

LOCALIZED COMPUTATION OF EIGENSTATES OF RANDOM
SCHRÖDINGER OPERATORS*R. ALTMANN[†] AND D. PETERSEIM[†]

Abstract. This paper concerns the numerical approximation of low-energy eigenstates of the linear random Schrödinger operator. Under oscillatory high-amplitude potentials with a sufficient degree of disorder it is known that these eigenstates localize in the sense of an exponential decay of their moduli. We propose a reliable numerical scheme which provides localized approximations of such localized states. The method is based on a preconditioned inverse iteration including an optimal multigrid solver which spreads information only locally. The practical performance of the approach is illustrated in various numerical experiments in two and three space dimensions and also for a nonlinear random Schrödinger operator.

Key words. random potential, iterative eigensolver, multigrid solver

AMS subject classifications. 65N25, 65N55, 47B80

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1. Introduction. This paper concerns the numerical approximation of essentially localized eigenstates of the linear Schrödinger eigenvalue problem

$$(1.1) \quad -\Delta u + Vu = \lambda u$$

on a bounded domain $D \subseteq \mathbb{R}^d$ with homogeneous Dirichlet boundary conditions. The nonnegative variable coefficient V represents an external potential reflecting a high degree of disorder. This apparently simple problem is relevant in the context of quantum-physical processes related to ultracold bosonic or photonic gases, known as Bose–Einstein condensates [Bos24, Ein24, DGPS99, PS03]. A Bose–Einstein condensate (BEC) is an extreme state of matter formed by a dilute gas of bosons at ultracold temperatures, very close to absolute zero. In a BEC, individual particles (i.e., their wave packages) overlap, lose their identity, and form one single super atom. BECs allow one to study macroscopic quantum phenomena such as superfluidity (i.e., the frictionless flow of a fluid) on an observable scale. When BECs are trapped in a highly oscillatory high-amplitude potential V that exhibits a sufficiently large degree of disorder, the low-energy stationary states essentially localize in the sense of an exponential decay of their moduli. This localization is a universal wave phenomenon referred to as Anderson localization [And58]. For BECs, it has been observed experimentally in [FFI08].

On a mathematical level, the formation of stationary quantum states can be modeled by the slightly more involved Gross–Pitaevskii eigenvalue problem (GPEVP). In nondimensional form, the GPEVP seeks L^2 -normalized eigenfunctions $u \in H_0^1(D)$ and corresponding eigenvalues (so-called chemical potentials) $\lambda \in \mathbb{R}$ such that

$$-\Delta u + Vu + \delta|u|^2u = \lambda u.$$

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The parameter $\delta \geq 0$ resembles the strength of repulsive particle interactions depending on physical properties of the particles that form the BEC. The linear case (1.1) corresponds to the regime of vanishing particle interaction ($\delta = 0$). Since the interactions are weak for BECs, the linear case provides very good approximations of actual BEC states [RS13]. This is why we will mostly consider the numerical solution of the linear eigenvalue problem (1.1). However, the numerical techniques can be generalized to the nonlinear setting, which will be demonstrated through numerical experiments at the end of this paper.

The numerical approximation of localized Schrödinger eigenstates has recently caused great interest in the fields of computational physics and scientific computing. Fundamentally novel methodologies have been developed to cope with the intrinsic difficulty coming from the multiscale nature of the potential [ADJ⁺16, Ste17, ADF⁺19, XZO18]. They are based on the link of the groundstate u_1 , normalized by $\|u_1\|_{L^\infty(D)} = 1$, and the so-called landscape function $\psi \in H_0^1(D)$ defined through the homogeneous elliptic equation $-\Delta\psi + V\psi = 1$; cf. [FM12]. The landscape function ψ gives rise to surprisingly sharp eigenvalue bounds, and its local maxima indicate regions where localization may occur. While the new techniques based on landscape functions are empirically successful in predicting the eigenvalues, they lack any control over the accuracy of the approximation. In particular the approximation of the states is rather sketchy.

The present paper aims at a more sophisticated method leading not only to the regions of localization but also to actual approximations of the lowermost eigenstates. The starting point is the recent rigorous a priori prediction of exponentially localized low-energy states caused by the interplay of disorder (randomness) and high amplitude (contrast) of the potential trap V [AHP18]. The results of [AHP18] employ the convergence analysis of a preconditioned inverse iteration in the spirit of iterative numerical homogenization [KY16] and thereby provide a role model for efficient simulation. The main idea is to exploit the localization property, meaning that these eigenfunctions can be approximated in a sophisticated manner by functions supported in the union of only a few small subdomains. The main contribution of this paper is the finding of an appropriate starting subspace and the construction of a preconditioned eigensolver which only relies on local operations. In this way, we are able to approximate the eigenstates of lowest energy roughly at the same costs as the computation of the landscape function ψ . In addition, the algorithm is applicable for the nonlinear case.

The first step is a finite element discretization of the eigenvalue problem (1.1), which we discuss in section 2. For this, we consider a uniform refinement of the ε -mesh on which the potential V is defined. This automatically provides a mesh hierarchy for which we define a multigrid-based preconditioner. Using only a small number of smoothing steps and no direct solves, one multigrid step preserves locality in the sense that the support of the resulting function is only slightly larger than the initial function. This then leads to the *localization-preserving* eigensolver introduced in section 3. In other words, the simple yet efficient trick is to consider a multigrid preconditioner on a hierarchy of meshes starting from the ε -level. This sufficed to be optimal in the sense of an $\mathcal{O}(1)$ condition number of the preconditioned operator. If no direct solver is used on the coarsest level, this preconditioner prevents the otherwise global communication of a standard multigrid involving coarser levels. The overall algorithm consists of two parts. First, we apply in parallel the localization-preserving iteration scheme to finite element basis functions on a coarse grid. Based on the energies we select the most promising candidates indicating the regions of localization. Second, we

consider a Ritz-Rayleigh iteration on the remaining local functions; i.e., we project the eigenvalue problem on a very small subspace. This procedure is applicable in any dimension and thus allows us to compute eigenfunctions for $d = 3$ where standard eigensolvers break. This and further numerical experiments are the subject of section 4.

2. Schrödinger eigenvalue problem. This section is devoted to the linear Schrödinger eigenvalue problem (1.1) and the introduction of needed finite element spaces. Further, we discuss localization effects of the lowermost eigenfunctions if the potential contains disorder.

2.1. Model problem. In this paper, we consider the d -dimensional linear eigenvalue problem of Schrödinger type with a potential being highly oscillatory and of large amplitude. In particular, we assume that the potential includes some kind of disorder such that the first few eigenfunctions of lowest energy localize.

The variational formulation corresponding to the eigenvalue problem (1.1) reads as follows: Given a nonnegative potential $0 \leq V \in L^\infty(D)$, find nontrivial eigenpairs $(u, \lambda) \in \mathcal{V} \times \mathbb{R}$ with search and test space $\mathcal{V} := H_0^1(D)$ such that

$$(2.1) \quad a(u, v) := \int_D \nabla u(x) \cdot \nabla v(x) + V(x) u(x)v(x) dx = \lambda(u, v)$$

for all test functions $v \in \mathcal{V}$. Here, (\cdot, \cdot) denotes the L^2 -inner product on D and eigenfunctions are assumed to be normalized in the L^2 -norm. Further, we assume that the eigenvalues are ordered, i.e., $0 < \lambda_1 < \lambda_2 \leq \dots$.

