Contents

1 Data Structure

1.1 Splay

```
struct node_t {
  node_t();
  void update();
  int dir() { return (this == p->ch[1]); }
  void setc(node_t *c, int d) { ch[d] = c, c->p = this; }
  node_t *p, *ch[2];
  int size, cnt; // maintain tag from top to bottom (via find).
} s[maxn], *nil = s, *root;
node_t::node_t() { p = ch[0] = ch[1] = nil; }

void node_t::update() {
  if (this == nil) return;
  size = ch[0]->size + ch[1]->size + cnt;
}

node_t *newNode(int cnt) {
  ++pt;
  s[pt].cnt = cnt; s[pt].p = s[pt].ch[0] = s[pt].ch[1] = nil;
  s[pt].update();
  return &s[pt];
}

void rotate(node_t *t) {
  node_t *p = t->p;
  p->p->update();
  p->update();
  t->update();
  int d = t->dir();
  p->p->setc(t, p->dir());
  p->setc(t->ch[!d], d);
  t->setc(p, !d);
  if (p == root) root = t;
  p->update(), t->update();
}

node_t *splay(node_t *t, node_t *dst = nil) {
  while (t->p != dst) {
    if (t->p->p == dst) rotate(t);
    else if (t->dir() == t->p->dir()) rotate(t->p), rotate(t);
    else rotate(t), rotate(t);
  }
  t->update();
  return t;
}

```

```
node_t *prev(node_t *p) {
  splay(p);
  p = p->ch[0], p->update();
  while (p->ch[1] != nil) p = p->ch[1], p->update();
  return p;
}

node_t *succ(node_t *p) {
  splay(p);
  p = p->ch[1], p->update();
  while (p->ch[0] != nil) p = p->ch[0], p->update();
  return p;
}

void insert(node_t *y, node_t *x) { // Insert node x after y
  splay(y);
  if (y->ch[1] == nil) {
    y->ch[1] = x;
    x->p = y;
    y->update();
  } else {
    y = y->ch[1], y->update();
    while (y->ch[0] != nil) y = y->ch[0], y->update();
    y->ch[0] = x;
    x->p = y;
    y->update();
  }
  splay(x);
}

void removeAll(node_t *x) { // Remove all the whole subtree of x
  x->p->update();
  x->p->ch[x->dir()] = nil;
  x->p->update();
  splay(x->p);
  x->p = nil;
}

void remove(node_t *x) { // Remove the single node x
  node_t *p = prev(x); node_t *s = succ(x);
  splay(p);
  splay(s, p);
  removeAll(s->ch[0]);
}

node_t *find(node_t *t, int k) {
  t->update();
  if (t->ch[0]->size < k && t->ch[0]->size + t->cnt >= k) return t;
  if (t->ch[0]->size >= k) return find(t->ch[0], k);
  return find(t->ch[1], k - t->ch[0]->size - t->cnt);
}

node_t *findAndSplit(node_t *t, int k) {
  t->update();
  if (t->ch[0]->size < k && t->ch[0]->size + t->cnt >= k) {
    int cnt = t->cnt;
    k -= t->ch[0]->size;
    t->cnt = 1;
    splay(t);
    node_t *p = prev(t);
    if (k - 1) insert(p, newNode(k - 1));
    if (cnt - k) insert(t, newNode(cnt - k));
    return t;
  }
  if (t->ch[0]->size >= k) return findAndSplit(t->ch[0], k);
  return findAndSplit(t->ch[1], k - t->ch[0]->size - t->cnt);
}

void init() {
  pt = 0, nil->p = nil->ch[0] = nil->ch[1] = nil;
}

node_t *expose(node_t *x, node_t *y) {
  x = prev(x), y = succ(y);
  return splay(y, splay(x))->ch[0];
}
```

1.2 Dynamic Tree

```
struct node_t {
  node_t();
  node_t *ch[2], *p;
  int size, root;
  int dir() { return this == p->ch[1]; }
  void setc(node_t *c, int d) { ch[d] = c, c->p = this; }
  void update() { size = ch[0]->size + ch[1]->size + 1; }
} s[maxn], *nil = s;

node_t::node_t() {
  size = 1, root = true;
  ch[0] = ch[1] = p = nil;
}

void rotate(node_t *t) {
  node_t *p = t->p;
  int d = t->dir();
```

```
  if (!p->root) {
    p->p->setc(t, p->dir());
  } else {
    p->root = false, t->root = true;
    t->p = p->p; // Path Parent
  }
  p->setc(t->ch[!d], d);
  t->setc(p, !d);
  p->update(), t->update();
}

void splay(node_t *t) {
  // t->update(); // tag!
  while (!t->root) {
    // if (!t->p->root) t->p->p->update(); t->p->update(), t->update(); // !
    if (!t->p->root) rotate(t->dir() == t->p->dir() ? t->p : t);
    rotate(t);
  }
}

void access(node_t *x) { // Ask u, v: access(u), access(v, true), x = LCA
  node_t *y = nil;
  while (x != nil) {
    splay(x);
    // if (x->p == nil) at second call, x->ch[1](rev) + (x)_single + y
    x->ch[1]->root = true;
    x->ch[1] = y, y->root = false;
    x->update();
    y = x, x = x->p;
  }
}

void cut(node_t *x) {
  access(x);
  splay(x);
  x->ch[0]->root = true;
  x->ch[0]->p = nil;
  x->ch[0] = nil;
}

void link(node_t *x, node_t *y) {
  access(y);
  splay(y);
  y->p = x;
  access(y);
}

void init() { nil->size = 0; }
```

1.3 KD Tree

```
//如果被卡可以考虑写上 minx,maxx,miny,maxy 维护矩形，修改 KDTree_Build 加上对应的维护。
struct POINT { int x,y,id; };
inline bool cmp_x(const POINT& a,const POINT& b) { return a.x == b.x ? a.y < b.y : a.x < b.x; }
inline bool cmp_y(const POINT& a,const POINT& b) { return a.y == b.y ? a.x < b.x : a.y < b.y; }

struct KDNODE {
  POINT p;
//  int minx,maxx,miny,maxy;

  KDNODE* Child[2], *fa;
};
KDNODE NPool[111111];
KDNODE* NPTop = NPool;
KDNODE* Root;

inline KDNODE* AllocNode() { memset(NPTop,0,sizeof(KDNODE)); return NPTop++; }
inline ll PDist(const POINT& a,const POINT& b) { return sqr((ll)(a.x-b.x))+sqr((ll)(a.y-b.y)); }

POINT pnt[111111];
KDNODE* KDTree_Build(int l,int r,int depth=0) {
  if(l >= r) return NULL;

  if(depth&1) sort(pnt+l,pnt+r,cmp_y);
  else sort(pnt+l,pnt+r,cmp_x);

  int mid = (l+r)/2;
  KDNODE* t = AllocNode();

  t->Child[0] = KDTree_Build(l,mid,depth+1);
  t->Child[1] = KDTree_Build(mid+1,r,depth+1);
  for(int i = 0;i < 2;i++) if(t->Child[i]) t->Child[i]->fa = t;
  return t;
}

void KDTree_Insert(KDNODE* cur,POINT& P,int depth=0) {
  KDNODE* node = AllocNode(); node->p = P;
  while(cur) {
    if(cur->p.x == P.x && cur->p.y == P.y && cur->p.id == P.id) break;
    int dir = 0;
    if(depth&1) dir = cmp_y(x->p,P);
    else dir = cmp_x(x->p,P);
    if(!cur->Child[dir]) {
      cur->Child[dir] = node;
```

```
      node->fa = cur;
      break;
    } else {
      cur = cur->Child[dir];
      depth++;
    }
  }
}

ll KDTree_Nearest(KDNODE* x,const POINT& q,int depth=0) {
  KDNODE* troot = x->fa;
  int dir = 0;
  while(x) {
    if(depth&1) dir = cmp_y(x->p,q);
    else dir = cmp_x(x->p,q);

    if(!x->Child[dir]) break;
    x = x->Child[dir];
    depth++;
  }
  ll ans = ~0ULL>>1;
  while(x != troot) {
    ll tans = PDist(q,x->p);
    if(tans < ans) ans = tans;
    KDNODE* oside = x->Child[dir^1];
    if(oside) {
      ll ldis = 0;
      /*if(depth&1) ldis = min(sqr((ll)q.y-oside->miny),sqr((ll)q.y-oside->maxy));
      else ldis = min(sqr((ll)q.x-oside->minx),sqr((ll)q.x-oside->maxx));*/
      if(depth & 1) ldis = sqr<ll>(x->p.y-q.y);
      else ldis = sqr<ll>(x->p.x-q.x);
      if(ldis < ans) {
        tans = KDTree_Nearest(oside,q,depth+1);
        if(tans && tans < ans) ans = tans;
      }
    }

    if(x->fa && x == x->fa->Child[0]) dir = 0;
    else dir = 1;
    x = x->fa;
    depth--;
  }
  return ans;
}
```

1.4 Treap

```
struct node {
  int v, key, size;
  node *c[2];
  void resize() { size = c[0]->size + c[1]->size + 1; }
};
node *newNode(int _v, node *n) {
  ++ref;
  pool[ref].v = _v, pool[ref].c[0] = pool[ref].c[1] = n, pool[ref].size = 1, pool[
    ref].key = rand();
  return &pool[ref];
}
struct Treap {
  node *root, *nil;
  void rotate(node *&t, int d) {
    node *c = t->c[d];
    t->c[d] = c->c[!d];
    c->c[!d] = t;
    t->resize(); c->resize();
    t = c;
  }
  void insert(node *&t, int x) {
    if (t == nil) t = newNode(x, nil);
    else {
      if (x == t->v) return;
      int d = x > t->v;
      insert(t->c[d], x);
      if (t->c[d]->key < t->key) rotate(t, d);
      else t->resize();
    }
  }
  void remove(node *&t, int x) {
    if (t == nil) return;
    if (t->v == x) {
      int d = t->c[1]->key < t->c[0]->key;
      if (t->c[d] == nil) {
        t = nil;
        return;
      }
      rotate(t, d);
      remove(t->c[!d], x);
    } else {
      int d = x > t->v;
      remove(t->c[d], x);
    }
    t->resize();
  }
  int rank(node *t, int x) {
    if (t == nil) return 0;
    int r = t->c[0]->size;
```

```
    if (x == t->v) return r + 1;
    if (x < t->v) return rank(t->c[0], x);
    return r + 1 + rank(t->c[1], x);
  }
  int select(node *t, int k) {
    int r = t->c[0]->size;
    if (k == r + 1) return t->v;
    if (k <= r) return select(t->c[0], k);
    return select(t->c[1], k - r - 1);
  }
  int size() {
    return root->size;
  }
  void init(int *a, int n) {
    nil = newNode(0, 0);
    nil->size = 0, nil->key = ~0U >> 1;
    root = nil;
  }
};
```

1.5 President Treap

```
struct node_t {
  int key, cnt, size;
  string v;
  node_t *c[2];
  void resize() {
    size = (c[0] ? c[0]->size : 0) + cnt + (c[1] ? c[1]->size : 0);
  }
} *nil;

node_t *newNode(string v, node_t *l = nil, node_t *r = nil, int key = rand()) {
  node_t *ret = new node_t();
  ret->key = key;
  ret->cnt = v.length(), ret->v = v;
  ret->c[0] = l, ret->c[1] = r;
  ret->resize();
  return ret;
}

void init() {
  nil = newNode("", 0, 0);
  nil->size = 0, nil->key = ~0U >> 1;
}

struct PresidentTreap {
  node_t *root;
  node_t *splitL(node_t *a, int size) {
    if (a == nil || size == 0) return nil;
    if (a->c[0]->size >= size) return splitL(a->c[0], size);
    if (a->c[0]->size + a->cnt >= size) return newNode(a->v.substr(0, size - a->c
      [0]->size), a->c[0], nil, a->key);
    return newNode(a->v, a->c[0], splitL(a->c[1], size - a->c[0]->size - a->cnt), a
      ->key);
  }
  node_t *splitR(node_t *a, int size) {
    if (a == nil || size == 0) return nil;
    if (a->c[1]->size >= size) return splitR(a->c[1], size);
    if (a->c[1]->size + a->cnt >= size) return newNode(a->v.substr(a->v.length() - (
      size - a->c[1]->size), size - a->c[1]->size), nil, a->c[1], a->key);
    return newNode(a->v, splitR(a->c[0], size - a->c[1]->size - a->cnt), a->c[1], a
      ->key);
  }
  node_t *merge(node_t *a, node_t *b) {
    if (a == nil) return b;
    if (b == nil) return a;
    if (a->key > b->key) return newNode(a->v, a->c[0], merge(a->c[1], b), a->key);
    return newNode(b->v, merge(a, b->c[0]), b->c[1], b->key);
  }
  node_t *insert(string v, int p) { // insert after p
    int l = root->size;
    return merge(merge(splitL(root, p), newNode(v, nil, nil)), splitR(root, l - p));
  }
  node_t *remove(int x, int y) { // remove [x, y]
    int l = root->size;
    return merge(splitL(root, x - 1), splitR(root, l - y));
  }
};
```

1.6 President Segment Tree

```
struct Node {
  int s, d;
  Node *left, *right;
} pool[maxm], *nil, *root[maxn];
int pt, a[maxn];

Node *newNode(int _d, int _s, Node *_left, Node *_right) {
  ++pt;
  pool[pt].d = _d, pool[pt].s = _s, pool[pt].left = _left, pool[pt].right = _right;
  return pool + pt;
}

Node *build(int l, int r) {
  if (l == r) return newNode(0, a[l], nil, nil);
  int mid = (l + r) / 2;
```

```cpp
  Node *nl = build(l, mid), *nr = build(mid + 1, r);
  return newNode(0, nl->s + nr->s, nl, nr);
}

void init(int n) {
  pt = 0; nil = newNode(0, 0, NULL, NULL);
  root[0] = build(1, n);
}

void push(Node *node, int l, int r) {
  if (l == r) {
    node->d = 0;
  } else {
    if (node->d == 0) return;
    int mid = (l + r) / 2;
    Node *nl = newNode(node->left->d + node->d, node->left->s + node->d * int(mid -
      l + 1), node->left->left, node->left->right);
    Node *rl = newNode(node->right->d + node->d, node->right->s + node->d * int(r -
      mid), node->right->left, node->right->right);
    node->d = 0;
    node->left = nl;
    node->right = rl;
  }
}

int ask(Node *node, int l, int r, int ll, int rr) {
  push(node, l, r);
  if (l == ll && r == rr) return node->s;
  int mid = (l + r) / 2;
  if (rr <= mid) return ask(node->left, l, mid, ll, rr);
  else if (ll > mid) return ask(node->right, mid + 1, r, ll, rr);
  else return ask(node->left, l, mid, ll, mid) + ask(node->right, mid + 1, r, mid +
    1, rr);
}

Node *add(Node *node, int l, int r, int ll, int rr, int d) {
  push(node, l, r);
  if (l == ll && r == rr) return newNode(node->d + d, node->s + d * int(r - l + 1),
    node->left, node->right);
  int mid = (l + r) / 2;
  if (rr <= mid) {
    Node *nl = add(node->left, l, mid, ll, rr, d);
    return newNode(0, nl->s + node->right->s, nl, node->right);
  } else if (ll > mid) {
    Node *nr = add(node->right, mid + 1, r, ll, rr, d);
    return newNode(0, node->left->s + nr->s, node->left, nr);
  } else {
    Node *nl = add(node->left, l, mid, ll, mid, d);
    Node *nr = add(node->right, mid + 1, r, mid + 1, rr, d);
    return newNode(0, nl->s + nr->s, nl, nr);
  }
}
```

1.7 Merge-Split Treap

```cpp
struct TNODE {
  int val,rd,size;
  TNODE* left,*right,*fa;
  inline int update() {
    size = 1;
    if(left) { size += left->size; left->fa = this; }
    if(right) { size += right->size; right->fa = this; }
    fa = NULL;
    return 0;
  }
};
typedef pair<TNODE*,TNODE*> ptt;
TNODE TPool[233333];
TNODE* TPTop = TPool;

inline int real_rand() { return ((rand()&32767)<<15)^rand(); }
TNODE* newNode(int val,TNODE* left=NULL,TNODE* right=NULL) {
  TNODE* result = TPTop++;
  result->val = val; result->rd = real_rand();
  result->left = left; result->right = right; result->fa = NULL;
  result->update();
  return result;
}

TNODE* Merge(TNODE* t1,TNODE* t2) {
  if(!t1) return t2;
  if(!t2) return t1;
  if(t1->rd <= t2->rd) { t1->right = Merge(t1->right,t2); t1->update(); return t1; }
  else { t2->left = Merge(t1,t2->left); t2->update(); return t2; }
}

ptt Split(TNODE* x,int pos) {
  if(pos == 0) return ptt(NULL,x);
  if(pos == x->size) return ptt(x,NULL);

  int lsize = x->left ? x->left->size : 0;
  int rsize = x->right ? x->right->size : 0;
  if(lsize == pos) {
    TNODE* oleft = x->left;
    if(x->left) x->left->update();
    x->left = NULL;
```

```
    x->update();
    return ptt(oleft,x);
  }
  if(pos < lsize) {
    ptt st = Split(x->left,pos);
    x->left = st.second; x->update(); if(st.first) st.first->update();
    return ptt(st.first,x);
  } else {
    ptt st = Split(x->right,pos-lsize-1);
    x->right = st.first; x->update(); if(st.second) st.second->update();
    return ptt(x,st.second);
  }
}

inline int Rank(TNODE* x) {
  int ans = x->left ? x->left->size : 0;
  for(;x->fa;x = x->fa)
    if(x == x->fa->right) ans += (x->fa->left ? x->fa->left->size : 0) + 1;
  return ans;
}
```

2 String Algorithms

2.1 Common

```
// please note that all strings are indexed from 0
void kmp(const char *s, int *next)
{
  --s, --next;
  next[1] = 0;
  int j = 0, n = strlen(s + 1);
  for (int i = 2; i <= n; ++i)
  {
    while (j > 0 && s[j + 1] != s[i]) j = next[j];
    if (s[j + 1] == s[i]) j = j + 1;
    next[i] = j;
  }
}

// s: text, t: text being searched, ex[i]: maximum l satisfying s[i...i+l-1] = t
   [0...l-1]
void exkmp(const char *s, const char *t, int *next, int *ex)
{
  int n = strlen(t), m = strlen(s), k, c;
  next[0] = n;
  k = 0, c = 1;
  while (k + 1 < n && t[k] == t[k + 1]) ++k;
  next[1] = k;
  for (int i = 2; i < n; ++i)
  {
    int p = next[c] + c - 1;
    int l = next[i - c];
    if (i + l < p + 1) next[i] = l;
    else
    {
      k = max(0, p - i + 1);
      while (i + k < n && t[i + k] == t[k]) ++k;
      next[i] = k;
      c = i;
    }
  }
  k = c = 0;
  while (k < m && k < n && s[k] == t[k]) ++k;
  ex[0] = k;
  for (int i = 1; i < m; ++i)
  {
    int p = ex[c] + c - 1;
    int l = next[i - c];
    if (l + i < p + 1) ex[i] = next[i - c];
    else
    {
      k = max(0, p - i + 1);
      while (i + k < m && k < n && s[i + k] == t[k]) ++k;
      ex[i] = k;
      c = i;
    }
  }
}

// minimum representation of a string
int minimum_representation(string s)
{
  s += s;
  int l = s.length(), i = 0, j = 1, k = 0;
  while (i + k < l && j + k < l)
  {
    if (s[i + k] == s[j + k])
      ++k;
    else
    {
      if (s[j + k] > s[i + k])
        j += k + 1;
      else
        i += k + 1;
      k = 0;
```

```
      if (i == j)
        ++j;
    }
  }
  return min(i, j);
}

// l[i], the length of palindrome at the centre of i
int manacher(const char *s, int *l)
{
  int n = strlen(s);
  for (int i = 0, j = 0, k; i < n * 2; i += k, j = max(j - k, 0))
  {
    while (i >= j && i + j + 1 < n * 2 && s[(i - j) / 2] == s[(i + j + 1) / 2])
      ++j;
    l[i] = j;
    for (k = 1; i >= k && j >= k && l[i - k] != j - k; ++k)
      l[i + k] = min(l[i - k], j - k);
  }
  return *max_element(l, l + n + n);
}
```

2.2 Aho-Crosick Automaton

```
struct trie_t {
  bool flag;
  trie_t *child[C], *fail;
} trie[maxn], *root;
trie_t *new_trie() { return &trie[++pt]; }

void add(char *str) {
  int l = strlen(str);
  trie_t *p = root;
  for (int i = 0; i < l; ++i) {
    int ch = str[i]; // fixed to [0, C - 1], C = |SIGMA|
    if (!p->child[ch]) p->child[ch] = new_trie();
    p = p->child[ch];
  }
  p->flag = true;
}

void build() {
  queue<trie_t *> q;
  q.push(root);
  while (!q.empty()) {
    trie_t *p = q.front(), *t;
    q.pop();
    for (int i = 0; i < C; ++i) {
      t = p->fail;
      while (t && !t->child[i]) t = t->child[i];
      t = !t ? root : t->child[i];
      if (p->child[i]) {
        p->child[i]->fail = t;
        p->child[i]->flag |= t->flag;
        q.push(p->child[i]);
      } else p->child[i] = t;
    }
  }
}
```

2.3 Suffix Array

```
const int maxn = 100002, logn = 21, maxint = 0x7f7f7f7f;
int n, sa[maxn], r[maxn + maxn], h[maxn], mv[maxn][logn];
void initlg() {
  _lg[1] = 0;
  for (int i = 2; i < maxn; ++i)
    _lg[i] = _lg[i - 1] + ((i & (i - 1)) == 0 ? 1 : 0);
}
void da(int *r, int *sa, int n, int m) //r[n] = 0!!
{
  int i, j, p, *x = wa, *y = wb, *t;
  for(i = 0; i < m; i++) ws[i] = 0;
  for(i = 0; i < n; i++) ws[x[i] = r[i]]++;
  for(i = 1; i < m; i++) ws[i] += ws[i-1];
  for(i = n-1; i >= 0; i--) sa[--ws[x[i]]] = i;
  for(j = 1, p = 1; p < n; j *= 2, m = p)
  {
    for(p = 0, i = n - j; i < n; i++) y[p++] = i;
    for(i = 0; i < n; i++) if(sa[i] >= j) y[p++] = sa[i] - j;
    for(i = 0; i < n; i++) wv[i] = x[y[i]];
    for(i = 0; i < m; i++) ws[i] = 0;
    for(i = 0; i < n; i++) ws[wv[i]]++;
    for(i = 1; i < m; i++) ws[i] += ws[i-1];
    for(i = n - 1; i >= 0; i--) sa[--ws[wv[i]]] = y[i];
    t = x; x = y; y = t;
    p = 1;
    x[sa[0]] = 0;
    for (i = 1; i < n; i++)
      x[sa[i]] = (y[sa[i]] == y[sa[i - 1]] && y[sa[i] + j] == y[sa[i - 1] + j]) ? p
        -1 : p++;
  }
  return;
}
int height[maxn], rank[maxn];    //height[2..n]
void calheight(int *r, int *sa)
```

```
{
  for (int i = 1; i <= n; i++)
    rank[sa[i]] = i;
  int j, k = 0;
  for (int i = 0; i < n; height[rank[i++]] = k)
    for (k ? k-- : 0, j = sa[rank[i] - 1]; r[i+k] == r[j+k]; k++);
}
int askRMQ(int l, int r) {
  int len = r - l + 1, log = _lg[r - l + 1];
  return min(mv[l][log], mv[r - (1 << log) + 1][log]);
}

int LCP(int i, int j) {
  i = r[i], j = r[j];
  if (i > j) swap(i, j);
  return askRMQ(++i, j);
}
```

