ECS 32B - Trees: Advanced

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UC Davis - Summer Session #2 2020



Overview

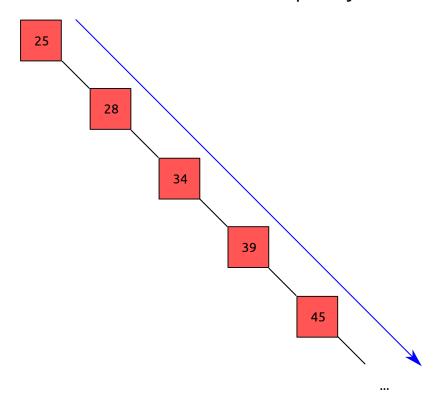
- Self-balancing binary search trees.
 - Motivation.
 - AVL trees.
 - Splay trees.

Self-Balancing Binary Search Tree

• After certain operations (e.g. insertion, deletion), reorients itself to achive some goal (usu.) faster future operations.

Motivation

• Binary search tree has linear worst-case time complexity for find/insert/delete.



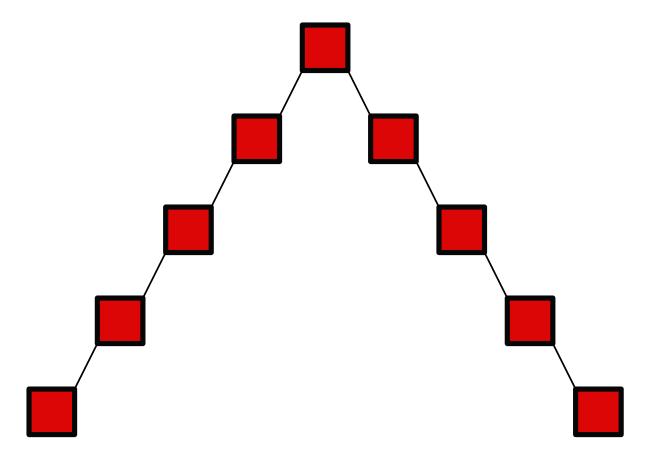
• Self-balancing binary search trees can usually achieve logarithmic time, i.e. $\Theta(\lg n)$.

Balance Condition¹

• What balance condition can we force a binary search tree (BST) to maintain?

Example (of a Bad Idea)

- Require left/right subtrees of root to have same height.
- Doesn't force BST to be shallow.

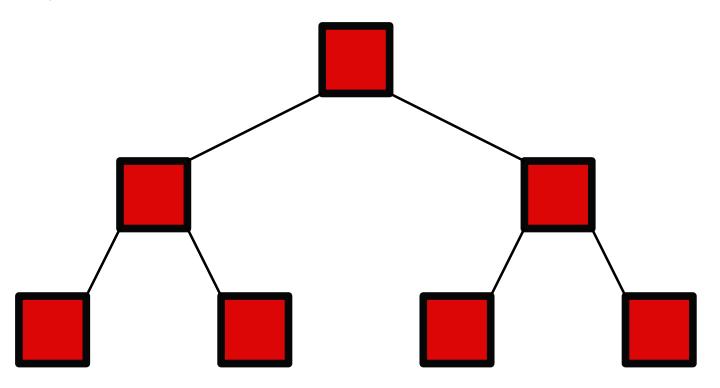


1. This slide and the next one were not in this slide deck during the 08/27 lecture but were inserted before the balance factor slides shown during that lecture. 4/50

Balance Condition

Example (of Another Bad Idea)

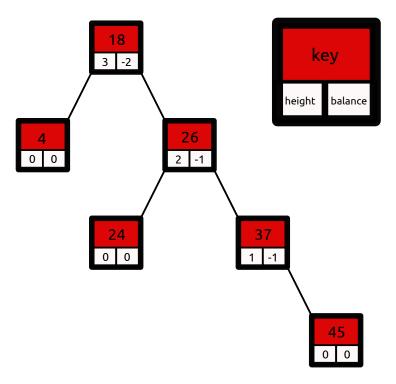
- Force every node to have left/right subtrees of same height.
- Too rigid: only BSTs with 2^k-1 nodes could obey, where $k\in {\bf N}_1$ (positive natural numbers).



Balance Factor

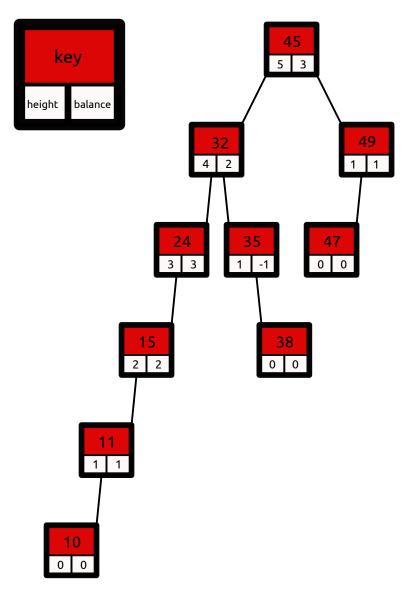
- Can give each node a balance factor \Rightarrow *height*(leftSubTree) *height*(rightSubTree).
 - Subtree is *left-heavy* if root's balance factor is positive; *right-heavy* if negative.
 - \circ Height of empty/nonexistent subtree is -1.
- *height*(*node*) = 1 + *max*(*height*(leftSubTree), *height*(rightSubTree)).

Example: Right-Heavy Tree



Balance Factor

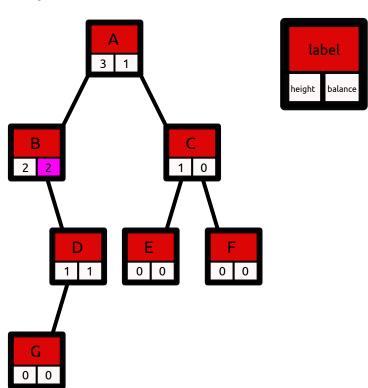
Example: Left-Heavy Tree



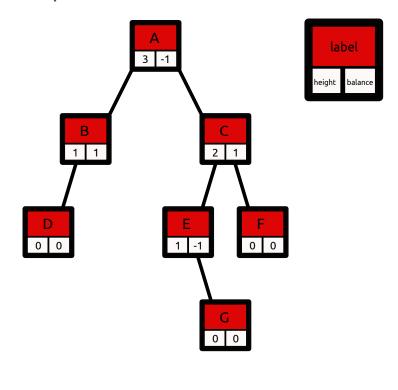
Description

- An AVL tree is a binary search tree in which each node has a balance factor of -1, 0, or 1.
- Through some math, we¹ can prove that at any time, the height of an AVL tree is at most around $1.44 \lg n$, where n is the number of nodes. Thus, searching takes $\Theta(\lg n)$ in the worst case.

