



Causal graphical models

Causality

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Announcements

- Series 2 will be uploaded later today
- Next week:
 - In-class exercise from 11-12
 - Please setup Jupyter and R (see website for details)

Last week

- Internal vs. external validity
- Graph terminology
- Directed acyclic graph (DAG) models
- Markov properties
- d-separation

DAG models

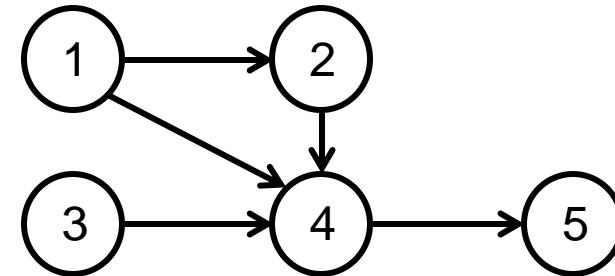
- Let $G = (V, E)$ be a DAG and p be the distribution of X_V
- The pair (G, p) is a **DAG model** or a **Bayesian network** if

$$p(x_V) = \prod_{i \in V} p(x_i | x_{\text{pa}(i)})$$

- If p factorizes according to G , d-separations in G imply conditional independencies in p

Graph terminology

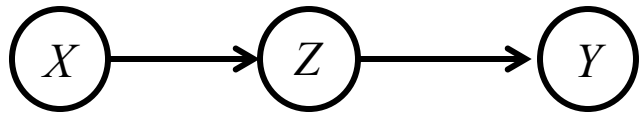
- A non-endpoint node i is a **collider on a path** if the path contains $\rightarrow i \leftarrow$ (arrows collide at i).
- Otherwise, it is a **non-collider on the path**.
- Collider status is always relative to a path
 - 4 is a collider on the path (3,4,1)
 - 4 is a non-collider on the path (3,4,5)



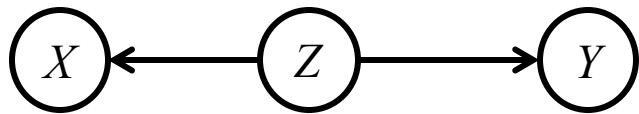
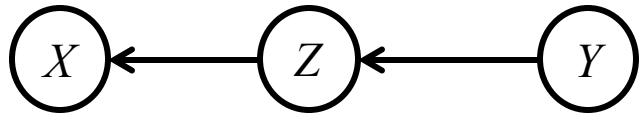
d-separation

- A **path** between i to j is **blocked** by a set S (not containing i or j) if at least one of the following holds:
 - There is a non-collider on the path that is in S ; or
 - There is a collider on the path such that neither this collider nor any descendants are in S .
- A path that is not blocked is **active**.
- If all paths between $i \in A$ and $j \in B$ are blocked by S , then **A and B are d-separated by S** . Otherwise they are **d-connected** given S .
- Denote d-separation by \perp