As far as the theory is concerned, we focus on a representative class of potentials which are piecewise constant with respect to a mesh \mathcal{T}^ε consisting of cubes with side length $\varepsilon \ll 1$. For the sake of simplicity we assume $\varepsilon = 2^{-\ell_\varepsilon}$, where ℓ_ε denotes the level of the ε -scale. On each cube in \mathcal{T}^ε , the potential takes (randomly) a value in the interval $[\alpha, \beta]$ with moderate $0 \leq \alpha \approx 1$ and large β in the sense of $\beta \gtrsim \varepsilon^{-2}$. We emphasize that the resulting potentials are highly oscillatory due to the underlying mesh on the ε -scale. Examples of such random potentials are shown in Figure 2.1. In the field of matter waves, one often considers disorder potentials created optically by using speckle patterns [BMRF⁺99, LFM⁺05, FFI08]. This means that a laser beam is transmitted through a diffusive plate forming randomized and high-contrast patterns. Within this paper, we imitate such speckles by piecewise constant potentials with respect to a quadrilateral mesh consisting of cubes with side length ε . On each of these cubes the potential takes random values following certain statistical assumptions; cf. [Goo75, DKW08].

Within this paper, $\|\cdot\| := \sqrt{(\cdot, \cdot)}$ denotes the standard L^2 -norm on D , whereas the V -weighted L^2 -norm is given by

$$\|v\|_V^2 := (Vv, v) = \int_D V(x) |v(x)|^2 dx.$$

Corresponding to the Schrödinger operator, we define the energy norm as

$$\|\|v\|\|^2 := a(v, v) = \|\nabla v\|^2 + \|v\|_V^2.$$

The energy of a function is characterized by the Rayleigh quotient, namely,

$$\lambda(v) := \frac{a(v, v)}{\|v\|^2} = \frac{\|\|v\|\|^2}{\|v\|^2}.$$

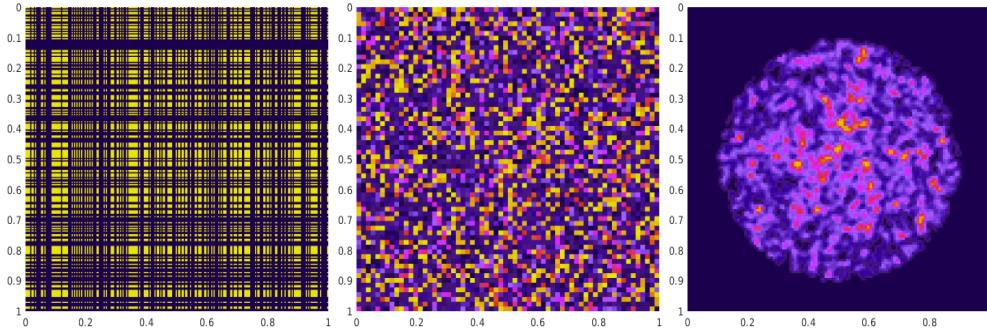


FIG. 2.1. Three examples of prototype disorder potentials: a one-dimensional tensorized potential with only two values (left), a fully random potential (middle), and a speckle potential (right). In all cases, dark color implies a large value of the potential up to the maximum β .

In case v is an eigenfunction of the Schrödinger eigenvalue problem (2.1), the energy $\lambda(v)$ is equal to the corresponding eigenvalue. The eigenfunction of minimal energy $\lambda_1 := \min_{v \in \mathcal{V} \setminus \{0\}} \lambda(v)$ is called the groundstate.

2.2. Exponential decay of the Green's functions. For certain classes of potentials it is known that the corresponding Green's function of the Schrödinger operator decays exponentially. For constant potentials $V \equiv \beta$ with sufficiently large β this was shown in [Glo11, Lem. 3.2].

Piecewise constant potentials with two values α and β were considered in [AHP18]. For this, an operator preconditioner was constructed depending on the geometric structure of the potential, i.e., on the interaction of α -valleys and β -peaks. It was designed in such a way that the application of this operator preconditioner only enlarges the support by a small amount of ε -layers within \mathcal{T}^ε . With this, one can show that the weak solution $u \in \mathcal{V}$ of the variational problem $a(u, \cdot) = (f, \cdot)$ decays exponentially fast around the support of f for potentials under certain statistical assumptions (including, e.g., one-dimensional tensorized potentials as in Figure 2.1). More precisely, this means that

$$\|u\|_{D \setminus B_{r\varepsilon L}^\infty(\text{supp } f)} \leq c \gamma^p \|u\|$$

for constants $c > 0$ and $0 < \gamma < 1$ independent of ε , $L \approx \log(1/\varepsilon)$, and $B_r^\infty(z)$ denoting the ball of radius r around z . We emphasize that this result only relies on ε being small (oscillatory) and β being large (high amplitude). Thus, disorder does not play a role for the exponential decay of the Green's function.

2.3. Localization of eigenfunctions. For the localization of eigenfunctions, the potential needs to include a certain degree of disorder. For a periodic potential, the lowermost part of the spectrum of the Schrödinger operator is clustered. In the one-dimensional case, which is illustrated in Figure 2.2, one can prove that there exist about $\varepsilon^{-d}/2$ (the number of potential valleys) eigenvalues in the energy range of ε^{-2} . Disorder changes the picture dramatically and leads to significant spectral gaps already within the first few eigenvalues. In one space dimension there is a one-to-one correspondence between the largest α -valleys of the potential and the smallest eigenvalues. This is illustrated by dotted vertical lines which correspond to the largest α -valleys and coincide with the spectral gaps for the random potential. This then leads to the exponential decay of the lowermost eigenfunctions; cf. Figure 2.2.

In [AHP18] the localization of eigenfunctions was rigorously proven for the regime

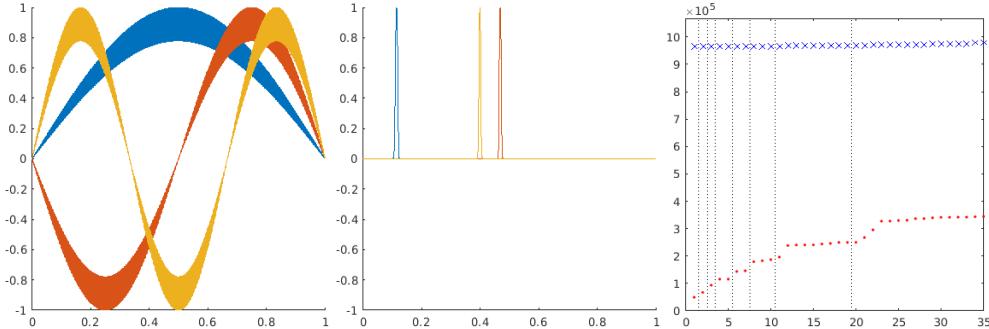


FIG. 2.2. The first three eigenfunctions for a periodic (left) and random (middle) potential in the one-dimensional case with $\ell_\varepsilon = 10$ and $\beta = 2 \cdot \varepsilon^{-2}$. The lower part of the spectrum for both cases (periodic \times and random \cdot) is shown on the right, clearly depicting the different nature of the two cases. The dotted vertical lines indicate for the random case that there is a single valley of largest, second largest, and third largest diameter, two valleys of fourth largest diameter, and so forth.

