MGroups

Finite Group Theory in Mathematica

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MGroups is a Mathematica Package that implements a part of Finite Group Theory. It facilitates studying group operations, order and inverses of the group elements, Cayley Tables, (ordinary and normal) subgroup structures of a group, and group morphisms easily and quickly. **MGroups** is licensed under the MIT Open-Source License.

1. Preface

In **MGroups**, groups are defined in the form of "Associations" that are the Mathematica version of mappings. Quite literally, a group in this package is nothing but its Cayley Table. For example, to define the Z_2 group, all that is needed is to define

- 1. How 0 operates with 0,
- 2. How 0 operates with 1,
- 3. How 1 operates with 0, and
- **4.** How 1 operates with 1.

In Mathematica, Associations are of the form

```
ln[1]:= \langle |a \rightarrow b, c \rightarrow d, e \rightarrow f| \rangle;
```

which means that a maps to b, c maps to d, and e maps to f. Now, it is only appropriate to see how Z_2 will be defined in such a way:—

```
\ln[2] = \ \mathsf{Z}_2 = \langle |\, \mathsf{0} \,\rightarrow\, \langle |\, \mathsf{0} \,\rightarrow\, \mathsf{0} \,,\ \ \mathsf{1} \,\rightarrow\, \mathsf{1} \,|\, \mathsf{>} \,,\ \ \mathsf{1} \,\rightarrow\, \langle |\, \mathsf{0} \,\rightarrow\, \mathsf{1} \,,\ \ \mathsf{1} \,\rightarrow\, \mathsf{0} \,|\, \mathsf{>} \,|\, \mathsf{>} \,|\, \mathsf{>} \,;
```

... which is nothing but nested Associations. Now, if we need to see what is 0^*0 in \mathbb{Z}_2 , we can type

```
In[3]:= Z_2[0][0]
```

Out[3]= **0**

to get the required output. Similarly, other complex groups are also defined.

2. Installation

To install the package, you can head over to my GitHub page (github.com/zplus11/MGroups) and download the MGroups.m file from there. In any Mathematica Notebook, type

```
_{\text{ln[4]}=} $UserBaseDirectory <> "\\Applications" (* run this to get your directory *)
```

Out[4]= C:\Users\Naman Taggar\AppData\Roaming\Mathematica\Applications

which should give you a folder path. Place MGroups.m file into this path on your device. Then, whenever you need to use **MGroups** in a Mathematica notebook, type

In[5]:= << MGroups`

which will call the package. Now type

In[6]:= AdditiveGroup[2]

$$\text{Out[6]= } <\mid 0 \rightarrow <\mid 0 \rightarrow 0 \text{, } 1 \rightarrow 1 \mid \text{> , } 1 \rightarrow <\mid 0 \rightarrow 1 \text{, } 1 \rightarrow 0 \mid \text{>} \mid$$

If you get the same output as above, then congratulations — you have successfully installed **MGroups!**

3. Introduction

This documentation covers each aspect of the package, from basic to advanced. We define a group first:-

Definition (Group). A group is a non-empty set in Mathematics, elements of which follow 4 properties namely Closure, Associativity, Existence of Identity, and Existence of Inverses under a certain binary operation.

Available Groups

This package provides the groups as tabulated below.

Group	Description	
AdditiveGroup	Z_n : The group $\{0, 1,, n-1\}$ formed	
	under addition modulo <i>n</i> .	
MultiplicativeGroup	U_n : The group $\{0 \le x < n : \gcd(x, n) == 1\}$ forme	
	under multiplication modulo <i>n</i> .	
DihedralGroupp	Dn: The group of symmetries of a regular	
	polygon formed under their composition.	
K ₄ & Q ₈	Klein's 4 Group and the Quaternion Group.	
ExternalDirectProduct	The External Direct Product of given groups.	

They can be called by their respective function names.

Defining a Group

Groups can be freely formed with the following command:—

```
In[7]:= FormGroup[{0}, #[1] + #[1] &]
Out[7]= \langle | 0 \rightarrow \langle | 0 \rightarrow 0 | \rangle | \rangle
```

without having to type out the Associations yourself.