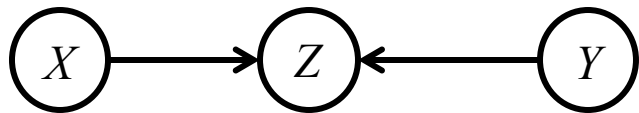
Example



eg fire \rightarrow smoke \rightarrow alarm
 $X \perp Y | Z$



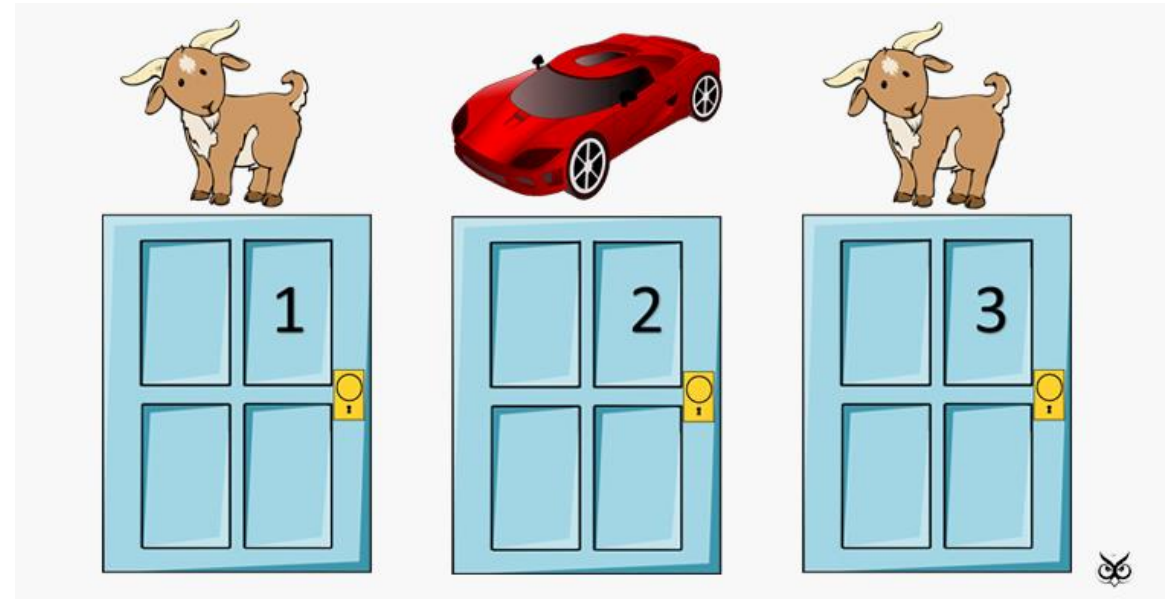
eg shoe size \leftarrow age of child \rightarrow reading ability
 $X \perp Y | Z$



eg talent \rightarrow celebrity \leftarrow beauty
 $X \not\perp Y | Z$

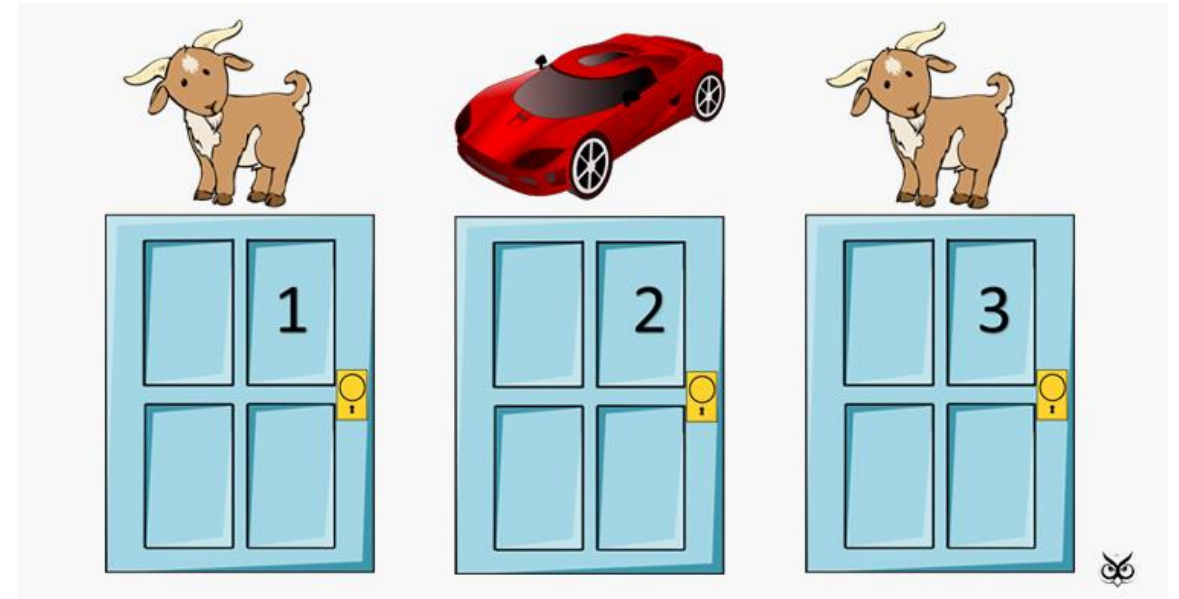
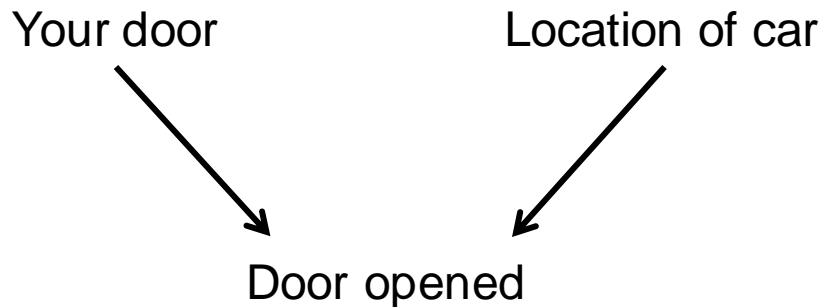
Example: Monty Hall