$\beta \gtrsim \varepsilon^{-2}$ and certain statistical assumptions on the potential. The key ingredient was to prove the existence of spectral gaps in the presence of disorder in combination with a preconditioned block inverse iteration. For this, particular finite element spaces and quasi-interpolation operators were considered. Further, the connection of valley sizes and eigenvalues was used. More precisely, we considered the first eigenfunctions of the Laplacian in the largest α -valleys with homogeneous Dirichlet boundary conditions to obtain eigenvalue estimates of the Schrödinger operator. These Laplace eigenfunctions also serve as starting functions within the preconditioned block inverse iteration. The claimed decay then follows from the exponential convergence with respect to the number of iteration steps.

The exponential decay may also be characterized a posteriori in terms of the landscape function $\psi \in \mathcal{V}$ defined through

$$(2.2) \quad a(\psi, v) = (1, v)$$

for all test functions $v \in \mathcal{V}$; cf. [FM12]. The connection to the eigenvalue problem (1.1) becomes visible by the possible reformulation as an eigenvalue problem with the effective confining potential $1/\psi$, which encodes the decay of the eigenfunction in some Agmon measure [ADJ⁺16]. This means that the eigenfunction reduces by a certain factor when crossing a valley of $1/\psi$. This interplay was also analyzed in [Ste17] using averages over local Brownian motion paths.

2.4. Finite element discretization. In order to approximate the (localized) eigenstates of the Schrödinger operator, we consider a finite element discretization of (2.1). For this, we consider a uniform refinement of \mathcal{T}^ε , namely, \mathcal{T}^h , consisting of cubes with side length $h = 2^{-\ell_h} \leq \varepsilon$. The corresponding set of nodes is denoted by \mathcal{N}^h and the set of interior nodes by \mathcal{N}_0^h .

Based on \mathcal{T}^h , we define $V_h := Q_1(\mathcal{T}^h) \cap \mathcal{V} \subseteq \mathcal{V}$ as the conforming Q_1 -finite element space; cf. [BS08, sect. 3.5]. This space has the dimension $n := |\mathcal{N}_0^h|$ and is spanned by the standard Q_1 hat functions, which we denote by φ_z^h for $z \in \mathcal{N}_0^h$. Recall that φ_z^h is a piecewise polynomial of partial degree one with $\varphi_z^h(z) = 1$ and $\varphi_z^h(w) = 0$ for any other node $w \in \mathcal{N}^h \setminus \{z\}$. Clearly, hat functions can also be defined on the original mesh \mathcal{T}^ε with respect to its set of interior nodes $\mathcal{N}_0^\varepsilon$. For these hat functions we write φ_z^ε for $z \in \mathcal{N}_0^\varepsilon$.

We now apply a Galerkin ansatz to the eigenvalue problem (2.1). Thus, we restrict the trial and test space to V_h , which then leads to a discrete eigenvalue problem of the form

$$(2.3) \quad A_h u_h = \lambda_h M_h u_h.$$

Here, $A_h \in \mathbb{R}^{n,n}$ and $M_h \in \mathbb{R}^{n,n}$ denote the symmetric stiffness and mass matrices defined through

$$(A_h)_{ij} := a(\varphi_{z_i}^h, \varphi_{z_j}^h), \quad (M_h)_{ij} := (\varphi_{z_i}^h, \varphi_{z_j}^h).$$

Note that the stiffness matrix already includes the potential. Eigenpairs of the matrix eigenvalue problem (2.3) approximate eigenpairs of the PDE eigenvalue problem (2.1). Due to the min-max principle of eigenvalues based on the Rayleigh quotient, we know that $\lambda_1 \leq \lambda_{h,1}$.

As mentioned above, we consider highly oscillatory potentials meaning that ε is small. Further, the mesh size h needs to be sufficiently small compared to ε in order to resolve the oscillations of the potential, and thus guaranteeing a reasonable approximation of the eigenpairs. Such a condition on the minimal resolution is justified by standard a priori error analysis. If D is convex, any eigenfunction $u \in H_0^1(D)$ is H^2 regular. When normalized in $L^2(D)$, u satisfies the bound

$$\|D^2 u\| \leq \|\Delta u\| = \|\lambda u - Vu\| \leq \lambda + \beta,$$

where λ is the eigenvalue it corresponds to. For the lowermost eigenvalue in the regime of [AHP18], where $\lambda_1 \approx \beta \approx \varepsilon^{-2}$, this leads to an error bound

$$\frac{\lambda_{h,1} - \lambda_1}{\lambda_1} \lesssim \frac{h^2}{\varepsilon^2} + \frac{h^4}{\varepsilon^4};$$

see, e.g., [SF73, Lem. 6.1]. While the hidden constant in this bound depends only on the quasi-uniformity of the mesh, multiplicative constants in bounds for larger eigenvalues or any eigenfunction may deteriorate with the distance to neighboring eigenvalues in the case of clustered eigenvalues [Yse13]. In this sense the resolution condition $h \lesssim \varepsilon$ is minimal for the approximation of the lowermost eigenvalue and may be much more restrictive in other cases. As a result, the eigenvalue problem (2.3) is of large dimension, which makes the solution computationally costly.

As we are interested in the smallest eigenvalues and the corresponding localized eigenstates, we aim to construct a preconditioner based on local operations. Such a *localization-preserving* preconditioner then allows parallel computations and is the subject of the following section.

3. Localization preserving preconditioner. In [AHP18] we have presented a locally operating preconditioner based on a domain decomposition of D , which was a key ingredient for the proof of the exponential decay of the first eigenstates. The construction, however, was tailored to theoretical needs and checkerboard potentials. It included exact projections of local subdomains. For actual computations, it turns out that already a simple multigrid preconditioned iteration may act as a localized version of a block inverse power method, leading to sophisticated approximation results. In order to preserve locality, the coarsest level used within the multigrid cycle is the mesh \mathcal{T}^ε on which the potential is defined. This still yields an optimal preconditioner due to the properties of the Green's function of the Schrödinger operator.

Further, we discuss how to find a low-dimensional starting subspace of local functions with which we can initialize the eigenvalue iteration. This is a crucial step in order to obtain local approximations of the lowermost eigenfunctions.

