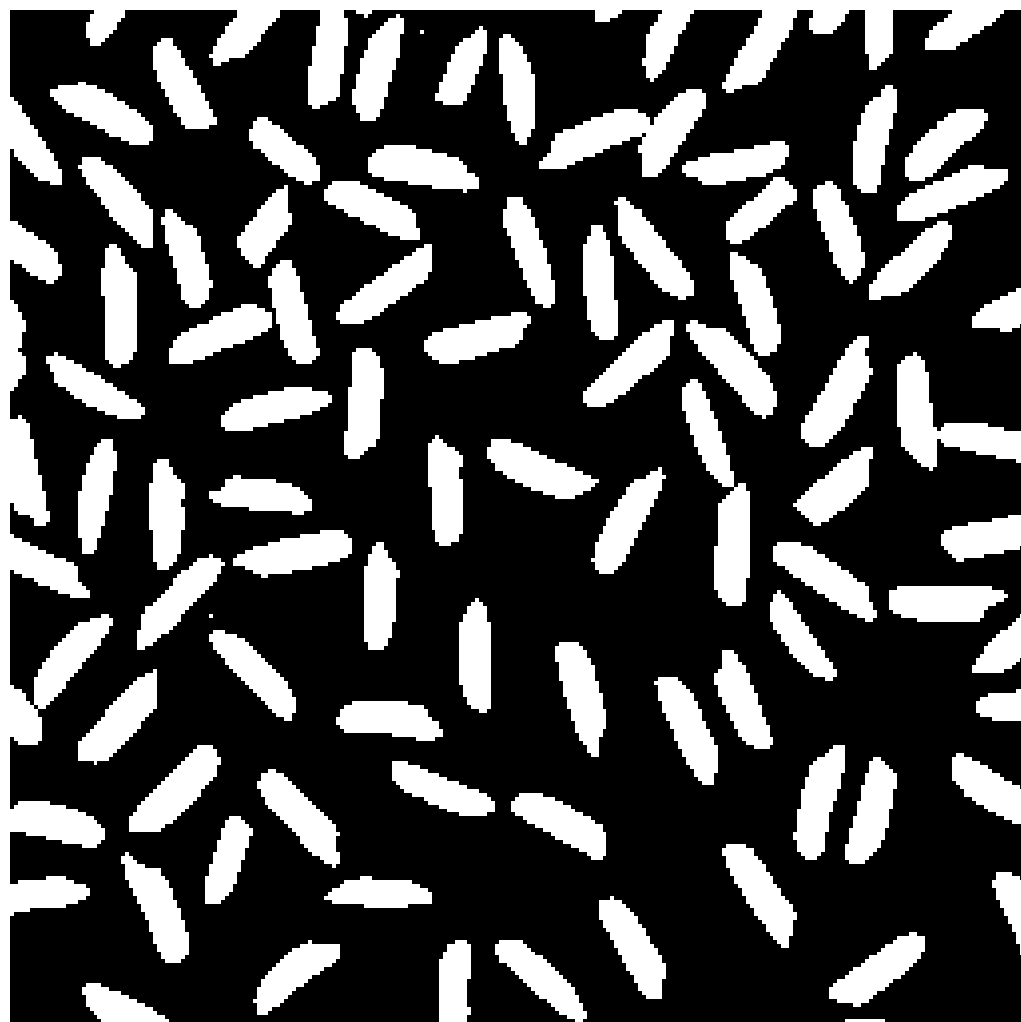


# 二值图像处理

# BINARY IMAGE PROCESSING

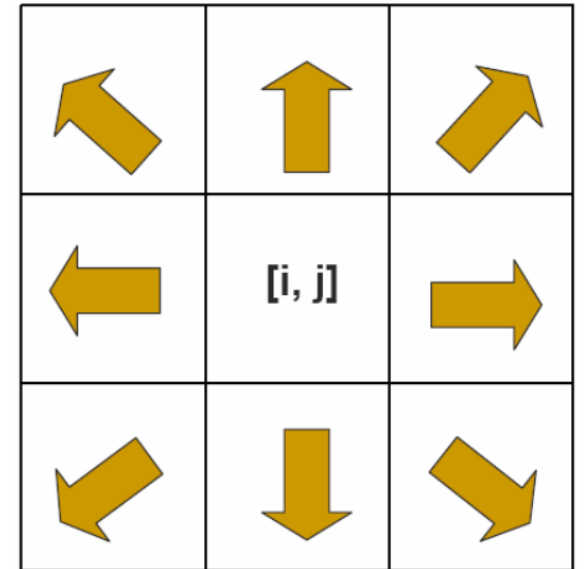
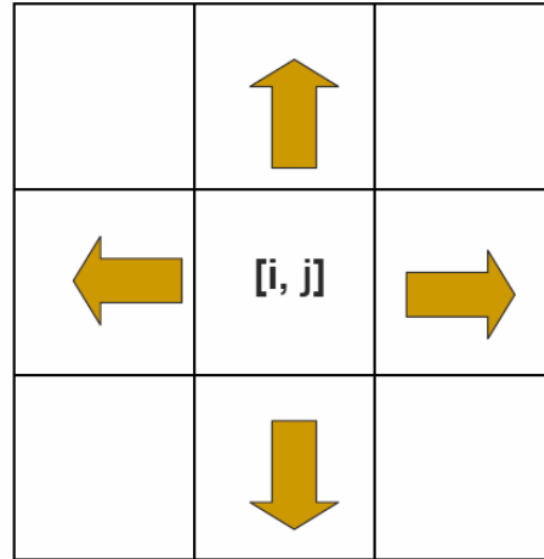