- Quiz show hosted by Monty Hall
- Setting:
 - 3 closed doors with 1 car and 2 goats
 - You pick one door
 - Monty Hall opens one of the remaining doors with a goat
 - Then he asks you whether you want to switch
- How do you decide?



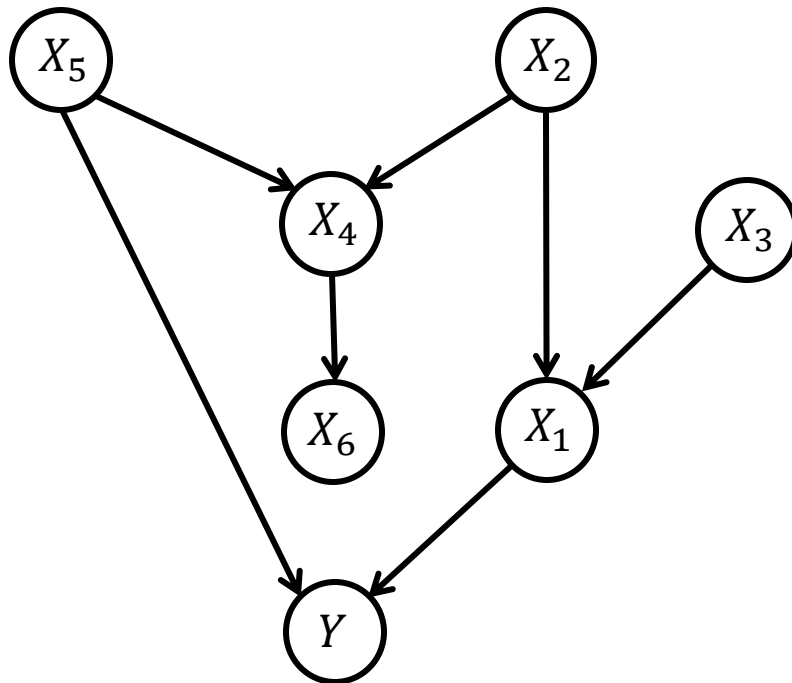
Example: Monty Hall

- Can show with Bayes rule:
 - If switch: success probability is $2/3$
 - If stay: success probability is $1/3$
- Instance of “selection bias”
 - “collider bias”, “Berkson’s paradox”



Clicker question – d-separation

- Consider the following graph G . Assume $p(x_V)$ factorizes according to G .



$X_2 \perp\!\!\!\perp X_5$? Yes

$X_2 \perp\!\!\!\perp X_5 | X_6$? No

$X_2 \perp\!\!\!\perp X_5 | X_3$? Yes

$X_3 \perp\!\!\!\perp X_5 | X_2$? Yes

$X_2 \perp\!\!\!\perp X_3 | X_5$? Yes

$Y \perp\!\!\!\perp X_3$? No

$Y \perp\!\!\!\perp X_3 | X_1$? yes

DAG models

- A **DAG model** or **Bayesian network** is a combination (G, f) , where G is a DAG and f is a distribution that factorizes according to G
- DAG models can be used for various purposes:
 - Estimating the joint density from low order conditional densities
 - Reading off conditional independencies from the DAG
 - **Probabilistic reasoning (expert systems)**
 - Causal inference

