

Computer- and robot-assisted Surgery



NATIONALES CENTRUM
FÜR TUMORERKRANKUNGEN
PARTNERSTANDORT DRESDEN
UNIVERSITÄTS KREBSCENTRUM UCC

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Basics of Machine Learning

getragen von:
Deutsches Krebsforschungszentrum
Universitätsklinikum Carl Gustav Carus Dresden
Medizinische Fakultät Carl Gustav Carus, TU Dresden
Helmholtz-Zentrum Dresden-Rossendorf

SHK – Development and maintenance of a surgical robot testbed

- Help developing control software for our robot testbed i.e.:
 - Industrial 7-DOF robot (franka emika - panda / universal robots - ur5e)
 - 3D input device (forcedimension - lambda 7)
 - Custom end effector for controlling laparoscopic instruments
- Goal: system to perform surgical tasks with e.g. for reinforcement / imitation learning applications



Prerequisites

C/C++

(ROS/ROS2)

Send us your application!

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Master/Diploma thesis - Recognition and/or prediction of fine grained surgical actions in a laparoscopic setting using deep neural networks

- Supervised Learning task using deep neural networks
- Usage of temporal video and sensor data

Prerequisite: Python

Useful prior knowledge:

Pytorch | Machine Learning fundamentals



Write me if you're interested:

Martin Lelis
martin.lelis@nct-dresden.de

Content

- Introduction
 - What and why
- Supervised Learning
 - Introduction
 - Linear Methods for Regression and Classification
 - Tree-Based Methods
- Unsupervised Learning
 - Introduction
 - Cluster Analysis
- Model Assessment and Selection

What is machine learning?

The subfield of computer science that “gives computers the ability to learn without being explicitly programmed”.

Arthur Samuel, 1959

A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P if its performance at tasks in T , as measured by P , improves with experience E .

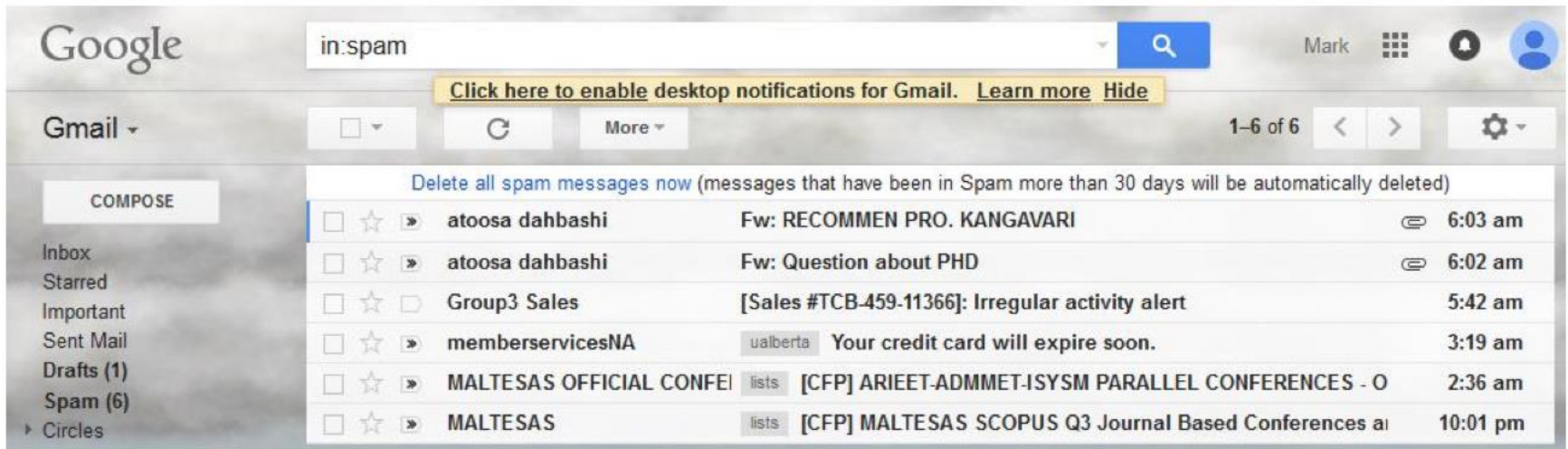
Tom Mitchell 1997

What is machine learning?

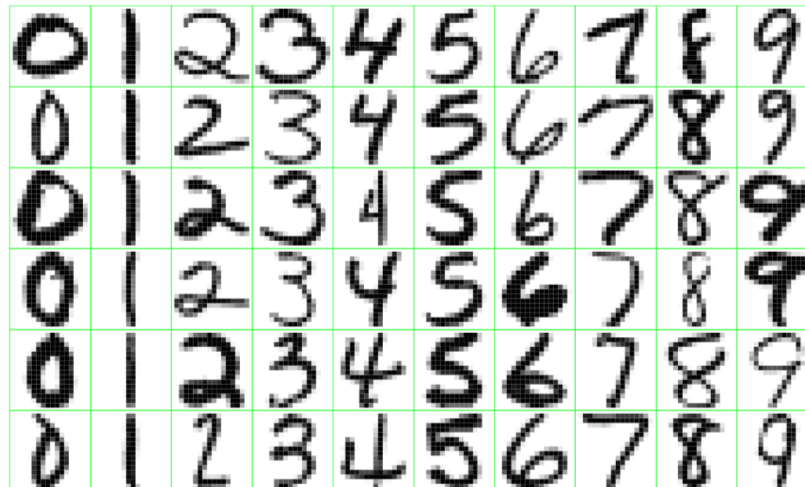
- A subset of artificial intelligence
- Mathematical models build on sample data
- Make predictions or decisions without being programmed to do so
- Locate patterns in data

Introduction – Applications

- *Spam filtering*: Try to predict whether an email is junk email

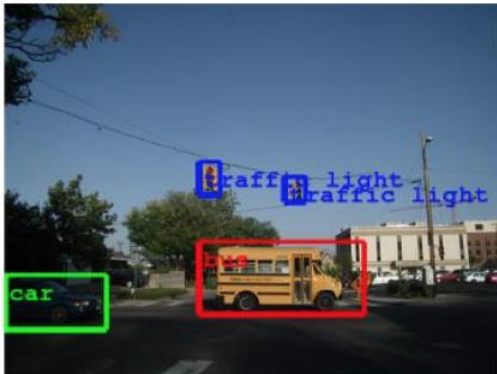
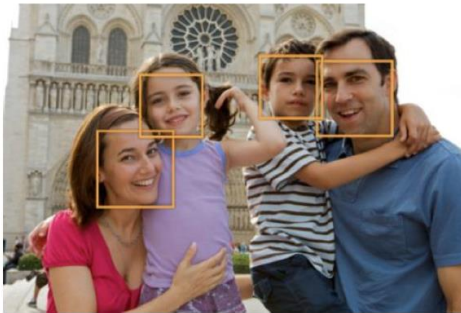


- *Handwritten digits*:
Identify the numbers in a
handwritten ZIP code,
from a digitised image



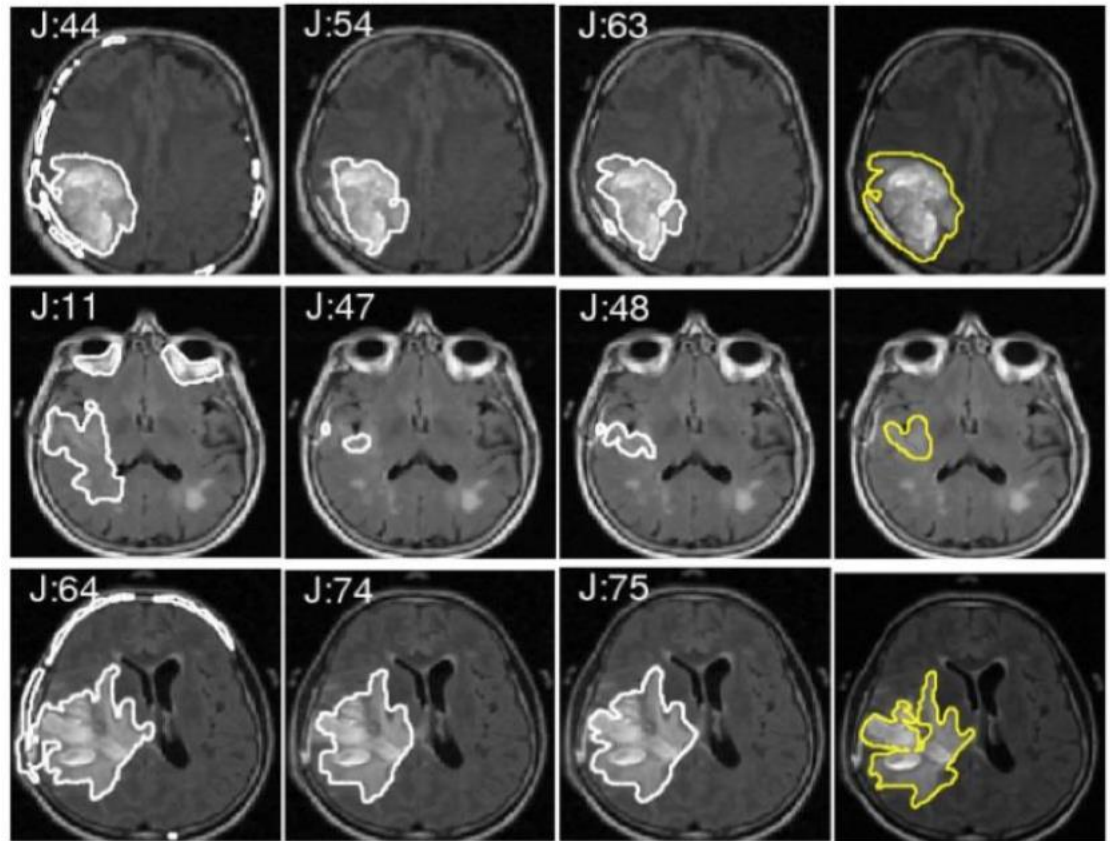
Introduction – Applications

- *Prostate cancer*: Identify the risk factors for prostate cancer, based on clinical and demographic variables
- *Face & Object detection*:



Introduction – Applications

- *Medical Imaging:*
Tumour segmentation



- *Self driving cars:*



Classification Machine Learning

Classification Machine Learning

Mode of inference: Deductive vs inductive

- Deductive reasoning
 - Logical conclusions (Top-down logic), e.g. using Modus ponens:
If P, then Q
P
Therefore Q
 - Example:
If today is Saturday, then it is the weekend
Today is Saturday
Therefore it is the weekend

Classification Machine Learning

Mode of inference: Deductive vs inductive

- Inductive reasoning

- Generalization from given samples (bottom-up logic)

The proportion Q of the sample has attribute A

Therefore, the proportion Q of the population has attribute A

- Example:

