



Graph

- Basic Concepts
 - Representation
 - Adjacency Matrices
 - Adjacency Lists
- Traversal Algorithms
 - Depth-first Search
 - Breadth-first Search
- Applications
 - Spanning Tree
 - Shortest Paths
 - Activity Networks
 - Critical Activities



Introduction

Graphs have been widely used in:

- analysis of electrical circuits
- finding shortest routes
- project planning
- identification of chemical compounds
- statistical mechanics
- genetics
- cybernetics
- linguistics
- social science
- ...



Definitions

Graph $G = (V, E)$

- vertices $V(G) \neq \emptyset$
- edges $E(G)$
- undirected graph: $(u, v) = (v, u)$
- directed graph: $\langle u, v \rangle$, u ---tail, v ---head,
 $\langle u, v \rangle \neq \langle v, u \rangle$



Examples

$$\mathbf{G_1: V(G_1)=\{0,1,2,3\}}$$

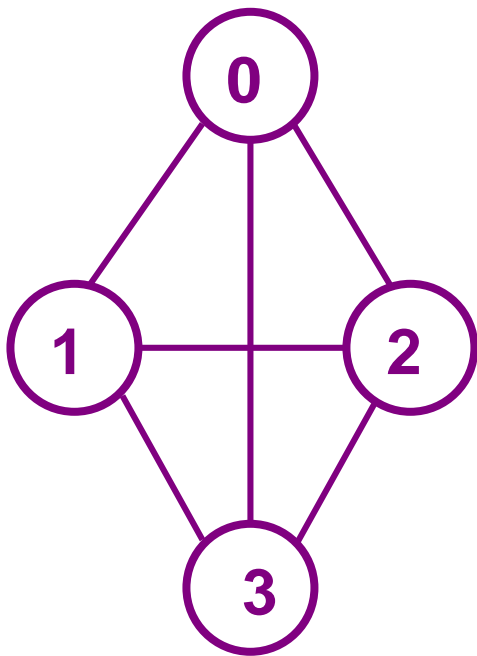
$$\mathbf{E(G_1)=\{(0,1),(0,2),(0,3),(1,2),(1,3),(2,3)\}}$$

$$\mathbf{G_2: V(G_2)=\{0,1,2,3,4,5,6\}}$$

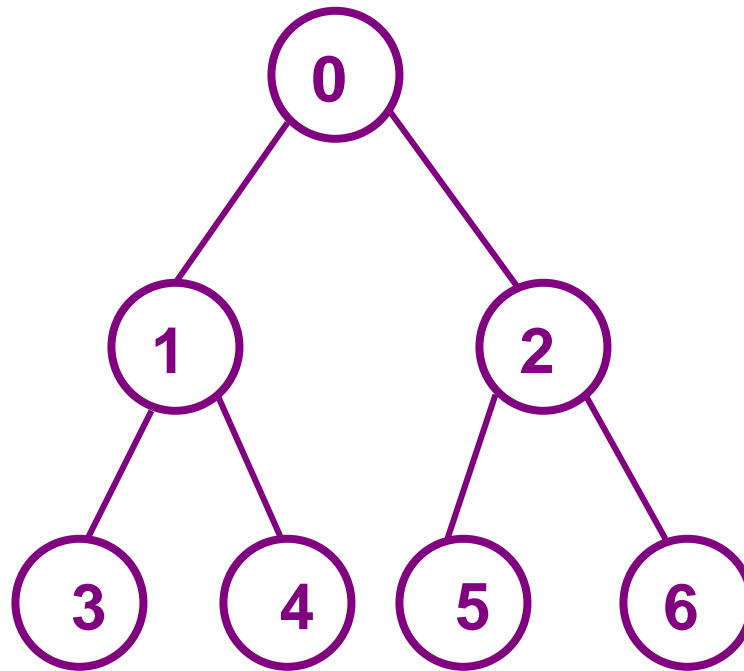
$$\mathbf{E(G_2)=\{(0,1),(0,2),,(1,3),(1,4),(2,5),(2,6)\}}$$

