

# HW7. 35-38 in "Quadratic Stability"

**Exercise 35** Prove the following result: Suppose there exist a positive-definite symmetric matrix  $P$  and a positive scalar  $\alpha$  which satisfy

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$$\begin{pmatrix} PA + A^T P + C^T C + 2\alpha P & PB \\ B^T P & -\gamma^{-2} I \end{pmatrix} \leq 0. \quad (11.26)$$

Then system (11.18)-(11.19) is globally exponentially stable about the origin with rate of convergence  $\alpha$ .

$$\dot{x} = Ax + B\phi(Cx) \quad A: n \times n \quad B: n \times m \quad C: p \times n$$

$$z = Cx, \quad \|\phi(z)\| \leq \gamma \|z\|, \quad \exists \gamma \geq 0. \\ \leq \gamma \|Cx\|$$

$$\text{Let } v = x^T P x$$

$$\dot{v} = 2x^T P \dot{x}$$

$$= 2x^T P (Ax + B\phi(Cx))$$

$$= 2x^T P A x + 2x^T P B \phi(Cx)$$

$$= x^T (PA + A^T P) x + 2x^T P B \phi(Cx)$$

$$\leq x^T (PA + A^T P) x + 2\|B^T P x\| \cdot \|\phi\|$$

$$\leq x^T (PA + A^T P) x + 2\|B^T P x\| \cdot \gamma \|Cx\|$$

$$\leq x^T (PA + A^T P) x + \gamma^2 \|B^T P x\|^2 + \|Cx\|^2$$

$$= x^T (PA + A^T P) x + \gamma^2 x^T P B B^T P x + x^T C^T C x$$

$$= x^T (PA + A^T P + \gamma^2 P B B^T P + C^T C) x$$

$$= x^T Q x.$$

Thus the system is GES.

using Schur complement result.

$$PA + A^T P + C^T C + 2\alpha P - PB \cdot (-\gamma^2) \cdot B^T P \leq 0 \quad -\gamma^{-2} I \leq 0$$

$$PA + A^T P + C^T C + 2\alpha P + \gamma^2 P B B^T P \leq 0$$

$$PA + A^T P + C^T C + \gamma^2 P B B^T P \leq -2\alpha P$$

$$Q \leq -2\alpha P$$

Thus the system is GES with rate of  $\alpha$ .

**Exercise 36** Recall the double inverted pendulum of ~~Example~~ <sup>Exercise</sup> 34. Using the results of this section, obtain a value of the spring constant  $k$  which guarantees that this system is globally exponentially stable about the zero solution.

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$$\ddot{\theta}_1 + 2\dot{\theta}_1 - \dot{\theta}_2 + 2k\theta_1 - k\theta_2 - \sin\theta_1 = 0$$

$$\ddot{\theta}_2 - \dot{\theta}_1 + \dot{\theta}_2 - k\theta_1 + k\theta_2 - \sin\theta_2 = 0$$

$$A_0 = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -2k & k & -2 & 1 \\ k & -k & 1 & -1 \end{bmatrix}$$

$$x = \begin{bmatrix} \theta_1 \\ \theta_2 \\ \dot{\theta}_1 \\ \dot{\theta}_2 \end{bmatrix}$$

$$\psi_1(\theta_1) = \begin{cases} \frac{\sin\theta_1}{\theta_1} & \theta_1 \neq 0 \\ 1 & \theta_1 = 0 \end{cases} \quad \Delta A_1 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$-1 \leq \psi_1(x) \leq 1$$

$a_1 \qquad b_1$

$$\psi_2(\theta_2) = \begin{cases} \frac{-\sin\theta_2}{\theta_2} & \theta_2 \neq 0 \\ 1 & \theta_2 = 0 \end{cases} \quad \Delta A_2 = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

$$-1 \leq \psi_2(x) \leq 1$$

$a_2 \qquad b_2$

$$\dot{x} = A_0 \cdot x + \Delta A_1 \cdot \psi_1(\theta_1) + \Delta A_2 \psi_2(\theta_2)$$

$$= A x + B_1 \psi_1(C_1 x) + B_2 \psi_2(C_2 x)$$

$$A = A_0$$

$$\Rightarrow B_1 = \Delta A_1 \quad C_1 = [1 \ 0 \ 0 \ 0]$$

$$B_2 = \Delta A_2 \quad C_2 = [0 \ 1 \ 0 \ 0]$$

$$\begin{bmatrix} PA + A^T P + \sum_{i=1}^2 M_i C_i' C_i & PB_1 & PB_2 \\ B_1^T P & -M_1 I & 0 \\ B_2^T P & 0 & -M_2 I \end{bmatrix} < 0.$$

After using LMI toolbox to solve the LMI  
shown above,  $k = 80$  yields a feasible solution.