A sample of 5 balls from a urn with 20 balls has 4 black balls and 1 white ball

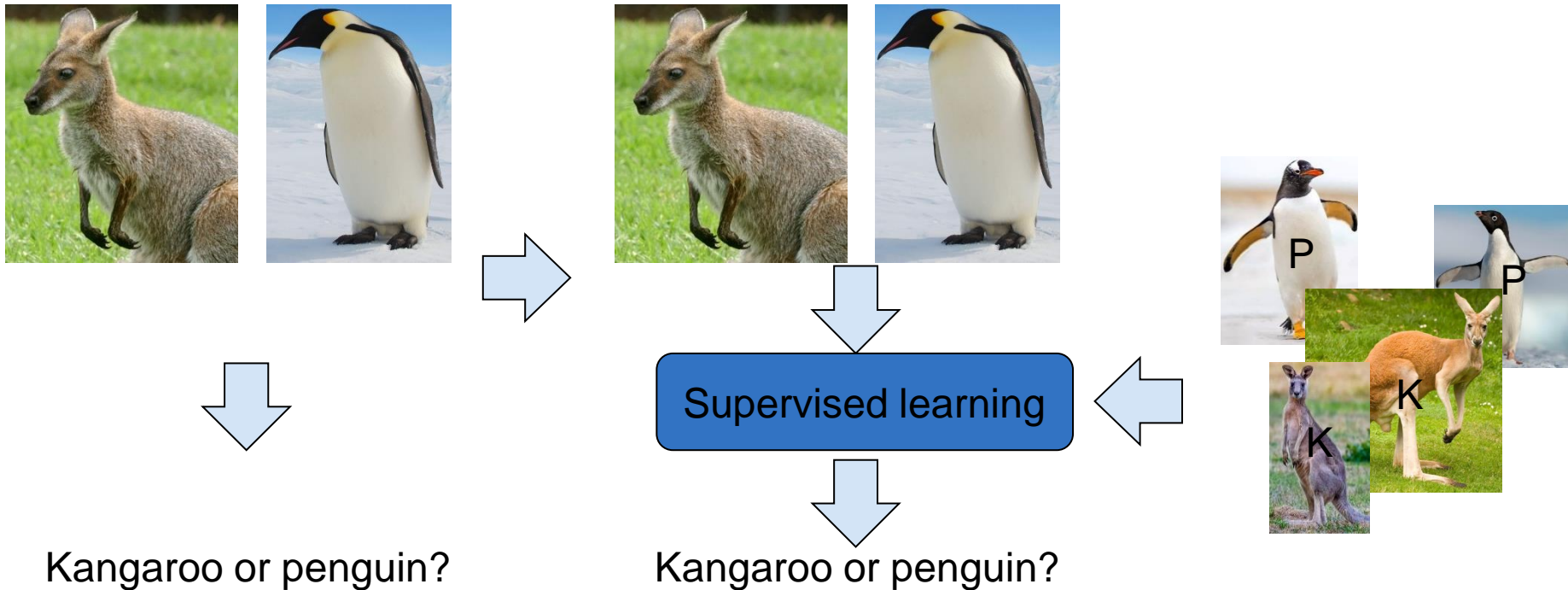
Therefore, the urn contains 16 black balls and 4 white balls

=> Learning through data analysis

Classification Machine Learning

Category: Supervised learning (concept learning)

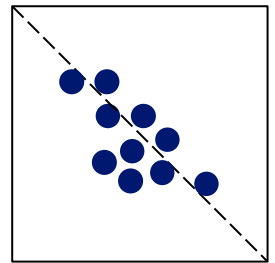
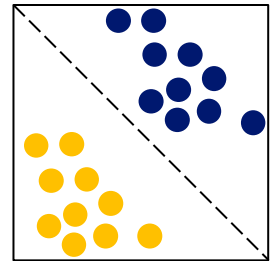
- Learning by labeled example, i.e. we “tell” the algorithm what to learn



Classification Machine Learning

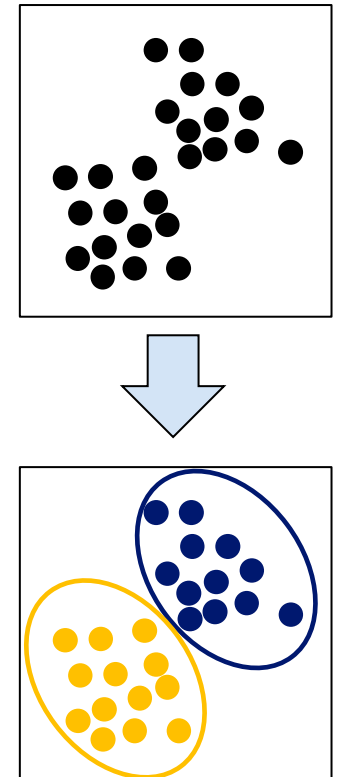
Category: Supervised learning (concept learning)

- Learning by labeled example, i.e. we “tell” the algorithm what to learn
- Two forms of output
 - Symbolic
 - Output is a discrete value/category, e.g. kangaroo or penguin
 - Subsymbolic/regression
 - Output is continuous value, e.g. age or temperature



Classification Machine Learning

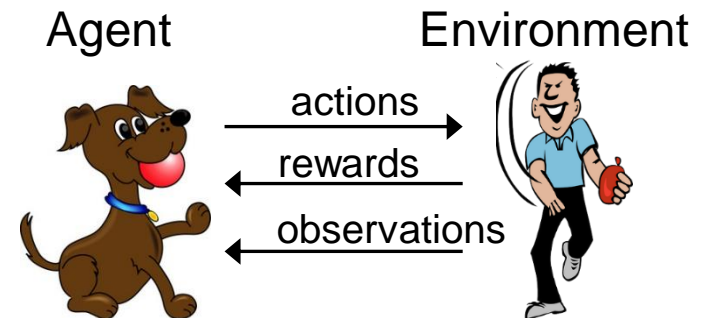
- Category: Unsupervised learning
 - Detect previously unknown patterns in unlabeled data
 - No desired output!
 - Example applications
 - Find anomalies in data, e.g. credit card usage
 - Find clusters, e.g. grouping pictures



Classification Machine Learning

Category: Reinforcement learning

- A software agent learns how to interact (e.g. take actions) in an environment in order to maximize a reward function
 - Environment gives positive or negative rewards based on action(s)
- Examples:
 - Teaching algorithms to play (video) games
 - Robot navigation
 - Modeling dopamine-based learning in the brain



Steps for Machine Learning

- Collect data
 - Most problems require (expert-)labeled data
 - Quantity: Many algorithms require large amounts of data
 - Quality: Is the collected data representative? Are there biases?
- Feature selection
 - Feature: individual measurable property or characteristic of a phenomenon being observed
 - Represents the data
 - Present the data in a more useful manner to help algorithms learn
- Select algorithm
- Train algorithm
- Perform predictions

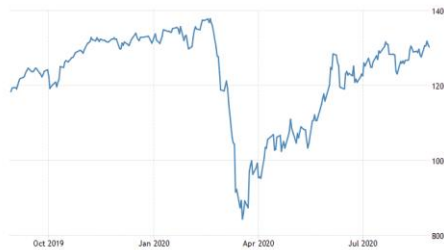
Feature selection

- Examples low level features

- Images

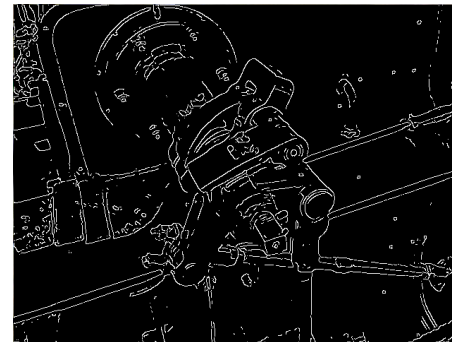
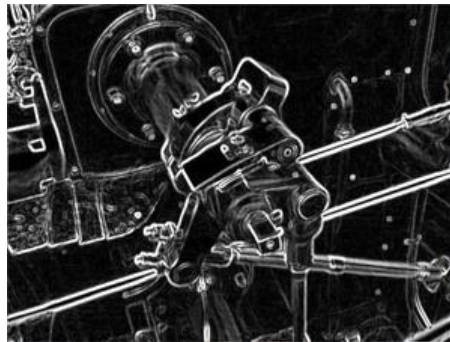
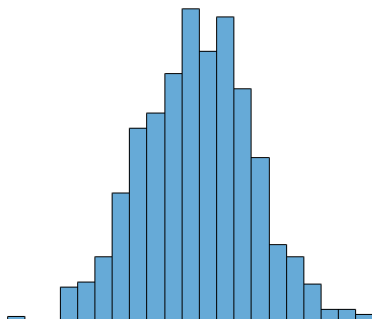


- Time series

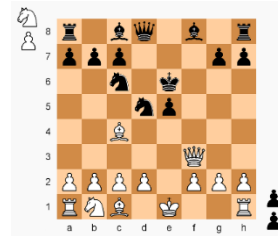


Feature selection

- Examples higher level features
 - Image histogram, gradient, lines, geometric primitives



- Environment states, e.g. state of a game, position of robot on a map, ...



Feature selection

- Examples higher level features
 - Attributes



legs: 5
Avg. height: 1.8m
Political spectrum:
Communist
Fav. Food:
Schnapps
chocolates



legs: 2
Avg. height: 1.1m
Political spectrum:
Capitalist
Fav. Food:
Tea sausage



legs: 4
Avg. height: 0.7m
Political spectrum:
Social democrat
Fav. Food:
Eucalyptus