Probabilistic reasoning

- Conditional probabilities are rather counterintuitive for many people
- DAGs allow us to obtain conditional probabilities efficiently, using a “message passing” algorithm.
 - See R script “Graphical models”
 - We won’t discuss the details behind these algorithms

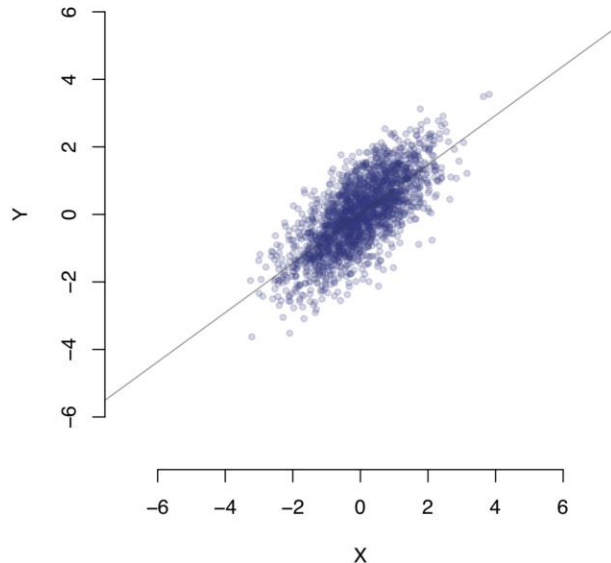
Today

- Selection bias
- Causal effects and do-operator
- Causal graphical models
- Structural equation models
- Path method

Classical regression models

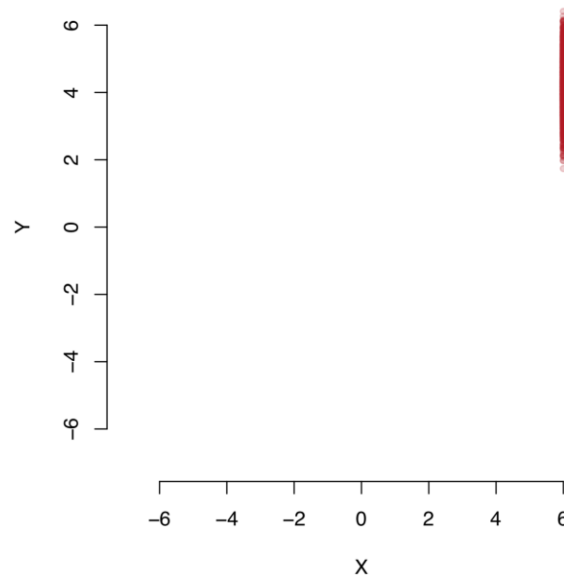
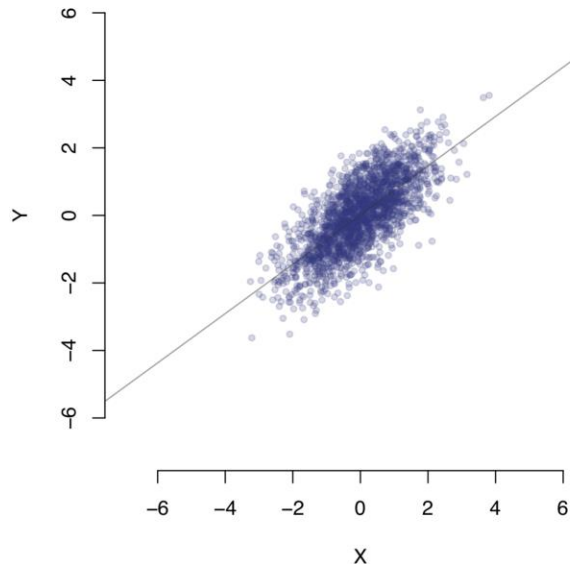
- We **observe** n i.i.d. observations of (X, Y) with distribution p
- Goal is to model certain aspects of $p(y|x)$, for example $E(Y|X = x)$
- Useful for prediction