# 距离与邻域(Distance & Neighbors)

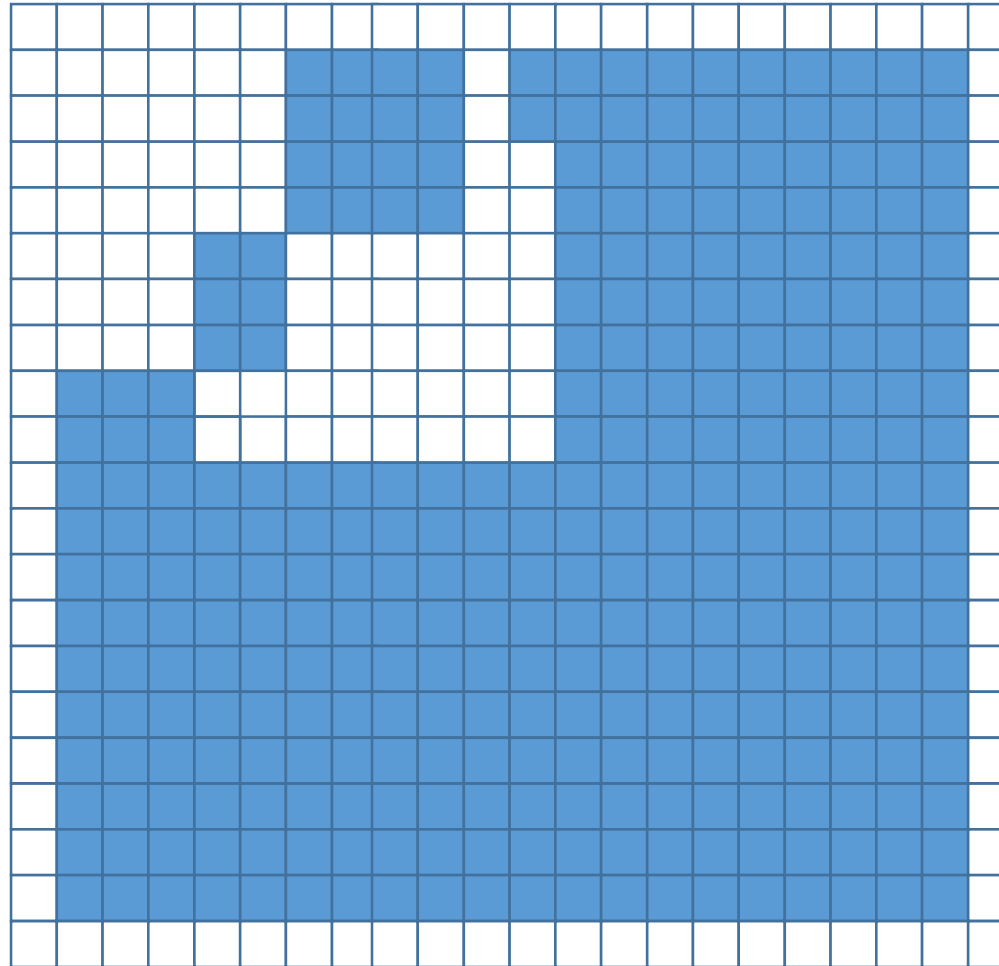
$$d_4 = |\Delta x| + |\Delta y|$$

$$d_8 = \max(|\Delta x|, |\Delta y|)$$

$$d = \sqrt{(\Delta x)^2 + (\Delta y)^2}$$



# 连通性 (Connectness)

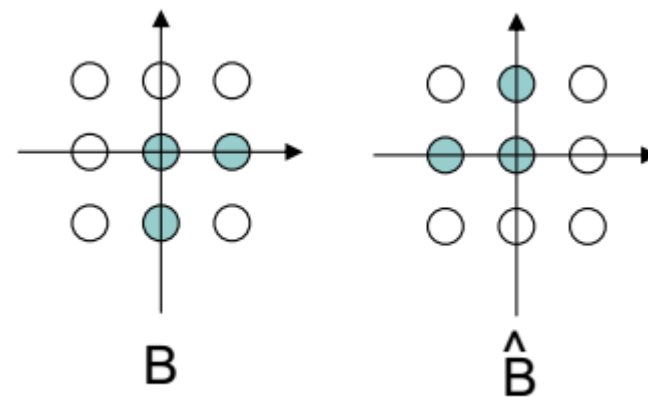


平移 Translation Operator

$$(A)_z = \{w \mid w = a + z, a \in A\}$$

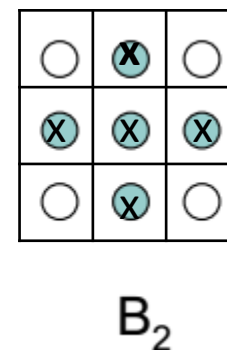
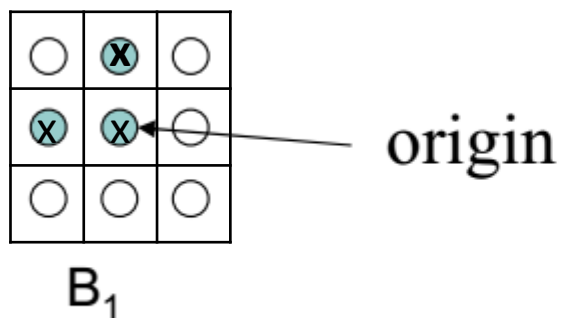
镜像 Reflection Operator