2.4 Suffix Automation

```
SAMNODE* Root,*Last; // take care, init them
int append_char(int ch) {
  SAMNODE* x = Last, t = SPTop++;
  t->len = x->len+1;
  for(;x && !x->child[ch];x = x->fa) x->child[ch] = t;
  if(!x) t->fa = Root;
  else {
    SAMNODE* bro = x->child[ch];
    if(x->len+1 == bro->len) t->fa = bro; // actually it's fa.
    else {
      SAMNODE* nfa = SPTop++;
      nfa[0] = bro[0];
      nfa->len = x->len+1;
      bro->fa = t->fa = nfa;

      for(;x && x->child[ch] == bro;x = x->fa) x->child[ch] = nfa;
    }
  }
  Last = t;
  return 0;
}

// SAM::Match //
SAMNODE* x = Root;
int mlen = 0;
for(int j = 0;j < len;j++) {
  int ch = Text[j];
  /*// 强制后撤一个字符，部分情况下可能有用
  if(mlen == qlen) {
    mlen--;
    while(mlen <= x->fa->len) x = x->fa;
  } */
  if(x->child[ch]) { mlen++; x = x->child[ch]; }
  else {
    while(x && !x->child[ch]) x = x->fa;
    if(!x) {
      mlen = 0;
      x = Root;
    } else {
      mlen = x->len+1;
      x = x->child[ch];
    }
  }
  Match[j] = mlen;
} // End of SAM::Match //

// 基排方便上推一些东西，比如出现次数 //
SAMNODE* order[2222222];
int lencnt[1111111];
int post_build(int len) {
  for(SAMNODE* cur = SPool;cur < SPTop;cur++) lencnt[cur->len]++;
  for(int i = 1;i <= len;i++) lencnt[i] += lencnt[i-1];
  int ndcnt = lencnt[len];
  for(SAMNODE* cur = SPTop-1;cur >= SPool;cur--) order[--lencnt[cur->len]] = cur;
  for(int i = ndcnt-1;i >= 0;i--) {
    // 此处上推
    if(order[i]->fa) order[i]->fa->cnt += order[i]->cnt;
  }
  return 0;
}
```

2.5 Palindromic Tree

所谓的 Palindrome Tree 其实是每个点表示了一个回文子串，而边则是表示在两侧同时添加上这个字母可以得到的新回文子串。从点 u 到点 w 的 suffix link 表示 w 是 u 的所有不是 u 本身的后缀中最长的回文子串。这个所谓的 “Tree” 实际上有两个根。一个表示 -1 长度的串，用于表示只有一个字母的新回文串的产生，一个表示空串。两个根的 suffix link 都指向 -1 根。有编号大的点就是拓扑序小的点这个性质。

一些应用：

1. 统计加入一个字母的时候增加了多少个新的（不同的）回文串：看看加入字母的时候多出来几个点就行了。答案只可能是 0 或 1。
2. 计算回文子串个数：注意到 Suffix Link 关系是棵树（两个根两棵树），对每个点维护它到根的连接数，然后对于新加入的点加上它的连接数即可（考虑 Suffix Link 关系的意义，显然）。

3. 计算每个不同的子回文串的出现次数：基本同上，注意到对于新加入的点它是对本身和 Suffix Link 上的所有点贡献了 1 的答案，于是上推一遍即可。

```
struct Palindromic_Tree {
  int next[maxn][N], fail[maxn], cnt[maxn], num[maxn], len[maxn];
  int S[maxn];
  int last, n, p;

  int newnode(int l) {
    for (int i = 0; i < N; ++i) next[p][i] = 0;
    cnt[p] = 0;
    num[p] = 0;
    len[p] = l;
    return p++;
  }

  void init() {
    p = 0;
    newnode(0);
    newnode(-1);
    n = last = 0;
    S[n] = -1;
    fail[0] = 1;
  }

  void add(int c) {
    c -= 'a';
    S[++n] = c;
    int cur = last;
    while (S[n - len[cur] - 1] != S[n])
      cur = fail[cur];
    if (!next[cur][c]) {
      int now = newnode(len[cur] + 2);
      int x = fail[cur];
      while (S[n - len[x] - 1] != S[n])
        x = fail[x];
      fail[now] = next[x][c];
      next[cur][c] = now;
      num[now] = num[fail[now]] + 1;
    }
    last = next[cur][c];
    cnt[last]++;
  }

  void count() {
    for (int i = p - 1; i >= 0; --i) cnt[fail[i]] += cnt[i];
  }
};
```

2.6 Cyclic LCS

```
const int maxn = 3001;
int dp[maxn][maxn], pa[maxn][maxn];

int trace(int sx, int sy, int ex, int ey) {
  int l = 0;
  while (ex != sx || ey != sy) {
    if (pa[ex][ey] == 1) --ey;
    else if (pa[ex][ey] == 2) --ex, --ey, ++l;
    else --ex;
  }
  return l;
}

void reroot(int root, int m, int n) {
  int i = root, j = 1;
  while (j <= n && pa[i][j] != 2) ++j;
  if (j > n) return;
  pa[i][j] = 1;
  while (i < 2 * m && j < n) {
    if (pa[i + 1][j] == 3) pa[++i][j] = 1;
    else if (pa[i + 1][j + 1] == 2) pa[++i][++j] = 1;
    else ++j;
  }
  while (i < 2 * m && pa[i + 1][j] == 3) pa[++i][j] = 1;
}

void lcs(char *a, char *b) {
  int m = strlen(a + 1), n = strlen(b + 1);
  for (int i = 0; i <= m; ++i) {
    for (int j = 0; j <= n; ++j) {
      if (i != 0 || j != 0) dp[i][j] = -1;
      if (j >= 1 && dp[i][j] < dp[i][j - 1]) dp[i][j] = dp[i][j - 1], pa[i][j] = 1;
      if (i >= 1 && j >= 1 && dp[i][j] < dp[i - 1][j - 1] + 1 && a[i] == b[j]) dp[i
        ][j] = dp[i - 1][j - 1] + 1, pa[i][j] = 2;
      if (i >= 1 && dp[i][j] < dp[i - 1][j]) dp[i][j] = dp[i - 1][j], pa[i][j] = 3;
    }
  }
}

int clcs(char *a, char *b) {
  int m = strlen(a + 1), n = strlen(b + 1), ans = 0;
  for (int i = m + 1; i <= m + m; ++i) a[i] = a[i - m];
  a[m + m + 1] = 0;
  lcs(a, b);
  ans = trace(0, 0, m, n);
  for (int i = 1; i < m; ++i) {
    reroot(i, m, n);
```

```
    ans = max(ans, trace(i, 0, m + i, n));
  }
  a[m + 1] = 0;
  return ans;
}
```

3 Math

3.1 Matrix Multiplication

```
struct matrix_t {
  int x[N + 1][N + 1];
  matrix_t(int v) {
    memset(x, 0, sizeof(x));
    for (int i = 1; i <= N; ++i) x[i][i] = v;
  }
  matrix_t operator*(const matrix_t &r) {
    matrix_t p = 0;
    for (int k = 1; k <= N; ++k) {
      for (int i = 1; i <= N; ++i) {
        if (x[i][k] == 0) continue;
        for (int j = 1; j <= N; ++j) {
          p.x[i][j] += x[i][k] * r.x[k][j];
          p.x[i][j] %= MOD;
        }
      }
    }
    return p;
  }
  matrix_t power(LL p) {
    matrix_t r = 1, a = *this;
    for (; p; p >>= 1) {
      if (p & 1) r = r * a;
      a = a * a;
    }
    return r;
  }
};
```

Optimization of recursion matrix:

$h_n = a_1 h_{n-1} + a_2 h_{n-2} + a_3 h_{n-3} + \ldots + a_k h_{n-k}$, Construct matrix of $k * k$:

$$\mathbf{M} = \begin{bmatrix} a_1 & a_2 & a_3 & \cdots & a_{k-2} & a_{k-1} & a_k \\ 1 & 0 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 1 & 0 & \cdots & 0 & 0 & 0 \\ 0 & 0 & 1 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 1 & 0 & 0 \\ 0 & 0 & 0 & \cdots & 0 & 1 & 0 \end{bmatrix}$$

Then the characteristic polynomial of $\mathbf{M}$ is

$$f(\lambda) = |\lambda\mathbf{E} - \mathbf{M}| = \begin{bmatrix} \lambda - a_1 & -a_2 & -a_3 & \cdots & -a_{k-2} & -a_{k-1} & -a_k \\ -1 & \lambda & 0 & \cdots & 0 & 0 & 0 \\ 0 & -1 & \lambda & \cdots & 0 & 0 & 0 \\ 0 & 0 & -1 & \cdots & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & -1 & \lambda & 0 \\ 0 & 0 & 0 & \cdots & 0 & -1 & \lambda \end{bmatrix}$$
$$= \lambda^k - a_1\lambda^{k-1} - a_2\lambda^{k-2} - \ldots - a_k.$$

Apply Hamilton-Cayley theorem, we have $f(\mathbf{M}) = \mathbf{0}$.
And, $\forall i$, $\mathbf{M}^i$ can be written as a linear combination of $\mathbf{E}$,$\mathbf{M}$,$\mathbf{M}^2$,$\ldots$,$\mathbf{M}^{k-1}$.
So the matrix multiplication is reduced to polynomial multiplication, which can be computed in $O(n^2)$.

3.2 Gauss Elimiation

```
void gauss(int n, double g[maxn][maxn]) { // input: N * (N + 1) Matrix
  for (int i = 1; i <= n; ++i) {
    double temp = 0;
    int pos = -1;
    for (int j = i; j <= n; ++j) {
      if (fabs(g[j][i]) > temp) temp = fabs(g[j][i]), pos = j;
    }
    if (pos == -1) continue;
    for (int k = 1; k <= n + 1; ++k) swap(g[pos][k], g[i][k]);
    temp = g[i][i];
    for (int k = 1; k <= n + 1; ++k) g[i][k] /= temp;
    for (int j = i + 1; j <= n; ++j) {
      temp = g[j][i];
      for (int k = 1; k <= n + 1; ++k) g[j][k] -= temp * g[i][k];
    }
  }
  for (int i = n; i >= 1; --i) {
    for (int j = 1; j < i; ++j) {
```

```
      g[j][n + 1] -= g[i][n + 1] * g[j][i];
      g[j][i] = 0;
    }
  }
}
// n is the number of variables, t is the number of equations
// index from 1
// return the number of free variables
int gauss()
{
  int pos;
  int i = 1, j = 1;
  while (i <= t && j <= n)
  {
    pos = i;
    for (int k = i; k <= t; k++)
      if (a[k][j] != 0)
      {
        pos = k;
        break;
      }
    if (a[pos][j] > 0)
    {
      if (pos != i)
        for (int k = 1; k <= n; k++)
          swap(a[i][k], a[pos][k]);
      for (int p = i+1; p <= t; p++)
        if (a[p][j] > 0)
        {
          for (int k = j; k <= n; k++)
            a[p][k] ^= a[i][k];
        }
      i++;
    }
    j++;
  }
  return n - i + 1;
}
```

3.3 Linear Dependency

求线性无关方程组，本质是个消元，不过按照常用的形式进行了压位（这里是 31 位）。可以顺便维护出一组基。

```
for(int i = 0;i < n;i++) {
  for(int j = 31;j >= 0;j--) {
    if(xx[i] & (1LL<<j)) {
      if(!ind[j]) { ind[j] = xx[i]; break; }
      else xx[i] ^= ind[j];
    }
  }
}
```

3.4 Determinant

```
LL determinant() {
  LL result = 1;
  for (int i = 1; i <= n; ++i) {
    for (int j = i + 1; j <= n; ++j) {
      while (det[j][i]) {
        LL ratio = det[i][i] / det[j][i];
        for (int k = i; k <= n; ++k) {
          det[i][k] -= ratio * det[j][k];
          swap(det[i][k], det[j][k]);
        }
        result = -result;
      }
    }
    result = result * det[i][i];
  }
  return result;
}
```

Laplacian matrix $L = (\ell_{i,j})_{n*n}$ is defined as: $L = D - A$, that is, it is the difference of the degree matrix D and the adjacency matrix A of the graph.
From the definition it follows that:

$$\ell_{i,j} = \begin{cases} deg(v_i) & \text{if } i = j \\ -1 & \text{if } i \neq j \text{ and } v_i \text{ is adjacent to } v_j \\ 0 & \text{otherwise} \end{cases}$$

Then the number of spanning trees of a graph on n vertices is the determinant of any $n-1$ submatrix of L.

3.5 Polynomial Root

```
double cal(const vector<double> &coef, double x) {
  double e = 1, s = 0;
  for (int i = 0; i < coef.size(); ++i) s += coef[i] * e, e *= x;
  return s;
}

double find(const vector<double> &coef, double l, double r) {
  int sl = dblcmp(cal(coef, l)), sr = dblcmp(cal(coef, r));
  if (sl == 0) return l;
```

```
  if (sr == 0) return r;
  if (sl * sr > 0) return maxdbl;
  for (int tt = 0; tt < 100 && r - l > eps; ++tt) {
    double mid = (l + r) / 2;
    int smid = dblcmp(cal(coef, mid));
    if (smid == 0) return mid;
    if (sl * smid < 0) r = mid;
    else l = mid;
  }
  return (l + r) / 2;
}

vector<double> solve(vector<double> coef, int n) {
  vector<double> ret; // c[0]+c[1]*x+c[2]*x^2+...+c[n]*x^n
  if (n == 1) {
    if (dblcmp(coef[1]) != 0) ret.push_back(-coef[0] / coef[1]);
    return ret;
  }
  vector<double> dcoef(n);
  for (int i = 0; i < n; ++i) dcoef[i] = coef[i + 1] * (i + 1);
  vector<double> droot = solve(dcoef, n - 1);
  droot.insert(droot.begin(), -maxdbl);
  droot.push_back(maxdbl);
  for (int i = 0; i + 1 < droot.size(); ++i) {
    double tmp = find(coef, droot[i], droot[i + 1]);
    if (tmp < maxdbl) ret.push_back(tmp);
  }
  return ret;
}
```

3.6 Number Theory Library

```
LL mult64(LL a, LL b, LL m) { // 64bit multiply 64bit
  a %= m, b %= m;
  LL ret = 0;
  for (; b; b >>= 1) {
    if (b & 1) ret = (ret + a) % m;
    a = (a + a) % m;
  }
  return ret;
}
/* return x*y%mod. no overflow if x,y < mod
 * remove 'i' in "idiv"/"imul" -> unsigned */
inline long mulmod(long x,long y,long mod)
{
  long ans = 0;
  __asm__ (
    "movq %1,%%rax\n imulq %2\n idivq %3\n"
    :"=d"(ans):"m"(x),"m"(y),"m"(mod):"%rax"
  );
  return ans;
}

LL fpow(LL a, LL p, int mod) { // fast power-modulo algorithm
  LL res = 1;
  for (; p; p >>= 1) {
    if (p & 1) res = (res * a) % mod; // using mult64 when mod is 64-bit
    a = (a * a) % mod;
  }
  return res;
}

int exgcd(int x, int y, int &a, int &b) { // extended gcd, ax + by = g.
  int a0 = 1, a1 = 0, b0 = 0, b1 = 1;
  while (y != 0) {
    a0 -= x / y * a1; swap(a0, a1);
    b0 -= x / y * b1; swap(b0, b1);
    x %= y; swap(x, y);
  }
  if (x < 0) a0 = -a0, b0 = -b0, x = -x;
  a = a0, b = b0;
  return x;
}

int inverse(int x, int mod) { // multiplicative inverse.
  int a = 0, b = 0;
  if (exgcd(x, mod, a, b) != 1) return -1;
  return (a % mod + mod) % mod; // C1: x & mod are co-prime
  return fpow(x, mod - 2, mod); // C2: mod is prime
}

void init_inverse(int mod) { // O(n), all multiplicative inverse, mod is prime
  inv[0] = inv[1] = 1;
  for (int i = 2; i < n; ++i) {
    inv[i] = (LL)inv[mod % i] * (mod - mod / i) % mod; // overflows?
  }
}

LL CRT(int cnt, int *p, int *b) { // chinese remainder theorem
  LL N = 1, ans = 0;
  for (int i = 0; i < k; ++i) N *= p[i];
  for (int i = 0; i < k; ++i) {
    LL mult = (inverse(N / p[i], p[i]) * (N / p[i])) % N;
    mult = (mult * b[i]) % N;
    ans += mult; ans %= N;
  }
```

```
  if (ans < 0) ans += N;
  return ans;
}

void sieve(int n) { // generating primes using euler's sieve
  notP[1] = 1;
  for (int i = 2; i <= n; ++i) {
    if (!notP[i]) P[++Pt] = i;
    for (int j = 1; j <= Pt && P[j] * i <= n; ++j) {
      notP[P[j] * i] = 1;
      if (i % P[j] == 0) break;
    }
  }
}
void sieve(int n)
{
  memset(isP,0,sizeof(isP));
  mu[1] = 1;
  phi[1] = 0;
  for (int i = 2; i <= n; i++)
  {
     if (isP[i] == 0)
     {
       isP[i] = 1;
       mu[i] = -1;
       phi[i] = i-1;
       prime[np++] = i;
     }
     for (int j = 0; j < np && i * prime[j]<=n ; j++)
       if (i % prime[j])
       {
         int k = i * prime[j];
         isP[k] = -1;
         mu[k] = -mu[i];
         phi[k] = phi[i] * (prime[j]-1);
       }
       else
       {
         int k = i * prime[j];
         isP[k] = -1;
         mu[k] = 0;
         phi[k] = phi[i] * prime[j];
         break;
       }
     summu[i] = summu[i-1] + mu[i];
     sumphi[i] = sumphi[i-1] + phi[i];
  }
}

int p[1000010], prime[100010], psize = 1000000;
LL a[1000100];
void sieve(){
  int i,j,tot,t1;
  for (i=1;i<=psize;i++) p[i]=i;
  for (i=2,tot=0;i<=psize;i++){
    if (p[i]==i) prime[++tot]=i;
    for (j=1;j<=tot && (t1=prime[j]*i)<=psize;j++){
      p[t1]=prime[j];
      if (i%prime[j]==0) break;
    }
  }
}
inline LL mul(LL a, LL b, LL p)
{
  if (p <= 1000000000)
    return a * b % p;
  else
    if (p<=1000000000000LL)
      return (((a * (b >> 20) % p) << 20) + (a * (b & ((1 << 20) - 1)))) % p;
    else
    {
      LL d = (LL)floor(a * (long double)b / p + 0.5);
      LL ret = (a * b - d * p) % p;
      if (ret < 0) ret += p;
      return ret;
    }
}
LL fpow(LL a,LL n,LL p)
{
  LL ans=1;
  for (; n; n >>= 1)
  {
    if (n & 1) ans = mul(ans, a, p);
    a = mul(a, a, p);
  }
  return ans;
}
bool witness(LL a, LL n)  //二次探查
{
  int t = 0;
  LL u = n - 1;
  for (; ~u & 1; u >>= 1) t++;
  LL x = fpow(a, u, n), _x = 0;
  for (; t; t--)
  {
    _x = mul(x, x, n);
```

```
    if (_x == 1 && x != 1 && x != n-1) return 1;
    x = _x;
  }
  return _x != 1;
}
bool miller(LL n)
{
  if (n < 2) return 0;
  if (n < psize) return p[n] == n;
  if (~n & 1) return 0;
  for (int j = 0; j <= 7; j++)
    if (witness(rand() % (n - 1) + 1, n))
      return 0;
  return 1;
}
LL gcd(LL a,LL b)
{
  LL ret = 1;
  while (a != 0)
  {
    if ((~a & 1) && (~b & 1))
      ret <<= 1,a >>= 1,b >>= 1;
    else
      if (~a & 1)
        a >>= 1;
      else
        if (~b & 1)
          b >>= 1;
        else
        {
          if (a < b)
            swap(a, b);
          a -= b;
        }
  }
  return ret * b;
}
LL rho(LL n)
{
  for (;;)
  {
    LL X = rand() % n, Y, Z, T = 1, *lY = a, *lX = lY;
    int tmp = 20;
    LL C = rand() % 10 + 3;
    X = mul(X, X, n) + C;
    *(lY++) = X; lX++;
    Y = mul(X, X, n) + C;
    *(lY++) = Y;
    for(; X != Y;)
    {
      LL t = X - Y + n;
      Z = mul(T, t, n);
      if(Z == 0)
        return gcd(T, n);
      tmp--;
      if (tmp == 0)
      {
        tmp = 20;
        Z = gcd(Z, n);
        if (Z != 1 && Z != n)
          return Z;
      }
      T = Z;
      Y = *(lY++) = mul(Y, Y, n) + C;
      Y = *(lY++) = mul(Y, Y, n) + C;
      X = *(lX++);
    }
  }
}
void find(LL n, int c)
{
  for (int i = 0; i < ct; i++)
    if (n % fac[i] == 0)
      n /= fac[i], fac[ct++] = fac[i];
    if(n == 1) return;
  if (n <= psize)
  {
    for (; n != 1; n /= p[n])
      fac[ct++] = p[n];
    return;
  }
    if(miller(n))
    {
        fac[ct++] = n;
        return ;
    }
    LL p = n;
    LL k = c;
    while(p >= n) p = rho(p);
    find(p, k);
    find(n / p, k);
}
void factorize(LL n, vector<pair<LL, LL> > &result)
{
  result.clear();
  if (n == 1)
```

```
    return;
  ct = 0;
  find(n, 120);
  sort(fac, fac + ct);
  num[0] = 1;
  int k = 1;
  for(int i=1; i<ct; i++)
  {
    if(fac[i] == fac[i-1])
      ++num[k-1];
    else
    {
      num[k] = 1;
      fac[k++] = fac[i];
    }
  }
  cnt = k;
  for (int i = 0; i < cnt; i++)
    result.push_back(make_pair(fac[i], num[i]));
}

// discrete-logarithm, finding y for equation b = g^y % p
//p is prime
int M;  //M = (int)sqrt(phi(p));
void discrete_log_init(LL g, LL p)
{
  hash_init();
  int i;
  LL tmp;
  for(i = 0, tmp = 1; i < M; i++, tmp = tmp * g % p)
    insert(tmp % p, i * 1LL);
}
LL discrete_log(LL g, LL p, LL b)
{
  LL res, am = fpow(g, M, p), inv = fpow(b, p - 2, p), x = 1;
  for(LL i = M; ; i += M)
  {
    if((res = find((x = x * am % p) * inv % p)) != -1)
    {
      return i - res;
    }
    if(i > p)break;
  }
  return -1;
}

//A^x=B mod C
//hash add(); find();
int Inval(int a,int b,int n){
  int x,y,e;
  ext_gcd(a, n, x, y);
  e=(LL)x * b % n;
  return e < 0 ? e + n : e;
}
int BabyStep(int A, int B, int C)
{
  top = maxn; ++ idx;
  LL buf = 1 % C, D = buf, K;
  int i, d = 0, tmp;
  for(i = 0; i <= 100; buf = buf * A % C, ++i)
    if (buf == B)
      return i;
  while((tmp = gcd(A, C)) != 1)
  {
    if(B % tmp) return -1;
    ++d;
    C /= tmp;
    B /= tmp;
    D = D * A / tmp % C;
  }
  int M = (int)ceil(sqrt((double)C));
  for(buf = 1 % C, i = 0; i <= M; buf = buf * A % C, ++i)
    add(i, buf); //hash
  for(i = 0, K = fpow((LL)A, M, C); i <= M; D = D * K % C, ++i)
  {
    tmp = Inval((int)D, B, C);
    int w;
    if(tmp >= 0 && (w = find(tmp)) != -1)  //hash
      return i * M + w + d;
  }
  return -1;
}

// primtive root, finding the number with order p-1
int primtive_root(int p) {
  vector<int> factor;
  int tmp = p - 1;
  for (int i = 2; i * i <= tmp; ++i) {
    if (tmp % i == 0) {
      factor.push_back(i);
      while (tmp % i == 0) tmp /= i;
    }
  }
  if (tmp != 1) factor.push_back(tmp);
  for (int root = 1; ; ++root) {
    bool flag = true;
```

```
    for (int i = 0; i < factor.size(); ++i) {
      if (fpow(root, (p - 1) / factor[i], p) == 1) {
        flag = false;
        break;
      }
    }
    if (flag) return root;
  }
}
```

3.7 Number Partition

```
// number of ways to divide n to integers(unordered), O(n^(3/2))
int partition(int n) {
  int dp[n + 1];
  dp[0] = 1;
  for (int i = 1; i <= n; i++) {
    dp[i] = 0;
    for (int j = 1, r = 1; i - (3 * j * j - j) / 2 >= 0; ++j, r *= -1) {
      dp[i] += dp[i - (3 * j * j - j) / 2] * r;
      if (i - (3 * j * j + j) / 2 >= 0) dp[i] += dp[i - (3 * j * j + j) / 2] * r;
    }
  }
  return dp[n];
}
```

3.8 Lucas

```
LL C(LL n, LL m)
{
  if (m > n) return 0;
  LL ans = 1;
  for (int i = 1; i <= m; i++)
  {
    LL a = (n + i - m) % p;
    LL b = i % p;
    ans = ans * (a * fpow(b, p-2, p) % p) % p;
  }
  return ans;
}
LL lucas(LL n, LL m)
{
  if (m == 0) return 1;
  return C(n % p, m % p) * lucas(n / p, m / p) % p;
}
```