↳ distribution of Y when we
observe $X=x$

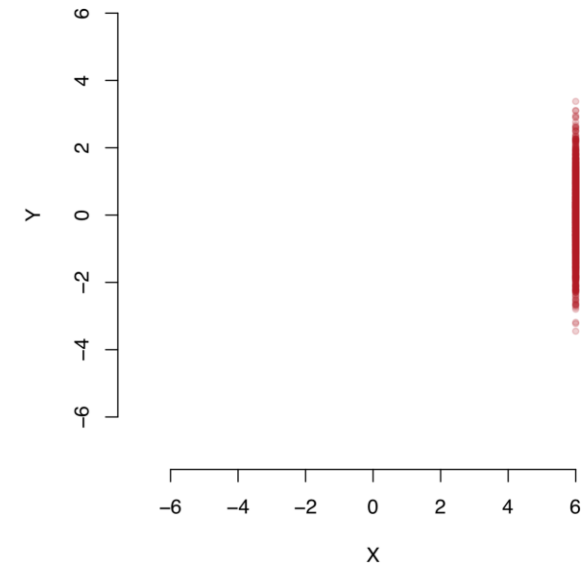


Classical regression models

- We **observe** n i.i.d. observations of (X, Y) with distribution p
- Goal is to model certain aspects of $p(y|x)$, for example $E(Y|X = x)$
- Useful for prediction – but what if we **set** X to e.g. 6?



$X \rightarrow Y$



$Y \rightarrow X$

Classical regression models

- We **observe** n i.i.d. observations of (X, Y) with distribution p
- Goal is to model certain aspects of $p(y|x)$, for example $E(Y|X = x)$
- Useful for prediction

- Such analyses are generally **not** useful for policy or treatment decisions, since such decisions involve predictions in manipulated systems with **post-intervention distributions** different from p

Causal effect and do-operator

- Interventional definition of causal effect:
 X has a causal effect on Y if manipulating X changes the distribution of Y
- Mathematical notion of manipulation (see Pearl):
 - $do(X = x)$ (or shorthand $do(x)$) represents a hypothetical **intervention** where X is set to the value x , uniformly over the entire population
 - $p(y|do(X = x))$ is the distribution of Y after $do(X = x)$
 - $E(Y|do(X = x))$ is the expectation of Y after $do(X = x)$, etc

Conditioning on observing: $p(y|see(X=x)) = p(y|x)$ (ordinary conditioning)

vs.
 Intervening: $p(y|do(X=x))$, also written as $p^{do(X=x)}(y)$

Causal effect and do-operator

- Mathematical definition of causal effect:

X has a causal effect on Y if $p(y|do(X = x'))$ depends on x' ,
i.e., if $\exists a$ and b so that $p(y|do(X = a)) \neq p(y|do(X = b))$

- Average causal effect:

$$ACE(x, x') = E(y|do(X = x)) - E(y|do(X = x'))$$

eg X binary; $x=0$ (control), $x=1$ (treatment)
 $ACE = E(y|do(x=1)) - E(y|do(x=0))$

Example

- Consider a rehabilitation program for prisoners. Participation in the program is voluntary.
 - $X = 1$ if prisoner participated in the program; $X = 0$ otherwise
 - $Y = 1$ if prisoner is rearrested within a year; $Y = 0$ otherwise
- $P(Y = 1|X = 1)$: probability of re-arrest for prisoners who **choose** to participate
- $P(Y = 1|do(X = 1))$: probability of re-arrest if program were **compulsory** for all prisoners
- Note that generally $P(Y = 1|do(X = 1)) \neq P(Y = 1|X = 1)$

Example

- Suppose $P(Y = 1|X = 1) < P(Y = 1|X = 0)$.
 - Re-arrest rate among prisoners who participated in the program is lower than among those who did not participate
 - Could be due to the program, due to the intrinsic motivation of the prisoners who chose to participate, due to a mixture of these two, or....
- Suppose $P(Y = 1|do(X = 1)) < P(Y = 1|do(X = 0))$.
 - Program lowers the re-arrest rate, i.e., program has a causal effect on the re-arrest rate
 - Manipulating X changes the distribution of Y
 - X is causal for Y

