

Problem 1.

Show  $P_H f = P_M f + R_{f\psi} R_\psi^{-1} \psi$

$$E(f - P_H f)(f - P_H f)^* = E(f - P_M f)(f - P_M f)^* - R_{f\psi} R_\psi^{-1} R_{\psi f}.$$

using Lemma 2.4.1 in Ch. 2.

$$T = \begin{bmatrix} R & M \\ N & Q \end{bmatrix}, \quad \Delta = Q - NR^{-1}M \text{ (Schur complement of } T \text{)}$$

$$\begin{aligned} T^{-1} &= \begin{bmatrix} I & -R^{-1}M \\ 0 & I \end{bmatrix} \begin{bmatrix} R^{-1} & 0 \\ 0 & \Delta^{-1} \end{bmatrix} \begin{bmatrix} I & 0 \\ -NR^{-1} & I \end{bmatrix} \\ &= \begin{bmatrix} R^{-1} + R^{-1}M\Delta^{-1}NR^{-1} & -R^{-1}M\Delta^{-1} \\ \Delta^{-1}NR^{-1} & \Delta^{-1} \end{bmatrix} \end{aligned}$$

In this case

$$T = R_h = \begin{bmatrix} R_g & R_{gy} \\ R_{yg} & R_y \end{bmatrix}, \quad \Delta = R_\psi = R_y - R_{yg}R_g^{-1}R_{gy}$$

$$T^{-1} = R_h^{-1} = \begin{bmatrix} I & -R_g^{-1}R_{gy} \\ 0 & I \end{bmatrix} \begin{bmatrix} R_g^{-1} & 0 \\ 0 & R_\psi^{-1} \end{bmatrix} \begin{bmatrix} I & 0 \\ -R_{yg}R_g^{-1} & I \end{bmatrix}$$

$$P_H f = R_{fh} \cdot R_h^{-1} \cdot h$$

$$= \begin{bmatrix} R_{fg} & R_{fy} \end{bmatrix} \begin{bmatrix} I & -R_g^{-1}R_{gy} \\ 0 & I \end{bmatrix} \begin{bmatrix} R_g^{-1} & 0 \\ 0 & R_\psi^{-1} \end{bmatrix} \begin{bmatrix} I & 0 \\ R_{yg}R_g^{-1} & I \end{bmatrix} \begin{bmatrix} g \\ y \end{bmatrix}$$

$$= \begin{bmatrix} R_{fg} & R_{fy} - R_{fg}R_g^{-1}R_{gy} \end{bmatrix} \begin{bmatrix} R_g^{-1} & 0 \\ 0 & R_\psi^{-1} \end{bmatrix} \begin{bmatrix} g \\ y - R_{yg}R_g^{-1}g \end{bmatrix}$$

$$= \begin{bmatrix} R_{fg} & R_{fy} - R_{fg}R_g^{-1}R_{gy} \end{bmatrix} \begin{bmatrix} R_g^{-1}g \\ R_\psi^{-1}y - R_\psi^{-1} \overbrace{R_{yg}R_g^{-1}g}^{P_M g} \end{bmatrix}$$

$$= R_{fg} R_g^{-1} y + (R_{fy} - R_{fg} R_g^{-1} R_{gy}) (R_y^{-1} y - R_y^{-1} P_m y)$$

$$= P_m f + (R_{fy} - R_{fg} R_g^{-1} R_{gy}) R_y^{-1} (y - P_m y)$$

$$= \underline{P_m f + R_{fy} \cdot R_y^{-1} \cdot y}$$

$$E(f - P_m f)(f - P_m f)^* = R_f - R_{fh} R_h^{-1} R_{hf}$$

$$R_f = E(f - P_m f)(f - P_m f)^*$$

$$R_{fh} R_h^{-1} R_{hf} = \begin{bmatrix} R_{fg} & R_{fy} \end{bmatrix} \begin{bmatrix} I & -R_g^{-1} R_{gy} \\ 0 & I \end{bmatrix} \begin{bmatrix} R_g^{-1} & 0 \\ 0 & R_y^{-1} \end{bmatrix} \begin{bmatrix} I & 0 \\ -R_{yg} R_g^{-1} & I \end{bmatrix} \begin{bmatrix} R_{gf} \\ R_{yf} \end{bmatrix}$$