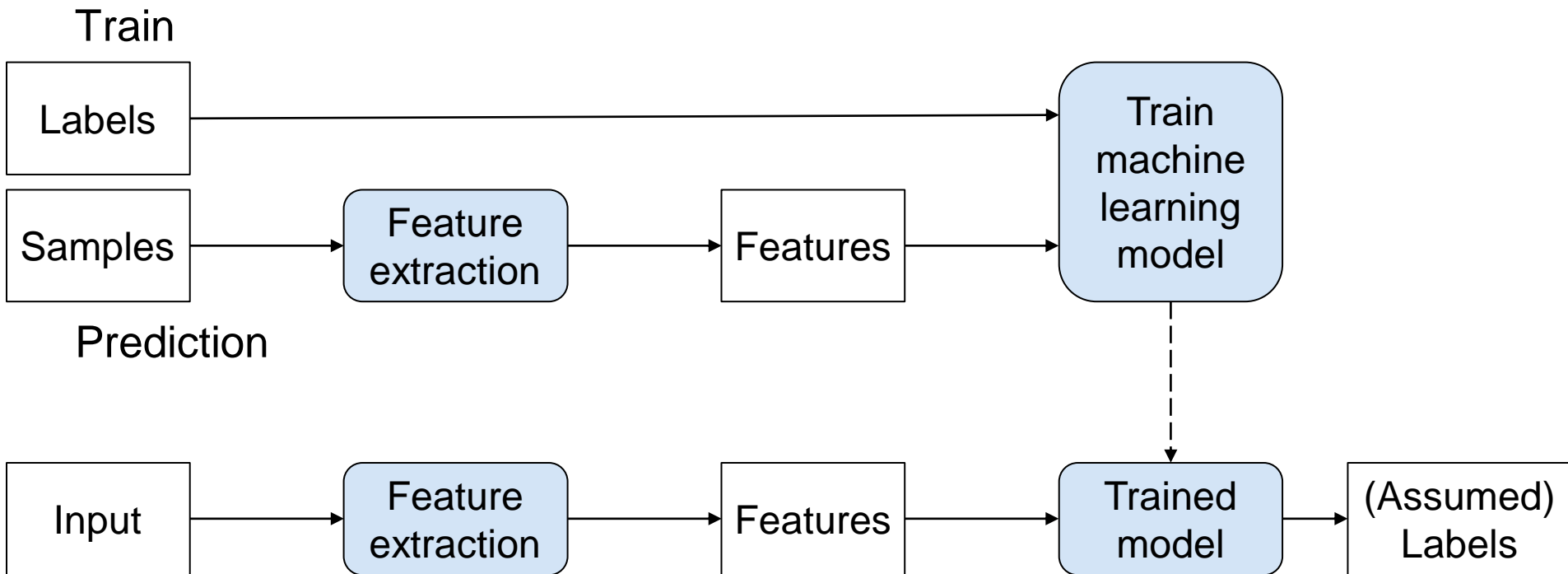


legs: 4
Avg. height: 1m
Political spectrum:
Green
Fav. Food:
Steak



legs: 4
Avg. height: 0.25m
Political spectrum:
Monarchist
Fav. Food:
Fish

Train and predict



Inductive Machine Learning Algorithms

Supervised

- k-Nearest Neighbor
- Linear classifier
- Bayes classifier
- Decision Trees
- Random Forests
- Support Vector Machine
- Neural Networks (Deep Learning)

Unsupervised

- PCA
- Hierarchical clustering
- k-Means
- DBSCAN

Reinforcement Learning

- SARSA- λ
- Q-Learning

Inductive Machine Learning Algorithms

Supervised

- *k-Nearest Neighbor (in tutorial)*
- **Linear classifier**
- Bayes classifier
- **Decision Trees**
- **Random Forests**
- Support Vector Machine
- *Neural Networks (Deep Learning)*

Unsupervised

- *PCA (in tutorial)*
- Hierarchical clustering
- **k-Means**
- DBSCAN

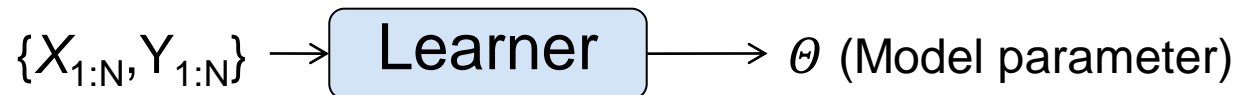
Reinforcement Learning

- SARSA- λ
- Q-Learning

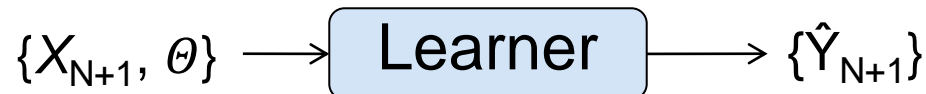
Supervised Learning

Supervised Learning - Introduction

- “... task of learning a function that maps an input X to output Y based on example input-output pairs.”
 - Trainings data set of N instances: $\{X_{1:N}, Y_{1:N}\}$
 - Each input $X_i \in \mathbb{R}^{1 \times p}$ is a vector with p attributes/predictors/features
- (1) Training (learning):

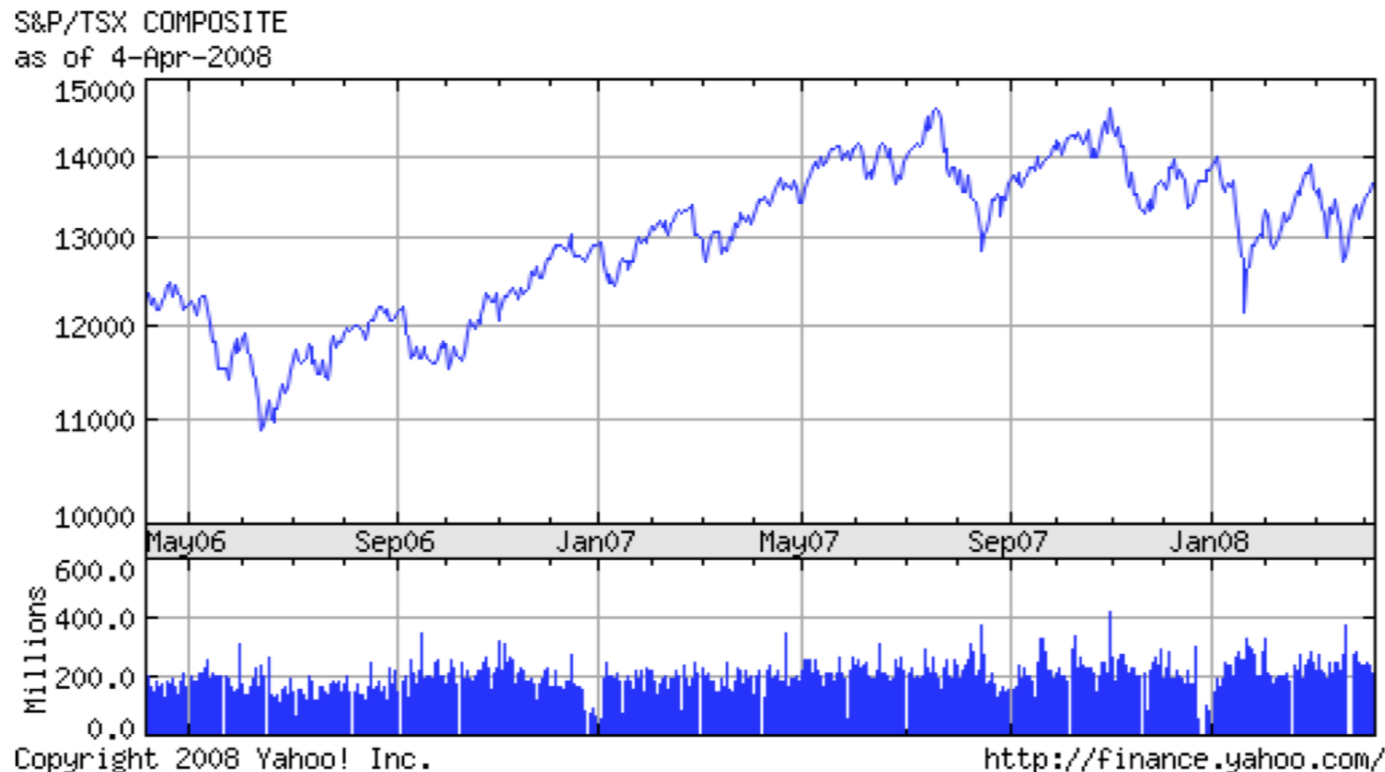


- (2) Testing (prediction):



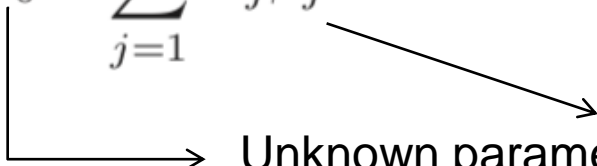
Supervised Learning – Linear Methods for Regression

- Many real processes can be approximated with linear models
- Linear problems can be solved analytically



Supervised Learning – Linear Methods for Regression

- Input vector $X^T = (X_1, X_2, \dots, X_p)$ and we want to predict a real-valued output Y
- Linear regression model has the form:

$$f(X) = \beta_0 + \sum_{j=1}^p X_j \beta_j$$


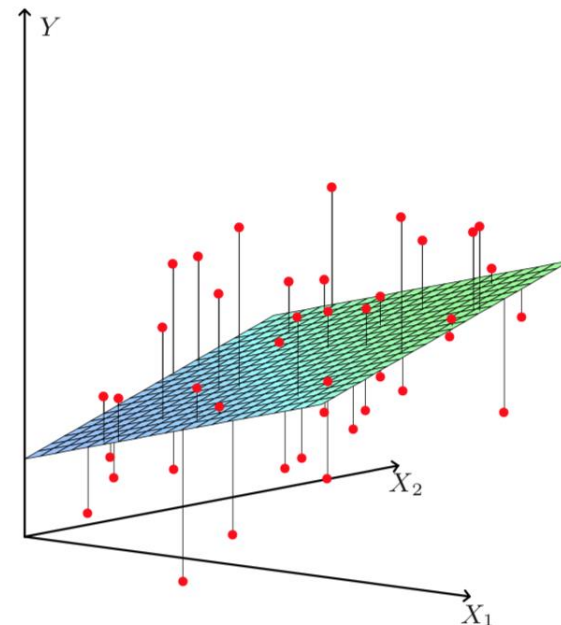
Unknown parameters/coefficients

- Input variables X_j can come from different sources:
 - quantitative inputs,
 - transformation of quantitative inputs,
 - coding of the levels of qualitative (class labels) inputs,
 - basis expansions
- No matter of the source of the X_j , model is linear in the parameters

Supervised Learning – Linear Methods for Regression

- Typically, using a training set $(x_1, y_1) \dots (x_N, y_N)$ from which to estimate the parameters β .
- Each $x_i = (x_{i1}, x_{i2}, \dots, x_{ip})^T$ is a factor of measurements of i -th case
- Popular estimation method is *least squares*, which minimise the residual sum of squares:

$$\begin{aligned}\text{RSS}(\beta) &= \sum_{i=1}^N (y_i - f(x_i))^2 \\ &= \sum_{i=1}^N \left(y_i - \beta_0 - \sum_{j=1}^p x_{ij} \beta_j \right)^2.\end{aligned}$$



Supervised Learning – Linear Methods for Classification

- Goal in classification is to take input x and assign it to one of K discrete classes C_k
- C_k typically disjoint (unique class membership)

$$x_i = \boxed{\text{4}} \quad t_i = (0, 0, 0, 1, 0, 0, 0, 0, 0, 0)$$

- Training set $\{(x_1, t_1), \dots, (x_N, t_N)\}$
- Learning problem is to construct a “good” function $y(x)$ from these by:
 - Discriminant function
 - Probabilistic generative models
 - Probabilistic discriminative models

