

## Appendix A 2)

Intersection:

a)  $y$  axis,  $(0, 1, 0)$

b) line through  $(1, 1)$ , the line is on the plane.

c) zero vector

d) zero vector

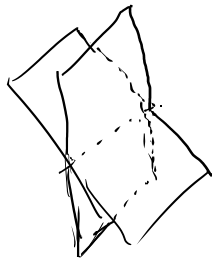
Sum:

a)  $\mathbb{R}^3$

b) plane through  $(1, 2, 0)$  &  $(0, 1, 1)$

c)  $\mathbb{R}^3$

d)  $\mathbb{R}^3$



2.5 2)

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix}$$

Let  $b$  be the linear combination of columns of  $A$

$$Ax = b$$

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} x_1 + \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} x_2 + \begin{bmatrix} 0 \\ -1 \\ -1 \end{bmatrix} x_3 = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$x_1 - x_2 = b_1$$

$$x_2 - x_3 = b_2$$

$$x_1 - x_3 = b_3$$

$$(x_1 - x_2) + (x_2 - x_3) - (x_1 - x_3) = 0 = b_1 + b_2 - b_3$$

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Shown from columns

$$\left[ \begin{array}{ccc|c} 1 & -1 & 0 & b_1 \\ 0 & 1 & -1 & b_2 \\ 1 & 0 & -1 & b_3 \end{array} \right] \xRightarrow{r_1 + r_2} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & b_1 + b_2 \\ 0 & 1 & -1 & b_2 \\ 1 & 0 & -1 & b_3 \end{array} \right] \xRightarrow{r_1 - r_3} \left[ \begin{array}{ccc|c} 0 & 0 & 0 & b_1 + b_2 - b_3 \\ 0 & 1 & -1 & b_2 \\ 1 & 0 & -1 & b_3 \end{array} \right]$$

$$\Rightarrow \underline{b_1 + b_2 - b_3 = 0}$$

Shown from rows

This means the potential difference in the loop is zero

25 4)

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} \quad A^T = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

It's quite evident that  $A^T A$  is symmetric.  $A_{ji} = A_{ij}$

$$\text{reduce} \left( \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} \right) \Rightarrow \begin{bmatrix} 0 & 3 & -3 \\ -1 & 2 & -1 \\ 0 & -3 & 3 \end{bmatrix} \Rightarrow \begin{bmatrix} -1 & 2 & -1 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{bmatrix}, \text{rank} = 2 < 3 \\ \Rightarrow \begin{bmatrix} -1 & 2 & -1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

singular.

$$\begin{aligned} x_1 + x_3 &= 0 \\ x_2 - x_3 &= 0 \end{aligned} \quad \bar{x} = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} x_3$$

$$N(A^T A) \in \left\{ c \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \mid c \in \mathbb{R} \right\}, \text{null space of } A^T A \text{ span all multiples of } \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}, \quad 2 \times 2 - 1 \times 1 = 3 \neq 0, \\ \text{not singular}$$

2.6 2)

$\rightarrow \leftarrow \rightarrow \leftarrow \rightarrow \leftarrow \downarrow \rightarrow \uparrow \leftarrow \downarrow \rightarrow \uparrow \leftarrow$

It is a refutation

$$2.6 \quad 8) \quad a_0 + a_1 t + a_2 t^2 + a_3 t^3$$

$$a_0 (2+3t) + a_1 t (2+3t) \dots$$

$$2a_0 + 3a_0 t + 2a_1 t + 3a_1 t^2 + \dots + 3a_3 t^4$$

$$2a_0 + (3a_0 + 2a_1)t + \dots + 3a_3 t^4$$

$$A = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 3 & 2 & 0 & 0 \\ 0 & 3 & 2 & 0 \\ 0 & 0 & 3 & 2 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

2.6 (b)

$$\ddot{u} = u$$

$$s^2 - 1 = 0$$

$$s = \pm 1$$

$$u = c_1 e^t + c_2 e^{-t}$$

$$u(0) = c_1 + c_2 = x$$

$$u'(0) = c_1 - c_2 = y$$

$$\begin{cases} c_1 = \frac{x+y}{2} \\ c_2 = \frac{x-y}{2} \end{cases}$$

$$u = \frac{x+y}{2} e^t + \frac{x-y}{2} e^{-t}$$

$$u = \frac{e^t + e^{-t}}{2} x + \frac{e^t - e^{-t}}{2} y$$

$$\begin{bmatrix} \dot{u} \\ \ddot{u} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} u \\ \dot{u} \end{bmatrix}$$

The matrix is  $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

2.6 20)

$$\begin{matrix} (x_1, x_2, x_3) & \rightarrow & (x_2, x_3, x_1) \\ X & R & X' \end{matrix}$$

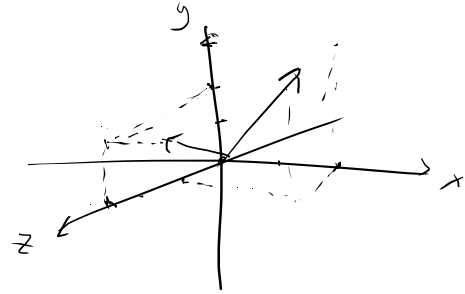
$$R = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

Let the axis of rotation be  $a$ ,

$$Ra = a$$

$$\begin{bmatrix} a_2 \\ a_3 \\ a_1 \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix} \Rightarrow \begin{cases} a_2 = a_1 \\ a_3 = a_2 \\ a_1 = a_3 \end{cases}$$

$$a_1 = a_2 = a_3, \quad a = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$



$$\text{tr}(R) = 1 + 2\cos(\theta) = 0$$

$$\cos(\theta) = -\frac{1}{2}$$

$$\boxed{\theta = \frac{2\pi}{3}} = 120^\circ$$