$$\hat{B} = \{w \mid w = -b, b \in B\}$$



# 形态学滤波器 Morphological filtering

## 结构元 Structuring Element B

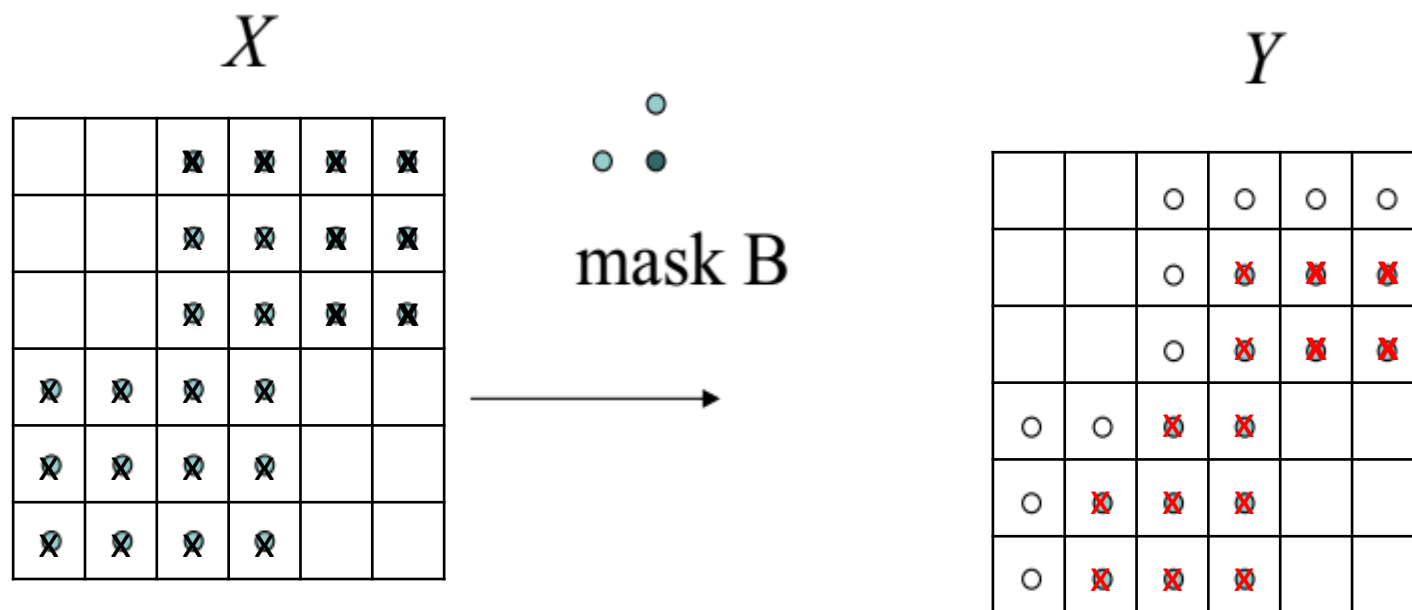


腐蚀

**Erosion**

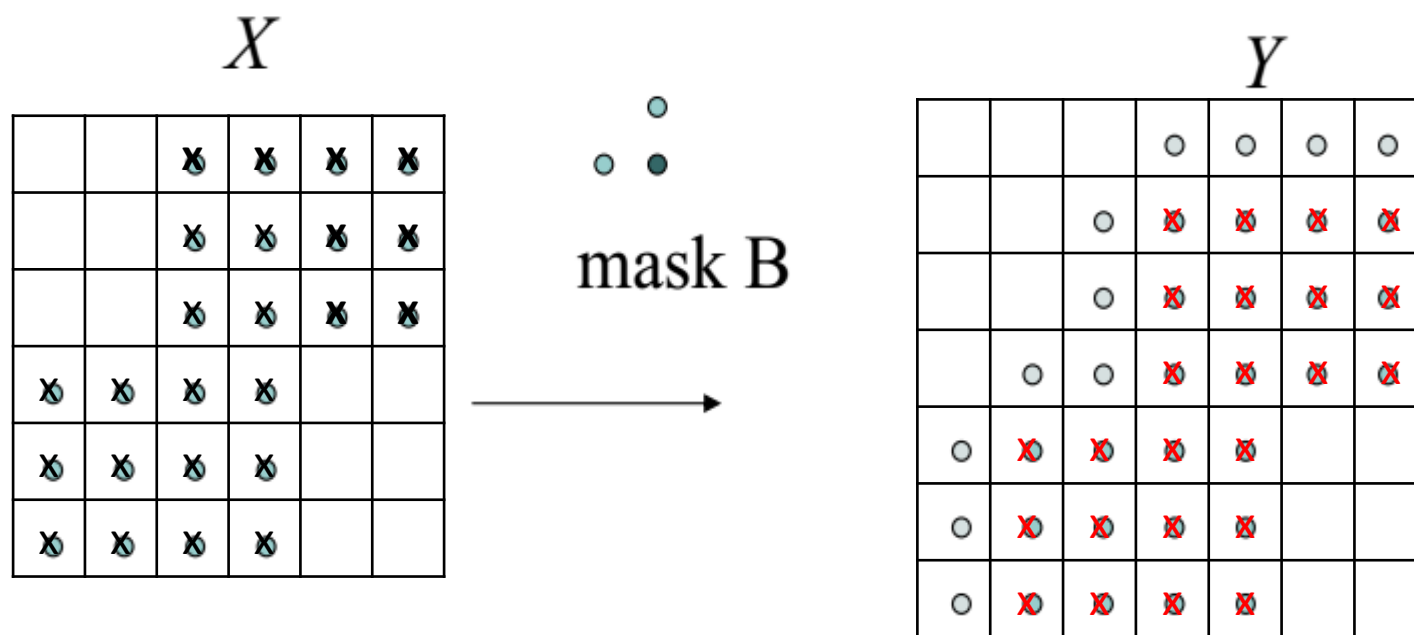
$$Y = X \ominus B = \{x : B_x \subset X\}$$