Supervised Learning – Linear Methods for Classification

- Generalised linear model for classification:

$$y(\mathbf{x}) = f(\mathbf{w}^T \mathbf{x} + w_0)$$

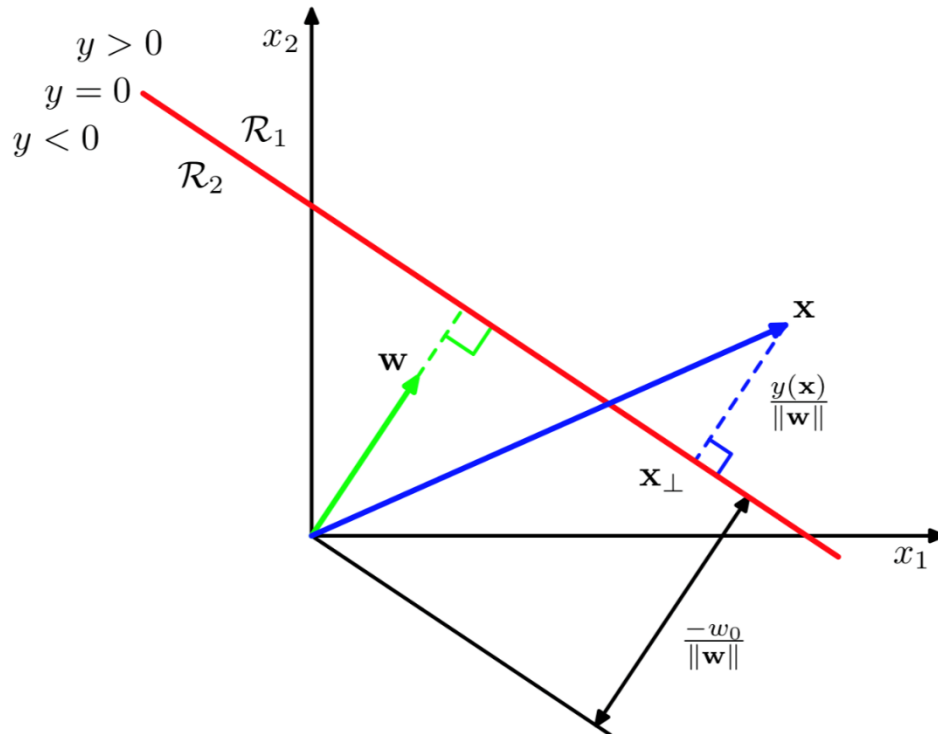
- $f(\cdot)$ is a fixed non-linear function
 - No longer linearity in the parameters
 - More complex analytical and computational properties

$$f(u) = \begin{cases} 1 & \text{if } u \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

- Decision boundary between classes will be a linear function of \mathbf{x}

Supervised Learning – Linear Methods for Classification

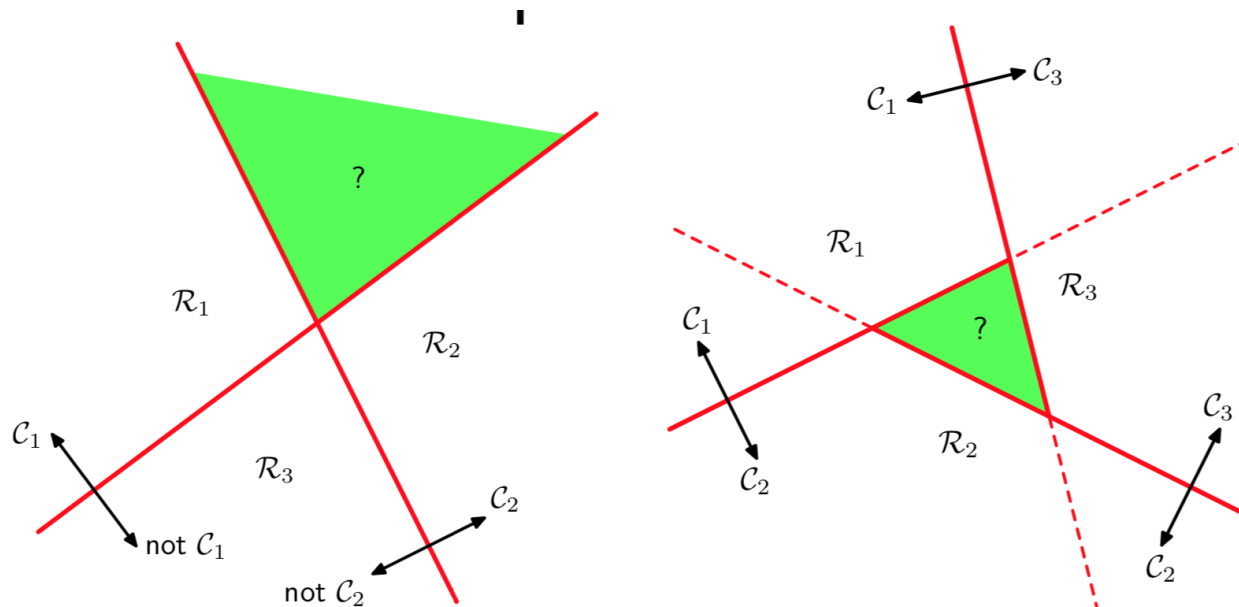
- Discriminant functions for two classes: $y(x) = w^T x + w_0$
 - Takes an input vector x_i and assigns it to one of K classes C_k
 - If $y(x) \geq 0 \rightarrow$ assigned to class C_1 and to class C_2 otherwise



- 2 class problem, $t \in \{0,1\}$
- Simple linear discriminant $y(x) = w^T x + w_0$
- Apply threshold function to get classification

Supervised Learning – Linear Methods for Classification

- Discriminant functions with for multiple classes:
 - One-versus-the-rest method: build $K - 1$ classifiers, between C_k and all others
 - One-versus-one method: build $K(K - 1)/2$ classifiers, between all pairs



Supervised Learning – Linear Methods for Classification

- Learning of K discriminant functions:

$$y_k(\mathbf{x}) = \mathbf{w}_k^T \mathbf{x} + w_{k0}$$

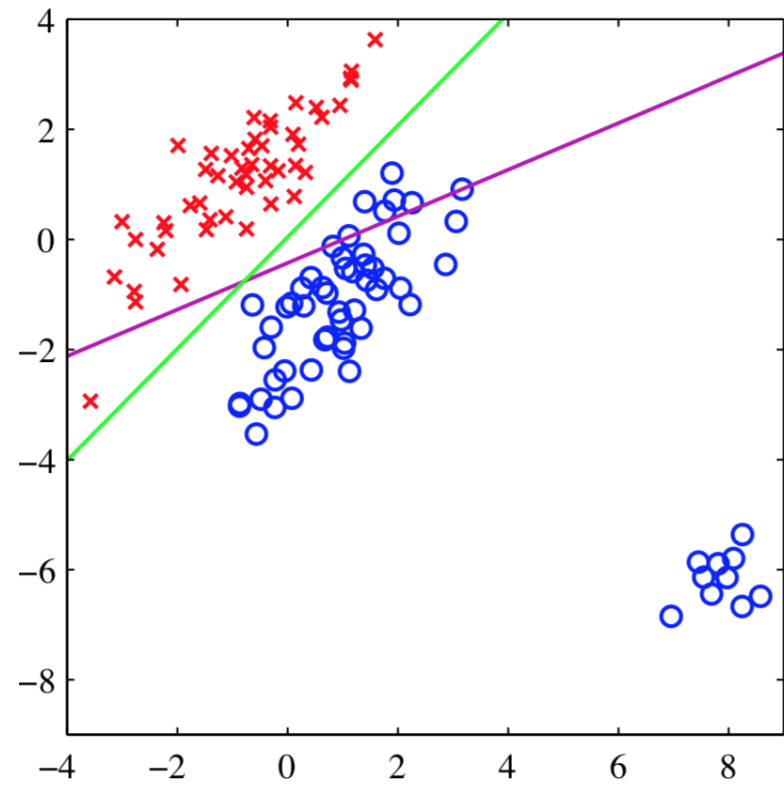
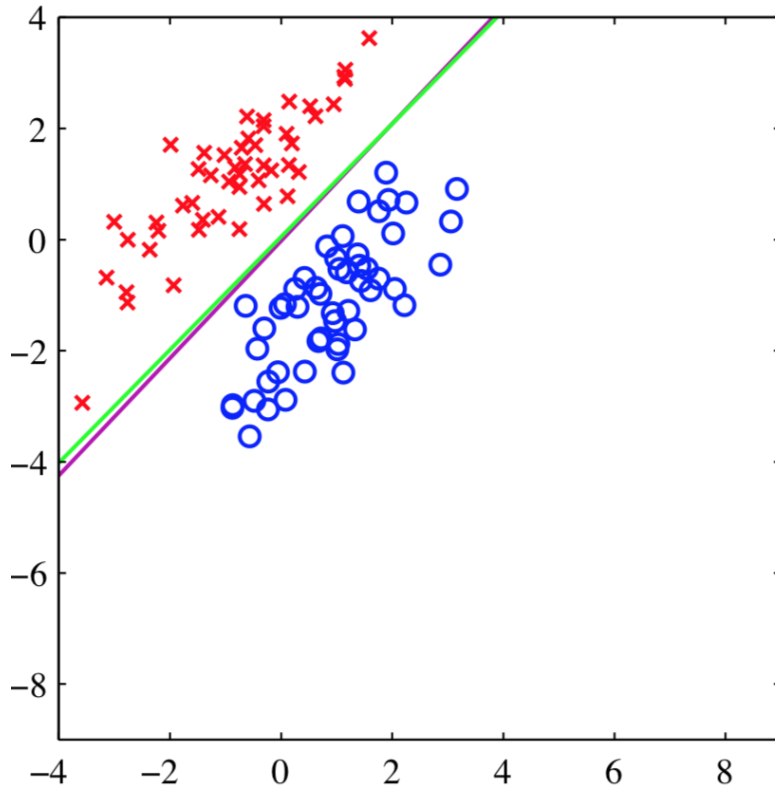
- Assign \mathbf{x} to class $\arg \max_k y_k(\mathbf{x})$
- How do we learn the decision boundaries (\mathbf{w}_k, w_{k0}) ?

$$E(\mathbf{W}) = \frac{1}{2} \sum_{n=1}^N \sum_{k=1}^K (y_k(\mathbf{x}_n) - t_{nk})^2$$

- Use least squares, to find \mathbf{W} which minimise squared error over all examples and all class labels

Supervised Learning – Linear Methods for Classification

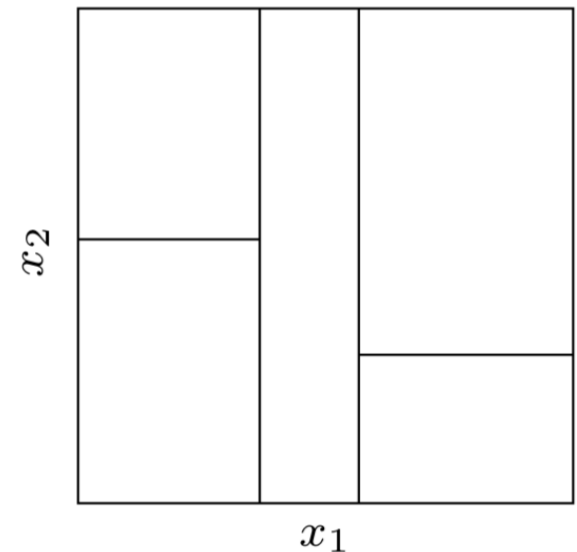
- Problem with least square method:



- Points far away from the decision boundary will cause a large error \rightarrow boundary is moved

Supervised Learning – Tree-Based Methods

- In both regression and classification settings we seek a function $y(\mathbf{x})$ which maps the input \mathbf{x} into a prediction.
- One **flexible** way is to partition the input space into disjoint regions and fit a simple model in each region.
- **Classification:** Majority vote within the region.
- **Regression:** Mean of training data within the region.