$$= \begin{bmatrix} R_{fg} & R_{fy} - R_{fg} R_g^{-1} R_{gy} \end{bmatrix} \begin{bmatrix} R_g^{-1} & 0 \\ 0 & R_y^{-1} \end{bmatrix} \begin{bmatrix} R_{gf} \\ R_{yf} - R_{yg} R_g^{-1} R_{gf} \end{bmatrix}$$

$$= \begin{bmatrix} R_{fg} R_g^{-1} & R_{fy} R_y^{-1} \end{bmatrix} \begin{bmatrix} R_{gf} \\ R_{yf} \end{bmatrix}$$

$$= \cancel{R_{fg} R_g^{-1} R_{gf}} + R_{fy} R_y^{-1} R_{yf}$$

$$= R_{fy} R_y^{-1} R_{yf}$$

$$E(f - P_m f)(f - P_m f)^* = \underline{E(f - P_m f)(f - P_m f)^* - R_{fy} R_y^{-1} R_{yf}}$$

2. Consider SS system:

$$x(n+1) = Ax(n) + Bu(n) \quad \& \quad y(n) = Cx(n) + Dv(n)$$

$$\hat{x}(n) = P_{n-1} x(n)$$

find state estimate  $P_n x(n)$  in terms of  $\hat{x}(n)$  &  $y(n)$ .

Lemma 3.3.1:  $P_n f = P_{n-1} f + R_{f\psi(n)} R_{\psi(n)}^{-1} \psi(n)$

$$\psi(n) = y(n) - P_{n-1} y(n)$$

$$= y(n) - P_{n-1} [Cx(n) + Dv(n)]$$

$$= y(n) - P_{n-1} Cx(n) - \cancel{P_{n-1} Dv(n)}$$

$$= y(n) - C\hat{x}(n)$$

$$= C\tilde{x}(n) + Dv(n) \quad \tilde{x}(n) = x(n) - \hat{x}(n) \text{ (estimation error)}$$

$$\hat{x}(n) = P_n x(n) = P_{n-1} x(n) + R_{x(n)\psi(n-1)} R_{\psi(n-1)}^{-1} \psi(n-1)$$

$$= P_{n-1} [Ax(n-1) + Bu(n-1)] + R_{x(n)\psi(n-1)} R_{\psi(n-1)}^{-1} \psi(n-1)$$

$$= A\hat{x}(n-1) + R_{x(n)\psi(n-1)} R_{\psi(n-1)}^{-1} \psi(n-1)$$

$$R_{x(n)\psi(n-1)} = E x(n) \psi(n-1)^*$$

$$R_{\psi(n-1)} = E \psi(n-1) \psi(n-1)^* = CQ_{n-1} C^* + DD^*$$

$$= E (Ax(n-1) + Bu(n-1)) \psi(n-1)^*$$

$$= A E x(n-1) \psi(n-1)^*$$

$$= A E x(n-1) (C\tilde{x}(n-1) + Dv(n-1))^*$$

$$= A E x(n-1) \tilde{x}(n-1)^* C^*$$

$$= A E (\hat{x}(n-1) + \tilde{x}(n-1)) \tilde{x}(n-1)^* C^*$$

$$= A E \tilde{x}(n-1) \tilde{x}(n-1)^* C^* = A Q_{n-1} C^*$$

$$\hat{x}(n) = A\hat{x}(n-1) + A Q_{n-1} C^* (C Q_{n-1} C^* + D D^*)^{-1} \psi(n-1)$$


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3. Consider  $x(n+1) = ax(n) + u(n)$ ,

$$y(n) = x(n) + v(n).$$

$a$  is a scalar,  $\{u(0), v(0), v(1), x(0)\}$  are i.i.d independent  $G(0,1)$  r.v.

Let  $M_0 = \text{span}\{y(0)\}$ ,  $M_1 = \text{span}\{y(0), y(1)\}$ .

