

WELL-POSEDNESS OF A NON-LOCAL MODEL FOR MATERIAL FLOW ON CONVEYOR BELTS

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Abstract. In this paper, we focus on finite volume approximation schemes to solve a non-local material flow model in two space dimensions. Based on the numerical discretisation with dimensional splitting, we prove the convergence of the approximate solutions, where the main difficulty arises in the treatment of the discontinuity occurring in the flux function. In particular, we compare a Roe-type scheme to the well-established Lax–Friedrichs method and provide a numerical study highlighting the benefits of the Roe discretisation. Besides, we also prove the L^1 -Lipschitz continuous dependence on the initial datum, ensuring the uniqueness of the solution.

Mathematics Subject Classification. 35L65, 65M12.

Received February 20, 2019. Accepted August 26, 2019.

1. INTRODUCTION

In this paper, we consider the Cauchy problem for a non-local scalar conservation law in two space dimensions, namely

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{v}^{\text{stat}}(x, y) + \rho \mathbf{v}^{\text{dyn}}(\rho)) = 0, & (t, x, y) \in [0, T] \times \mathbb{R}^2, \\ \rho(0, x, y) = \rho_o(x, y), & (x, y) \in \mathbb{R}^2, \end{cases} \quad (1.1)$$

for any $T > 0$, where for the weighting factor $\varepsilon > 0$

$$\mathbf{v}^{\text{dyn}}(\rho) = H(\rho - \rho_{\max}) \mathbf{I}(\rho) \quad \text{with } \mathbf{I}(\rho) = -\varepsilon \frac{\nabla(\eta * \rho)}{\sqrt{1 + \|\nabla(\eta * \rho)\|^2}}. \quad (1.2)$$

Here, H denotes the Heaviside function which becomes active whenever the maximal density $\rho_{\max} > 0$ is exceeded, while η is a positive smooth mollifier. The norm appearing in the denominator of $\mathbf{I}(\rho)$ is the Euclidean norm in \mathbb{R}^2 so that the denominator acts as a smooth normalisation factor.

The above model was introduced in [9], to describe the flow of objects on a conveyor belt. Specifically, the model consists of a linear convection term and a diffusion term. The non-local diffusion term is switched

Keywords and phrases. Non-local conservation laws, material flow, Roe scheme, Lax–Friedrichs scheme.

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on when the density exceeds the maximal density, otherwise it vanishes. In particular, the unknown function $\rho = \rho(t, x, y)$ is the density of transported parts, \mathbf{v}^{stat} is the velocity vector field induced by the conveyor belt, which is constant in time. So, below the maximal density, parts are transported with the velocity of the conveyor belt. On the other hand, the dynamic velocity vector field \mathbf{v}^{dyn} is active only at high densities and accounts for colliding parts through the operator $\mathbf{I}(\rho)$. The negative gradient of the convolution $\eta * \rho$ pushes the mass towards lower density regions. The particular choice of the collision operator $\mathbf{I}(\rho)$ was introduced in [6] to describe crowd dynamics.

Conservation laws with non-local flux function have been recently introduced in the literature to describe transport phenomena accounting for non-local interaction effects among agents, such as road traffic flow [3] or pedestrian dynamics [6]. General well-posedness results have been provided by Amorim *et al.* [2] in the scalar one-dimensional case, while [1] deals with systems of non-local conservation laws in multi-space dimensions. Even if the latter result applies to our problem (1.1), estimates in [1] were obtained for general flux functions using finite volume approximate solutions constructed *via* Lax–Friedrichs scheme. The aim of the present paper is instead to derive sharp estimates for the Roe scheme, which is known to give less diffusive solutions and is therefore computationally more convenient, especially in the case of non-local problems in multi-D. The same remark holds for the L^1 -stability estimates, which have been derived from scratch even if more general results are present in the literature [14, 15]. More recently, an alternative approach based on the method of characteristics and on Banach’s fixed-point theorem has been proposed in [11, 12]. In particular, no entropy condition is needed to prove uniqueness and stability of solutions, showing that weak solutions are indeed unique. Nevertheless, these results rely on stronger regularity assumptions on the flux function, and cannot give information on the convergence of the finite volume numerical schemes studied in this paper.

We finally remark that, even if the original model proposes the use of the discontinuous Heaviside function, the stability of the numerical schemes requires a smooth approximation of it. Indeed, it can be noticed that L^∞ -norm of the derivative H' appears in the estimates (for instance in the CFL condition (3.13) that guarantees the BV-estimates), which blow up with it.

The paper is organised as follows: for a better overview, we introduce our main results in Section 2 and start then to prove convergence of the approximate solution constructed by the Roe scheme in Section 3. We also add a proof of the Lipschitz continuous dependence on the initial data in Section 4. Sections 5 and 6 are devoted to the comparison of results obtained by the Lax–Friedrichs method. The numerical results, contrasting one scheme with the other, emphasise the good performance of the Roe scheme.

2. MAIN RESULTS

Throughout the paper, we will denote $\mathcal{I}(r, s) := [\min\{r, s\}, \max\{r, s\}]$, for any $r, s \in \mathbb{R}$. We require the following assumptions to hold:

- (\mathbf{v}) $\mathbf{v}^{\text{stat}} \in C^2(\mathbb{R}^2; \mathbb{R}^2)$.
- (\mathbf{H}) The function H is a smooth approximation of the Heaviside function such that, setting

$$f(r) = r H(r - \rho_{\max}),$$

the function f has a bounded derivative. In particular, we denote by L_f the Lipschitz constant of the function f :

$$L_f = \|f'\|_{L^\infty(\mathbb{R})}. \quad (2.1)$$

- ($\boldsymbol{\eta}$) $\eta \in (C^3 \cap W^{3,\infty})(\mathbb{R}^2; \mathbb{R}^+)$.

Recall the definition of solution to the Cauchy problem (1.1), see also [1, 2, 6].

Definition 2.1. Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. A map $\rho : [0, T] \rightarrow L^\infty(\mathbb{R}^2; \mathbb{R})$ is a solution to (1.1) if it is a Kružkov solution to

$$\begin{cases} \partial_t \rho + \nabla \cdot g(t, x, y, \rho) = 0, & (t, x, y) \in [0, T] \times \mathbb{R}^2, \\ \rho(0, x, y) = \rho_o(x, y), & (x, y) \in \mathbb{R}^2, \end{cases} \quad (2.2)$$

$$\text{with } g(t, x, y, \rho) = \rho \mathbf{v}^{\text{stat}}(x, y) - \varepsilon \rho H(\rho - \rho_{\max}) \frac{\nabla(\eta * \rho)}{\sqrt{1 + \|\nabla(\eta * \rho)\|^2}}.$$

Above, for the definition of Kružkov solution we refer to Definition 1 of [13].

Theorem 2.2. *Let $\rho_o \in (\text{L}^\infty \cap \text{BV})(\mathbb{R}^2; \mathbb{R}^+)$. Let assumptions (\mathbf{v}) , (\mathbf{H}) and $(\boldsymbol{\eta})$ hold. Then, for all $T > 0$, there exists a unique weak entropy solution $\rho \in (\text{L}^\infty \cap \text{BV})([0, T] \times \mathbb{R}^2; \mathbb{R}^+)$ to problem (1.1). Moreover, the following estimates hold: for all $t \in [0, T]$*

$$\begin{aligned} \|\rho(t)\|_{\text{L}^1} &= \|\rho_o\|_{\text{L}^1}, \\ \|\rho(t)\|_{\text{L}^\infty} &\leq \|\rho_o\|_{\text{L}^\infty} e^{\mathcal{C}_\infty t}, \\ \text{TV}(\rho(t)) &\leq \text{TV}(\rho_o) e^{2t\mathcal{K}_1} + \frac{2\mathcal{K}_2}{\mathcal{K}_1} (e^{2t\mathcal{K}_1} - 1), \\ \|\rho(t) - \rho(t - \tau)\|_{\text{L}^1} &\leq 2\mathcal{C}_t(t) \tau, \quad \text{for } \tau > 0, \end{aligned}$$

where \mathcal{C}_∞ is defined in (3.12), \mathcal{K}_1 is defined in (3.16), \mathcal{K}_2 is defined in (3.17) and $\mathcal{C}_t(t)$ is as in (3.40).

The proof of existence of solutions is based on the constructions of a converging sequence of approximate solutions and follows standard guidelines, see *e.g.* Theorem 2.3 of [1]. In the literature, this usually relies on Lax–Friedrichs type schemes. In this paper, we derive the necessary compactness estimates for Roe scheme. The bounds presented in Theorem 2.2 are obtained by passing to the limit in the corresponding discrete bounds. Uniqueness is ensured by Proposition 4.1, which provides the Lipschitz continuous dependence estimate of solutions to (1.1) on the initial data.

3. EXISTENCE

Introduce the uniform mesh of width Δx along the x -axis and Δy along the y -axis, and a time step Δt subject to a CFL condition, specified later on. For $k \in \mathbb{Z}$ set

$$\begin{aligned} x_k &= (k - 1/2)\Delta x, & y_k &= (k - 1/2)\Delta y, \\ x_{k+1/2} &= k\Delta x, & y_{k+1/2} &= k\Delta y, \end{aligned}$$

where $(x_{i+\frac{1}{2}}, y_j)$ and $(x_i, y_{j+1/2})$ denote the cells interfaces and (x_i, y_j) are the cells centres. Set $N_T = \lfloor T/\Delta t \rfloor$ and let $t^n = n\Delta t$, $n = 0, \dots, N_T$, be the time mesh. Set $\lambda_x = \Delta t/\Delta x$ and $\lambda_y = \Delta t/\Delta y$.

For the sake of brevity, sometimes we will use also the notation $x_{i,j} = (x_i, y_j)$, $x_{i+1/2,j} = (x_{i+1/2}, y_j)$ and $x_{i,j+1/2} = (x_i, y_{j+1/2})$.

We approximate the initial datum as follows: for $i, j \in \mathbb{Z}$

$$\rho_{i,j}^0 = \frac{1}{\Delta x \Delta y} \int_{x_{i-1/2}}^{x_{i+1/2}} \int_{y_{j-1/2}}^{y_{j+1/2}} \rho_o(x, y) \, dx \, dy,$$

and we define a piece-wise constant solution to (1.1) as

$$\rho_\Delta(t, x, y) = \rho_{i,j}^n \quad \text{for} \quad \begin{cases} t \in [t^n, t^{n+1}[, \\ x \in [x_{i-1/2}, x_{i+1/2}[, \\ y \in [y_{j-1/2}, y_{j+1/2}[, \end{cases} \quad \begin{matrix} \text{where} \\ i \in \mathbb{Z}, \\ j \in \mathbb{Z}. \end{matrix} \quad n = 0, \dots, N_T - 1, \quad (3.1)$$

through a modified Roe-type scheme with dimensional splitting, exactly as in [9]:

Algorithm 3.1.

$$V_1(x, y, u, w) = v_1^{\text{stat}}(x, y) u + \min\{0, v_1^{\text{stat}}(x, y)\}(w - u) \quad (3.2)$$

$$F(u, w, J(t, x, y)) = J(t, x, y) f(u) + \min\{0, J(t, x, y)\} (f(w) - f(u)) \quad (3.3)$$

$$V_2(x, y, u, w) = v_2^{\text{stat}}(x, y) u + \min\{0, v_2^{\text{stat}}(x, y)\}(w - u) \quad (3.4)$$

for $n = 0, \dots, N_T - 1$

$$\begin{aligned} \rho_{i,j}^{n+1/2} &= \rho_{i,j}^n - \lambda_x [V_1(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) - V_1(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n)] \\ &\quad + F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j})) - F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j})) \end{aligned} \quad (3.5)$$

$$\begin{aligned} \rho_{i,j}^{n+1} &= \rho_{i,j}^{n+1/2} - \lambda_y [V_2(x_{i,j+1/2}, \rho_{i,j}^n, \rho_{i,j+1}^n) - V_2(x_{i,j-1/2}, \rho_{i,j-1}^n, \rho_{i,j}^n)] \\ &\quad + F(\rho_{i,j}^n, \rho_{i,j+1}^n, J_2^n(x_{i,j+1/2})) - F(\rho_{i,j-1}^n, \rho_{i,j}^n, J_2^n(x_{i,j-1/2})) \end{aligned} \quad (3.6)$$

end

Above, we set $\mathbf{I}(\rho^n)(x, y) = (J_1^n(x, y), J_2^n(x, y))$ and the convolution products are computed through the following quadrature formula, for $k = 1, 2$,

$$(\partial_i \eta * \rho)(x_i, y_j) = \Delta x \Delta y \sum_{k, \ell \in \mathbb{Z}} \rho_{k,\ell} \partial_i \eta(x_{i-k}, y_{j-\ell}), \quad (3.7)$$

where $\partial_1 \eta = \partial_x \eta$ and $\partial_2 \eta = \partial_y \eta$. Remark that the choice of evaluating the numerical flux at t^n for both fractional steps allows to save computational time, because the convolution products (3.7) are computed only once per time step.

Introduce the following notation, which is of use below:

$$v_{i+1/2} = v_1^{\text{stat}}(x_{i+1/2}). \quad (3.8)$$

3.1. Positivity

In the case of positive initial datum, we prove that under a suitable CFL condition the approximate solution to (1.1) constructed *via* the Algorithm 3.1 preserves the positivity.

Lemma 3.2 (Positivity). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) and $(\boldsymbol{\eta})$ hold. Assume that*

$$\lambda_x \leq \frac{1}{2(\varepsilon + \|v_1^{\text{stat}}\|_{L^\infty})}, \quad \lambda_y \leq \frac{1}{2(\varepsilon + \|v_2^{\text{stat}}\|_{L^\infty})}. \quad (3.9)$$

Then, for all $t > 0$ and $(x, y) \in \mathbb{R}^2$, the piece-wise constant approximate solution ρ_Δ (3.1) constructed through Algorithm 3.1 is such that $\rho_\Delta(t, x, y) \geq 0$.

Proof. Fix n between 0 and $N_T - 1$ and assume that $\rho_{i,j}^n \geq 0$ for all $i, j \in \mathbb{Z}$. Consider (3.5), with the notation (3.2) and (3.3), and observe that:

$$\begin{aligned} &V_1(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) + F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j})) \\ &\leq v_1^{\text{stat}}(x_{i+1/2,j}) \rho_{i,j}^n + J_1^n(x_{i+1/2,j}) f(\rho_{i,j}^n) \leq (\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon) \rho_{i,j}^n, \\ &V_1(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n) + F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j})) \\ &\geq v_1^{\text{stat}}(x_{i-1/2,j}) \rho_{i,j}^n + J_1^n(x_{i-1/2,j}) f(\rho_{i,j}^n) \geq -(\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon) \rho_{i,j}^n. \end{aligned}$$

Therefore, by (3.5),

$$\rho_{i,j}^{n+1/2} \geq \rho_{i,j}^n - 2 \lambda_x (\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon) \rho_{i,j}^n \geq 0,$$

thanks to the CFL condition (3.9). Starting from (3.6), an analogous argument shows that $\rho_{i,j}^{n+1} \geq 0$, concluding the proof. \square

3.2. L^1 bound

The following result on the L^1 bound follows from the conservation property of the Roe scheme.