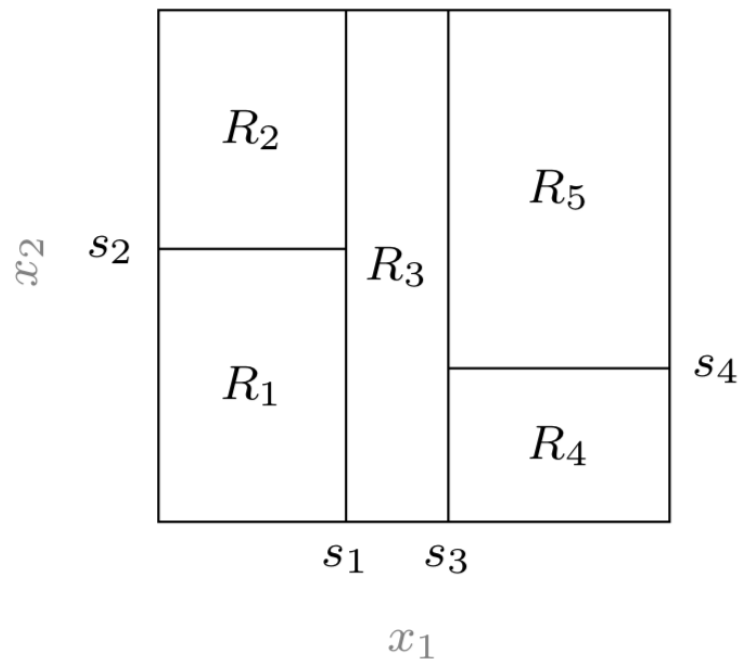


Supervised Learning – Tree-Based Methods

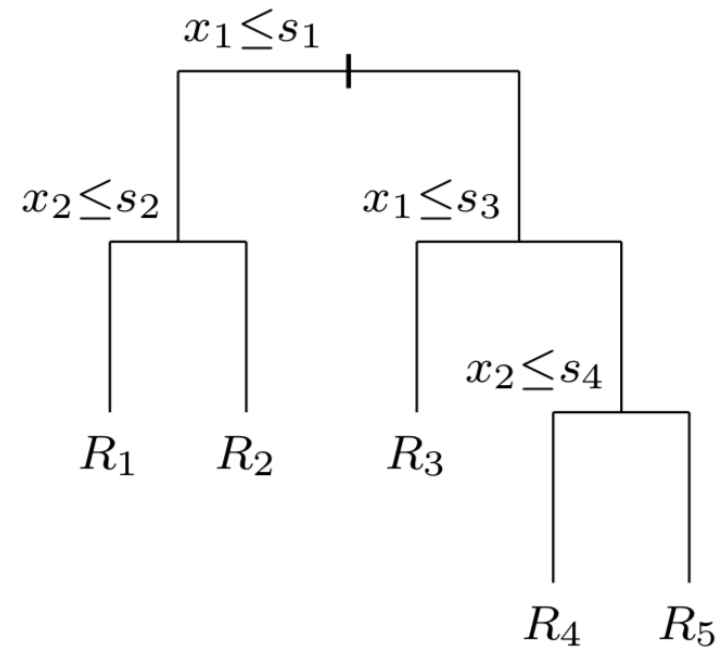
- Challenge: find a good partition
- Instead, we use a “greedy” approach: **recursive binary splitting**.
- 1. Select one of the inputs x_j and a cut-point s . Partition the input space into two half-spaces,
$$\{\mathbf{x}: x_j < s\} \qquad \qquad \qquad \{\mathbf{x}: x_j \geq s\}$$
- 2. Repeat this splitting for each region until some stopping criterion is met (e.g., no region contains more than 5 training data points).
- Generally a metric is used to calculate the benefit of a split, e.g.
information gain: Information gain = Entropy before split – Entropy after split

Supervised Learning – Tree-Based Methods

Partitioning of input space



Tree representation



Supervised Learning – Classification Tree

- The class prediction for each region is based on the proportion of data points from each class in that region.

$$\hat{\pi}_{mk} = \frac{1}{n_m} \sum_{i: \mathbf{x}_i \in R_m} \mathbb{I}\{y_i = k\}$$

- Proportion of training observations in the m -th region that belong to the k -th class.
- Approximation of the class probability:

$$p(y = k | \mathbf{x}) \approx \sum_{m=1}^M \hat{\pi}_{mk} \mathbb{I}\{\mathbf{x} \in R_m\}$$

Supervised Learning – Improving tree-based Models

- The performance of a tree-based model is often unsatisfactory
- To improve the practical performance:
 - **Pruning** – grow a deep tree which is then pruned into a smaller one
 - **Ensemble methods** – average or combine multiple trees.
 - Bagging and Random Forests
 - Boosted trees

Supervised Learning – Random Forest

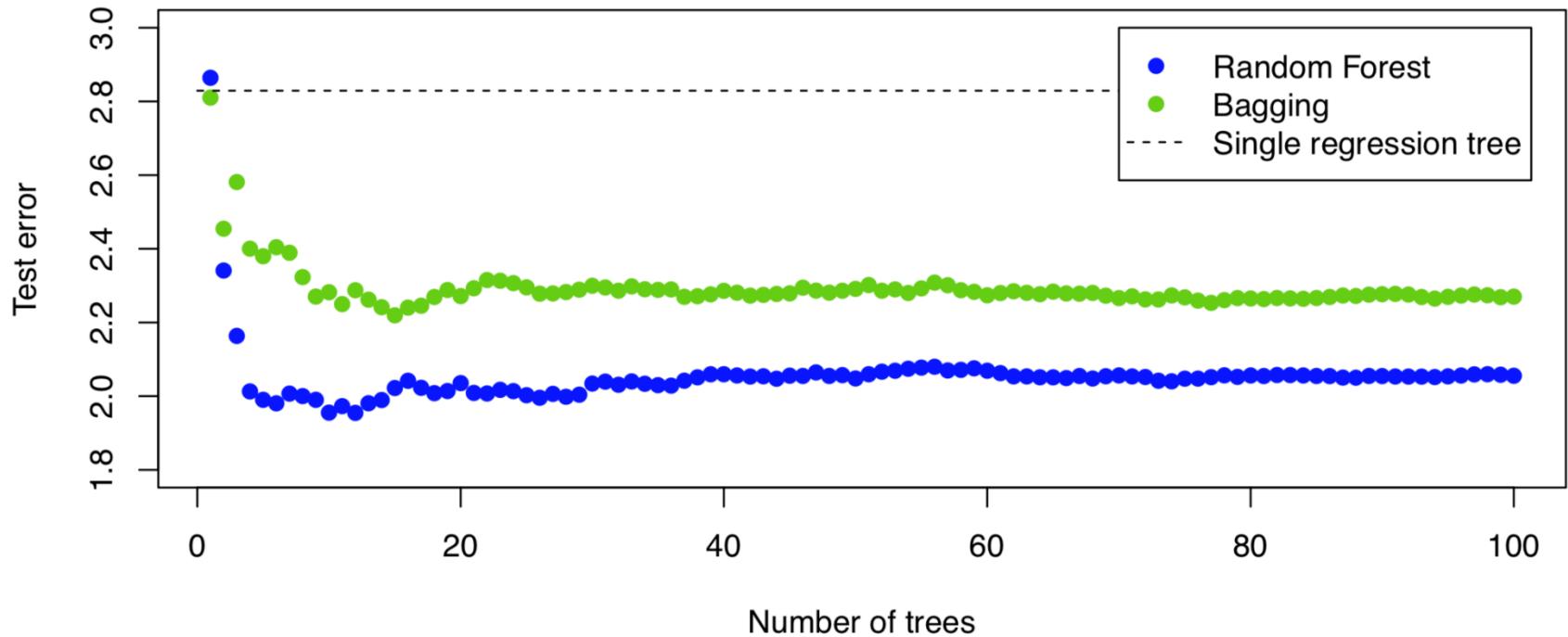
- A **random forest** is constructed by bagging, but for each split in each tree only a **random subset** of $q \leq p$ inputs are considered as splitting variables.
- Rule of thumb: $q = \sqrt{p}$ for classification trees and $q = p/3$ for regression trees.