Basic Operations

Import the package by running

```
In[8]:= << MGroups`
      Define a group using one of the functions as shown below.
 որթյ։= D4 = DihedralGroupp[4]; (* Caution: DihedralGroup is an inbuilt function,
      so this package uses DihedralGroupp *)
      and check the domain of this group:—
In[10]:= FindDomain[D4]
Out[10]= \{r0, r1, r2, r3, s0, s1, s2, s3\}
      Group operations can be applied just by indexing those elements through the associations.
In[11]:= D4["r2"]["s3"]
Out[11] = s1
In[12]:= D4["s1"]["s1"]
Out[12]= r0
      Trying some other group:—
In[13]:= MultiplicativeGroup[13][3][4]
Out[13]= 12
      which is 3 × 4 (mod 13). Doing something more exciting...
In[14]:= DihedralGroupp[240]["s60"]["r190"]
Out[14]= 510
      which is the composition of the 191st rotation and reflection about the 61st axis, in the Dihedral
      group of order 480.
      External Direct Products can be formed as follows:—
In[15]:= edp1 =
        ExternalDirectProduct[AdditiveGroup[12], MultiplicativeGroup[20], QuaternionGroup];
      The order of this group will be 12 × 8 × 8. Let's confirm that.
In[16]:= OrderGroup[edp1]
Out[16]= 768
      That is perfect! In EDPs, operations are done component-wise. For example,
ln[17]:= el1 = {5, 3, "-j"};
      el2 = {8, 19, "k"};
      edp1[el1][el2]
Out[19]= \{1, 17, i\}
```

Group Properties

You can check whether a group is abelian or cyclic using AbelianQ or CyclicQ commands respectively.

Cayley Tables

Complete Cayley Tables can be printed for any group using **CayleyTable** command.

In[24]:= CayleyTable[QuaternionGroup]

Out[24]//TableForm=

	1	- 1	i	$-\mathbf{i}$	j	-j	k	$-\mathbf{k}$
		-1						
-1	-1	1	- i	i	-j	j	$-\mathbf{k}$	k
i	i	$-\mathbf{i}$	-1	1	k	$-\mathbf{k}$	-j	j
$-\mathbf{i}$	- i	i	1	-1	$-\mathbf{k}$	k	j	-j
j	j	-j	$-\mathbf{k}$	k	-1	1	i	-i
-j	-j	j	k	$-\mathbf{k}$	1	-1	$-\mathtt{i}$	i
k	k	$-\mathbf{k}$	j	-j	$-\mathtt{i}$	i	-1	1
		k						

or for an EDP:-

In[25]:= CayleyTable[ExternalDirectProduct[AdditiveGroup[2], MultiplicativeGroup[3]]]

Out[25]//TableForm=

	{ 0, 1 }	$\{0, 2\}$	$\{1, 1\}$	{1, 2 }
{ 0, 1 }	0	0	1	1
{ U , I}	1	2	1	2
{0, 2 }	0	0	1	1
	2	1	2	1
{1, 1 }	1	1	0	0
	1	2	1	2
(1)	1	1	0	0
1, 2 }	2	1	2	1

Orders and Inverses

Table of Orders and Inverses for a group can also be printed as follows:—

In[26]:= InversesTable[DihedralGroupp[6]]

Out[26]//TableForm=

x	x^{-1}	x
r0	r0	1
r1	r5	6
r2	r4	3
r3	r3	2
r4	r2	3
r5	r1	6
s0	s0	2
s1	s1	2
s2	s2	2
s3	s3	2
s4	s4	2
s5	s5	2

4. Subgroups

We define a subgroup.

Definition (Subgroup of a group). A subset $H \subseteq G$ is said to be a subgroup of the group G if it forms a group itself under the operation of G.