Lemma 3.3 (L^1 bound). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) , $(\boldsymbol{\eta})$ and (3.9) hold. Then, for all $t > 0$ and $(x, y) \in \mathbb{R}^2$, ρ_Δ (3.1) constructed through Algorithm 3.1 satisfies*

$$\|\rho_\Delta(t, \cdot, \cdot)\|_{L^1(\mathbb{R}^2)} = \|\rho_o\|_{L^1(\mathbb{R}^2)}. \quad (3.10)$$

3.3. L^∞ bound

Lemma 3.4 (L^∞ bound). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) , $(\boldsymbol{\eta})$ and (3.9) hold. Then, for all $t > 0$ and $(x, y) \in \mathbb{R}^2$, ρ_Δ (3.1) constructed through Algorithm 3.1 satisfies*

$$\|\rho_\Delta(t, \cdot, \cdot)\|_{L^\infty(\mathbb{R}^2)} \leq \|\rho_o\|_{L^\infty} e^{C_\infty t}, \quad (3.11)$$

where

$$C_\infty = \|\partial_x v_1^{\text{stat}}\|_{L^\infty} + \|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 4\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}. \quad (3.12)$$

Proof. Omitting the dependencies on j and exploiting the notation introduced in (3.8), we observe that (3.5) attains its maximum for $v_{i+1/2} < 0$, $v_{i-1/2} \geq 0$, $J_1^n(x_{i+1/2}) < 0$ and $J_1^n(x_{i-1/2}) \geq 0$. In this case

$$\rho_{i,j}^{n+1/2} \leq \rho_i^n - \lambda_x (\rho_{i+1}^n v_{i+1/2} + J_1^n(x_{i+1/2}) f(\rho_{i+1}^n)) + \lambda_x (\rho_{i-1}^n v_{i-1/2} + J_1^n(x_{i-1/2}) f(\rho_{i-1}^n)),$$

where we use the positivity of each ρ_i^n and of the function f and discard all the terms giving a negative contribution. Moreover, since $v_{i+1/2} < 0$ and $v_{i-1/2} \geq 0$,

$$\lambda_x (-\rho_{i+1}^n v_{i+1/2} + \rho_{i-1}^n v_{i-1/2}) \leq \lambda_x \|\rho^n\|_{L^\infty} (-v_{i+1/2} + v_{i-1/2}) = \lambda_x \|\rho^n\|_{L^\infty} (-\Delta x) \partial_x v_1^{\text{stat}}(\hat{x}_i)$$

with $\hat{x}_i \in]x_{i-1/2}, x_{i+1/2}[$. In a similar way, since $J_1^n(x_{i+1/2}) < 0$ and $J_1^n(x_{i-1/2}) \geq 0$, exploiting also the fact that $f(r) \leq r$ for all $r \geq 0$, we get

$$\begin{aligned} \lambda_x (-J_1^n(x_{i+1/2}) f(\rho_{i+1}^n) + J_1^n(x_{i-1/2}) f(\rho_{i-1}^n)) &\leq \lambda_x \|\rho^n\|_{L^\infty} (-J_1^n(x_{i+1/2}) + J_1^n(x_{i-1/2})) \\ &\leq \lambda_x \|\rho^n\|_{L^\infty} 2\varepsilon \Delta x \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1}, \end{aligned}$$

thanks to (A.2). Therefore,

$$\rho_{i,j}^{n+1/2} \leq \|\rho^n\|_{L^\infty} [1 + \Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1})].$$

In a similar way we get

$$\rho_{i,j}^{n+1} \leq \|\rho^{n+1/2}\|_{L^\infty} [1 + \Delta t (\|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1})].$$

An iterative argument completes the proof. \square

3.4. BV bound

Proposition 3.5 (BV estimate in space). *Let $\rho_o \in (L^\infty \cap BV)(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) , (\mathbf{H}) , and $(\boldsymbol{\eta})$ hold. Assume that*

$$\lambda_x \leq \frac{1}{3(\varepsilon L_f + \|v_1^{\text{stat}}\|_{L^\infty})}, \quad \lambda_y \leq \frac{1}{3(\varepsilon L_f + \|v_2^{\text{stat}}\|_{L^\infty})}. \quad (3.13)$$

Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 3.1 satisfies the following estimate: for all $n = 0, \dots, N_T$,

$$\sum_{i,j \in \mathbb{Z}} (\Delta y |\rho_{i+1,j}^n - \rho_{i,j}^n| + \Delta x |\rho_{i,j+1}^n - \rho_{i,j}^n|) \leq C_x(t^n), \quad (3.14)$$

where

$$\mathcal{C}_x(t) = e^{2t\mathcal{K}_1} \sum_{i,j \in \mathbb{Z}} (\Delta x |\rho_{i,j+1}^0 - \rho_{i,j}^0| + \Delta y |\rho_{i+1,j}^0 - \rho_{i,j}^0|) + \frac{2\mathcal{K}_2}{\mathcal{K}_1} (e^{2t\mathcal{K}_1} - 1), \quad (3.15)$$

with

$$\mathcal{K}_1 = 6 (\|\nabla \mathbf{v}^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}), \quad (3.16)$$

$$\mathcal{K}_2 = \left(4\varepsilon \left(c_1 \|\rho_o\|_{L^1} + c_2 \|\rho_o\|_{L^1}^2 \right) + 3 \|\nabla^2 \mathbf{v}^{\text{stat}}\|_{L^\infty} \right) \|\rho_o\|_{L^1}, \quad (3.17)$$

and c_1, c_2 are defined in (A.6).

Remark 3.6. Observe that the CFL conditions (3.13) are stricter than (3.9).

Proof. We follow the idea of Lemma 2.7 from [1]. First consider the term

$$\sum_{i,j \in \mathbb{Z}} \Delta y \left| \rho_{i+1,j}^{n+1/2} - \rho_{i,j}^{n+1/2} \right|.$$

In particular, fixing $i, j \in \mathbb{Z}$ and omitting the dependencies on y_j for the sake of simplicity, by (3.5) we get

$$\begin{aligned} \rho_{i+1}^{n+1/2} - \rho_i^{n+1/2} &= \rho_{i+1}^n - \rho_i^n - \lambda_x [V_1(x_{i+3/2}, \rho_{i+1}^n, \rho_{i+2}^n) + F(\rho_{i+1}^n, \rho_{i+2}^n, J_1^n(x_{i+3/2})) \\ &\quad - V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})) \\ &\quad - V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})) \\ &\quad + V_1(x_{i-1/2}, \rho_{i-1}^n, \rho_i^n) + F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i-1/2}))] \\ &\pm \lambda_x [V_1(x_{i+3/2}, \rho_i^n, \rho_{i+1}^n) + F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+3/2})) \\ &\quad - V_1(x_{i+1/2}, \rho_{i-1}^n, \rho_i^n) - F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i+1/2}))] \\ &= \mathcal{A}_{i,j}^n - \lambda_x \mathcal{B}_{i,j}^n, \end{aligned}$$

where we set

$$\begin{aligned} \mathcal{A}_{i,j}^n &= \rho_{i+1}^n - \rho_i^n \\ &\quad - \lambda_x [V_1(x_{i+3/2}, \rho_{i+1}^n, \rho_{i+2}^n) + F(\rho_{i+1}^n, \rho_{i+2}^n, J_1^n(x_{i+3/2})) - V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})) \\ &\quad + V_1(x_{i+1/2}, \rho_{i-1}^n, \rho_i^n) + F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i+1/2})) - V_1(x_{i+3/2}, \rho_i^n, \rho_{i+1}^n) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+3/2}))], \\ \mathcal{B}_{i,j}^n &= V_1(x_{i+3/2}, \rho_i^n, \rho_{i+1}^n) + F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+3/2})) - V_1(x_{i+1/2}, \rho_{i-1}^n, \rho_i^n) - F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i+1/2})) \\ &\quad + V_1(x_{i-1/2}, \rho_{i-1}^n, \rho_i^n) + F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i-1/2})) - V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})). \end{aligned}$$

For the sake of shortness, introduce the following notation

$$H_{k,\ell}^n(u, w) = V_1(x_{k,\ell}, u, w) + F(u, w, J_1^n(x_{k,\ell})), \quad (3.18)$$

so that, dropping the j dependencies, $\mathcal{A}_{i,j}^n$ reads

$$\begin{aligned} \mathcal{A}_{i,j}^n &= \rho_{i+1}^n - \rho_i^n - \lambda_x \left[H_{i+3/2}^n(\rho_{i+1}^n, \rho_{i+2}^n) - H_{i+1/2}^n(\rho_i^n, \rho_{i+1}^n) + H_{i+1/2}^n(\rho_{i-1}^n, \rho_i^n) - H_{i+3/2}^n(\rho_i^n, \rho_{i+1}^n) \right] \\ &= \rho_{i+1}^n - \rho_i^n - \lambda_x \frac{H_{i+3/2}^n(\rho_{i+1}^n, \rho_{i+2}^n) - H_{i+3/2}^n(\rho_{i+1}^n, \rho_{i+1}^n)}{\rho_{i+2}^n - \rho_{i+1}^n} (\rho_{i+2}^n - \rho_{i+1}^n) \\ &\quad - \lambda_x \frac{H_{i+3/2}^n(\rho_{i+1}^n, \rho_{i+1}^n) - H_{i+3/2}^n(\rho_i^n, \rho_{i+1}^n)}{\rho_{i+1}^n - \rho_i^n} (\rho_{i+1}^n - \rho_i^n) \end{aligned}$$

$$\begin{aligned}
& + \lambda_x \frac{H_{i+1/2}^n(\rho_i^n, \rho_{i+1}^n) - H_{i+1/2}^n(\rho_i^n, \rho_i^n)}{\rho_{i+1}^n - \rho_i^n} (\rho_{i+1}^n - \rho_i^n) \\
& + \lambda_x \frac{H_{i+1/2}^n(\rho_i^n, \rho_i^n) - H_{i+1/2}^n(\rho_{i-1}^n, \rho_i^n)}{\rho_i^n - \rho_{i-1}^n} (\rho_i^n - \rho_{i-1}^n) \\
& = \delta_{i+1}^n (\rho_{i+2}^n - \rho_{i+1}^n) + \vartheta_i^n (\rho_i^n - \rho_{i-1}^n) + (1 - \delta_i^n - \vartheta_{i+1}^n) (\rho_{i+1}^n - \rho_i^n),
\end{aligned}$$

where

$$\delta_i^n = \begin{cases} -\lambda_x \frac{H_{i+1/2}^n(\rho_i^n, \rho_{i+1}^n) - H_{i+1/2}^n(\rho_i^n, \rho_i^n)}{\rho_{i+1}^n - \rho_i^n} & \text{if } \rho_i^n \neq \rho_{i+1}^n, \\ 0 & \text{if } \rho_i^n = \rho_{i+1}^n, \end{cases} \quad (3.19)$$

$$\vartheta_i^n = \begin{cases} \lambda_x \frac{H_{i+1/2}^n(\rho_i^n, \rho_i^n) - H_{i+1/2}^n(\rho_{i-1}^n, \rho_i^n)}{\rho_i^n - \rho_{i-1}^n} & \text{if } \rho_i^n \neq \rho_{i-1}^n, \\ 0 & \text{if } \rho_i^n = \rho_{i-1}^n. \end{cases} \quad (3.20)$$

Exploiting (3.18), observe that, whenever $\rho_i^n \neq \rho_{i+1}^n$,

$$\begin{aligned}
\delta_i^n &= -\frac{\lambda_x}{\rho_{i+1}^n - \rho_i^n} [V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) + F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})) - V_1(x_{i+1/2}, \rho_i^n, \rho_i^n) - F(\rho_i^n, \rho_i^n, J_1^n(x_{i+1/2}))] \\
&= -\frac{\lambda_x}{\rho_{i+1}^n - \rho_i^n} [\min \{0, v_1^{\text{stat}}(x_{i+1/2})\} (\rho_{i+1}^n - \rho_i^n) + \min \{0, J_1^n(x_{i+1/2})\} (f(\rho_{i+1}^n) - f(\rho_i^n))] \\
&= -\lambda_x \left(\min \{0, v_1^{\text{stat}}(x_{i+1/2})\} + \min \{0, J_1^n(x_{i+1/2})\} f'(r_{i+1/2}^n) \right),
\end{aligned}$$

with $r_{i+1/2}^n \in \mathcal{I}(\rho_i^n, \rho_{i+1}^n)$. Since $f'(r) \geq 0$ and by (3.13) we get

$$\delta_i^n \in \left[0, \frac{1}{3} \right].$$

In a similar way one can prove that $\vartheta_i^n \in [0, 1/3]$. Thus,

$$\sum_{i,j \in \mathbb{Z}} |\mathcal{A}_{i,j}^n| \leq \sum_{i,j \in \mathbb{Z}} |\rho_{i+1,j}^n - \rho_{i,j}^n|. \quad (3.21)$$

We pass now to $\mathcal{B}_{i,j}^n$. Consider separately the terms involving V_1 and those involving F . Observe that the maps

$$x \mapsto \min \{0, v_1^{\text{stat}}(x)\}, \quad x \mapsto \min \{0, J_1^n(x)\}$$

are Lipschitz continuous, with constant respectively $\|\partial_x v_1^{\text{stat}}\|_{L^\infty}$ and $2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}$. Exploiting (3.2) we get:

$$\begin{aligned}
& V_1(x_{i+3/2}, \rho_i^n, \rho_{i+1}^n) - V_1(x_{i+1/2}, \rho_{i-1}^n, \rho_i^n) + V_1(x_{i-1/2}, \rho_{i-1}^n, \rho_i^n) - V_1(x_{i+1/2}, \rho_i^n, \rho_{i+1}^n) \\
&= v_1^{\text{stat}}(x_{i+3/2}) \rho_i^n + \min \{0, v_1^{\text{stat}}(x_{i+3/2})\} (\rho_{i+1}^n - \rho_i^n) - v_1^{\text{stat}}(x_{i+1/2}) \rho_i^n \\
&\quad - \min \{0, v_1^{\text{stat}}(x_{i+1/2})\} (\rho_{i+1}^n - \rho_i^n) \\
&\quad + v_1^{\text{stat}}(x_{i-1/2}) \rho_{i-1}^n + \min \{0, v_1^{\text{stat}}(x_{i-1/2})\} (\rho_i^n - \rho_{i-1}^n) \\
&\quad - v_1^{\text{stat}}(x_{i+1/2}) \rho_{i-1}^n - \min \{0, v_1^{\text{stat}}(x_{i+1/2})\} (\rho_i^n - \rho_{i-1}^n) \pm (v_1^{\text{stat}}(x_{i-1/2}) - v_1^{\text{stat}}(x_{i+1/2})) \rho_i^n
\end{aligned} \quad (3.22)$$

$$\begin{aligned}
&= (v_1^{\text{stat}}(x_{i+3/2}) - 2v_1^{\text{stat}}(x_{i+1/2}) + v_1^{\text{stat}}(x_{i-1/2})) \rho_i^n + (v_1^{\text{stat}}(x_{i-1/2}) - v_1^{\text{stat}}(x_{i+1/2})) (\rho_{i-1}^n - \rho_i^n) \\
&\quad + (\min \{0, v_1^{\text{stat}}(x_{i+3/2})\} - \min \{0, v_1^{\text{stat}}(x_{i+1/2})\}) (\rho_{i+1}^n - \rho_i^n) \\
&\quad + (\min \{0, v_1^{\text{stat}}(x_{i-1/2})\} - \min \{0, v_1^{\text{stat}}(x_{i+1/2})\}) (\rho_i^n - \rho_{i-1}^n) \\
&\leq 2(\Delta x)^2 \|\partial_{xx}^2 v_1^{\text{stat}}\|_{L^\infty} |\rho_i^n| + \Delta x \|\partial_x v_1^{\text{stat}}\|_{L^\infty} (|\rho_{i+1}^n - \rho_i^n| + 2|\rho_i^n - \rho_{i-1}^n|),
\end{aligned} \quad (3.23)$$

since

$$\begin{aligned} v_1^{\text{stat}}(x_{i+3/2}) - 2v_1^{\text{stat}}(x_{i+1/2}) + v_1^{\text{stat}}(x_{i-1/2}) &= \Delta x \partial_x v_1^{\text{stat}}(\xi_{i+1}) - \Delta x \partial_x v_1^{\text{stat}}(\xi_i) \\ &= \Delta x (\xi_{i+1} - \xi_i) \partial_{xx}^2 v_1^{\text{stat}}(\zeta_{i+1/2}), \end{aligned}$$

with $\xi_i \in]x_{i-1/2}, x_{i+1/2}[$ and $\zeta_{i+1/2} \in]\xi_i, \xi_{i+1}[$.

