

# Stat 206: Linear Models

## Lecture 6

October 14, 2019

## Adjusted Coefficient of Determination $R_a^2$

- A modified measure for degree of linear association between  $X$  and  $Y$ :

$$R_a^2 = 1 - \frac{MSE}{MSTO} = 1 - \frac{n-1}{n-2} \frac{SSE}{SSTO}.$$

- $R_a^2 \leq R^2 = 1 - \frac{SSE}{SSTO}$ .
- Heights.

$$R_a^2 = 1 - \frac{927}{926} \times \frac{4659}{5893} = 0.2085.$$

# Model Diagnostics

- Assumptions of the simple linear model with Normal errors:
  - 
  - 
  - 
  -
- Diagnostic plots can be used to examine the appropriateness of these assumptions.
  - **Residual plots.**
- Remedial measures: transformations.

# Model Diagnostics

- Assumptions of the simple linear model with Normal errors:
  - **linearity** of the regression relation
  - **normality** of the error terms
  - **constant variance** of the error terms
  - **independence** of the error terms
- Diagnostic plots can be used to examine the appropriateness of these assumptions.
  - **Residual plots.**
- Remedial measures: transformations.

# Residual Plots

- Examine regression relation and error variance.
  - Residual vs. predictor variable or residual vs. fitted value.
  - Residual vs. omitted predictor variable(s). (Later)
- Examine error distributions.
  - Normality: normal probability plot (Q-Q plot) of residuals.

# Detection of Nonlinearity

- If the residual vs. predictor variable plot (or residual vs. fitted value plot) shows a **, then it is an indication of possible nonlinearity in regression relation.**
- True model :  $Y = 5 - X + 0.1X^2 + \varepsilon$ .
  - 30 cases with  $X \sim N(100, 16^2)$  and  $\varepsilon \sim N(0, 10^2)$ .
  - Summary statistics:

$$\bar{X} = 104.13, \bar{Y} = 1004.79, \sum_i X_i^2 = 330962.9, \sum_i Y_i^2 = 32466188, \sum_i X_i Y_i = 3249512.$$

- Simple linear regression model was fitted to this data.

Coefficients	Estimate	Std. Error	t-statistic	P-value
Intercept	-1021.3803	40.0648	-25.49	$< 2 \times 10^{-16}$
Slope	19.4587	0.3814	51.01	$< 2 \times 10^{-16}$

$$\sqrt{MSE} = 28.78, R^2 = 0.9894, R_a^2 = 0.989.$$

## Detection of Nonlinearity

- If the residual vs. predictor variable plot (or residual vs. fitted value plot) shows a clear nonlinear pattern, then it is an indication of possible nonlinearity in regression relation as the nonlinearity would be left to the residuals.
- True model :  $Y = 5 - X + 0.1X^2 + \varepsilon$ .
  - 30 cases with  $X \sim N(100, 16^2)$  and  $\varepsilon \sim N(0, 10^2)$ .
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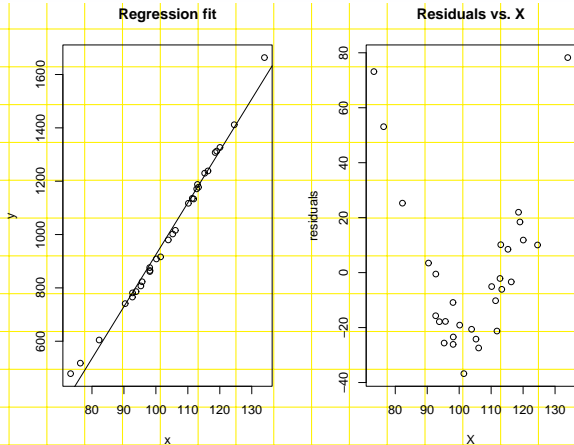
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$$\sqrt{MSE} = 28.78, R^2 = 0.9894, R_a^2 = 0.989.$$

Note that  $R^2$  is very large.



Here, the scatter plot (left) is not very effective in showing the nonlinearity: the observations  $Y_i$  are close to the fitted values  $\hat{Y}_i$  due to the steep slope of the fitted regression line.



# Detection of Nonconstancy in Variance

- If the residual vs. predictor variable plot (or residual vs. fitted value plot) shows

, then this is an indication of unequal variance.

