrow{R_2-2R_1}
\begin{bmatrix}
1 & 1 & 1 & 5 \\
0 & 1 & 3 & -2 \\
4 & 0 & 5 & 2
\end{bmatrix}$$

$$\xrightarrow{R_3-4R_1}
\begin{bmatrix}
1 & 1 & 1 & 5 \\
0 & 1 & 3 & -2 \\
0 & -4 & 1 & -18
\end{bmatrix}
\xrightarrow{R_1-R_2}
\begin{bmatrix}
1 & 0 & 0 & 3 \\
0 & 1 & 0 & 4 \\
0 & 0 & 1 & -2
\end{bmatrix}$$

$$\xrightarrow{R_3+4R_2}
\begin{bmatrix}
1 & 1 & 1 & 5 \\
0 & 1 & 3 & -2 \\
0 & 0 & 13 & -26
\end{bmatrix}
\xrightarrow{R_1-R_3}
\begin{bmatrix}
1 & 1 & 0 & 7 \\
0 & 1 & 0 & 4 \\
0 & 0 & 1 & -2
\end{bmatrix}$$

$$\xrightarrow{\frac{1}{13}R_3}
\begin{bmatrix}
1 & 1 & 1 & 5 \\
0 & 1 & 3 & -2 \\
0 & 0 & 1 & -2
\end{bmatrix}
\xrightarrow{R_2-3R_3}
\begin{bmatrix}
1 & 1 & 1 & 5 \\
0 & 1 & 0 & 4 \\
0 & 0 & 1 & -2
\end{bmatrix}$$