MGroups

Finite Group Theory in Mathematica

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MGroups is a Mathematica Package that implements a part of Finite Group Theory. It facilitates studying group operations, order and inverses of the group elements, Cayley Tables, (ordinary and normal) subgroup structures of a group, and group morphisms easily and quickly.

0. License

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1. Preface

In **MGroups,** groups are defined in the form of "Associations" that are the Mathematica version of mappings. Quite literally, a group in this package is nothing but its Cayley Table. For example, to define the Z_2 group, all that is needed is to define

1. How 0 operates with 0,

- 2. How 0 operates with 1,
- 3. How 1 operates with 0, and
- **4.** How 1 operates with 1.

In Mathematica, Associations are of the form

```
ln[1]:= \langle |a \rightarrow b, c \rightarrow d, e \rightarrow f| \rangle;
```

which means that a maps to b, c maps to d, and e maps to f. Now, it is only appropriate to see how Z_2 will be defined in such a way:

```
\ln[2]:= \ Z_{10} = \langle |0 \rightarrow \langle |0 \rightarrow 0, \ 1 \rightarrow 1| \rangle, \ 1 \rightarrow \langle |0 \rightarrow 1, \ 1 \rightarrow 0| \rangle |\rangle;
```

... which is nothing but nested Associations. Now, if we need to see what is 0*0 in Z_{10} , we can type

```
In[3]:= Z_{10}[0][0]
```

Out[3]= **0**

to get the required output. Similarly, other complex groups are also defined.

2. Installation

To install the package, you can head over to my GitHub page (github.com/zplus11/MGroups) and download the MGroups.m file from there. Place it in the

```
ln[4]:= $UserBaseDirectory <> "\\Applications" (\star run this to get your directory \star)
```

Out[4]= C:\Users\Naman Taggar\AppData\Roaming\Mathematica\Applications

directory of your device. Then, whenever you need to use MGroups in a Mathematica notebook, type

In[5]:= << MGroups`

which will call the package. Now type

```
In[6]:= AdditiveGroup[2]
```

```
\text{Out[6]= } <\mid 0 \rightarrow <\mid 0 \rightarrow 0 \text{, } 1 \rightarrow 1 \mid \text{> , } 1 \rightarrow <\mid 0 \rightarrow 1 \text{, } 1 \rightarrow 0 \mid \text{>} \mid
```

If you get the same output as above, then congratulations — you have successfully installed **MGroups!**

3. Introduction

This documentation covers each aspect of the package, from basic to advanced. We define a group first:

Definition (Group). A group is a non-empty set in Mathematics, elements of which follow 4 properties namely Closure, Associativity, Existence of Identity, and Existence of Inverses under a certain binary operation.

Available Groups

This package provides the following groups:

Group	Description		
AdditiveGroup	Z_n : The group $\{0, 1,, n-1\}$ formed		
	under addition modulo <i>n</i> .		
MultiplicativeGroup	U_n : The group $\{0 \le x < n : \gcd(x, n) == 1\}$ formed		
	under multiplication modulo <i>n</i> .		
DihedralGroupp	Dn: The group of symmetries of a regular		
	polygon formed under their composition.		
K ₄ & Q ₈	Klein's 4 Group and the Quaternion Group.		
ExternalDirectProduct	The External Direct Product of given groups.		

that can be called by their respective function names.

Basic Operations

```
Import the package by running
```

In[13]:= DihedralGroupp[240]["s60"]["r190"]

Out[13]= **S110**

```
In[7]:= << MGroups`
      Define a group using one of the functions as follows:
 In[8]:= D4 = DihedralGroupp[4]; (* Caution: DihedralGroup is an inbuilt function,
      so this package uses DihedralGroupp *)
      and check the domain of this group:
 In[9]:= FindDomain[D4]
Out[9]= { r0, r1, r2, r3, s0, s1, s2, s3}
     Applying group operations:
In[10]:= D4["r2"]["s3"]
Out[10]= S1
In[11]:= D4["s1"]["s1"]
Out[11]= r0
      or with some other group:
In[12]:= MultiplicativeGroup[13][3][4]
Out[12]= 12
      which is 3 × 4 (mod 13). Do something more exciting:
```

which is the composition of the 190th rotation and reflection about the 61st axis, in the Dihedral group of order 480.