Algorithm Random forest for regression

1. For $b = 1$ to B (*can run in parallel*)
 - (a) Draw a bootstrap data set $\tilde{\mathcal{T}}$ of size n from \mathcal{T} .
 - (b) Grow a regression tree by repeating the following steps until a minimum node size is reached:
 - i. Select q out of the p input variables uniformly at random.
 - ii. Find the variable x_j among the q selected, and the corresponding split point s , that minimizes the squared error.
 - iii. Split the node into two children with $\{x_j \leq s\}$ and $\{x_j > s\}$.
2. Final model is the average the B ensemble members,

$$\hat{y}_{\star}^{\text{rf}} = \frac{1}{B} \sum_{b=1}^B \tilde{y}_{\star}^b.$$

Supervised Learning – Random Forest



Unsupervised Learning

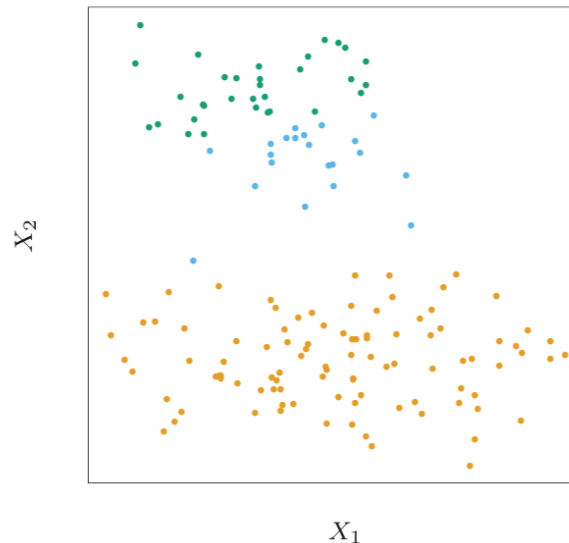
Unsupervised Learning – Introduction

- Supervised: We are given input/output samples (X, y) which we relate with a function $y = f(X)$.
- We would like to “learn” f , and evaluate it on new data.
- Types:
 - Classification: y is discrete (e.g. class labels).
 - Regression: y is continuous, e.g. linear regression.
- Unsupervised: Given only samples X of the data, we compute a function f such that $y = f(X)$ is “simpler”.
 - y is discrete: Clustering
 - y is continuous: Matrix factorisation, Kalman filtering, unsupervised neural networks
- Example: Clustering for segmentation
 - Break an image into regions of points with similar features



Unsupervised Learning – Cluster Analysis

- Identifying groups, or clusters of data points
- Objects within each cluster are more closely related to one another than objects assigned to different clusters
- Object can be described by a set of measurements, or by its relation to other objects



Unsupervised Learning – Cluster Analysis

- To measure the relation between objects similarities or dissimilarities can be used
- Most often we have measurements x_{ij} for $i = 1, 2, \dots, N$, on variables $j = 1, 2, \dots, p$ (attributes/features)
- Dissimilarity between objects i and i' is:

$$D(x_i, x_{i'}) = \sum_{j=1}^p d_j(x_{ij}, x_{i'j})$$

- Common choice is squared distance:

$$d_j(x_{ij}, x_{i'j}) = (x_{ij} - x_{i'j})^2$$

Unsupervised Learning – Cluster Analysis

- Further dissimilarities-based methods:

- Absolute differences:

$$d(x_i, x_{i'}) = l(|x_i - x_{i'}|).$$

- Correlation:

$$\rho(x_i, x_{i'}) = \frac{\sum_j (x_{ij} - \bar{x}_i)(x_{i'j} - \bar{x}_{i'})}{\sqrt{\sum_j (x_{ij} - \bar{x}_i)^2 \sum_j (x_{i'j} - \bar{x}_{i'})^2}}$$

Unsupervised Learning – Clustering Algorithms

- Centroid-based clustering:
 - K -means
 - Kernel k -means
 - Fuzzy C -means
- Hierarchical clustering:
 - Agglomerative: bottom-up
 - Divisive: top-down
- Distribution-based clustering:
 - Gaussian mixture model (GMM)
- Density-based clustering:
 - Mean-shift

Unsupervised Learning – *K*-means Clustering

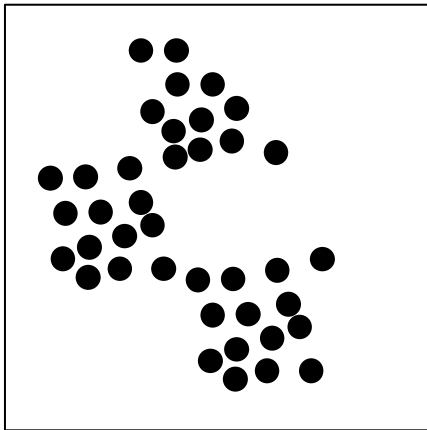
- The basic idea is to describe each cluster by its mean value.
- The goal of k-means is to assign data to clusters and define these clusters with their means.
- An iterative clustering algorithm:
 - Initialize: Pick K random points as cluster centres
 - Alternate:
 - 1. Assign data points to closest cluster centre
 - 2. Change the cluster centre to the average of its assigned points
- Stop when no points' assignments change

K-Means

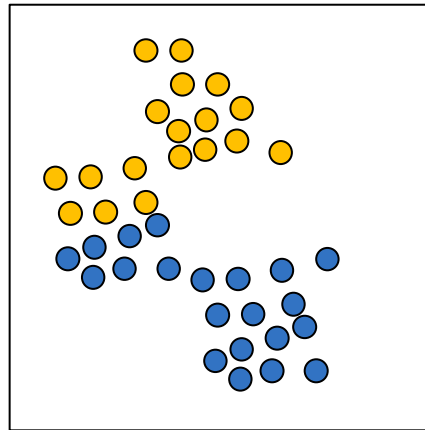
Problem

- Given: N data points
- Wanted: Divide data points into K clusters

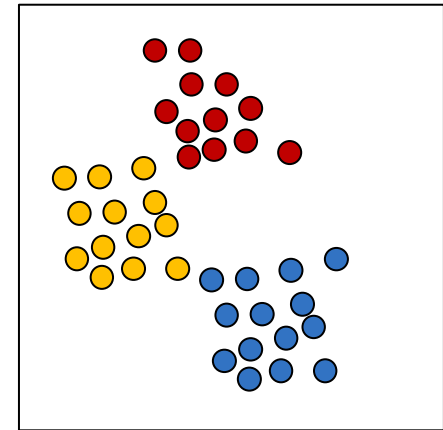
$K = 1$



$K = 2$



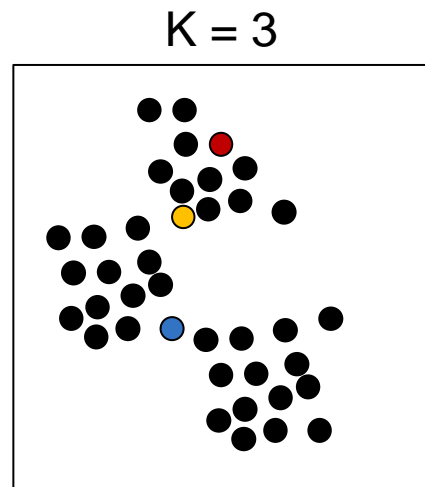
$K = 3$



K-Means

Approach

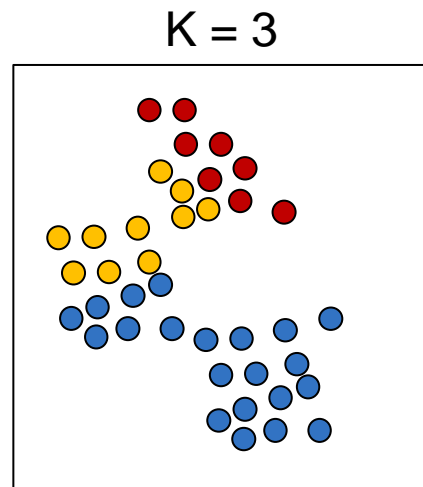
- Select K initial points (centroids)



K-Means

Approach

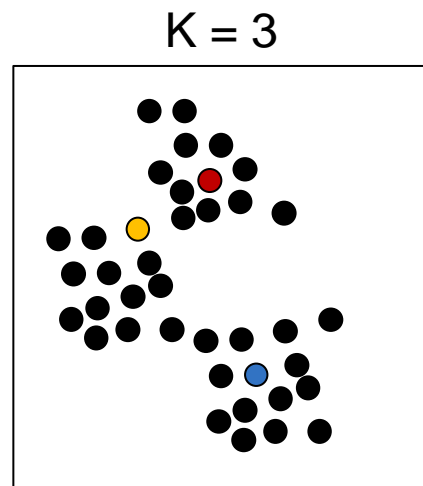
- Select K initial points (centroids)
- Assign each point to the closest centroid



K-Means

Approach

- Select K initial points (centroids)
- Assign each point to the closest centroid
- Compute new centroid for each cluster

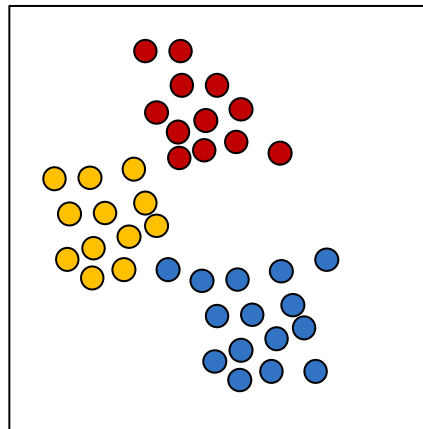


K-Means

Approach

- Select K initial points (centroids)
- Assign each point to the closest centroid
- Compute new centroid for each cluster
- Repeat (for a fixed amount of times or until convergence)