$$\min(X, B)$$



扩张 **Dilation**  $Y = X \oplus B = \{z \mid (\hat{B})_z \cap X \neq \emptyset\}$

$\max(X, \hat{B})$































开运算

# Opening Operator

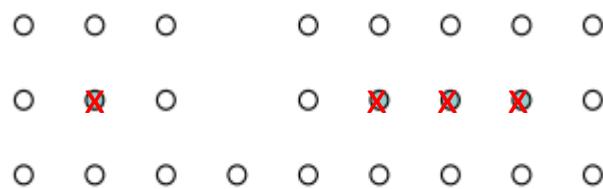
$$X \circ B = (X \ominus B) \oplus B$$

$X$

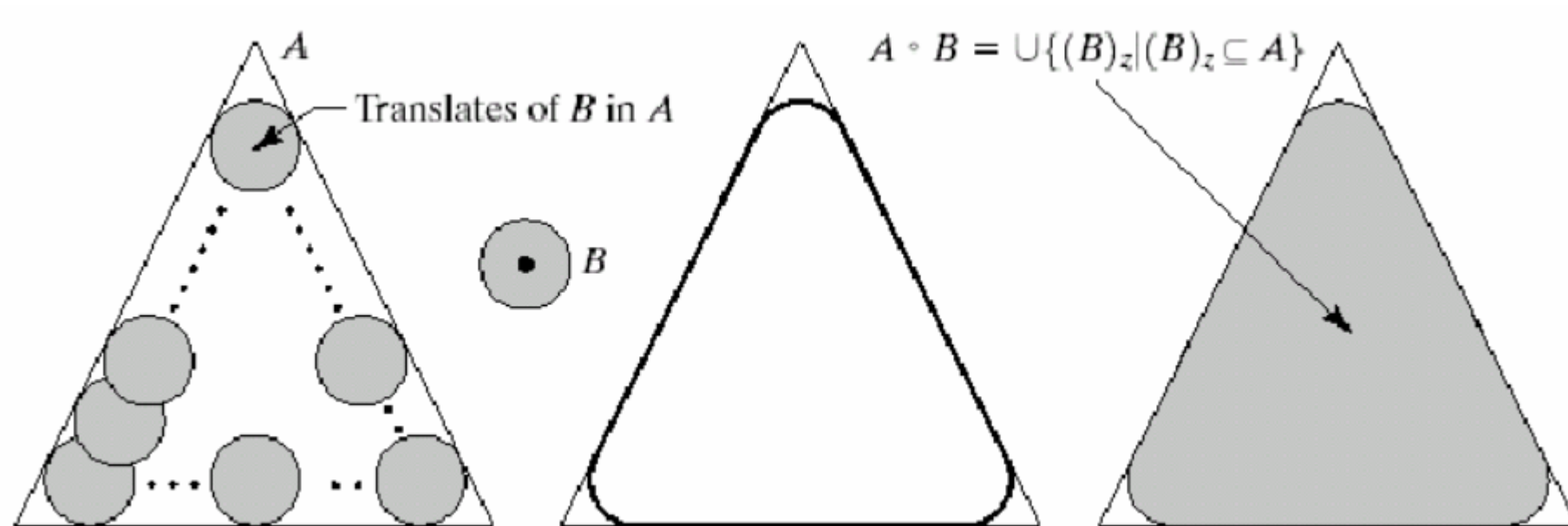


$B$



$X \circ B$





闭运算

# Closing Operator

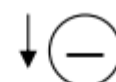
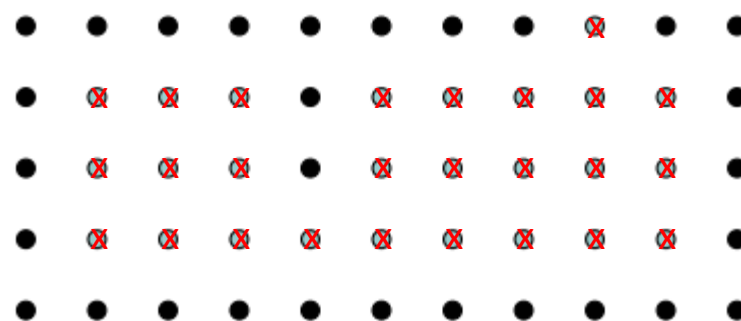
$$X \bullet B = (X \oplus B) \ominus B$$