3.9 Bonulli Number

```
//O(n^2)
LL fac[maxn], C[maxn][maxn], B[maxn], Inv[maxn], n, k;
void init()
{
  for (int i = 0; i < maxn; i++)
  {
    C[i][0] = C[i][i] = 1;
    if (i == 0) continue;
    for (int j = 1; j < i; j++)
      C[i][j] = (C[i-1][j] + C[i-1][j-1]) % Mod;
  }
  Inv[1] = 1;
  for (int i = 2; i < maxn; i++)
    Inv[i] = (Mod - Mod / i) * Inv[Mod % i] % Mod;
  B[0] = 1;
  for (int i = 1; i < maxn; i++)
  {
    LL ans = 0;
    if (i == maxn - 1)
      break;
    for (int j = 0; j < i; j++)
    {
      ans += B[j]*C[i+1][j];
      ans %= Mod;
    }
    ans *= -Inv[i+1];
    ans = (ans % Mod + Mod) % Mod;
    B[i] = ans;
  }
}
LL Cal(int n, int k)
{
  LL ans = Inv[k+1];
  LL sum = 0;
  for (int i = 1; i <= k+1; i++)
  {
    sum += C[k+1][i]*fac[i] % Mod * B[k+1-i] % Mod;
      sum %= Mod;
  }
  ans *= sum;
  ans %= Mod;
  return ans;
}
```

$\sum_{i=1}^{n} i^k$

3.10 Fast Walsh Transform

```
//n is power of 2
void FWT_And(int x[], int l, int r, int v) //FWT v = 1, DFWT v = -1
{
  if (l == r)
    return;
  int mid = (l + r) >> 1;
  FWT_And(x, l, mid, v);
  FWT_And(x, mid + 1, r, v);
  for (int i = 0; i <= mid - l; i++)
    x[i + l] += x[mid + i + 1] * v;
}
void FWT_Or(int x[], int l, int r, int v) // FWT v = 1 DFWT v = -1
{
  if (l == r)
    return;
  int mid = (l + r) >> 1;
  FWT_Or(x, l, mid, v);
  FWT_Or(x, mid + 1, r, v);
  for (int i = 0; i <= mid - l; i++)
    x[mid + i + 1] += x[l + i] * v;
}
void FWT_Xor(int x[], int l, int r)
{
  if (l == r)
    return;
  int mid = (l + r) >> 1;
  FWT_Xor(x, l, mid);
  FWT_Xor(x, mid + 1, r);
  for (int i = 0; i <= mid - l; i++)
    x[l + i] +=  x[mid + i + 1], x[mid + i + 1] = x[l + i] - 2 * x[mid + i + 1];
}
void DFWT_Xor(int x[], int l, int r)
{
  if (l == r)
    return;
  int mid = (l + r) >> 1;
  DFWT_Xor(x, l, mid);
  DFWT_Xor(x, mid + 1, r);
  for (int i = 0; i <= mid - l; i++)
    x[l + i] = (x[l + i] + x[mid + i + 1]) / 2, x[mid + i + 1] = x[l + i] - x[mid +
      i + 1];
}
```

3.11 Fast Fourier Transform

```
void fft(int sign, int n, double *real, double *imag) {
  double theta = sign * 2 * pi / n;
  for (int m = n; m >= 2; m >>= 1, theta *= 2) {
    double wr = 1, wi = 0, c = cos(theta), s = sin(theta);
    for (int i = 0, mh = m >> 1; i < mh; ++i) {
      for (int j = i; j < n; j += m) {
        int k = j + mh;
        double xr = real[j] - real[k], xi = imag[j] - imag[k];
        real[j] += real[k], imag[j] += imag[k];
        real[k] = wr * xr - wi * xi, imag[k] = wr * xi + wi * xr;
      }
      double _wr = wr * c - wi * s, _wi = wr * s + wi * c;
      wr = _wr, wi = _wi;
    }
  }
  for (int i = 1, j = 0; i < n; ++i) {
    for (int k = n >> 1; k > (j ^= k); k >>= 1);
    if (j < i) swap(real[i], real[j]), swap(imag[i], imag[j]);
  }
}
// Compute Poly(a)*Poly(b), write to r; Indexed from 0
int mult(int *a, int n, int *b, int m, int *r) {
  static double ra[maxn], rb[maxn], ia[maxn], ib[maxn];
  int fn = 1;
  while (fn < n + m) fn <<= 1; // n + m: interested length
  for (int i = 0; i < n; ++i) ra[i] = a[i], ia[i] = 0;
  for (int i = n; i < fn; ++i) ra[i] = ia[i] = 0;
  for (int i = 0; i < m; ++i) rb[i] = b[i], ib[i] = 0;
  for (int i = m; i < fn; ++i) rb[i] = ib[i] = 0;
  fft(1, fn, ra, ia);
  fft(1, fn, rb, ib);
  for (int i = 0; i < fn; ++i) {
    double real = ra[i] * rb[i] - ia[i] * ib[i];
    double imag = ra[i] * ib[i] + rb[i] * ia[i];
    ra[i] = real, ia[i] = imag;
  }
  fft(-1, fn, ra, ia);
  for (int i = 0; i < fn; ++i) r[i] = (int)floor(ra[i] / fn + 0.5);
  return fn;
}
```

3.12 Number Theoretic Transform

```
int n, K, inv_K;
int P = 1998585857, g = 3;
int w[2][100000];
int fpm(int a, int b)
{
  int ret = 1;
```

```
  for (; b; b >>= 1)
  {
    if (b & 1)
      ret = (LL)ret * a % P;
    a = (LL)a * a % P;
  }
  return ret;
}
void FFT_Init(int K)
{
  w[ 0 ][ 0 ] = w[ 0 ][ K ] = w[ 1 ][ 0 ] = w[ 1 ][ K ] = 1;
  int G = fpm( g, ( P - 1 ) / K );
  FOR( i, 1, K - 1 ) {
    w[ 0 ][ i ] = (ll)w[ 0 ][ i - 1 ] * G % P;
  }
  FOR( i, 0, K ) {
    w[ 1 ][ i ] = w[ 0 ][ K - i ];
  }
  inv_K = fpm(K, P - 2);
}
void FFT( int X[], int k, int v ) {
  int i, j, l;
  for ( i = j = 0; i < k; i++ ) {
    if ( i > j ) swap( X[ i ], X[ j ] );
    for ( l = k >> 1; ( j ^= l ) < l; l >>= 1 );
  }
  for ( i = 2; i <= k; i <<= 1 )
    for ( j = 0; j < k; j += i )
      for ( l = 0; l < i >> 1; l++ ) {
        int t = (ll)X[ j + l + ( i >> 1 ) ] * w[ v ][ ( k / i ) * l ] % P;
        X[ j + l + ( i >> 1 ) ] = ( (ll)X[ j + l ] - t + P ) % P;
        X[ j + l ] = ( (ll)X[ j + l ] + t ) % P;
      }
  if (v)
    for (i = 0; i < k; i++)
      X[i] = (ll)X[i] * inv_K % P;
}
int tmp[100000];
int invB[10000];
void GetInv( int A[], int A0[], int t ) {
  if ( t == 1 ) { A0[ 0 ] = fpm( A[ 0 ], P - 2); return; }
  GetInv( A, A0, ( t + 1 ) >> 1 );
  K = 1;
  for ( ; K <= ( t << 1 ) + 3; K <<= 1 );
  FFT_Init(K);
  FOR ( i, 0, t - 1 ) { tmp[ i ] = A[ i ]; } FOR ( i, t, K - 1 ) { tmp[ i ] = 0; }
  FFT( tmp, K, 0 ); FFT( A0, K, 0 );
  FOR ( i, 0, K - 1 ) { tmp[ i ] = 2 - (ll)tmp[ i ] * A0[ i ] % P + P; tmp[i] %= P;
  }
  FOR ( i, 0, K - 1 ) { A0[ i ] = (ll)A0[ i ] * tmp[ i ] % P; }
  FFT( A0, K, 1 );
  FOR ( i, t, K - 1 ) { A0[ i ] = 0; }
}
void Division(int A[], int B[], int D[], int R[], int n, int m)
{
  int K;
  for (K = 1; K < 2 * n; K <<= 1);
  For(i, 0, n - m)
    D[i] = A[n - i];
  For(i, n - m + 1, K - 1)
    D[i] = 0;
  For(i, 0, m / 2)
    swap(B[i], B[m - i]);
  GetInv(B, invB, n - m + 1);
  For(i, 0, m / 2)
    swap(B[i], B[m - i]);
  FFT_Init(K);
  FFT(D, K, 0);
  FFT(invB, K, 0);
  For(i, 0, K - 1)
    D[i] = (LL)D[i] * invB[i] % P;
  FFT(D, K, 1);
  For(i, n - m + 1, K - 1)
    D[i] = 0;
  For(i, 0, (n - m) / 2)
    swap(D[i], D[n - m - i]);
  For(i, 0, n - m)
    tmp[i] = D[i];
  For(i, n - m + 1, K - 1)
    tmp[i] = 0;
  FFT(tmp, K, 0);
  FFT(B, K, 0);
  For(i, 0, K - 1)
    tmp[i] = (LL)tmp[i] * B[i] % P;
  FFT(tmp, K, 1);
  For(i, m, K - 1)
    tmp[i] = 0;
  For(i, 0, m - 1)
    R[i] = (A[i] - tmp[i] + P) % P;
    For(i, m, K - 1)
    R[i] = 0;
  FFT(B, K, 1);
}
int fac[100010], inv_fac[100010], B[100010];
void GetBernoulli(int n)
{
```

```
  fac[0] = inv_fac[0] = 1;
  For(i, 1, n - 1)
    fac[i] = (ll)fac[i - 1] * i % P;
  For(i, 1, n)
    inv_fac[i] = (ll)inv_fac[i - 1] * fpm(i + 1, P - 2) % P;
  GetInv(inv_fac, B, n);
  rep(i, n)
    B[i] = (ll)B[i] * fac[i] % P;
  rep(i, n)
    cout << B[i] << endl;
}


//CRT version
const int P = 1000003; // Approximate 10^6
const int P1 = 998244353, P2 = 995622913;
const LL M1 = 397550359381069386LL, M2 = 596324591238590904LL;
const LL MM = 993874950619660289LL;

int CRT(int x1, int x2) {
  return (mult(M1, x1, MM) + mult(M2, x2, MM)) % MM % P; // 64bit multiplication
}

void NTT(int *A, int PM, int PW, int n) {
  for (int m = n, h; h = m / 2, m >= 2; PW = (LL)PW * PW % PM, m = h) {
    for (int i = 0, w = 1; i < h; ++i, w = (LL)w * PW % PM) {
      for (int j = i; j < n; j += m) {
        int k = j + h, x = (A[j] - A[k] + PM) % PM;
        A[j] += A[k]; A[j] %= PM;
        A[k] = (LL)w * x % PM;
      }
    }
  }
  for (int i = 0, j = 1; j < n - 1; ++j) {
    for (int k = n / 2; k > (i ^= k); k /= 2);
    if (j < i) swap(A[i], A[j]);
  }
}

int E1, E2, F1, F2, I1, I2;
int init(int n) { // assert(k <= 19);
  int k = 1, N = 2, p;
  while (N < n) N <<= 1, ++k;
  p = 7 * 17; for (int i = 1; i <= 23 - k; ++i) p *= 2;
  E1 = fpow(3, p, P1); F1 = fpow(E1, P1 - 2, P1); I1 = fpow(N, P1 - 2, P1);
  p = 9 * 211; for (int i = 1; i <= 19 - k; ++i) p *= 2;
  E2 = fpow(5, p, P2); F2 = fpow(E2, P2 - 2, P2); I2 = fpow(N, P2 - 2, P2);
  return N;
}

void mul(int *A, int *B, int *C, int n) {
  static int A1[maxn], B1[maxn], C1[maxn];
  int N = init(n);
  memset(A1, 0, sizeof(*A1) * N); memset(B1, 0, sizeof(*B1) * N); memset(C1, 0,
    sizeof(*C1) * N);
  memset(C, 0, sizeof(*C) * N);
  memcpy(A1, A, sizeof(*A) * n); memcpy(B1, B, sizeof(*B) * n);
  NTT(A1, P1, E1, N); NTT(B1, P1, E1, N);
  for (int i = 0; i < N; ++i) C1[i] = (LL)A1[i] * B1[i] % P1;
  NTT(C1, P1, F1, N);
  for (int i = 0; i < N; ++i) C1[i] = (LL)C1[i] * I1 % P1;
  NTT(A, P2, E2, N); NTT(B, P2, E2, N);
  for (int i = 0; i < N; ++i) C[i] = (LL)A[i] * B[i] % P2;
  NTT(C, P2, F2, N);
  for (int i = 0; i < N; ++i) C[i] = (LL)C[i] * I2 % P2;
  for (int i = 0; i < N; ++i) C[i] = CRT(C1[i], C[i]);
  for (int i = n; i < N; ++i) C[i] = 0;
}
```

3.13 Modular Factorial

$n!$ mod mod where $mod = p^k$. $O(p \log n)$

```
LL get(int n, int mod, int p) {
  LL ans = 1;
  for (int i = 1; i <= n; ++i) if (i % p != 0) {
    ans = ans * i % mod;
  }
  return ans;
}
pii solve(LL n, int mod, int p) {
  LL init = get(mod, mod, p);
  pii ans = pii(1, 0);
  for (LL now = p; now <= n; now *= p) {
    ans.second += n / now;
    if (now > n / p) break;
  }
  while (n > 0) {
    ans.first = (LL) ans.first * fpow(init, n / mod, mod) % mod;
    ans.first = ans.first * get(n % mod, mod, p) % mod;
    n /= p;
  }
  return ans;
}
```

3.14 Linar Programming

```
double a[maxn][maxm], b[maxn], c[maxm], d[maxn][maxm];
int ix[maxn + maxm]; // !!! array all indexed from 0
// max{cx|Ax<=b,x>=0}, n: constraints, m: vars
double simplex(double a[maxn][maxm], double b[maxn], double c[maxm], int n, int m) {
  ++m;
  int r = n, s = m - 1;
  memset(d, 0, sizeof(d));
  for (int i = 0; i < n + m; ++i) ix[i] = i;
  for (int i = 0; i < n; ++i) {
    for (int j = 0; j < m - 1; ++j) d[i][j] = -a[i][j];
    d[i][m - 1] = 1;
    d[i][m] = b[i];
    if (d[r][m] > d[i][m]) r = i;
  }
  for (int j = 0; j < m - 1; ++j) d[n][j] = c[j];
  d[n + 1][m - 1] = -1;
  for (double dd;; ) {
    if (r < n) {
      int t = ix[s]; ix[s] = ix[r + m]; ix[r + m] = t;
      d[r][s] = 1.0 / d[r][s];
      for (int j = 0; j <= m; ++j) if (j != s) d[r][j] *= -d[r][s];
      for (int i = 0; i <= n + 1; ++i) if (i != r) {
        for (int j = 0; j <= m; ++j) if (j != s) d[i][j] += d[r][j] * d[i][s];
        d[i][s] *= d[r][s];
      }
    }
    r = -1; s = -1;
    for (int j = 0; j < m; ++j) if (s < 0 || ix[s] > ix[j]) {
      if (d[n + 1][j] > eps || (d[n + 1][j] > -eps && d[n][j] > eps)) s = j;
    }
    if (s < 0) break;
    for (int i = 0; i < n; ++i) if (d[i][s] < -eps) {
      if (r < 0 || (dd = d[r][m] / d[r][s] - d[i][m] / d[i][s]) < -eps || (dd < eps && ix[r + m] > ix[i + m])) r = i;
    }
    if (r < 0) return -1; // not bounded
  }
  if (d[n + 1][m] < -eps) return -1; // not executable
  double ans = 0;
  for (int i = m; i < n + m; ++i) { // the missing enumerated x[i] = 0.  x[i] = c[ix[i]]
    if (ix[i] < m - 1) ans += d[i - m][m] * c[ix[i]];
  }
  return ans;
}
```

3.15 Simpson Integration

```
const double eps = 1e-15;
double f(double x) { return 0.0; }
double sim(double l, double r, double lv, double rv, double mv) {
  return (r - l) * (lv + rv + 4 * mv) / 6;
}
double rsim(double l, double r, double lv, double rv, double mv, double m1v, double m2v) {
  double mid = (l + r) / 2;
  if (fabs(sim(l, r, lv, rv, mv) - sim(l, mid, lv, mv, m1v) - sim(mid, r, mv, rv, m2v)) / 15 < eps) {
    return sim(l, r, lv, rv, mv);
  } else {
    double mid = (l + r) / 2, m1 = (l + (l + r) / 2) / 2, m2 = ((l + r) / 2 + r) / 2;
    return rsim(l, mid, lv, mv, m1v, f((l + m1) / 2), f((m1 + mid) / 2)) + rsim(mid, r, mv, rv, m2v, f((mid + m2) / 2), f((m2 + r) / 2));
  }
}
double simpson(double l, double r) {
  double mid = (l + r) / 2;
  return rsim(l, r, f(l), f(r), f(mid), f((l + mid) / 2), f((mid + r) / 2));
}
```

4 Computational Geometry

4.1 Common 2D

```
// implementation of (dblcmp,dist,cross,dot) is trivial
const double eps = 1e-8;
int dblcmp(double x)
{
  if (fabs(x) < eps)
    return 0;
  return x > 0 ? 1 : -1;
}
struct point_t
{
  double x, y;
  point_t(): x(0), y(0) {}
  point_t(double x, double y): x(x), y(y) {}
  bool operator <(const point_t &b) const
  {
    return dblcmp(x - b.x) < 0 || (dblcmp(x - b.x) == 0 && dblcmp(y - b.y) < 0);
  }
  bool operator ==(const point_t &b) const
```

```
  {
    return dblcmp(x - b.x) == 0 && dblcmp(y - b.y) == 0;
  }
  point_t operator +(const point_t &b)
  {
    return point_t(x + b.x, y + b.y);
  }
  point_t operator -(const point_t &b)
  {
    return point_t(x - b.x, y - b.y);
  }
  point_t operator /(double k)
  {
    return point_t(x / k, y / k);
  }
  double operator *(const point_t b)
  {
    return x * b.x + y * b.y;
  }
};
double dist(point_t p1, point_t p2)
{
  return sqrt((p1.x - p2.x) * (p1.x - p2.x) + (p1.y - p2.y) * (p1.y - p2.y));
}
double cross(point_t p1, point_t p2)
{
  return p1.x * p2.y - p1.y * p2.x;
}
// count-clock wise is positive direction
double angle(point_t p1, point_t p2) {
  double x1 = p1.x, y1 = p1.y, x2 = p2.x, y2 = p2.y;
  double a1 = atan2(y1, x1), a2 = atan2(y2, x2);
  double a = a2 - a1;
  while (a < -pi) a += 2 * pi;
  while (a >= pi) a -= 2 * pi;
  return a;
}

bool onSeg(point_t p, point_t a, point_t b) {
  return dblcmp(cross(a - p, b - p)) == 0 && dblcmp(dot(a - p, b - p)) <= 0;
}

// 1 normal intersected, -1 denormal intersected, 0 not intersected
int testSS(point_t a, point_t b, point_t c, point_t d) {
  if (dblcmp(max(a.x, b.x) - min(c.x, d.x)) < 0) return 0;
  if (dblcmp(max(c.x, d.x) - min(a.x, b.x)) < 0) return 0;
  if (dblcmp(max(a.y, b.y) - min(c.y, d.y)) < 0) return 0;
  if (dblcmp(max(c.y, d.y) - min(a.y, b.y)) < 0) return 0;
  int d1 = dblcmp(cross(c - a, b - a));
  int d2 = dblcmp(cross(d - a, b - a));
  int d3 = dblcmp(cross(a - c, d - c));
  int d4 = dblcmp(cross(b - c, d - c));
  if ((d1 * d2 < 0) && (d3 * d4 < 0)) return 1;
  if ((d1 * d2 <= 0 && d3 * d4 == 0) || (d1 * d2 == 0 && d3 * d4 <= 0)) return -1;
  return 0;
}

vector<point_t> isLL(point_t a, point_t b, point_t c, point_t d) {
  point_t p1 = b - a, p2 = d - c;
  vector<point_t> ret;
  double a1 = p1.y, b1 = -p1.x, c1;
  double a2 = p2.y, b2 = -p2.x, c2;
  if (dblcmp(a1 * b2 - a2 * b1) == 0) return ret; // colined <=> a1*c2-a2*c1=0 && b1
    *c2-b2*c1=0
  else {
    c1 = a1 * a.x + b1 * a.y;
    c2 = a2 * c.x + b2 * c.y;
    ret.push_back(point_t((c1 * b2 - c2 * b1) / (a1 * b2 - a2 * b1), (c1 * a2 - c2 *
       a1) / (b1 * a2 - b2 * a1)));
    return ret;
  }
}

point_t angle_bisector(point_t p0, point_t p1, point_t p2) {
  point_t v1 = p1 - p0, v2 = p2 - p0;
  v1 = v1 / dist(v1) * dist(v2);
  return v1 + v2 + p0;
}

point_t perpendicular_bisector(point_t p1, point_t p2) {
  point_t v = p2 - p1;
  swap(v.x, v.y);
  v.x = -v.x;
  return v + (p1 + p2) / 2;
}

point_t circumcenter(point_t p0, point_t p1, point_t p2) {
  point_t v1 = perpendicular_bisector(p0, p1);
  point_t v2 = perpendicular_bisector(p1, p2);
  return isLL((p0 + p1) / 2, v1, (p1 + p2) / 2, v2);
}

point_t incenter(point_t p0, point_t p1, point_t p2) {
  point_t v1 = angle_bisector(p0, p1, p2);
  point_t v2 = angle_bisector(p1, p2, p0);
  return isLL(p0, v1, p1, v2);
```

```
}

point_t orthocenter(point_t p0, point_t p1, point_t p2) {
  return p0 + p1 + p2 - circumcenter(p0, p1, p2) * 2;
}

// count-clock wise is positive direction
point_t rotate(point_t p, double a) {
  double s = sin(a), c = cos(a);
  return point_t(p.x * c - p.y * s, p.y * c + p.x * s);
}

bool insidePoly(point_t *p, int n, point_t t) {
  p[0] = p[n];
  for (int i = 0; i < n; ++i) if (onSeg(t, p[i], p[i + 1])) return true;
  point_t r = point_t(2353456.663, 5326546.243); // random point
  int cnt = 0;
  for (int i = 0; i < n; ++i) {
    if (testSS(t, r, p[i], p[i + 1]) != 0) ++cnt;
  }
  return cnt & 1;
}

bool insideConvex(point_t *convex, int n, point_t t) { // O(logN), convex polygen,
   cross(p[2] - p[1], p[3] - p[1]) > 0
  if (n == 2) return onSeg(t, convex[1], convex[2]);
  int l = 2, r = n;
  while (l < r) {
    int mid = (l + r) / 2 + 1;
    int side = dblcmp(cross(convex[mid] - convex[1], t - convex[1]));
    if (side == 1) l = mid;
    else r = mid - 1;
  }
  int s = dblcmp(cross(convex[l] - convex[1], t - convex[1]));
  if (s == -1 || l == n) return false;
  point_t v = convex[l + 1] - convex[l];
  if (dblcmp(cross(v, t - convex[l])) >= 0) return true;
  return false;
}
```

4.2 Graham Convex Hull

```
bool cmp(const point_t p1, const point_t p2) {
  return dblcmp(p1.y - p2.y) == 0 ? p1.x < p2.x : p1.y < p2.y;
}

int graham(point_t *p) { // Points co-lined are ignored.
  int top = 2; static point_t sk[maxn];
  sort(p + 1, p + 1 + n, cmp);
  sk[1] = p[1], sk[2] = p[2];
  for (int i = 3; i <= n; ++i) {
    while (top >= 2 && dblcmp(cross(p[i] - sk[top - 1], sk[top] - sk[top - 1])) >=
       0) --top;
    sk[++top] = p[i];
  }
  int ttop = top;
  for (int i = n - 1; i >= 1; --i) {
    while (top > ttop && dblcmp(cross(p[i] - sk[top - 1], sk[top] - sk[top - 1])) >=
       0) --top;
    sk[++top] = p[i];
  }
  for (int i = 1; i < top; ++i) p[i] = sk[i];
  return --top;
}
```