$$\mathbf{G_3: V(G_3) = \{0,1,2\}}$$

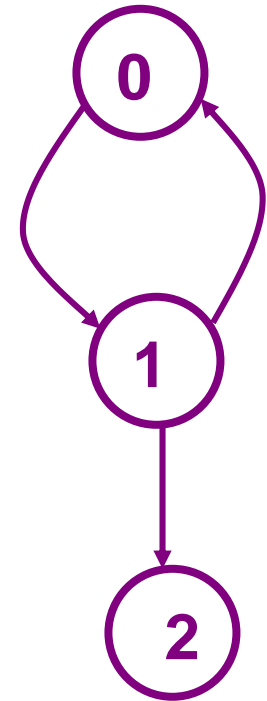
$$\mathbf{E(G_3) = \{<0,1>,<1,0>,<1,2>\} \text{ (directed)}}$$



(a) G_1



(b) G_2



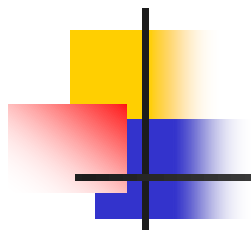
(c) G_3



Restrictions:

(1) (v, v) or $\langle v, v \rangle$ is not legal, such edges are known as self edges.

(2) multiple occurrences of the same edges are not allowed. If allowed, we get a multigraph.



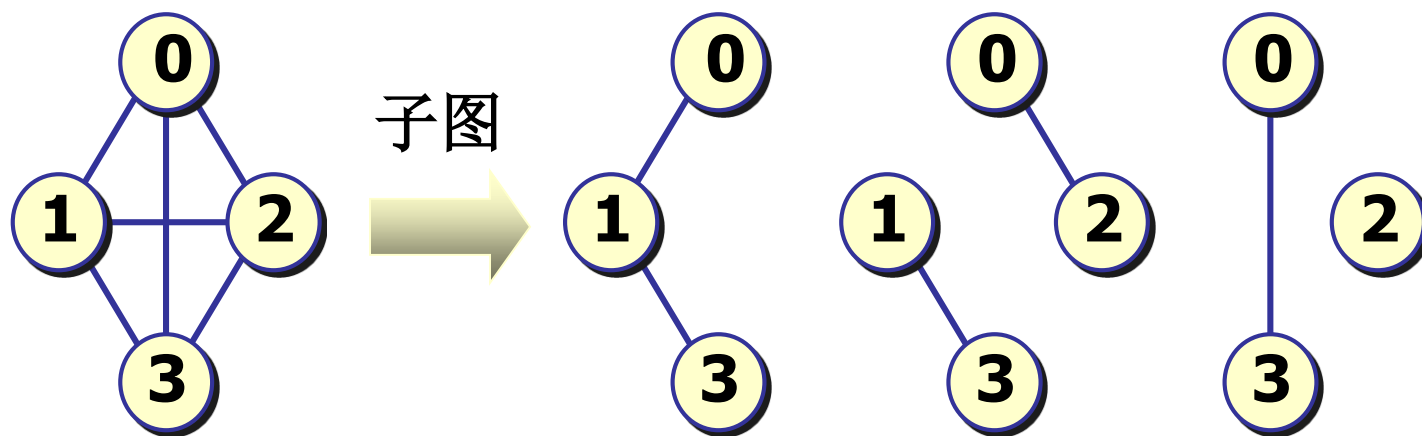
- The maximum number of edges in any n -vertex, undirected graph is $n(n-1)/2$, and in directed graph is $n(n-1)$.
- An n -vertex undirected graph with $n(n-1)/2$ edges is said to be complete.



