

Exponential Dispersion Family

Definition 1.1. An **exponential dispersion density** takes the form:

$$f(y_i|\theta_i, \phi) = \exp \left\{ \frac{y_i\theta_i - b(\theta_i)}{w_i\phi} + c(y_i, \phi) \right\}.$$

Here θ_i is the *canonical parameter*, w_i is an subject-specific weight, ϕ is the *dispersion parameter*, $b(\cdot)$ is the *cumulant function*, and $c(y_i, \phi)$ is the log partition function. ■

Result 1.1 (Exponential Dispersion Properties).

- The log likelihood contribution of y_i is:

$$\ell(\theta_i, \phi) = \frac{y_i\theta_i - b(\theta_i)}{w_i\phi} + c(y_i, \phi).$$

- The score contribution of y_i :

$$s_i(\theta_i, \phi) = \frac{\partial \ell_i}{\partial \theta_i} = \frac{y_i - \dot{b}(\theta_i)}{w_i\phi}.$$

- The information contribution of y_i :

$$\mathcal{I}_{\theta_i\theta_i} = -E \left(\frac{\partial^2 \ell_i}{\partial \theta_i^2} \right) = \frac{\ddot{b}(\theta_i)}{w_i\phi}.$$

- The mean $E[y_i]$ of an exponential dispersion model is the first derivative of the cumulant function:

$$\mu_i = \dot{b}(\theta_i).$$

- The variance of an exponential dispersion model is a function of the mean:

$$\text{Var}(y_i) = w_i\phi\ddot{b}(\theta_i) = w_i\phi\ddot{b} \circ \dot{b}^{-1}(\mu_i) \equiv w_i\phi\nu(\mu_i).$$

Here $\nu(\mu_i) = \ddot{b} \circ \dot{b}^{-1}(\mu_i)$ is the *variance function*.



Generalized Linear Models

Definition 2.1. In a **generalized linear model** (GLM), a regression function is specified for the conditional mean:

$$E(y_i | \mathbf{x}_i) \equiv \mu_i = h(\eta_i).$$

Here $\eta_i = \mathbf{x}_i' \boldsymbol{\beta}$ is the *linear predictor* and h is the *activation function*. The inverse g of h is the *link function*:

$$g(\mu_i) = \eta_i = \mathbf{x}_i' \boldsymbol{\beta}.$$

The activation function h and linear predictor η_i imply a model for the canonical parameter θ_i via:

$$\dot{b}(\theta_i) = \mu_i = h(\eta_i) \implies \theta_i = \dot{b}^{-1} \circ h(\eta_i).$$

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2.1 Miscellaneous Relations

Proposition 2.1.

$$\dot{h}(\eta_i) = \frac{1}{\dot{g}(\mu_i)}.$$

◆

Proof.

$$1 = \frac{\partial}{\partial \eta_i} \eta_i = \frac{\partial}{\partial \eta_i} g \circ h(\eta_i) = \dot{g}\{h(\eta_i)\} \dot{h}(\eta_i) \implies \dot{h}(\eta_i) = \frac{1}{\dot{g}\{h(\eta_i)\}}.$$

■

Definition 2.2. The canonical parameter is related to the linear predictor via:

$$\theta_i = \dot{b}^{-1} \circ h(\eta_i).$$

If $g = \dot{b}^{-1}$ st $h = \dot{b}$, then:

$$\theta_i = \dot{b}^{-1} \circ \dot{b}(\eta_i) = \eta_i.$$

This choice of g is referred to as the **canonical link**. Under the canonical link, the canonical parameter is exactly the linear predictor. ■

Proposition 2.2. Under the canonical link $h(\cdot) = \dot{b}(\cdot)$:

$$\nu(\mu_i)\dot{g}(\mu_i) = 1.$$

◆

Proof. Recall $\dot{b}(\theta_i) = \mu_i$ and $\ddot{b}(\theta_i) = \nu(\mu_i)$. Under the canonical link $h = \dot{b}$ and $\theta_i = \eta_i$, thus:

$$\nu(\mu_i) = \ddot{b}(\theta_i) = \dot{h}(\eta_i) = \frac{1}{\dot{g}(\mu_i)}.$$

Conclude $\nu(\mu_i)\dot{g}(\mu_i) = 1$. ■

Proposition 2.3.

$$\frac{\partial \theta_i}{\partial \mu_i} = \frac{1}{\ddot{b}(\theta_i)} = \frac{1}{\nu(\mu_i)}.$$

◆

Proof. Since $\dot{b}(\theta_i) = \mu_i$:

$$\ddot{b}(\theta_i) \frac{\partial \theta_i}{\partial \mu_i} = \frac{\partial \mu_i}{\partial \mu_i} = 1.$$

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2.2 Properties of GLMs

Result 2.1 (GLM Properties).