4.3 Minkowski Sum of Convex Hull

Wiki:
The Minkowski sum of two sets of position vectors A and B in Euclidean space is formed by adding each vector in A to each vector in B, i.e. the set

$$A + B = \{\vec{a} + \vec{b} \,|\, \vec{a} \in A, \vec{b} \in B\}.$$

For all subsets S_1 and S_2 of a real vector-space, the convex hull of their Minkowski sum is the Minkowski sum of their convex hulls $\mathrm{Conv}(S_1 + S_2) = \mathrm{Conv}(S_1) + \mathrm{Conv}(S_2)$.
Minkowski sums are used in motion planning of an object among obstacles. They are used for the computation of the configuration space, which is the set of all admissible positions of the object. In the simple model of translational motion of an object in the plane, where the position of an object may be uniquely specified by the position of a fixed point of this object, the configuration space are the Minkowski sum of the set of obstacles and the movable object placed at the origin and rotated 180 degrees.

```
int minkowski(point_t *h, point_t *h1, point_t *h2, int n, int m) {
  point_t c = point_t(0, 0);
  for (int i = 1; i <= m; ++i) c = c + h2[i];
  c = c / m;
  for (int i = 1; i <= m; ++i) h2[i] = h2[i] - c;
  int cur = -1;
  for (int i = 1; i <= m; ++i) {
    if (dblcmp(cross(h2[i], h1[1] - h1[n])) >= 0) {
      if (cur == -1 || cross(h2[i], h1[1] - h1[n]) > cross(h2[cur], h1[1] - h1[n]))
        cur = i;
    }
  }
  int cnt = 0;
```

```
  h1[n + 1] = h1[1];
  for (int i = 1; i <= n; ++i) {
    while (true) {
      h[++cnt] = h1[i] + h2[cur];
      int next = (cur == m ? 1 : cur + 1);
      if (dblcmp(cross(h2[cur], h1[i + 1] - h1[i])) < 0) cur = next;
      else {
        if (cross(h2[next], h1[i + 1] - h1[i]) > cross(h2[cur], h1[i + 1] - h1[i])) cur = next;
        else break;
      }
    }
  }
  for (int i = 1; i <= cnt; ++i) h[i] = h[i] + c;
  for (int i = 1; i <= m; ++i) h2[i] = h2[i] + c;
  return graham(h, cnt);
}
```

4.4 Rotating Calipers

```
// Calculate the maximum distance of a point set.
double rotate_caliper() {
  p[0] = p[n];
  int to = 0;
  double ans = 0;
  for (int i = 0; i < n; ++i) {
    while ((to + 1) % n != i) {
      if (dblcmp(cross(p[i + 1] - p[i], p[to + 1] - p[i]) - cross(p[i + 1] - p[i], p[to] - p[i])) >= 0) to = (to + 1) % n;
      else break;
    }
    ans = max(ans, dist(p[i], p[to]));
    ans = max(ans, dist(p[i + 1], p[to]));
  }
  return ans;
}
```

4.5 Closest Pair Points

```
double dac(point_t *p, int l, int r) {
  double d = 10e100;
  if (r - l <= 3) {
    for (int i = l; i <= r; ++i) {
      for (int j = i + 1; j <= r; ++j) {
        d = min(d, dist2(p[i], p[j]));
      }
    }
    sort(p + l, p + r + 1, cmpY);
  } else {
    int mid = (l + r) / 2;
    d = min(dac(p, l, mid), dac(p, mid + 1, r));
    inplace_merge(p + l, p + mid + 1, p + r + 1, cmpY);
    static point_t tmp[maxn]; int cnt = 0;
    for (int i = l; i <= r; ++i) {
      if ((p[i].x - p[mid].x) * (p[i].x - p[mid].x) <= d) tmp[++cnt] = p[i];
    }
    for (int i = 1; i <= cnt; ++i) {
      for (int j = 1; j <= 8 && j + i <= cnt; ++j) {
        d = min(d, dist2(tmp[i], tmp[j + i]));
      }
    }
  }
  return d;
}

double cal(point_t *p, int n) {
  sort(p + 1, p + 1 + n, cmpX);
  return sqrt(dac(p, 1, n));
}
```

4.6 Halfplane Intersection

```
// O(N^2) sol, polygon counterclockwise order
// i.e., left side of vector v1->v2 is the valid half plane
const double maxd = 1e5;
int n, cnt;
point_t p[maxn];

void init() { // order reversed if right side
  cnt = 4;
  p[1] = point_t(-maxd, -maxd);
  p[2] = point_t(maxd, -maxd);
  p[3] = point_t(maxd, maxd);
  p[4] = point_t(-maxd, maxd);
}

void cut(point_t p1, point_t p2) {
  int tcnt = 0;
  static point_t tp[maxn];
  p[cnt + 1] = p[1];
  for (int i = 1; i <= cnt; ++i) {
    double v1 = cross(p2 - p1, p[i] - p1);
    double v2 = cross(p2 - p1, p[i + 1] - p1);
    if (dblcmp(v1) >= 0) tp[++tcnt] = p[i]; // <= if right side
    if (dblcmp(v1) * dblcmp(v2) < 0) tp[++tcnt] = isLL(p1, p2, p[i], p[i + 1]);
```

```
  }
  cnt = tcnt;
  for (int i = 1; i <= cnt; ++i) p[i] = tp[i];
}
```

```
// O(NlogN) sol, Left is valid half plane. Note that the edge of hull may degenerate to a point.
struct hp_t {
  point_t p1, p2;
  double a;
  hp_t() { }
  hp_t(point_t tp1, point_t tp2) : p1(tp1), p2(tp2) {
    tp2 = tp2 - tp1;
    a = atan2(tp2.y, tp2.x);
  }
  bool operator==(const hp_t &r) const {
    return dblcmp(a - r.a) == 0;
  }
  bool operator<(const hp_t &r) const {
    if (dblcmp(a - r.a) == 0) return dblcmp(cross(r.p2 - r.p1, p2 - r.p1)) >= 0;
    else return a < r.a;
  }
} hp[maxn];

void addhp(point_t p1, point_t p2) {
  hp[++cnt] = hp_t(p1, p2);
}

void init() {
  cnt = 0;
  addhp(point_t(-maxd, -maxd), point_t(maxd, -maxd));
  addhp(point_t(maxd, -maxd), point_t(maxd, maxd));
  addhp(point_t(maxd, maxd), point_t(-maxd, maxd));
  addhp(point_t(-maxd, maxd), point_t(-maxd, -maxd));
}

bool checkhp(hp_t h1, hp_t h2, hp_t h3) {
  point_t p = isLL(h1.p1, h1.p2, h2.p1, h2.p2);
  return dblcmp(cross(p - h3.p1, h3.p2 - h3.p1)) > 0;
}

vector<point_t> hp_inter() {
  sort(hp + 1, hp + 1 + cnt);
  cnt = unique(hp + 1, hp + 1 + cnt) - hp - 1;
  deque<hp_t> DQ;
  DQ.push_back(hp[1]);
  DQ.push_back(hp[2]);
  for (int i = 3; i <= cnt; ++i) {
    while (DQ.size() > 1 && checkhp(*----DQ.end(), *--DQ.end(), hp[i])) DQ.pop_back();
    while (DQ.size() > 1 && checkhp(*++DQ.begin(), *DQ.begin(), hp[i])) DQ.pop_front();
    DQ.push_back(hp[i]);
  }
  while (DQ.size() > 1 && checkhp(*----DQ.end(), *--DQ.end(), DQ.front())) DQ.pop_back();
  while (DQ.size() > 1 && checkhp(*++DQ.begin(), *DQ.begin(), DQ.back())) DQ.pop_front();
  DQ.push_front(DQ.back());
  vector<point_t> res;
  while (DQ.size() > 1) {
    hp_t tmp = DQ.front();
    DQ.pop_front();
    res.push_back(isLL(tmp.p1, tmp.p2, DQ.front().p1, DQ.front().p2));
  }
  return res;
}
```

4.7 Tri-Cir Intersection & Tangent

```
vector<point_t> tanCP(point_t c, double r, point_t p) {
  double x = dot(p - c, p - c);
  double d = x - r * r;
  vector<point_t> res;
  if (d < -eps) return res;
  if (d < 0) d = 0;
  point_t q1 = (p - c) * (r * r / x);
  point_t q2 = ((p - c) * (-r * sqrt(d) / x)).rot90(); // rot90: (-y, x)
  res.push_back(c + q1 - q2);
  res.push_back(c + q1 + q2);
  return res;
}

vector<seg_t> tanCC(point_t c1, double r1, point_t c2, double r2) {
  vector<seg_t> res;
  if (abs(r1 - r2) < eps) {
    point_t dir = c2 - c1;
    dir = (dir * (r1 / dir.l())).rot90();
    res.push_back(seg_t(c1 + dir, c2 + dir));
    res.push_back(seg_t(c1 - dir, c2 - dir));
  } else {
    point_t p = ((c1 * -r2) + (c2 * r1)) / (r1 - r2);
    vector<point_t> ps = tanCP(c1, r1, p), qs = tanCP(c2, r2, p);
    for (int i = 0; i < ps.size() && i < qs.size(); ++i) {
      res.push_back(seg_t(ps[i], qs[i]));
    }
```

```
  }
  point_t p = ((c1 * r2) + (c2 * r1)) / (r1 + r2);
  vector<point_t> ps = tanCP(c1, r1, p), qs = tanCP(c2, r2, p);
  // point_t tmp = (c2 - c1).rot90().rot90().rot90();
  for (int i = 0; i < ps.size() && i < qs.size(); ++i) {
    /* if (dblcmp(dist(ps[i], qs[i])) == 0) {
      qs[i] = qs[i] + tmp;
      tmp = tmp.rot90().rot90();
    }*/
    res.push_back(seg_t(ps[i], qs[i]));
  }
  return res;
}
```

```
// Assume d <= r1 + r2 && d >= |r1 - r2|
pair<point_t, point_t> isCC(point_t c1, point_t c2, double r1, double r2) {
  if (r1 < r2) swap(c1, c2), swap(r1, r2);
  double d = dist(c1, c2);
  double x1 = c1.x, x2 = c2.x, y1 = c1.y, y2 = c2.y;
  double mid = atan2(y2 - y1, x2 - x1);
  double a = r1, c = r2;
  double t = acos(max(0.0, a * a + d * d - c * c) / (2 * a * d));
  point_t p1 = point_t(cos(mid - t) * r1, sin(mid - t) * r1) + c1;
  point_t p2 = point_t(cos(mid + t) * r1, sin(mid + t) * r1) + c1;
  return make_pair(p1, p2);
}

int testCC(point_t c1, point_t c2, double r1, double r2) {
  double d = dist(c1, c2);
  if (dblcmp(r1 + r2 - d) <= 0) return 1; // not intersected or tged
  if (dblcmp(r1 + d - r2) <= 0) return 2; // C1 inside C2
  if (dblcmp(r2 + d - r1) <= 0) return 3; // C2 inside C1
  return 0; // intersected
}

point_t isCL(point_t a, point_t b, point_t o, double r) {
  double x0 = o.x, y0 = o.y;
  double x1 = a.x, y1 = a.y;
  double x2 = b.x, y2 = b.y;
  double dx = x2 - x1, dy = y2 - y1;
  double A = dx * dx + dy * dy;
  double B = 2 * dx * (x1 - x0) + 2 * dy * (y1 - y0);
  double C = (x1 - x0) * (x1 - x0) + (y1 - y0) * (y1 - y0) - r * r;
  double delta = B * B - 4 * A * C;
  if (delta >= 0) {
    delta = sqrt(delta);
    double t1 = (-B - delta) / 2 / A;
    double t2 = (-B + delta) / 2 / A;
    if (dblcmp(t1) >= 0) return point_t(x1 + t1 * dx, y1 + t1 * dy); // Ray
    if (dblcmp(t2) >= 0) return point_t(x1 + t2 * dx, y1 + t2 * dy);
  }
  return point_t();
}
```

```
double areaTC(point_t ct, double r, point_t p1, point_t p2) { // intersected area
  double a, b, c, x, y, s = cross(p1 - ct, p2 - ct) / 2;
  a = dist(ct, p2), b = dist(ct, p1), c = dist(p1, p2);
  if (a <= r && b <= r) {
    return s;
  } else if (a < r && b >= r) {
    x = (dot(p1 - p2, ct - p2) + sqrt(c * c * r * r - sqr(cross(p1 - p2, ct - p2))))
       / c;
    return asin(s * (c - x) * 2 / c / b / r) * r * r / 2 + s * x / c;
  } else if (a >= r && b < r) {
    y = (dot(p2 - p1, ct - p1) + sqrt(c * c * r * r - sqr(cross(p2 - p1, ct - p1))))
       / c;
    return asin(s * (c - y) * 2 / c / a / r) * r * r / 2 + s * y / c;
  } else {
    if (fabs(2 * s) >= r * c || dot(p2 - p1, ct - p1) <= 0 || dot(p1 - p2, ct - p2)
      <= 0) {
      if (dot(p1 - ct, p2 - ct) < 0) {
        if (cross(p1 - ct, p2 - ct) < 0) {
          return (-pi - asin(s * 2 / a / b)) * r * r / 2;
        } else {
          return (pi - asin(s * 2 / a / b)) * r * r / 2;
        }
      } else {
        return asin(s * 2 / a / b) * r * r / 2;
      }
    } else {
      x = (dot(p1 - p2, ct - p2) + sqrt(c * c * r * r - sqr(cross(p1 - p2, ct - p2))
        )) / c;
      y = (dot(p2 - p1, ct - p1) + sqrt(c * c * r * r - sqr(cross(p2 - p1, ct - p1))
        )) / c;
      return (asin(s * (1 - x / c) * 2 / r / b) + asin(s * (1 - y / c) * 2 / r / a))
         * r * r / 2 + s * ((y + x) / c - 1);
    }
  }
}

double areaTC(point_t ct, double r, point_t p1, point_t p2, point_t p3) {
  return areaTC(ct, r, p1, p2) + areaTC(ct, r, p2, p3) + areaTC(ct, r, p3, p1);
}
```

4.8 Circle Area Union

```
/* O(n^2logn), please remove coincided circles first. */
```

```
point_t center[maxn];
double radius[maxn], cntarea[maxn];

pair<double, double> isCC(point_t c1, point_t c2, double r1, double r2) {
  double d = dist(c1, c2);
  double x1 = c1.x, x2 = c2.x, y1 = c1.y, y2 = c2.y;
  double mid = atan2(y2 - y1, x2 - x1);
  double a = r1, c = r2;
  double t = acos((a * a + d * d - c * c) / (2 * a * d));
  return make_pair(mid - t, mid + t);
}

struct event_t {
  double theta;
  int delta;
  event_t(double t, int d) : theta(t), delta(d) { }
  bool operator<(const event_t &r) const {
    if (fabs(theta - r.theta) < eps) return delta > r.delta;
    return theta < r.theta;
  }
};
vector<event_t> e;

void add(double begin, double end) {
  if (begin <= -pi) begin += 2 * pi, end += 2 * pi;
  if (end > pi) {
    e.push_back(event_t(begin, 1));
    e.push_back(event_t(pi, -1));
    e.push_back(event_t(-pi, 1));
    e.push_back(event_t(end - 2 * pi, -1));
  } else {
    e.push_back(event_t(begin, 1));
    e.push_back(event_t(end, -1));
  }
}

double calc(point_t c, double r, double a1, double a2) {
  double da = a2 - a1;
  double aa = r * r * (da - sin(da)) / 2;
  point_t p1 = point_t(cos(a1), sin(a1)) * r + c;
  point_t p2 = point_t(cos(a2), sin(a2)) * r + c;
  return cross(p1, p2) / 2 + aa;
}

void circle_union() {
  for (int c = 1; c <= n; ++c) {
    int cvrcnt = 0;
    e.clear();
    for (int i = 1; i <= n; ++i) {
      if (i != c) {
        int r = testCC(center[c], center[i], radius[c], radius[i]);
        if (r == 2) ++cvrcnt;
        else if (r == 0) {
          pair<double, double> paa = isCC(center[c], center[i], radius[c], radius[i
            ]);
          add(paa.first, paa.second);
        }
      }
    }
    if (e.size() == 0) {
      double a = pi * radius[c] * radius[c];
      cntarea[cvrcnt] -= a;
      cntarea[cvrcnt + 1] += a;
    } else {
      e.push_back(event_t(-pi, 1));
      e.push_back(event_t(pi, -2));
      sort(e.begin(), e.end());
      for (int i = 0; i < int(e.size()) - 1; ++i) {
        cvrcnt += e[i].delta;
        double a = calc(center[c], radius[c], e[i].theta, e[i + 1].theta);
        cntarea[cvrcnt - 1] -= a;
        cntarea[cvrcnt] += a;
      }
    }
  }
}
```

4.9 Minimum Covering Circle

```
void set_circle(point_t &p, double &r, point_t a, point_t b) {
  r = dist(a, b) / 2;
  p = (a + b) / 2;
}

void set_circle(point_t &p, double &r, point_t a, point_t b, point_t c) {
  if (dblcmp(cross(b - a, c - a)) == 0) {
    if (dist(a, c) > dist(b, c)) {
      r = dist(a, c) / 2;
      p = (a + c) / 2;
    } else {
      r = dist(b, c) / 2;
      p = (b + c) / 2;
    }
  } else {
    p = circumcenter(a, b, c);
    r = dist(p, a);
```

```
  }
}

bool in_circle(point_t &p, double &r, point_t x) {
  return dblcmp(dist(x, p) - r) <= 0;
}

pair<point_t, double> minimum_circle(int n, point_t *p) {
  point_t c = point_t(0, 0);
  double r = 0;
  random_shuffle(p + 1, p + 1 + n);
  set_circle(c, r, p[1], p[2]);
  for (int i = 3; i <= n; ++i) {
    if (in_circle(c, r, p[i])) continue;
    set_circle(c, r, p[i], p[1]);
    for (int j = 2; j < i; ++j) {
      if (in_circle(c, r, p[j])) continue;
      set_circle(c, r, p[i], p[j]);
      for (int k = 1; k < j; ++k) {
        if (in_circle(c, r, p[k])) continue;
        set_circle(c, r, p[i], p[j], p[k]);
      }
    }
  }
  return make_pair(c, r);
}
```

4.10 Convex Polygon Area Union

```
// modified from syntax_error's code
bool operator<(const point_t &a, const point_t &b) {
  if (dblcmp(a.x - b.x) == 0) return a.y < b.y;
  return a.x < b.x;
}

bool operator==(const point_t &a, const point_t &b) {
  return dblcmp(a.x - b.x) == 0 && dblcmp(a.y - b.y) == 0;
}

struct segment_t {
  point_t a, b;
  segment_t() { a = b = point_t(); }
  segment_t(point_t ta, point_t tb) : a(ta), b(tb) { }
  double len() const { return dist(a, b); }
  double k() const { return (a.y - b.y) / (a.x - b.x); }
  double l() const { return a.y - k() * a.x; }
};

struct line_t {
  double a, b, c;
  line_t(point_t p) { a = p.x, b = -1.0, c = -p.y; }
  line_t(point_t p, point_t q) {
    a = p.y - q.y;
    b = q.x - p.x;
    c = a * p.x + b * p.y;
  }
};

bool ccutl(line_t p, line_t q) {
  if (dblcmp(p.a * q.b - q.a * p.b) == 0) return false;
  return true;
}

point_t cutl(line_t p, line_t q) {
  double x = (p.c * q.b - q.c * p.b) / (p.a * q.b - q.a * p.b);
  double y = (p.c * q.a - q.c * p.a) / (p.b * q.a - q.b * p.a);
  return point_t(x, y);
}

bool onseg(point_t p, segment_t s) {
  if (dblcmp(p.x - min(s.a.x, s.b.x)) < 0 || dblcmp(p.x - max(s.a.x, s.b.x)) > 0)
    return false;
  if (dblcmp(p.y - min(s.a.y, s.b.y)) < 0 || dblcmp(p.y - max(s.a.y, s.b.y)) > 0)
    return false;
  return true;
}

bool ccut(segment_t p, segment_t q) {
  if (!ccutl(line_t(p.a, p.b), line_t(q.a, q.b))) return false;
  point_t r = cutl(line_t(p.a, p.b), line_t(q.a, q.b));
  if (!onseg(r, p) || !onseg(r, q)) return false;
  return true;
}

point_t cut(segment_t p, segment_t q) {
  return cutl(line_t(p.a, p.b), line_t(q.a, q.b));
}

struct event_t {
  double x;
  int type;
  event_t() { x = 0, type = 0; }
  event_t(double _x, int _t) : x(_x), type(_t) { }
  bool operator<(const event_t &r) const {
    return x < r.x;
  }
```

```
};

vector<segment_t> s;

double solve(const vector<segment_t> &v, const vector<int> &sl) {
  double ret = 0;
  vector<point_t> lines;
  for (int i = 0; i < v.size(); ++i) lines.push_back(point_t(v[i].k(), v[i].l()));
  sort(lines.begin(), lines.end());
  lines.erase(unique(lines.begin(), lines.end()), lines.end());
  for(int i = 0; i < lines.size(); ++i) {
    vector<event_t> e;
    vector<int>::const_iterator it = sl.begin();
    for(int j = 0; j < s.size(); j += *it++) {
      bool touch = false;
      for (int k = 0; k < *it; ++k) if (lines[i] == point_t(s[j + k].k(), s[j + k].l())) touch = true;
      if (touch) continue;
      vector<point_t> cuts;
      for (int k = 0; k < *it; ++k) {
        if (!ccutl(line_t(lines[i]), line_t(s[j + k].a, s[j + k].b))) continue;
        point_t r = cutl(line_t(lines[i]), line_t(s[j + k].a, s[j + k].b));
        if (onseg(r, s[j + k])) cuts.push_back(r);
      }
      sort(cuts.begin(), cuts.end());
      cuts.erase(unique(cuts.begin(), cuts.end()), cuts.end());
      if (cuts.size() == 2) {
        e.push_back(event_t(cuts[0].x, 0));
        e.push_back(event_t(cuts[1].x, 1));
      }
    }
    for (int j = 0; j < v.size(); ++j) {
      if (lines[i] == point_t(v[j].k(), v[j].l())) {
        e.push_back(event_t(min(v[j].a.x, v[j].b.x), 2));
        e.push_back(event_t(max(v[j].a.x, v[j].b.x), 3));
      }
    }
    sort(e.begin(), e.end());
    double last = e[0].x;
    int cntg = 0, cntb = 0;
    for (int j = 0; j < e.size(); ++j) {
      double y0 = lines[i].x * last + lines[i].y;
      double y1 = lines[i].x * e[j].x + lines[i].y;
      if (cntb == 0 && cntg) ret += (y0 + y1) * (e[j].x - last) / 2;
      last = e[j].x;
      if (e[j].type == 0) ++cntb;
      if (e[j].type == 1) --cntb;
      if (e[j].type == 2) ++cntg;
      if (e[j].type == 3) --cntg;
    }
  }
  return ret;
}

double polyUnion(vector<vector<point_t> > polys) {
  s.clear();
  vector<segment_t> A, B;
  vector<int> sl;
  for (int i = 0; i < polys.size(); ++i) {
    double area = 0;
    int tot = polys[i].size();
    for (int j = 0; j < tot; ++j) {
      area += cross(polys[i][j], polys[i][(j + 1) % tot]);
    }
    if (dblcmp(area) > 0) reverse(polys[i].begin(), polys[i].end());
    if (dblcmp(area) != 0) {
      sl.push_back(tot);
      for (int j = 0; j < tot; ++j) s.push_back(segment_t(polys[i][j], polys[i][(j + 1) % tot]));
    }
  }
  for (int i = 0; i < s.size(); ++i) {
    int sgn = dblcmp(s[i].a.x - s[i].b.x);
    if (sgn == 0) continue;
    else if (sgn < 0) A.push_back(s[i]);
    else B.push_back(s[i]);
  }
  return solve(A, sl) - solve(B, sl);
}
```

4.11 3D Common

```
double dot(point_t p1, point_t p2) {
  return p1.x * p2.x + p1.y * p2.y + p1.z * p2.z;
}

point_t cross(point_t p1, point_t p2) {
  return point_t(p1.y * p2.z - p1.z * p2.y, p1.z * p2.x - p1.x * p2.z, p1.x * p2.y - p1.y * p2.x);
}

double volume(point_t p1, point_t p2, point_t p3, point_t p4) {
  point_t v1 = cross(p2 - p1, p3 - p1);
  p4 = p4 - p1;
  return dot(v1, p4) / 6;
}
```

```

double area(point_t p1, point_t p2, point_t p3) {
  return cross(p2 - p1, p3 - p1).length() / 2;
}

pair<point_t, point_t> isFF(point_t p1, point_t o1, point_t p2, point_t o2) {
  point_t e = cross(o1, o2), v = cross(o1, e);
  double d = dot(o2, v);
  if (fabs(d) < eps) throw -1;
  point_t q = p1 + (v * (dot(o2, p2 - p1) / d));
  return make_pair(q, q + e);
}

double distLL(point_t p1, point_t u, point_t p2, point_t v) {
  double s = dot(u, v) * dot(v, p1 - p2) - dot(v, v) * dot(u, p1 - p2);
  double t = dot(u, u) * dot(v, p1 - p2) - dot(u, v) * dot(u, p1 - p2);
  double deno = dot(u, u) * dot(v, v) - dot(u, v) * dot(u, v);
  if (dblcmp(deno) == 0) return dist(p1, p2 + v * (dot(p1 - p2, u) / dot(u, v)));
  s /= deno; t /= deno;
  point_t a = p1 + u * s, b = p2 + v * t;
  return dist(a, b);
}
```