We can check this in MGroups as follows:—

```
In[27]:= Z20 = AdditiveGroup[20]; (* {0, 1, ..., 19} *)
      sub = Table[2i, {i, 0, 9}]; (* {0, 2, ..., 18} *)
      SubgroupQ[Z20, sub]
Out[29]= True
In[30]:= SubgroupQ[DihedralGroupp[10], {"s3", "r0", "r2", "r3"}]
Out[30]= False
```

The packages uses the Finite Subgroup Test to check subgroups. All subgroups can be obtained

In[31]:= Subgroups[DihedralGroupp[5]] // TableForm

```
Out[31]//TableForm=
       r0
             s0
       r0
             s1
             s2
       r0
       r0
             s3
             s4
       r0
       r0
             r1
                    r2
                          r3
                          r3
                                 r4
                                                                  s4
       r0
             r1
                    r2
                                        s0
                                              s1
                                                    s2 s3
```

List the cyclic subgroups of U_{30} :—

```
In[32]:= u30s = Subgroups[MultiplicativeGroup[30]];
        Select[u30s, CyclicQ[\langle | Table[x \rightarrow \langle | Table[y \rightarrow Mod[x y, 30], \{y, \#\}] | \rangle, \{x, \#\}] | \rangle] \& ]
\text{Out} \texttt{[33]= } \{\{1\}, \{1, 11\}, \{1, 19\}, \{1, 29\}, \{1, 7, 13, 19\}, \{1, 17, 19, 23\}\}
```

In the case of Cyclic subgroups, finding subgroups is easier (by virtue of Fundamental Theorem of Cyclic Groups). For example, even finding subgroups of U_{997} (order 996) is a doable task.

In[34]:= Subgroups [MultiplicativeGroup [997]]; Length[%]

Out[35]= **12**

5. Subgroup Lattices

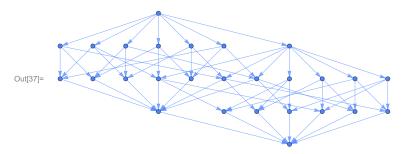
Most interesting, you can also see subgroup lattices of groups using this package. For example, let us see the subgroup lattice of Z_4 .

In[36]:= SubgroupLattice[AdditiveGroup[4]]



Here, the top most node is the group Z_4 itself, at the bottom we have $\{0\}$, and in the middle we must have {0, 2}. Let us proceed further and see something more exciting:—

In[37]:= SubgroupLattice[MultiplicativeGroup[40]]



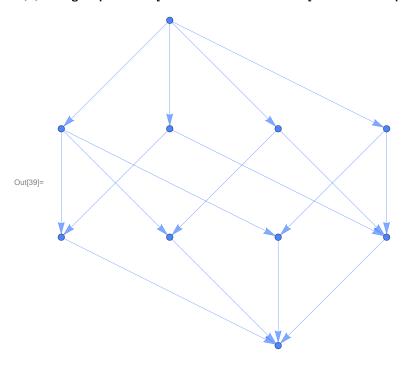
Beautiful! Subgroup Lattices of some Dihedral Groups:—

In[38]:= GraphicsRow[Table[SubgroupLattice[DihedralGroupp[i]], {i, 3, 6}]]

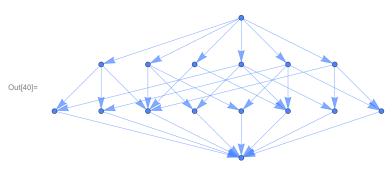


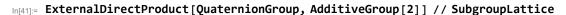
Some EDPs

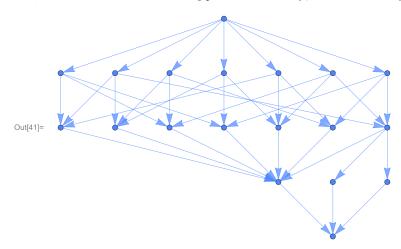
${}_{\text{ln}[39]:=} \textbf{SubgroupLattice} \textbf{[ExternalDirectProduct[AdditiveGroup[6],AdditiveGroup[2]]]}$



${\tt In[40]:=} \ \ \textbf{SubgroupLattice[ExternalDirectProduct[DihedralGroupp[3],AdditiveGroup[2]]]}$







6. Cosets and Normal Subgroups

Definition (Coset). If H is a subgroup of G, then for some a in G, the set $\{a \mid h : h \in H\}$ is called the left coset of H in G containing a. Subsequently, corresponding right coset is the set $\{h \ a : h \in H\}$.

You can define cosets in this package as follows:—

```
In[42]:= edp2 = ExternalDirectProduct[MultiplicativeGroup[8], Klein4Group];
      s = {{1, "e"}, {1, "c"}}; (* any one subgroup *)
In[44]:= Coset[edp2, s, {3, "b"}, "1"]
Out[44]= \{\{3,b\},\{3,a\}\}
In[45]:= Coset[edp2, s, {3, "b"}, "r"]
Out[45]= \{ \{3, b\}, \{3, a\} \}
```

Both are equal.