Frameworks

- Causal DAG models (Causal Bayesian networks)
- Structural equation models
- Potential outcomes

Causal Bayesian networks

- Let $G = (V, E)$ be a DAG and p be the distribution of X_V
- The pair (G, p) is a **DAG model** or a **Bayesian network** if

$$p(x_V) = \prod_{i \in V} p(x_i | x_{\text{pa}(i)})$$

Causal Bayesian networks

- Let $G = (V, E)$ be a DAG and p be the distribution of X_V
- The pair (G, p) is a **causal DAG model** or a **causal Bayesian network** if for any $W \subset V$

$$p(x_v \mid \text{do}(x_w = x_{w'})) = \begin{cases} \prod_{i \in V \setminus W} p(x_i \mid x_{\text{pa}(i)}) & \text{if } x_w = x_{w'} \\ 0 & \text{otherwise} \end{cases}$$

$$= \prod_{i \in V \setminus W} p(x_i \mid x_{\text{pa}(i)}) \mathbb{1}_{\{x_w = x_{w'}\}}$$

Causal Bayesian networks

- Let $G = (V, E)$ be a DAG and p be the distribution of X_V
- The pair (G, p) is a **DAG model** or a **Bayesian network** if

$$p(x_V) = \prod_{i \in V} p(x_i | x_{\text{pa}(i)})$$

- The pair (G, p) is a **causal DAG model** or a **causal Bayesian network** if for any $W \subset V$

$$p(x_V | do(x_W = x'_W)) = \prod_{i \in V \setminus W} p(x_i | x_{\text{pa}(i)}) 1\{x_W = x'_W\}$$

Causal Bayesian networks

- Let $G = (V, E)$ be a DAG and p be the distribution of X_V
- The pair (G, p) is a **DAG model** or a **Bayesian network** if

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- The pair (G, p) is a **causal DAG model** or a **causal Bayesian network** if for any $W \subset V$

$$p(x_{V \setminus W} | do(x_W = x'_W)) = \prod_{i \in V \setminus W} p(x_i | x_{\text{pa}(i)}) \Big|_{x_W = x'_W}$$

Causal Bayesian networks

- The pair (G, p) is a **causal DAG model** or a **causal Bayesian network** if for any $W \subset V$

$$p(x_V | do(x_W = x'_W)) = \prod_{i \in V \setminus W} p(x_i | x_{\text{pa}(i)}) 1\{x_W = x'_W\}$$

- Modified factorization known as
 - “**g-formula**” (Robins)
 - “**manipulation formula**” (Spirtes, Glymour, Scheines)
 - “**truncated factorization formula**” (Pearl)

Causal Bayesian networks

- The truncated factorization formula implies that an intervention on X_j only changes $p(x_j | x_{\text{pa}(j)})$; the other conditional distributions remain unchanged. This is also known as **invariance**.

Compare:
$$p(x_v) = \left\{ \prod_{i \in v \setminus \{j\}} p(x_i | x_{\text{pa}(i)}) \right\} p(x_j | x_{\text{pa}(j)})$$

$$p(x_v | \text{do}(X_j = x'_j)) = \left\{ \prod_{i \in v \setminus \{j\}} p(x_i | x_{\text{pa}(i)}) \right\} \cdot \mathbb{1}(x_j = x'_j)$$

Causal Bayesian networks

- The truncated factorization formula implies that an intervention on X_j only changes $p(x_j | x_{\text{pa}(j)})$; the other conditional distributions remain unchanged. This is also known as **invariance**.

eg: A : altitude
 T : temperature $p(a, t) = p(\underline{t|a}) p(a)$

→ if we change A , then we assume that the physical mechanism $p(t|a)$ responsible for producing an average temperature is still in place (**invariance**)

→ holds independent of $p(a)$

Causal Bayesian networks

- The pair (G, p) is a **causal DAG model** or a **causal Bayesian network** if for any $W \subset V$

