

# Influence Functions

## Empirical Distribution Function

**Definition 1.1.1.** Suppose  $(X_i) \stackrel{\text{IID}}{\sim} F_X$ . The **empirical (cumulative) distribution function**  $\mathbb{F}_n$  is defined as:

$$\mathbb{F}_n(x) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq x).$$

■

**Definition 1.1.2.** The **Kolmogorov-Smirnov** distance between two distributions functions  $F$  and  $G$ , mapping  $\mathbb{R} \rightarrow \mathbb{R}$ , is defined as:

$$d(F, G) = \sup_{x \in \mathbb{R}} |F(x) - G(x)|. \quad (1.1.1)$$

■

**Theorem 1.1.1 (Glivenko-Cantelli).** Suppose  $(X_i) \stackrel{\text{IID}}{\sim} F_X$ . The empirical distribution function  $\mathbb{F}_n$  converges *uniformly almost surely* to  $F_X$ :

$$\sup_{x \in \mathbb{R}} |\mathbb{F}_n(x) - F_X(x)| \xrightarrow{as} 0.$$

□

**Remark 1.1.1.** See Serfling (1980), theorem 2.1.4.

◆

## Statistical Functionals

### 2.1 Definition

**Definition 1.2.1.** A **functional**  $T$  is a mapping from a function space  $\mathcal{F}$  into  $\mathbb{R}$ . Typically,  $\mathcal{F}$  is a linear function (vector) space.

■

**Example 1.2.1.** Let  $\{F, F_0\}$  denote distribution functions. Examples of *statistical functionals* include:

- The expectation of a specified function  $\psi : \mathbb{R} \rightarrow \mathbb{R}$ :

$$T(F) = \int \psi(x) dF(x). \quad (1.2.2)$$

Functionals of the form (1.2.2) are **linear**.

- The  $k$ th central moment:

$$T(F) = \int \left\{ x - \int \xi dF(\xi) \right\}^k dF(x).$$

- The *Cramer von Mises* distance:

$$T(F) = \int \{F(x) - F_0(x)\}^2 dF_0(x).$$



**Example 1.2.2.** Let  $H_x$  denote the Heaviside function:

$$H_x(t) = \int_{-\infty}^t \delta_x(u) du = I(t \geq x),$$

where  $\delta_x(u)$  is a Dirac spike localized to  $x$ . The empirical distribution function is expressible as:

$$\mathbb{F}_n(t) = \frac{1}{n} \sum_{i=1}^n H_{X_i}(t) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq t).$$

The evaluation of a linear functional at  $\mathbb{F}_n$  is:

$$T(\mathbb{F}_n) = \int \psi(x) d \left\{ \frac{1}{n} \sum_{i=1}^n H_{X_i}(x) \right\} = \frac{1}{n} \sum_{i=1}^n \int \psi(x) \delta_{X_i}(x) dx = \frac{1}{n} \sum_{i=1}^n \psi(X_i).$$



## 2.2 Continuity

**Definition 1.2.2** (Lehmann 1999, definition 6.2.1). Let  $d$  denote the KS metric (1.1.1). A statistical functional  $T$  is **continuous** if for any sequence  $G_n \rightarrow F$ ,

$$\lim_{n \rightarrow \infty} d(G_n, F) = 0 \implies \lim_{n \rightarrow \infty} T(G_n) = T(F). \quad (1.2.3)$$



**Proposition 1.2.1 (Functional Consistency).** Suppose  $(X_i) \stackrel{\text{iid}}{\sim} F_X$ , and  $T$  is a continuous functional (1.2.3), then  $T(\mathbb{F}_n)$  is consistent for  $T(F)$ , i.e.  $T(\mathbb{F}_n) \xrightarrow{p} T(F)$ .  $\blacklozenge$

**Proposition 1.2.2** (Huber 2009, lemma 2.1). A *linear functional*  $L$  defined on the space  $\mathcal{F}$  of probability measures on  $(\mathbb{R}, \mathcal{B})$  is **continuous** if and only if it is expressible as:

$$L(F) = \int \psi(x) dF(x),$$

for some *bounded, continuous* function  $\psi : \mathbb{R} \rightarrow \mathbb{R}$ .  $\blacklozenge$