Subgraph

- If $(u, v) \in E(G)$, we say u and v are adjacent and edge (u, v) is incident on vertices u and v . If $\langle u, v \rangle$ is a directed edge, then vertex u is adjacent to v , and v is adjacent from u , $\langle u, v \rangle$ is incident to u and v .
- A subgraph of G is a graph G' such that $V(G') \subseteq V(G)$ and $E(G') \subseteq E(G)$.

Subgraph



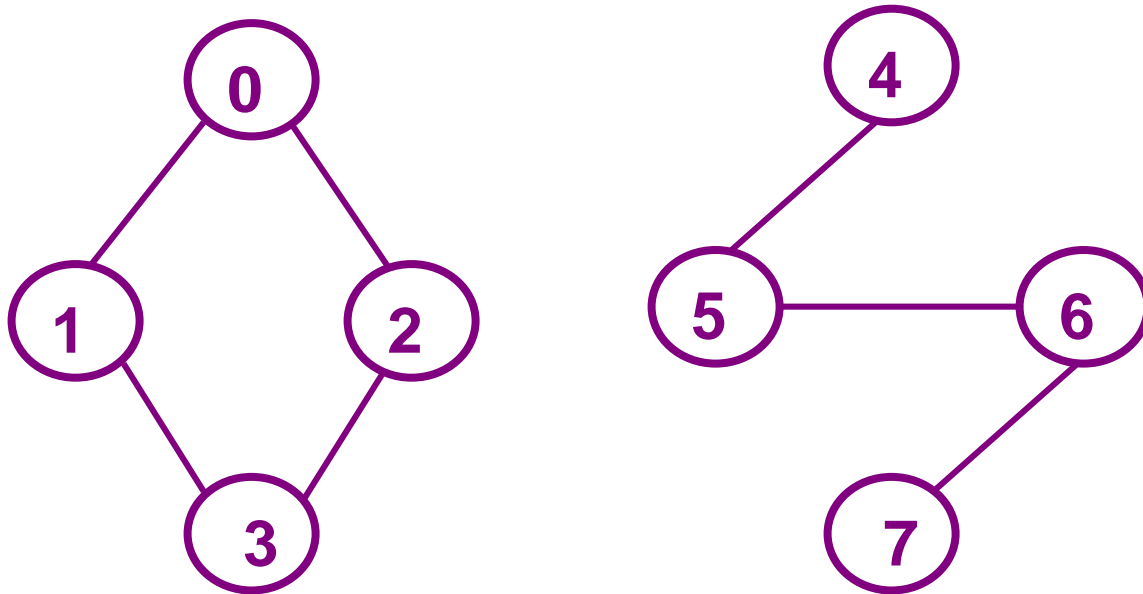


- A path from u to v in G is a sequence of vertices $u, i_1, i_2, \dots, i_k, v$ such that $(u, i_1), (i_1, i_2), \dots, (i_k, v)$ are edges in $E(G)$. If G is directed, then $\langle u, i_1 \rangle, \langle i_1, i_2 \rangle, \dots, \langle i_k, v \rangle$ are edges in $E(G)$.
- The length of a path is the number of edges on it.
- A simple path is a path in which all vertices except possibly the first and last are distinct.

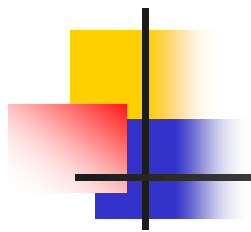


- A cycle is a simple path in which the first and last vertices are the same.
- For directed graph, we have directed paths and cycles.
- In an undirected G , u and v are connected iff there is a path in G from u to v (also from v to u).
- An undirected G is connected iff for every pair of distinct u and v in $V(G)$, there is a path from u to v .

- 
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- A connected component is a maximal connected subgraph.