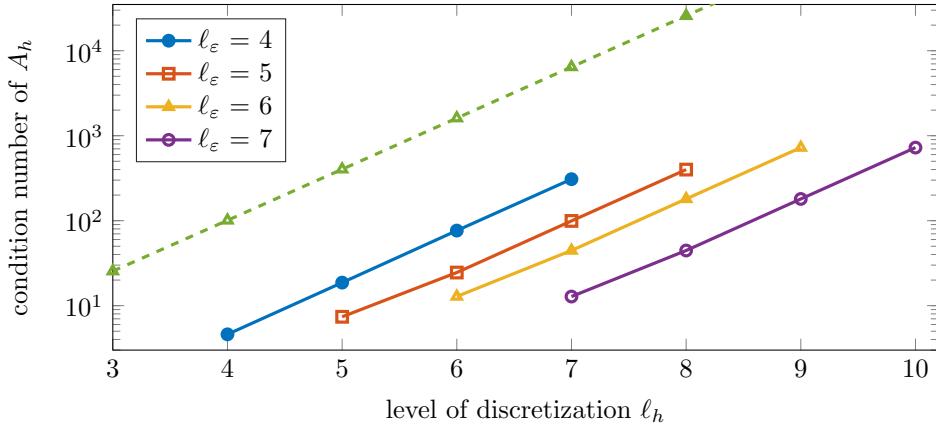


FIG. 3.1. Condition numbers of A_h for different values of $\varepsilon = 2^{-\ell_\varepsilon}$ and $h = 2^{-\ell_h}$. This includes A_ε if $\ell_h = \ell_\varepsilon$. The stiffness matrix is based on a random potential in 2D, only taking the values $\alpha = 0$ or $\beta = 5 \cdot \varepsilon^{-2}$ with equal probability. The dashed line shows the condition number of A_h without a potential.

3.1. Multigrid preconditioner. Recall that we have assumed that the finite element mesh \mathcal{T}^h is defined by a uniform refinement of the mesh on the ε -level on which the potential is defined. Thus, we have a mesh hierarchy given by \mathcal{T}^h , possible intermediate meshes, and \mathcal{T}^ε . For this hierarchy, we define a standard geometric multigrid method without direct solve on the coarsest level, which will serve as a preconditioner for the eigenvalue iteration. A major aspect is that the multigrid method maintains locality, i.e., for a local right-hand side b the resulting approximate solution of $A_h^{-1}b$ is supported on a domain which is only slightly larger than the support of b .

Given the mesh hierarchy, we consider a so-called V-cycle with only one smoothing step on each level; cf. [Hac85, McC87, Yse93]. Beginning with a vanishing starting vector, we consider the residuals of $A_h x = b$ on different levels of the hierarchy. On the coarsest level, i.e., on \mathcal{T}^ε , we run one single relaxation step. This means that we do not use a direct solver on the ε -level with the stiffness matrix A_ε but use instead a single step of the Jacobi iteration. This yields a reasonable approximation, since the condition number of A_ε is of order 1. The reason for this is the shift by the potential in the bilinear form a in (2.1) and the fact that $\beta \gtrsim \varepsilon^{-2}$. A computational study of the condition numbers of the stiffness matrices A_h and A_ε is shown in Figure 3.1. We emphasize that a direct solver would ruin the locality immediately.

On each level of the multigrid cycle the support of the iterate grows slightly due to the application of the stiffness matrix on the respective level. In total, the application of this preconditioner enlarges the support by strictly less than three layers of ε -cubes.

It is well known that multigrid solvers with a reduced tolerance (we only perform one V-cycle with a single relaxation step per level) can be used efficiently as a preconditioner within an external iterative solver, leading to methods such as *preconditioned conjugate gradient* (pcg) or *locally optimal preconditioned conjugate gradient* (lopchg); cf. [KN03]. To keep things simple, we concentrate on pcg. We denote the application of j steps of pcg with the multigrid preconditioner by \mathcal{P}_j . Thus, $\mathcal{P}_j(b)$ yields an approximation of $A_h^{-1}b$, where the accuracy can be controlled by the number of iteration steps. We emphasize that \mathcal{P}_j preserves locality in the following sense.

THEOREM 3.1 (localization preserving property of \mathcal{P}_j). *Assume that $x \in \mathbb{R}^n$ is the coefficient vector of a local function $u_h \in V_h \subset \mathcal{V}$. Then $\mathcal{P}_j(x)$ is the representative of a function in V_h with support being at most $3j$ layers of ε -cubes larger than $\text{supp}(u_h)$.*

Proof. As already mentioned, the application of a V-cycle as described above affects less than three layers of ε -cubes. More precisely, the support enlarges at most within a ball of radius $3\varepsilon - h$ around $\text{supp}(u_h)$. The conjugate gradient step involves another application of the stiffness matrix on the finest level and thus adds only one layer of h -cubes to the support. In total this leads to a growth of 3 layers with side length ε per pcg step. \square

Remark 3.2. Note that the choice of the preconditioner is by far not unique and may be replaced, e.g., by local variants of hierarchical basis [Yse86] or BPX [BPX90] preconditioners or Gamblets [XZO18]. Here, local means that \mathcal{T}^ε is the coarsest level in the underlying hierarchy of meshes.

3.2. Starting subspace. For an efficient eigenvalue iteration we also need a suitable starting subspace. Starting, for example, with a vector which has only positive entries, we will approach the groundstate, but every iteration step is “global.” Instead, we search for a number of local functions at positions where we expect localization of the first eigenfunctions. For the detection of a suitable starting subspace we discuss several approaches.

3.2.1. Landscape function. One possibility to find spots of localization is to compute the already mentioned *landscape function* $\psi \in \mathcal{V}$; cf. [FM12]. This function is defined as the solution of the Schrödinger source problem with right-hand side 1 and homogeneous Dirichlet boundary conditions; cf. (2.2). In other words, ψ is the outcome of one step of the inverse power method in the PDE setting. The corresponding discrete approximation ψ_h satisfies

$$\psi_h = A_h^{-1} M_h \mathbf{1},$$

where $\mathbf{1} = [1, 1, \dots, 1]^T \in \mathbb{R}^n$. The landscape function shall indicate where the first eigenfunctions may localize. To see this, let u_1 denote the normalized groundstate of the Schrödinger eigenvalue problem, i.e., $\|u_1\|_{L^\infty(D)} = 1$. Then it is shown in [FM12] that the landscape function satisfies pointwise

$$(3.1) \quad |u_1(x)| \leq \lambda_1 |\psi(x)|.$$

This bound implies that in regions where ψ is small compared to the smallest eigenvalue λ_1 , the eigenfunction u_1 needs to be small as well. Considering the peaks of the landscape function then provides empirically accurate predictions on where to expect localization. However, since we know that $\lambda_1 \gtrsim \varepsilon^{-2}$, the estimate may degenerate quickly to $|u_1(x)| \leq 1 = \|u_1\|_{L^\infty(D)}$. Thus, this approach does not allow rigorous predictions a priori but may serve as an indicator.

Although the estimate (3.1) only includes the groundstate, the landscape function has been used to locate a larger number of eigenfunctions by analyzing the local minima of ψ ; cf. [ADF⁺19]. Further, it may be used to partition the computational domain D into a network of valleys; cf. Figure 3.2. Yet another possibility is to consider multiple applications of the inverse Schrödinger operator, i.e., $(A_h^{-1} M_h)^k \mathbf{1}$ in the discrete setting; cf. [Ste17].