Example: *Not* an AVL Tree



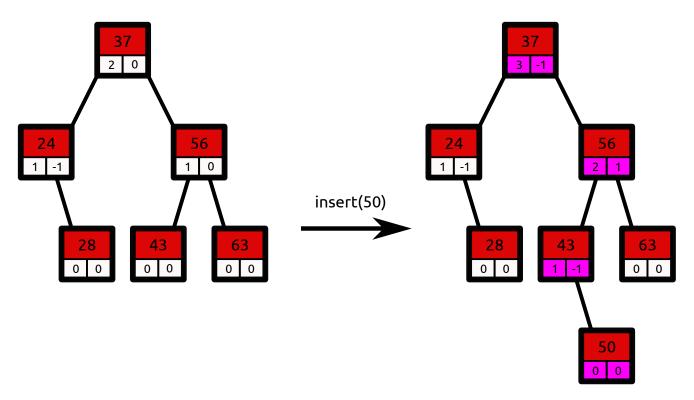
Example: Is an AVL Tree



Insert: Simple Balance Update (1 of 2)

- Start with same procedure as with BST. Inserted node is a leaf, i.e. height and balance factor of 0.
- Update parent:
 - New node is left child ⇒ increment parent's balance factor.
 - \circ Else \Rightarrow decrement.
- Update parent's parent, etc. Recursively apply until reach root.
- Adjust heights too.

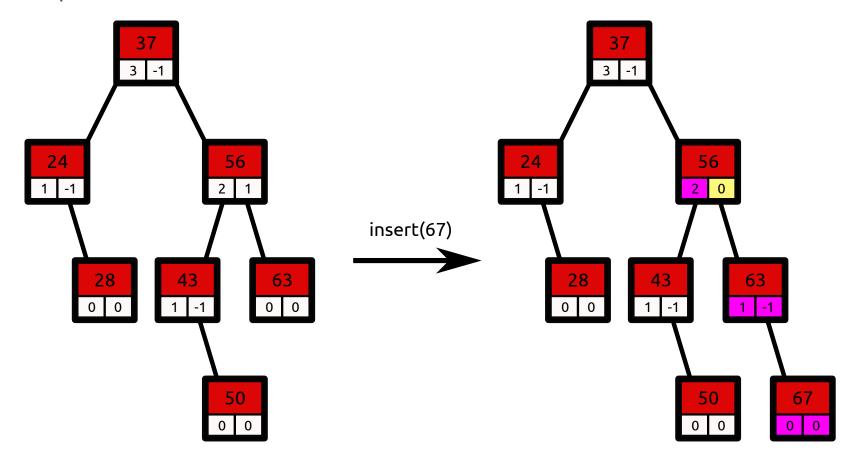
Example



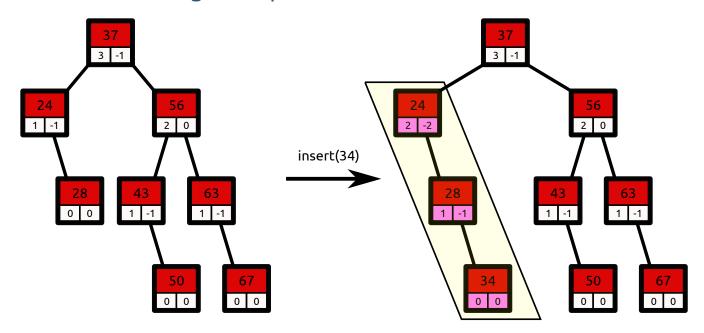
Insert: Simple Balance Update (2 of 2)

• If adjust parent's balance factor to zero, don't adjust ancestors.

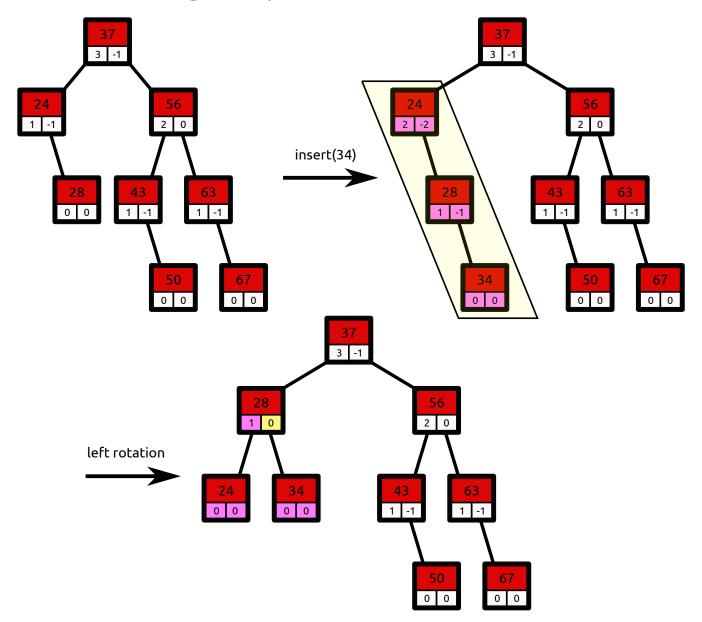
Example



Insert: When Rebalancing is Required

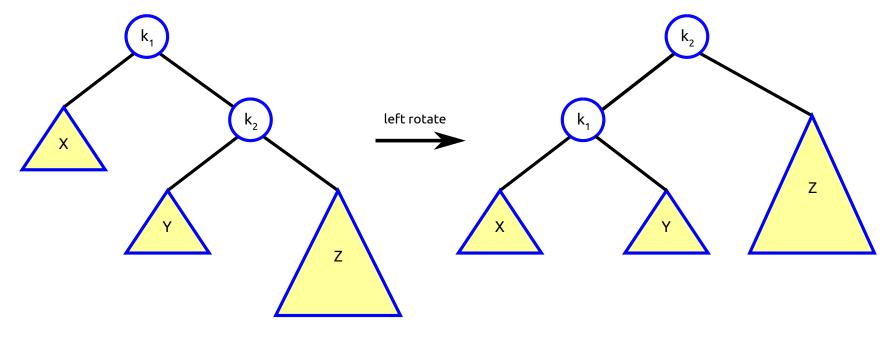


Insert: When Rebalancing is Required



Left Rotation

- Subtrees of k_1 differ by more than 1 in height.
 - \circ e.g. just inserted into Z.



- k_2 will have balance 0 after.
- ullet Previous example is a left rotation with empty X and Y.
- Takes constant time (adjust some references).

- Never need to do more than one rebalancing¹ per insertion.
- k_1 is node with bad balance factor.

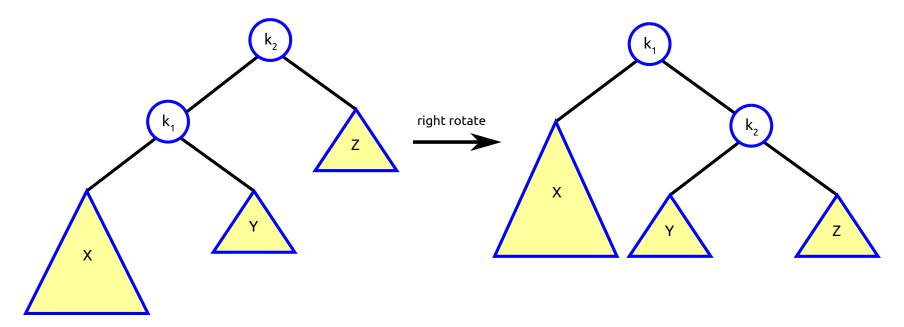
Four Reasons a Rebalance is Needed

- 1. An insertion into the left subtree of the left child of k_1 .
- 2. An insertion into the right subtree of the left child of k_1 .
- 3. An insertion into the left subtree of the right child of k_1 .
- 4. An insertion into the right subtree of the right child of k_1 .
 - Resolved by left rotation in previous slide.