## 2.3 Differentiability

**Definition 1.2.3.** Let  $F$  and  $G$  denote distribution functions. Define the  **$\epsilon$ -contaminated** distribution:

$$F_{G,\epsilon} = (1 - \epsilon)F + \epsilon G. \quad (1.2.4)$$

The **Gateaux differential**  $\partial T(F; G - F)$  of the functional  $T$  at  $F$  in the direction of  $G - F$  is defined by:

$$\partial T(F; G - F) = \lim_{\epsilon \downarrow 0} \frac{1}{\epsilon} \{T(F_{G,\epsilon}) - T(F)\}. \quad (1.2.5)$$

In general, the  $k$ th Gateaux differential is obtained via:

$$\partial^k T(F; G - F) = \lim_{\epsilon \downarrow 0} \left\{ \frac{\partial^k T(F_{G,\epsilon})}{\partial \epsilon^k} \right\}.$$

■

**Example 1.2.3.** Consider the Cramer von Mises functional:

$$T(F) = \int (F - F_0)^2 dF_0.$$

The evaluation at the  $\epsilon$ -contaminated distribution is:

$$T(F_{G,\epsilon}) = \int (F + \epsilon(G - F) - F_0)^2 dF_0.$$

The derivative with respect to  $\epsilon$  is:

$$\frac{\partial}{\partial \epsilon} T(F_{G,\epsilon}) = 2 \int (F + \epsilon(G - F) - F_0)(G - F) dF_0$$

Taking the limit as  $\epsilon \downarrow 0$  gives:

$$\partial T(F; G - F) = \lim_{\epsilon \downarrow 0} \frac{\partial}{\partial \epsilon} T(F_{G,\epsilon}) = 2 \int (F - F_0)(G - F) dF_0.$$

♠

**Discussion 1.2.1.** A functional  $T$  is **Frechet differentiable** if there exists a functional  $\partial T(F; G - F)$ , linear in  $G - F$ , such that:

$$|T(G_n) - T(F) - \partial T(F; G_n - F)| = o\{d(F, G_n)\}$$

for all sequences  $(G_n)$  such that  $d(G_n, F) \rightarrow 0$  as  $n \rightarrow \infty$ .

If  $T$  is continuous in a neighborhood of  $F$  and Frechet differentiable at  $F$ , then the Frechet derivative  $\partial T(F; G - F)$  is continuous at  $F$  (Huber 2009, proposition 2.19). By proposition (1.2.2), there exists a bounded, continuous function  $\psi_F$  such that:

$$\partial T(F; G - F) = \int \psi_F(x) d\{G(x) - F(x)\} = \int \left\{ \psi_F(x) - \int \psi_F(\xi) dF(\xi) \right\} dG(x).$$

Moreover, if the Frechet derivative exists, then the Gateaux derivative exists, and the two are equal (Serfling 1980, section 6.2). Thus, continuity and Frechet differentiability at  $F$  suffice to represent the Gateaux derivative  $\partial T(F; G - F)$  as:

$$\partial T(F; G - F) = \int \varphi_F(x) dG(x),$$

where  $\varphi_F$  bounded, continuous, and mean-zero. When Frechet differentiability cannot be established, it is often *assumed* that the Gateaux derivative is expressible as:

$$\partial h(F; G - F) = \int \psi_F(x) d\{G(x) - F(x)\} = \int \varphi_F(x) dG(x).$$

for some measurable function  $\psi_F$ . Bounding and continuity of  $\varphi_F(x)$  are not assumed. ♠

## Influence Functions

### 3.1 Definition

**Example 1.3.1.** Suppose  $T$  is a statistical functional whose Gateaux derivative admits the representation:

$$\partial T(F; G - F) = \int \varphi_F(x) dG(x).$$

To isolate the function  $\varphi_F(x)$ , set  $G(t) = H_x(t)$ , then:

$$\partial T(F; H_x - F) = \int \varphi_F(t) dH_x(t) = \int \varphi_F(t) \delta_x(t) dt = \varphi_F(x).$$

Therefore, for any other  $G$ , the Gateaux derivative is expressible as:

$$\partial T(F; G - F) = \int \varphi_F(x) dG(x) = \int \{\partial T(F; H_x - F)\} dG(x).$$