### Ex 36

```
clear;
k = 80;
A = [0 0 1 0; 0 0 0 1; -2*k k -2 1; k -k 1 -1];
B1 = zeros(4);
B1(3,1) = 1;

B2 = zeros(4);
B2(4,2) = 1;

C1 = [1 0 0 0];
C2 = [0 1 0 0];

setlmis([])
P = lmivar(1, [4,1]);
mu1 = lmivar(1, [1,1]);
mu2 = lmivar(1, [1,1]);

lmiterm([1,1,1,P], 1, A, 's')
lmiterm([1,1,1,mu1], C1', C1)
lmiterm([1,1,1,mu2], C2', C2)

lmiterm([1,1,2,P], 1, B1)
lmiterm([1,1,3,P], 1, B2)

lmiterm([1,2,1,P], B1', 1)
lmiterm([1,2,2,mu1], -1, 1)

lmiterm([1,3,1,P], B2', 1)
lmiterm([1,3,3,mu2], -1, 1)

Plmi = newlmi;
lmiterm([-Plmi,1,1,P],1,1)
% lmiterm([Plmi,1,1,0],1)

lmis = getlmis;

[tfeas, xfeas] = feasp(lmis)

P = dec2mat(lmis, xfeas, P)
```

k = 80

Solver for LMI feasibility problems  $L(x) < R(x)$   
This solver minimizes  $t$  subject to  $L(x) < R(x) + t \cdot I$   
The best value of  $t$  should be negative for feasibility

Iteration : Best value of  $t$  so far

|   |              |
|---|--------------|
| 1 | 0.048373     |
| 2 | 8.040934e-03 |
| 3 | 8.040934e-03 |
| 4 | 1.102835e-03 |
| 5 | -0.062455    |

Result: best value of  $t$ : -0.062455  
f-radius saturation: 0.000% of  $R = 1.00e+09$

tfeas = -0.0625

xfeas = 12x1

608.8023  
11.5894  
620.5462  
1.8273  
1.2761  
7.7609  
1.3040  
3.1191  
7.8959  
15.6586  
:  
:

P = 4x4

|          |          |        |         |
|----------|----------|--------|---------|
| 608.8023 | 11.5894  | 1.8273 | 1.3040  |
| 11.5894  | 620.5462 | 1.2761 | 3.1191  |
| 1.8273   | 1.2761   | 7.7609 | 7.8959  |
| 1.3040   | 3.1191   | 7.8959 | 15.6586 |

ans = 4x1

Here we consider systems described by

$$\dot{x} = Ax - B\phi(Cx) \quad (11.37)$$

where

$$z'\phi(z) \geq 0 \quad (11.38)$$

for all  $z$ . Examples of  $\phi$  include  $\phi(z) = z, z^3, z^5, \text{sat}(z), \text{sgn}(z)$ .

**Exercise 37** Prove the following result: Suppose there exists a positive-definite symmetric matrix  $P$  and a positive scalar  $\alpha$  which satisfy which satisfies

$$PA + A'P + 2\alpha P \leq 0 \quad (11.40a)$$

$$B'P = C \quad (11.40b)$$

Then system (11.37)-(11.38) is globally exponentially stable about the origin with rate  $\alpha$  and with Lyapunov matrix  $P$ .

$$\text{Let } v = x^T P x,$$

$$\dot{v} = 2x^T P \dot{x}$$

$$= 2x^T P (Ax - B\phi(Cx))$$

$$= 2x^T P A x - 2x^T P B \phi(Cx)$$

$$= 2x^T P A x - 2(Cx)'\phi(Cx). \quad \text{since } z'\phi(z) \geq 0,$$

$$\leq 2x^T P A x$$

$$= x^T (PA + A'P) x$$

$$\dot{v} \leq 2x^T Q x, \quad Q = PA$$

Thus the system is GES.

$$\text{Since } PA + A'P \leq -2\alpha P$$

The system has a convergence rate of  $\alpha$ .