$X$

							<del>x</del>	
<del>x</del>	<del>x</del>	<del>x</del>		<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>
<del>x</del>	<del>x</del>	<del>x</del>		<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>
<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>	<del>x</del>

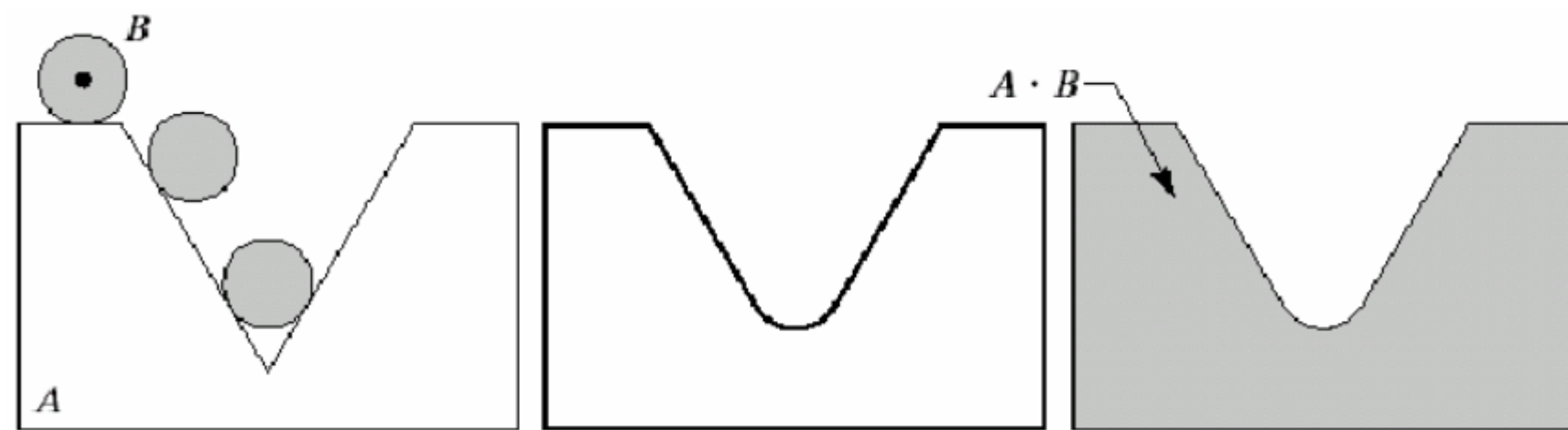


$B$



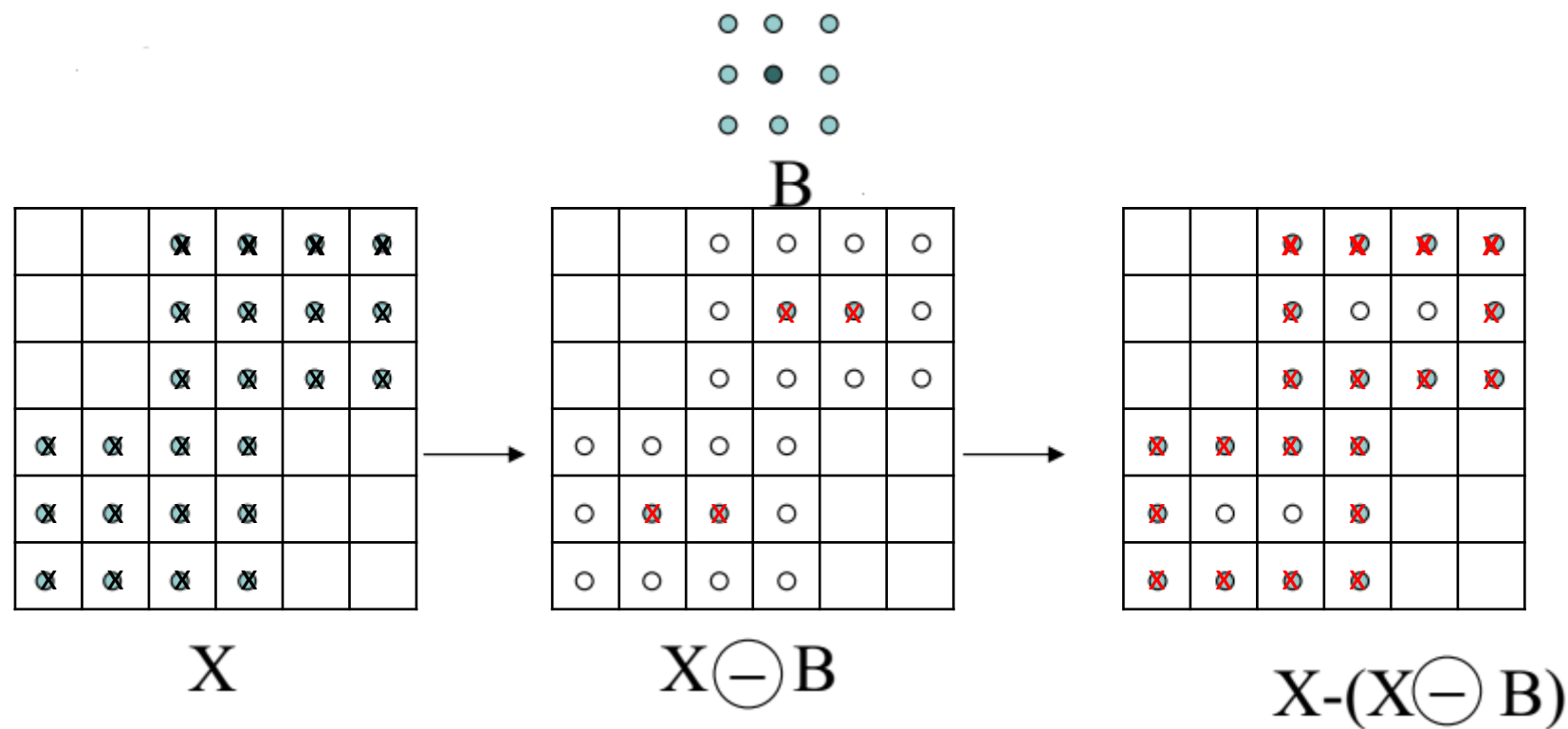