- The score for β is:

$$\mathbf{S}_\beta = \sum_{i=1}^n \frac{y_i - \dot{b}(\theta_i)}{w_i \phi \nu(\mu_i)} \frac{\mathbf{x}_i}{\dot{g}(\mu_i)}.$$

- The score for ϕ is:

$$S_\phi = \sum_{i=1}^n (-) \frac{y_i \theta_i - b(\theta_i)}{w_i \phi^2} + \dot{c}(y_i, \phi).$$

- The information for β is:

$$\mathcal{I}_{\beta\beta'} = \sum_{i=1}^n \frac{\mathbf{x}_i \mathbf{x}_i'}{w_i \phi \nu(\mu_i) \dot{g}^2(\mu_i)}.$$

- The information for ϕ is:

$$\mathcal{I}_{\phi\phi} = -2 \sum_{i=1}^n \frac{y_i \theta_i - b(\theta_i)}{w_i \phi^3} + \frac{1}{2} \ddot{c}(y_i, \phi).$$

- The cross information between β and ϕ is:

$$\mathcal{I}_{\beta\phi} = \mathbf{0}.$$



Proof. The model log likelihood is:

$$\ell(\beta, \phi) = \sum_{i=1}^n \ell_i(\beta, \phi) = \sum_{i=1}^n \frac{y_i \theta_i - b(\theta_i)}{w_i \phi} + c(y_i, \phi).$$

The score for β is:

$$\mathbf{S}_\beta = \frac{\partial \ell}{\partial \beta} = \sum_{i=1}^n \frac{\partial \ell_i}{\partial \theta_i} \frac{\partial \theta_i}{\partial \mu_i} \frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta} = \sum_{i=1}^n \frac{y_i - \dot{b}(\theta_i)}{w_i \phi} \cdot \frac{1}{\ddot{b}(\theta_i)} \cdot \dot{h}(\eta_i) \cdot \mathbf{x}_i.$$

Since $\ddot{b}(\theta_i) = \nu(\mu_i)$:

$$\mathbf{S}_\beta = \sum_{i=1}^n \mathbf{s}_i(\beta, \phi) = \sum_{i=1}^n \frac{y_i - \dot{b}(\theta_i)}{w_i \phi \nu(\mu_i)} \frac{\mathbf{x}_i}{\dot{g}(\mu_i)}.$$

The score for ϕ is:

$$S_\phi = \frac{\partial \ell}{\partial \phi} = \sum_{i=1}^n \frac{\partial \ell_i}{\partial \phi} = \sum_{i=1}^n (-) \frac{y_i \theta_i - b(\theta_i)}{w_i \phi^2} + \dot{c}(y_i, \phi).$$

The observed information for β is:

$$-\mathcal{J}_{\beta\beta'} = \frac{\partial^2 \ell}{\partial \beta \partial \beta'} = \sum_{i=1}^n \left(\frac{\partial \mathbf{s}_i}{\partial \theta_i} \frac{\partial \theta_i}{\partial \mu_i} \frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta'} + \frac{\partial \mathbf{s}_i}{\partial \mu_i} \frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta'} \right).$$

Evaluating the first derivative within the sum:

$$\frac{\partial \mathbf{s}_i}{\partial \theta_i} \frac{\partial \theta_i}{\partial \mu_i} \frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta} = - \frac{\ddot{b}(\theta_i)}{w_i \phi \nu(\mu_i)} \frac{\mathbf{x}_i}{\dot{g}(\mu_i)} \cdot \frac{1}{\ddot{b}(\theta_i)} \cdot \frac{1}{\dot{g}(\mu_i)} \mathbf{x}_i' = \frac{-\mathbf{x}_i \mathbf{x}_i'}{w_i \phi \nu(\mu_i) \dot{g}^2(\mu_i)}.$$

Observe that the second derivative within the sum is of the form:

$$(y_i - \dot{b}(\theta_i)) \frac{\mathbf{x}_i}{w \phi} \frac{\partial}{\partial \mu_i} \frac{1}{\nu(\mu_i) \dot{g}(\mu_i)} \cdot \frac{\partial \mu_i}{\partial \eta_i} \frac{\partial \eta_i}{\partial \beta'}$$