## Detection of Nonconstancy in Variance

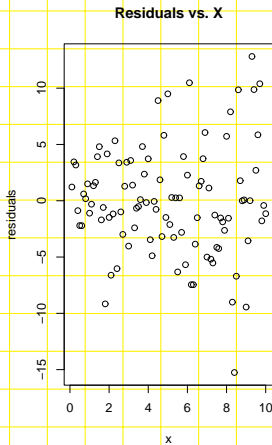
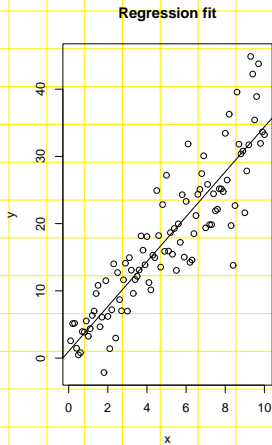
- **If the residual vs. predictor variable plot (or residual vs. fitted value plot) shows an unequal spread of the residuals along the x-axis, then this is an indication of unequal variance.**
- Sometimes, the variance of the error may depend on the value of the predictor variable.
  - Variance increases (or decreases) with the value of  $X$ : e.g., in financial data, the volume of transactions usually has a role in the uncertainty of the market.
  - Data may come from different strata with different variabilities: e.g., different measuring instruments with different precisions may have been used to obtain the observations.

True model :  $Y = 2 + 3X + \sigma(X)\varepsilon$ , where  $\log \sigma^2(X) = 1 + 0.1X$ .

- 100 cases with  $X_i = \frac{i}{10}$  and  $\varepsilon_i \sim N(0, 1)$ ,  $i = 1, \dots, 100$ .
- Simple linear regression model was fitted to this data.

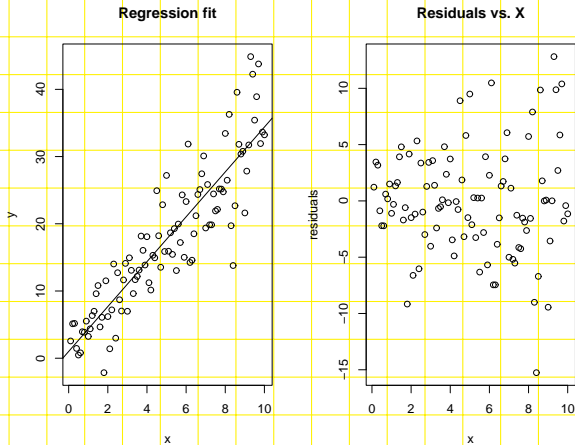
Coefficients	Estimate	Std. Error	t-statistic	P-value
Intercept	1.0074	0.9729	1.035	0.303
Slope	3.3382	0.1673	19.958	$< 2 \times 10^{-16}$

$$\sqrt{MSE} = 4.828, R^2 = 0.8026.$$



Note the spread of the residuals  
X.

with the value of



Note the spread of the residuals increases with the value of X.

# Detection of Nonnormality

- **Normality of the errors can be examined by a normal probability plot, a.k.a. Q-Q plot.**
  - $z_{(k)}$ 's: the *theoretical quantiles* under Normality
  - $e_{(k)}$ 's: the *sample quantiles or empirical quantiles*.
  - Q-Q plot is simply a scatter plot of  $e_{(k)}$ 's vs.  $z_{(k)}$ 's.

*Notes: Q-Q stands for quantile-quantile.*

## How to Read a Q-Q Plot?

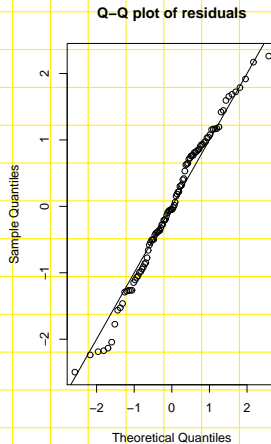
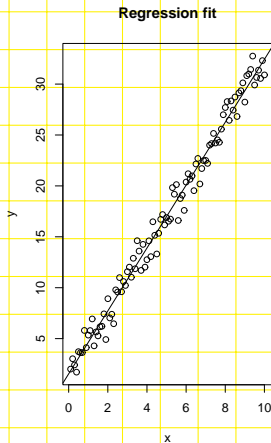
- If the errors are indeed normally distributed, then the points on the Q-Q plot should be .
- Departures from that could indicate **skewed** (non-symmetry) or **heavy-tailed** ( probability mass in tails than a Normal distribution) distributions.
- Other types of departures (e.g., nonlinearity) may affect the distribution of the residuals and render them non-normal.  
**Thus it is better to examine other types of departures before checking normality.**