1. I say "rebalancing" instead of rotation because, as you'll see soon, some insertions (i.e. ones that lead to cases #2 or #3 above) necessitate double rotations.

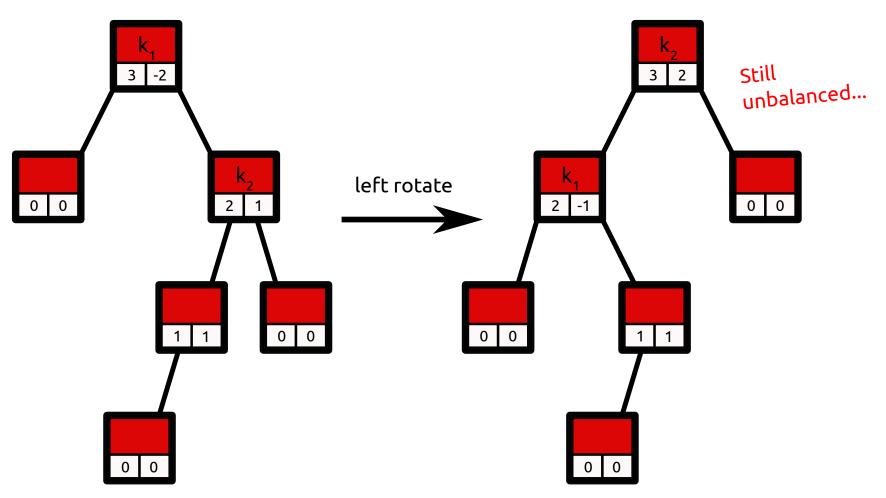
Right Rotation

• Resolves case #1.



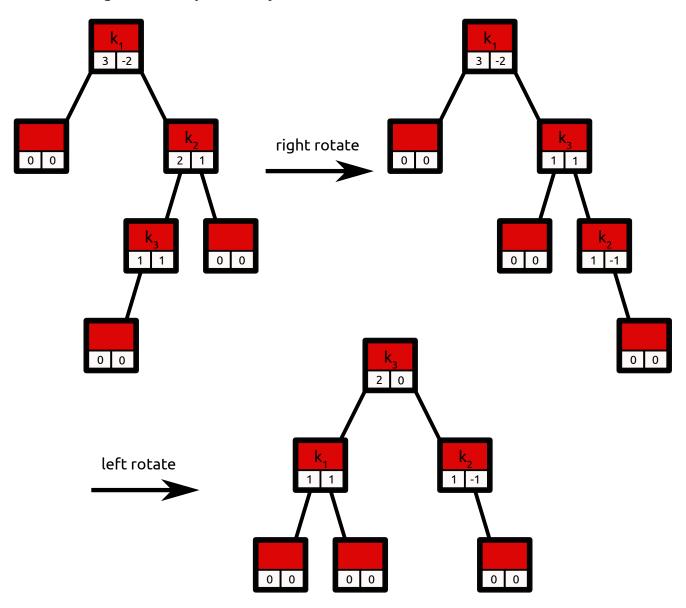
Insert: When a Single Rotation is Insufficient

• Corresponds to case #3.

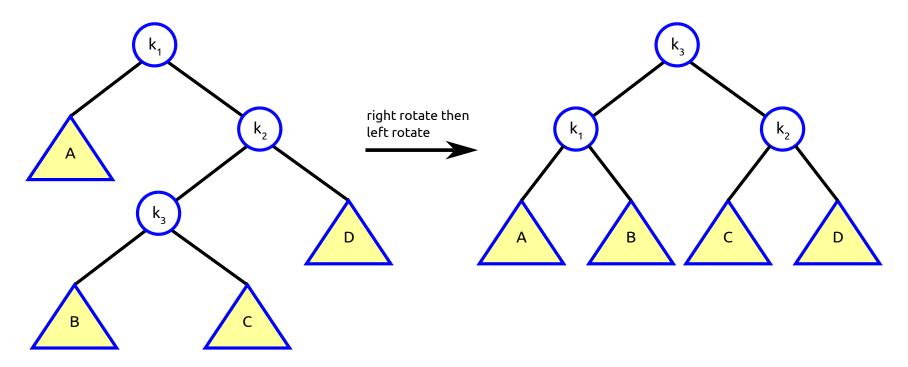


Right-left Double Rotation

• Solve case #3 with right rotation *followed by* left rotation.

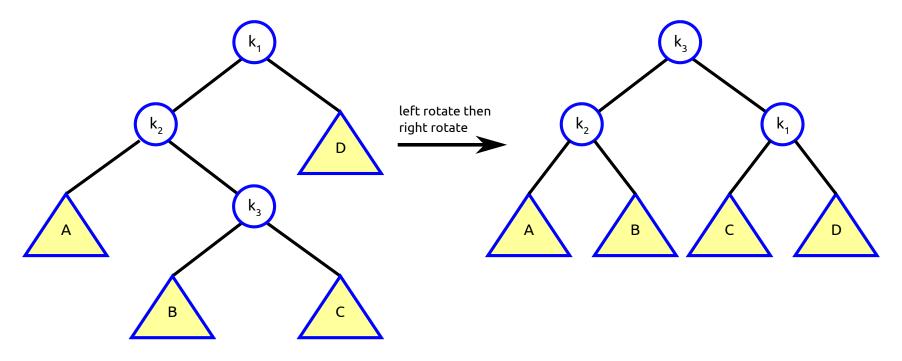


Right-left Double Rotation: Generic View



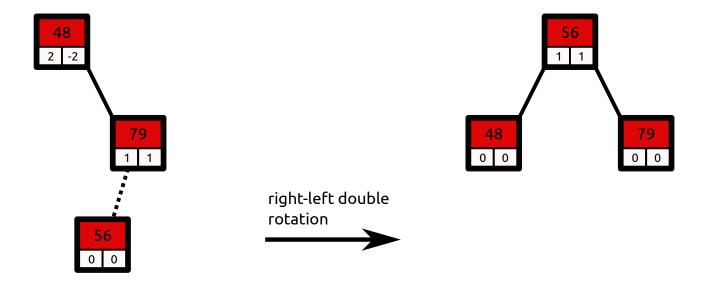
Left-right Double Rotation: Generic View

• Solve case #2 with left rotation followed by right rotation.