$X \bullet B$





# 边界提取 **Boundary Extraction Operator**

$$\partial X = X - (X \ominus B)$$

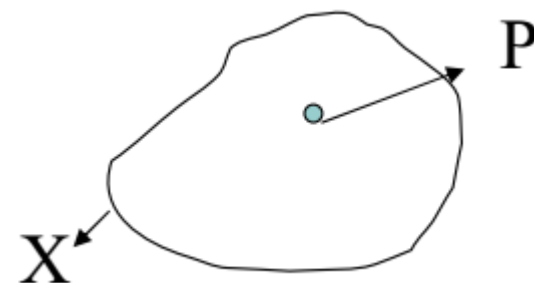




$X$

$\partial X$

# 区域填充 Region Filling Operator

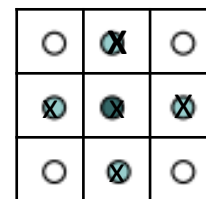


Iterations:

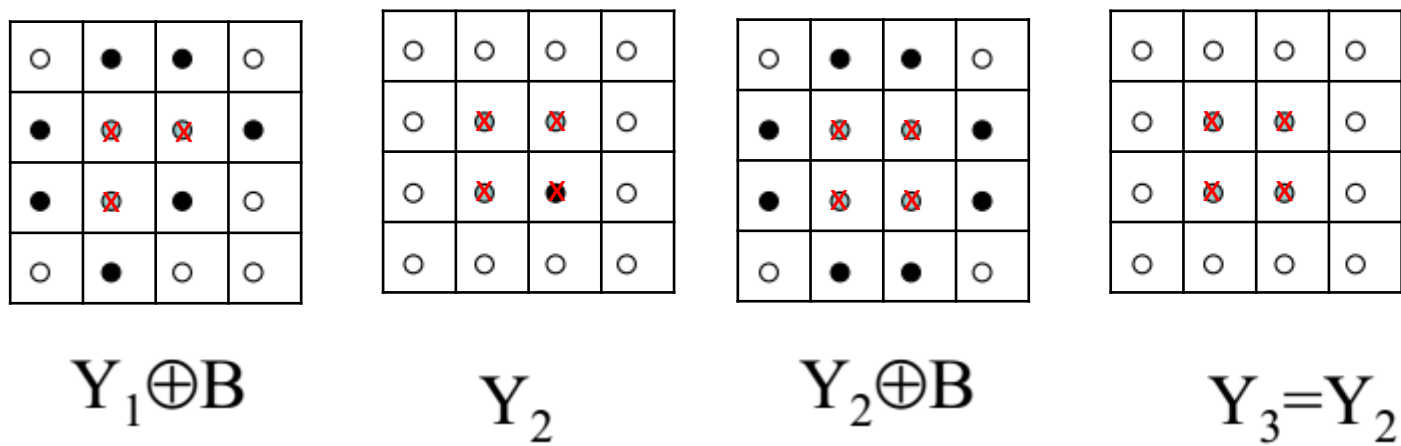
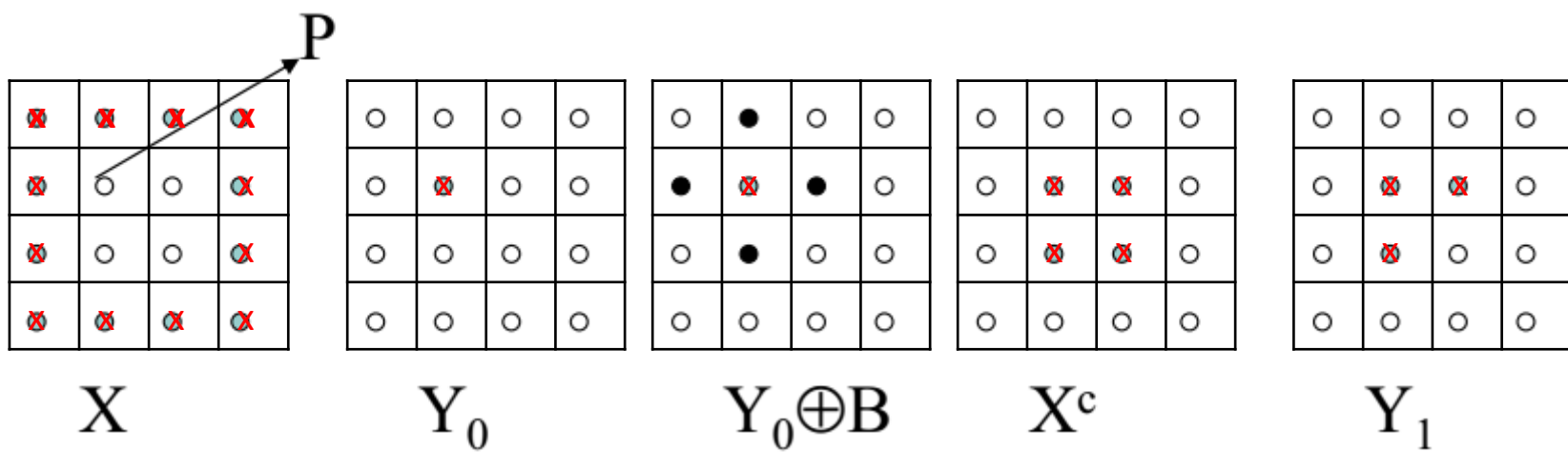
$$Y_0 = P$$