4.12 3D Convex Hull

```
int n, bf[maxn][maxn], fcnt;
point_t pt[maxn];
struct face_t {
  int a, b, c;
  bool vis;
} fc[maxn << 5]; /* Number of Faces(Unknown) */

bool remove(int p, int b, int a) {
  int f = bf[b][a];
  face_t ff;
  if (fc[f].vis) {
    if (dblcmp(volume(pt[p], pt[fc[f].a], pt[fc[f].b], pt[fc[f].c])) >= 0) {
      return true;
    } else {
      ff.a = a, ff.b = b, ff.c = p;
      bf[ff.a][ff.b] = bf[ff.b][ff.c] = bf[ff.c][ff.a] = ++fcnt;
      ff.vis = true;
      fc[fcnt] = ff;
    }
  }
  return false;
}

void dfs(int p, int f) {
  fc[f].vis = false;
  if (remove(p, fc[f].b, fc[f].a)) dfs(p, bf[fc[f].b][fc[f].a]);
  if (remove(p, fc[f].c, fc[f].b)) dfs(p, bf[fc[f].c][fc[f].b]);
  if (remove(p, fc[f].a, fc[f].c)) dfs(p, bf[fc[f].a][fc[f].c]);
}

void hull3d() {
  for (int i = 2; i <= n; ++i) {
    if (dblcmp((pt[i] - pt[1]).length()) > 0) swap(pt[i], pt[2]);
  }
  for (int i = 3; i <= n; ++i) {
    if (dblcmp(fabs(area(pt[1], pt[2], pt[i]))) > 0) swap(pt[i], pt[3]);
  }
  for (int i = 4; i <= n; ++i) {
    if (dblcmp(fabs(volume(pt[1], pt[2], pt[3], pt[i]))) > 0) swap(pt[i], pt[4]);
  }
  zm(fc), fcnt = 0, zm(bf);
  for (int i = 1; i <= 4; ++i) {
    face_t f;
    f.a = i + 1, f.b = i + 2, f.c = i + 3;
    if (f.a > 4) f.a -= 4;
    if (f.b > 4) f.b -= 4;
    if (f.c > 4) f.c -= 4;
    if (dblcmp(volume(pt[i], pt[f.a], pt[f.b], pt[f.c])) > 0) swap(f.a, f.b);
    f.vis = true;
    bf[f.a][f.b] = bf[f.b][f.c] = bf[f.c][f.a] = ++fcnt;
    fc[fcnt] = f;
  }
  random_shuffle(pt + 5, pt + 1 + n);
  for (int i = 5; i <= n; ++i) {
    for (int j = 1; j <= fcnt; ++j) {
      if (!fc[j].vis) continue;
      if (dblcmp(volume(pt[i], pt[fc[j].a], pt[fc[j].b], pt[fc[j].c])) >= 0) {
        dfs(i, j);
        break;
      }
    }
  }
  for (int i = 1; i <= fcnt; ++i) if (!fc[i].vis) swap(fc[i--], fc[fcnt--]);
}
```

5 Graph

5.1 Tarjan

```
//求强联通分量
```

```
void tarjan(int u)
{
  low[u] = dfn[u] = ++curDfn;
  sta[sta_n++] = u;
  for (int i = head[u]; i; i = E[i].nxt)
  {
    if (!dfn[E[i].nxt])
    {
      tarjan(E[i].nxt);
      low[u] = min(low[u], low[E[i].v]);
    }
    else
      if (!sccNum[E[i].v])
        low[u] = min(low[u], dfn[E[i].v]);
  }
  if (low[u] == dfn[u])
  {
    nScc++;
    int v;
    do
      v = sta[--sta_n], sccNum[v] = nScc;
    while (u != v);
  }
}
// 求点双连通分量+割点
void tarjan(int u, int peid = -1)
{
  low[u] = dfn[u] = ++curDfn;
  int nSubtree = 0;
  for (int i = head[u]; i = E[i].nxt; i = E[i].nxt)
    if (i != peid)
    {
      if (!dfn[E[i].v])
      {
        sta[sta_n++] = i;
        tarjan(E[i].v, i ^ 1);
        nSubtree++;
        if (low[E[i].v] >= dfn[v])
        {
          if (dfn[u] != 1)
            isCutPoint[u] = true;
          nBcc++;
          int e;
          do
            e = sta[--sta_n], bccNum[e] = nBcc;
          while (e != i);
        }
        low[u] = min(low[u], low[E[i].v]);
      }
      else
      {
        low[u] = min(low[u], dfn[E[i].v]);
        if (dfn[E[i].v] < dfn[u])
          sta[sta_n++] = i;
      }
    }
  if (dfn[u] == 1 && nSubtree >= 2)
    isCutPoint[u] = true;
}

// 求边双连通分量+桥
void tarjan(int u, int fa = -1)
{
  low[u] = dfn[u] = ++curDfn;
  sta[sta_n++] = u;
  inSta[u] = 1;
  for (int i = head[u]; i; i = E[i].nxt)
    if (E[i].v != fa)
    {
      if (!dfn[E[i].v])
      {
        tarjan(E[i].v, u);
        low[u] = min(low[u], low[E[i].v]);
      }
      else
        if (inSta[E[i].v])
          low[u] = min(low[u], dfn[E[i].v]);
    }
  if (low[u] == dfn[u])  //edge fa <-> u is a bridge
  {
    int v;
    do
      v = sta[--sta_n], ebccNum[v] = u, inSta[v] = 0;
    while (u != v);
  }
}
```

For bidirectional graph(cut vertex & bridge):
root: u has 2 or more children.
others: exist a child v satifsying $dfn[u] \le low[v]$.
(u, v) is bridge only if $dfn[u] < low[v]$ (trick: multiple edges).

5.2 Maximum Flow(ISAP)

```
// assuming the sink has the maximum vertex ID => t = n
```

```
int n, m, s, t, ec, d[maxn], vd[maxn];
struct edge_link {
  int v, r;
  edge_link *next, *pair;
} edge[maxm], *header[maxn], *current[maxn];
void add(int u, int v, int r) // (u, v, r), (v, u, 0)
{
  ec++;
  edge[ec].v = v; edge[ec].r = r;
  edge[ec].next = header[u]; header[u] = &edge[ec];
  edge[ec].pair = &edge[ec+1];
  ec++;
  edge[ec].pair = &edge[ec-1];
  edge[ec].next = header[v]; header[v] = &edge[ec];
  edge[ec].v = u; edge[ec].r = 0;
}
int augment(int u, int flow) {
  if (u == t) return flow;
  int temp, res = 0;
  for (edge_link *&e = current[u]; e != NULL; e = e->next) {
    if (e->r && d[u] == d[e->v] + 1) {
      temp = augment(e->v, min(e->r, flow - res));
      e->r -= temp, e->pair->r += temp, res += temp;
      if (d[s] == t || res == flow) return res;
    }
  }
  if (--vd[d[u]] == 0) d[s] = t;
  else current[u] = header[u], ++vd[++d[u]];
  return res;
}

int sap() {
  int flow = 0;
  memset(d, 0, sizeof(d)), memset(vd, 0, sizeof(vd));
  vd[0] = t;
  for (int i = 1; i <= t; ++i) current[i] = header[i];
  while (d[s] < t) flow += augment(s, maxint);
  return flow;
}
```

Notes on vertex covering and independent set on bipartite graph:
Minimum Vertex Covering Set V': $\forall(u,v) \in E$, $u \in V'$ or $v \in V'$ holds.
Maximum Vertex Independent Set V': $\forall u, v \in V'$, $(u,v) \notin E$ holds.
Construct a flow graph G, run DFS from s on reduction graph, the vertices not visited in left side and visited in right side form the minimum vertex covering set.
Maximum vertex independent set vice versa.
上下界网络流：
1：无源汇的可行流：新建源点，汇点，M[i] 为每个点进来的下界流减去出去的下界流，如果 M[i] 为正，由源点向改点建 M[i] 的边，反之，由该点向汇点建 M[i] 的边，原图中的边为每条边的上界建去下界。跑一遍最大流，每条边的流量加上下界流就是答案。
2：有源汇的最大流：从汇点向源点建一条容量为 INF 的边，用上面的方法判断是否有解，有解就再跑一遍从原图中源点到汇点的最大流
3：有源汇的最小流：先跑一遍最大流，然后连上从汇点到源点的边，再按照 1 的方法做就好了

5.3 Maximum Flow(HLPP)

```
#include <cstdio>
#include <cstring>
#include <cstdlib>
#include <cmath>
#include <ctime>
#include <iostream>
#include <algorithm>
#include <set>
#include <map>
#include <vector>
#include <string>
#include <queue>
using namespace std;
typedef long long LL;
#define For(i,a,b) for (int i = (a); i <= (b); i++)
#define Cor(i,a,b) for (int i = (a); i >= (b); i--)
#define Fill(a,b) memset(a,b,sizeof(a))

const int MAX_SIDE = 100000, MAX_NODE = 100000;

class network_flow
{
    private:

        int label[MAX_NODE], GAP[MAX_NODE];
        bool visited[MAX_NODE];
        int in_flow[MAX_NODE];
        int vS, vT;
        int tot_node, label_max;
        queue<int> active[MAX_NODE];

    public:
        struct EDGES
        {
            int pre[MAX_SIDE], val[MAX_SIDE], node[MAX_SIDE], last[MAX_NODE];
            int tot;
            EDGES()
            {
```

```
            tot = 1;
        }
        void add_edge(int s, int t, int v)
        {
            tot++;
            pre[tot] = last[s];
            node[tot] = t;
            val[tot] = v;
            last[s] = tot;
        }
    }edge;
    void set_s(int s) { vS = s; }
    void set_t(int t) { vT = t; }
    void set_tot_node(int n) { tot_node = n; }
    void HLPP()
    {
        get_length();
        prepare();
        max_flow();
    }

    void add_edge(int s, int t, int v)
    {
        edge.add_edge(s, t, v);
        edge.add_edge(t, s, 0);
    }

    void max_flow()
    {
        while(label_max)
        {
            if(active[label_max].empty())
            {
                label_max--;
                continue;
            }

            int now = active[label_max].front(), ext, val;
            int label_min = tot_node + 1;
            int push_flow;

            active[label_max].pop();
            for(int pos(edge.last[now]); pos; pos = edge.pre[pos])
            {
                ext = edge.node[pos];
                val = edge.val[pos];
                if(val > 0)
                {
                    if(label[ext] + 1 == label[now])
                    {
                        push_flow = min(val, in_flow[now]);
                        edge.val[pos] -= push_flow;
                        edge.val[pos ^ 1] += push_flow;
                        in_flow[now] -= push_flow;
                        in_flow[ext] += push_flow;
                        if(push_flow)
                            active[label[ext]].push(ext);
                    }
                }
                if(edge.val[pos])
                    label_min = min(label_min, label[ext]);
                if(!in_flow[now])
                    break;
            }
            if(in_flow[now] && now != vT && label_min < tot_node)
            {
                int cache = label[now];
                GAP[label[now]] --;
                label[now] = label_min + 1;
                GAP[label[now]] ++;
                if(GAP[cache] == 0)
                {
                    for(int i(1); i <= tot_node; ++ i)
                        if(label[i] > cache && label[i] < tot_node + 1)
                        {
                            GAP[label[i]]--;
                            GAP[tot_node + 1]++;
                            label[i] = tot_node + 1;
                        }
                }
                active[label[now]].push(now);
                if(label[now] > label_max)
                    label_max= label[now];
            }
        }
    }

    void prepare()
    {
        for(int pos(edge.last[vS]); pos; pos = edge.pre[pos])
        {
            int ext = edge.node[pos], val = edge.val[pos];
            if(val > 0)
            {
                in_flow[ext] += val;
                edge.val[pos] -= val;
```

```
                edge.val[pos ^ 1] += val;
                if(label[ext] > label_max)
                    label_max = label[ext];
                active[label[ext]].push(ext);
            }
        }
    }

    void get_length()
    {
        int queue[MAX_NODE];

        fill(label + 1, label + 1 + tot_node, tot_node + 1);
        memset(visited, 0, sizeof(visited));
        queue[0]  = vT;
        label[vT]= 0;
        visited[vT] = 1;
        GAP[0] = 1;
        GAP[tot_node + 1] = tot_node - 1;

        for(int p1(0), p2(0); p1 <= p2; ++ p1)
        {
            int now = queue[p1], ext;
            for(int pos(edge.last[now]); pos; pos = edge.pre[pos])
            {
                ext = edge.node[pos];
                if(!visited[ext])
                {
                    visited[ext] = 1;
                    queue[++p2] = ext;
                    label[ext] = label[now] + 1;
                    GAP[tot_node + 1]--;
                    GAP[label[ext]]++;
                }
            }
        }
    }
    int get_ans()
    {
        return in_flow[vT];
    }
}net;
```

5.4 Minimum Cost, Maximum Flow

```
using namespace std;
int n, m, s, t, ec, d[maxn]; // Minimum cost, maximum flow(ZKW version), t=n
struct edge_link {
  int v, r, w;
  edge_link *next, *pair;
} edge[maxm], *header[maxn];
bool vis[maxn];
//void add(int u, int v, int r, int w) // (u, v, r, w), (v, u, 0, -w)
void add(int u, int v, int r)
{
  ec++;
  edge[ec].v = v; edge[ec].r = r; edge[ec].w = w;
  edge[ec].next = header[u]; header[u] = &edge[ec];
  edge[ec].pair = &edge[ec+1];
  ec++;
  edge[ec].pair = &edge[ec-1];
  edge[ec].next = header[v]; header[v] = &edge[ec];
  edge[ec].v = u; edge[ec].r = 0; edge[ec].r = -w;
}
void spfa() {
  queue<int> q;
  for (int i = 1; i <= t; ++i) d[i] = maxint, vis[i] = false;
  d[s] = 0, q.push(s), vis[s] = true;
  while (!q.empty()) {
    int u = q.front();
    q.pop(), vis[u] = false;
    for (edge_link *e = header[u]; e != NULL; e = e->next) {
      if (e->r && d[u] + e->w < d[e->v]) {
        d[e->v] = d[u] + e->w;
        if (!vis[e->v]) q.push(e->v), vis[e->v] = true;
      }
    }
  }
  for (int i = 1; i <= t; ++i) d[i] = d[t] - d[i];
}

int augment(int u, int flow) {
  if (u == t) return flow;
  vis[u] = true;
  for (edge_link *e = header[u]; e != NULL; e = e->next) {
    if (e->r && !vis[e->v] && d[e->v] + e->w == d[u]) {
      int temp = augment(e->v, min(flow, e->r));
      if (temp) {
        e->r -= temp, e->pair->r += temp;
        return temp;
      }
    }
  }
  return 0;
}

```

```
bool adjust() {
  int delta = maxint;
  for (int u = 1; u <= t; ++u) {
    if (!vis[u]) continue;
    for (edge_link *e = header[u]; e != NULL; e = e->next) {
      if (e->r && !vis[e->v] && d[e->v] + e->w > d[u]) {
        delta = min(delta, d[e->v] + e->w - d[u]);
      }
    }
  }
  if (delta == maxint) return false;
  for (int i = 1; i <= t; ++i) {
    if (vis[i]) d[i] += delta;
  }
  memset(vis, 0, sizeof(vis));
  return true;
}

pair<int, int> cost_flow() {
  int temp, flow = 0, cost = 0;
  spfa();
  do {
    while (temp = augment(s, maxint)) {
      flow += temp;
      memset(vis, 0, sizeof(vis));
    }
  } while (adjust());
  for (int i = 2; i <= ec; i += 2) cost += edge[i].r * edge[i - 1].w;
  return make_pair(flow, cost);
}
void init()
{

}
```

5.5 Kuhn Munkras

```
// Kuhn-Munkras's algorithm, maxn: Left Size; maxm: Right Size.
int n, m, g[maxn][maxm], lx[maxn], ly[maxm], slack[maxm], match[maxm];
bool vx[maxn], vy[maxm];

bool find(int x) {
  vx[x] = true;
  for (int y = 1; y <= m; ++y) {
    if (!vy[y]) {
      int delta = lx[x] + ly[y] - g[x][y];
      if (delta == 0) {
        vy[y] = true;
        if (match[y] == 0 || find(match[y])) {
          match[y] = x;
          return true;
        }
      } else slack[y] = min(slack[y], delta);
    }
  }
  return false;
}

int km() { // #define sm(p, f) memset((p), f, sizeof(p))
  // maximum weight, if minimum, negate all g then restore at the end.
  sm(lx, 0x80), sm(ly, 0), sm(match, 0);
  for (int i = 1; i <= n; ++i) {
    for (int j = 1; j <= m; ++j) lx[i] = max(lx[i], g[i][j]);
  }
  for (int k = 1; k <= n; ++k) {
    sm(slack, 0x7f);
    while (true) {
      sm(vx, 0), sm(vy, 0);
      if (find(k)) break;
      else {
        int delta = maxint;
        for (int i = 1; i <= m; ++i) {
          if (!vy[i]) delta = min(delta, slack[i]);
        }
        for (int i = 1; i <= n; ++i) {
          if (vx[i]) lx[i] -= delta;
        }
        for (int i = 1; i <= m; ++i) {
          if (vy[i]) ly[i] += delta;
          if (!vy[i]) slack[i] -= delta;
        }
      }
    }
  }
  int result = 0;
  for (int i = 1; i <= n; ++i) result += lx[i];
  for (int i = 1; i <= m; ++i) result += ly[i];
  return result;
}
```

5.6 Hopcroft Karp

```
int n, m, vis[maxn], level[maxn], pr[maxn], pr2[maxn];
vector<int> edge[maxn]; // for Left

bool dfs(int u) {
```

```
  vis[u] = true;
  for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
    int v = pr2[*it];
    if (v == -1 || (!vis[v] && level[u] < level[v] && dfs(v))) {
      pr[u] = *it, pr2[*it] = u;
      return true;
    }
  }
  return false;
}

int hopcroftKarp() {
  memset(pr, -1, sizeof(pr)); memset(pr2, -1, sizeof(pr2));
  for (int match = 0; ;) {
    queue<int> Q;
    for (int i = 1; i <= n; ++i) {
      if (pr[i] == -1) {
        level[i] = 0;
        Q.push(i);
      } else level[i] = -1;
    }
    while (!Q.empty()) {
      int u = Q.front(); Q.pop();
      for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
        int v = pr2[*it];
        if (v != -1 && level[v] < 0) {
          level[v] = level[u] + 1;
          Q.push(v);
        }
      }
    }
    for (int i = 1; i <= n; ++i) vis[i] = false;
    int d = 0;
    for (int i = 1; i <= n; ++i) if (pr[i] == -1 && dfs(i)) ++d;
    if (d == 0) return match;
    match += d;
  }
}
```

5.7 Blossom Matching

```
int n, match[maxn], pre[maxn], base[maxn]; // maximum matching on graphs
vector<int> edge[maxn];
bool inQ[maxn], inB[maxn], inP[maxn];
queue<int> Q;

int LCA(int u, int v) {
  for (int i = 1; i <= n; ++i) inP[i] = false;
  while (true) {
    u = base[u];
    inP[u] = true;
    if (match[u] == -1) break;
    u = pre[match[u]];
  }
  while (true) {
    v = base[v];
    if (inP[v]) return v;
    v = pre[match[v]];
  }
}

void reset(int u, int a) {
  while (u != a) {
    int v = match[u];
    inB[base[u]] = inB[base[v]] = true;
    v = pre[v];
    if (base[v] != a) pre[v] = match[u];
    u = v;
  }
}

void contract(int u, int v) {
  int a = LCA(u, v);
  for (int i = 1; i <= n; ++i) inB[i] = false;
  reset(u, a), reset(v, a);
  if (base[u] != a) pre[u] = v;
  if (base[v] != a) pre[v] = u;
  for (int i = 1; i <= n; ++i) {
    if (!inB[base[i]]) continue;
    base[i] = a;
    if (!inQ[i]) Q.push(i), inQ[i] = true;
  }
}

bool dfs(int s) {
  for (int i = 1; i <= n; ++i) pre[i] = -1, inQ[i] = false, base[i] = i;
  while (!Q.empty()) Q.pop();
  Q.push(s), inQ[s] = true;
  while (!Q.empty()) {
    int u = Q.front();
    Q.pop();
    for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
      int v = *it;
      if (base[u] == base[v] || match[u] == v) continue;
      if (v == s || (match[v] != -1 && pre[match[v]] != -1)) contract(u, v);
      else if (pre[v] == -1) {
```

```
      pre[v] = u;
      if (match[v] != -1) {
        Q.push(match[v]), inQ[match[v]] = true;
      } else {
        u = v;
        while (u != -1) {
          v = pre[u];
          int w = match[v];
          match[u] = v, match[v] = u;
          u = w;
        }
        return true;
      }
    }
  }
}
return false;
}

int blossom() {
  int ans = 0;
  for (int i = 1; i <= n; ++i) match[i] = -1;
  for (int i = 1; i <= n; ++i) {
    if (match[i] == -1 && dfs(i)) ++ans;
  }
  return ans;
}
```

5.8 Stoer Wagner

```
// stoer-wagner algorithm, complexity: O(n^3)
// used to compute the global minimum cut, and self-loop is ignored.
int n, g[maxn][maxn], v[maxn], d[maxn], vis[maxn];
int stoer_wagner(int n) {
  int res = maxint;
  for (int i = 1; i <= n; i++) v[i] = i, vis[i] = 0;
  while (n > 1) {
    int p = 2, prev = 1;
    for (int i = 2; i <= n; ++i) {
      d[v[i]] = g[v[1]][v[i]];
      if (d[v[i]] > d[v[p]]) p = i;
    }
    vis[v[1]] = n;
    for (int i = 2; i <= n; ++i) {
      if (i == n) {
        res = min(res, d[v[p]]); // if d[v[p]] < res, then s = v[p] & t = v[prev]
        for (int j = 1; j <= n; ++j) {
          g[v[prev]][v[j]] += g[v[p]][v[j]];
          g[v[j]][v[prev]] = g[v[prev]][v[j]];
        }
        v[p] = v[n--];
        break;
      }
      vis[v[p]] = n;
      prev = p;
      p = -1;
      for (int j = 2; j <= n; ++j) {
        if (vis[v[j]] != n) {
          d[v[j]] += g[v[prev]][v[j]];
          if (p == -1 || d[v[p]] < d[v[j]]) p = j;
        }
      }
    }
  }
  return res;
}
```

5.9 Arborescence

```
/*最小树形图
不定根的情况，造一个虚拟根， MAXINT 连上所有的点，最后答案减去 MAXINT 。
求有向森林的同上，插0边即可。可以支持负边权求最大。*/
int n, ec, ID[maxn], pre[maxn], in[maxn], vis[maxn];
struct edge_t {
  int u, v, w;
} edge[maxm];
void add(int u, int v, int w) {
  edge[++ec].u = u, edge[ec].v = v, edge[ec].w = w;
}

int arborescence(int n, int root) {
  int res = 0, index;
  while (true) {
    for (int i = 1; i <= n; ++i) {
      in[i] = maxint, vis[i] = -1, ID[i] = -1;
    }
    for (int i = 1; i <= ec; ++i) {
      int u = edge[i].u, v = edge[i].v;
      if (u == v || in[v] <= edge[i].w) continue;
      in[v] = edge[i].w, pre[v] = u;
    }
    pre[root] = root, in[root] = 0;
    for (int i = 1; i <= n; ++i) {
      res += in[i];
      if (in[i] == maxint) return -1;
    }
```

```
    index = 0;
    for (int i = 1; i <= n; ++i) {
      if (vis[i] != -1) continue;
      int u = i, v;
      while (vis[u] == -1) {
        vis[u] = i;
        u = pre[u];
      }
      if (vis[u] != i || u == root) continue;
      for (v = u, u = pre[u], ++index; u != v; u = pre[u]) ID[u] = index;
      ID[v] = index;
    }
    if (index == 0) return res;
    for (int i = 1; i <= n; ++i) if (ID[i] == -1) ID[i] = ++index;
    for (int i = 1; i <= ec; ++i) {
      int u = edge[i].u, v = edge[i].v;
      edge[i].u = ID[u], edge[i].v = ID[v];
      edge[i].w -= in[v];
    }
    n = index, root = ID[root];
  }
  return res;
}
```