Exercise 38 Consider the transfer function

$$\hat{g}(s) = \frac{\beta s + 1}{s^2 + s + 2}$$

Using Lemma 12, determine the range of  $\beta$  for which this transfer function is SPR. Verify your results with the KYSPR lemma.

$$\hat{g}(s) \text{ has poles at } \frac{-1 \pm \sqrt{-7}}{2} = \frac{-1 \pm j\sqrt{7}}{2}$$

$\operatorname{Re}(s_p) < 0$  thus  $\hat{g}(s)$  is stable, Condition (a) holds.

$$\hat{g}(j\omega) = \frac{j\beta\omega + 1}{-\omega^2 + j\omega + 2}$$

$$\hat{g}'(j\omega) = \frac{-j\beta\omega + 1}{-\omega^2 - j\omega + 2}$$

$$\hat{g}(j\omega) + \hat{g}'(j\omega) = \frac{j\beta\omega + 1}{-\omega^2 + j\omega + 2} + \frac{-j\beta\omega + 1}{-\omega^2 - j\omega + 2}$$

$$= \frac{2\beta\omega^2 - 2\omega^2 + 4}{( \omega^2 )^2 + (2 - j\omega)^2}$$

$$= \frac{2[\omega^2(\beta - 1) + 2]}{(\omega^2)^2 + (2 - j\omega)^2}$$

It's clear that the denominator is  $> 0$ , and the numerator is only  $> 0$ ,  $\forall \omega \in \mathbb{R}$  iff  $\beta \geq 1$

Thus condition b) holds.

The state space of this transfer function are

$$A = \begin{bmatrix} -1 & 2 \\ 1 & 0 \end{bmatrix}, \quad B = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad C = [\beta \ 1], \quad D = 0$$

$$\lim_{\omega \rightarrow \infty} \omega^2 [\hat{g}(j\omega) + \hat{g}'(j\omega)] = 2(\beta - 1) \neq 0 \text{ iff } \beta > 1.$$

Condition c) holds.

Thus for  $\hat{g}(s)$  to be SPR,

$$\boxed{\beta > 1}$$

$$M = \begin{pmatrix} PA + A'P + 2\alpha P & PB - C' \\ B'P - C & -(D + D') \end{pmatrix} \leq 0$$

```

52 beta = 2;
53 C = [beta 1];
54 D = 0;
55
56 alpha = 1
57
58 setlmis([])
59 P = lmivar(1, [2,1]);
60
61 lmiterm([1,1,1,P], 1, A, 's')
62
63 lmiterm([1,1,2,P], 1, B)
64 lmiterm([1,1,2,0], -C')
65
66 lmiterm([1,2,1,P], B', 1)
67 lmiterm([1,2,1,0], -C)
68
69 Plmi = newlmi;
70 lmiterm([-Plmi,1,1,P],1,1)
71
72 lmis = getlmis;
73
74 [tfeas, xfeas] = feasp(lmis)
75
76 P = dec2mat(lmis, xfeas, P)
77
78 M = [P*A+A'*P-2*alpha*P P*B-C'; B'*P-C 0]
79 eig(M)
80 ans(3) < eps

```

```

19 4.688759e-08
20 4.688759e-08
*** new lower bound: -6.642174e-07
21 4.399369e-09
22 4.399369e-09
*** new lower bound: -1.238600e-07
23 5.834172e-10
24 5.834172e-10
*** new lower bound: -2.208705e-08
25 5.834172e-10
26 5.834172e-10
*** new lower bound: -6.180929e-09
27 1.783034e-10
28 1.783034e-10
*** new lower bound: -1.074197e-09
29 7.717890e-11
tfeas = 9.8058e-13
xfeas = 3x1
2.0000
1.0000
5.7053
P = 2x2
2.0000 1.0000
1.0000 5.7053
M = 3x3
-6.0000 -1.2947 0.0000
-1.2947 -15.4106 -0.0000
0.0000 -0.0000 0
ans = 3x1
-15.5854
-5.8251
0.0000
ans = Logical
1

```

Though the LMI solver shows marginal feasibility,

the  $M$  matrix has two negative eigenvalues,  
one zero eigenvalue. thus  $M \leq 0$ .

The  $H_2$ SPR holds.