Similarly, exploiting (3.3) we obtain

$$\begin{aligned} F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+3/2})) - F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i+1/2})) + F(\rho_{i-1}^n, \rho_i^n, J_1^n(x_{i-1/2})) - F(\rho_i^n, \rho_{i+1}^n, J_1^n(x_{i+1/2})) \\ = J_1^n(x_{i+3/2})f(\rho_i^n) + \min \{0, J_1^n(x_{i+3/2})\} (f(\rho_{i+1}^n) - f(\rho_i^n)) \\ - J_1^n(x_{i+1/2})f(\rho_i^n) - \min \{0, J_1^n(x_{i+1/2})\} (f(\rho_{i+1}^n) - f(\rho_i^n)) \\ + J_1^n(x_{i-1/2})f(\rho_{i-1}^n) + \min \{0, J_1^n(x_{i-1/2})\} (f(\rho_i^n) - f(\rho_{i-1}^n)) \\ - J_1^n(x_{i+1/2})f(\rho_{i-1}^n) - \min \{0, J_1^n(x_{i+1/2})\} (f(\rho_i^n) - f(\rho_{i-1}^n)) \pm (J_1^n(x_{i-1/2}) - J_1^n(x_{i+1/2})) f(\rho_i^n) \\ = (J_1^n(x_{i+3/2}) - 2J_1^n(x_{i+1/2}) + J_1^n(x_{i-1/2})) f(\rho_i^n) + (J_1^n(x_{i-1/2}) - J_1^n(x_{i+1/2})) (f(\rho_{i-1}^n) - f(\rho_i^n)) \\ + (\min \{0, J_1^n(x_{i+3/2})\} - \min \{0, J_1^n(x_{i+1/2})\}) (f(\rho_{i+1}^n) - f(\rho_i^n)) \\ + (\min \{0, J_1^n(x_{i-1/2})\} - \min \{0, J_1^n(x_{i+1/2})\}) (f(\rho_i^n) - f(\rho_{i-1}^n)) \\ \leq 2\varepsilon (\Delta x)^2 C |\rho_i^n| + 2\varepsilon L_f \Delta x \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1} (|\rho_{i+1}^n - \rho_i^n| + 2|\rho_i^n - \rho_{i-1}^n|), \end{aligned} \quad (3.24)$$

where we used the fact that $f(r) \leq r$, (A.2) and (A.4), with the notation (A.6). Collecting together (3.23) and (3.24) we therefore obtain

$$\begin{aligned} |\mathcal{B}_{i,j}^n| &\leq 2(\Delta x)^2 (\|\partial_{xx}^2 v_1^{\text{stat}}\|_{L^\infty} + \varepsilon C) |\rho_i^n| \\ &\quad + \Delta x (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) (|\rho_{i+1}^n - \rho_i^n| + 2|\rho_i^n - \rho_{i-1}^n|), \end{aligned}$$

so that

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \lambda_x |\mathcal{B}_{i,j}^n| &\leq 3\Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \sum_{i,j \in \mathbb{Z}} |\rho_{i+1}^n - \rho_i^n| \\ &\quad + 2\Delta t (\|\partial_{xx}^2 v_1^{\text{stat}}\|_{L^\infty} + \varepsilon C) \Delta x \sum_{i,j \in \mathbb{Z}} |\rho_i^n|. \end{aligned} \quad (3.25)$$

Therefore, by (3.21) and (3.25), using also Lemma 3.3

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \Delta y \left| \rho_{i+1,j}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| &\leq \sum_{i,j \in \mathbb{Z}} \Delta y (|\mathcal{A}_{i,j}^n| + \lambda_x |\mathcal{B}_{i,j}^n|) \\ &\leq [1 + 3\Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1})] \sum_{i,j \in \mathbb{Z}} \Delta y |\rho_{i+1}^n - \rho_i^n| \\ &\quad + 2\Delta t [\|\partial_{xx}^2 v_1^{\text{stat}}\|_{L^\infty} + \varepsilon C] \|\rho_o\|_{L^1}. \end{aligned} \quad (3.26)$$

Now pass to the term

$$\sum_{i,j \in \mathbb{Z}} \Delta x \left| \rho_{i,j+1}^{n+1/2} - \rho_{i,j}^{n+1/2} \right|.$$

Fix $i, j \in \mathbb{Z}$ and exploit (3.5) again to get

$$\begin{aligned} \rho_{i,j+1}^{n+1/2} - \rho_{i,j}^{n+1/2} &= \rho_{i,j+1}^n - \rho_{i,j}^n - \lambda_x [V_1(x_{i+1/2,j+1}, \rho_{i,j+1}^n, \rho_{i+1,j+1}^n) + F(\rho_{i,j+1}^n, \rho_{i+1,j+1}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad - V_1(x_{i-1/2,j+1}, \rho_{i-1,j+1}^n, \rho_{i,j+1}^n) - F(\rho_{i-1,j+1}^n, \rho_{i,j+1}^n, J_1^n(x_{i-1/2,j+1})) \\ &\quad - V_1(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) - F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j})) \\ &\quad + V_1(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n) + F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j}))] \\ &\quad \pm \lambda_x [V_1(x_{i+1/2,j+1}, \rho_{i,j}^n, \rho_{i+1,j}^n) + F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad - V_1(x_{i-1/2,j+1}, \rho_{i-1,j}^n, \rho_{i,j}^n) - F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j+1}))] \\ &= \mathcal{D}_{i,j}^n + \lambda_x \mathcal{E}_{i,j}^n, \end{aligned}$$

where we set

$$\begin{aligned} \mathcal{D}_{i,j}^n &= \rho_{i,j+1}^n - \rho_{i,j}^n - \lambda_x [V_1(x_{i+1/2,j+1}, \rho_{i,j+1}^n, \rho_{i+1,j+1}^n) + F(\rho_{i,j+1}^n, \rho_{i+1,j+1}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad - V_1(x_{i+1/2,j+1}, \rho_{i,j}^n, \rho_{i+1,j}^n) - F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad + V_1(x_{i-1/2,j+1}, \rho_{i-1,j}^n, \rho_{i,j}^n) + F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j+1})) \\ &\quad - V_1(x_{i-1/2,j+1}, \rho_{i-1,j+1}^n, \rho_{i,j+1}^n) - F(\rho_{i-1,j+1}^n, \rho_{i,j+1}^n, J_1^n(x_{i-1/2,j+1}))], \\ \mathcal{E}_{i,j}^n &= V_1(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) + F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j})) \\ &\quad - V_1(x_{i+1/2,j+1}, \rho_{i,j}^n, \rho_{i+1,j}^n) - F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad + V_1(x_{i-1/2,j+1}, \rho_{i-1,j}^n, \rho_{i,j}^n) + F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j+1})) \\ &\quad - V_1(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n) - F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j})). \end{aligned}$$

Similarly as before, rearrange $\mathcal{D}_{i,j}^n$, exploiting the notation (3.18):

$$\begin{aligned} \mathcal{D}_{i,j}^n &= \rho_{i,j+1}^n - \rho_{i,j}^n - \lambda_x \left[H_{i+1/2,j+1}^n(\rho_{i,j+1}^n, \rho_{i+1,j+1}^n) - H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j}^n) \right. \\ &\quad \left. + H_{i-1/2,j+1}^n(\rho_{i-1,j}^n, \rho_{i,j}^n) - H_{i-1/2,j+1}^n(\rho_{i-1,j+1}^n, \rho_{i,j+1}^n) \right] \\ &\quad \pm \lambda_x H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j+1}^n) \pm \lambda_x H_{i-1/2,j+1}^n(\rho_{i-1,j}^n, \rho_{i,j+1}^n) \\ &= \rho_{i,j+1}^n - \rho_{i,j}^n - \lambda_x \frac{H_{i+1/2,j+1}^n(\rho_{i,j+1}^n, \rho_{i+1,j+1}^n) - H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j+1}^n)}{\rho_{i,j+1}^n - \rho_{i,j}^n} (\rho_{i,j+1}^n - \rho_{i,j}^n) \\ &\quad - \lambda_x \frac{H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j+1}^n) - H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j}^n)}{\rho_{i+1,j+1}^n - \rho_{i+1,j}^n} (\rho_{i+1,j+1}^n - \rho_{i+1,j}^n) \\ &\quad + \lambda_x \frac{H_{i-1/2,j+1}^n(\rho_{i-1,j}^n, \rho_{i,j+1}^n) - H_{i-1/2,j+1}^n(\rho_{i-1,j}^n, \rho_{i,j}^n)}{\rho_{i,j+1}^n - \rho_{i,j}^n} (\rho_{i,j+1}^n - \rho_{i,j}^n) \\ &\quad + \lambda_x \frac{H_{i-1/2,j+1}^n(\rho_{i-1,j+1}^n, \rho_{i,j+1}^n) - H_{i-1/2,j+1}^n(\rho_{i-1,j}^n, \rho_{i,j+1}^n)}{\rho_{i-1,j+1}^n - \rho_{i-1,j}^n} (\rho_{i-1,j+1}^n - \rho_{i-1,j}^n) \\ &= (1 - \kappa_{i,j}^n - \nu_{i,j}^n)(\rho_{i,j+1}^n - \rho_{i,j}^n) + \nu_{i+1,j}^n(\rho_{i+1,j+1}^n - \rho_{i+1,j}^n) + \kappa_{i-1,j}^n(\rho_{i-1,j+1}^n - \rho_{i-1,j}^n), \end{aligned}$$

where

$$\begin{aligned} \kappa_{i,j}^n &= \begin{cases} \lambda_x \frac{H_{i+1/2,j+1}^n(\rho_{i,j+1}^n, \rho_{i+1,j+1}^n) - H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j+1}^n)}{\rho_{i,j+1}^n - \rho_{i,j}^n} & \text{if } \rho_{i,j+1}^n \neq \rho_{i,j}^n, \\ 0 & \text{if } \rho_{i,j+1}^n = \rho_{i,j}^n, \end{cases} \\ \nu_{i,j}^n &= \begin{cases} -\lambda_x \frac{H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j+1}^n) - H_{i+1/2,j+1}^n(\rho_{i,j}^n, \rho_{i+1,j}^n)}{\rho_{i+1,j+1}^n - \rho_{i+1,j}^n} & \text{if } \rho_{i+1,j+1}^n \neq \rho_{i+1,j}^n, \\ 0 & \text{if } \rho_{i+1,j+1}^n = \rho_{i+1,j}^n. \end{cases} \end{aligned}$$

As for δ_i^n (3.19) and ϑ_i^n (3.20), it is immediate to prove that $\kappa_{i,j}^n, \nu_{i,j}^n \in \left[0, \frac{1}{3}\right]$ for all $i, j \in \mathbb{Z}$. Hence,

$$\sum_{i,j \in \mathbb{Z}} |\mathcal{D}_{i,j}^n| \leq \sum_{i,j \in \mathbb{Z}} |\rho_{i,j+1}^n - \rho_{i,j}^n|. \quad (3.27)$$