Upon taking the expectation, this term vanishes due to the leading factor of $y_i - \dot{b}(\theta_i)$. Therefore, the Fisher information for $\boldsymbol{\beta}$ is:

$$\mathcal{I}_{\boldsymbol{\beta}\boldsymbol{\beta}'} = -E \left(\frac{\partial^2 \ell}{\partial \boldsymbol{\beta} \partial \boldsymbol{\beta}'} \right) = \sum_{i=1}^n \frac{\mathbf{x}_i \mathbf{x}_i'}{w_i \phi \nu(\mu_i) \dot{g}^2(\mu_i)}.$$

The observed information for ϕ is:

$$-\mathcal{J}_{\phi\phi} = \frac{\partial^2 \ell}{\partial \phi^2} = \sum_{i=1}^n 2 \frac{y_i \theta_i - b(\theta_i)}{w_i \phi^3} + \ddot{c}(y_i, \phi).$$

The Fisher information for ϕ is:

$$\mathcal{I}_{\phi\phi} = -E \left(\frac{\partial^2 \ell}{\partial \phi^2} \right) = -2 \sum_{i=1}^n \frac{y_i \theta_i - b(\theta_i)}{w_i \phi^3} + \frac{1}{2} \ddot{c}(y_i, \phi).$$

The observed information between $\boldsymbol{\beta}$ and ϕ is:

$$-\mathcal{J}_{\boldsymbol{\beta}\phi} = \frac{\partial^2 \ell}{\partial \boldsymbol{\beta} \partial \phi} = \sum_{i=1}^n (-) \frac{y_i - \dot{b}(\theta_i)}{w_i \phi^2 \nu(\mu_i)} \frac{\mathbf{x}_i}{\dot{g}(\mu_i)}.$$

The Fisher information between $\boldsymbol{\beta}$ and ϕ is:

$$\mathcal{I}_{\boldsymbol{\beta}\phi} = -E \left(\frac{\partial^2 \ell}{\partial \boldsymbol{\beta} \partial \phi} \right) = \mathbf{0}.$$

■

Remark 2.1. Since $\hat{\boldsymbol{\beta}}$ is asymptotically independent of ϕ , a consistent estimate of $\boldsymbol{\beta}$ is obtained by solving the score equations $\mathbf{S}_{\boldsymbol{\beta}}$ for $\boldsymbol{\beta}$ with any consistent estimator $\hat{\phi}$ substituted for the unknown dispersion parameter ϕ . ♦

Result 2.2. Define the following $n \times n$ matrices:

$$\begin{aligned} \boldsymbol{\Delta} &= \text{diag} \left\{ \dot{g}(\mu_i) \right\} \\ \mathbf{W} &= \text{diag} \left\{ \frac{1}{w_i \phi \nu(\mu_i) \dot{g}^2(\mu_i)} \right\} \\ \boldsymbol{\Sigma} &= \text{diag} \left\{ \text{Var}(y_i) \right\} = \text{diag} \left\{ w_i \phi \nu(\mu_i) \right\} \end{aligned}$$

These matrices are related through:

$$\mathbf{W}^{-1} = \boldsymbol{\Delta} \boldsymbol{\Sigma} \boldsymbol{\Delta}.$$

Using these forms, the score for $\boldsymbol{\beta}$ is expressible as:

$$\mathbf{S}_{\boldsymbol{\beta}} = \mathbf{X}' \mathbf{W} \boldsymbol{\Delta} (\mathbf{y} - \boldsymbol{\mu}).$$

The information for $\boldsymbol{\beta}$ is expressible as:

$$\mathcal{I}_{\boldsymbol{\beta}\boldsymbol{\beta}'} = \mathbf{X}' \mathbf{W} \mathbf{X}.$$

♣

Result 2.3. Suppose $\hat{\boldsymbol{\beta}}^{(r)}$ is the current estimate of $\boldsymbol{\beta}$, and define the *working response vector* as:

$$\mathbf{z}^{(r)} = \mathbf{X}\hat{\boldsymbol{\beta}}^{(r)} + \boldsymbol{\Delta}^{(r)} (\mathbf{y} - \boldsymbol{\mu}^{(r)}).$$

The $(r+1)$ st estimate of $\boldsymbol{\beta}$, as given by the Newton-Raphson iteration, is identically the weighted least squares (WLS) estimator for regression of $\mathbf{z}^{(r)}$ on \mathbf{X} using weights $\mathbf{W}^{(r)}$. That is:

$$\hat{\boldsymbol{\beta}}^{(r+1)} = (\mathbf{X}'\mathbf{W}^{(r)}\mathbf{X})^{-1}\mathbf{X}'\mathbf{W}^{(r)}\mathbf{z}^{(r)}.$$