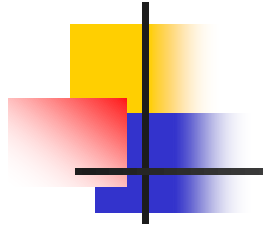
A graph with two connected components



- A tree is a connected acyclic graph.
- A directed G is strongly connected iff for every pair of distinct u and v in $V(G)$, there is a directed path from u to v and also from v to u .
- A strongly connected component is a maximal subgraph that is strongly connected.
- The degree of a vertex is the number of edges incident to it.



- For directed G , the in-degree of $v \in V(G)$ is the number of edges for which v is the head. The out-degree is the number of edges for which v is the tail.



- If d_i is the degree of vertex i in G with n vertices and e edges, then

$$e = \left(\sum_{i=0}^{n-1} d_i \right) / 2$$

- We'll refer to a directed graph as digraph, and a undirected graph as graph.



ADT of Graph

```
class Graph
```

```
{ // A non empty set of vertices and a set of undirected  
  // edges, where each edge is a pair of vertices.
```

```
public:
```

```
  virtual ~Graph(){ };
```

```
    // virtual destructor
```

```
  bool IsEmpty() const {return n==0;};
```

```
    // return true iff graph has no vertices
```

```
  int NumberOfVertices() const {return n;};
```

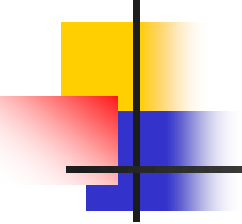
```
    // return the number of vertices in the graph
```

```
  int NumberofEdges() const {return e;};
```

```
    // return number of edges in the graph
```

```
  virtual int Degree(int u) const =0;
```

```
    // return number of edges incident to vertex u
```

```
virtual bool ExisteEdge(int u, int v) const =0;  
    // return true iff graph has edge (u, v)  
virtual void InsertVertex (int v) =0;  
    // insert vertex v into graph, v has no incident edges  
virtual void InsertEdge (int u, int v) =0;  
    // insert edge (u, v) into graph  
virtual void DeleteVertex (int v);  
    // delete v and all edges incident to it  
virtual void DeleteEdge (int u, int v) =0;  
    // delete edge (u, v) from the graph
```

```
private:
```

```
    int n;    // number of vertices
```

```
    int e;    // number of edges
```

```
};
```



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Graph Representations

Three most commonly used representations:

- (1) Adjacency matrices
- (2) Adjacency lists
- (3) Adjacency multilists

The actual choice depends on application.



Graph

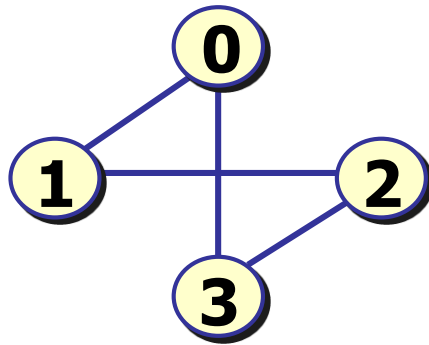
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Adjacency Matrix

The adjacency matrix of G is a $n \times n$ array, say a , such that:

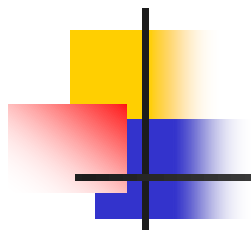
$$a[i,j] = \begin{cases} 1 & \text{iff } (i, j) \in E(G) \text{ (or } \langle i, j \rangle \in E(G) \text{)} \\ 0 & \text{otherwise} \end{cases}$$