$\varphi_F = \partial T(F; G - F)$  is described as the *influence function*. ♠

**Definition 1.3.1.** Suppose  $(X_i) \stackrel{\text{iid}}{\sim} F$ , and  $T$  is a statistical functional. Recall that  $H_x(t) = I(x \leq t)$  denotes the Heaviside function. The **influence function** of  $h$  is the Gateaux derivative of  $T$  at  $F$  in the direction of  $H_x - F$ :

$$\partial T(F; H_x - F) = \lim_{\epsilon \downarrow 0} \left[ \frac{\partial}{\partial \epsilon} T\{F + \epsilon(H_x - F)\} \right]. \quad (1.3.6)$$

■

## 3.2 Properties

**Proposition 1.3.1.** Influence functions inherit the chain, product, and quotient rules from differentiation.

- i. **(Linearity)** If  $T = \sum_{j=1}^m \alpha_j T_j$  is a linear combination of functionals, then:

$$\partial T(F; H_x - F) = \sum_{j=1}^m \alpha_j \partial T_j(F; H_x - F).$$

- ii. **(Product Rule)** If  $T = T_1 \cdot T_2$  is a product of functionals, then:

$$\partial T(F; H_x - F) = \partial T_1(F; H_x - F) \cdot T_2(F) + T_1(F) \cdot \partial T_2(F; H_x - F).$$

- iii. **(Quotient Rule)** If  $T = T_1/T_2$  is a ratio of functionals, then:

$$\partial T(F; H_x - F) = \frac{\partial T_1(F; H_x - F) \cdot T_2(F) - T_1(F) \cdot \partial T_2(F; H_x - F)}{T_2^2(F)}.$$

- iv. **(Chain Rule)** If  $T = U \circ T_1$  is a differentiable function of a functional, then:

$$\partial T(F; H_x - F) = \dot{U}\{T_1(F)\} \partial T_1(F; H_x - F).$$

◆

**Example 1.3.2** (Linear Functional). Consider the linear functional:

$$T(F) = \int \psi(x) dF(x).$$

Evaluating at  $F_{x,\epsilon}$ :

$$T(F_{x,\epsilon}) = \int \psi(u) d\{(1 - \epsilon)F(u) + \epsilon H_x(u)\} = (1 - \epsilon) \int \psi(u) dF(u) + \epsilon \psi(x)$$

Taking the derivative with respect to  $\epsilon$ :

$$\frac{\partial T(F_{x,\epsilon})}{\partial \epsilon} = - \int \psi(u) dF(u) + \psi(x).$$

Thus, the influence function is:

$$\varphi_F(x) = \psi(x) - E\{\psi(x)\}.$$



**Example 1.3.3** (Sample Variance). The variance functional is expressible as:

$$T(F) = \int \{x - T_1(F)\}^2 dF(x),$$

where  $T_1(F)$  is the mean functional. Expanding the quadratic:

$$T(F) = \int \{x^2 + T_1^2(F) - 2xT_1(F)\} dF(x) = T_2(F) - T_1^2(F).$$

where  $T_2$  is the second moment functional. Since the  $k$ th moment is a linear functional, the influence functions for  $T_1$  and  $T_2$  are:

$$\varphi_1(x) = x - \mu_1, \quad \varphi_2(x) = x^2 - m_2.$$

By linearity and the chain rule, the influence function of  $T$  is:

$$\varphi(x) = (x^2 - m_2) - 2\mu_1(x - \mu_1).$$



**Example 1.3.4** (Third Central Moment). The 3rd central moment functional is:

$$T(F) = \int \{x - T_1(F)\}^3 dF(x).$$

Upon expansion:

$$T(F) = T_3(F) - 3T_2(F)T_1(F) + 2T_1^3(F)$$

By linearity, the product and chain rules, the influence function is:

$$\varphi(x) = (x^3 - \mu_3) - 3\{(x^2 - m_2)\mu_1 + m_2(x - \mu_1)\} + 6\mu_1^2(x - \mu_1).$$



### 3.3 von Mises Expansion

**Definition 1.3.2** (Serfling 1980, section 6.2). Suppose  $T$  is a statistical functional. The **von Mises expansion** of order  $m$  is:

$$T(\mathbb{F}_n) - T(F) = V_{n,m} + R_{n,m}, \quad (1.3.7)$$

where  $V_{n,m}$  is given by:

$$V_{n,m} = \sum_{k=1}^m \frac{1}{k!} \partial^k T(F; \mathbb{F}_n - F)$$

The *remainder* is expressible either as  $R_{n,m} = \{T(\mathbb{F}_n) - T(F)\} - V_{n,m}$ , or as:

$$R_{n,m} = \frac{1}{(m+1)!} \left[ \frac{\partial^{m+1}}{\partial \epsilon^{m+1}} T\{F + \epsilon(\mathbb{F}_n - F)\} \right]_{\epsilon=\epsilon^*}$$

for  $\epsilon^* \in [0, 1]$ . To validate the von Mises expansion (1.3.7), it is necessary to show that the scaled remainder is asymptotically negligible:

$$n^{m/2} R_{n,m} \xrightarrow{p} 0.$$

■

### 3.4 Asymptotic Normality

**Proposition 1.3.2.** Suppose  $(X_i) \stackrel{\text{IID}}{\sim} F$  and  $T$  is a statistical functional that admits an *influence function expansion* of the form:

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \varphi_F(X_i) + \sqrt{n}R_n,$$

where  $E\{\varphi_F(x)\} = 0$  and  $\sqrt{n}R_n \xrightarrow{p} 0$ . Then:

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} \xrightarrow{\mathcal{L}} N(0, \gamma_F^2), \quad (1.3.8)$$

where  $\gamma_F^2 = E\{\varphi_F^2(X)\}$ .

◆

**Proof.** Since  $T$  admits an influence function:

$$\begin{aligned} T(\mathbb{F}_n) - T(F) &= \int \varphi_F(x) d\mathbb{F}_n(x) + R_n \\ &= \int \varphi_F(x) d\left\{ \frac{1}{n} \sum_{i=1}^n H_{X_i}(x) \right\} + R_n = \frac{1}{n} \sum_{i=1}^n \varphi_F(X_i) + R_n. \end{aligned}$$

Rescaling by  $\sqrt{n}$  gives:

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} = \frac{1}{\sqrt{n}} \sum_{i=1}^n \varphi_F(X_i) + \sqrt{n}R_n.$$

Since  $E\{\varphi_F(X_i)\} = 0$ , by the ordinary CLT:

$$\frac{1}{\sqrt{n}} \sum_{i=1}^n \varphi_F(X_i) \xrightarrow{\mathcal{L}} N(0, \gamma_F^2).$$

By hypothesis, the scaled remainder is asymptotically negligible  $\sqrt{n}R_n \xrightarrow{p} 0$ . The conclusion follows from Slutsky's theorem. ■

**Remark 1.3.1** (Lehmann 1999, section 6.3). Consistency and asymptotic normality of  $T(\mathbb{F})$  as an estimator of  $T(F)$  may be established via the following steps:

- i. Derive the influence function for  $T$ :

$$\varphi_F(x) = \lim_{\epsilon \downarrow 0} \left[ \frac{\partial}{\partial \epsilon} T\{F + \epsilon(H_x - F)\} \right].$$

- ii. Verify that the influence function is unbiased:

$$\int \varphi_F(x) dF(x) = 0.$$

- iii. Verify that the remainder is asymptotically negligible:

$$\sqrt{n}R_n = \sqrt{n} \left\{ T(\mathbb{F}_n) - T(F) - \frac{1}{n} \sum_{i=1}^n \varphi_F(X_i) \right\} \xrightarrow{p} 0.$$

- iv. Determine the asymptotic variance:

$$\gamma_F^2 = E\{\varphi_F^2(X)\} = \int \varphi_F^2(x) dF(x).$$

◆



### 3.5 Examples

**Example 1.3.5** (Cramer von Mises Distance). Recall from a previous example that the Gateaux derivative of the Cramer von Mises functional is:

$$\partial T(F; G - F) = 2 \int (F - F_0)(G - F) dF_0.$$

Therefore, the candidate influence function is:

$$\varphi_F(x) = 2 \int (F - F_0)(H_x - F) dF_0.$$

The influence function is unbiased since:

$$E\{\varphi_F(X)\} = 2 \int (F - F_0)\{E(H_X) - F\} dF_0 = 2 \int (F - F_0)(F - F) dF_0 = 0.$$

The remainder takes the form:

$$\begin{aligned} R_n &= T(\mathbb{F}_n) - T(F) - \frac{2}{n} \sum_{i=1}^n \int (F - F_0)(H_{x_i} - F) dF_0 \\ &= \int (\mathbb{F}_n - F_0)^2 dF_0 - \int (F - F_0)^2 dF_0 - 2 \int (F - F_0)(\mathbb{F}_n - F) dF_0 \\ &= \int \{(\mathbb{F}_n - F_0)^2 - (F - F_0)^2 - 2(F - F_0)(\mathbb{F}_n - F)\} dF_0 \\ &= \int \{\mathbb{F}_n - 2\mathbb{F}_n F + F^2\} dF_0 = \int (\mathbb{F}_n - F)^2 dF_0. \end{aligned}$$