$$Y_k = (Y_{k-1} \oplus B) \cap X^c, k=1,2,3\dots$$

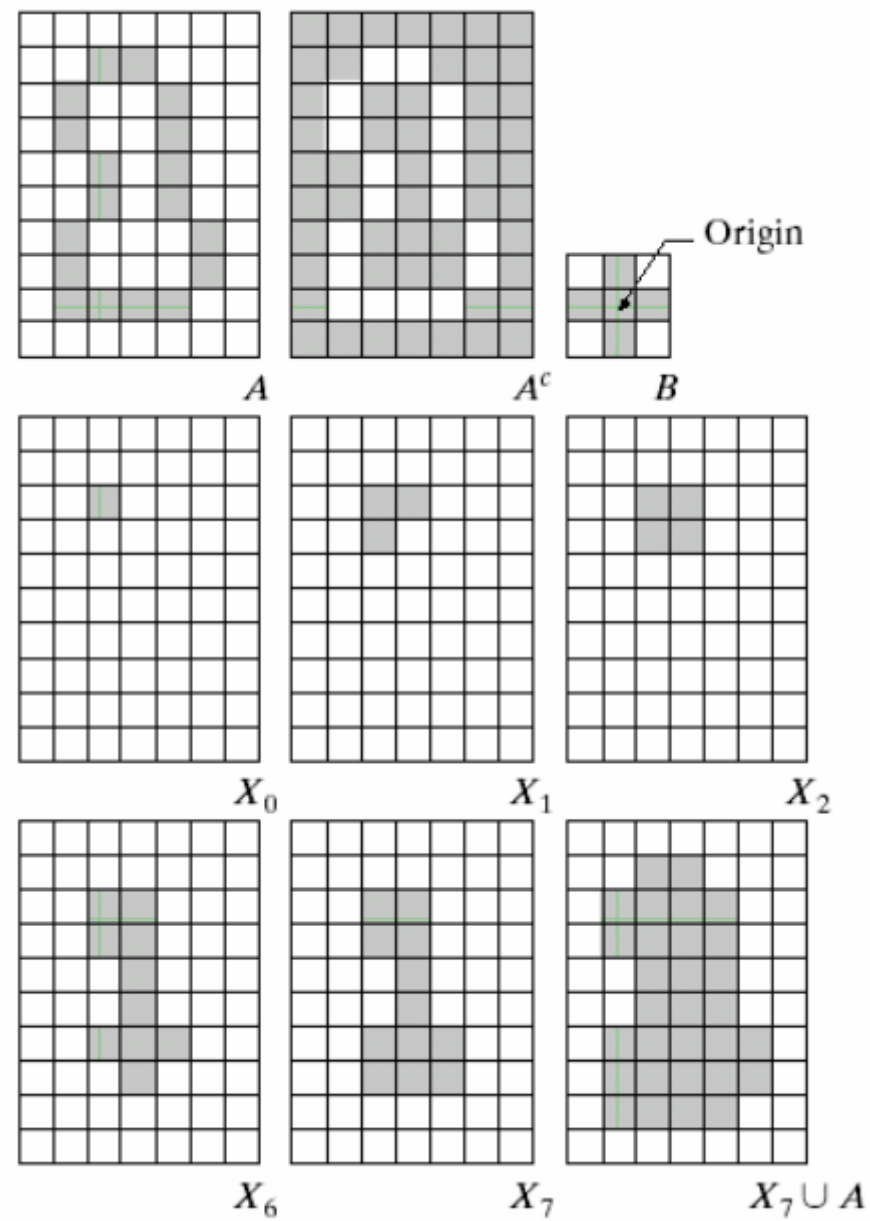
Terminate when  $Y_k = Y_{k-1}$ , output  $Y_k \cup X$



$B$







# 链码与边界跟踪

## Chain-code & contour tracing

方向编码  
(链码 Chain Code)