## How to Read a Q-Q Plot?

- If the errors are indeed normally distributed, then the points on the Q-Q plot should be nearly on a straight line.
- Departures from that could indicate **skewed** (non-symmetry) or **heavy-tailed** (more probability mass in tails than a Normal distribution) distributions.
- Other types of departures (e.g., nonlinearity) may affect the distribution of the residuals and render them non-normal.  
**Thus it is better to examine other types of departures before checking normality.**



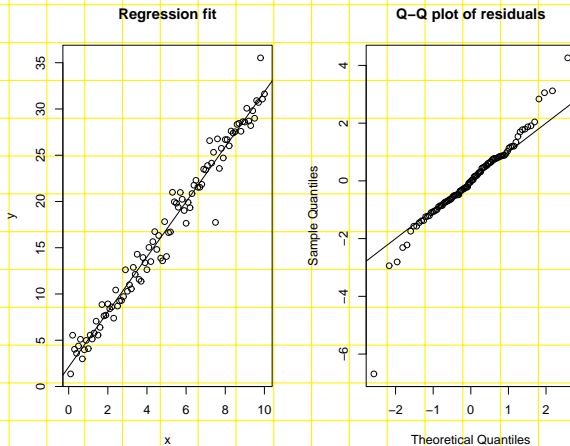
True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim N(0, 1)$ .



Q-Q plot shows a

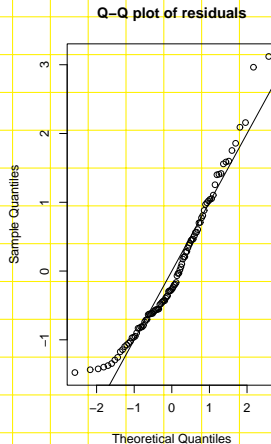
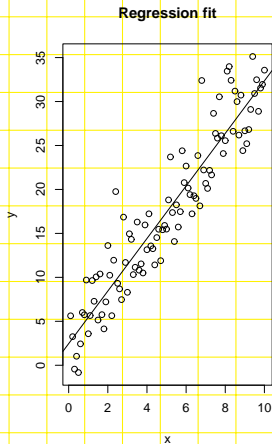
pattern.

True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim t_{(5)}$  – symmetrical but heavy-tailed errors.



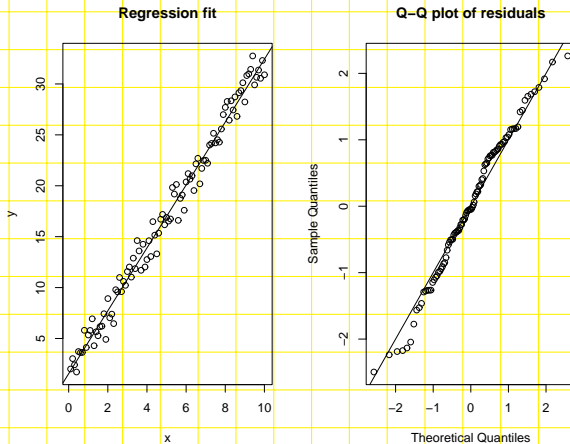
Q-Q plot shows  
than a Normal distribution.

True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim \chi^2_{(5)}$  – right-skewed errors.



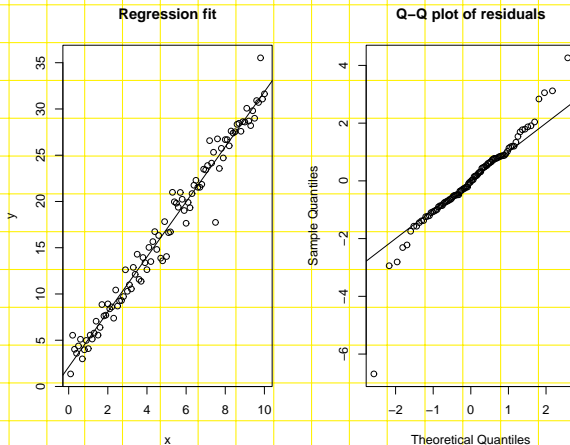
Q-Q plots shows

True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim N(0, 1)$ .