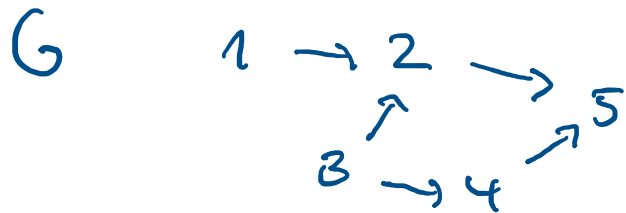
$$p(x_V | do(x_W = x'_W)) = \prod_{i \in V \setminus W} p(x_i | x_{pa(i)}) 1\{x_W = x'_W\}$$

post-intervention
distribution needed
to define causal
effects

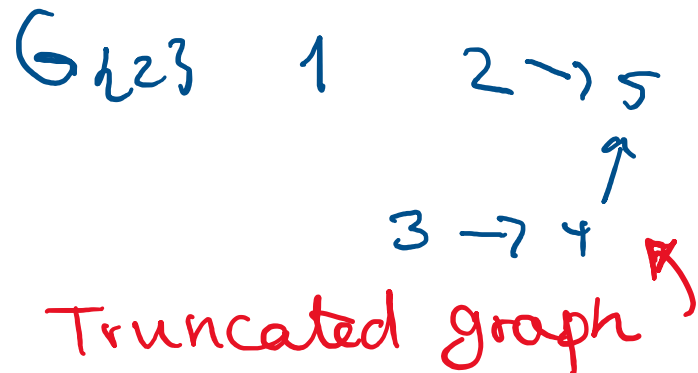
conditional distribution
that can be estimated
from observational
data

Causal Bayesian networks

- The modified factorizations represent factorizations wrt truncated graphs G_W , where all edges into W are removed



$$p(x_1, x_2, x_3, x_4, x_5) = p(x_1) p(x_3) p(x_2 | x_1, x_3) p(x_4 | x_3) \cdot p(x_5 | x_2, x_4)$$



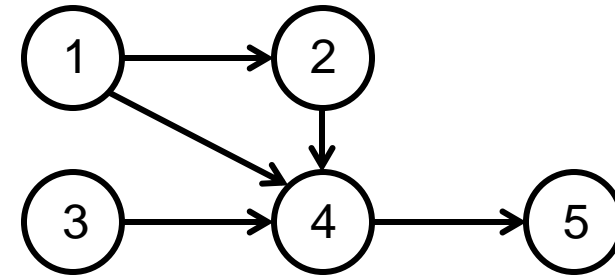
Consider do-intervention on x_2

$$p(x_1, x_2, x_3, x_4, x_5 | \text{do}(x_2 = x_2')) = p(x_1) p(x_3) \mathbb{1}\{x_2 = x_2'\} \cdot p(x_4 | x_3) p(x_5 | x_2, x_4)$$

$$p(x_1, x_3, x_4, x_5 | \text{do}(x_2 = x_2')) = p(x_1) p(x_3) p(x_4 | x_3) \cdot p(x_5 | x_2, x_4) \Big|_{x_2 = x_2'}$$

Causal Bayesian networks

- $X_{\text{pa}(j)}$ can be interpreted as the direct causes of X_j
- Directed edges can be interpreted as **direct causal effects**



Example

- Consider the DAGs: $1 \rightarrow 2$ and $2 \rightarrow 1$
- Assume (X_1, X_2) are dependent
- Any distribution p of (X_1, X_2) factorizes wrt these two DAGs:
$$p(x_1, x_2) = p(x_1)p(x_2|x_1) = p(x_2)p(x_1|x_2).$$
- But the two DAGs are very different when interpreted causally:
 - The post-intervention distribution of X_1 is:
 - $p(x_1|do(x_2)) = p(x_1)$ for causal DAG $1 \rightarrow 2$
 - $p(x_1|do(x_2)) = p(x_1|x_2)$ for causal DAG $2 \rightarrow 1$
 - Thus, X_2 does not cause X_1 in the first DAG, but X_2 causes X_1 in the second graph

Examples

Causal DAGs

- Causal DAGs imply strong assumptions, allowing us to estimate post-intervention distributions from observational data
- How do we know the causal DAG?
 - Now: assume it is given, e.g. from background knowledge
 - Later: consider learning causal DAG (under some assumptions)
 - In any case, causal DAG provides clear framework to state causal assumptions for analysis
 - Allows for an honest debate about such assumptions
 - Can draw several possible causal DAGs, conduct the analysis for each of them and perform a sensitivity analysis