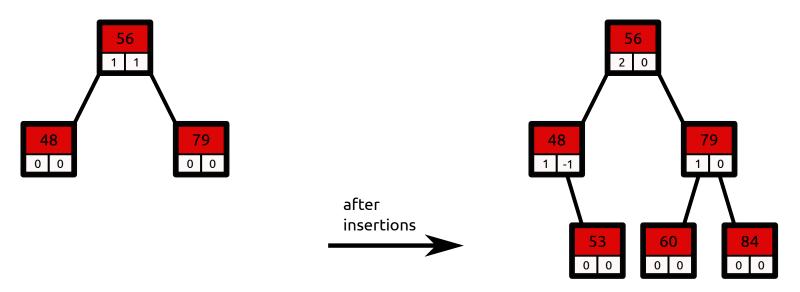
Examples of Insertions

insert(56):



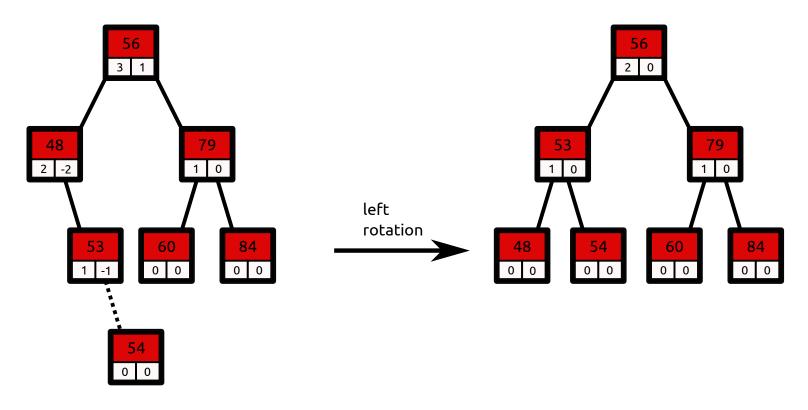
Examples of Insertions

insert(53), insert(60), insert(84):



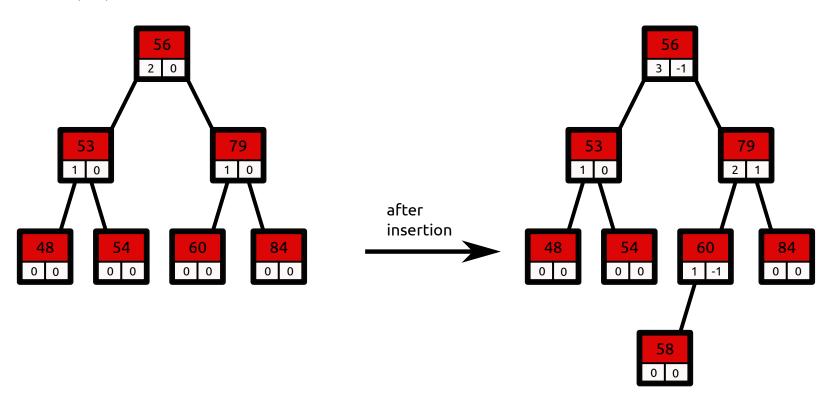
Examples of Insertions

insert(54):



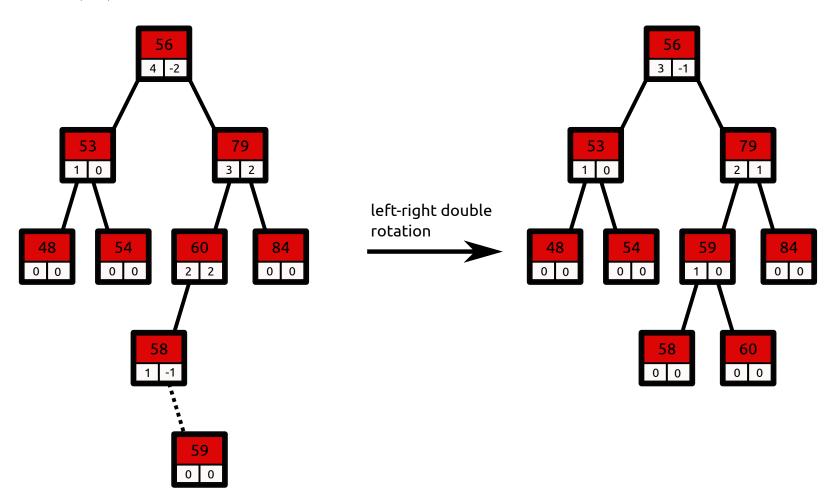
Examples of Insertions

insert(58):



Examples of Insertions

insert(59):



Notes on Textbook¹ Implementation

- The book has a BinarySearchTree class implementation that we didn't talk about.
- Their AVLTree class subclasses it / inherits from it. We probably will not talk about inheritance in this course², and you will not be expected to understand inheritance unless I teach it, but feel free to ask questions about it.
- Their AVLTree does not implement deletion.

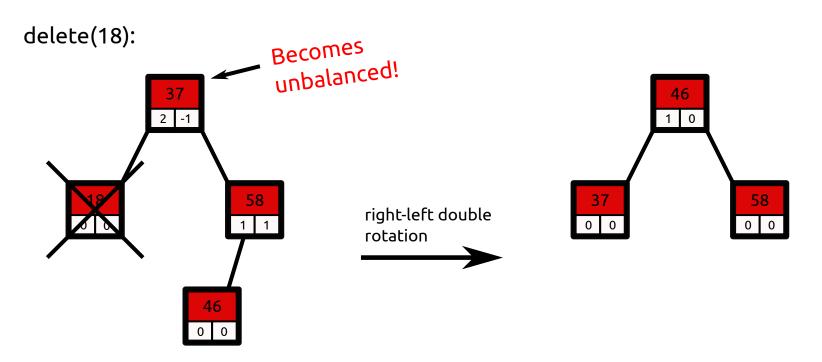
- 1. Problem Solving with Algorithms and Data Structures using Python by Brad Miller and David Ranum.
- 2. We will talk about inheritance in ECS 34, but even then, inheritance is a concept that is fading in popularity. One new popular language, Golang, does not even support inheritance (at least, not in the traditional sense).

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Deletion

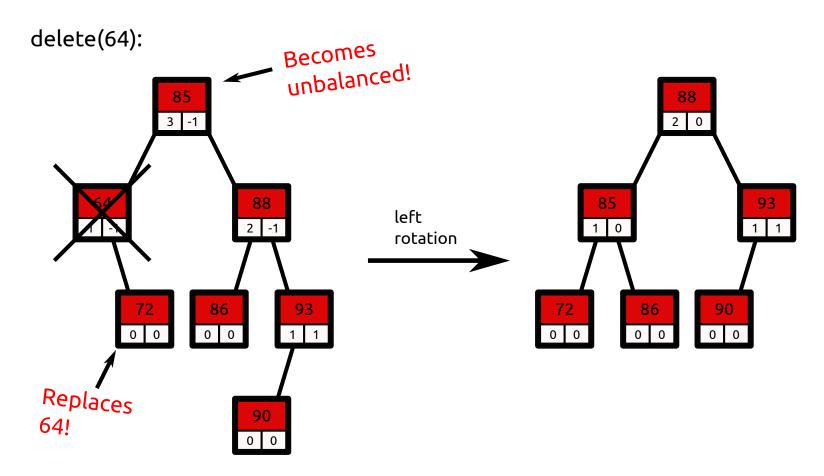
- Start with same procedure as BST.
- Going from replacement node (if any) up to root of tree, rebalance any unbalanced node.