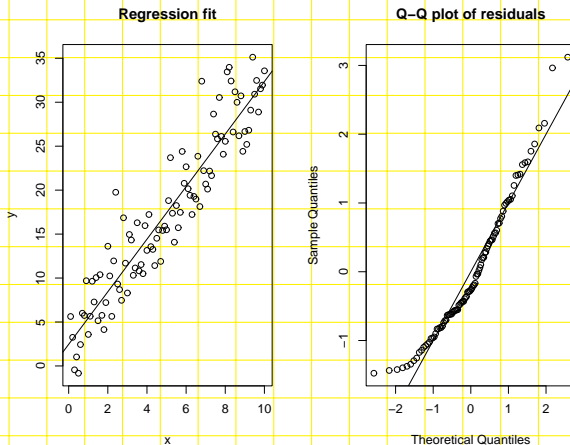
Q-Q plot shows a straight line pattern.

True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim t_{(5)}$  – symmetrical but heavy-tailed errors.



Q-Q plot shows more probabilities in both tails compared with Normal distribution.

True model :  $Y = 2 + 3X + \varepsilon$ .  $\varepsilon \sim \chi^2_{(5)}$  – right-skewed errors.



Q-Q plots shows more probabilities in the right tail and less probabilities in the left tail compared with Normal distribution.

# Transformations to Treat Unequal Variance and Nornormality

- Unequal variance and nornormality often appear together.
- Transformations on  $Y$  may fix the error distributions.
  - $Y' = \sqrt{Y}$
  - $Y' = \log Y$
  - $Y' = 1/Y$
  - Sometimes, add a constant to the transformation, e.g.,  $Y' = \log(c + Y)$ , to avoid negative or nearly zero values.
- A member from the family of power transformations may be chosen automatically by the **Box-Cox** procedure.
- Sometimes, a simultaneous transformation on  $X$  may be needed to maintain a linear relationship.

## Box-Cox Procedure

- For each  $\lambda \in R$ , standardize  $Y_i^\lambda$  such that the magnitude of SSE does not depend on  $\lambda$ :

$$Y_i^* = \begin{cases} K_1 \frac{Y_i^{\lambda-1}}{\lambda}, & \text{if, } \lambda \neq 0 \\ K_2 \log(Y_i), & \text{if, } \lambda = 0 \end{cases}$$

with

$$K_2 = \left( \prod_{i=1}^n Y_i \right)^{1/n}, \quad K_1 = 1/K_2^{\lambda-1}.$$

- Notes:  $\lambda = 0$  corresponds to the logarithm transformation.
- For each  $\lambda$ , fit a regression model on the transformed data  $Y_i^*$  and derive  $SSE(\lambda)$  (or maximum loglikelihood).
- Find the  $\lambda$  that maximizes loglikelihood.

(Notes: Read the lab 2 handout on Box-Cox procedure.)



# Simple Linear Regression in Matrix Form

The regression equations:

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i, \quad i = 1, \dots, n$$

can be written in a compact matrix form:

- **Response vector  $\mathbf{Y}$  and error vector** :  $n \times 1$  column vectors

# Simple Linear Regression in Matrix Form

The regression equations:

$$Y_i = \beta_0 + \beta_1 X_i + \epsilon_i, \quad i = 1, \dots, n$$

can be written in a compact matrix form:

$$\underset{n \times 1}{\mathbf{Y}} = \underset{n \times 2}{\mathbf{X}} \underset{2 \times 1}{\boldsymbol{\beta}} + \underset{n \times 1}{\boldsymbol{\epsilon}}.$$

- **Response vector  $\mathbf{Y}$  and error vector** :  $n \times 1$  column vectors

$$\mathbf{Y} = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_i \\ \vdots \\ Y_n \end{bmatrix}, \quad \boldsymbol{\epsilon} = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_i \\ \vdots \\ \epsilon_n \end{bmatrix}$$

- **Design matrix:** an  $n \times 2$  matrix:

- **Coefficient vector:** a  $2 \times 1$  column vector:

- **Design matrix:** an  $n \times 2$  matrix:

$$\mathbf{X} = \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_i \\ \vdots & \vdots \\ 1 & X_n \end{bmatrix}.$$

- **Coefficient vector:** a  $2 \times 1$  column vector:

$$\boldsymbol{\beta} = \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix}.$$

- Model assumptions:

$$E(\epsilon_i) = 0, \quad \text{Var}(\epsilon_i) = \sigma^2, \quad \text{for all } i = 1, \dots, n$$

$$\text{Cov}(\epsilon_i, \epsilon_j) = 0, \quad \text{for all } i \neq j.$$

- Matrix form:

- In terms of the response vector  $\mathbf{Y}$ :

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- Matrix form:

$$\mathbf{E}\{\boldsymbol{\epsilon}\} = \mathbf{0}_n, \quad \sigma^2\{\boldsymbol{\epsilon}\} = \sigma^2 \mathbf{I}_n.$$

- In terms of the response vector:

$$\mathbf{E}\{\mathbf{Y}\} = \mathbf{X}\boldsymbol{\beta}, \quad \sigma^2\{\mathbf{Y}\} = \sigma^2 \mathbf{I}_n.$$

- $\mathbf{0}_n$  is the  $n \times 1$  zero vector,  $\mathbf{I}_n$  is the  $n \times n$  identity matrix.
- Mean of the error vector:

$$\mathbf{E}\{\boldsymbol{\epsilon}\} := \begin{bmatrix} E(\epsilon_1) \\ E(\epsilon_2) \\ \vdots \\ E(\epsilon_n) \end{bmatrix} =$$

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$$\mathbf{E}\{\boldsymbol{\epsilon}\} := \begin{bmatrix} E(\epsilon_1) \\ E(\epsilon_2) \\ \vdots \\ E(\epsilon_n) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \mathbf{0}_n.$$



Variance-covariance matrix of the error vector:

$$\sigma^2_{\{\epsilon\}} : = \begin{bmatrix} \text{Var}(\epsilon_1) & \text{Cov}(\epsilon_1, \epsilon_2) & \cdots & \text{Cov}(\epsilon_1, \epsilon_n) \\ \text{Cov}(\epsilon_2, \epsilon_1) & \text{Var}(\epsilon_2) & \cdots & \text{Cov}(\epsilon_2, \epsilon_n) \\ \vdots & \vdots & \vdots & \vdots \\ \text{Cov}(\epsilon_n, \epsilon_1) & \text{Cov}(\epsilon_n, \epsilon_2) & \cdots & \text{Var}(\epsilon_n) \end{bmatrix}$$

=

Variance-covariance matrix of the error vector:

$$\begin{aligned}\sigma^2\{\epsilon\} &:= \begin{bmatrix} \text{Var}(\epsilon_1) & \text{Cov}(\epsilon_1, \epsilon_2) & \cdots & \text{Cov}(\epsilon_1, \epsilon_n) \\ \text{Cov}(\epsilon_2, \epsilon_1) & \text{Var}(\epsilon_2) & \cdots & \text{Cov}(\epsilon_2, \epsilon_n) \\ \vdots & \vdots & \ddots & \vdots \\ \text{Cov}(\epsilon_n, \epsilon_1) & \text{Cov}(\epsilon_n, \epsilon_2) & \cdots & \text{Var}(\epsilon_n) \end{bmatrix} \\ &= \begin{bmatrix} \sigma^2 & 0 & \cdots & 0 \\ 0 & \sigma^2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma^2 \end{bmatrix} = \sigma^2 \mathbf{I}_n.\end{aligned}$$

**Mean response vector:** an  $n \times 1$  column vector

$$\mathbf{E}\{\mathbf{Y}\} = \begin{bmatrix} E(Y_1) \\ E(Y_2) \\ \vdots \\ E(Y_i) \\ \vdots \\ E(Y_n) \end{bmatrix} =$$