3.2.2. Randomized landscape function. A similar approach to detect positions of localization was introduced in [LS18]. Therein, the inverse power method is

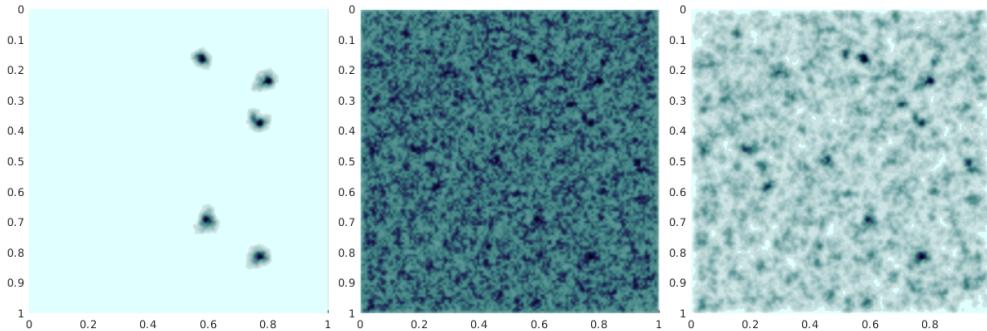


FIG. 3.2. Sum of the first five eigenfunctions (left) for a two-dimensional random potential with $\ell_\varepsilon = 7$, $\beta = 5 \cdot \varepsilon^{-2}$ and the corresponding landscape function ψ (middle). Four additional steps of the inverse power method leads to a more selective landscape (right).

applied to the unit vectors of dimension n . More precisely, for a fixed parameter $p \in \mathbb{N}$ and $e_k \in \mathbb{R}^n$ denoting the k th unit vector, one computes for $k = 1, \dots, n$

$$f_p(k) = \log (\|(A_h^{-1} M_h)^p e_k\|_2).$$

In [LS18] it was shown that highly localized eigenfunctions correspond to metastable states of the power iteration and thus are directly connected to local maxima of the function f_p . Note that in the given setting f_p computes the inverse iteration to all hat functions on the h -scale, which is expensive due to the size of the eigenvalue problem.

A variant is the following randomized version: Given a random matrix $R \in \mathbb{R}^{n,m}$ with $m \ll n$ we compute

$$f_{R,p}(k) = \log (\|e_k^T (A_h^{-1} M_h)^p R\|_2).$$

Thus, we apply the inverse power method to random vectors and consider the means in each component. In other words, we replace the application of $A_h^{-1} M_h$ to n local functions by the application to m global functions [LS18]. The outcome of this approach is displayed in Figure 3.3. It shows a landscape function which seems more smoothed than the previous approach of section 3.2.1. Further, an increase of the number of iterations does not focus purely on the groundstate, as this would happen by applying the inverse power method to the vector $M_h \mathbf{1}$.

3.2.3. Largest valleys. Assume that the potential V is given in the form of a random checkerboard, i.e., the function values of V are either α or β , each with probability 0.5. Then, motivated by the theoretical findings in [AHP18], we may start with a number of hat functions distributed in the largest valleys. Here, a valley denotes a cube in which the potential is constant α . For special classes of such checkerboard potentials, this approach guarantees to yield an appropriate starting subspace, meaning that the number of initial functions is $\mathcal{O}(1)$, that these functions are local, and that the inverse power method converges quickly; cf. [AHP18].

However, the search for valleys comes with the drawback that one first needs to analyze the structure of the given potential. Further, a generalization of the term valley is needed to consider general potentials. Nevertheless, the idea motivates the subsequent approach using uniformly distributed hat functions.

3.2.4. Uniformly distributed hat functions. The current approach combines the benefits of the previous subsections. In this manner, we obtain a suitable subspace of local functions which is highly eligible to serve as a starting point within a

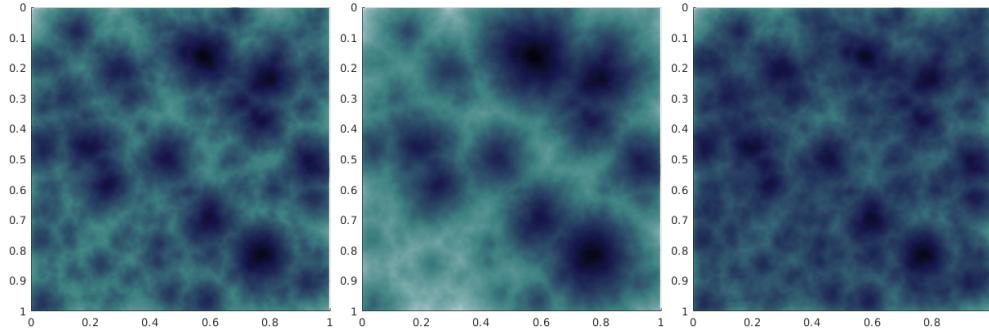


FIG. 3.3. Examples of randomized landscape functions $f_{R,p}$ using m random vectors and p applications of the inverse power method (left: $m = 1$, $p = 50$; middle: $m = 3$, $p = 100$) with the same potential as used in Figure 3.2. The plot on the right shows the result for $m = 3$ and $p = 1000$ if we replace A_h^{-1} by $I_n - A_h/\|A_h\|$.

(preconditioned) eigenvalue iteration. At the same time, the computational costs are comparable to a single step of the inverse power method.

Let \mathcal{T}^H be a mesh of cubes with side length $H = 2^{-\ell_H} \geq \varepsilon$ such that \mathcal{T}^ε is a refinement of \mathcal{T}^H and thus $\ell_H \leq \ell_\varepsilon$. For each interior node $z \in \mathcal{N}_0^H$ there exists a Q_1 hat function φ_z^H . Similarly to the approach in section 3.2.2 we may now apply several steps of the inverse power method. Instead, we apply a single pcg iteration step, as introduced in section 3.1, to each hat function. Note that all these computations may be performed in parallel and that the application of \mathcal{P}_1 maintains locality in the sense that the support of $\mathcal{P}_1(\varphi_z^H)$ is only slightly larger than the support of φ_z^H ; cf. Theorem 3.1. Although we perform only one pcg step, we gain sufficient information in order to rank the importance of the basis function. For this we compute the energies $\lambda(\mathcal{P}_1(\varphi_z^H))$ and sort them in an increasing order. Afterwards, we only keep the functions of lowest energy defined through a fixed ratio, $0 < \eta < 1$. This procedure is then repeated until the number of functions is small enough.

We emphasize that the support of each function only grows gently in each step, whereas the number of functions decreases by the prescribed factor η . In other words, the proposed algorithm is approximately as costly as computing the landscape function ψ ; cf. section 3.2.1. Here, however, we directly obtain a number of candidates where the first eigenfunctions will localize without the need for constructing a network structure. An illustration of the algorithm is given in Figure 3.4.

3.3. Approximation of eigenfunctions. In this subsection we finally introduce an algorithm to approximate the eigenfunctions of lowest energy of the linear Schrödinger eigenvalue problem (2.1) under disorder potentials. Thus, we do not only intend to find possible regions of localization but actually compute approximations of the smallest eigenvalues and their corresponding eigenstates as well.