Example #1



Deletion

Example #2

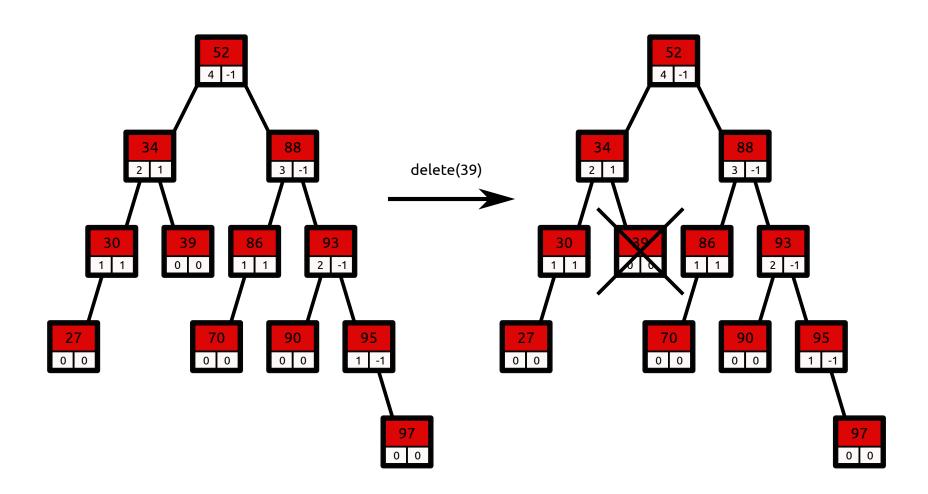


• 93 (instead of 86) is involved in rotation because higher height.

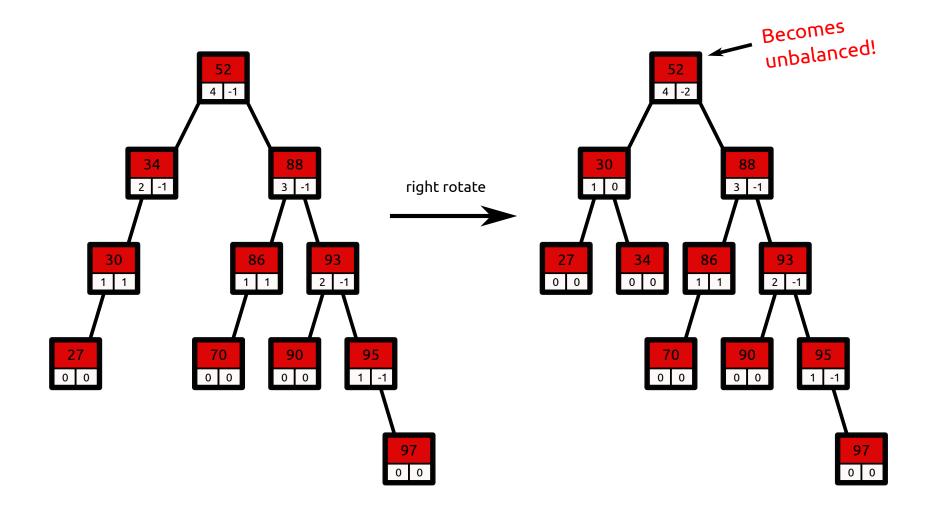
Deletion

• May have to rebalance at multiple nodes.

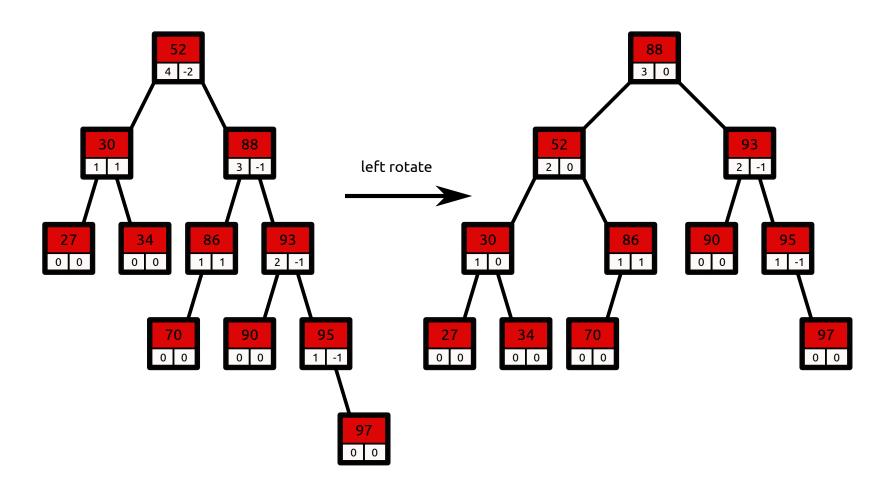
Example



Deletion Example



Deletion Example

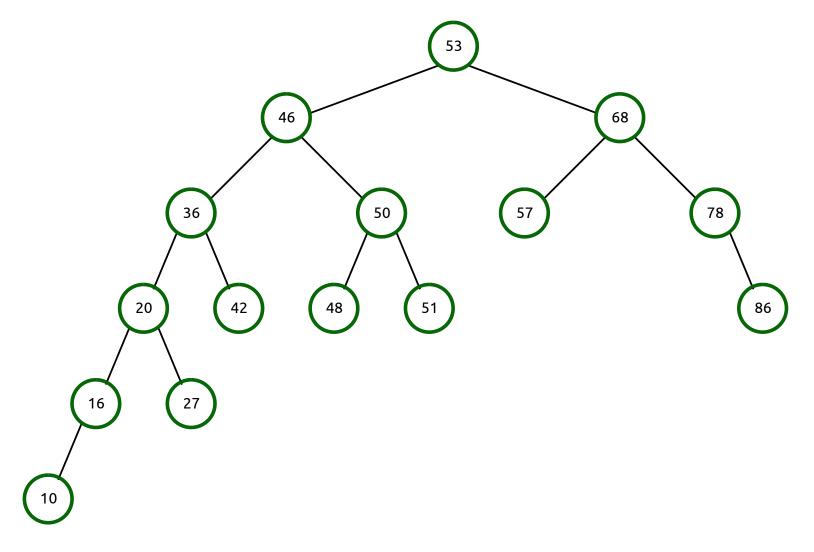


• I'll show you how the tree works and then explain the use of it / why one might use it over an AVL tree.