5.10 Manhattan MST

```
struct point {
  int x, y, index;
  bool operator<(const point &p) const { return x == p.x ? y < p.y : x < p.x; }
} p[maxn];
struct node {
  int value, p;
} T[maxn];

int query(int x) {
  int r = maxint, p = -1;
  for (; x <= n; x += (x & -x)) if (T[x].value < r) r = T[x].value, p = T[x].p;
  return p;
}

void modify(int x, int w, int p) {
  for (; x > 0; x -= (x & -x)) if (T[x].value > w) T[x].value = w, T[x].p = p;
}

int manhattan() {
  for (int i = 1; i <= n; ++i) p[i].index = i;
  for (int dir = 1; dir <= 4; ++dir) {
    if (dir == 2 || dir == 4) {
      for (int i = 1; i <= n; ++i) swap(p[i].x, p[i].y);
    } else if (dir == 3) {
      for (int i = 1; i <= n; ++i) p[i].x = -p[i].x;
    }
    sort(p + 1, p + 1 + n);
    vector<int> v; static int a[maxn];
    for (int i = 1; i <= n; ++i) a[i] = p[i].y - p[i].x, v.push_back(a[i]);
    sort(v.begin(), v.end()); v.erase(unique(v.begin(), v.end()), v.end());
    for (int i = 1; i <= n; ++i) a[i] = lower_bound(v.begin(), v.end(), a[i]) - v.
      begin() + 1;
    for (int i = 1; i <= n; ++i) T[i].value = maxint, T[i].p = -1;
    for (int i = n; i >= 1; --i) {
      int pos = query(a[i]);
      if (pos != -1) add(p[i].index, p[pos].index, dist(p[i], p[pos]));
      modify(a[i], p[i].x + p[i].y, i);
    }
  }
  return kruskal();
}
```

5.11 Minimum Mean Cycle

```
int dp[maxn][maxn]; // minimum mean cycle(allow negative weight)
double mmc(int n) {
  for (int i = 0; i < n; ++i) {
    memset(dp[i + 1], 0x7f, sizeof(dp[i + 1]));
    for (int j = 1; j <= ec; ++j) {
      int u = edge[j].u, v = edge[j].v, w = edge[j].w;
      if (dp[i][u] != maxint) dp[i + 1][v] = min(dp[i + 1][v], dp[i][u] + w);
    }
  }
  double res = maxdbl;
  for (int i = 1; i <= n; ++i) {
    if (dp[n][i] == maxint) continue;
    double value = -maxdbl;
    for (int j = 0; j < n; ++j) {
      value = max(value, (double)(dp[n][i] - dp[j][i]) / (n - j));
    }
    res = min(res, value);
  }
  return res;
}
```

5.12 Divide and Conquer on Tree

```
int bk, size[maxn], parent[maxn], ver[maxn];
bool cut[maxn];
```

```

void bfs(int r) { // bfs in each sub-tree
  parent[r] = 0, bk = 0; // maintain root extra information
  static queue<int> Q; static stack<int> U;
  Q.push(r);
  while (!Q.empty()) {
    int u = Q.front();
    Q.pop(); U.push(u);
    size[u] = 1, ver[++bk] = u; // find a node in sub-tree
    for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
      int v = *it;
      if (v == parent[u] || cut[v]) continue;
      parent[v] = u; // maintain v from u
      Q.push(v);
    }
  }
  while (!U.empty()) {
    int u = U.top(); U.pop();
    if (parent[u]) size[parent[u]] += size[u];
  }
}

int findCentre(int r) {
  static queue<int> Q;
  int result = 0, rsize = maxint;
  bfs(r);
  Q.push(r);
  while (!Q.empty()) {
    int u = Q.front();
    Q.pop();
    int temp = size[r] - size[u];
    for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
      int v = *it;
      if (cut[v] || v == parent[u]) continue;
      temp = max(temp, size[v]);
      Q.push(v);
    }
    if (temp < rsize) rsize = temp, result = u;
  }
  return result;
}

int work(int u) {
  int result = 0;
  u = findCentre(u);
  cut[u] = true;
  for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
    int v = *it;
    if (!cut[v]) /*result += */work(v); // process each sub-tree
  }
  for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
    int v = *it;
    if (cut[v]) continue;
    bfs(v); // then combine sub-trees
  }
  cut[u] = false;
  return result;
}

int fa[maxn], dep[maxn], son[maxn], size[maxn];
void dfs1(int x, int p, int depth)
{
  fa[x] = p; dep[x] = depth;
  size[x] = 1;
  int maxsize = 0;
  son[x] = 0;
  for (int i = head[x]; i; i = E[i].nxt)
  {
    int v = E[i].v;
    if (v != p)
    {
      dfs1(v, x, depth + 1);
      size[x] += size[v];
      if (size[v] > maxsize)
      {
        maxsize = size[v];
        son[x] = v;
      }
    }
  }
}
int top[maxn], p[maxn], fp[maxn], lable;
void dfs2(int x, int sp)
{
  top[x] = sp;
  p[x] = ++lable;
  fp[p[x]] = x;
  if (son[x])
    dfs2(son[x], sp);
  else
    return;
  for (int i = head[x]; i; i = E[i].nxt)
  {
    int v = E[i].v;
    if (v != son[x] && v != fa[x])
      dfs2(v, v);
```

```
  }
}
int find(int u, int v)
{
  int f1 = top[u], f2 = top[v];
  int ret = 0;
  while (f1 != f2)
  {
    if (dep[f1] < dep[f2])
    {
      swap(f1, f2);
      swap(u, v);
    }
    ret = max(ret, seg.query(p[f1], p[u], 1, n, 1));
    u = fa[f1]; f1 = top[u];
  }
  if (u == v)
    return ret;
  if (dep[u] > dep[v])
    swap(u, v);
  ret = max(ret, seg.query(p[son[u]], p[v], 1, n, 1));
  return ret;
}
```

5.13 Dominator Tree

A dominator tree is a tree where each node's children are those nodes it immediately dominates. Because the immediate dominator is unique, it is a tree. The start node is the root of the tree.

```
int parent[maxn], label[maxn], cnt, real[maxn];
vector<int> edge[maxn], succ[maxn], pred[maxn];
int semi[maxn], idom[maxn], ancestor[maxn], best[maxn];
deque<int> bucket[maxn];

void dfs(int u) {
  label[u] = ++cnt; real[cnt] = u;
  for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
    int v = *it;
    if (v == parent[u] || label[v] != -1) continue;
    parent[v] = u;
    dfs(v);
  }
}

void link(int v, int w) {
  ancestor[w] = v;
}

void compress(int v) {
  int a = ancestor[v];
  if (ancestor[a] == 0) return;
  compress(a);
  if (semi[best[v]] > semi[best[a]]) best[v] = best[a];
  ancestor[v] = ancestor[a];
}

int eval(int v) {
  if (ancestor[v] == 0) return v;
  compress(v);
  return best[v];
}

void dominator() { // clear succ & pred, let cnt = 0 first
  for (int i = 1; i <= n; ++i) label[i] = -1;
  dfs(n); // n is root
  for (int u = 1; u <= n; ++u) {
    for (vector<int>::iterator it = edge[u].begin(); it != edge[u].end(); ++it) {
      int v = *it;
      if (label[u] != -1 && label[v] != -1) {
        succ[label[u]].push_back(label[v]);
        pred[label[v]].push_back(label[u]);
      }
    }
  }
  for (int i = 1; i <= n; ++i) {
    semi[i] = best[i] = i;
    idom[i] = ancestor[i] = 0;
    bucket[i].clear();
  }
  for (int w = cnt; w >= 2; --w) {
    int p = label[parent[real[w]]];
    for (vector<int>::iterator it = pred[w].begin(); it != pred[w].end(); ++it) {
      int v = *it;
      int u = eval(v);
      if (semi[w] > semi[u]) semi[w] = semi[u];
    }
    bucket[semi[w]].push_back(w);
    link(p, w);
    while (!bucket[p].empty()) {
      int v = bucket[p].front();
      bucket[p].pop_front();
      int u = eval(v);
      idom[v] = (semi[u] < p ? u : p);
    }
  }
```

```
  for (int w = 2; w <= cnt; ++w) {
    if (idom[w] != semi[w]) idom[w] = idom[idom[w]];
  }
  idom[1] = 0;
  for (int i = 1; i <= cnt; ++i) {
    int u = real[idom[i]], v = real[i];
    // u is immediate dominator of v (i == 1?)
  }
}
```

5.14 Steiner's Problem

```
// Steiner's Problem: ts[m], list of vertices to be united, indexed from 0.
int steiner(int *ts, int m) { // O(3^m*n+2^m*n^2+n^3)
  floyd();
  memset(dp, 0, sizeof(dp));
  for (int i = 0; i < m; ++i) {
    for (int j = 1; j <= n; ++j) {
      dp[1 << i][j] = g[ts[i]][j];
    }
  }
  for (int i = 1; i < (1 << m); ++i) {
    if (((i - 1) & i) != 0) {
      for (int j = 1; j <= n; ++j) {
        dp[i][j] = maxint;
        for (int k = (i - 1) & i; k > 0; k = (k - 1) & i) {
          dp[i][j] = min(dp[i][j], dp[k][j] + dp[i ^ k][j]);
        }
      }
      for (int j = 1; j <= n; ++j) {
        for (int k = 1; k <= n; ++k) {
          dp[i][j] = min(dp[i][j], dp[i][k] + g[k][j]);
        }
      }
    }
  }
  return dp[(1 << m) - 1][ts[0]];
}
```

5.15 LCA

```
const int logn = 20;
int parent[maxn], lca[logn][maxn], depth[maxn];

void initLCA() {
  for (int i = 1; i <= n; ++i) lca[0][i] = parent[i];
  for (int j = 1; j < logn; ++j) {
    for (int i = 1; i <= n; ++i) {
      lca[j][i] = lca[j - 1][lca[j - 1][i]];
    }
  }
}

int LCA(int x, int y) {
  if (depth[x] < depth[y]) swap(x, y);
  for (int i = logn - 1; i >= 0; --i) {
    if (depth[x] - (1 << i) >= depth[y]) x = lca[i][x];
  }
  if (x == y) return x;
  for (int i = logn - 1; i >= 0; --i) {
    if (lca[i][x] != lca[i][y]) {
      x = lca[i][x], y = lca[i][y];
    }
  }
  return lca[0][x];
}
```

5.16 Chordal Graph

一些结论：

弦：连接环中不相邻的两个点的边。

弦图：一个无向图称为弦图当且仅当图中任意长度大于 3 的环都至少有一个弦。

单纯点：设 N(v) 表示与点 v 相邻的点集。一个点称为单纯点当 v + N(v) 的诱导子图为一个团。

完美消除序列：这是一个序列 v[i]，它满足 v[i] 在 v[i..n] 的诱导子图中为单纯点。

弦图的判定：存在完美消除序列的图为弦图。可以用 MCS 最大势算法求出完美消除序列。

最大势算法从 n 到 1 的顺序依次给点标号 (标号为 i 的点出现在完美消除序列的第 i 个)。设 label[i] 表示第 i 个点与多少个已标号的点相邻，每次选择 label[i] 最大的未标号的点进行标号。

判断一个序列是否为完美消除序列：设 vi+1,⋯,vn 中所有与 vi 相邻的点依次为 vj1,⋯, vjk。只需判断 vj1 是否与 vj2,⋯, vjk 相邻即可。弦图的最大点独立集——完美消除序列从前往后能选就选。最小团覆盖数 = 最大点独立集数。

```
int label[10010], order[10010], seq[10010], color[10010], usable[10010];

int chordal() {
  label[0] = -5555;
  for(int i = N;i > 0;i--) {
    int t = 0;
    for(int j = 1;j <= N;j++) if(!order[j] && label[j] > label[t]) t = j;
    order[t] = i; seq[i] = t;
    for(auto y: edges[t]) label[y]++;
  }
```

```

  int ans = 0;
  for(int i = N;i > 0;i--) {
    for(auto y: edges[seq[i]]) usable[color[e->y]] = i;
    int c = 1;
    while(usable[c] == i) c++;
    color[seq[i]] = c;
    ans = max(ans, c)
  }
  return ans;
}
```

5.17 Planar Gragh

5.17.1 Euler Characteristic

$$\chi = V - E + F$$

其中，V 为点数，E 为边数，F 为面数，对于平面图即为划分成的平面数（包含外平面），χ 为对应的欧拉示性数，对于平面图有 $\chi = C + 1$，C 为连通块个数。

5.17.2 Dual Graph

将原图中所有平面区域作为点，每条边若与两个面相邻则在这两个面之间连一条边，只与一个面相邻连个自环，若有权值 (容量) 保留。

5.17.3 Maxflow on Planar Graph

连接 s 和 t，显然不影响图的平面性，转对偶图，令原图中 s 和 t 连接产生的新平面在对偶图中对应的节点为 s'，外平面对应的顶点为 t'，删除 s' 和 t' 之间直接相连的边。此时 s' 到 t' 的一条最短路就对应了原图上 s 到 t 的一个最大流。

5.18 Prufer Code

5.18.1 根据树构造

我们通过不断地删除顶点编过号的树上的叶子节点直到还剩下 2 个点为止的方法来构造这棵树的 Prüfer sequence。特别的，考虑一个顶点编过号的树 T，点集为 $1, 2, 3, \ldots, n$。在第 i 步中，删除树中编号值最小的叶子节点，设置 Prüfer sequence 的第 i 个元素为与这个叶子节点相连的点的编号。

5.18.2 还原

设 a_i 是一个 Prüfer sequence。这棵树将有 $n+2$ 个节点，编号从 1 到 $n+2$，对于每个节点，计它在 Prüfer sequence 中出现的次数 +1 为其度数。然后，对于 a 中的每个数 a_i，找编号最小的度数值为 1 节点 j，加入边 (j, a_i)，然后将 j 和 a_i 的度数值减少 1。最后剩下两个点的度数值为 1，连起来即可。

5.18.3 一些结论

完全图 K_n 的生成树，顶点的度数必须为 $d_1, d_2, \ldots, d_n$，这样的生成树棵数为：

$$\frac{(n-2)!}{[(d_1-1)!(d_2-1)!(d_3-1)!\ldots(d_n-1)!]}$$

一个顶点编号过的树，实际上是编号的完全图的一棵生成树。通过修改枚举 Prüfer sequence 的方法，可以用类似的方法计算完全二分图的生成树棵数。如果 G 是完全二分图，一边有 n_1 个点，另一边有 n_2 个点，则其生成树棵数为 $n_1^{n_2-1} * n_2^{n_1-1}$。

6 Miscellaneous

6.1 Expression Parsing

```
void deal(stack<int> &num, stack<char> &oper) {
  int x, y;
  y = num.top(); num.pop();
  char op = oper.top(); oper.pop();
  if (op == '?') num.push(-y);
  else {
    x = num.top(); num.pop();
    num.push(cal(x, y, op));
  }
}

int parse(char *s) {
  static int priv[256];
  stack<int> num;
  stack<char> oper;
  priv['+'] = priv['-'] = 3;
  priv['*'] = priv['/'] = 2;
  priv['('] = 10;
  int len = strlen(s);
  char last = 0;
  for (int i = 0; i < len; ++i)  {
    if (isdigit(s[i])) {
      int tmp = 0;
      while (isdigit(s[i])) tmp = tmp * 10 + s[i++] - '0';
      i -= 1;
      num.push(tmp);
    } else if (s[i] == '(') {
      oper.push(s[i]);
    } else if (s[i] == ')') {
      while (oper.top() != '(') deal(num, oper);
      oper.pop();
    } else if (s[i] == '-' && (last == 0 || last == '(')) {
      oper.push('?'); // unary operator
```

```
    } else if (priv[s[i]] > 0) {
      while (!oper.empty() && priv[s[i]] >= priv[oper.top()]) deal(num, oper); // >=
         used for operator of left associative law
      oper.push(s[i]);
    } else continue;
    last = s[i];
  }
  while (!oper.empty()) deal(num, oper);
  return num.top();
}
```

6.2 AlphaBeta

```
int alphabeta(state s, int alpha, int beta) {
  if (s.finished()) return s.score();
  for (state t : s.next()) {
    alpha = max(alpha, -alphabeta(t, -beta, -alpha));
    if (alpha >= beta) break;
  }
  return alpha;
}
```

6.3 Dancing Links X

```
const int maxm = 2000, maxk = 500000;
struct dancingLinksX
{
    int pt, L[maxk], R[maxk], U[maxk], D[maxk];
    int C[maxk], A[maxk];
    int S[maxm], H[maxm];
    int ans[maxm], totAns;
    void init(int m) {
        Fill(H, -1);
        for (int i = 0; i <= m; ++i) S[i] = 0, L[i] = i - 1, R[i] = i + 1, D[i] = U[
          i] = i;
        L[0] = m, R[m] = 0;
        pt = m;
    }
    inline void insert(int row, int col) {
            ++S[col], ++pt;
            C[pt] = col, A[pt] = row, U[pt] = U[col], D[pt] = col;
            D[U[col]] = pt, U[col] = pt;
            if (~H[row]) {
                L[pt] = L[H[row]], R[pt] = H[row], L[R[pt]] = R[L[pt]] = pt;
            } else {
                H[row] = L[pt] = R[pt] = pt;
            }
    }

    inline void remove(int x) {
        L[R[x]] = L[x], R[L[x]] = R[x];
        for (int i = D[x]; i != x; i = D[i]) {
            for (int j = R[i]; j != i; j = R[j]) {
                U[D[j]] = U[j], D[U[j]] = D[j], --S[C[j]];
            }
        }
    }

    inline void resume(int x) {
        for (int i = U[x]; i != x; i = U[i]) {
            for (int j = L[i]; j != i; j = L[j]) {
                U[D[j]] = j, D[U[j]] = j, ++S[C[j]];
            }
        }
        L[R[x]] = x, R[L[x]] = x;
    }

    bool dlx(int k) {
        if (R[0] == 0)
        {
            totAns = k;
            return true;
        }
        int col = R[0];
        for (int i = R[0]; i != 0; i = R[i]) {
            if (S[col] > S[i]) col = i;
        }
        if (S[col] == 0) return false;
        remove(col);
        for (int i = D[col]; i != col; i = D[i]) {
            ans[k] = A[i];
            for (int j = R[i]; j != i; j = R[j]) remove(C[j]);
            if (dlx(k + 1)) return true;
            for (int j = L[i]; j != i; j = L[j]) resume(C[j]);
        }
        resume(col);
        return false;
    }
    // call dlx(0)
}DLX;
```

Find the minimum row set, satisfying each column has exactly one 1.
Let the row representing each choice, if some choices are mutually exclusive, add a column with these rows associated.
Use the sudoku problem as an instance. There are 729 choices(81 squares can be filled

in with 9 numbers), 4 constraints:
(1). Each box has exactly one number;
(2). Number 1 to 9 appears exactly once in each row, column, sub square.
Thus we can construct a 729∗324 matrix, each 81 columns representing each constraint.

6.4 Mo-Tao Algorithm

```
// Complexity: Q*N^0.5 * O(add)
int SQRTN = (int)sqrt((double)q);
sort(Q + 1, Q + 1 + q, cmpL);
for (int i = 1; i <= q; i += SQRTN) {
  clear();
  int begin = i, end = i + SQRTN - 1;
  if (end > q) end = q;
  sort(Q + begin, Q + end + 1, cmpR);
  Q[begin - 1].l = 1, Q[begin - 1].r = 0;
  for (int j = begin; j <= end; ++j) {
    for (int k = Q[j - 1].r + 1; k <= Q[j].r; ++k) add(k, 1);
    if (Q[j].l > Q[j - 1].l) {
      for (int k = Q[j - 1].l; k < Q[j].l; ++k) add(k, -1);
    } else if (Q[j].l < Q[j - 1].l) {
      for (int k = Q[j].l; k < Q[j - 1].l; ++k) add(k, 1);
    }
    ans[Q[j].ID] = res;
  }
}
```

6.5 Digits Dp

```
#include <cstdio>
#include <cstring>
#include <cmath>
#include <cstdlib>
#include <algorithm>
#include <iostream>
using namespace std;
typedef long long LL;
L1 getsum1(int n, int k)
{
  LL B = 1;
  for (int i = 0; i < n; i++) B *= k;
  return B * n * (k - 1) / 2;
}
L2 getsum2(int prefixsum, int n, int k)
{
  LL B = getsum1(n, k);
  LL C = prefixsum;
  for (int i = 0; i < n; i++)
    C *= k;
  return B + C;
}
LL getsum3(int prefixsum, long long n, int k)
{
  if (n < k)
  {
    LL ret = 0;
    for (int i = 0; i <= n; i++)
      ret += prefixsum + i;
    return ret;
  }
  LL t = 1, tn = n;
  int d = 0;
  while (tn >= k)
  {
    tn /= k;
    t *= k;
    d++;
  }
  LL ret = 0;
  for (int i = 0; i < tn; i++)
    ret += getsum2(prefixsum + i, d, k);
  ret += getsum3(prefixsum + tn, n - tn * t, k);
  return ret;
}
int main()
{
  int k;
  long long a, b;
  scanf("%lld%lld%d",&a, &b, &k);
  printf("%lld\n", getsum3(0,b,k) - getsum3(0,a-1,k));
  return 0;
}
```