Find: (i)  $\hat{x}(0) = P_{M_0} x(0)$

(ii)  $E |x(0) - \hat{x}(0)|^2$

(iii)  $\alpha$  &  $\beta$  such that  $y(1) - P_{M_0} y(1) = \alpha y(1) + \beta y(0)$ .

1)

$$\hat{y}_0 = x_0 + v_0$$

$$y_1 = x_1 + v_1$$

$$x_1 = ax_0 + u_0$$

$$= ax_0 + u_0 + v_1$$

$$\hat{x}_0 = R_{x_0 y} R_y^{-1} y \quad \text{where } y = \begin{bmatrix} y_0 \\ y_1 \end{bmatrix} = \begin{bmatrix} x_0 + v_0 \\ ax_0 + u_0 + v_1 \end{bmatrix}$$

$$R_y = E_{yy^*} = \begin{bmatrix} E_{y_0^2} & E_{y_0 y_1} \\ E_{y_1 y_0} & E_{y_1^2} \end{bmatrix}$$

$$E_{y_0^2} = E(x_0 + v_0)^2 = E_{x_0^2} + 2E_{x_0 v_0} + E_{v_0^2} = 1 + 1 - 2 = 0$$

$$E_{y_0 y_1} = E(x_0 + v_0)(ax_0 + u_0 + v_1) = E_{ax_0^2} + E_{x_0 u_0} + E_{x_0 v_1} + E_{v_0 ax_0} + E_{v_0 u_0} + E_{v_0 v_1} = a$$

$$E_{y_1^2} = E(ax_0 + v_0 + v_1)^2 = E_{a^2 x_0^2} + \dots + E_{v_0^2} + \dots + E_{v_1^2} = a^2 + 2$$

$$\Rightarrow R_y = \begin{bmatrix} 2 & a \\ a & a^2 + 2 \end{bmatrix} \quad R_y^{-1} = \frac{1}{a^2 + 4} \begin{bmatrix} a^2 + 2 & -a \\ -a & 2 \end{bmatrix}$$

$$R_{x_0 y} = E_{x_0 y^*} = E \begin{bmatrix} x_0^2 + x_0 v_0 & ax_0^2 + x_0 u_0 + x_0 v_1 \end{bmatrix} = \begin{bmatrix} 1 & a \end{bmatrix}$$

$$\hat{x}_0 = \frac{1}{a^2 + 4} \begin{bmatrix} 1 & a \end{bmatrix} \begin{bmatrix} a^2 + 2 & -a \\ -a & 2 \end{bmatrix} \begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$$

$$= \frac{1}{a^2 + 4} \begin{bmatrix} 2 & a \end{bmatrix} \begin{bmatrix} y_0 \\ y_1 \end{bmatrix}$$

$$= \frac{2y_0 + ay_1}{a^2 + 4}$$

$$i) E |x_0 - \hat{x}_0|^2 = E x_0^2 - R_{x_0 y} R_y^{-1} R_{x_0 y}^*$$

$$R_{x_0 y} R_y^{-1} R_{x_0 y}^* = \frac{1}{a^2+4} [1 \ a] \begin{bmatrix} a^2+2 & -a \\ -a & 2 \end{bmatrix} \begin{bmatrix} 1 \\ a \end{bmatrix} = \frac{2+a^2}{a^2+4}$$

$$= 1 - \frac{2+a^2}{a^2+4}$$

$$= \frac{2}{a^2+4}$$

$$ii) \mathcal{I} = y_0$$

$$P_{m_0} y_1 = R_{y_1} R_y^{-1} \mathcal{I} = \frac{a y_0}{2}$$

$$\begin{cases} R_{y_1 \mathcal{I}} = E y_1 \mathcal{I}^* = a \\ R_{\mathcal{I}} = E \mathcal{I} \mathcal{I}^* = 2 \end{cases}$$

$$\varphi(a) = y_1 - \frac{a y_0}{2}$$

$$\alpha = 1 \quad \beta = \frac{a}{2}$$