Quick Description

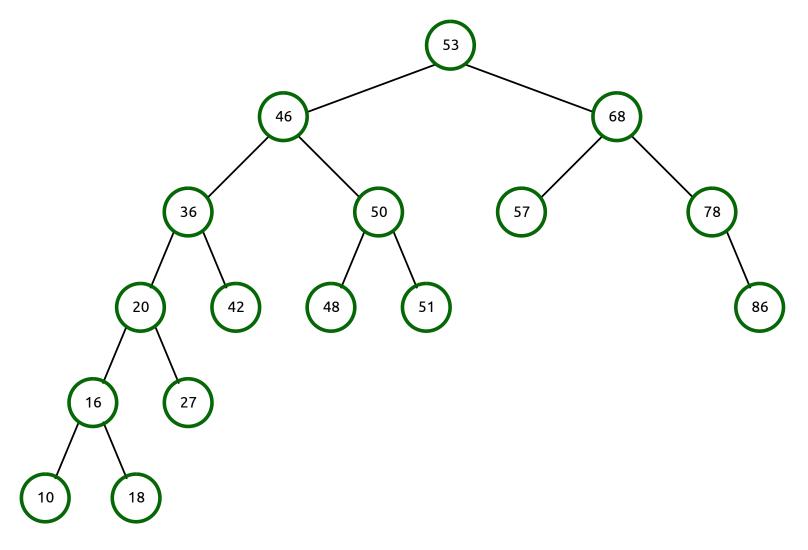
- Self-balancing, but less rigidly so.
- No balance factors.
- When a node is *accessed* (whether by find, insert, or delete), the node is pushed to the top.

Example #1



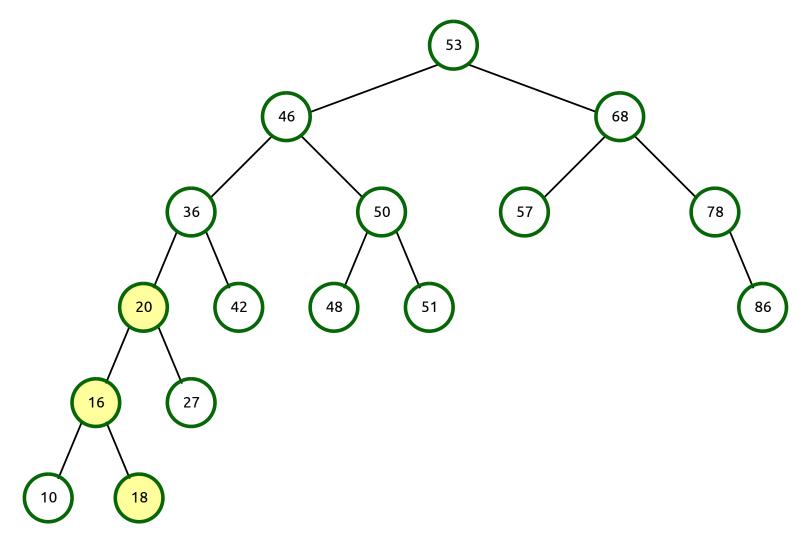
• Let's insert 18.

Example #1



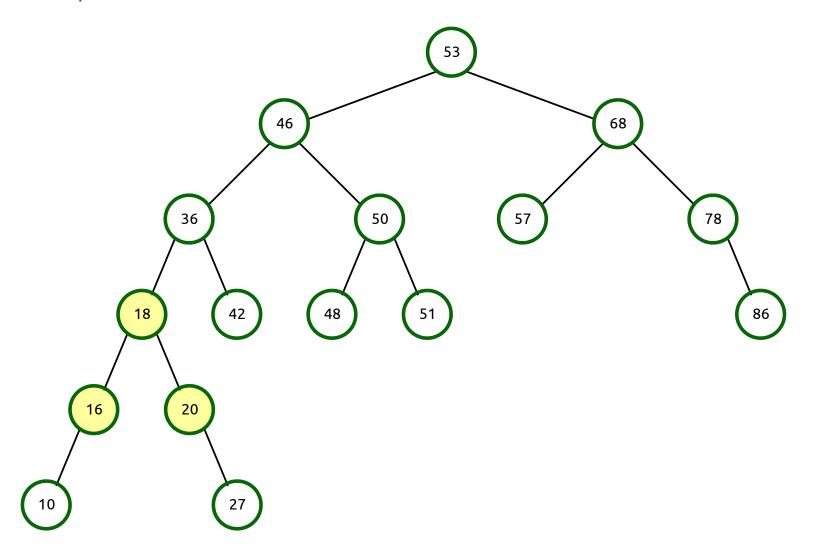
• Must splay 18 to the root.

Example #1

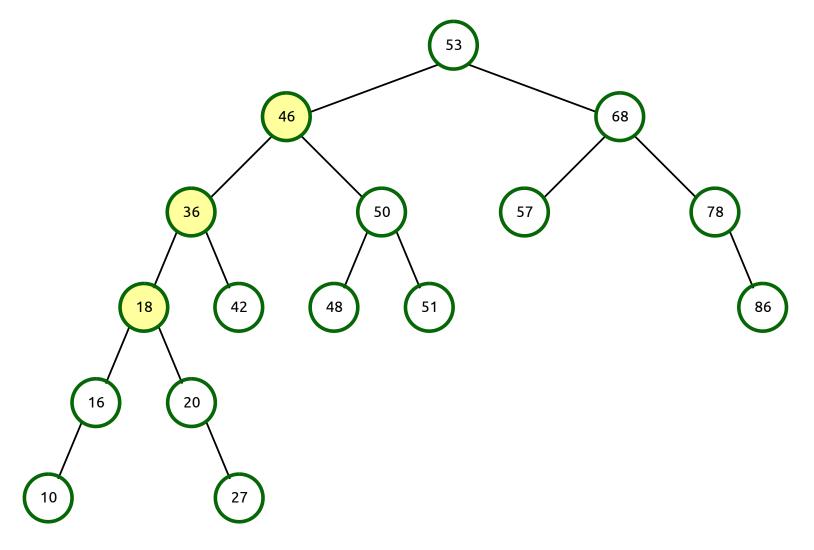


• Do a zig-zag! (i.e. an AVL tree-style left rotation and right rotation)