External Direct Products can be formed:

Group Properties

You can check whether a group is abelian or cyclic as follows:

Cayley Tables

Complete Cayley Tables can be printed for any group:

In[23]:= CayleyTable[QuaternionGroup]

Out[23]//TableForm=

mieroiii-								
						-j		
1	1	-1	i	$-\mathbf{i}$	j	-j	k	-k
-1	-1	1	$-\mathbf{i}$	i	-j	j	$-\mathbf{k}$	k
i	i	-i	-1	1	k	-k	-j	j
$-\mathbf{i}$	- i	i	1	-1	$-\mathbf{k}$	k	j	-j
j	j	-j	$-\mathbf{k}$	k	-1	1	i	- i
-j	-j	j	k	$-\mathbf{k}$	1	-1 i	$-\mathbf{i}$	i
k	k	$-\mathbf{k}$	j	-j	$-\mathbf{i}$	i	-1	1
$-\mathbf{k}$	-k	k	-j	j	i	$-\mathbf{i}$	1	-1

or for an EDP:

In[24]:= CayleyTable[ExternalDirectProduct[AdditiveGroup[2], MultiplicativeGroup[3]]]

Out[24]//TableForm=

	{ 0, 1 }	{0, 2 }	{1, 1 }	$\{1, 2\}$
{ 0, 1 }	0	0	1	1
	1	2	1	2
{ 0, 2 }	0	0	1	1
	2	1	2	1
(1 1)	1	1	0	0
{ 1, 1 }	1	2	1	2
{1, 2 }	1	1	0	0
	2	1	2	1

Orders and Inverses

Table of Orders and Inverses for a group can also be printed:

In[25]:= InversesTable[DihedralGroupp[6]]

Out[25]//TableForm=

Χ	X^{-1}	X
r0	r0	1
r1	r5	6
r2	r4	3
r3	r3	2
r4	r2	3
r5	r1	6
s0	s0	2
s1	s1	2
s2	s2	2
s3	s3	2
s4	s4	2
s5	s5	2

4. Subgroups

We define a subgroup:

Definition (Subgroup of a group). A subset $H \subseteq G$ is said to be a subgroup of the group G if it forms a group itself under the operation of G.

We can check this in MGroups as follows:

```
In[26]:= Z20 = AdditiveGroup[20]; (* {0, 1, ..., 19} *)
      sub = Table[2i, {i, 0, 9}]; (* {0, 2, ..., 18} *)
      SubgroupQ[Z20, sub]
Out[28]= True
In[29]:= SubgroupQ[DihedralGroupp[10], {"s3", "r0", "r2", "r3"}]
Out[29]= False
```

The packages uses the Finite Subgroup Test to check subgroups. All subgroups can be obtained using

```
In[30]:= Subgroups[DihedralGroupp[5]] // TableForm
Out[30]//TableForm=
        r0
        r0
                s0
        r0
                s1
        r0
                s2
                s3
        r0
        r0
        r0
                r1
                        r2
                                r3
                                       r4
                                                           s2 s3
                                                                              s4
        List the cyclic subgroups of U_{30}:
  ln[31]:= u30s = Subgroups[MultiplicativeGroup[30]];
        Select[u30s, CyclicQ[\langle |Table[x \rightarrow \langle |Table[y \rightarrow Mod[x y, 30], \{y, \#\}] | \rangle, \{x, \#\}] | \rangle] &]
 \texttt{Out} \texttt{[32]=} \ \{ \{1\}, \{1, 11\}, \{1, 19\}, \{1, 29\}, \{1, 7, 13, 19\}, \{1, 17, 19, 23\} \}
        In the case of Cyclic subgroups, finding subgroups is easier (by virtue of Fundamental Theorem of
        Cyclic Groups). For example, even finding subgroups of U_{997} (order 996) is a doable task:
  In[33]:= Subgroups [MultiplicativeGroup [997]];
        Length[%]
 Out[34]= 12
```

5. Subgroup Lattices

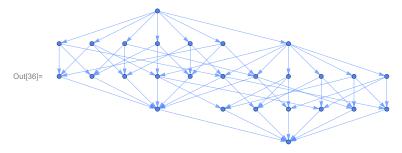
Most interesting, you can also see subgroup lattices of groups using this package. For example, let us see the subgroup lattice of Z_4 .





Here, the top most node is the group Z_4 itself, at the bottom we have $\{0\}$, and in the middle we must have {0, 2}. Let us proceed further and see something more exciting:

In[36]:= SubgroupLattice[MultiplicativeGroup[40]]



Beautiful! Subgroup Lattices of some Dihedral Groups:

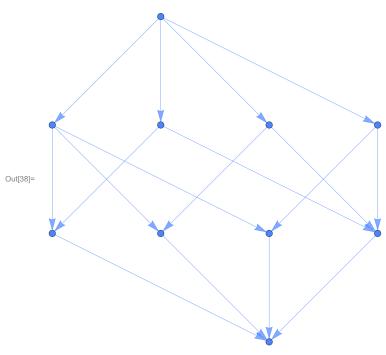
In[37]:= GraphicsRow[Table[SubgroupLattice[DihedralGroupp[i]], {i, 3, 6}]]



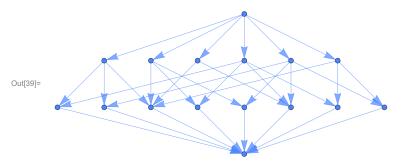
Who else sees the POSETS M_4 and M_6 !?