Pass now to $\mathcal{E}_{i,j}^n$: we can proceed analogously to $\mathcal{B}_{i,j}^n$, treating separately the terms involving V_1 and those involving F . First, by (3.2),

$$\begin{aligned} & V_1(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) - V_1(x_{i+1/2,j+1}, \rho_{i,j}^n, \rho_{i+1,j}^n) + V_1(x_{i-1/2,j+1}, \rho_{i-1,j}^n, \rho_{i,j}^n) - V_1(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n) \\ &= v_1^{\text{stat}}(x_{i+1/2,j})\rho_{i,j}^n + \min\{0, v_1^{\text{stat}}(x_{i+1/2,j})\}(\rho_{i+1,j}^n - \rho_{i,j}^n) \\ &\quad - v_1^{\text{stat}}(x_{i+1/2,j+1})\rho_{i,j}^n - \min\{0, v_1^{\text{stat}}(x_{i+1/2,j+1})\}(\rho_{i+1,j}^n - \rho_{i,j}^n) \\ &\quad + v_1^{\text{stat}}(x_{i-1/2,j+1})\rho_{i-1,j}^n + \min\{0, v_1^{\text{stat}}(x_{i-1/2,j+1})\}(\rho_{i,j}^n - \rho_{i-1,j}^n) \\ &\quad - v_1^{\text{stat}}(x_{i-1/2,j})\rho_{i-1,j}^n - \min\{0, v_1^{\text{stat}}(x_{i-1/2,j})\}(\rho_{i,j}^n - \rho_{i-1,j}^n) \\ &\quad \pm (v_1^{\text{stat}}(x_{i-1/2,j+1}) - v_1^{\text{stat}}(x_{i-1/2,j}))\rho_{i,j}^n \\ &= (v_1^{\text{stat}}(x_{i+1/2,j}) - v_1^{\text{stat}}(x_{i+1/2,j+1}) - v_1^{\text{stat}}(x_{i-1/2,j}) + v_1^{\text{stat}}(x_{i-1/2,j+1}))\rho_{i,j}^n \\ &\quad + (v_1^{\text{stat}}(x_{i-1/2,j+1}) - v_1^{\text{stat}}(x_{i-1/2,j}))(\rho_{i-1,j}^n - \rho_{i,j}^n) \\ &\quad + (\min\{0, v_1^{\text{stat}}(x_{i+1/2,j})\} - \min\{0, v_1^{\text{stat}}(x_{i+1/2,j+1})\})(\rho_{i+1,j}^n - \rho_{i,j}^n) \\ &\quad + (\min\{0, v_1^{\text{stat}}(x_{i-1/2,j+1})\} - \min\{0, v_1^{\text{stat}}(x_{i-1/2,j})\})(\rho_{i,j}^n - \rho_{i-1,j}^n) \\ &\leq \Delta x \Delta y \|\partial_{xy}^2 v_1^{\text{stat}}\|_{L^\infty} |\rho_{i,j}^n| + \Delta y \|\partial_y v_1^{\text{stat}}\|_{L^\infty} (|\rho_{i+1,j}^n - \rho_{i,j}^n| + 2|\rho_{i,j}^n - \rho_{i-1,j}^n|), \end{aligned} \quad (3.28)$$

since

$$\begin{aligned} v_1^{\text{stat}}(x_{i+1/2,j}) - v_1^{\text{stat}}(x_{i+1/2,j+1}) - v_1^{\text{stat}}(x_{i-1/2,j}) + v_1^{\text{stat}}(x_{i-1/2,j+1}) &= \Delta x \partial_x v_1^{\text{stat}}(\xi_i, y_j) - \Delta x \partial_x v_1^{\text{stat}}(\xi_i, y_{j+1}) \\ &= -\Delta x \Delta y \partial_{xy}^2 v_1^{\text{stat}}(\xi_i, \zeta_{j+1/2}), \end{aligned}$$

with $\xi_i \in]x_{i-1/2}, x_{i+1/2}[$ and $\zeta_{j+1/2} \in]y_j, y_{j+1}[$. In a similar way, by (3.3),

$$\begin{aligned} & F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j})) - F(\rho_{i,j}^n, \rho_{i+1,j}^n, J_1^n(x_{i+1/2,j+1})) \\ &\quad + F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j+1})) - F(\rho_{i-1,j}^n, \rho_{i,j}^n, J_1^n(x_{i-1/2,j})) \\ &= J_1^n(x_{i+1/2,j}) f(\rho_{i,j}^n) + \min\{0, J_1^n(x_{i+1/2,j})\} (f(\rho_{i+1,j}^n) - f(\rho_{i,j}^n)) \\ &\quad - J_1^n(x_{i+1/2,j+1}) f(\rho_{i,j}^n) - \min\{0, J_1^n(x_{i+1/2,j+1})\} (f(\rho_{i+1,j}^n) - f(\rho_{i,j}^n)) \\ &\quad + J_1^n(x_{i-1/2,j+1}) f(\rho_{i-1,j}^n) + \min\{0, J_1^n(x_{i-1/2,j+1})\} (f(\rho_{i,j}^n) - f(\rho_{i-1,j}^n)) \\ &\quad - J_1^n(x_{i-1/2,j}) f(\rho_{i-1,j}^n) - \min\{0, J_1^n(x_{i-1/2,j})\} (f(\rho_{i,j}^n) - f(\rho_{i-1,j}^n)) \\ &\quad \pm (J_1^n(x_{i-1/2,j+1}) - J_1^n(x_{i-1/2,j})) f(\rho_{i,j}^n) \\ &= (J_1^n(x_{i+1/2,j}) - J_1^n(x_{i+1/2,j+1}) - J_1^n(x_{i-1/2,j}) + J_1^n(x_{i-1/2,j+1})) f(\rho_{i,j}^n) \\ &\quad + (J_1^n(x_{i-1/2,j+1}) - J_1^n(x_{i-1/2,j})) (f(\rho_{i-1,j}^n) - f(\rho_{i,j}^n)) \\ &\quad + (\min\{0, J_1^n(x_{i+1/2,j})\} - \min\{0, J_1^n(x_{i+1/2,j+1})\}) (f(\rho_{i+1,j}^n) - f(\rho_{i,j}^n)) \\ &\quad + (\min\{0, J_1^n(x_{i-1/2,j+1})\} - \min\{0, J_1^n(x_{i-1/2,j})\}) (f(\rho_{i,j}^n) - f(\rho_{i-1,j}^n)) \\ &\leq 2\varepsilon \Delta x \Delta y C |\rho_i^n| + 2\varepsilon L_f \Delta y \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1} (|\rho_{i+1,j}^n - \rho_{i,j}^n| + 2|\rho_{i,j}^n + \rho_{i-1,j}^n|), \end{aligned} \quad (3.30)$$

where we used the fact that $f(r) \leq r$, (A.3) and (A.5), with the notation (A.6). Therefore, collecting together (3.29) and (3.30), we get

$$\begin{aligned} |\mathcal{E}_{i,j}^n| &\leq \Delta x \Delta y \left(\|\partial_{xy}^2 v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon C \right) |\rho_i^n| \\ &\quad + \Delta y \left(\|\partial_y v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1} \right) (|\rho_{i+1,j}^n - \rho_{i,j}^n| + 2|\rho_{i,j}^n + \rho_{i-1,j}^n|), \end{aligned}$$

so that

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \lambda_x |\mathcal{E}_{i,j}^n| &\leq 3 \lambda_x \Delta y (\|\partial_y v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \sum_{i,j \in \mathbb{Z}} |\rho_{i+1,j}^n - \rho_{i,j}^n| \\ &\quad + \Delta t \left(\|\partial_{xy}^2 v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon C \right) \Delta y \sum_{i,j \in \mathbb{Z}} \rho_{i,j}^n. \end{aligned} \quad (3.31)$$

Hence, by (3.27) and (3.31), using also Lemma 3.3, we obtain

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \Delta x \left| \rho_{i,j+1}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| &\leq \sum_{i,j \in \mathbb{Z}} \Delta x (|\mathcal{D}_{i,j}^n| + \lambda_x |\mathcal{E}_{i,j}^n|) \\ &\leq \sum_{i,j \in \mathbb{Z}} \Delta x |\rho_{i,j+1}^n - \rho_{i,j}^n| \\ &\quad + 3 \Delta t (\|\partial_y v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \sum_{i,j \in \mathbb{Z}} \Delta y |\rho_{i+1,j}^n - \rho_{i,j}^n| \\ &\quad + \Delta t \left(\|\partial_{xy}^2 v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon C \right) \|\rho_o\|_{L^1}. \end{aligned} \quad (3.32)$$

Setting

$$K_1 = 3 (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + \|\partial_y v_1^{\text{stat}}\|_{L^\infty} + 4\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}), \quad (3.33)$$

$$K_2 = (4\varepsilon C + 2 \|\partial_{xx}^2 v_1^{\text{stat}}\|_{L^\infty} + \|\partial_{xy}^2 v_1^{\text{stat}}\|_{L^\infty}) \|\rho_o\|_{L^1}, \quad (3.34)$$

by (3.26) and (3.32) we conclude

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \left(\Delta y \left| \rho_{i+1,j}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| + \Delta x \left| \rho_{i,j+1}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| \right) \\ \leq (1 + \Delta t K_1) \sum_{i,j \in \mathbb{Z}} (\Delta x |\rho_{i,j+1}^n - \rho_{i,j}^n| + \Delta y |\rho_{i+1,j}^n - \rho_{i,j}^n|) + \Delta t K_2. \end{aligned}$$

Analogous computations yield

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} (\Delta y |\rho_{i+1,j}^{n+1} - \rho_{i,j}^{n+1}| + \Delta x |\rho_{i,j+1}^{n+1} - \rho_{i,j}^{n+1}|) \\ \leq (1 + \Delta t K_3) \sum_{i,j \in \mathbb{Z}} \left(\Delta x \left| \rho_{i,j+1}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| + \Delta y \left| \rho_{i+1,j}^{n+1/2} - \rho_{i,j}^{n+1/2} \right| \right) + \Delta t K_4, \end{aligned}$$

where

$$K_3 = 3 (\|\partial_x v_2^{\text{stat}}\|_{L^\infty} + \|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 4\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}), \quad (3.35)$$

$$K_4 = (4\varepsilon C + 2 \|\partial_{yy}^2 v_2^{\text{stat}}\|_{L^\infty} + \|\partial_{xy}^2 v_2^{\text{stat}}\|_{L^\infty}) \|\rho_o\|_{L^1}. \quad (3.36)$$

Observe that, using the notation (3.16) and (3.17),

$$K_1, K_3 \leq \mathcal{K}_1, \quad K_2, K_4 \leq \mathcal{K}_2.$$

A recursive argument yields the desired result:

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} (\Delta y |\rho_{i+1,j}^n - \rho_{i,j}^n| + \Delta x |\rho_{i,j+1}^n - \rho_{i,j}^n|) \\ \leq e^{2n \Delta t \mathcal{K}_1} \sum_{i,j \in \mathbb{Z}} (\Delta x |\rho_{i,j+1}^0 - \rho_{i,j}^0| + \Delta y |\rho_{i+1,j}^0 - \rho_{i,j}^0|) + \frac{2\mathcal{K}_2}{\mathcal{K}_1} (e^{2n \Delta t \mathcal{K}_1} - 1). \end{aligned}$$

□

Corollary 3.7 (BV estimate in space and time). *Let $\rho_o \in (\mathrm{L}^\infty \cap \mathrm{BV})(\mathbb{R}^2; \mathbb{R}^+)$. Let (v) , (H) , (η) , (3.13) hold. Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 3.1 satisfies the following estimate: for all $n = 1, \dots, N_T$,*

$$\sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta t (\Delta y |\rho_{i+1,j}^m - \rho_{i,j}^m| + \Delta x |\rho_{i,j+1}^m - \rho_{i,j}^m|) + \sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta x \Delta y |\rho_{i,j}^{m+1} - \rho_{i,j}^m| \leq \mathcal{C}_{xt}(t^n), \quad (3.37)$$

where

$$\mathcal{C}_{xt}(t) = t (\mathcal{C}_x(t) + 2 \mathcal{C}_t(t)), \quad (3.38)$$

with \mathcal{C}_x as in (3.15) and \mathcal{C}_t as in (3.40).

Proof. By Proposition 3.5 we have

$$\sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta t (\Delta y |\rho_{i+1,j}^m - \rho_{i,j}^m| + \Delta x |\rho_{i,j+1}^m - \rho_{i,j}^m|) \leq n \Delta t \mathcal{C}_x(n \Delta t). \quad (3.39)$$

Since

$$|\rho_{i,j}^{m+1} - \rho_{i,j}^m| \leq \left| \rho_{i,j}^{m+1} - \rho_{i,j}^{m+1/2} \right| + \left| \rho_{i,j}^{m+1/2} - \rho_{i,j}^m \right|,$$

we focus first on

$$\sum_{i,j \in \mathbb{Z}} \Delta x \Delta y \left| \rho_{i,j}^{m+1/2} - \rho_{i,j}^m \right|.$$

By the scheme (3.5), we have, using the notation (3.8),

$$\begin{aligned} \rho_{i,j}^{m+1/2} - \rho_{i,j}^m &= -\lambda_x [V_1(x_{i+1/2,j}, \rho_{i,j}^m, \rho_{i+1,j}^m) + F(\rho_{i,j}^m, \rho_{i+1,j}^m, J_1^m(x_{i+1/2,j})) \\ &\quad - V_1(x_{i-1/2,j}, \rho_{i-1,j}^m, \rho_{i,j}^m) - F(\rho_{i-1,j}^m, \rho_{i,j}^m, J_1^m(x_{i-1/2,j}))] \\ &= -\lambda_x [v_{i+1/2,j} \rho_{i,j}^m + \min \{0, v_{i+1/2,j}\} (\rho_{i+1,j}^m - \rho_{i,j}^m) \\ &\quad - v_{i-1/2,j} \rho_{i-1,j}^m - \min \{0, v_{i-1/2,j}\} (\rho_{i,j}^m - \rho_{i-1,j}^m) \\ &\quad + J_1^m(x_{i+1/2,j}) f(\rho_{i,j}^m) + \min \{0, J_1^m(x_{i+1/2,j})\} (f(\rho_{i+1,j}^m) - f(\rho_{i,j}^m)) \\ &\quad - J_1^m(x_{i-1/2,j}) f(\rho_{i-1,j}^m) - \min \{0, J_1^m(x_{i-1/2,j})\} (f(\rho_{i,j}^m) - f(\rho_{i-1,j}^m)) \\ &\quad \pm v_{i-1/2,j} \rho_{i,j}^m \pm J_1^m(x_{i-1/2,j}) f(\rho_{i,j}^m)] \\ &= -\lambda_x [\Delta x \partial_x v_1^{\text{stat}}(\xi_i, y_j) \rho_{i,j}^m + (v_{i-1/2,j} - \min \{0, v_{i-1/2,j}\}) (\rho_{i,j}^m - \rho_{i-1,j}^m) \\ &\quad + \min \{0, v_{i+1/2,j}\} (\rho_{i+1,j}^m - \rho_{i,j}^m) + (J_1^m(x_{i+1/2,j}) - J_1^m(x_{i-1/2,j})) f(\rho_{i,j}^m) \\ &\quad + (J_1^m(x_{i-1/2,j}) - \min \{0, J_1^m(x_{i-1/2,j})\}) (f(\rho_{i,j}^m) - f(\rho_{i-1,j}^m)) \\ &\quad + \min \{0, J_1^m(x_{i+1/2,j})\} (f(\rho_{i+1,j}^m) - f(\rho_{i,j}^m))] \\ &\leq \Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \rho_{i,j}^m \\ &\quad + \lambda_x (\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) (|\rho_{i,j}^m - \rho_{i-1,j}^m| + |\rho_{i+1,j}^m - \rho_{i,j}^m|), \end{aligned}$$

where $\xi_i \in]x_{i-1/2}, x_{i+1/2}[$ and we used $f(r) \leq r$, (A.1) and (A.2). Therefore,

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \Delta x \Delta y \left| \rho_{i,j}^{m+1/2} - \rho_{i,j}^m \right| &\leq 2 \Delta t (\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) \sum_{i,j \in \mathbb{Z}} \Delta y |\rho_{i+1,j}^m - \rho_{i,j}^m| \\ &\quad + \Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \|\rho_o\|_{L^1} \\ &\leq 2 \Delta t (\|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) \mathcal{C}_x(m \Delta t) \\ &\quad + \Delta t (\|\partial_x v_1^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \|\rho_o\|_{L^1} \\ &\leq \Delta t \mathcal{C}_t(m \Delta t), \end{aligned}$$

where we set

$$\mathcal{C}_t(s) = 2 (\|v^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) \mathcal{C}_x(s) + (\|\nabla v^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \|\rho_o\|_{L^1}. \quad (3.40)$$