6.6 Plugin Dp

```
//verison 1
//hash
const int maxn = 1000010;
const int Hash_Mod = 30007;
const int maxm = 15;
int maze[maxm][maxm];
int code[maxm];
int n, m;
struct HashMap
```

```
{
  int head[Hash_Mod], nxt[maxn], size;
  long long f[maxn],state[maxn];
  void init()
  {
    memset(head,0,sizeof(head));
    size = 0;
  }
  void push(long long st, long long ans)
  {
    int ht = st % Hash_Mod;
    for (int i = head[ht]; i; i = nxt[i])
    {
      if (state[i] == st)
      {
        f[i] += ans;
        return;
      }
    }
    size++;
    nxt[size] = head[ht]; head[ht] = size;
    state[size] = st; f[size] = ans;
  }
}hm[2];
void decode(int *code, int m, long long st)
{
  for (int i = m; i >= 0; i--)
  {
    code[i] = st & 7;
    st >>= 3;
  }
}
int ch[maxm];
long long encode(int *code, int m)
{
  long long st = 0;
  memset(ch,-1,sizeof(ch));
  ch[0] = 0;
  int cnt = 1;
  for (int i = 0; i <= m; i++)
  {
    if (ch[code[i]] == -1)
      ch[code[i]] = cnt++;
    code[i] = ch[code[i]];
    st <<= 3;
    st |= code[i];
  }
  return st;
}
//换行原理: 上一行行尾是----|,下一行行首是|----,水平线上的状态完全相同
void shift(int *code, int m)
{
  for (int i = m; i > 0; i--)
    code[i] = code[i-1];
  code[0] = 0;
}
int ex, ey;
void dpblank(int i, int j, int cur)
{
  int k, up, left;
  for (k = 1; k <= hm[cur].size; k++)
  {
    decode(code, m, hm[cur].state[k]);
    left = code[j-1];
    up = code[j];
    if (up && left)
    {
      if (up == left)
      {
        if (i == ex && j == ey)
        {
          code[j-1] = code[j] = 0;
          if (j == m)
            shift(code,m);
          hm[cur ^ 1].push(encode(code,m),hm[cur].f[k]);
        }
      }
      else
      {
        code[j] = code[j-1] = 0;
        for (int p = 0; p <= m; p++)
          if (code[p] == left)
            code[p] = up;
        if (j == m)
          shift(code,m);
        hm[cur ^ 1].push(encode(code,m),hm[cur].f[k]);
      }
    }
    else
      if ((left != 0 && up == 0) || (up != 0 && left == 0))
      {
        int p = left + up;
        if (maze[i+1][j])
        {
          code[j-1] = p; code[j] = 0;
          if (j == m)
```

```
            shift(code,m);
          hm[cur ^ 1].push(encode(code,m),hm[cur].f[k]);
        }
        if (maze[i][j+1])
        {
          code[j-1] = 0; code[j] = p;
          hm[cur ^ 1].push(encode(code,m),hm[cur].f[k]);
        }
      }
      else
      {
        if (maze[i][j+1] && maze[i+1][j])
        {
          code[j-1] = code[j] = 13;
          hm[cur ^ 1].push(encode(code,m),hm[cur].f[k]);
        }
      }
  }

}
void dpblock(int i, int j, int cur)
{
  for (int k = 1; k <= hm[cur].size; k++)
  {
    decode(code, m, hm[cur].state[k]);
    code[j-1] = code[j] = 0;
    if (j == m)
      shift(code,m);
    hm[cur ^ 1].push(encode(code,m), hm[cur].f[k]);
  }
}
void solve()
{
  int cur = 0;
  hm[cur].init();
  hm[cur].push(0,1);
  for (int i = 1; i <= n; i++)
    for (int j = 1; j <= m; j++)
    {
      hm[cur ^ 1].init();
      if (maze[i][j])
        dpblank(i,j,cur);
      else
        dpblock(i,j,cur);
      cur ^= 1;
    }
  long long ans = 0;
  for (int i = 1; i <= hm[cur].size; i++)
    ans += hm[cur].f[i];
  printf("%lld\n", ans);
}

//version 2
//matrix improved
const int maxm = 7, maxs = 2187, pow3[] = {1, 3, 9, 27, 81, 243, 729, 2187}; // m+1, 3**(m+1)
int n, m, top, stack[maxm + 1], match[maxs][maxm + 1], cnt, valid[maxs], ID[maxs];
int mt[N + 1][N + 1], mt2[N + 1][N + 1], f[maxm][maxs], g[maxs]; // N: cnt
int gb3(int v, int bit) { return (v / pow3[bit - 1]) % 3; }
int mb3(int v, int bit, int value) { return v - pow3[bit - 1] * gb3(v, bit) + pow3[bit - 1] * value; }
int ub3(int v, int bit) { return v - pow3[bit - 1] * gb3(v, bit); }
void upd(int &x, int v) { x += v; x %= mod; }

void dfs(int p, int st, int lt) {
  if (p > m + 1) {
    if (lt == 0) {
      valid[st] = true;
      if (st % 3 == 0) ID[st] = ++cnt; // omitted
      top = 0;
      for (int j = 1; j <= m + 1; ++j) {
        if (gb3(st, j) == 1) {
          stack[++top] = j;
        } else if (gb3(st, j) == 2) {
          match[st][j] = stack[top];
          match[st][stack[top--]] = j;
        }
      }
    }
  } else {
    dfs(p + 1, st, lt); // #
    dfs(p + 1, mb3(st, p, 1), lt + 1); // (
    if (lt) dfs(p + 1, mb3(st, p, 2), lt - 1); // )
  }
}

int plugDP(int n, int m) {
  memset(valid, 0, sizeof(valid)), memset(ID, -1, sizeof(ID)), cnt = 0;
  memset(mt, 0, sizeof(mt)), memset(mt2, 0, sizeof(mt2));
  dfs(1, 0, 0);
  for (int start = 0; start < pow3[m + 1]; ++start) {
    if (ID[start] == -1) continue;
    for (int fi = 0; fi < 2; ++fi) { // Last colume flag
      memset(f, 0, sizeof(f)); memset(g, 0, sizeof(g));
      f[0][start] = 1;
      for (int j = 0; j <= m; ++j) {
```

```
      for (int k = 0; k < pow3[m + 1]; ++k) {
        if (!valid[k]) continue;
        if (j == m) {
          if (!fi && !gb3(k, j + 1)) { // i != n
            upd(g[ub3(k, j + 1) * 3], f[j][k]); // Unmark last bit
          }
        } else {
           // Consider mp[i][j + 1] valid ? (bit1 = bit2 = 0)
          int bit1 = gb3(k, j + 1), bit2 = gb3(k, j + 2),
            t = ub3(ub3(k, j + 1), j + 2), tt;
          if (bit1 == 1 && bit2 == 2) { // Merge two brackets
            if (fi && j + 1 == m) { // i == n
              upd(f[j + 1][t], f[j][k]);
            }
          } else if (bit1 == 2 && bit2 == 1) {
            upd(f[j + 1][t], f[j][k]);
          } else if (!bit1 && !bit2) { // bit1 == 0 && bit2 == 0
            tt = mb3(mb3(t, j + 1, 1), j + 2, 2);
            upd(f[j + 1][tt], f[j][k]);
          } else if (bit1 == bit2) {
            if (bit1 == 1) { // bit1 == 1 && bit2 == 1
              tt = mb3(t, match[k][j + 2], 1);
              upd(f[j + 1][tt], f[j][k]);
            } else { // bit1 == 2 && bit2 == 2
              tt = mb3(t, match[k][j + 1], 2);
              upd(f[j + 1][tt], f[j][k]);
            }
          } else { // bit1 == 0 || bit2 == 0
            upd(f[j + 1][k], f[j][k]);
            swap(bit1, bit2);
            tt = mb3(mb3(t, j + 1, bit1), j + 2, bit2);
            upd(f[j + 1][tt], f[j][k]);
          }
        }
      }
    }
    if (fi) {
      for (int i = 0; i < pow3[m + 1]; ++i) if (ID[i] != -1) mt2[ID[start]][ID[i]]
         = f[m][i];
    } else {
      for (int i = 0; i < pow3[m + 1]; ++i) if (ID[i] != -1) mt[ID[start]][ID[i]]
        = g[i];
    }
  }
}
matrix_t mat = 0, mat2 = 0, mf = 0;
for (int i = 1; i <= cnt; ++i) for (int j = 1; j <= cnt; ++j) {
  mat.x[j][i] = mt[i][j], mat2.x[j][i] = mt2[i][j];
}
mat = mat2 * mat.power(n - 1);
mf.x[ID[0]/* ?? */][1] = 1;
mf = mat * mf;
return mf.x[ID[0]][1];
}
```

7 Tips

7.1 Useful Codes

- Accelerated C++ stream IO

```
#include <iomanip>
ios_base::sync_with_stdio(false);
```

- Enumerate all non-empty subsets

```
for (int sub = mask; sub > 0; sub = (sub - 1) & mask)
```

- Enumerate C_n^k

```
for (int comb = (1 << k) - 1; comb < 1 << n; ) {
  // ...
  int x = comb & -comb, y = comb + x;
  comb = ((comb & ~y) / x >> 1) | y;
}
```

- Convert YY/MM/DD to date

```
int days(int y, int m, int d) {
  if (m < 3) y--, m += 12;
  return 365 * y + y / 4 - y / 100 + y / 400 + (153 * m + 2) / 5 + d;
}
```

- Increase Stack Size

```
#pragma comment(linker,"/STACK:102400000,102400000")

register char *_sp __asm__("rsp"); // esp / sp
int main(void) {
  const int size = 64*1024*1024;
  static char *sys, *mine(new char[size]+size-4096);
  sys = _sp; _sp = mine; mmain(); _sp = sys;
  return 0;
}
```

- Compare Code

```
#!/bin/bash
while true; do
./make_data
./prog1
./prog2
diff ans1.out ans2.out
if [ $? -ne 0 ] ; then break; fi
done
```

7.2 Formulas

7.2.1 Geometry

■ Euler's Formula

For convex polyhedron: $V - E + F = 2$.
For planar graph: $|F| = |E| - |V| + n + 1$, n denotes the number of connected components.

■ Pick's Theorem

$$S = I + \frac{B}{2} - 1$$

S is the area of lattice polygon, I is the number of lattice interior points, and B is the number of lattice boundary points.

■ Heron's Formula

$$S = \sqrt{p(p-a)(p-b)(p-c)}$$
$$p = \frac{a+b+c}{2}$$

■ Volumes

- Pyramid $V = \frac{1}{3}Sh$.
- Sphere $V = \frac{4}{3}\pi R^3$.
- Frustum $V = \frac{1}{3}h(S_1 + \sqrt{S_1 S_2} + S_2)$.
- Ellipsoid
  For ellipsoid with the standard equation in a Cartesian coordinate system $\frac{(x-x_0)^2}{a^2} + \frac{(y-y_0)^2}{b^2} + \frac{(z-z_0)^2}{c^2} = 1$, $V = \frac{4}{3}\pi abc$.
- Ellipsoid $V = \frac{4}{3}\pi abc$.
- Tetrahedron
  For tetrahedron $O - ABC$, let $a = AB, b = BC, c = CA, d = OC, e = OA, f = OB$, $(12V)^2 = a^2d^2(b^2+c^2+e^2+f^2-a^2-d^2) + b^2e^2(c^2+a^2+f^2+d^2-b^2-e^2) + c^2f^2(a^2+b^2+d^2+e^2-c^2-f^2) - a^2b^2c^2 - a^2e^2f^2 - d^2b^2f^2 - d^2e^2c^2$.

■ Radius of Inscribedcircle & Circumcircle

$$r = \frac{2S}{a+b+c},\ R = \frac{abc}{4S}$$

■ Euler Point 欧拉线上的四点中，九点圆圆心到垂心和外心的距离相等，而且重心到外心的距离是重心到垂心距离的一半。

■ Hypersphere

$$\begin{aligned}
&V_2 = \pi R^2,\ S_2 = 2\pi R\\
&V_3 = \frac{4}{3}\pi R^3,\ S_3 = 4\pi R^2\\
&V_4 = \frac{1}{2}\pi^2 R^4,\ S_4 = 2\pi^2 R^3\\
&V_5 = \frac{8}{15}\pi^2 R^5,\ S_5 = \frac{8}{3}\pi^2 R^4\\
&V_6 = \frac{1}{6}\pi^3 R^6,\ S_6 = \pi^3 R^5\\
&\text{Generally, } V_n = \frac{2\pi}{n}V_{n-2},\ S_{n-1} = \frac{2\pi}{n-2}S_{n-3}\\
&\text{Where, } S_0 = 2,\ V_1 = 2,\ S_1 = 2\pi,\ V_2 = \pi
\end{aligned}$$

■ Affine Transformation

$$\begin{aligned}
\mathrm{Tr} = \mathrm{TrTra} * \mathrm{TrRot} * \mathrm{TrSca} &= \begin{bmatrix}1 & 0 & T_x\\ 0 & 1 & T_y\\ 0 & 0 & 1\end{bmatrix}\begin{bmatrix}\cos\alpha & -\sin\alpha & 0\\ \sin\alpha & \cos\alpha & 0\\ 0 & 0 & 1\end{bmatrix}\begin{bmatrix}S_x & 0 & 0\\ 0 & S_y & 0\\ 0 & 0 & 1\end{bmatrix}\\
&= \begin{bmatrix}S_x\cos\alpha & -S_y\sin\alpha & T_x\\ S_x\sin\alpha & S_y\cos\alpha & T_y\\ 0 & 0 & 1\end{bmatrix}
\end{aligned}$$

The fixed point is (x_0, y_0), where

$$x_0 = -\frac{T_x(S_y\cos\alpha - 1)}{S_xS_y - S_x\cos\alpha - S_y\cos\alpha + 1} - \frac{S_yT_y\sin\alpha}{S_xS_y - S_x\cos\alpha - S_y\cos\alpha + 1}$$
$$y_0 = \frac{S_xT_x\sin\alpha}{S_xS_y - S_x\cos\alpha - S_y\cos\alpha + 1} - \frac{T_y(S_x\cos\alpha - 1)}{S_xS_y - S_x\cos\alpha - S_y\cos\alpha + 1}$$

■ Matrix of rotating θ about arbitrary axis A $|A| = 1$

$$\begin{bmatrix}c + (1-c)A_x^2 & (1-c)A_xA_y - sA_z & (1-c)A_xA_z + sA_y\\ (1-c)A_xA_y + sA_z & c + (1-c)A_y^2 & (1-c)A_yA_z - sA_x\\ (1-c)A_xA_z - sA_y & (1-c)A_yA_z + sA_x & c + (1-c)A_z^2\end{bmatrix}$$

7.2.2 Math

■ **Sums**

$$1+2+\ldots+n=\frac{n^2}{2}+\frac{n}{2}$$
$$1^2+2^2+\ldots+n^2=\frac{n^3}{3}+\frac{n^2}{2}+\frac{n}{6}$$
$$1^3+2^3+\ldots+n^3=\frac{n^4}{4}+\frac{n^3}{2}+\frac{n^2}{4}$$
$$1^4+2^4+\ldots+n^4=\frac{n^5}{5}+\frac{n^4}{2}+\frac{n^3}{3}-\frac{n}{30}$$
$$1^5+2^5+\ldots+n^5=\frac{n^6}{6}+\frac{n^5}{2}+\frac{5n^4}{12}-\frac{n^2}{12}$$
$$1^6+2^6+\ldots+n^6=\frac{n^7}{7}+\frac{n^6}{2}+\frac{n^5}{2}-\frac{n^3}{6}+\frac{n}{42}$$
$$\mathrm{P}(k)=\frac{(n+1)^{k+1}-\sum_{i=0}^{k-1}\binom{k+1}{i}\mathrm{P}(i)}{k+1},\mathrm{P}(0)=n\mathbf{+1}$$

$$\sum_{k=1}^{n}k(k+1)=\frac{n(n+1)(n+2)}{3}$$
$$\sum_{k=1}^{n}k(k+1)(k+2)=\frac{n(n+1)(n+2)(n+3)}{4}$$
$$\sum_{k=1}^{n}k(k+1)(k+2)(k+3)=\frac{n(n+1)(n+2)(n+3)(n+4)}{5}$$

■ **Power Reduction** $a^b\%p=a^{(b\%\varphi(p))+\varphi(p)}\%p\,(b\geq\varphi(p))$

■ **C(n,m) 奇偶** 如果 (n & m)=m，那么为奇数，否则为偶数

■ **Burnside's Lemma**

$$|X/G|=\frac{1}{|G|}\sum_{g\in G}|X^g|$$

$$\text{Polya}: X^g=t^{c(g)}$$

Let X^g denote the set of elements in X fixed by g.
$c(g)$ is the number of cycles of the group element g as a permutation of X.

■ **Lagrange Multiplier**

A strategy for finding the local extrema of a function subject to equality constraints. If we want to maximize $f(x_1,x_2,\ldots,x_n)$, which subject to $\varphi(x_1,x_2,\ldots,x_n)=0$. We introduce a new variable λ called a Lagrange multiplier, and study the Lagrange function $L(x_1,x_2,\ldots,x_n)=f(x_1,x_2,\ldots,x_n)+\lambda\varphi(x_1,x_2,\ldots,x_n)$.
Then we calculate x_i's first partial derivatives of $L(x_1,x_2,\ldots,x_n)$, and add the simultaneous equation $\varphi(x_1,x_2,\ldots,x_n)=0$. We get these equations

$$\begin{cases}\ldots\\ f_{x_i}(x_1,x_2,\ldots,x_n)+\lambda\varphi_{x_i}(x_1,x_2,\ldots,x_n)=0\\ \ldots\\ \varphi(x_1,x_2,\ldots,x_n)=0\end{cases}$$

Solve it to get all **probable** extrema points.
Also it can extend to multiple constraints. Just set multiple Lagrange multipliers λ, ψ, etc.

■ **Lucas' Theorem**

For non-negative integers m and n and a prime p, holds the equation

$$\binom{m}{n}\equiv\prod_{i=0}^{k}\binom{m_i}{n_i}\mod p$$

where $m=m_kp^k+m_{k-1}p^{k-1}+\ldots+m_1p+m_0$, and $n=n_kp^k+n_{k-1}p^{k-1}+\ldots+n_1p+n_0$, are the base p expansions of m and n respectively.

■ **Wilson's Theorem**

p is a prime $\iff(p-1)!\equiv-1\pmod p$.

■ **Polynomial Congruence Equation**

Solve the polynomial congruence equation $f(x)\equiv0\mod m$, $m=\prod_{i=1}^{k}p_i^{a_i}$.
We just simply consider the equation $f(x)\equiv0\mod p^a$, then use the Chinese Remainder theorem to merge the result.
If x is the root of the equation $f(x)\equiv0\mod p^a$, then x is also the root of $f(x)\equiv0\mod p^{a-1}$.
$f'(x')\equiv0\mod p$ **and** $f(x')\equiv0\mod p^a\Rightarrow x=x'+dp^{a-1}(d=0,\ldots,p-1)$
$f'(x')\not\equiv0\mod p\Rightarrow x=x'-\frac{f(x')}{f'(x')}$

■ **Binomial Coefficients**

$$\mathrm{C}_r^k=\frac{r}{k}\mathrm{C}_{r-1}^{k-1}\qquad\mathrm{C}_r^k=\mathrm{C}_{r-1}^k+\mathrm{C}_{r-1}^{k-1}$$
$$\mathrm{C}_r^m\mathrm{C}_m^k=\mathrm{C}_r^k\mathrm{C}_{r-k}^{m-k}\qquad\sum_{k\leq n}\mathrm{C}_{r+k}^k=\mathrm{C}_{r+n+1}^n$$
$$\sum_{0\leq k\leq n}\mathrm{C}_k^m=\mathrm{C}_{n+1}^{m+1}\qquad\sum_k\mathrm{C}_r^k\mathrm{C}_s^{n-k}=\mathrm{C}_{r+s}^n$$

The number of non-negative solutions to equation $x_1+x_2+x_3+\ldots+x_k=n$ is $\binom{n+k-1}{k-1}$.

■ Probability Distribution

- Binomial distribution: $\Pr[X=k]=\binom{n}{k}p^kq^{n-k}, p+q=1, \mathrm{E}[X]=np$.
- Poisson distribution: $\Pr[X=k]=\frac{e^{-\lambda}\lambda^k}{k!}, \mathrm{E}[X]=\lambda$.
- Gaussian distribution: $p(x)=\frac{1}{\sigma\sqrt{2\pi}}e^{-(x-\mu)^2/2\sigma^2}, \mathrm{E}[X]=\mu$.
- Geometric distribution: $\Pr[X=k]=pq^{k-1}, p+q=1, \mathrm{E}[X]=\frac{1}{p}$.

■ Catalan Number

The number of sequences with 1 of m and -1 of n, and m$\geq n$, satifisying the constraint that any sum of the first k elements is always non-negative: $\mathrm{C}_{m+n}^{m}-\mathrm{C}_{m+n}^{m+1}$.
Specially, when $m=n$, it equals to $\mathrm{C}_n=\frac{\mathrm{C}_{2n}^{n}}{n+1}$, which is the Catalan number.
The first 10 Catalan numbers are 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, from $n=1$, and $C_0=1$.
Besides, $C_{n+1}=\sum_{i=0}^{n}C_iC_{n-i}$, for $n\geq 0$.

■ Stirling Number of 2^{nd}

The Stirling number of the second kind is the number of ways to partition a set of n objects into k non-empty subsets, denoted by $S(n,k)$.
$S(n,k)=kS(n-1,k)+S(n-1,k-1)$, and $S(0,0)=1$, $S(n,0)=0$, $S(n,n)=1$.

■ Bell Number

The Bell Number is the number of ways to partition a set of n objects into several subsets, denoted by B_n.
The first few Bell Numbers are 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, 115975.
$B_{n+1}=\sum_{k=0}^{n}\binom{n}{k}B_k$, $B_n=\sum_{k=0}^{n}S(n,k)$, where $S(n,k)$ is Stirling Number of 2^{nd}.
If p is a prime then, $B_{p+n}\equiv B_n+B_{n+1}(mod\ p)$, $B_{p^m+n}\equiv mB_n+B_{n+1}(mod\ p)$.

■ Derangement Number

The number of permutations of n elements with no fixed points, denotes as D_n.
$D_n=n!(1-\frac{1}{1!}+\frac{1}{2!}-\frac{1}{3!}+\ldots+(-1)^n\frac{1}{n!})$, or $D_n=n*D_{n-1}+(-1)^n, D_n=(n-1)*(D_{n-1}+D_{n-2})$, with $D_1=1, D_2=1$. The first 10 derangement numbers are 0, 1, 2, 9, 44, 265, 1854, 14833, 133496, 41334961, from $n=1$.

7.2.3 Integration

■ $ax+b(a\neq 0)$

1. $\int\frac{\mathrm{d}x}{ax+b}=\frac{1}{a}\ln|ax+b|+C$
2. $\int(ax+b)^\mu\mathrm{d}x=\frac{1}{a(\mu+1)}(ax+b)^{\mu+1}+C(\mu\neq 1)$
3. $\int\frac{x}{ax+b}\mathrm{d}x=\frac{1}{a^2}(ax+b-b\ln|ax+b|)+C$
4. $\int\frac{x^2}{ax+b}\mathrm{d}x=\frac{1}{a^3}\left(\frac{1}{2}(ax+b)^2-2b(ax+b)+b^2\ln|ax+b|\right)+C$
5. $\int\frac{\mathrm{d}x}{x(ax+b)}=-\frac{1}{b}\ln\left|\frac{ax+b}{x}\right|+C$
6. $\int\frac{\mathrm{d}x}{x^2(ax+b)}=-\frac{1}{bx}+\frac{a}{b^2}\ln\left|\frac{ax+b}{x}\right|+C$
7. $\int\frac{x}{(ax+b)^2}\mathrm{d}x=\frac{1}{a^2}\left(\ln|ax+b|+\frac{b}{ax+b}\right)+C$
8. $\int\frac{x^2}{(ax+b)^2}\mathrm{d}x=\frac{1}{a^3}\left(ax+b-2b\ln|ax+b|-\frac{b^2}{ax+b}\right)+C$
9. $\int\frac{\mathrm{d}x}{x(ax+b)^2}=\frac{1}{b(ax+b)}-\frac{1}{b^2}\ln\left|\frac{ax+b}{x}\right|+C$

■ $\sqrt{ax+b}$

1. $\int\sqrt{ax+b}\mathrm{d}x=\frac{2}{3a}\sqrt{(ax+b)^3}+C$
2. $\int x\sqrt{ax+b}\mathrm{d}x=\frac{2}{15a^2}(3ax-2b)\sqrt{(ax+b)^3}+C$
3. $\int x^2\sqrt{ax+b}\mathrm{d}x=\frac{2}{105a^3}(15a^2x^2-12abx+8b^2)\sqrt{(ax+b)^3}+C$
4. $\int\frac{x}{\sqrt{ax+b}}\mathrm{d}x=\frac{2}{3a^2}(ax-2b)\sqrt{ax+b}+C$
5. $\int\frac{x^2}{\sqrt{ax+b}}\mathrm{d}x=\frac{2}{15a^3}(3a^2x^2-4abx+8b^2)\sqrt{ax+b}+C$
6. $\int\frac{\mathrm{d}x}{x\sqrt{ax+b}}=\begin{cases}\frac{1}{\sqrt{b}}\ln\left|\frac{\sqrt{ax+b}-\sqrt{b}}{\sqrt{ax+b}+\sqrt{b}}\right|+C & (b>0)\\ \frac{2}{\sqrt{-b}}\arctan\sqrt{\frac{ax+b}{-b}}+C & (b<0)\end{cases}$
7. $\int\frac{\mathrm{d}x}{x^2\sqrt{ax+b}}=-\frac{\sqrt{ax+b}}{bx}-\frac{a}{2b}\int\frac{\mathrm{d}x}{x\sqrt{ax+b}}$
8. $\int\frac{\sqrt{ax+b}}{x}\mathrm{d}x=2\sqrt{ax+b}+b\int\frac{\mathrm{d}x}{x\sqrt{ax+b}}$
9. $\int\frac{\sqrt{ax+b}}{x^2}\mathrm{d}x=-\frac{\sqrt{ax+b}}{x}+\frac{a}{2}\int\frac{\mathrm{d}x}{x\sqrt{ax+b}}$

■ $x^2\pm a^2$

1. $\int\frac{\mathrm{d}x}{x^2+a^2}=\frac{1}{a}\arctan\frac{x}{a}+C$
2. $\int\frac{\mathrm{d}x}{(x^2+a^2)^n}=\frac{x}{2(n-1)a^2(x^2+a^2)^{n-1}}+\frac{2n-3}{2(n-1)a^2}\int\frac{\mathrm{d}x}{(x^2+a^2)^{n-1}}$
3. $\int\frac{\mathrm{d}x}{x^2-a^2}=\frac{1}{2a}\ln\left|\frac{x-a}{x+a}\right|+C$

■ $ax^2+b(a>0)$

1. $\int \frac{\mathrm{d}x}{ax^2+b} = \begin{cases} \frac{1}{\sqrt{ab}}\arctan\sqrt{\frac{a}{b}}x + C & (b>0) \\ \frac{1}{2\sqrt{-ab}}\ln\left|\frac{\sqrt{a}x-\sqrt{-b}}{\sqrt{a}x+\sqrt{-b}}\right| + C & (b<0) \end{cases}$