The remainder is bounded above by:

$$|R_n| \leq \sup_{x \in \mathbb{R}} \{\mathbb{F}_n(x) - F(x)\}^2.$$

By the Dvoretzky, Kiefer, Wolfowitz inequality:

$$\sqrt{n} \left\{ \sup_{x \in \mathbb{R}} |\mathbb{F}_n(x) - F(x)| \right\} = \mathcal{O}_p(1),$$

therefore:

$$\sqrt{n} |R_n| \leq \frac{1}{\sqrt{n}} \cdot n \cdot \sup_{x \in \mathbb{R}} \{\mathbb{F}_n(x) - F(x)\}^2 = \mathcal{O}(n^{-1/2}) \xrightarrow{p} 0.$$

This establishes the influence function expansion for the Cramer von Mises functional:

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} = \frac{2}{\sqrt{n}} \sum_{i=1}^n \int (F - F_0)(H_{x_i} - F) dF_0 + \mathcal{O}_p(n^{-1/2}).$$

Now,

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} \xrightarrow{\mathcal{L}} N(0, \gamma_F^2),$$

with asymptotic variance:

$$\gamma_F^2 = E\{\varphi_F^2(X)\} = 4E_F \left\{ \int (F - F_0)(H_X - F) dF_0 \right\}^2.$$



**Example 1.3.6** (Sample Quantile). Consider the  $p$ th sample quantile:

$$t_p = T(F) = F^{-1}(p).$$

Towards obtaining the influence function, let  $t_{p,\epsilon} = T(F_{x,\epsilon}) = F_{x,\epsilon}^{-1}(p)$ , then:

$$p = F_{x,\epsilon}(t_{p,\epsilon}) = (1 - \epsilon)F(t_{p,\epsilon}) + \epsilon H_x(t_{p,\epsilon}).$$

Taking the implicit derivative with respect to  $\epsilon$ :

$$0 = -F(t_{p,\epsilon}) + (1 - \epsilon)f(t_{p,\epsilon})\frac{\partial t_{p,\epsilon}}{\partial \epsilon} + H_x(t_{p,\epsilon}) + \epsilon \delta_x(t_{p,\epsilon})\frac{\partial t_{p,\epsilon}}{\partial \epsilon}$$

In the limit as  $\epsilon \downarrow 0$ :

$$0 = -F(t_p) + f(t_p) \left\{ \frac{\partial t_{p,\epsilon}}{\partial \epsilon} \right\}_{\epsilon=0^+} + H_x(t_p).$$

Identify  $\{\partial_\epsilon t_{p,\epsilon}\}_{\epsilon=0^+}$  as the influence function, and rearrange to obtain:

$$\varphi_F(x) = \frac{F(t_p) - H_x(t_p)}{f(t_p)} = \frac{p - I(x \leq t_p)}{f(t_p)}.$$

The influence function is unbiased:

$$E\{\varphi_F(X)\} = \frac{p - F(t_p)}{f(t_p)} = \frac{p - p}{f(t_p)} = 0.$$

From Serfling (1980), theorem 2.5.1:

$$\sqrt{n} \left( T(\mathbb{F}_n) - T(F) - \frac{1}{n} \sum_{i=1}^n \frac{p - I(x \leq t_p)}{f(t_p)} \right) \xrightarrow{p} 0.$$

Therefore:

$$\sqrt{n}\{T(\mathbb{F}_n) - T(F)\} \xrightarrow{\mathcal{L}} N(0, \gamma_F^2),$$

where the asymptotic variance is:

$$\gamma_F^2 = \text{Var}\{\varphi_F(X)\} = \frac{F(t_p)\{1 - F(t_p)\}}{f^2(t_p)} = \frac{p(1 - p)}{f^2(t_p)}.$$