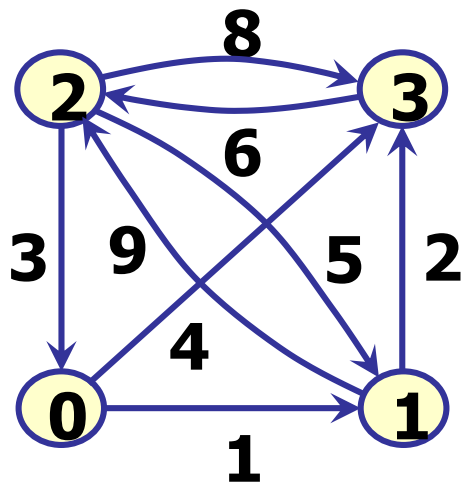
$$\mathbf{A.edge} = \begin{bmatrix} 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}$$



$$\mathbf{A.edge} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$



$$\mathbf{A.edge}[i][j] = \begin{cases} \mathbf{W}(i, j), & \text{若 } i \neq j \text{ 且 } \langle i, j \rangle \in \mathbf{E} \text{ 或 } (i, j) \in \mathbf{E} \\ \infty, & \text{若 } i \neq j \text{ 且 } \langle i, j \rangle \notin \mathbf{E} \text{ 或 } (i, j) \notin \mathbf{E} \\ \mathbf{0}, & \text{若 } i = j \end{cases}$$



$$\mathbf{A.edge} = \begin{bmatrix} \mathbf{0} & \mathbf{1} & \infty & \mathbf{4} \\ \infty & \mathbf{0} & \mathbf{9} & \mathbf{2} \\ \mathbf{3} & \mathbf{5} & \mathbf{0} & \mathbf{8} \\ \infty & \infty & \mathbf{6} & \mathbf{0} \end{bmatrix}$$



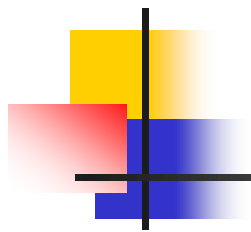
For an graph, a is symmetric, and

$$d_i = \sum_{j=0}^{n-1} a[i][j]$$

For a digraph, a may not be symmetric, and

$$\text{out-}d_i = \sum_{j=0}^{n-1} a[i][j]$$

$$\text{in-}d_j = \sum_{i=0}^{n-1} a[i][j]$$



Problem: how many edges are there in G ?

Using a , we need $O(n^2)$. When $e \ll n^2 / 2$, and if we explicitly represent only edges in G , then we can solve the above problem in $O(e + n)$.

This lead to:

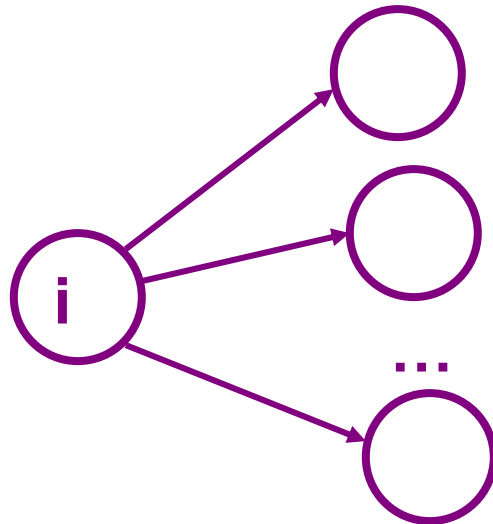


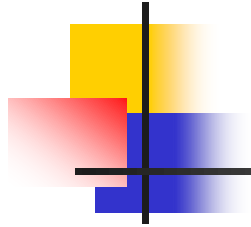
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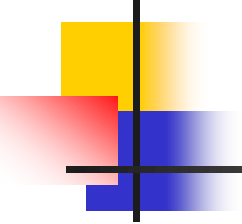
Adjacency Lists

- The n rows of the adjacency matrix are represented as n chains.
- The nodes in chain i represent the vertices adjacent from i .