Recall the definition of \mathcal{P}_j in section 3.1 containing j pcg steps preconditioned by a multigrid cycle. Further, we fix the following parameters.

Parameter	Default value	Meaning
N_{eigs}	5	number of eigenfunctions to compute
K_{pre}	3	number of preiteration steps
K_{post}	5	number of postiteration steps
ℓ_H	$\ell_\varepsilon - \lfloor \log(\ell_\varepsilon) \rfloor$	level of \mathcal{T}^H for initial hat functions
η	0.2	ratio for selection process

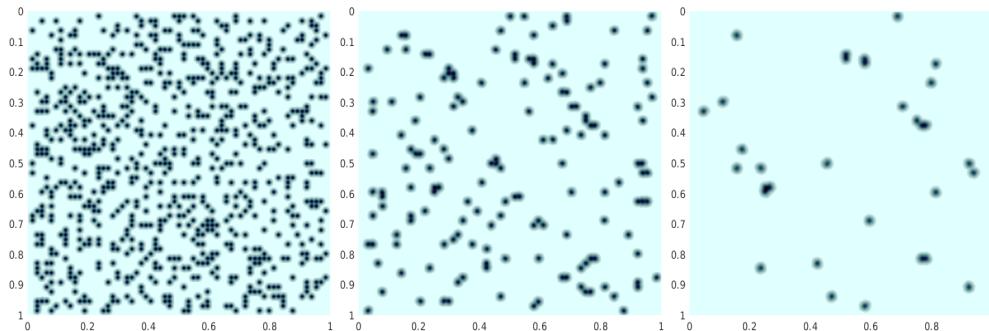


FIG. 3.4. Illustration of finding an appropriate local and low-dimensional starting subspace. Starting point is the hat functions on a coarser grid \mathcal{T}^H . After each pcg step a fixed amount of functions is selected. Pictures show the results for $\eta = 0.2$ after one (left), two (middle), and three (right) pcg steps.

The proposed algorithm consists of two parts: During *preiteration*, we apply the selection process described in section 3.2.4. For this, we consider hat functions on a (coarser) mesh of level ℓ_H . Using the hat functions corresponding to \mathcal{T}^H rather than \mathcal{T}^ε reduces the number of initial functions. Further, we truncate these hat functions in order to improve the locality. After K_{pre} iteration steps with ratio η we then have a much smaller number of functions, which already give a rough approximation of certain eigenfunctions. Most notably, however, they indicate with high precision where localization will take place without the need for constructing an additional mesh or finding local minima as with the landscape approach. If we are only interested in the groundstate, then one may reduce the number of functions until only a single function is left. Otherwise, we need to keep a sufficiently large amount of functions within the iteration process in order to prevent only the groundstate from being approximated. Further, since we only perform rough approximations of the inverse power method, we cannot guarantee that the functions of lowest energy correspond to the lowermost eigenstates. Therefore, we always keep at least $3 N_{\text{eigs}}$ functions within the preiteration.

In *postiteration*, we combine all functions which were selected by the preiteration in the form of a Ritz–Rayleigh approximation. This means that we first perform three pcg steps to each function and then project the mass and stiffness matrices to the span of these functions and solve a (small) eigenvalue problem of the form $\mathbf{M}\alpha = \mu\mathbf{A}\alpha$. Note that the dimension of the eigenvalue problem depends on the number of preiteration steps. The first eigenvector α_1 contains the coefficients of the optimal linear combination of the ansatz functions and provides the approximate groundstate. The second eigenvector α_2 then defines the function which serves as approximation of the second eigenstate, and so on. Further, we decrease the number of ansatz functions by cutting off the candidates of highest energy. Similar to the preiteration, we always keep a certain number of functions, namely, twice the amount of eigenfunctions we are interested in, i.e., $2 N_{\text{eigs}}$. Note that, in contrast to the parallel steps within the preiteration, we consider here a combined iteration of all remaining candidates.

A summary of the procedure is given in Algorithm 1, and obtained numerical results for the two- and three-dimensional cases are discussed in the subsequent section.

Remark 3.3. The simple pcg steps in the preiteration of Algorithm 1 (line 6) may also be replaced by K_{pre} steps of lopcg; cf. [Kny00, Kny01]. Since the main purpose

Algorithm 1. Approximation of first N_{eigs} localized eigenstates.

```

1: Input:  $N_{\text{eigs}}, K_{\text{pre}}, K_{\text{post}}, \ell_H, \eta$ 
2: define mesh  $\mathcal{T}^H$  with  $H = 2^{-\ell_H}$ 
3:  $m = |\mathcal{N}_0^H|$ 
4: coefficient matrix of hat functions  $\Phi = [\varphi_1^H, \dots, \varphi_m^H] \in \mathbb{R}^{n,m}$ 
5: for  $k = 1$  to  $K_{\text{pre}}$  do ▷ start preiteration
6:    $\Phi = \mathcal{P}_1(M_h \Phi)$ 
7:    $\Phi_j = \Phi_j / \|\Phi_j\|_{M_h}, j = 1, \dots, m$ 
8:   energies =  $\text{diag}(\Phi^T A_h \Phi)$ 
9:   [energies, idx] =  $\text{sort}(\text{energies})$ 
10:   $m = \max(\lfloor \eta m \rfloor, 3 N_{\text{eigs}})$ 
11:   $\Phi = [\Phi_{\text{idx}(1)}, \dots, \Phi_{\text{idx}(m)}]$ 
12: for  $k = 1$  to  $K_{\text{post}}$  do ▷ start postiteration
13:    $\Phi = \mathcal{P}_3(M_h \Phi)$ 
14:    $\Phi_j = \Phi_j / \|\Phi_j\|_{M_h}, j = 1, \dots, m$ 
15:    $\mathbf{M} = \Phi^T M_h \Phi \in \mathbb{R}^{m,m}$ 
16:    $\mathbf{A} = \Phi^T A_h \Phi \in \mathbb{R}^{m,m}$ 
17:   solve eigenvalue problem  $\mathbf{M}\alpha = \mu \mathbf{A}\alpha$ 
18:   resulting eigenpairs  $(\alpha_1, \mu_1), \dots, (\alpha_m, \mu_m)$  with  $\mu_1 \leq \dots \leq \mu_m$ 
19:    $m = \max(\lfloor \eta m \rfloor, 2 N_{\text{eigs}})$ 
20:    $\Phi = [\Phi\alpha_1, \dots, \Phi\alpha_m]$ 

```

of the preiteration is the detection of regions of localization, we consider here only this simple variant.

Remark 3.4. In order to accelerate the iteration and improve the stability of the method, one may consider additional cut-offs. In particular, one may set components of α_j in line 18 of Algorithm 1 to zero if they are beneath a certain threshold. This also increases the level of locality.