**Example 1.3.7** (M-Estimation). Suppose  $(X_i) \stackrel{\text{iid}}{\sim} F$ , and consider an  $M$ -estimator  $\hat{\theta}_n = T(\mathbb{F}_n)$ , defined implicitly by the relation:

$$0 = \frac{1}{n} \sum_{i=1}^n \psi(X_i; \hat{\theta}_n) = \int \psi\{u; T(\mathbb{F}_n)\} d\mathbb{F}_n(u),$$

where  $\psi$  is the *estimating equation*. Towards finding the influence function, consider evaluation of the estimating relation at  $F_{x,\epsilon}$ :

$$\begin{aligned} 0 &= \int \psi\{u; T(F_{x,\epsilon})\} dF_{x,\epsilon}(u) = \int \psi\{u; T(F_{x,\epsilon})\} d\{(1-\epsilon)F(u) + \epsilon H_x(u)\} \\ &= (1-\epsilon) \int \psi\{u; T(F_{x,\epsilon})\} dF(u) + \epsilon \psi\{x; T(F_{x,\epsilon})\} \end{aligned}$$

Taking the implicit derivative with respect to  $\epsilon$ :

$$\begin{aligned} 0 &= - \int \dot{\psi}\{u; T(F_{x,\epsilon})\} dF(u) + (1-\epsilon) \int \dot{\psi}\{u; T(F_{x,\epsilon})\} \frac{\partial T(F_{x,\epsilon})}{\partial \epsilon} dF(u) \\ &\quad + \psi\{x; T(F_{x,\epsilon})\} + \epsilon \dot{\psi}\{x; T(F_{x,\epsilon})\} \frac{\partial T(F_{x,\epsilon})}{\partial \epsilon}. \end{aligned}$$

In the limit as  $\epsilon \downarrow 0$ :

$$\begin{aligned} 0 &= - \int \dot{\psi}\{u; T(F)\} dF(u) + \int \dot{\psi}\{u; T(F_{x,\epsilon})\} dF(u) \cdot \left\{ \frac{\partial T(F_{x,\epsilon})}{\partial \epsilon} \right\}_{\epsilon=0^+} + \psi\{x; T(F)\} \\ &= -E_F\{\dot{\psi}(X; \theta)\} + E_F\{\dot{\psi}(X; \theta)\} \cdot \varphi_F(x) + \psi(x; \theta) \end{aligned}$$

Upon rearranging:

$$\varphi_F(x) = - \frac{\psi(x; \theta) - E_F\{\psi(X; \theta)\}}{E_F\{\dot{\psi}(X; \theta)\}}.$$

Under the regularity conditions for  $M$ -estimation the remainder is asymptotically negligible, and:

$$\sqrt{n}\{\hat{\theta}_n - \theta\} \xrightarrow{\mathcal{L}} N(0, \gamma_F^2),$$

with asymptotic variance:

$$\text{Var}\{\varphi_F(X)\} = \frac{\text{Var}\{\psi(X; \theta)\}}{E_F^2\{\dot{\psi}(X; \theta)\}}.$$

In the case of maximum likelihood estimation,  $\psi(x; \theta) = \dot{\ell}(x; \theta)$ ,  $\ell(x; \theta) = \ln f(x; \theta)$ , is the *score equation*, which is unbiased  $E\{\psi(X; \theta)\} = E\{\dot{\ell}(X; \theta)\} = 0$ .

The negative expectation of  $\dot{\psi}(X; \theta)$  is the Fisher information:

$$-E_F\{\dot{\psi}(X; \theta)\} = -E_F\{\ddot{\ell}(X; \theta)\} = \mathcal{I}(\theta).$$

The influence function takes the form:

$$\varphi_F(x) = -\mathcal{I}^{-1}(\theta)\dot{\ell}(x; \theta),$$

and the asymptotic variance is:

$$\gamma_F^2 = \frac{\text{Var}\{\dot{\ell}(X; \theta)\}}{\mathcal{I}^2(\theta)} = \frac{\mathcal{I}(\theta)}{\mathcal{I}^2(\theta)} = \mathcal{I}^{-1}(\theta).$$



**Example 1.3.8** (V-Estimation). Consider a  $V$ -estimator of order  $m = 2$  with symmetric kernel function  $h(X_1, X_2)$ :

$$T(F) = \int h(x_1, x_2) dF(x_1) dF(x_2).$$

Towards finding the influence function, consider the evaluation at  $F_{x,\epsilon}$ :

$$\begin{aligned} T(F_{x,\epsilon}) &= \int h(x_1, x_2) d\{(1-\epsilon)F(x_1) + \epsilon H_x(x_1)\} d\{(1-\epsilon)F(x_2) + \epsilon H_x(x_2)\} \\ &= (1-\epsilon)^2 \int h(x_1, x_2) dF(x_1) dF(x_2) + (1-\epsilon)\epsilon \int h(x_1, x) dF(x_1) \\ &\quad + \epsilon(1-\epsilon) \int h(x, x_2) dF(x_2) + \epsilon^2 h(x, x). \end{aligned}$$

