

# AAO Final Project

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## Abstract

My term project is to plot the HR diagram of M6 open cluster. To achieve the goal, I do image reduction, stacking, flux measurement, standard star calibration, and error estimation. The whole code is available on the following website:[https://github.com/zrk-dreamer/Advanced-Astronomical-Observation/blob/main/AAO\\_project.ipynb](https://github.com/zrk-dreamer/Advanced-Astronomical-Observation/blob/main/AAO_project.ipynb)

## 1 Procedure

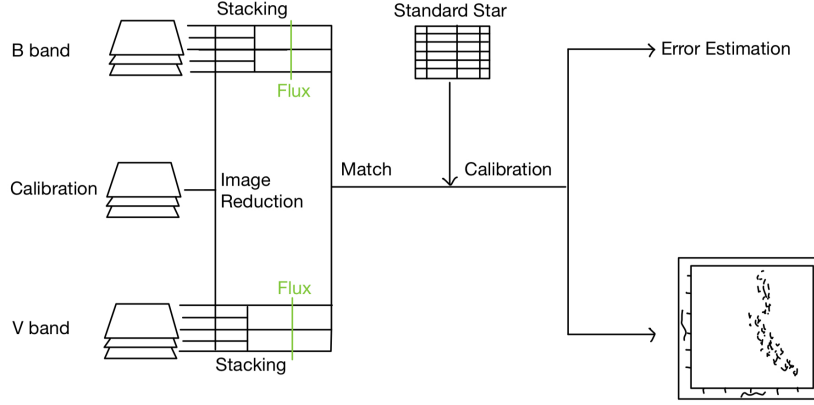
In this section, I will show the details of the procedures.

### 1.1 Image Reduction

I performed image reduction using the calibration frames shot under  $-15^{\circ}\text{C}$  and the dark frames with the same exposure time to the light frames. (B: 4sec, 40sec, and 8min; V: 3sec, 30sec, 5min) After the reduction, I got six sets of reduced images with different bands and different exposure time.

### 1.2 Stacking

Before registration, to deal with artifacts (hot pixels or dead pixels) and to avoid their effect on the transformation, I first used Python package called `ccdproc` to clean the images (`ccdproc.cosmicray_lacosmic`). Then I use another package called `astroalign` to perform registration and transformation. After, stacking, I use mean method to stack the images. Finally, I got six



stacked images with different bands and different exposure time.

### 1.3 Flux Measurement

To remove background and perform aperture photometry, I used a package called SEP(Source Extraction and Photometry). First, I use `sep.Background` to get global backgrounds, and then I subtract backgrounds from the stacked images. Next I use `sep.extract` to find positions, semi-major axes, semi-minor axes, and theta (orientation) of potential object with  $7\sigma$  for V band and  $6\sigma$  for B band. Before the formal measurement of flux, I impose maximum limits on the peak values in the area of detected objects to prevent the saturation. With the information about the objects, I use `sep.sum_ellipse` to calculate the total flux and the associated error. Here, the radius of the aperture (ellipse) is Kron Radius.

### 1.4 WCS and Cross Match

Before going on, I first uploaded the six stacked image to Astrometry.net to do plate solving and to get new header that could be accepted by `astropy.wcs.WCS`. After getting WCS, I could map the position on the images to its corresponding equatorial system coordinate, which allowed me to match the objects detected in V band and in B band. In this case, the threshold is two arcsecond; that's to say, the object with only B band photometry or V band photometry would be discarded. After the cross match, there were

3303 remain objects.

## 1.5 Standard Star Calibration

I first generated a .txt file containing the position (RA, Dec) of those 3303 objects and upload to VizieR to get nearby standard stars (2 arcsecond), including the V mag, the B mag, and the associated error. Then, I perform matching between the standard star catalog and the objects I found; the threshold is one arcsecond. After matching, there were 437 remain objects (The other objects were not discarded in this case). With those remain objects, I use kmpfit from a package called Kapteyn to do fitting and try to figure out the extinction coefficient  $K$ , the zero point  $\gamma$ , and the color term  $\beta$ . However, during fitting,  $K$  and  $\gamma$  tend to show degeneracy ( $-KX + \gamma = \text{const.}$ , but the values of reduced  $\chi^2$  is insensitive to  $K$  and  $\gamma$ ); hence I let  $A = -KX + \gamma$ , which becomes a new parameter in my fitting.

## 1.6 Error Estimation

After obtaining the calibration formula, I could do the error propagation. The sources of error are  $A$  and  $\beta$  in the formula (includes the error from standard star) and flux measurement using SEP. As mentioned, the formula I used to do standard star is:

$$m_{\lambda_{std}} = m_{\lambda_{inst}} + A + \beta(m_{\lambda_{inst}} - m_{\lambda_{2,inst}}) \quad (1)$$

Then the associated error can be calculated via following formula:

$$\sigma_{\lambda_{std}}^2 = \sigma_{\lambda_{inst}}^2 + \sigma_A^2 + \beta^2(\sigma_{\lambda_{std}}^2 + \sigma_{\lambda_{2,inst}}^2) + ((m_{\lambda_{inst}} - m_{\lambda_{2,inst}})\sigma_\beta)^2 \quad (2)$$

The result of error estimation will be show in the next section, along with the diagrams.

Case	$A$	$\beta$
To calculate V mag	$21.69237 \pm 0.00970$	$0.04299 \pm 0.03199$
To calculate B mag	$21.66878 \pm 0.00740$	$0.49828 \pm 0.02793$

## 2 Results