3	2	1
4	P	0
5	6	7

		x	x			
	x	x	x	x		
	x	x	x	x	x	
	x	x	x	x	x	
		x	x	x		

初始化：最“东面”边界点，方向：0

依次判断初始方向右、前、左是否存在前景点

是： 设置前进方向并前进到下一边界点  
修改初始方向为小于等于前进方向的偶数编号

否： 初始方向+2

结束条件： 回到起始点

同一点连续修改初始方向4次

3, 3, 4, 5, 6, 6, 7, 0, 0, 1, 2

# 距离图与距离变换

## Distance Map & Distance Transform

逆向扫描 Backward scanning

$$d_4(i, j) = \min\{d_4(i + 1, j) + 1, d_4(i, j + 1) + 1, d_4(i, j)\}$$

0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	0	0	0	0	0	0	0
0	0	0	1	1	1	1	1	0	0	0	0	0	0
0	0	0	0	1	1	1	1	1	1	0	0	0	0
0	0	0	0	0	1	1	1	1	1	0	0	0	0
0	0	0	0	0	0	1	1	1	1	1	0	0	0
0	0	0	0	0	0	0	1	1	1	1	1	0	0
0	0	0	0	0	0	0	1	1	1	1	1	1	0
0	0	0	0	0	0	0	1	1	0	0	1	1	0
0	0	0	0	0	0	0	1	1	1	0	1	1	0
0	0	0	0	0	0	0	1	1	1	1	1	1	0
0	0	0	0	0	0	0	0	1	1	1	1	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0

0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	0	0	0	0	0	0	0
0	0	0	1	2	2	2	1	0	0	0	0	0	0
0	0	0	0	1	2	3	2	1	1	0	0	0	0
0	0	0	0	0	1	2	3	2	2	0	0	0	0
0	0	0	0	0	0	1	2	3	3	1	0	0	0
0	0	0	0	0	0	0	1	2	3	4	2	1	0
0	0	0	0	0	0	0	1	2	0	0	1	2	0
0	0	0	0	0	0	0	1	2	1	0	1	2	0
0	0	0	0	0	0	0	1	2	2	1	2	3	0
0	0	0	0	0	0	0	0	1	2	2	3	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0

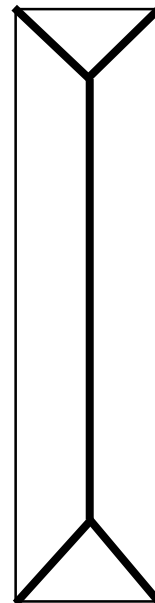
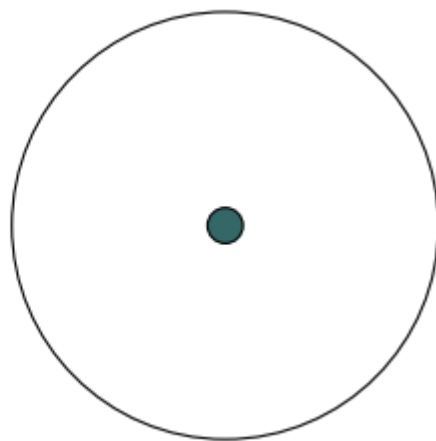
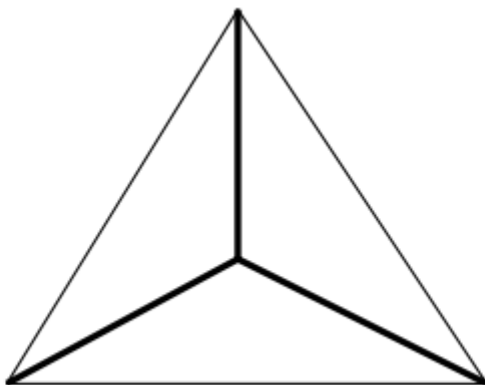
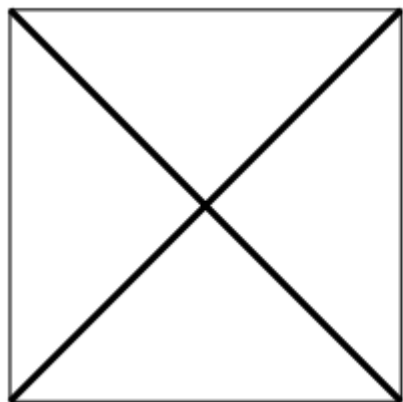
0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	1	1	1	1	0	0	0	0	0	0	0
0	0	0	1	2	2	2	1	0	0	0	0	0	0
0	0	0	0	1	2	3	2	1	1	0	0	0	0
0	0	0	0	0	1	2	3	2	1	0	0	0	0
0	0	0	0	0	0	1	2	2	2	1	0	0	0
0	0	0	0	0	0	0	1	2	1	1	2	1	0
0	0	0	0	0	0	0	1	1	0	0	1	1	0
0	0	0	0	0	0	0	1	2	1	0	1	1	0
0	0	0	0	0	0	0	1	2	2	1	2	1	0
0	0	0	0	0	0	0	0	1	1	1	1	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0

正向扫描 Forward scanning, for  $d(i, j) = 1$

$$d_4(i, j) = \min\{d(i - 1, j), d(i, j - 1)\} + 1$$

# 中心轴线（骨架）

## Medial Axis (Skeleton)





original



skeleton