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$$\mathbf{E}\{\mathbf{Y}\} = \begin{bmatrix} E(Y_1) \\ E(Y_2) \\ \vdots \\ E(Y_i) \\ \vdots \\ E(Y_n) \end{bmatrix} = \begin{bmatrix} \beta_0 + \beta_1 X_1 \\ \beta_0 + \beta_1 X_2 \\ \vdots \\ \beta_0 + \beta_1 X_i \\ \vdots \\ \beta_0 + \beta_1 X_n \end{bmatrix} = \begin{bmatrix} 1 & X_1 \\ 1 & X_2 \\ \vdots & \vdots \\ 1 & X_i \\ \vdots & \vdots \\ 1 & X_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} = \mathbf{X}\boldsymbol{\beta}.$$

# Summary: Simple Linear Regression in Matrix Form

$$\underset{n \times 1}{\mathbf{Y}} = \underset{n \times 2}{\mathbf{X}} \underset{2 \times 1}{\boldsymbol{\beta}} + \underset{n \times 1}{\boldsymbol{\epsilon}}.$$

- $\boldsymbol{\epsilon}$  is a random vector with  $\mathbf{E}\{\boldsymbol{\epsilon}\} = \mathbf{0}_n$ ,  $\sigma^2\{\boldsymbol{\epsilon}\} = \sigma^2 \mathbf{I}_n$ .
- Normal error model:  $\boldsymbol{\epsilon} \sim \text{Normal}_n(\mathbf{0}_n, \sigma^2 \mathbf{I}_n)$ .

# Least Squares Estimation in Matrix Form

- Least squares criterion:

$$Q(b_0, b_1) = \sum_{i=1}^n (Y_i - (b_0 + b_1 X_i))^2.$$

- Matrix form :

$$Q(\mathbf{b}) = (\mathbf{Y} - \mathbf{X}\mathbf{b})' (\mathbf{Y} - \mathbf{X}\mathbf{b}) = \mathbf{Y}'\mathbf{Y} - \mathbf{b}'\mathbf{X}'\mathbf{Y} - \mathbf{Y}'\mathbf{X}\mathbf{b} + \mathbf{b}'\mathbf{X}'\mathbf{X}\mathbf{b}.$$

- Differentiate  $Q$  with respect to  $\mathbf{b}$ :

$$\frac{\partial}{\partial \mathbf{b}} Q = -2\mathbf{X}'\mathbf{Y} + 2\mathbf{X}'\mathbf{X}\mathbf{b}.$$

- Set the gradient to zero  $\implies$  normal equation:

$$\mathbf{X}'\mathbf{X}\mathbf{b} = \mathbf{X}'\mathbf{Y}. \quad (1)$$

Least-square estimators are the solutions of equation (1).

- Multiply both sides of equation (1) by  $(\mathbf{X}'\mathbf{X})^{-1}$ :

$$(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{X}\mathbf{b} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y}.$$

- The left hand side becomes

- **LS estimators:**

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- The left hand side becomes

$$\mathbf{I}_2\mathbf{b} = \mathbf{b}$$

- **LS estimators:**

$$\hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y}. \quad (2)$$



$$\mathbf{X}'\mathbf{X} =$$

Note that  $\mathbf{X}'\mathbf{X}$  and  $(\mathbf{X}'\mathbf{X})^{-1}$  are

matrices.

$$\mathbf{X}'\mathbf{X} = \begin{bmatrix} n & \sum_{i=1}^n X_i \\ \sum_{i=1}^n X_i & \sum_{i=1}^n X_i^2 \end{bmatrix}, \quad \mathbf{X}'\mathbf{Y} = \begin{bmatrix} \sum_{i=1}^n Y_i \\ \sum_{i=1}^n X_i Y_i \end{bmatrix}.$$

When

$$D := n \sum_{i=1}^n X_i^2 - \left( \sum_{i=1}^n X_i \right)^2 = n \sum_{i=1}^n (X_i - \bar{X})^2 \neq 0$$

$$\begin{aligned} (\mathbf{X}'\mathbf{X})^{-1} &= \begin{bmatrix} \frac{\sum_{i=1}^n X_i^2}{n \sum_{i=1}^n (X_i - \bar{X})^2} & -\frac{\sum_{i=1}^n X_i}{n \sum_{i=1}^n (X_i - \bar{X})^2} \\ -\frac{\sum_{i=1}^n X_i}{n \sum_{i=1}^n (X_i - \bar{X})^2} & \frac{n}{n \sum_{i=1}^n (X_i - \bar{X})^2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{n} + \frac{\bar{X}^2}{\sum_{i=1}^n (X_i - \bar{X})^2} & -\frac{\bar{X}}{\sum_{i=1}^n (X_i - \bar{X})^2} \\ -\frac{\bar{X}}{\sum_{i=1}^n (X_i - \bar{X})^2} & \frac{1}{\sum_{i=1}^n (X_i - \bar{X})^2} \end{bmatrix}. \end{aligned}$$

Note that  $\mathbf{X}'\mathbf{X}$  and  $(\mathbf{X}'\mathbf{X})^{-1}$  are symmetric positive definite matrices.