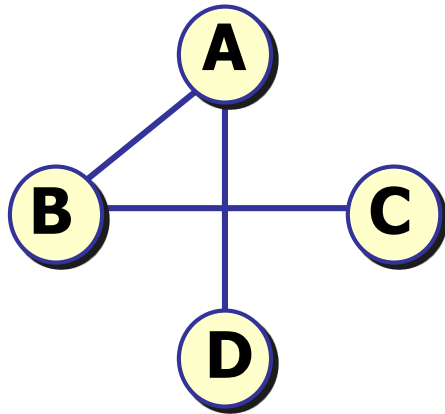




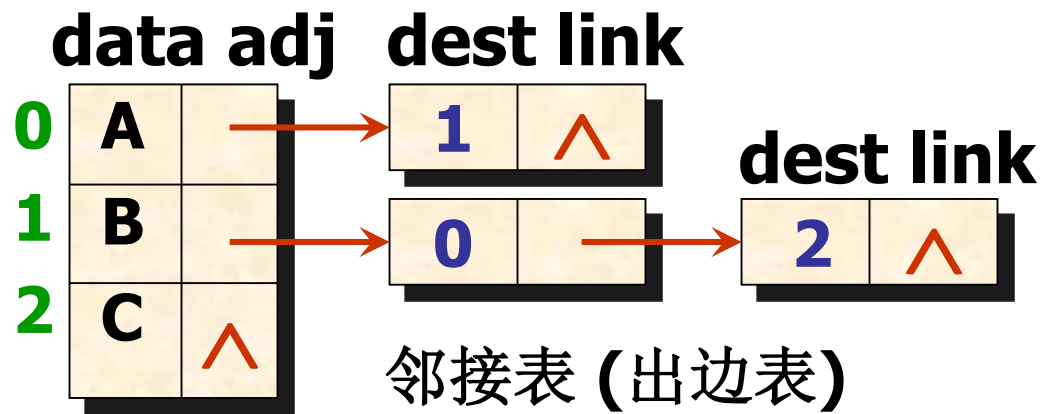
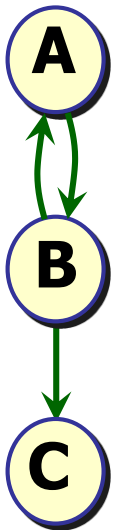
- The data field of a chain node store the index of an adjacent vertex.
- The vertices in each chain are not required to be ordered.
- An array `adjLists` is used for accessing any chain in $O(1)$.

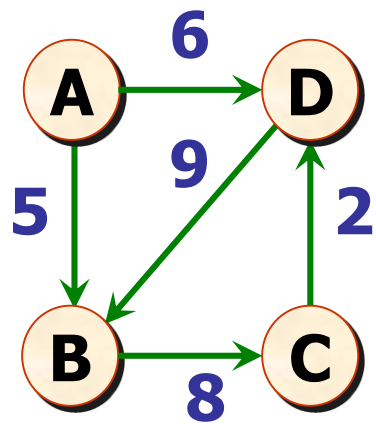


```
class LinkedGraph
{
public:
    LinkedGraph (const int vertices): e(0)
    {
        if (vertices < 1) throw "Number of vertices must be > 0";
        n = vertices;
        adjLists = new Chain<int>[n];
    };
private:
    Chain<int>* adjLists;
    int n;
    int e;
};
```



	data	adj	dest	link	dest	link
0	A		→	1	→	3 ^
1	B		→	0	→	2 ^
2	C					
3	D		→	1	→	^
			→	0	→	^



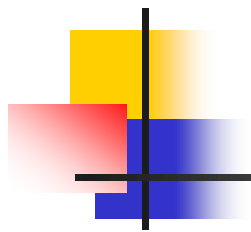


data adjdest cost link

0	A	→	1	5	→	3	6	^
1	B	→	2	8	→			^
2	C	→	3	2	→			^
3	D	→	1	9	→			^

(顶点表)

(出边表)



- For an undirected graph with n vertices and e edges, this representation requires an array of size n and $2e$ chain nodes.
- Now it is possible to determine the total number of edges in G in $O(e+n)$.
- In case of digraph, the in-degree of a vertex is a little more complex to determine --- use a vector $c[n]$, when traverse from i to j , $c[j]++$.