Frameworks

- Causal DAG models (Causal Bayesian networks)
- Structural equation models
- Potential outcomes

Structural equation models

- Let X_V be a collection of variables, and $G = (V, E)$ be a DAG
- Each X_i is generated as a function of its graphical parents in G and noise ϵ_i :

$$X_i \leftarrow h_i(X_{\text{pa}(i)}, \epsilon_i), \quad i \in V$$

where $\epsilon_i, i \in V$, are jointly independent

- The structural equations and the distribution of ϵ_V yield a distribution p for X_V

Structural equation models

- Then (G, p) is a causal Bayesian network if interventions are modelled as follows:
 - An intervention on X_j is modelled by replacing h_j . The generating mechanisms of the other variables (other structural equations) remain unchanged (**invariance**).
 - Thus, $do(X_j = x'_j)$ is modelled by replacing

$$X_j \leftarrow h_j(X_{\text{pa}(j)}, \epsilon_j) \quad \text{by} \quad X_j \leftarrow x'_j.$$

$$\begin{cases} X_1 \leftarrow h_1(X_{\text{pa}(1)}, \epsilon_1) \\ X_2 \leftarrow h_2(X_{\text{pa}(2)}, \epsilon_2) \\ \vdots \\ X_p \leftarrow h_p(X_{\text{pa}(p)}, \epsilon_p) \end{cases}$$

Intervention on X_2

$$\begin{cases} X_1 \leftarrow h_1(X_{\text{pa}(1)}, \epsilon_1) \\ X_2 \leftarrow x'_2 \\ \vdots \\ X_p \leftarrow h_p(X_{\text{pa}(p)}, \epsilon_p) \end{cases}$$

Example

Clicker question – Observational and interventional distributions

Course outline

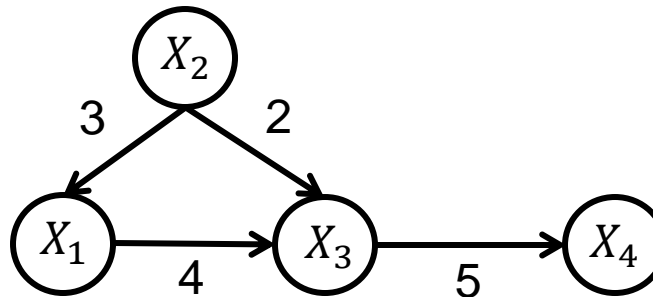
- Background and framework
- Using the known causal graph structure to identify causal effects
- Causal structure learning

Linear structural equation models

- **Linear SEMs:** all structural equations are linear and the noise is additive

- **Example:**

- $X_1 \leftarrow 3X_2 + \varepsilon_1$
- $X_2 \leftarrow \varepsilon_2$
- $X_3 \leftarrow 4X_1 + 3X_2 + \varepsilon_3$
- $X_4 \leftarrow 5X_3 + \varepsilon_4$



- What is the total causal effect of X_1 on X_4 ?

- **Path method:**

Increasing X_1 by 1 will on average increase X_3 by $4 \cdot 1 = 4$.

Increasing X_3 by 4 will on average increase X_4 by $4 \cdot 5 = 20$.

Causal effects in linear SEMs via the path method

- **Path method** to compute the total causal effect of X_i on X_j in a **linear SEM**:
 - For each directed path from X_i to X_j , multiply the edge weights along the path
 - Sum up the results over all paths
- See R and note that it matches up with simulating from interventional distributions

Recap

- Concepts to know:
 - Selection bias
 - Causal effects and do-operator
 - Causal graphical models
 - Structural equation models
 - Path method

References and acknowledgments

- Slides adapted from M. Maathuis
- Some examples from
 - Script by J. Peters & N. Meinshausen (2018)
 - Peters, Janzing and Schölkopf (2017). Elements of Causal Inference.
 - Shalizi (2019). Advanced Data Analysis from an Elementary Point of View.