Example #1

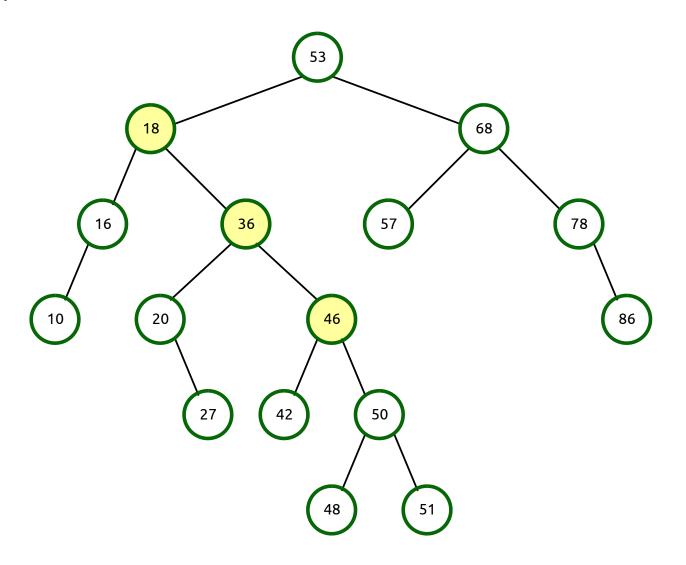


Example #1

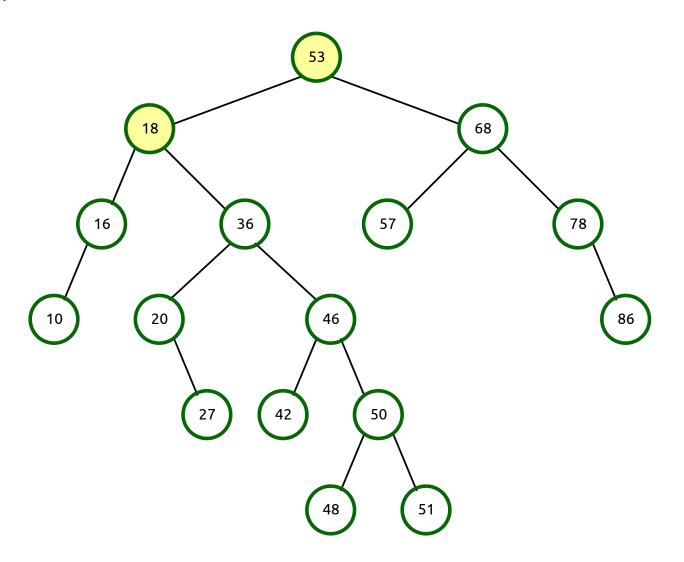


• Now do a zig-zig! (not similar to anything AVL tree does)

Example #1

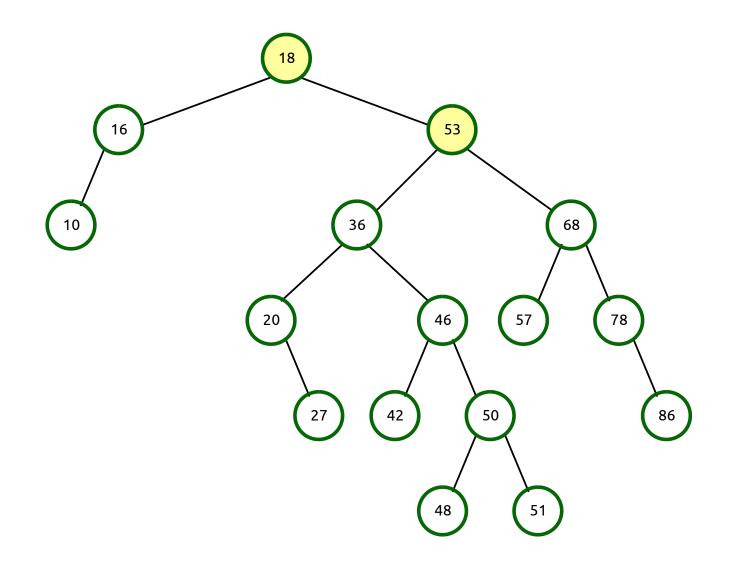


Example #1

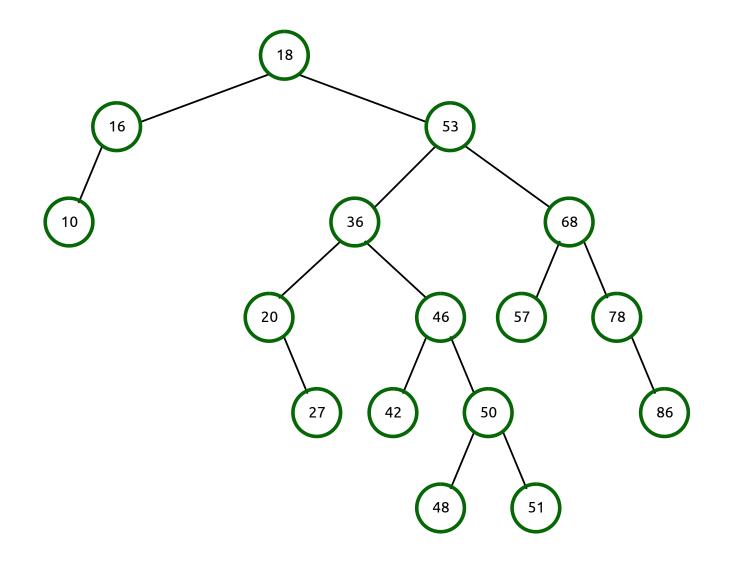


• Then a small pivot (a zig?).

Example #1



Example #1



• Done.

When Splay Operation Occurs

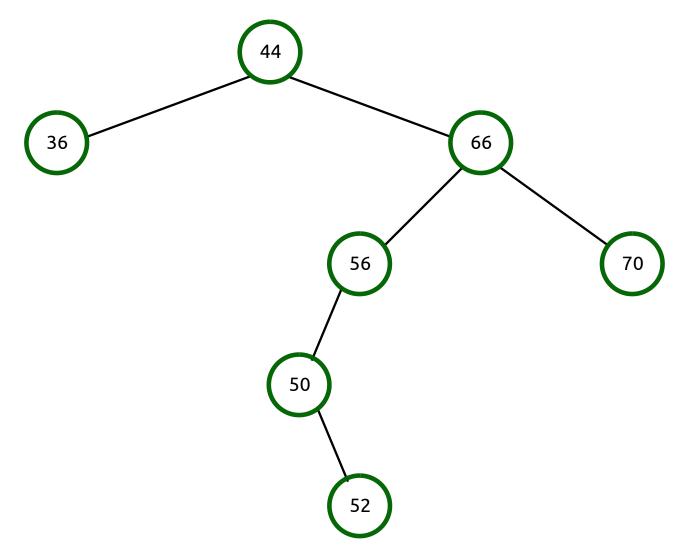
- Push node to the root when:
 - o *Insert* the node, i.e. insert the node following normal BST rules, then push to top.
 - Find the node.
 - Unlike previous data structures, a find operation modifies the structure.
 - o Delete the node.

Deletion

- 1. Push the node-to-delete to the top.
 - o Implementation: perform a find operation on it.
- 2. Delete it (now the root).
- 3. Find largest in left subtree¹. Push² that element to root of left subtree.
- 4. Make it root of entire tree.

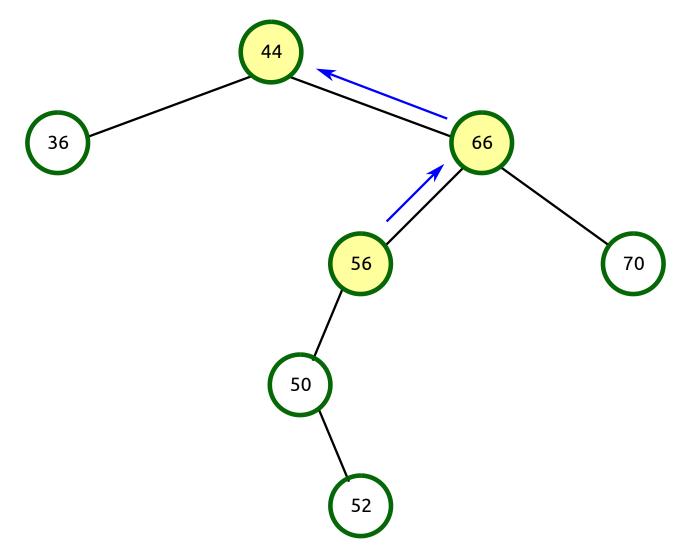
- 1. Could instead do smallest in right subtree.
- 2. This differs from BST which replaces instead of pushes.

