# **ZACH MORGAN**

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### Objective

• I am seeking open-ended opportunities with potential to further my skillset & experience in unanticipated directions.

#### Education

B.S. in Computer Science, December 2009
The University of North Carolina at Greensboro

#### Skills

- Operating Systems: Linux (Ubuntu, Debian), Windows 2000/XP/7
- Computer Languages:
  - Proficient in Perl, Javascript, Regular expressions, SQL, C, C++, HTML, Java
  - Familiar with Ruby, LATEX, Java, Bash, Python
- Tools and Systems:
  - Proficient in Mojolicious, Catalyst, DBIx::Class, Moose, SQLite, Git, Redis, GTK+
  - Familiar with Vim, MySQL, Lighttpd, Android, PDL
- Other Skills: Machine learning, Text processing, APIs, OpenID, OAuth, Excellent car driver

## **Projects**

- Basilisk Go Server—Senior Project at UNCG was to build a a successful correspondence board game server in Perl. It demonstrates proficiency with object-relational mapping (ORM), web templating with forms and javascript, version control, regular expressions.
- Collision::2D—Collision::2D is a float-precision continuous collision detection system for some geometric shapes in 2D; it detects collisions between points, circles, and rects of any size and velocity. Originally implemented on Moose, it was ported to an XS backend.
- AI::Nerl AI::Nerl is a perceptron-type neural network library. AI::Nerl uses PDL, the Perl Data Language for fast linear operations, including training using backpropagation. AI::Nerl has been used to build a digit classifier and a general image classifier.
- Cinderblock Go Server— Another Go server, fixes many faults of Cinderblock. Uses Redis for storage and websockets to enable either correspondence or real-time play. Games::Go::Cinderblock spawned as a variant rulemap implementation. Scrollable board rendered with HTML5 canvas. POV-Ray was also used for some reason.
- Cataclysm: Dark Days Ahead— An established post-apocalyptic sandboc-style roguelike game. I solved almost all of the instability problems and rewrote the vehicle collision system to enable more "realistic" vehicle-vehicle collisions.