Analogously, we get

$$\begin{aligned} \sum_{i,j \in \mathbb{Z}} \Delta x \Delta y |\rho_{i,j}^{m+1} - \rho_{i,j}^{m+1/2}| &\leq 2 \Delta t (\|v_2^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) \sum_{i,j \in \mathbb{Z}} \Delta x |\rho_{i,j+1}^{m+1/2} - \rho_{i,j}^{m+1/2}| \\ &\quad + \Delta t (\|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \|\rho_o\|_{L^1} \\ &\leq 2 \Delta t (\|v_2^{\text{stat}}\|_{L^\infty} + \varepsilon L_f) \mathcal{C}_x(m \Delta t) \\ &\quad + \Delta t (\|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 2\varepsilon \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}) \|\rho_o\|_{L^1} \\ &\leq \Delta t \mathcal{C}_t(m \Delta t). \end{aligned}$$

Hence

$$\sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta x \Delta y |\rho_{i,j}^{m+1} - \rho_{i,j}^m| \leq 2n \Delta t \mathcal{C}_t(n \Delta t), \quad (3.41)$$

which together with (3.39) completes the proof. \square

3.5. Discrete entropy inequalities

Following [1], see also [7, 8], introduce the following notation: for $i, j \in \mathbb{Z}$, $n = 0, \dots, N_T - 1$ and $\kappa \in \mathbb{R}$,

$$\begin{aligned} \Phi_{i+1/2,j}^n(u, v) &= V_1(x_{i+1/2,j}, u \vee \kappa, v \vee \kappa) + F(u \vee \kappa, v \vee \kappa, J_1^n(x_{i+1/2,j})) \\ &\quad - V_1(x_{i+1/2,j}, u \wedge \kappa, v \wedge \kappa) - F(u \wedge \kappa, v \wedge \kappa, J_1^n(x_{i+1/2,j})), \\ \Gamma_{i,j+1/2}^n(u, v) &= V_2(x_{i,j+1/2}, u \vee \kappa, v \vee \kappa) + F(u \vee \kappa, v \vee \kappa, J_2^n(x_{i,j+1/2})) \\ &\quad - V_2(x_{i,j+1/2}, u \wedge \kappa, v \wedge \kappa) - F(u \wedge \kappa, v \wedge \kappa, J_2^n(x_{i,j+1/2})), \end{aligned}$$

with V_1 , V_2 and F defined as in (3.2), (3.4) and (3.3) respectively.

Lemma 3.8 (Discrete entropy condition). *Fix $\rho_o \in (L^\infty \cap BV)(\mathbb{R}^2; \mathbb{R}^+)$. Let (v) , (H) , (η) , (3.13) hold. Then, the solution ρ_Δ in (3.1) constructed through Algorithm 3.1 satisfies the following discrete entropy inequality: for $i, j \in \mathbb{Z}$, for $n = 0, \dots, N_T - 1$ and $\kappa \in \mathbb{R}$,*

$$\begin{aligned} |\rho_{i,j}^{n+1} - \kappa| - |\rho_{i,j}^n - \kappa| &+ \lambda_x \left(\Phi_{i+1/2,j}^n(\rho_{i,j}^n, \rho_{i+1,j}^n) - \Phi_{i-1/2,j}^n(\rho_{i-1,j}^n, \rho_{i,j}^n) \right) \\ &+ \lambda_x \operatorname{sgn}(\rho_{i,j}^{n+1/2} - \kappa) (v_1^{\text{stat}}(x_{i+1/2,j}) - v_1^{\text{stat}}(x_{i-1/2,j})) \kappa \\ &+ \lambda_x \operatorname{sgn}(\rho_{i,j}^{n+1/2} - \kappa) (J_1^n(x_{i+1/2,j}) - J_1^n(x_{i-1/2,j})) f(\kappa) \\ &+ \lambda_y \left(\Gamma_{i,j+1/2}^n(\rho_{i,j}^{n+1/2}, \rho_{i,j+1}^{n+1/2}) - \Gamma_{i,j-1/2}^n(\rho_{i,j-1}^{n+1/2}, \rho_{i,j}^{n+1/2}) \right) \\ &+ \lambda_y \operatorname{sgn}(\rho_{i,j}^{n+1} - \kappa) (v_2^{\text{stat}}(x_{i,j+1/2}) - v_2^{\text{stat}}(x_{i,j-1/2})) \kappa \\ &+ \lambda_y \operatorname{sgn}(\rho_{i,j}^{n+1} - \kappa) (J_2^n(x_{i,j+1/2}) - J_2^n(x_{i,j-1/2})) f(\kappa) \leq 0. \end{aligned}$$

The proof is omitted, being entirely analogous to that of Proposition 2.8 from [2], see also Lemma 2.8 of [1].

4. LIPSCHITZ CONTINUOUS DEPENDENCE ON INITIAL DATA

Proposition 4.1. *Fix $T > 0$. Let (v) , (H) and (η) hold. Let $\rho_o, \sigma_o \in (L^\infty \cap BV)(\mathbb{R}^2; \mathbb{R}^+)$. Call ρ and σ the corresponding solutions to (1.1). Then the following estimate holds:*

$$\|\rho(t) - \sigma(t)\|_{L^1(\mathbb{R}^2)} \leq \|\rho_o - \sigma_o\|_{L^1(\mathbb{R}^2)} e^{t A(t)}.$$

with $A(t)$ defined in (4.2).

Proof. In the rest of the proof, to avoid heavy notation, we will denote pairs in \mathbb{R}^2 by \mathbf{x} or \mathbf{y} . Introduce the following notation:

$$\mathbf{R}(t, \mathbf{x}) = (\mathbf{I}(\rho(t)))(\mathbf{x}), \quad \mathbf{S}(t, \mathbf{x}) = (\mathbf{I}(\sigma(t)))(\mathbf{x}). \quad (4.1)$$

The idea is to apply the *doubling of variables method* introduced by Kružkov in [13], exploiting in particular the proof of Lemma 4 from [4]. There, a flux of the form $f(t, x, \rho) V(t, x)$ is taken into account, with $x \in \mathbb{R}$, the proof being valid also in the multidimensional case, i.e. $x \in \mathbb{R}^n$. Therefore we are going to use this result for what concerns the part of the flux of type $f(\rho) \mathbf{R}(t, \mathbf{x})$.

For the sake of completeness, we recall that a flux function of type $l(x) g(\rho)$ is considered in [10], with $x \in \mathbb{R}^n$, and the proof of Lemma 4 from [4] follows the lines of that of Theorem 1.3 from [10]. Thus, here we are adding the dependence on time to the function $l(x)$ considered in [10].

Let $\varphi \in C_c^1(]0, T[\times \mathbb{R}^2; \mathbb{R}^+)$ be a test function as in the definition of solution by Kružkov. Let $Y \in C_c^\infty(\mathbb{R}; \mathbb{R}^+)$ be such that

$$Y(z) = Y(-z), \quad Y(z) = 0 \text{ for } |z| \geq 1, \quad \int_{\mathbb{R}} Y(z) dz = 1.$$

Define, for $h > 0$, $Y_h(z) = \frac{1}{h} Y(\frac{z}{h})$. Clearly, $Y_h \in C_c^\infty(\mathbb{R}; \mathbb{R}^+)$, $Y_h(z) = Y_h(-z)$, $Y_h(z) = 0$ for $|z| \geq h$, $\int_{\mathbb{R}} Y_h(z) dz = 1$ and $Y_h \rightarrow \delta_0$ as $h \rightarrow 0$, δ_0 being the Dirac delta in 0. Define moreover

$$\psi_h(t, \mathbf{x}, s, \mathbf{y}) = \varphi \left(\frac{t+s}{2}, \frac{\mathbf{x}+\mathbf{y}}{2} \right) Y_h(t-s) \prod_{i=1}^2 Y_h(x_i - y_i).$$

Introduce the space $\Pi_T =]0, T[\times \mathbb{R}^2$ and, from the definition of solution, derive the following entropy inequalities for $\rho = \rho(t, \mathbf{x})$ and $\sigma = \sigma(s, \mathbf{y})$:

$$\begin{aligned} & \iiint_{\Pi_T \times \Pi_T} \{ |\rho - \sigma| \partial_t \psi_h + |\rho - \sigma| \nabla_{\mathbf{x}} \mathbf{v}^{\text{stat}}(\mathbf{x}) \cdot \nabla_{\mathbf{x}} \psi_h + \text{sgn}(\rho - \sigma) (f(\rho) - f(\sigma)) \mathbf{R}(t, \mathbf{x}) \cdot \nabla_{\mathbf{x}} \psi_h \\ & \quad - \text{sgn}(\rho - \sigma) \sigma \operatorname{div}_{\mathbf{x}} \mathbf{v}^{\text{stat}}(\mathbf{x}) \psi_h - \text{sgn}(\rho - \sigma) f(\sigma) \operatorname{div}_{\mathbf{x}} \mathbf{R}(t, \mathbf{x}) \psi_h \} d\mathbf{x} dt d\mathbf{y} ds \geq 0, \\ & \iiint_{\Pi_T \times \Pi_T} \{ |\sigma - \rho| \partial_s \psi_h + |\sigma - \rho| \nabla_{\mathbf{y}} \mathbf{v}^{\text{stat}}(\mathbf{y}) \cdot \nabla_{\mathbf{y}} \psi_h + \text{sgn}(\sigma - \rho) (f(\sigma) - f(\rho)) \mathbf{S}(s, \mathbf{y}) \cdot \nabla_{\mathbf{y}} \psi_h \\ & \quad - \text{sgn}(\sigma - \rho) \rho \operatorname{div}_{\mathbf{y}} \mathbf{v}^{\text{stat}}(\mathbf{y}) \psi_h - \text{sgn}(\sigma - \rho) f(\rho) \operatorname{div}_{\mathbf{y}} \mathbf{S}(s, \mathbf{y}) \psi_h \} d\mathbf{x} dt d\mathbf{y} ds \geq 0. \end{aligned}$$

Sum the two inequalities above and rearrange the terms therein, following the proof of Theorem 1 from [13] for what concerns the linear part of the flux and the proof of Lemma 4 from [4], see also Theorem 1.3 of [10], for the other part:

$$\begin{aligned} & \iiint_{\Pi_T \times \Pi_T} \{ |\rho - \sigma| (\partial_t \psi_h + \partial_s \psi_h) + \text{sgn}(\rho - \sigma) (\rho \mathbf{v}^{\text{stat}}(\mathbf{x}) - \sigma \mathbf{v}^{\text{stat}}(\mathbf{y})) \cdot (\nabla_{\mathbf{x}} \psi_h + \nabla_{\mathbf{y}} \psi_h) \\ & \quad + \text{sgn}(\rho - \sigma) \sigma [(\mathbf{v}^{\text{stat}}(\mathbf{y}) - \mathbf{v}^{\text{stat}}(\mathbf{x})) \cdot \nabla_{\mathbf{x}} \psi_h - \operatorname{div}_{\mathbf{x}} \mathbf{v}^{\text{stat}}(\mathbf{x}) \psi_h] \\ & \quad + \text{sgn}(\rho - \sigma) \rho [(\mathbf{v}^{\text{stat}}(\mathbf{y}) - \mathbf{v}^{\text{stat}}(\mathbf{x})) \cdot \nabla_{\mathbf{y}} \psi_h + \operatorname{div}_{\mathbf{y}} \mathbf{v}^{\text{stat}}(\mathbf{y}) \psi_h] \\ & \quad + \text{sgn}(\rho - \sigma) (f(\rho) \mathbf{R}(t, \mathbf{x}) - f(\sigma) \mathbf{S}(s, \mathbf{y})) \cdot (\nabla_{\mathbf{x}} \psi_h + \nabla_{\mathbf{y}} \psi_h) \\ & \quad + \text{sgn}(\rho - \sigma) f(\sigma) [(\mathbf{S}(s, \mathbf{y}) - \mathbf{R}(t, \mathbf{x})) \cdot \nabla_{\mathbf{x}} \psi_h - \operatorname{div}_{\mathbf{x}} \mathbf{R}(t, \mathbf{x}) \psi_h] \\ & \quad + \text{sgn}(\rho - \sigma) f(\rho) [(\mathbf{S}(s, \mathbf{y}) - \mathbf{R}(t, \mathbf{x})) \cdot \nabla_{\mathbf{y}} \psi_h + \operatorname{div}_{\mathbf{y}} \mathbf{S}(s, \mathbf{y}) \psi_h] \} d\mathbf{x} dt d\mathbf{y} ds \geq 0. \end{aligned}$$

Let $h \rightarrow 0$, which gives

$$\begin{aligned} & \iint_{\Pi_T} \left\{ |\rho - \sigma| \partial_t \varphi + \operatorname{sgn}(\rho - \sigma) [(\rho - \sigma) \mathbf{v}^{\text{stat}}(\mathbf{x}) + \mathbf{S}(t, \mathbf{x})(f(\rho) - f(\sigma))] \cdot \nabla_{\mathbf{x}} \varphi \right. \\ & \quad \left. + \operatorname{sgn}(\rho - \sigma) f(\rho) \operatorname{div}_{\mathbf{x}} (\mathbf{S}(t, \mathbf{x}) - \mathbf{R}(t, \mathbf{x})) \varphi \right. \\ & \quad \left. + \operatorname{sgn}(\rho - \sigma) f'(\rho) (\mathbf{S}(t, \mathbf{x}) - \mathbf{R}(t, \mathbf{x})) \partial_x \rho(t, \mathbf{x}) \varphi \right\} d\mathbf{x} dt dy ds \geq 0. \end{aligned}$$

Choosing a suitable test function φ leads to

$$\begin{aligned} & \int_{\mathbb{R}^2} |\rho(t, \mathbf{x}) - \sigma(t, \mathbf{x})| d\mathbf{x} - \int_{\mathbb{R}^2} |\rho(\tau, \mathbf{x}) - \sigma(\tau, \mathbf{x})| d\mathbf{x} + \int_{\tau}^t \int_{\mathbb{R}^2} |\operatorname{div}(\mathbf{S}(s, \mathbf{x}) - \mathbf{R}(s, \mathbf{x}))| f(\rho(s, \mathbf{x})) d\mathbf{x} ds \\ & \quad + \int_{\tau}^t L_f \|\mathbf{S}(s) - \mathbf{R}(s)\|_{L^\infty(\mathbb{R}^2)} \operatorname{TV}(\rho(s)) ds \geq 0. \end{aligned}$$

Observe that, following Lemma 4.1 of [5], the following bounds hold

$$\begin{aligned} \|\mathbf{S}(s) - \mathbf{R}(s)\|_{L^\infty(\mathbb{R}^2)} & \leq 2\varepsilon \|\nabla \eta\|_{L^\infty} \|\rho(s) - \sigma(s)\|_{L^1(\mathbb{R}^2)}, \\ \|\operatorname{div}(\mathbf{S}(s) - \mathbf{R}(s))\|_{L^\infty(\mathbb{R}^2)} & \leq \varepsilon \|\rho(s) - \sigma(s)\|_{L^1(\mathbb{R}^2)} \|\Delta \eta\|_{L^\infty} \left(1 + \|\sigma(s)\|_{L^1(\mathbb{R}^2)} \|\nabla \eta\|_{L^1} \right). \end{aligned}$$