Example #2



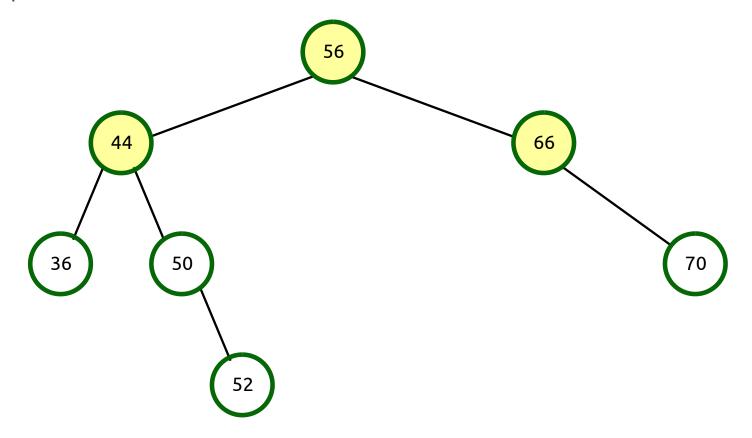
• Goal: delete 56.

Example #2



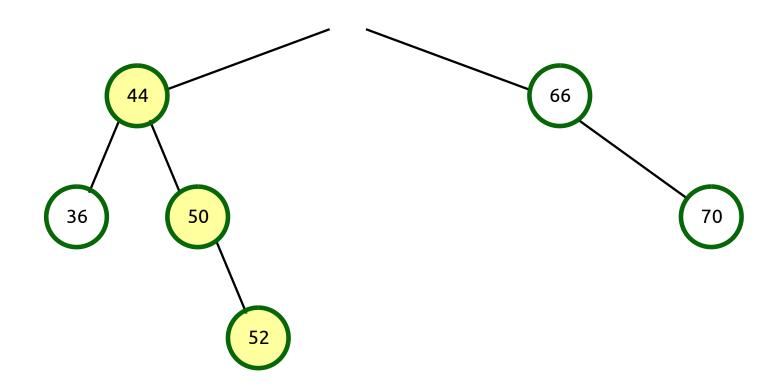
• Need to splay 56 to the top: zig-zag!

Example #2



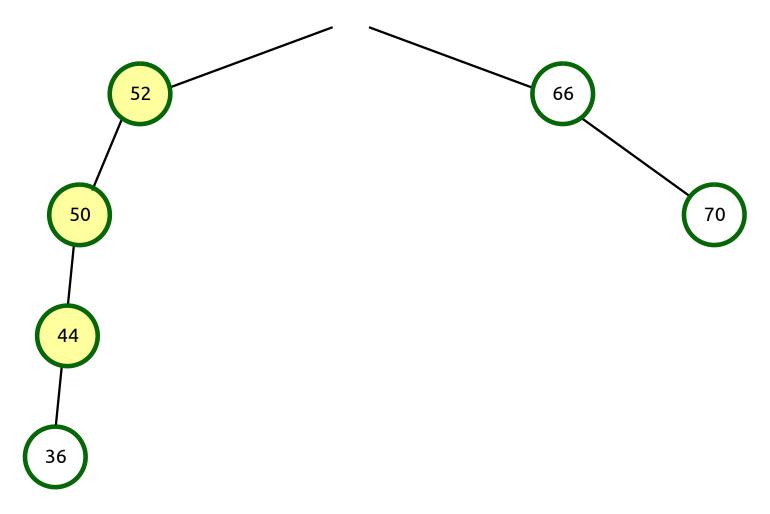
• Now, need to remove 56.

Example #2



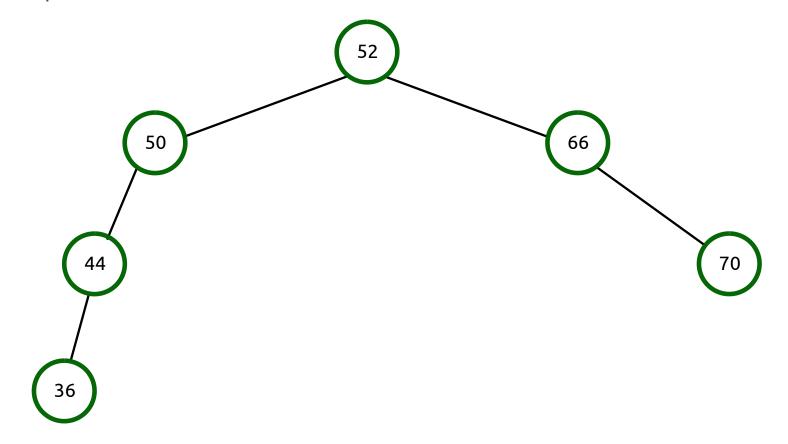
• Next, splay highest element in left subtree to top of that subtree: zig-zig!

Example #2



• Now, can combine the trees.

Example #2



• Done.

Reasons to Use

• Are situations in which data that was recently accessed is more likely to be accessed.

Worst-Case Time Complexity

- Single operation (find/insert/delete): $\Theta(n)$ in worst case.
- m operations (any combination of find/insert/delete): $\Theta(m \lg n)$ time in worst case \Rightarrow single operation takes **amortized** $\Theta(\lg n)$ time in worst case.
 - Splay operation on a deep node will bring it and its surrounding nodes up ⇒ worst-case scenario *provably* can't happen consistently, unlike normal BST.

Compared to AVL Tree

- AVL tree is preferable for *consistency*.
- Splay tree is easier to program¹.
- Splay tree takes less storage; no height info.

Other BST Operations

- Find, insert, and delete are not all.
- Other operations (that rely on the values being sorted in the BST):
 - Find min.
 - Find max.
 - Print tree's values in sorted order in linear time. (in order traversal)
 - o etc.
- Next slide deck: hash tables, which sacrifice some of these operations for speed.

References / Further Reading

- Additional topics that we will skip:
 - Red-black trees.
 - B trees.
- Chapter 7 of *Problem Solving with Algorithms and Data Structures using Python* by Brad Miller and David Ranum.
- Data Structures and Algorithm Analysis in C++ by Mark Allen Weiss (Fourth Edition).
 - Chapter 4: AVL trees, splay trees, B trees.
 - Chapter 11: amortized analysis.
- Introduction to Algorithms by Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein (Third Edition).
 - Chapter 13 is about red-black trees.
 - Chapter 17 is about amortized analysis.
- Chapter 10 of *Data Structures and Algorithms with Python* by Kent D. Lee and Steve Hubbard.
 - I believe this book is still legally, freely available.