The procedure of Algorithm 1 assumes that the first eigenfunctions are indeed localized. Thus, global eigenstates as they would appear for periodic potentials are not well approximated by this method. However, one may adapt the selection process in the algorithm to such an extent that periodic structures are at least detected. For this, one may substitute the fixed-ratio criterion with a selection step which is based on the energies of the considered functions. In a periodic structure, where all hat functions would have a comparable energy, we would then not cut off any functions, meaning that the parameter m does not decrease and that the eigenvalue problem in line 17 of the algorithm is still of large dimension.

4. Numerical examples. We perform several numerical tests in order to explore the performance and feasibility of the proposed method. In the first experiment we consider the two-dimensional random potential, which was already used in section 3 for the illustration of the approaches used to find regions of localization. Second, we consider a three-dimensional speckle potential leading to huge eigenvalue problems which quickly overcharge standard eigenvalue solvers. Finally, we apply the method

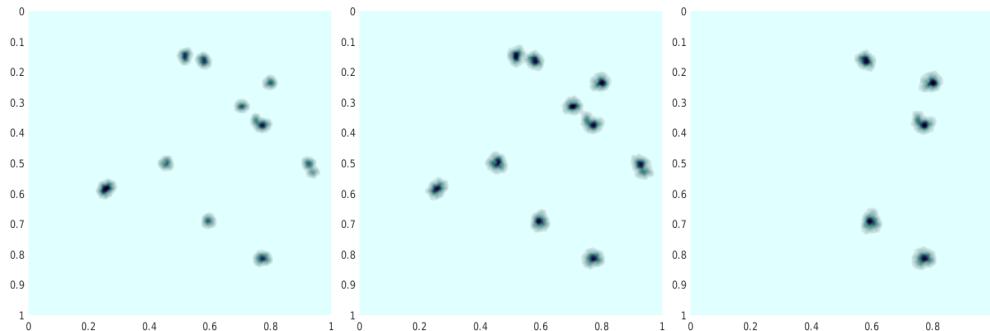


FIG. 4.1. Outcome of Algorithm 1 with the default parameters after one (left), three (middle), and five (right) Ritz-Rayleigh steps. The two pictures on the left show the sum of all remaining functions, whereas the picture on the right includes only the five functions of lowest energy. Cf. Figure 3.2 for a reference solution.

to the nonlinear GPEVP.

All computations have been performed with MATLAB on an *HPC Infiniband cluster* (1.7 TB RAM, 2 Tesla V100 32GB GPUs). The reference solutions, which are used for the error plots, are obtained by the MATLAB solver *eigs* with tolerance 10^{-12} for the two-dimensional examples and 10^{-10} in three dimensions, both with a maximum of 100 iterations. The code is available as supplementary material.

4.1. Random potential in two dimensions. In this first numerical experiment we consider a random potential in two space dimensions with parameters

$$\ell_\varepsilon = 7, \quad \ell_h = 9, \quad \ell_H = 6, \quad \alpha = 1, \quad \beta = 5 \cdot \varepsilon^{-2}.$$

We are interested in the first five eigenstates of lowest energy. The outcome of the preiteration with $\eta = 0.2$ was already illustrated in Figure 3.4, leading to a small number of regions in which we expect the smallest eigenstates to localize. Applying the Ritz-Rayleigh method and the additional selection process, we end up in a ten-dimensional subspace of V_h , where all basis functions have local support. The five functions with lowest energy then serve as approximations of the eigenfunctions u_1, \dots, u_5 . The results, depicted in Figure 4.1, are very convincing. For a comparison with the actual eigenstates, we refer the reader to Figure 3.2 (left).

As mentioned above, the preiteration only provides very rough approximations of the eigenstates and is more useful in finding an appropriate starting subspace for the Rayleigh–Ritz method. As a result, the assignments of the localization regions to the actual eigenstates may be inaccurate in the beginning. In the present example, four Rayleigh–Ritz steps were needed until the fifth eigenstate was correctly assigned. This effect can also be observed in the convergence plot in Figure 4.2. Therein, the relative error in λ_5 drops significantly from step 6 to step 7. Such effects are directly influenced by gaps within the spectrum of the Schrödinger operator. Here, the fifth and sixth eigenvalues are given by $2.6076 \cdot 10^4$ and $2.6093 \cdot 10^4$ and thus at close quarters.

Figure 4.3 shows that the proposed method also works if we are interested in a larger number of eigenvalues and eigenfunctions. If we only consider the preiteration, the relative error of the eigenvalues seems to be almost constant, which is in agreement with the observations in [ADF⁺19]. In contrast to the landscape function approach, we are able to control the accuracy of the method by the number of post-

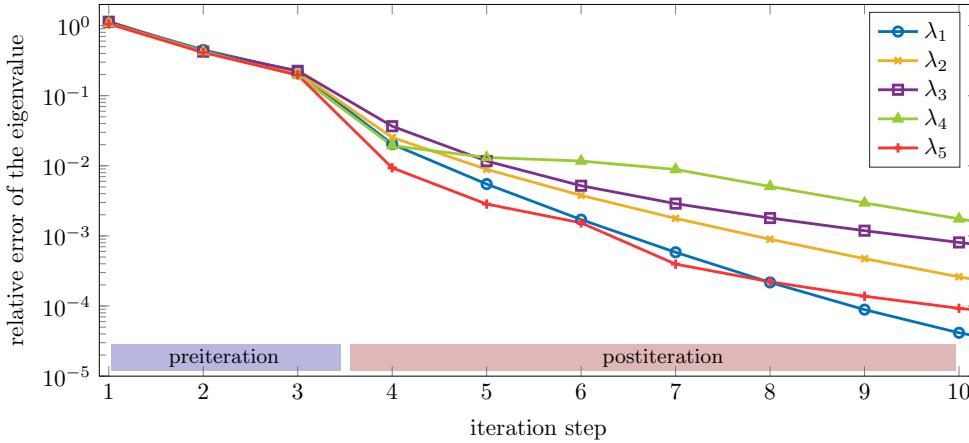


FIG. 4.2. Convergence history of the relative error of the first five eigenvalues $\lambda_1, \dots, \lambda_5$. Iteration steps 1–3 are the preiteration; the remaining steps are part of the postiteration of Algorithm 1.

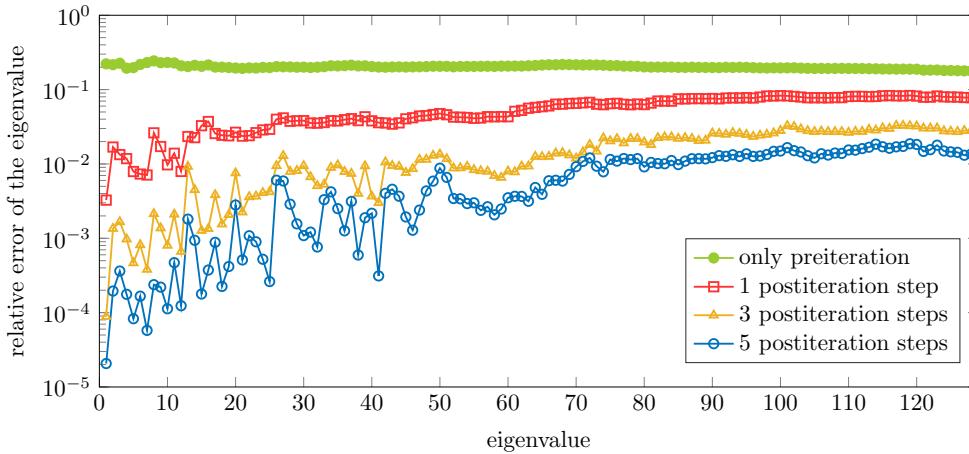


FIG. 4.3. Reliability of the method for a large number ($1/\varepsilon = 128$) of eigenvalues.

iterations. Further, the method is flexible enough to recognize when there are several eigenfunctions located in a single valley.