Thus, letting $\tau \rightarrow 0$ and exploiting the bounds on ρ and σ given by Theorem 2.2, as well as $f(r) \leq r$, we get

$$\begin{aligned} \int_{\mathbb{R}^2} |\rho(t, \mathbf{x}) - \sigma(t, \mathbf{x})| d\mathbf{x} & \leq \int_{\mathbb{R}^2} |\rho_o(\mathbf{x}) - \sigma_o(\mathbf{x})| d\mathbf{x} + 2\varepsilon \|\nabla \eta\|_{L^\infty} \|\rho_o\|_{L^1(\mathbb{R}^2)} \int_0^t \int_{\mathbb{R}^2} |\rho(s, \mathbf{x}) - \sigma(s, \mathbf{x})| d\mathbf{x} ds \\ & \quad + \varepsilon L_f \|\Delta \eta\|_{L^\infty} \left(1 + \|\sigma_o\|_{L^1(\mathbb{R}^2)} \|\nabla \eta\|_{L^1} \right) \\ & \quad \times \int_0^t \operatorname{TV}(\rho(s)) \left(\int_{\mathbb{R}^2} |\rho(s, \mathbf{x}) - \sigma(s, \mathbf{x})| d\mathbf{x} \right) ds \\ & = \int_{\mathbb{R}^2} |\rho_o(\mathbf{x}) - \sigma_o(\mathbf{x})| d\mathbf{x} + \int_0^t A(s) \left(\int_{\mathbb{R}^2} |\rho(s, \mathbf{x}) - \sigma(s, \mathbf{x})| d\mathbf{x} \right) ds, \end{aligned}$$

with

$$A(s) = 2\varepsilon \|\nabla \eta\|_{L^\infty} \|\rho_o\|_{L^1(\mathbb{R}^2)} + \varepsilon L_f \|\Delta \eta\|_{L^\infty} \left(1 + \|\sigma_o\|_{L^1(\mathbb{R}^2)} \|\nabla \eta\|_{L^1} \right) \operatorname{TV}(\rho(s)). \quad (4.2)$$

An application of Gronwall Lemma, together with

$$\int_0^t A(s) \exp \left(\int_s^t A(r) dr \right) ds = -1 + \exp \left(\int_0^t A(s) ds \right),$$

yields the desired estimate

$$\|\rho(t) - \sigma(t)\|_{L^1(\mathbb{R}^2)} \leq \|\rho_o - \sigma_o\|_{L^1(\mathbb{R}^2)} e^{t A(t)}.$$

□

Remark 4.2. We can interpret ρ and σ as solutions of the following Cauchy problems:

$$\begin{cases} \partial_t \rho + \nabla \cdot \mathbf{g}(t, \mathbf{x}, \rho) = 0, \\ \rho(0, \mathbf{x}) = \rho_o(\mathbf{x}), \end{cases} \quad \begin{cases} \partial_t \sigma + \nabla \cdot \mathbf{h}(t, \mathbf{x}, \sigma) = 0, \\ \sigma(0, \mathbf{x}) = \sigma_o(\mathbf{x}), \end{cases} \quad (t, \mathbf{x}) \in [0, T] \times \mathbb{R}^2, \quad \mathbf{x} \in \mathbb{R}^2,$$

where

$$\mathbf{g}(t, \mathbf{x}, r) = r \mathbf{v}^{\text{stat}}(\mathbf{x}) + f(r) \mathbf{R}(t, \mathbf{x}), \quad \mathbf{h}(t, \mathbf{x}, r) = r \mathbf{v}^{\text{stat}}(\mathbf{x}) + f(r) \mathbf{S}(t, \mathbf{x}),$$

so that the L^1 distance between the solutions at time $t > 0$ can be estimated by Proposition 2.10 of [14], see also the refinement in Proposition 2.9 of [15]. However, making use of the explicit expression of the flux in the present case, one may see that the bound provided by Proposition 4.1 is sharper than that coming from Proposition 2.9 of [15].

5. LAX–FRIEDRICHSCHEM

It is also possible to consider a piece-wise constant solution ρ_Δ to (1.1) as in (3.1) defined through a Lax–Friedrichs type finite volume scheme with dimensional splitting. To this aim, let $\alpha, \beta > 0$ be the viscosity coefficients. The algorithm reads as follows

Algorithm 5.1.

```

for  $n = 0, \dots, N_T - 1$ 
   $F^n(x, y, u, w) = \frac{1}{2} [v_1^{\text{stat}}(x, y)(u + w) + J_1^n(x, y)(f(u) + f(w))] - \frac{\alpha}{2}(w - u)$  (5.1)
   $G^n(x, y, u, w) = \frac{1}{2} [v_2^{\text{stat}}(x, y)(u + w) + J_2^n(x, y)(f(u) + f(w))] - \frac{\beta}{2}(w - u)$  (5.2)
   $\rho_{i,j}^{n+1/2} = \rho_{i,j}^n - \lambda_x [F^n(x_{i+1/2,j}, \rho_{i,j}^n, \rho_{i+1,j}^n) - F^n(x_{i-1/2,j}, \rho_{i-1,j}^n, \rho_{i,j}^n)]$  (5.3)
   $\rho_{i,j}^{n+1} = \rho_{i,j}^{n+1/2} - \lambda_y [G^n(x_{i,j+1/2}, \rho_{i,j}^n, \rho_{i,j+1}^n) - G^n(x_{i,j-1/2}, \rho_{i,j-1}^n, \rho_{i,j}^n)]$  (5.4)
end

```

The algorithm is close to that studied in [1], except that in the present case to compute ρ^{n+1} the flux is evaluated at ρ^n , instead of $\rho^{n+1/2}$.

Following closely the proofs presented in [1], it is possible to recover also for Algorithm 5.1 the bounds on the approximate solution necessary to prove the convergence. Below, we state only the final results, omitting the computations.

Lemma 5.2 (Positivity). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let assumptions **(v)**, **(H)** and **(η)** hold. Assume that*

$$\alpha \geq \|v_1^{\text{stat}}\|_{L^\infty} + \varepsilon L_f, \quad \lambda_x \leq \frac{1}{3} \min \left\{ \frac{1}{\alpha}, \frac{1}{2\varepsilon L_f + \Delta x \|v_1^{\text{stat}}\|_{L^\infty}} \right\}, \quad (5.5)$$

$$\beta \geq \|v_2^{\text{stat}}\|_{L^\infty} + \varepsilon L_f, \quad \lambda_y \leq \frac{1}{3} \min \left\{ \frac{1}{\beta}, \frac{1}{2\varepsilon L_f + \Delta x \|v_2^{\text{stat}}\|_{L^\infty}} \right\}. \quad (5.6)$$

Then, for all $t > 0$ and $(x, y) \in \mathbb{R}^2$, the piece-wise constant approximate solution ρ_Δ (3.1) constructed through Algorithm 5.1 is such that $\rho_\Delta(t, x, y) \geq 0$.

Lemma 5.3 (L^1 bound). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let **(v)**, **(H)**, **(η)**, (5.5) and (5.6) hold. Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 5.1 satisfies (3.10), that is*

$$\|\rho_\Delta(t)\|_{L^1(\mathbb{R}^2)} = \|\rho_o\|_{L^1(\mathbb{R}^2)}.$$

Lemma 5.4 (L^∞ bound). *Let $\rho_o \in L^\infty(\mathbb{R}^2; \mathbb{R}^+)$. Let **(v)**, **(H)**, **(η)**, (5.5) and (5.6) hold. Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 5.1 satisfies*

$$\|\rho_\Delta(t)\|_{L^\infty(\mathbb{R}^2)} \leq \|\rho_o\|_{L^\infty} e^{\tilde{C}_\infty t},$$

where

$$\tilde{C}_\infty = \|\partial_x v_1^{\text{stat}}\|_{L^\infty} + \|\partial_y v_2^{\text{stat}}\|_{L^\infty} + 4\varepsilon L_f \|\nabla^2 \eta\|_{L^\infty} \|\rho_o\|_{L^1}.$$

Remark 5.5. Compare the L^∞ estimate obtained in Lemma 5.4 using the Lax–Friedrichs scheme with that in Lemma 3.4, given by the Roe scheme. Although they look very similar, the constants appearing in the exponent are actually different: when comparing \tilde{C}_∞ above to C_∞ as in (3.12), we see that in \tilde{C}_∞ the last addend is multiplied by L_f .

Proposition 5.6 (BV estimate in space). *Let $\rho_o \in (\mathrm{L}^\infty \cap \mathrm{BV})(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) , (\mathbf{H}) , $(\boldsymbol{\eta})$, (5.5) and (5.6) hold. Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 5.1 satisfies the following estimate: for all $n = 0, \dots, N_T$,*

$$\sum_{i,j \in \mathbb{Z}} (\Delta y |\rho_{i+1,j}^n - \rho_{i,j}^n| + \Delta x |\rho_{i,j+1}^n - \rho_{i,j}^n|) \leq \tilde{\mathcal{C}}_x(t^n),$$

where

$$\tilde{\mathcal{C}}_x(t) = e^{2t\tilde{\mathcal{K}}_1} \sum_{i,j \in \mathbb{Z}} (\Delta x |\rho_{i,j+1}^0 - \rho_{i,j}^0| + \Delta y |\rho_{i+1,j}^0 - \rho_{i,j}^0|) + \frac{2\mathcal{K}_2}{\tilde{\mathcal{K}}_1} (e^{2t\tilde{\mathcal{K}}_1} - 1), \quad (5.7)$$

with

$$\tilde{\mathcal{K}}_1 = 2 \|\nabla \mathbf{v}^{\text{stat}}\|_{\mathrm{L}^\infty} + 4\varepsilon L_f \|\nabla^2 \eta\|_{\mathrm{L}^\infty} \|\rho_o\|_{\mathrm{L}^1},$$

\mathcal{K}_2 as in (3.17) and c_1, c_2 are defined in (A.6).

Remark 5.7. Observe that $\tilde{\mathcal{K}}_1 < \mathcal{K}_1$ in (3.16).

Corollary 5.8 (BV estimate in space and time). *Let $\rho_o \in (\mathrm{L}^\infty \cap \mathrm{BV})(\mathbb{R}^2; \mathbb{R}^+)$. Let (\mathbf{v}) , (\mathbf{H}) , $(\boldsymbol{\eta})$, (5.5) and (5.6) hold. Then, for all $t > 0$, ρ_Δ in (3.1) constructed through Algorithm 5.1 satisfies the following estimate: for all $n = 1, \dots, N_T$,*

$$\sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta t (\Delta y |\rho_{i+1,j}^m - \rho_{i,j}^m| + \Delta x |\rho_{i,j+1}^m - \rho_{i,j}^m|) + \sum_{m=0}^{n-1} \sum_{i,j \in \mathbb{Z}} \Delta x \Delta y |\rho_{i,j}^{m+1} - \rho_{i,j}^m| \leq \tilde{\mathcal{C}}_{xt}(t^n),$$

where

$$\tilde{\mathcal{C}}_{xt}(t) = t (\tilde{\mathcal{C}}_x(t) + 2\tilde{\mathcal{C}}_t(t)),$$

with $\tilde{\mathcal{C}}_x$ as in (5.7) and

$$\tilde{\mathcal{C}}_t(s) = 2 (\|\mathbf{v}^{\text{stat}}\|_{\mathrm{L}^\infty} + \varepsilon L_f) \tilde{\mathcal{C}}_x(s) + (\|\nabla \mathbf{v}^{\text{stat}}\|_{\mathrm{L}^\infty} + \varepsilon \|\nabla^2 \eta\|_{\mathrm{L}^\infty} \|\rho_o\|_{\mathrm{L}^1}) \|\rho_o\|_{\mathrm{L}^1}.$$

6. NUMERICAL RESULTS

We consider the test setting given in [9] to compare the results of the Roe scheme, *cf.* Algorithm 3.1, to the results of the Lax–Friedrichs type scheme, *cf.* Algorithm 5.1.

6.1. Test setting

A total number of $N = 192$ parts in the shape of metal cylinders are transported on a conveyor belt moving with speed $v_T = 0.42$ m/s and are redirected by a diverter. The diverter is positioned at an angle of $\vartheta = 45$ degree with respect to the border of the conveyor belt. Figure 1 illustrates the static velocity field of the conveyor belt. Parts are transported with velocity $\mathbf{v}^{\text{stat}} = (v_T, 0)$ in Region A and the diverter redirects the parts. At the diverter (Region C), the parts are redirected according to the normal vector of the obstacle surface $\mathbf{v}^{\text{stat}} = (\cos \vartheta \cos \vartheta, \sin \vartheta \cos \vartheta)$. The area behind the diverter (Region B) is modelled in a way that should prohibit parts from passing through the diverter, see [9]. The point (x_d, y_d) marks the end of the diverter.

6.2. Discretisation and solution properties

To numerically model the setting, we introduce a uniform grid $\Delta x = \Delta y$ on the selected area of the conveyor belt. Initial conditions for the density at time $t = 0$ are given by the experimental data and normalised so that $\rho_{\max} = 1$. The mollifier η which is used in the operator $\mathbf{I}(\rho)$ (1.2) is chosen as follows

$$\eta(x) = \frac{\sigma}{2\pi} e^{-\frac{1}{2}\sigma||x||_2^2},$$

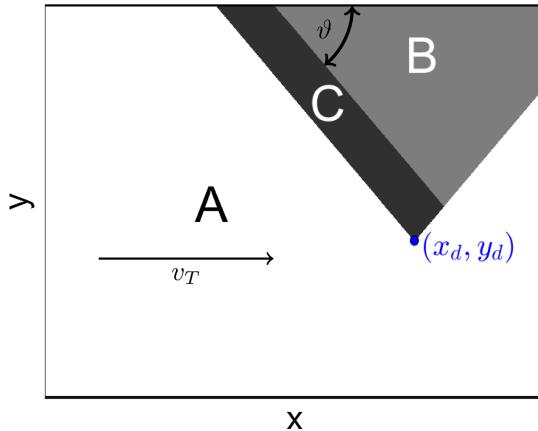


FIGURE 1. Schematic view of the static field of the conveyor belt.

with $\sigma = 10\,000$.

In the original model formulation [9], the Heaviside function was introduced to avoid densities larger than ρ_{\max} . In this work, we investigate the performances of two numerical schemes with two types of smooth approximations of the Heaviside function, one sensibly closer than the other. The former is the approximation H_t (atan), obtained using the inverse tangent

$$H_t(u) = \frac{\arctan(50(u - 1))}{\pi} + 0.5, \quad (6.1)$$

while the latter is denoted H_p (polynomial) and it is obtained by cubic spline interpolation with the following conditions

$$\begin{aligned} H_p(u) &= 0 & \forall u \leq d_l < 1, & H_p(u) &= 1 & \forall u \geq d_r > 1, \\ H_p(d_l) &= 0, & H_p(1) &= \frac{1}{2}, & H_p(d_r) &= 1, & H'_p(d_l) &= 0, & H'_p(d_r) &= 0. \end{aligned}$$

The approximation H_p for $d_l = \frac{1}{2}$ and $d_r = \frac{8}{5}$ together with the inverse tangent approximation are depicted in Figure 2.