Definition (Normal Subgroup of a group). A subgroup H of G is said to be normal in G if the left coset by every element is equal to the right counterpart.

To find normal subgroups of a group:—

In[46]:= NormalSubgroups [QuaternionGroup] // TableForm

```
Out[46]//TableForm=
        1
               -1
        1
              -1
                            -i
                      i
                      j
                            -j
        1
                      k
              -1
                            -k
                                    j
                                          -j
```

7. Morphisms

Definition (Group Homomorphism). A map ϕ from G_1 to G_2 is said to be a homomorphism, if and only if it is operation preserving, *i.e.*, if $\phi(xy) = \phi(x) \phi(y) \forall x, y \in G_1$.

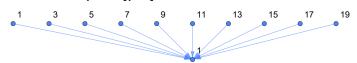
To define a Group Homomorphism, you need to define the domain, the codomain, and the map's definition. It can be done as follows:-

```
In[47]:= phi = Homomorphism[
                                                                                                                                                  AdditiveGroup[20], (* domain *)
                                                                                                                                                  AdditiveGroup[2], (* co-domain *)
                                                                                                                                                  Mod[#, 2] & (* definition in the form of a function *)
\text{Out}[47] = \  \  \, \langle |\ \theta \rightarrow \theta \text{, } 1 \rightarrow 1 \text{, } 2 \rightarrow \theta \text{, } 3 \rightarrow 1 \text{, } 4 \rightarrow \theta \text{, } 5 \rightarrow 1 \text{, } 6 \rightarrow \theta \text{, } 7 \rightarrow 1 \text{, } 8 \rightarrow \theta \text{, } 9 \rightarrow 1 \text{, } 8 \rightarrow \theta \text{, } 9 \rightarrow 1 \text{, } 9 \rightarrow \theta \text{, } 9 
                                                                                                                           10 \rightarrow 0, 11 \rightarrow 1, 12 \rightarrow 0, 13 \rightarrow 1, 14 \rightarrow 0, 15 \rightarrow 1, 16 \rightarrow 0, 17 \rightarrow 1, 18 \rightarrow 0, 19 \rightarrow 1 \mid
```

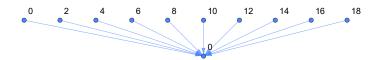
Morphisms can be visualised as follows.

```
In[48]:= << MGroups`
```

In[49]:= VisualiseMorphism[phi]



Out[49]=



We can see that the kernel of phi is {0, 2, ..., 18}.

Definition (*Group Isomorphism*). A homomorphism ϕ is said to be an isomorphism, if and only if it is one-one.

```
In[50]:= Isomorphism[
                    \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle
                    \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle
                   # &
                1
Out[50]= \langle | 1 \rightarrow 1 | \rangle
```

Definition (Group Automorphism). An isomorphism from a group to itself is said to be an automorphism.

```
In[51]:= Automorphism[
                 \langle |1 \rightarrow \langle |1 \rightarrow 1| \rangle | \rangle
                # &
Out[51]= \langle | 1 \rightarrow 1 | \rangle
```

Definition (Inner Automorphism). An inner automorphism is an automorphism that is induced by a group element a, with the definition $x \longrightarrow a \times a^{-1}$.

In[52]:= InnerAutomorphism[DihedralGroupp[4], "s3"] VisualiseMorphism[%]

 $\texttt{Out} \texttt{[52]=} \quad \langle | \ \textbf{r0} \rightarrow \textbf{r0}, \ \textbf{r1} \rightarrow \textbf{r3}, \ \textbf{r2} \rightarrow \textbf{r2}, \ \textbf{r3} \rightarrow \textbf{r1}, \ \textbf{s0} \rightarrow \textbf{s2}, \ \textbf{s1} \rightarrow \textbf{s1}, \ \textbf{s2} \rightarrow \textbf{s0}, \ \textbf{s3} \rightarrow \textbf{s3} | \rangle$ Out[53]=

Thank you

Github Repository: https://github.com/zplus11/MGroups.git.

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