Proof. The Newton-Raphson iteration for updating $\boldsymbol{\beta}$ is:

$$\hat{\boldsymbol{\beta}}^{(r+1)} = \hat{\boldsymbol{\beta}}^{(r)} + \mathcal{I}_{\boldsymbol{\beta}\boldsymbol{\beta}'}^{-1}(\hat{\boldsymbol{\beta}}^{(r)}) \mathbf{S}_{\boldsymbol{\beta}}(\hat{\boldsymbol{\beta}}^{(r)}).$$

Writing out the score and information:

$$\begin{aligned} \hat{\boldsymbol{\beta}}^{(r+1)} &= \hat{\boldsymbol{\beta}}^{(r)} + (\mathbf{X}'\mathbf{W}^{(r)}\mathbf{X})^{-1}\mathbf{X}'\mathbf{W}^{(r)}\boldsymbol{\Delta}^{(r)} (\mathbf{y} - \boldsymbol{\mu}^{(r)}) \\ &= (\mathbf{X}'\mathbf{W}^{(r)}\mathbf{X})^{-1} \left[(\mathbf{X}'\mathbf{W}^{(r)}\mathbf{X})\hat{\boldsymbol{\beta}}^{(r)} + \mathbf{X}'\mathbf{W}^{(r)}\boldsymbol{\Delta}^{(r)} (\mathbf{y} - \boldsymbol{\mu}^{(r)}) \right] \\ &= (\mathbf{X}'\mathbf{W}^{(r)}\mathbf{X})^{-1}\mathbf{X}'\mathbf{W}^{(r)} \left[\mathbf{X}\hat{\boldsymbol{\beta}}^{(r)} + \boldsymbol{\Delta}^{(r)} (\mathbf{y} - \boldsymbol{\mu}^{(r)}) \right]. \end{aligned}$$



2.3 Deviance

Definition 2.3. Let $\ell(\boldsymbol{\mu}, \phi; \mathbf{y})$ denote the log likelihood as a function of the mean vector $\boldsymbol{\mu} = (\mu_1, \dots, \mu_n)$ and the dispersion parameter ϕ . If $\hat{\boldsymbol{\beta}}$ is the MLE of $\boldsymbol{\beta}$ and $\hat{\boldsymbol{\mu}} = h(\mathbf{X}\hat{\boldsymbol{\beta}})$, then $\ell(\hat{\boldsymbol{\mu}}, \phi; \mathbf{y})$ is the realized log likelihood. The maximum attainable log likelihood is $\ell(\mathbf{y}, \phi; \mathbf{y})$. Let $\hat{\theta}_i$ denote the canonical parameter for the i th observation under the MLE, and let $\tilde{\theta}_i$ denote the canonical parameter for the model that maximizes the log likelihood. The **scaled deviance** is:

$$D = -2\{\ell(\hat{\boldsymbol{\mu}}, \phi; \mathbf{y}) - \ell(\mathbf{y}, \phi; \mathbf{y})\} = \frac{2}{\phi} \sum_{i=1}^n w_i^{-1} \left[y_i(\hat{\theta}_i - \tilde{\theta}_i) - \{b(\hat{\theta}_i) - b(\tilde{\theta}_i)\} \right].$$



Result 2.4. The Pearson χ^2 statistic for GLMs is:

$$T = \sum_{i=1}^n \left\{ \frac{y_i - \mu_i}{\sqrt{\text{Var}(y_i)}} \right\}^2 = \sum_{i=1}^n \frac{(y_i - \mu_i)^2}{w_i \phi \nu(\mu_i)} \xrightarrow{\mathcal{L}} \chi_{n-p}^2,$$

where $p = \dim(\boldsymbol{\beta})$. Setting $T \stackrel{\text{Set}}{=} E\{\chi_{n-p}^2\} = (n-p)$ and solving for ϕ gives a method of moments estimator for ϕ :

$$\hat{\phi} = \frac{1}{n-p} \sum_{i=1}^n \frac{(y_i - \hat{\mu}_i)^2}{w_i \nu(\hat{\mu}_i)}.$$



2.4 Quasi Likelihood

Definition 2.4. The **log quasi likelihood** of an observation y_i with mean μ_i :

$$q_i = q(\mu_i) = \int_{y_i}^{\mu_i} \frac{y_i - u}{\phi \nu(\mu_i)} du.$$



Remark 2.2. The use of quasi likelihood allows for specification of GLMs with non-standard mean-variance relationships.