$K = 3$

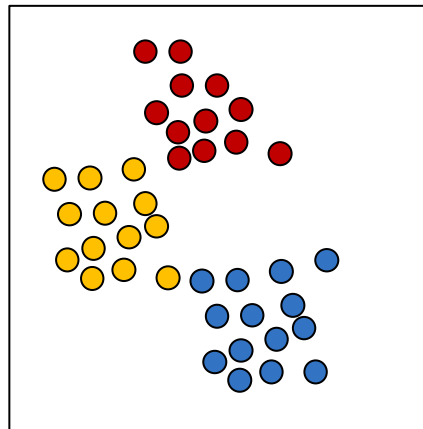


K-Means

Summary

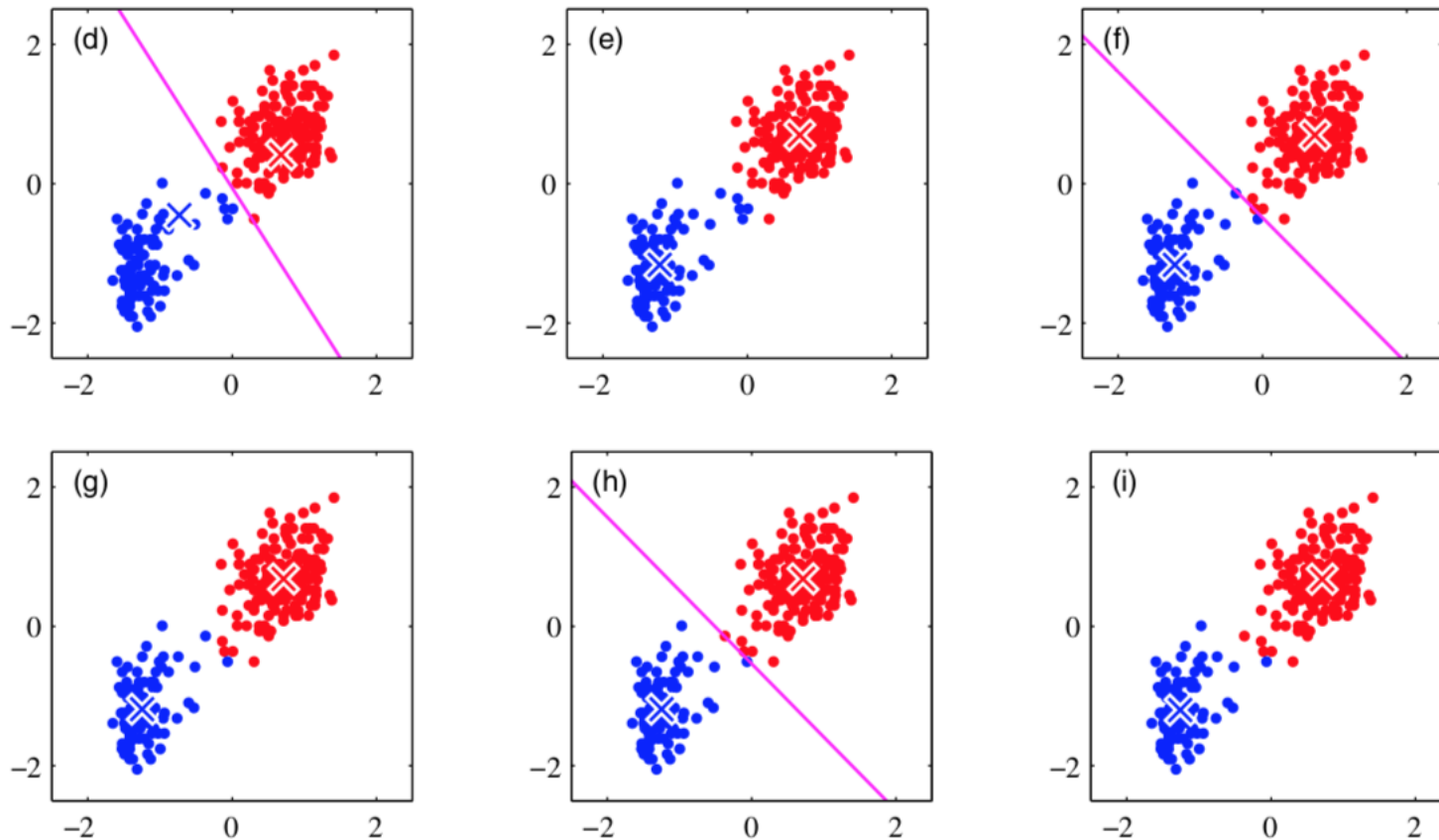
- Simple method for dividing data into clusters
- No supervision required
- Results depended on choice of initial points
- => not guaranteed to converge into global optimum

$K = 3$



Unsupervised Learning – K -means Clustering

Repeat until convergence:



Unsupervised Learning – *K*-means Clustering

Segmentation example:

K=2



K=3

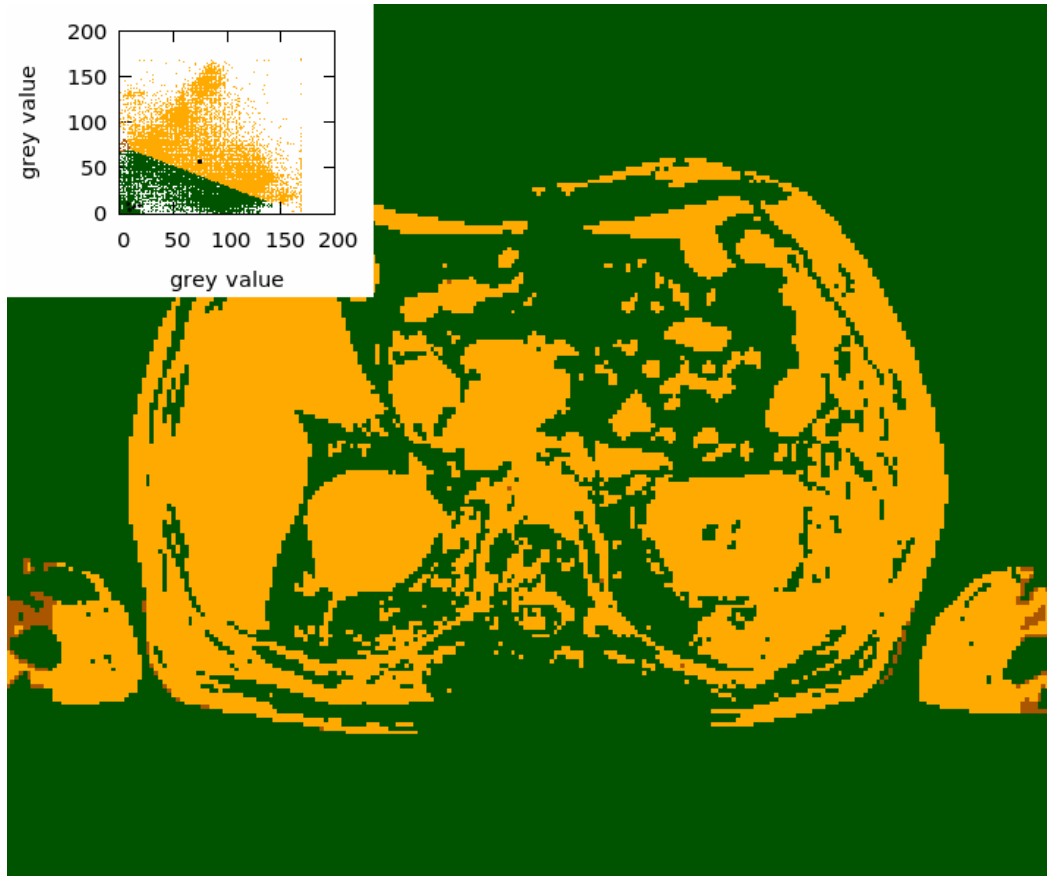


Original



Unsupervised Learning – *K*-means Clustering

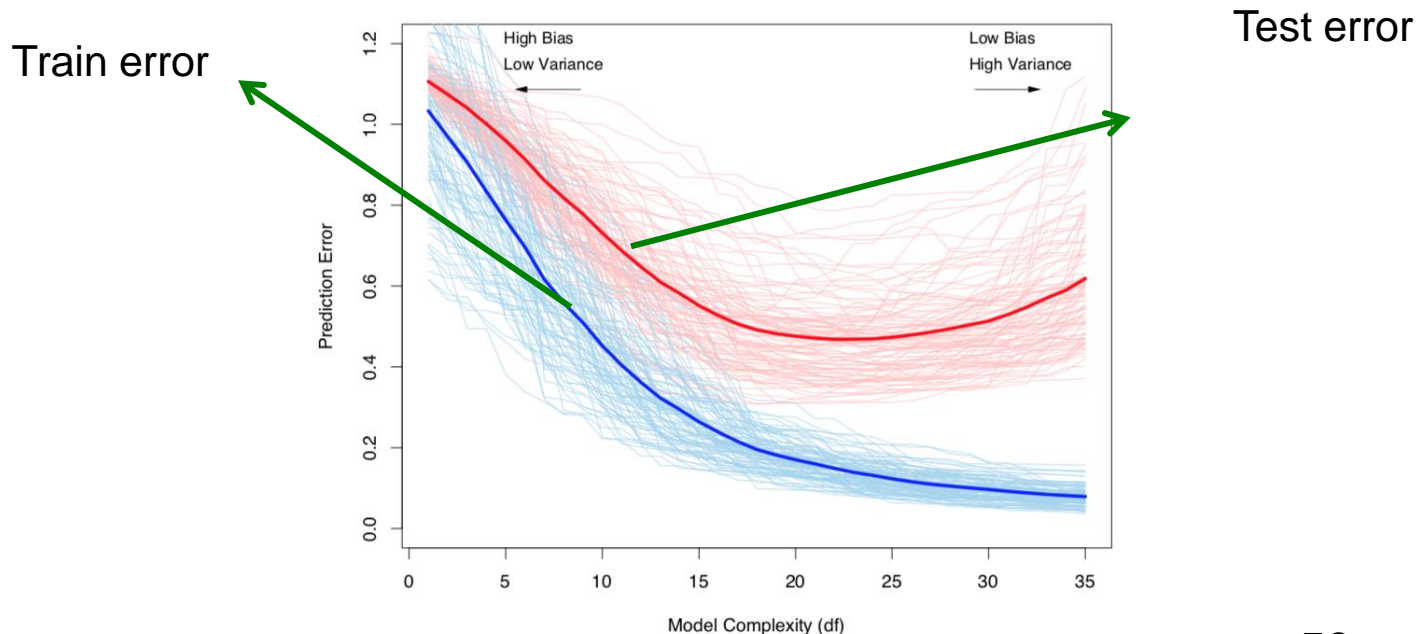
Segmentation example:



Model Assessment and Selection

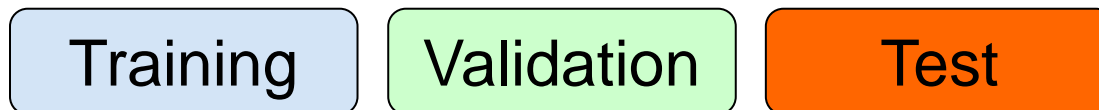
Model Assessment and Selection

- Assessment of this performance is extremely important in practice:
 - It guides the choice of learning method or model
 - Measure of the quality of the chosen model
- Generalisation performance of a learning method relates to its prediction capability on independent test data



Model Assessment and Selection

- Tuning parameters α varies the model complexity
- Find value of α which minimise the average test error
- Objectives:
 - Model selection: estimating the performance of different models in order to choose the best one
 - Model assessment: estimating the prediction error on new data using the chosen model



Model Assessment and Selection

- **K-Fold Cross-Validation:**
 - Split data into K roughly equal-sized parts
- **Example for $K=5$:**
 - Fit model to $K-1$ parts and calculate the prediction error using k -th part

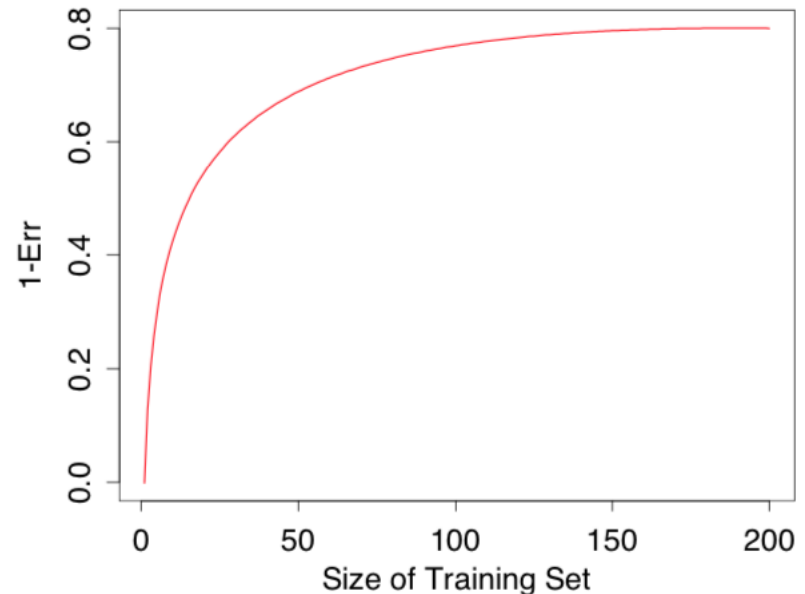
1	2	3	4	5
Train	Train	Validation	Train	Train