- LS estimators:

$$\begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} =$$

provided that  $X_i$ s are

- $n \times 1$  vector of fitted values:

$$\widehat{\mathbf{Y}} =$$

where  $\mathbf{H} := \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$  is called the

- $n \times 1$  vector of residuals:

$$\mathbf{e} =$$

- Fitted values vector  $\widehat{\mathbf{Y}}$  and residuals vector  $\mathbf{e}$  are of the observations vector  $\mathbf{Y}$ .

- LS estimators:

$$\begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \end{bmatrix} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} = \begin{bmatrix} \bar{Y} - \hat{\beta}_1\bar{X} \\ \frac{\sum_{i=1}^n (X_i - \bar{X})(Y_i - \bar{Y})}{\sum_{i=1}^n (X_i - \bar{X})^2} \end{bmatrix},$$

provided that  $X_i$ s are not all equal.

- $n \times 1$  vector of fitted values:

$$\widehat{\mathbf{Y}} = \mathbf{X}\hat{\boldsymbol{\beta}} = \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{Y} = \mathbf{H}\mathbf{Y},$$

where  $\mathbf{H} := \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'$  is called the **hat matrix**.

- $n \times 1$  vector of residuals:

$$\mathbf{e} = \mathbf{Y} - \widehat{\mathbf{Y}} = (\mathbf{I}_n - \mathbf{H})\mathbf{Y}.$$

- Fitted values vector  $\widehat{\mathbf{Y}}$  and residuals vector  $\mathbf{e}$  are linear transformations of the observations vector  $\mathbf{Y}$ .

# Hat Matrix

$$\mathbf{H}_{n \times n} := \mathbf{X}(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'.$$

$\mathbf{H}$  and  $\mathbf{I}_n - \mathbf{H}$  are **projection matrices**.

- Symmetric:
- Idempotent:
- Moreover,  $\text{rank}(\mathbf{H}) =$  ,  $\text{rank}(\mathbf{I}_n - \mathbf{H}) =$  .

# Hat Matrix

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$\mathbf{H}$  and  $\mathbf{I}_n - \mathbf{H}$  are **projection matrices**.

- Symmetric:

$$\mathbf{H}' = \mathbf{H}, \quad (\mathbf{I}_n - \mathbf{H})' = \mathbf{I}_n - \mathbf{H}$$

- Idempotent:

$$\mathbf{H}^2 := \mathbf{H}\mathbf{H} = \mathbf{H}, \quad (\mathbf{I}_n - \mathbf{H})^2 = \mathbf{I}_n - \mathbf{H}.$$

- Moreover,  $\text{rank}(\mathbf{H}) = 2$ ,  $\text{rank}(\mathbf{I}_n - \mathbf{H}) = n - 2$ .

## Column Space of the Design Matrix $X$

- Let  $\mathbf{1}_n$  denote the  $n \times 1$  vector of ones and  $\mathbf{x} = (X_1, \dots, X_n)^T$  denote the  $n \times 1$  vector of design points.

- The design matrix

$$\mathbf{X} = (\mathbf{1}_n, \mathbf{x}).$$

- $\langle X \rangle$  is the

- $\langle X \rangle =$

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$$\mathbf{X} = (\mathbf{1}_n, \mathbf{x}).$$

- $\langle X \rangle$  is the linear subspace of  $\mathbf{R}^n$  generated by the columns of  $\mathbf{X}$ .
- $\langle X \rangle = \{c_0 \mathbf{1}_n + c_1 \mathbf{x} = \mathbf{X}\mathbf{c} : c_0, c_1 \in R, \mathbf{c} = (c_0, c_1)^T\}.$