

Let u , v and w (and the corresponding Reynolds stress tensor) be defined on a grid $Ox \times Oy \times Oz$ where the unit vector \hat{e}_x is turned by θ with respect to the [negative] direction of surface shear stress¹. We require the velocities on the grid $Ox_\star \times Oy \times Oz_\star$ that is aligned with the surface shear stress, i.e.

$$\begin{pmatrix} \hat{e}_{x_\star} \\ \hat{e}_y \\ \hat{e}_{z_\star} \end{pmatrix} = \begin{pmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{pmatrix} \begin{pmatrix} \hat{e}_x \\ \hat{e}_y \\ \hat{e}_z \end{pmatrix}. \quad (1)$$

This implies

$$\begin{aligned} u_\theta &= u \cos \theta + w \sin \theta \\ w_\theta &= -u \sin \theta + w \cos \theta. \end{aligned}$$

Let $c_\theta \equiv \cos \theta$, $s_\theta \equiv \sin \theta$ and $m_\theta = \sin \theta \cos \theta$. The corresponding Reynolds stress tensor is

$$\begin{pmatrix} u_\theta u_\theta & u_\theta v_\theta & u_\theta w_\theta \\ u_\theta v_\theta & v_\theta v_\theta & v_\theta w_\theta \\ u_\theta w_\theta & v_\theta w_\theta & w_\theta w_\theta \end{pmatrix} = \begin{pmatrix} (uc_\theta + ws_\theta)^2 & uvc_\theta + wvs_\theta & (uc_\theta + ws_\theta)(-us_\theta + wc_\theta) \\ & vv & (-us_\theta + wc_\theta)v \\ & & (-us_\theta + wc_\theta)^2 \end{pmatrix} \quad (2)$$

$$= \begin{pmatrix} u^2 c_\theta^2 + w^2 s_\theta^2 + 2uwm_\theta & uvc_\theta + wvs_\theta & m_\theta(w^2 - u^2) + uw(c_\theta^2 - s_\theta^2) \\ & v^2 & -uvs_\theta + wvc_\theta \\ & & u^2 s_\theta^2 + w^2 c_\theta^2 - 2uwm_\theta \end{pmatrix} \quad (3)$$

$$= \begin{pmatrix} u^2 c_\theta + w^2 s_\theta & & \\ & v^2 & \\ & & u^2 s_\theta + w^2 c_\theta \end{pmatrix} \quad (4)$$

¹Here, negative means that we consider the grid aligned with the positive vector of the velocity gradient at the surface