Recall that  $\theta = E_F\{h(X_1, X_2)\}$ , and that  $h_1(x) = E\{h(X_1, X_2)|X_1 = x\}$  denotes the first projection. The functional at  $F_{x,\epsilon}$  is expressible as:

$$T(F_{x,\epsilon}) = (1-\epsilon)^2\theta + 2\epsilon(1-\epsilon)h_1(x) + \epsilon^2 h(x, x).$$

Taking the derivative with respect to  $\epsilon$ :

$$\frac{\partial T(F_{x,\epsilon})}{\partial \epsilon} = -2(1-\epsilon)\theta + 2(1-\epsilon)h_1(x) - 2\epsilon h_1(x) + 2\epsilon h(x, x).$$

In the limit as  $\epsilon \downarrow 0$ :

$$\varphi_F(x) = 2\{h_1(x) - \theta\}$$

The remainder takes the form:

$$R_n = \frac{1}{n^2} \sum_{j=1}^n \sum_{i=1}^n \{h(X_i, X_j) - \theta\} - \frac{2}{n} \sum_{i=1}^n \{h_1(X_i) - \theta\}$$

Supposing  $\text{Var}\{h(X, X)\} < \infty$ , it can be shown that  $n\text{Var}(R_n) \rightarrow 0$  (see Serfling 1980, 6.3.2), which implies  $\sqrt{n}R_n = o_p(1)$ . Therefore:

$$\sqrt{n}\{\hat{\theta}_n - \theta\} \xrightarrow{\mathcal{L}} N(0, \gamma_F^2),$$

where the asymptotic variance is:

$$\text{Var}\{\varphi_F(X)\} = 4\text{Var}\{h_1(X)\} = 4\zeta_1^2.$$



# Jackknife

## 4.1 Definition

**Definition 1.4.1.** Suppose  $(X_i) \stackrel{\text{IID}}{\sim} F$ , and let  $\hat{\theta}_n = t(x_1, \dots, x_n)$  denote an estimator. Denote by  $\hat{\theta}_{(-i)} = t(x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n)$  the estimate obtained by omitting the  $i$ th observation. Define the  $i$ th **pseudo-value** as:

$$\tilde{\theta}_i = n\hat{\theta}_n - (n-1)\hat{\theta}_{(-i)}.$$

The jackknife estimator of  $\theta$  is:

$$\hat{\theta}_J = \frac{1}{n} \sum_{i=1}^n \tilde{\theta}_i.$$

■

## 4.2 Empirical Influence Function

**Proposition 1.4.1.** Define  $\mathbb{F}_{(-i)}$  as the empirical distribution function obtained by omitting the  $i$ th observation.  $\mathbb{F}_{(-i)}$  is related to the overall distribution function  $\mathbb{F}_n$  via:

$$\mathbb{F}_{(-i)} = \mathbb{F}_n + \epsilon_n(H_{X_i} - \mathbb{F}_n).$$

Thus,  $\mathbb{F}_{(-i)}$  may be regarded as an  $\epsilon$ -contaminated distribution (1.2.4). ◆

**Proof.** Expressing  $\mathbb{F}_n$  in terms of  $\mathbb{F}_{(-i)}$ :

$$\mathbb{F}_n = \frac{1}{n}X_i + \frac{1}{n} \sum_{j \neq i}^n H_{X_j} = \frac{1}{n}H_{X_i} + \frac{n-1}{n} \frac{1}{n-1} \sum_{j \neq i} \delta_{X_j} = \frac{1}{n}H_{X_i} + \frac{n-1}{n} \mathbb{F}_{(-i)}.$$

Solving for  $\mathbb{F}_{(-i)}$ :

$$\mathbb{F}_{(-i)} = \frac{n}{n-1} \mathbb{F}_n - \frac{1}{n-1} H_{X_i} = \left(1 + \frac{1}{n-1}\right) \mathbb{F}_n - \frac{1}{n-1} H_{X_i}.$$