4.2. Speckle potential in three dimensions. The second example considers the linear Schrödinger eigenvalue problem (1.1) in three space dimensions with a speckle-like potential as is used in actual experiments [FFI08]. For parameters we choose

$$\ell_\varepsilon = 5, \quad \ell_h = 6, \quad \ell_H = 4, \quad \alpha = 1, \quad \beta = 5 \cdot \varepsilon^{-2}.$$

An illustration of the potential is given in Figure 4.4. As for the previous example we compare the outcome of Algorithm 1 with the results obtained by the *eigs* solver in MATLAB. As a consequence, we are not able to exceed level $\ell_h = 6$, as this marks the limit of the integrated eigenvalue solver.

The approximation of the first eigenfunction and the corresponding result obtained by *eigs* are compared in Figure 4.4. The displayed approximations are com-

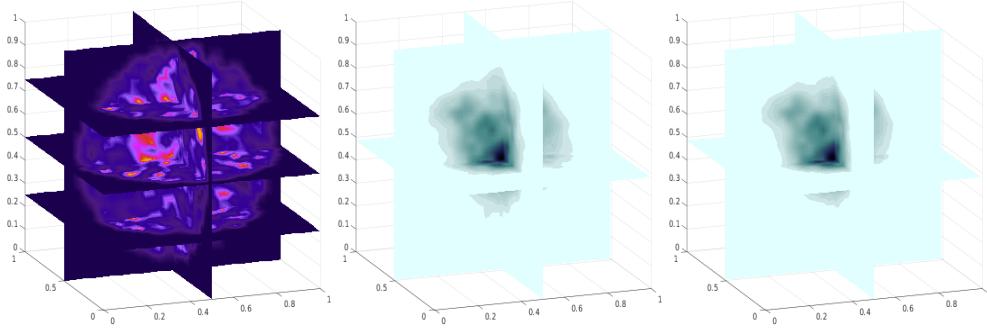


FIG. 4.4. Speckle potential (left) and comparison of the first eigenfunction (middle) and its numerical approximation obtained by Algorithm 1 (right).

puted with $K_{\text{pre}} = 3$ pre- and $K_{\text{post}} = 5$ postiteration steps. A comparison of computation times for various mesh levels of \mathcal{T}^ε and \mathcal{T}^h is summarized in the following table:

	$\ell_h = \ell_\varepsilon + 1$			$\ell_h = \ell_\varepsilon + 2$		
	$\ell_\varepsilon = 4$	$\ell_\varepsilon = 5$	$\ell_\varepsilon = 6$	$\ell_\varepsilon = 3$	$\ell_\varepsilon = 4$	$\ell_\varepsilon = 5$
MATLAB <i>eigs</i>	7.15 s	279.10 s	∞	7.21 s	228.60 s	∞
Algorithm 1	4.86 s	57.65 s	1788.02 s	6.43 s	74.99 s	1242.41 s

4.3. Nonlinear Gross–Pitaevskii eigenvalue problem. In this final example we consider the nonlinear version of the Schrödinger equation, describing quantum–physical processes with interaction. This GPEVP has the form

$$-\Delta u + Vu + \delta|u|^2u = \lambda u$$

with $\delta \geq 0$ regulating the nonlinearity. For moderate values of δ , similar localization results for the groundstates can be observed [APV18]. As a result, the localization-preserving preconditioner presented here promises good approximation results. We emphasize that this nonlinear case is not easily treated by the landscape function approach. Considering again a finite element discretization as in section 2.4, we obtain the nonlinear matrix eigenvalue problem

$$A_h u_h + \delta N_h(u_h) u_h = \lambda M_h u_h,$$

where $N_h(u_h)$ equals the finite-dimensional approximation of the nonlinearity. Inspired by the inverse iteration for the linear case, i.e., $u_h^{n+1} = A_h^{-1}M_h u_h^n$, one may consider the iteration

$$u_h^{n+1} = (A_h + \delta N_h(u_h^n))^{-1} M_h u_h^n$$

with an additional normalization step. This then leads to the results shown in Figure 4.5, illustrating that the groundstate can be well approximated by local functions also in the nonlinear case. It goes without saying that the iteration scheme may be replaced by more advanced methods, e.g., based on gradient flows [BD04, HP18, AHP19].

5. Conclusion. In this paper, we have constructed a novel iterative scheme using analytical inside and adapting numerical analysis techniques used in localization proofs of the eigenstates [AHP18]. This novel method is solely based on local operations (relative to the oscillation/correlation length of the potential) and, hence, able to

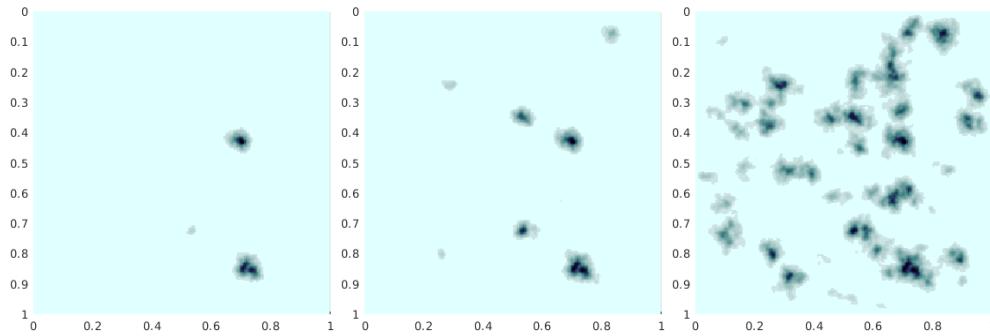


FIG. 4.5. Approximation of the groundstate for the GPEVP for $\delta = 1$ (left), $\delta = 10$ (middle), and $\delta = 100$ (right) for a two-dimensional random potential with $\ell_\varepsilon = 7$, $\beta = 5 \cdot \varepsilon^{-2}$. Results after 100 iteration steps with initial function being constant 1.

approximate eigenfunctions of the random Schrödinger operator up to high precision. For this, we exploit the fact that oscillatory, high-amplitude random potentials lead to a localization of the lowermost eigenstates, which allows an efficient computation.

The numerical experiments prove the applicability of the method also for the three-dimensional case as well as the corresponding nonlinear eigenvalue problem. Future research aims to further develop this approach in view of other applications with similar localization effects (such as light in a disordered medium [WBLR97]) as well as time-dependent problems.

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