Using the inverse tangent approximation corresponds to activating the collision operator $\mathbf{I}(\rho)$ very close to ρ_{\max} . On the other hand, with the polynomial approximation, the collision operator starts activating at $\frac{1}{2}\rho_{\max}$, which implies that clusters with densities values between $\frac{1}{2}\rho_{\max}$ and ρ_{\max} are already dispersed to some extent. Numerically, this means that densities above the maximum one are more likely to appear when using the inverse tangent approximation, while exploiting the polynomial approximation prevents from reaching such high values of the density.

Clearly, different approximations of the Heaviside function lead to different Lipschitz constants L_f (2.1) and therefore influence the CFL time steps of the Roe scheme (3.13) and of the Lax–Friedrichs scheme (5.5) and (5.6). Moreover, the constants α and β given by the CFL condition for the Lax–Friedrichs scheme depend on the Lipschitz constant L_f . Larger Lipschitz constants, and therefore higher viscosity coefficients α and β , add additional viscosity to the Lax–Friedrichs scheme and therefore more diffusion, as shown in [16]. Note that in general, the Lax–Friedrichs scheme is more diffusive than the Roe scheme. To ensure conservation of mass within the given area of the conveyor belt, we impose zero-flux-conditions at the boundaries of the conveyor belt for the Lax–Friedrichs scheme. Therefore, at the boundary, the flux that would exit the domain is set to zero.

The Lipschitz constants of the approximations of the Heaviside functions depicted in Figure 2, as well as the corresponding CFL conditions, are displayed in Table 1, for a fixed space step size Δx . The inverse tangent

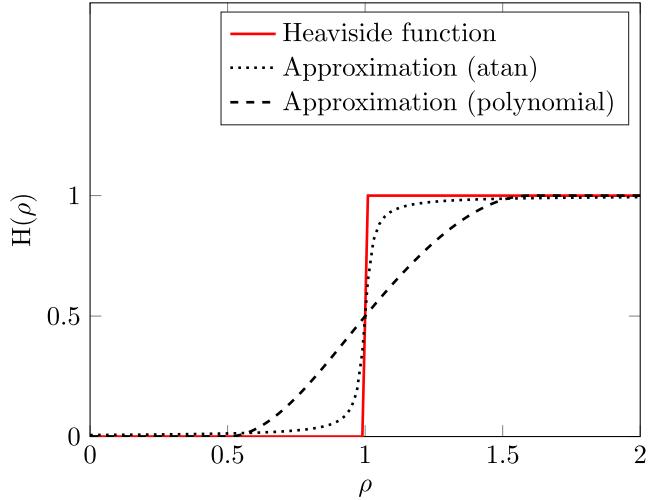


FIGURE 2. The Heaviside function and approximations H_t (atan) and H_p (polynomial).

TABLE 1. CFL time steps for different Heaviside approximations and fixed $\Delta x, \Delta y$.

Approximation	L_f	$\Delta x = \Delta y$ [m]	CFL time step Roe [s]	CFL time step LxF [s]
H_t (atan)	16.42	1×10^{-2}	2.37×10^{-4}	1.21×10^{-4}
H_p (polynomial)	2.09	1×10^{-2}	1.63×10^{-3}	9.50×10^{-4}

approximation has a greater Lipschitz constant, leading to small CFL time steps and thus to an increased computational effort.

We analyse the amount of parts that pass the obstacle, *i.e.* the outflow at the end of the obstacle (x_d, y_d). The time-dependent mass function $U(t)$ counts the measured parts that are located in the region Ω_0

$$U(t) = \frac{1}{N} \sum_{i=1}^N \mathcal{X}_{\Omega_0}(x^{(i)}(t), y^{(i)}(t)) \quad \mathcal{X}_{\Omega_0}(x, y) = \begin{cases} 1, & (x, y) \in \Omega_0 \\ 0, & \text{otherwise} \end{cases} \quad (6.2)$$

where $\Omega_0 = \{(x, y) \in \mathbb{R}^2 \mid x \leq x_d\}$ is the left sided region upstream the obstacle and $(x^{(i)}(t), y^{(i)}(t))$ is the position of part i , $i \in 1, \dots, N$, at time t . The time-dependent mass function describing the outflow to the solution of the conservation law is given by

$$U_\rho(t) = \frac{1}{\int_{\Omega_0} \rho(x, 0) dx} \int_{\Omega_0} \rho(x, t) dx. \quad (6.3)$$

The outflow curves obtained using Roe scheme, Lax–Friedrichs scheme and the outflow measured experimentally are shown in Figure 3. The parameters chosen for each scheme are those given in Table 1. Figure 4 displays the L^∞ norms of the solution over time.

The outflow curve given by Roe scheme for both approximations of the Heaviside function is closer to the experimental data, due to the fact that the scheme captures more congestion, as indicated also by the L^∞ norm. With Roe scheme, as expected, the density piles up even more when using the inverse tangent approximation. We observe that a maximum principle is not verified. On the contrary, with the polynomial approximation, higher densities are avoided, since the collision operator is activated earlier. Due to the influence of the viscosity

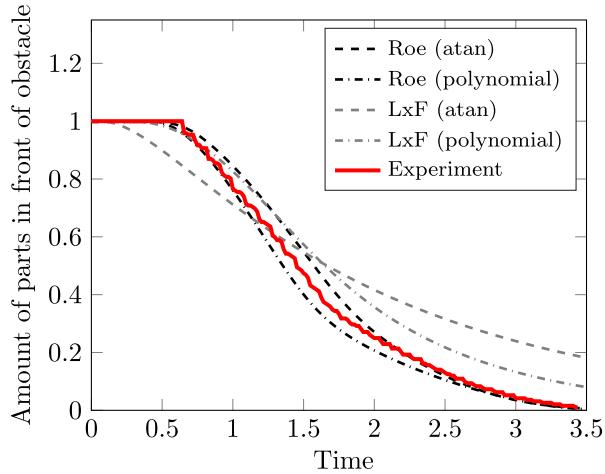
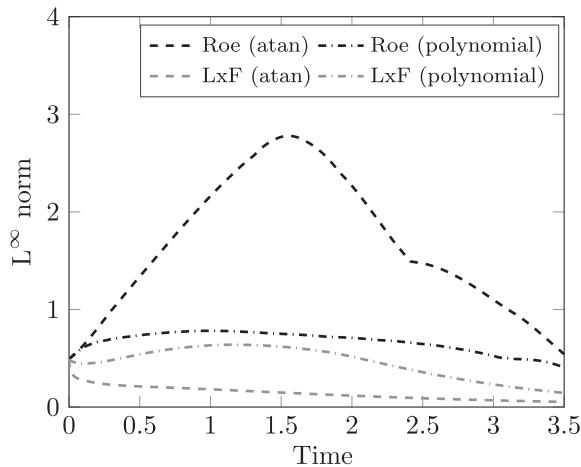


FIGURE 3. Outflow.

FIGURE 4. Time evolution of the L^∞ norm of the approximate solutions.

coefficients, an opposite behaviour is observable with the Lax–Friedrichs scheme. Results for the L^∞ norm of the solution are quite promising using the polynomial approximation, whereas the viscosity of the scheme is too large in the case of the inverse tangent approximation. The L^∞ norm of the solution is constantly decreasing over time because of diffusion.

Figure 5 displays the parts’ positions in the experiment and the density distribution computed with Roe and Lax–Friedrichs scheme using the polynomial Heaviside approximation at time $t = 1.5\text{s}$. The density plot of the Roe scheme matches the experimental data quite well: regions with higher densities mostly coincide with regions in the experiments, where the parts are side by side. In contrast, the Lax–Friedrichs scheme produces a more widely spread density distribution. Even the parts on the upper section of the belt, which are transported to the right with the velocity of the conveyor belt, are not correctly portrayed.

Since the Roe scheme using the sharper approximation of the Heaviside function provides the best result in comparison to the experimental data, we analyse its behaviour for $\Delta x, \Delta y \rightarrow 0$. Table 2 shows the L^1, L^2 and

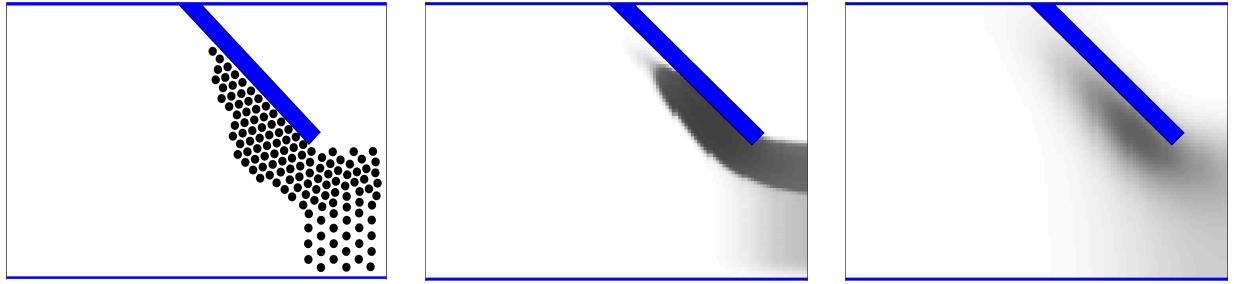


FIGURE 5. Experimental data (*left*), results of the Roe scheme (*middle*) and the Lax–Friedrichs scheme (*right*) at $t = 1.5$ s.

TABLE 2. Error norms of Roe scheme, with the inverse tangent approximation of the Heaviside function (6.1), against experimental data.

$\Delta x = \Delta y$	CFL time step	L^1 -error	L^2 -error	L^∞ -error	$\ \rho_{\Delta x} - \rho_{\Delta x/2}\ _{L^1}$	$\gamma(\Delta_x)$
1.6×10^{-1}	3.8×10^{-3}	1.74	1.14	0.94	0.0966	0.78
8×10^{-2}	1.9×10^{-3}	0.77	0.49	0.36	0.0561	1.06
4×10^{-2}	9.47×10^{-4}	0.42	0.26	0.20	0.0268	0.86
2×10^{-2}	4.73×10^{-4}	0.16	0.10	0.10	0.0148	0.81
1×10^{-2}	2.37×10^{-4}	0.09	0.07	0.09	0.008	
5×10^{-3}	1.18×10^{-4}	0.07	0.05	0.07		

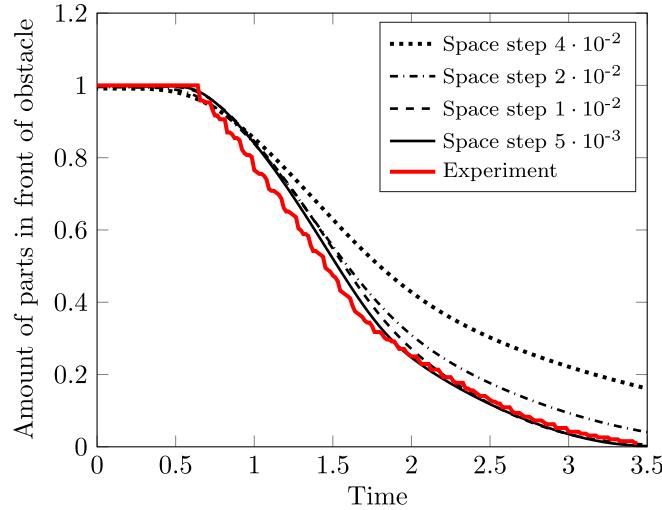


FIGURE 6. Outflow computed by Roe scheme with different space step sizes using the inverse tangent approximation of the Heaviside function (6.1).

L^∞ error of the outflow of the simulations with the Roe scheme and the inverse tangent approximation of the Heaviside function compared to the outflow given by the experimental data.

The scheme is evaluated for different space step sizes and their corresponding CFL time steps. We observe that the error of the Roe scheme decreases as the space step decreases, suggesting the convergence of the outflow to the experimental data, compare also Figure 6. As in [1], the convergence rate for the approximate solutions

of the Roe scheme

$$\gamma(\Delta x) = \log_2 \left(\frac{\|\rho_{\Delta x} - \rho_{\Delta x/2}\|_{L^1}}{\|\rho_{\Delta x/2} - \rho_{\Delta x/4}\|_{L^1}} \right),$$

is computed using the L^1 distance between the numerical solutions $\rho_{\Delta x}$ and $\rho_{\Delta x/2}$ corresponding to the grid sizes Δx and $\Delta x/2$ at time $t = 1$. Note that the Roe scheme was adopted to treat the linear convection term and the diffusion term of (1.1). If we put the diffusion term aside, the scheme is based on the upwind property and the scheme therefore is similar to the monotone scheme. Thus, at most first order can be expected. The results in Table 2 suggest a convergence rate of $\gamma \approx 0.8$. Here, the diffusion term including the convolution does not significantly worsen the performance of the scheme.

APPENDIX A. TECHNICAL LEMMA

Lemma A.1. *Let $\eta \in (C^3 \cap W^{3,\infty})(\mathbb{R}^2; \mathbb{R})$. Then, for $n = 0, \dots, N_T$, for $i, j \in \mathbb{Z}$, the following estimates hold:*

$$\|J_k^n\|_{L^\infty} \leq \varepsilon \quad \text{for } k = 1, 2, \quad (\text{A.1})$$

$$|J_1^n(x_{i+1/2,j}) - J_1^n(x_{i-1/2,j})| \leq 2\varepsilon \Delta x \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1}, \quad (\text{A.2})$$

$$|J_1^n(x_{i+1/2,j}) - J_1^n(x_{i+1/2,j+1})| \leq 2\varepsilon \Delta y \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1}, \quad (\text{A.3})$$

$$|J_2^n(x_{i,j+1/2}) - J_2^n(x_{i,j-1/2})| \leq 2\varepsilon \Delta y \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1},$$

$$|J_2^n(x_{i+1,j+1/2}) - J_2^n(x_{i,j+1/2})| \leq 2\varepsilon \Delta x \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1},$$

$$|J_1^n(x_{i+3/2,j}) - 2J_1^n(x_{i+1/2,j}) + J_1^n(x_{i-1/2,j})| \leq 2\varepsilon (\Delta x)^2 \left(c_1 \|\rho^n\|_{L^1} + c_2 \|\rho^n\|_{L^1}^2 \right), \quad (\text{A.4})$$

$$|J_2^n(x_{i,j+3/2}) - 2J_2^n(x_{i,j+1/2}) + J_2^n(x_{i,j-1/2})| \leq 2\varepsilon (\Delta y)^2 \left(c_1 \|\rho^n\|_{L^1} + c_2 \|\rho^n\|_{L^1}^2 \right),$$

$$|J_1^n(x_{i+1/2,j}) - J_1^n(x_{i+1/2,j+1}) - J_1^n(x_{i-1/2,j}) + J_1^n(x_{i-1/2,j+1})| \leq 2\varepsilon \Delta x \Delta y C, \quad (\text{A.5})$$

$$|J_2^n(x_{i,j+1/2}) - J_2^n(x_{i+1,j+1/2}) - J_2^n(x_{i,j-1/2}) + J_2^n(x_{i+1,j-1/2})| \leq 2\varepsilon \Delta x \Delta y C,$$

where we set

$$C = c_1 \|\rho^n\|_{L^1} + c_2 \|\rho^n\|_{L^1}^2, \quad c_1 = 2 \|\nabla^3 \eta\|_{L^\infty}, \quad c_2 = 3 \|\nabla^2 \eta\|_{L^\infty}^2. \quad (\text{A.6})$$

Proof. The proof of (A.1) is immediate.