- Cross-validation estimate of prediction error:

$$CV(\hat{f}) = \frac{1}{N} \sum_{i=1}^N L(y_i, \hat{f}^{-\kappa(i)}(x_i)).$$

Model Assessment and Selection

- What value should we choose for K ?
 - $K=N$: Unbiased for the true (expected) prediction error but can have high variance AND high computational burden
 - $K=5$: Has lower variance but bias could be a problem
- Hypothetical “learning curve”
 - Only small benefit if increasing the number of observation from 100 to 200
 - Trainings set $N=50$: 5-Fold CV leads to an underestimation
- For practice:
 - 5-Fold or 10-Fold CV are recommended as a good compromise

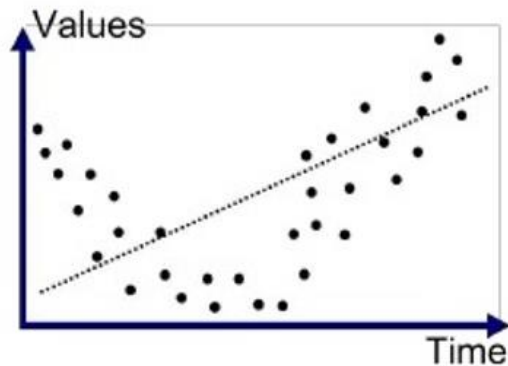


Model Assessment and Selection

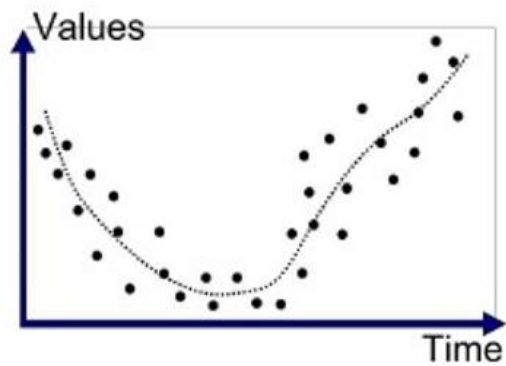
- Right Way to do Cross-validation:
 - Divide samples into K cross-validation folds at random
 - For each fold $k=1,2,\dots,K$
 - Find a subset of „good“ predictors using all the samples except those in fold k
 - Using this subset and build classifier on all samples except those in fold k
 - Use this classifier to perform prediction for the samples in fold k

Model Assessment and Selection

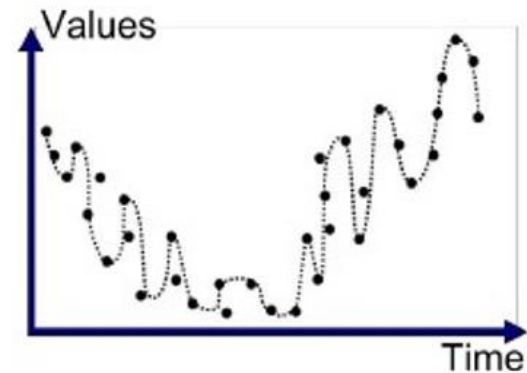
- Underfitting
 - Model is too simple to fit the given data
- Overfitting
 - Model is not able to generalize, as it also learns noise and outliers



Underfitted



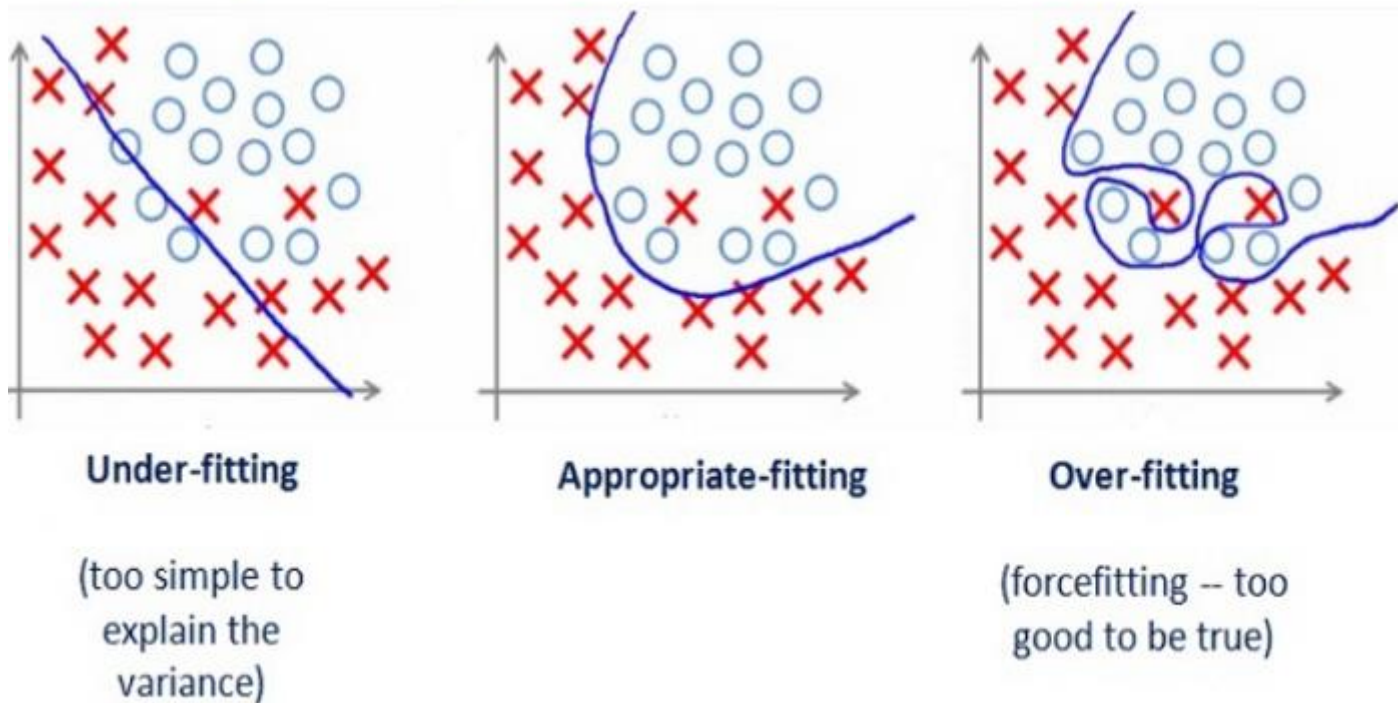
Good Fit/Robust



Overfitted

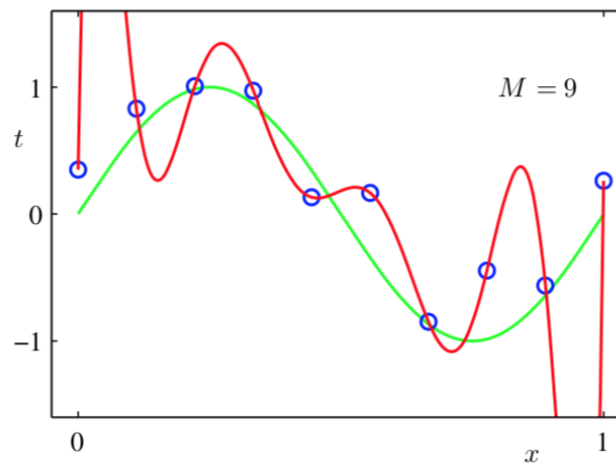
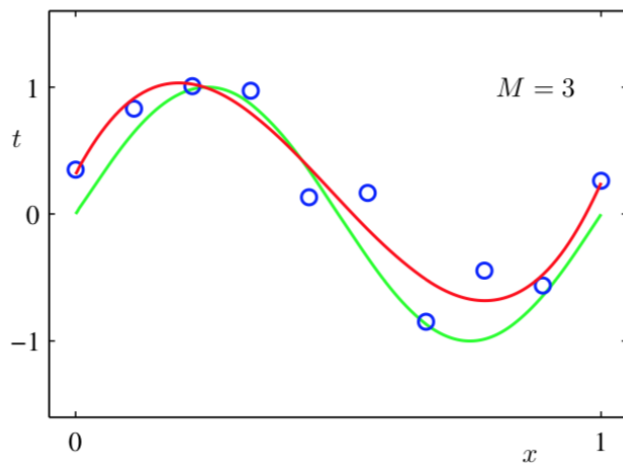
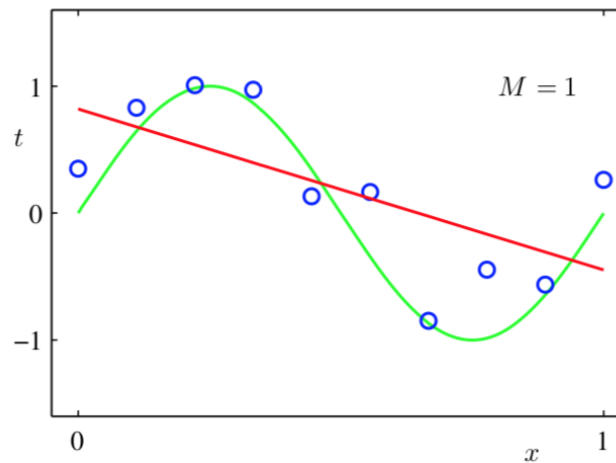
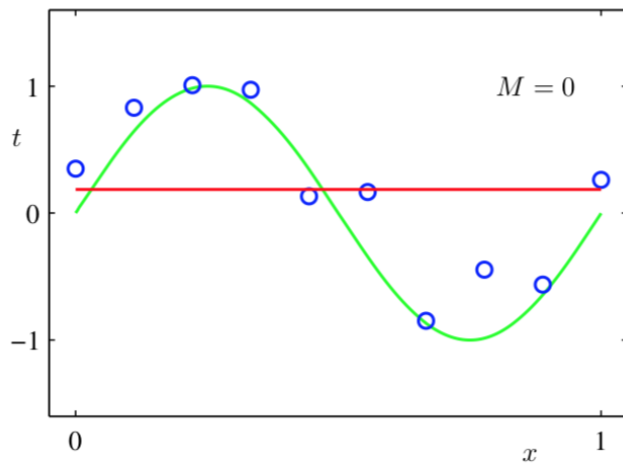
Model Assessment and Selection

- Underfitting
 - Model is too simple to fit the given data
- Overfitting
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Model Assessment and Selection

- Polynomial function: $y(x, \mathbf{w}) = w_0 + w_1x + w_2x^2 + \dots + w_Mx^M = \sum_{j=0}^M w_jx^j$



Literature

- Bishop et al., Pattern Recognition and Machine Learning
- Barber et al., Bayesian Reasoning and Machine Learning
- Hastie et al. The Elements of Statistical Learning