Let  $\epsilon_n = -(n-1)^{-1}$ , then:

$$\mathbb{F}_{(-i)} = \mathbb{F}_n - \epsilon_n \mathbb{F}_n + \epsilon_n H_{X_i} = \mathbb{F}_n + \epsilon_n (H_{X_i} - \mathbb{F}_n).$$

■

**Proposition 1.4.2.** The difference between the  $i$ th *pseudo-value*  $\tilde{\theta}_i$  and the overall sample estimator  $\hat{\theta}_n$  is an empirical approximation to the influence function at  $X_i$ :

$$\tilde{\theta}_i - \hat{\theta}_n = \hat{\varphi}_F(X_i).$$

◆

**Proof.** Consider the  $i$ th pseudo-value:

$$\begin{aligned}\tilde{\theta}_i &= n\hat{\theta}_n - (n-1)\hat{\theta}_{(-i)} = \hat{\theta}_n - (n-1)(\hat{\theta}_{(-i)} - \hat{\theta}_n), \\ \tilde{\theta}_i - \hat{\theta}_n &= \frac{\hat{\theta}_{(-i)} - \hat{\theta}_n}{-(n-1)^{-1}} = \frac{\hat{\theta}_{(-i)} - \hat{\theta}_n}{\epsilon_n}.\end{aligned}$$

Writing  $\theta = T(F)$  as a statistical functional:

$$\tilde{\theta}_i - \hat{\theta}_n = \epsilon_n^{-1} \{T(\mathbb{F}_{(-i)}) - T(\mathbb{F}_n)\} = \epsilon_n^{-1} \left[ T\{\mathbb{F}_n + \epsilon_n(H_{X_i} - \mathbb{F}_n)\} - T(\mathbb{F}_n) \right].$$

Comparison to the Gateaux derivative (1.2.5) suggests that for  $n \rightarrow \infty$ :

$$\tilde{\theta}_i - \hat{\theta}_n \approx \varphi_F(X_i).$$

■

**Example 1.4.1** (Jackknife Variance Estimator). Suppose  $\hat{\theta}_n = T(\mathbb{F}_n)$  admits an influence function expansion:

$$\sqrt{n}(\hat{\theta}_n - \theta) = \frac{1}{\sqrt{n}} \sum_{i=1}^n \varphi_F(X_i) + o_p(1).$$

The asymptotic variance of  $\sqrt{n}(\hat{\theta}_n - \theta)$  is  $\text{Var}\{\varphi_F(X)\}$ , which is estimated by:

$$\hat{V}\{\varphi_F(X)\} = \frac{1}{n} \sum_{i=1}^n \varphi_F^2(X_i).$$

Approximating the true influence function  $\varphi_F$  by the empirical influence of  $X_i$ :

$$\frac{1}{n} \sum_{i=1}^n \varphi_F^2(X_i) \approx \frac{1}{n} \sum_{i=1}^n \hat{\varphi}_F^2(X_i) = \frac{1}{n} \sum_{i=1}^n (\tilde{\theta}_i - \hat{\theta}_n)^2.$$

This approximation motivates the jackknife variance estimator:

$$\hat{V}_J\{\sqrt{n}(\hat{\theta}_n - \theta)\} = \frac{1}{n-1} \sum_{i=1}^n (\tilde{\theta}_i - \hat{\theta}_n)^2.$$

Note that this is an estimate of  $\text{Var}\{\sqrt{n}(\hat{\theta}_n - \theta)\}$ . The jackknife estimate of  $\text{Var}(\hat{\theta}_n)$  is:

$$\hat{V}_J(\hat{\theta}_n) = \frac{1}{n} \cdot \frac{1}{n-1} \sum_{i=1}^n (\tilde{\theta}_i - \hat{\theta}_n)^2.$$

Expressed in terms of the leave-1-out estimates:

$$\hat{V}_J(\hat{\theta}_n) = \frac{n-1}{n} \sum_{i=1}^n (\hat{\theta}_{(-i)} - \hat{\theta}_n)^2.$$

♠

## References

References for influence functions:

- Serfling. *Approximation Theorems of Mathematical Statistics* (1980); Chapter 6.
- Lehmann. *Elements of Large Sample Theory* (1999); Chapter 6.
- Tsiatis. *Semiparametric Theory and Missing Data* (2006); Chapter 3.
- Huber & Ronchetti. *Robust Statistics* (2009); Chapters 1 & 2.