Pass now to (A.2). For the sake of simplicity, introduce the following notation:

$$D_+ = \sqrt{1 + \|(\nabla \eta * \rho^n)(x_{i+1/2}, y_j)\|^2}, \quad D_- = \sqrt{1 + \|(\nabla \eta * \rho^n)(x_{i-1/2}, y_j)\|^2}.$$

Hence,

$$|J_1^n(x_{i+1/2}, y_j) - J_1^n(x_{i-1/2}, y_j)| \quad (\text{A.7})$$

$$= \varepsilon \left| \frac{\Delta x \Delta y}{D_+} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \partial_1 \eta(x_{i+1/2-k}, y_{j-\ell}) - \frac{\Delta x \Delta y}{D_-} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \partial_1 \eta(x_{i-1/2-k}, y_{j-\ell}) \right|$$

$$\leq \varepsilon \left| \frac{\Delta x \Delta y}{D_+} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n (\partial_1 \eta(x_{i+1/2-k}, y_{j-\ell}) - \partial_1 \eta(x_{i-1/2-k}, y_{j-\ell})) \right| \quad (\text{A.8})$$

$$+ \varepsilon \Delta x \Delta y \left| \frac{1}{D_+} - \frac{1}{D_-} \right| \sum_{k,\ell \in \mathbb{Z}} |\rho_{k,\ell}^n| |\partial_1 \eta(x_{i-1/2-k}, y_{j-\ell})|. \quad (\text{A.9})$$

Consider (A.8): since $D_+ \geq 1$ and

$$|\partial_1 \eta(x_{i+1/2-k}, y_{j-\ell}) - \partial_1 \eta(x_{i-1/2-k}, y_{j-\ell})| \leq \int_{x_{i-1/2-k}}^{x_{i+1/2-k}} |\partial_{11}^2 \eta(x, y_{j-\ell})| dx,$$

we obtain

$$[(A.8)] \leq \varepsilon \Delta x \|\partial_{11}^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1}. \quad (A.10)$$

On the other hand, to estimate (A.9), compute

$$\left| \frac{1}{D_+} - \frac{1}{D_-} \right| = \frac{|D_+ - D_-|}{D_+ D_-}.$$

Introduce $a(x) = \nabla \eta * \rho^n(x)$ and $b(z) = (1 + \|z\|^2)^{1/2}$, for $z \in \mathbb{R}^2$. In particular compute $b'(z) = \frac{\|z\|}{(1 + \|z\|^2)^{1/2}}$ and observe that $|b'(z)| \leq 1$. Then

$$\begin{aligned} |D_+ - D_-| &= |b(a(x_{i+1/2})) - b(a(x_{i-1/2}))| = |b'(a(\tilde{x}_i)) a'(\tilde{x}_i) (x_{i+1/2} - x_{i-1/2})| \\ &= \left| \frac{a(\tilde{x}_i)}{(1 + a(\tilde{x}_i)^2)^{1/2}} (\partial_x \nabla \eta * \rho^n)(\tilde{x}_i) \Delta x \right| \\ &\leq \Delta x \|\rho^n\|_{L^1} \|\nabla^2 \eta\|_{L^\infty}. \end{aligned} \quad (A.11)$$

Therefore,

$$\varepsilon \Delta x \Delta y \left| \frac{1}{D_+} - \frac{1}{D_-} \right| \sum_{k,\ell \in \mathbb{Z}} |\rho_{k,\ell}^n| |\partial_1 \eta(x_{i-1/2-k}, y_{j-\ell})| \leq \varepsilon \Delta x \|\nabla^2 \eta\|_{L^\infty} \|\rho^n\|_{L^1}. \quad (A.12)$$

Inserting (A.10) and (A.12) into the estimate of (A.7) yields the desired result.

Consider now (A.4). Introduce the following notation: for $\mu \in \{-1; 1; 3\}$ set

$$D_\mu = \sqrt{1 + \|(\nabla \eta * \rho^n)(x_{i+\mu/2}, y_j)\|^2}.$$

Thus

$$\begin{aligned} J_1^n(x_{i+3/2,j}) - 2J_1^n(x_{i+1/2,j}) + J_1^n(x_{i-1/2,j}) \\ = -\varepsilon \left(\frac{(\partial_1 \eta * \rho^n)(x_{i+3/2,j})}{D_3} - 2 \frac{(\partial_1 \eta * \rho^n)(x_{i+1/2,j})}{D_1} + \frac{(\partial_1 \eta * \rho^n)(x_{i-1/2,j})}{D_{-1}} \right. \\ \left. \pm \frac{(\partial_1 \eta * \rho^n)(x_{i+3/2,j})}{D_1} \pm \frac{(\partial_1 \eta * \rho^n)(x_{i-1/2,j})}{D_1} \right) \\ = -\varepsilon \left(\left(\frac{1}{D_3} - \frac{1}{D_1} \right) (\partial_1 \eta * \rho^n)(x_{i+3/2,j}) + \frac{1}{D_1} ((\partial_1 \eta * \rho^n)(x_{i+3/2,j}) - (\partial_1 \eta * \rho^n)(x_{i+1/2,j})) \right. \\ \left. + \frac{1}{D_1} ((\partial_1 \eta * \rho^n)(x_{i-1/2,j}) - (\partial_1 \eta * \rho^n)(x_{i+1/2,j})) + \left(\frac{1}{D_{-1}} - \frac{1}{D_1} \right) (\partial_1 \eta * \rho^n)(x_{i-1/2,j}) \right). \end{aligned}$$

Consider the terms separately, forgetting for a moment the ε in front of everything. Focus first on the terms with common denominator D_1 :

$$\begin{aligned}
& \frac{1}{D_1} ((\partial_1 \eta * \rho^n)(x_{i+3/2,j}) - (\partial_1 \eta * \rho^n)(x_{i+1/2,j}) + (\partial_1 \eta * \rho^n)(x_{i-1/2,j}) - (\partial_1 \eta * \rho^n)(x_{i+1/2,j})) \\
&= \frac{\Delta x \Delta y}{D_1} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n (\partial_1 \eta(x_{i+3/2-k}, y_{j-\ell}) - \partial_1 \eta(x_{i+1/2-k}, y_{j-\ell}) \\
&\quad + \partial_1 \eta(x_{i-1/2-k}, y_{j-\ell}) - \partial_1 \eta(x_{i+1/2-k}, y_{j-\ell})) \\
&= \frac{\Delta x \Delta y}{D_1} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \Delta x (\partial_{11}^2 \eta(\hat{x}_{i+1-k}, y_{j-\ell}) - \partial_{11}^2 \eta(\hat{x}_{i-k}, y_{j-\ell})) \\
&= \frac{\Delta x \Delta y}{D_1} \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \Delta x \int_{\hat{x}_{i-k}}^{\hat{x}_{i+1-k}} \partial_{111}^3 \eta(x, y_{j-\ell}) dx \\
&\leq 2 (\Delta x)^2 \|\partial_{111}^3 \eta\|_{L^\infty} \|\rho^n\|_{L^1},
\end{aligned} \tag{A.13}$$

with $\hat{x}_{i-k} \in]x_{i-1/2-k}, x_{i+1/2-k}[$. We are left with

$$\left(\frac{1}{D_3} - \frac{1}{D_1} \right) (\partial_1 \eta * \rho^n)(x_{i+3/2,j}) + \left(\frac{1}{D_{-1}} - \frac{1}{D_1} \right) (\partial_1 \eta * \rho^n)(x_{i-1/2,j}). \tag{A.14}$$

Add and subtract to (A.14)

$$\left(\frac{1}{D_{-1}} - \frac{1}{D_1} \right) (\partial_1 \eta * \rho^n)(x_{i+3/2,j}).$$

Hence,

$$\left(\frac{1}{D_3} - 2 \frac{1}{D_1} + \frac{1}{D_{-1}} \right) (\partial_1 \eta * \rho^n)(x_{i+3/2,j}) \tag{A.15}$$

$$+ \left(\frac{1}{D_{-1}} - \frac{1}{D_1} \right) ((\partial_1 \eta * \rho^n)(x_{i-1/2,j}) - (\partial_1 \eta * \rho^n)(x_{i+3/2,j})). \tag{A.16}$$

Consider first (A.16): exploiting also (A.11), we obtain

$$\begin{aligned}
[(A.16)] &= \frac{D_1 - D_{-1}}{D_1 D_{-1}} \Delta x \Delta y \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n (\partial_1 \eta(x_{i-1/2-k}, y_{j-\ell}) - \partial_1 \eta(x_{i+3/2-k}, y_{j-\ell})) \\
&= \frac{D_1 - D_{-1}}{D_1 D_{-1}} \Delta x \Delta y \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \int_{x_{i+3/2-k}}^{x_{i-1/2-k}} \partial_{11}^2 \eta(x, y_{j-\ell}) dx \\
&\leq 2 (\Delta x)^2 \|\nabla^2 \eta\|_{L^\infty}^2 \|\rho^n\|_{L^1}^2.
\end{aligned} \tag{A.17}$$

As far as (A.15) is concerned, focus on the terms in the brackets:

$$\begin{aligned}
\frac{1}{D_3} - 2 \frac{1}{D_1} + \frac{1}{D_{-1}} &= \frac{D_1 D_{-1} - 2 D_3 D_{-1} + D_3 D_1}{D_3 D_1 D_{-1}} \\
&= \frac{D_{-1}(D_1 - D_3) - D_3(D_{-1} - D_1) \pm D_3(D_1 - D_3)}{D_3 D_1 D_{-1}} \\
&= \frac{(D_{-1} - D_3)(D_1 - D_3)}{D_3 D_1 D_{-1}} - \frac{D_{-1} - 2 D_1 + D_3}{D_1 D_{-1}}.
\end{aligned} \tag{A.18}$$

Inserting the first addend of (A.18) back into (A.15) yields

$$\frac{(D_{-1} - D_3)(D_1 - D_3)}{D_3 D_1 D_{-1}} (\partial_1 \eta * \rho^n)(x_{i+3/2,j}) \leq 2(\Delta x)^2 \|\nabla^2 \eta\|_{L^\infty}^2 \|\rho^n\|_{L^1}^2, \quad (\text{A.19})$$

where we exploit (A.11) twice and use the fact that $\frac{(\partial_1 \eta * \rho^n)(x_{i+3/2,j})}{D_3} \leq 1$. Concerning the second addend of (A.18), focus on its numerator: with the notation introduced before (A.11),

$$\begin{aligned} D_{-1} - 2D_1 + D_3 &= b(a(x_{i+3/2})) - 2b(a(x_{i+1/2})) + b(a(x_{-1/2})) \\ &= b'(a(\check{x}_{i+1})) a'(\check{x}_{i+1})(x_{i+3/2} - x_{i+1/2}) - b'(a(\check{x}_i)) a'(\check{x}_i)(x_{i+1/2} - x_{i-1/2}) \\ &= \Delta x (b'(a(\check{x}_{i+1})) (\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) - b'(a(\check{x}_i)) (\partial_1 \nabla \eta * \rho^n)(\check{x}_i)) \\ &\quad \pm \Delta x b'(a(\check{x}_i)) (\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) \\ &= \Delta x [b'(a(\check{x}_{i+1})) - b'(a(\check{x}_i))] (\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) \\ &\quad + \Delta x b'(a(\check{x}_i)) [(\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) - (\partial_1 \nabla \eta * \rho^n)(\check{x}_i)] \\ &= \Delta x b''(a(\bar{x}_{i+1/2})) a'(\bar{x}_{i+1/2})(\check{x}_{i+1} - \check{x}_i) (\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) \\ &\quad + \Delta x b'(a(\check{x}_i)) \Delta x \Delta y \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n (\partial_1 \nabla \eta(\check{x}_{i+1-k}, y_{j-\ell}) - \partial_1 \nabla \eta(\check{x}_{i-k}, y_{j-\ell})) \\ &= \Delta x b''(a(\bar{x}_{i+1/2})) a'(\bar{x}_{i+1/2})(\check{x}_{i+1} - \check{x}_i) (\partial_1 \nabla \eta * \rho^n)(\check{x}_{i+1}) \\ &\quad + \Delta x b'(a(\check{x}_i)) \Delta x \Delta y \sum_{k,\ell \in \mathbb{Z}} \rho_{k,\ell}^n \int_{\check{x}_{i-k}}^{\check{x}_{i+1-k}} \partial_{11}^2 \nabla \eta(x, y_{j-\ell}) dx \end{aligned}$$

where $\check{x}_i \in]x_{i-1/2}, x_{i+1/2}[$ and $\bar{x}_{i+1/2} \in]\check{x}_i, \check{x}_{i+1}[$. Now insert this estimate back into (A.18) and (A.15): since $|b''(z)| \leq 1$,

$$\left| \frac{D_{-1} - 2D_1 + D_3}{D_1 D_{-1}} (\partial_1 \eta * \rho^n)(x_{i+3/2,j}) \right| \leq 2(\Delta x)^2 \left[\|\partial_1 \nabla \eta\|_{L^\infty}^2 \|\rho^n\|_{L^1}^2 + \|\partial_{11}^2 \nabla \eta\|_{L^\infty} \|\rho^n\|_{L^1} \right]. \quad (\text{A.20})$$

Collecting together (A.13), (A.17), (A.19) and (A.20) yields

$$|J_1^n(x_{i+3/2}, y_j) - 2J_1^n(x_{i+1/2}, y_j) + J_1^n(x_{i-1/2}, y_j)| \leq 2\varepsilon(\Delta x)^2 \left(2\|\nabla^3 \eta\|_{L^\infty} \|\rho^n\|_{L^1} + 3\|\nabla^2 \eta\|_{L^\infty}^2 \|\rho^n\|_{L^1}^2 \right).$$

The proofs of the other inequalities follow analogously. \square

Acknowledgements. This work was financially supported by the project “Non-local conservation laws for engineering applications” co-funded by DAAD (Project-ID 57445223) and the PHC Procope (Project no. 42503RM) and the DFG project GO 1920/7-1. Elena Rossi was partially supported by University of Mannheim and acknowledges its hospitality during the accomplishment of this work.

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