Some EDPs

In[38]≔ SubgroupLattice[ExternalDirectProduct[AdditiveGroup[6], AdditiveGroup[2]]]



In[39]:= SubgroupLattice[ExternalDirectProduct[DihedralGroupp[3], AdditiveGroup[2]]]



6. Cosets and Normal Subgroups

Definition (Coset). If H is a subgroup of G, then for some a in G, the set $\{a \mid h : h \in H\}$ is called the left coset of *H* in *G* containing *a*. Subsequently, corresponding right coset is the set $\{h \ a : h \in H\}$.

You can define cosets in this package as follows:

```
ln[40]:= edp2 = ExternalDirectProduct[MultiplicativeGroup[8], Klein4Group];
      s = \{\{1, "e"\}, \{1, "c"\}\}; (* any one subgroup *)
In[42]:= Coset[edp2, s, {3, "b"}, "1"]
Out[42]= \{\{3, b\}, \{3, a\}\}
In[43]:= Coset[edp2, s, {3, "b"}, "r"]
Out[43]= \{ \{3, b\}, \{3, a\} \}
```

Both are equal.

Definition (Normal Subgroup of a group). A subgroup H of G is said to be normal in G if the left coset by every element is equal to the right counterpart.

To find normal subgroups of a group:

```
In[44]:= NormalSubgroups [QuaternionGroup] // TableForm
```

```
Out[44]//TableForm=
    1
    1
        -1
        -1 i -i
    1
    1
        -1 j
                -j
    1 -1 k -k
    1
        -1 i -i j -j k
                                -k
```

7. Morphisms

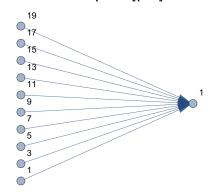
Definition (Group Homomorphism). A map ϕ from G_1 to G_2 is said to be a homomorphism, if and only if it is operation preserving, *i.e.*, if $\phi(xy) = \phi(x) \phi(y) \forall x, y \in G_1$.

To define a Group Homomorphism, you need to define the domain, the codomain, and the map's definition. It can be done as follows:

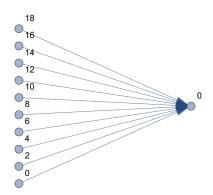
```
In[45]:= phi = Homomorphism[
                                                                                                                                         AdditiveGroup[20], (* domain *)
                                                                                                                                         AdditiveGroup[2], (* co-domain *)
                                                                                                                                         Mod[#, 2] & (* definition in the form of a pure function *)
Out[45]= \langle | 0 \rightarrow 0, 1 \rightarrow 1, 2 \rightarrow 0, 3 \rightarrow 1, 4 \rightarrow 0, 5 \rightarrow 1, 6 \rightarrow 0, 7 \rightarrow 1, 8 \rightarrow 0, 9 \rightarrow 1, 6 \rightarrow 0, 7 \rightarrow 1, 8 \rightarrow 0, 9 \rightarrow 1, 9
                                                                                                                   10 \rightarrow 0, 11 \rightarrow 1, 12 \rightarrow 0, 13 \rightarrow 1, 14 \rightarrow 0, 15 \rightarrow 1, 16 \rightarrow 0, 17 \rightarrow 1, 18 \rightarrow 0, 19 \rightarrow 1 \mid
```

Morphisms can be visualised as follows:

In[46]:= VisualiseMorphism[phi]



Out[46]=



We can see that the kernel of phi is {0, 2, ..., 18}.

Definition (*Group Isomorphism*). A homomorphism ϕ is said to be an isomorphism, if and only if it is one-one.

```
In[47]:= Isomorphism[
                    \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle,
                    \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle
                   # &
                ]
Out[47]= \langle | 1 \rightarrow 1 | \rangle
```

Definition (Group Automorphism). An isomorphism from a group to itself is said to be an automorphism.

```
In[48]:= Automorphism[
                 \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle
                # &
              ]
Out[48]= \langle | 1 \rightarrow 1 | \rangle
```

Definition (Inner Automorphism). An inner automorphism is an automorphism that is induced by a group element a, with the definition $x \longrightarrow a \times a^{-1}$.

In[49]:= InnerAutomorphism[DihedralGroupp[4], "s3"] VisualiseMorphism[%] $\texttt{Out[49]=} \quad \langle | \ \textbf{r0} \rightarrow \textbf{r0}, \ \textbf{r1} \rightarrow \textbf{r3}, \ \textbf{r2} \rightarrow \textbf{r2}, \ \textbf{r3} \rightarrow \textbf{r1}, \ \textbf{s0} \rightarrow \textbf{s2}, \ \textbf{s1} \rightarrow \textbf{s1}, \ \textbf{s2} \rightarrow \textbf{s0}, \ \textbf{s3} \rightarrow \textbf{s3} | \rangle$ Out[50]=

Thank you

Github Repository: https://github.com/zplus11/MGroups.git