2. $\int \frac{x}{ax^2+b}\mathrm{d}x = \frac{1}{2a}\ln\left|ax^2+b\right| + C$

3. $\int \frac{x^2}{ax^2+b}\mathrm{d}x = \frac{x}{a} - \frac{b}{a}\int\frac{\mathrm{d}x}{ax^2+b}$

4. $\int \frac{\mathrm{d}x}{x(ax^2+b)} = \frac{1}{2b}\ln\frac{x^2}{|ax^2+b|} + C$

5. $\int \frac{\mathrm{d}x}{x^2(ax^2+b)} = -\frac{1}{bx} - \frac{a}{b}\int\frac{\mathrm{d}x}{ax^2+b}$

6. $\int \frac{\mathrm{d}x}{x^3(ax^2+b)} = \frac{a}{2b^2}\ln\frac{|ax^2+b|}{x^2} - \frac{1}{2bx^2} + C$

7. $\int \frac{\mathrm{d}x}{(ax^2+b)^2} = \frac{x}{2b(ax^2+b)} + \frac{1}{2b}\int\frac{\mathrm{d}x}{ax^2+b}$

■ $ax^2+bx+c(a>0)$

1. $\frac{\mathrm{d}x}{ax^2+bx+c} = \begin{cases} \frac{2}{\sqrt{4ac-b^2}}\arctan\frac{2ax+b}{\sqrt{4ac-b^2}} + C & (b^2<4ac) \\ \frac{1}{\sqrt{b^2-4ac}}\ln\left|\frac{2ax+b-\sqrt{b^2-4ac}}{2ax+b+\sqrt{b^2-4ac}}\right| + C & (b^2>4ac) \end{cases}$

2. $\int \frac{x}{ax^2+bx+c}\mathrm{d}x = \frac{1}{2a}\ln|ax^2+bx+c| - \frac{b}{2a}\int\frac{\mathrm{d}x}{ax^2+bx+c}$

■ $\sqrt{x^2+a^2}(a>0)$

1. $\int \frac{\mathrm{d}x}{\sqrt{x^2+a^2}} = \operatorname{arsh}\frac{x}{a} + C_1 = \ln(x+\sqrt{x^2+a^2}) + C$

2. $\int \frac{\mathrm{d}x}{\sqrt{(x^2+a^2)^3}} = \frac{x}{a^2\sqrt{x^2+a^2}} + C$

3. $\int \frac{x}{\sqrt{x^2+a^2}}\mathrm{d}x = \sqrt{x^2+a^2} + C$

4. $\int \frac{x}{\sqrt{(x^2+a^2)^3}}\mathrm{d}x = -\frac{1}{\sqrt{x^2+a^2}} + C$

5. $\int \frac{x^2}{\sqrt{x^2+a^2}}\mathrm{d}x = \frac{x}{2}\sqrt{x^2+a^2} - \frac{a^2}{2}\ln(x+\sqrt{x^2+a^2}) + C$

6. $\int \frac{x^2}{\sqrt{(x^2+a^2)^3}}\mathrm{d}x = -\frac{x}{\sqrt{x^2+a^2}} + \ln(x+\sqrt{x^2+a^2}) + C$

7. $\int \frac{\mathrm{d}x}{x\sqrt{x^2+a^2}} = \frac{1}{a}\ln\frac{\sqrt{x^2+a^2}-a}{|x|} + C$

8. $\int \frac{\mathrm{d}x}{x^2\sqrt{x^2+a^2}} = -\frac{\sqrt{x^2+a^2}}{a^2x} + C$

9. $\int \sqrt{x^2+a^2}\mathrm{d}x = \frac{x}{2}\sqrt{x^2+a^2} + \frac{a^2}{2}\ln(x+\sqrt{x^2+a^2}) + C$

10. $\int \sqrt{(x^2+a^2)^3}\mathrm{d}x = \frac{x}{8}(2x^2+5a^2)\sqrt{x^2+a^2} + \frac{3}{8}a^4\ln(x+\sqrt{x^2+a^2}) + C$

11. $\int x\sqrt{x^2+a^2}\mathrm{d}x = \frac{1}{3}\sqrt{(x^2+a^2)^3} + C$

12. $\int x^2\sqrt{x^2+a^2}\mathrm{d}x = \frac{x}{8}(2x^2+a^2)\sqrt{x^2+a^2} - \frac{a^4}{8}\ln(x+\sqrt{x^2+a^2}) + C$

13. $\int \frac{\sqrt{x^2+a^2}}{x}\mathrm{d}x = \sqrt{x^2+a^2} + a\ln\frac{\sqrt{x^2+a^2}-a}{|x|} + C$

14. $\int \frac{\sqrt{x^2+a^2}}{x^2}\mathrm{d}x = -\frac{\sqrt{x^2+a^2}}{x} + \ln(x+\sqrt{x^2+a^2}) + C$

■ $\sqrt{x^2-a^2}(a>0)$

1. $\int \frac{\mathrm{d}x}{\sqrt{x^2-a^2}} = \frac{x}{|x|}\operatorname{arch}\frac{|x|}{a} + C_1 = \ln\left|x+\sqrt{x^2-a^2}\right| + C$

2. $\int \frac{\mathrm{d}x}{\sqrt{(x^2-a^2)^3}} = -\frac{x}{a^2\sqrt{x^2-a^2}} + C$

3. $\int \frac{x}{\sqrt{x^2-a^2}}\mathrm{d}x = \sqrt{x^2-a^2} + C$

4. $\int \frac{x}{\sqrt{(x^2-a^2)^3}}\mathrm{d}x = -\frac{1}{\sqrt{x^2-a^2}} + C$

5. $\int \frac{x^2}{\sqrt{x^2-a^2}}\mathrm{d}x = \frac{x}{2}\sqrt{x^2-a^2} + \frac{a^2}{2}\ln|x+\sqrt{x^2-a^2}| + C$

6. $\int \frac{x^2}{\sqrt{(x^2-a^2)^3}}\mathrm{d}x = -\frac{x}{\sqrt{x^2-a^2}} + \ln|x+\sqrt{x^2-a^2}| + C$

7. $\int \frac{\mathrm{d}x}{x\sqrt{x^2-a^2}} = \frac{1}{a}\arccos\frac{a}{|x|} + C$

8. $\int \frac{\mathrm{d}x}{x^2\sqrt{x^2-a^2}} = \frac{\sqrt{x^2-a^2}}{a^2x} + C$

9. $\int \sqrt{x^2-a^2}\mathrm{d}x = \frac{x}{2}\sqrt{x^2-a^2} - \frac{a^2}{2}\ln|x+\sqrt{x^2-a^2}| + C$

10. $\int \sqrt{(x^2-a^2)^3}\mathrm{d}x = \frac{x}{8}(2x^2-5a^2)\sqrt{x^2-a^2} + \frac{3}{8}a^4\ln|x+\sqrt{x^2-a^2}| + C$

11. $\int x\sqrt{x^2-a^2}\mathrm{d}x = \frac{1}{3}\sqrt{(x^2-a^2)^3} + C$

12. $\int x^2\sqrt{x^2-a^2}\mathrm{d}x = \frac{x}{8}(2x^2-a^2)\sqrt{x^2-a^2} - \frac{a^4}{8}\ln|x+\sqrt{x^2-a^2}| + C$

13. $\int \frac{\sqrt{x^2-a^2}}{x}\mathrm{d}x = \sqrt{x^2-a^2} - a\arccos\frac{a}{|x|} + C$

14. $\int \frac{\sqrt{x^2-a^2}}{x^2}\mathrm{d}x = -\frac{\sqrt{x^2-a^2}}{x} + \ln|x+\sqrt{x^2-a^2}| + C$

■ $\sqrt{a^2-x^2}(a>0)$

1. $\int \frac{\mathrm{d}x}{\sqrt{a^2-x^2}} = \arcsin\frac{x}{a} + C$
2. $\frac{\mathrm{d}x}{\sqrt{(a^2-x^2)^3}} = \frac{x}{a^2\sqrt{a^2-x^2}} + C$
3. $\int \frac{x}{\sqrt{a^2-x^2}}\mathrm{d}x = -\sqrt{a^2-x^2} + C$
4. $\int \frac{x}{\sqrt{(a^2-x^2)^3}}\mathrm{d}x = \frac{1}{\sqrt{a^2-x^2}} + C$
5. $\int \frac{x^2}{\sqrt{a^2-x^2}}\mathrm{d}x = -\frac{x}{2}\sqrt{a^2-x^2} + \frac{a^2}{2}\arcsin\frac{x}{a} + C$
6. $\int \frac{x^2}{\sqrt{(a^2-x^2)^3}}\mathrm{d}x = \frac{x}{\sqrt{a^2-x^2}} - \arcsin\frac{x}{a} + C$
7. $\int \frac{\mathrm{d}x}{x\sqrt{a^2-x^2}} = \frac{1}{a}\ln\frac{a-\sqrt{a^2-x^2}}{|x|} + C$
8. $\int \frac{\mathrm{d}x}{x^2\sqrt{a^2-x^2}} = -\frac{\sqrt{a^2-x^2}}{a^2x} + C$
9. $\int \sqrt{a^2-x^2}\mathrm{d}x = \frac{x}{2}\sqrt{a^2-x^2} + \frac{a^2}{2}\arcsin\frac{x}{a} + C$
10. $\int \sqrt{(a^2-x^2)^3}\mathrm{d}x = \frac{x}{8}(5a^2-2x^2)\sqrt{a^2-x^2} + \frac{3}{8}a^4\arcsin\frac{x}{a} + C$
11. $\int x\sqrt{a^2-x^2}\mathrm{d}x = -\frac{1}{3}\sqrt{(a^2-x^2)^3} + C$
12. $\int x^2\sqrt{a^2-x^2}\mathrm{d}x = \frac{x}{8}(2x^2-a^2)\sqrt{a^2-x^2} + \frac{a^4}{8}\arcsin\frac{x}{a} + C$
13. $\int \frac{\sqrt{a^2-x^2}}{x}\mathrm{d}x = \sqrt{a^2-x^2} + a\ln\frac{a-\sqrt{a^2-x^2}}{|x|} + C$
14. $\int \frac{\sqrt{a^2-x^2}}{x^2}\mathrm{d}x = -\frac{\sqrt{a^2-x^2}}{x} - \arcsin\frac{x}{a} + C$

■ $\sqrt{\pm ax^2+bx+c}(a>0)$

1. $\int \frac{\mathrm{d}x}{\sqrt{ax^2+bx+c}} = \frac{1}{\sqrt{a}}\ln|2ax+b+2\sqrt{a}\sqrt{ax^2+bx+c}| + C$
2. $\int \sqrt{ax^2+bx+c}\mathrm{d}x = \frac{2ax+b}{4a}\sqrt{ax^2+bx+c} + \frac{4ac-b^2}{8\sqrt{a^3}}\ln|2ax+b+2\sqrt{a}\sqrt{ax^2+bx+c}| + C$
3. $\int \frac{x}{\sqrt{ax^2+bx+c}}\mathrm{d}x = \frac{1}{a}\sqrt{ax^2+bx+c} - \frac{b}{2\sqrt{a^3}}\ln|2ax+b+2\sqrt{a}\sqrt{ax^2+bx+c}| + C$
4. $\int \frac{\mathrm{d}x}{\sqrt{c+bx-ax^2}} = -\frac{1}{\sqrt{a}}\arcsin\frac{2ax-b}{\sqrt{b^2+4ac}} + C$
5. $\int \sqrt{c+bx-ax^2}\mathrm{d}x = \frac{2ax-b}{4a}\sqrt{c+bx-ax^2} + \frac{b^2+4ac}{8\sqrt{a^3}}\arcsin\frac{2ax-b}{\sqrt{b^2+4ac}} + C$
6. $\int \frac{x}{\sqrt{c+bx-ax^2}}\mathrm{d}x = -\frac{1}{a}\sqrt{c+bx-ax^2} + \frac{b}{2\sqrt{a^3}}\arcsin\frac{2ax-b}{\sqrt{b^2+4ac}} + C$

■ $\sqrt{\pm\frac{x-a}{x-b}}$ **or** $\sqrt{(x-a)(x-b)}$

1. $\int \sqrt{\frac{x-a}{x-b}}\mathrm{d}x = (x-b)\sqrt{\frac{x-a}{x-b}} + (b-a)\ln(\sqrt{|x-a|} + \sqrt{|x-b|}) + C$
2. $\int \sqrt{\frac{x-a}{b-x}}\mathrm{d}x = (x-b)\sqrt{\frac{x-a}{b-x}} + (b-a)\arcsin\sqrt{\frac{x-a}{b-x}} + C$
3. $\int \frac{\mathrm{d}x}{\sqrt{(x-a)(b-x)}} = 2\arcsin\sqrt{\frac{x-a}{b-x}} + C\ (a<b)$
4. $\int \sqrt{(x-a)(b-x)}\mathrm{d}x = \frac{2x-a-b}{4}\sqrt{(x-a)(b-x)} + \frac{(b-a)^2}{4}\arcsin\sqrt{\frac{x-a}{b-x}} + C, (a<b)$

■ **Exponentials**

1. $\int a^x\mathrm{d}x = \frac{1}{\ln a}a^x + C$
2. $\int \mathrm{e}^{ax}\mathrm{d}x = \frac{1}{a}a^{ax} + C$
3. $\int x\mathrm{e}^{ax}\mathrm{d}x = \frac{1}{a^2}(ax-1)a^{ax} + C$
4. $\int x^n\mathrm{e}^{ax}\mathrm{d}x = \frac{1}{a}x^n\mathrm{e}^{ax} - \frac{n}{a}\int x^{n-1}\mathrm{e}^{ax}\mathrm{d}x$
5. $\int xa^x\mathrm{d}x = \frac{x}{\ln a}a^x - \frac{1}{(\ln a)^2}a^x + C$
6. $\int x^na^x\mathrm{d}x = \frac{1}{\ln a}x^na^x - \frac{n}{\ln a}\int x^{n-1}a^x\mathrm{d}x$
7. $\int \mathrm{e}^{ax}\sin bx\mathrm{d}x = \frac{1}{a^2+b^2}\mathrm{e}^{ax}(a\sin bx - b\cos bx) + C$
8. $\int \mathrm{e}^{ax}\cos bx\mathrm{d}x = \frac{1}{a^2+b^2}\mathrm{e}^{ax}(b\sin bx + a\cos bx) + C$
9. $\int \mathrm{e}^{ax}\sin^n bx\mathrm{d}x = \frac{1}{a^2+b^2n^2}\mathrm{e}^{ax}\sin^{n-1}bx(a\sin bx - nb\cos bx) + \frac{n(n-1)b^2}{a^2+b^2n^2}\int \mathrm{e}^{ax}\sin^{n-2}bx\mathrm{d}x$
10. $\int \mathrm{e}^{ax}\cos^n bx\mathrm{d}x = \frac{1}{a^2+b^2n^2}\mathrm{e}^{ax}\cos^{n-1}bx(a\cos bx + nb\sin bx) + \frac{n(n-1)b^2}{a^2+b^2n^2}\int \mathrm{e}^{ax}\cos^{n-2}bx\mathrm{d}x$

■ **Logarithms**

1. $\int \ln x\mathrm{d}x = x\ln x - x + C$
2. $\int \frac{\mathrm{d}x}{x\ln x} = \ln\left|\ln x\right| + C$
3. $\int x^n\ln x\mathrm{d}x = \frac{1}{n+1}x^{n+1}(\ln x - \frac{1}{n+1}) + C$
4. $\int (\ln x)^n\mathrm{d}x = x(\ln x)^n - n\int (\ln x)^{n-1}\mathrm{d}x$
5. $\int x^m(\ln x)^n\mathrm{d}x = \frac{1}{m+1}x^{m+1}(\ln x)^n - \frac{n}{m+1}\int x^m(\ln x)^{n-1}\mathrm{d}x$

■ Trigonometric Functions

1. $\int \sin x \mathrm{d}x = -\cos x + C$
2. $\int \cos x \mathrm{d}x = \sin x + C$
3. $\int \tan x \mathrm{d}x = -\ln|\cos x| + C$
4. $\int \cot x \mathrm{d}x = \ln|\sin x| + C$
5. $\int \sec x \mathrm{d}x = \ln\left|\tan\left(\frac{\pi}{4} + \frac{x}{2}\right)\right| + C = \ln|\sec x + \tan x| + C$
6. $\int \csc x \mathrm{d}x = \ln\left|\tan\frac{x}{2}\right| + C = \ln|\csc x - \cot x| + C$
7. $\int \sec^2 x \mathrm{d}x = \tan x + C$
8. $\int \csc^2 x \mathrm{d}x = -\cot x + C$
9. $\int \sec x \tan x \mathrm{d}x = \sec x + C$
10. $\int \csc x \cot x \mathrm{d}x = -\csc x + C$
11. $\int \sin^2 x \mathrm{d}x = \frac{x}{2} - \frac{1}{4}\sin 2x + C$
12. $\int \cos^2 x \mathrm{d}x = \frac{x}{2} + \frac{1}{4}\sin 2x + C$
13. $\int \sin^n x \mathrm{d}x = -\frac{1}{n}\sin^{n-1} x \cos x + \frac{n-1}{n}\int \sin^{n-2} x \mathrm{d}x$
14. $\int \cos^n x \mathrm{d}x = \frac{1}{n}\cos^{n-1} x \sin x + \frac{n-1}{n}\int \cos^{n-2} x \mathrm{d}x$
15. $\int \frac{\mathrm{d}x}{\sin^n x} = -\frac{1}{n-1}\frac{\cos x}{\sin^{n-1} x} + \frac{n-2}{n-1}\int \frac{\mathrm{d}x}{\sin^{n-2} x}$
16. $\int \frac{\mathrm{d}x}{\cos^n x} = \frac{1}{n-1}\frac{\sin x}{\cos^{n-1} x} + \frac{n-2}{n-1}\int \frac{\mathrm{d}x}{\cos^{n-2} x}$
17.
$$\begin{aligned}
&\int \cos^m x \sin^n x \mathrm{d}x \\
=&\frac{1}{m+n}\cos^{m-1} x \sin^{n+1} x + \frac{m-1}{m+n}\int \cos^{m-2} x \sin^n x \mathrm{d}x \\
=&-\frac{1}{m+n}\cos^{m+1} x \sin^{n-1} x + \frac{n-1}{m+1}\int \cos^m x \sin^{n-2} x \mathrm{d}x
\end{aligned}$$
18. $\int \sin ax \cos bx \mathrm{d}x = -\frac{1}{2(a+b)}\cos(a+b)x - \frac{1}{2(a-b)}\cos(a-b)x + C$
19. $\int \sin ax \sin bx \mathrm{d}x = -\frac{1}{2(a+b)}\sin(a+b)x + \frac{1}{2(a-b)}\sin(a-b)x + C$
20. $\int \cos ax \cos bx \mathrm{d}x = \frac{1}{2(a+b)}\sin(a+b)x + \frac{1}{2(a-b)}\sin(a-b)x + C$
21. $\int \frac{\mathrm{d}x}{a+b\sin x} = \begin{cases} \frac{2}{\sqrt{a^2-b^2}}\arctan\frac{a\tan\frac{x}{2}+b}{\sqrt{a^2-b^2}} + C & (a^2 > b^2) \\ \frac{1}{\sqrt{b^2-a^2}}\ln\left|\frac{a\tan\frac{x}{2}+b-\sqrt{b^2-a^2}}{a\tan\frac{x}{2}+b+\sqrt{b^2-a^2}}\right| + C & (a^2 < b^2) \end{cases}$
22. $\int \frac{\mathrm{d}x}{a+b\cos x} = \begin{cases} \frac{2}{a+b}\sqrt{\frac{a+b}{a-b}}\arctan\left(\sqrt{\frac{a-b}{a+b}}\tan\frac{x}{2}\right) + C & (a^2 > b^2) \\ \frac{1}{a+b}\sqrt{\frac{a+b}{a-b}}\ln\left|\frac{\tan\frac{x}{2}+\sqrt{\frac{a+b}{b-a}}}{\tan\frac{x}{2}-\sqrt{\frac{a+b}{b-a}}}\right| + C & (a^2 < b^2) \end{cases}$
23. $\int \frac{\mathrm{d}x}{a^2\cos^2 x+b^2\sin^2 x} = \frac{1}{ab}\arctan\left(\frac{b}{a}\tan x\right) + C$
24. $\int \frac{\mathrm{d}x}{a^2\cos^2 x-b^2\sin^2 x} = \frac{1}{2ab}\ln\left|\frac{b\tan x+a}{b\tan x-a}\right| + C$
25. $\int x \sin ax \mathrm{d}x = \frac{1}{a^2}\sin ax - \frac{1}{a}x\cos ax + C$
26. $\int x^2 \sin ax \mathrm{d}x = -\frac{1}{a}x^2\cos ax + \frac{2}{a^2}x\sin ax + \frac{2}{a^3}\cos ax + C$
27. $\int x \cos ax \mathrm{d}x = \frac{1}{a^2}\cos ax + \frac{1}{a}x\sin ax + C$
28. $\int x^2 \cos ax \mathrm{d}x = \frac{1}{a}x^2\sin ax + \frac{2}{a^2}x\cos ax - \frac{2}{a^3}\sin ax + C$

■ Inverse Trigonometric Functions($a > 0$)

1. $\int \arcsin\frac{x}{a}\mathrm{d}x = x\arcsin\frac{x}{a} + \sqrt{a^2-x^2} + C$
2. $\int x\arcsin\frac{x}{a}\mathrm{d}x = (\frac{x^2}{2} - \frac{a^2}{4})\arcsin\frac{x}{a} + \frac{x}{4}\sqrt{x^2-x^2} + C$
3. $\int x^2\arcsin\frac{x}{a}\mathrm{d}x = \frac{x^3}{3}\arcsin\frac{x}{a} + \frac{1}{9}(x^2+2a^2)\sqrt{a^2-x^2} + C$
4. $\int \arccos\frac{x}{a}\mathrm{d}x = x\arccos\frac{x}{a} - \sqrt{a^2-x^2} + C$
5. $\int x\arccos\frac{x}{a}\mathrm{d}x = (\frac{x^2}{2} - \frac{a^2}{4})\arccos\frac{x}{a} - \frac{x}{4}\sqrt{a^2-x^2} + C$
6. $\int x^2\arccos\frac{x}{a}\mathrm{d}x = \frac{x^3}{3}\arccos\frac{x}{a} - \frac{1}{9}(x^2+2a^2)\sqrt{a^2-x^2} + C$
7. $\int \arctan\frac{x}{a}\mathrm{d}x = x\arctan\frac{x}{a} - \frac{a}{2}\ln(a^2+x^2) + C$
8. $\int x\arctan\frac{x}{a}\mathrm{d}x = \frac{1}{2}(a^2+x^2)\arctan\frac{x}{a} - \frac{a}{2}x + C$
9. $\int x^2\arctan\frac{x}{a}\mathrm{d}x = \frac{x^3}{3}\arctan\frac{x}{a} - \frac{a}{6}x^2 + \frac{a^3}{6}\ln(a^2+x^2) + C$

7.3 Primes

100003, 200003, 300007, 400009, 500009, 600011, 700001, 800011, 900001,
1000003, 2000003, 3000017, 4100011, 5000011, 8000009, 9000011,
10000019, 20000003, 50000017, 50100007,
100000007, 100200011, 200100007, 250000019

7.4 Vimrc

```
set smartindent
set cindent
set number
set st=4
set ts=4
set sw=4
map <F9> :w<cr>:!g++ % -o %< -g -Wall<cr>
map <C-F9> :!time ./%<<cr>
map <F4> :w<cr>:!gedit %<cr>
set smarttab
set nowrap
```

7.5 Makefile

```
all : prog

prog : prog.cpp
g++ -o prog -g prog.cpp -Wall
```

7.6 Java Fast IO

```java
import java.io.*;
import java.util.*;
import java.math.*;
public class Main {
  public static void main(String[] args) {
    InputStream inputStream = System.in;
    OutputStream outputStream = System.out;
    InputReader in = new InputReader(inputStream);
    PrintWriter out = new PrintWriter(outputStream);
    int tests = in.nextInt();
    for (int noT = 1; noT <= tests && in.hasNext(); ++noT) (new Task()).solve(noT,
      in, out);
    out.close();
  }
}
class Task {
  public void solve(int testNumber, InputReader in, PrintWriter out) {
    // Implementation here.
  }
}
class InputReader {
  BufferedReader reader;
  StringTokenizer tokenizer;
  public InputReader(InputStream stream) {
    reader = new BufferedReader(new InputStreamReader(stream));
    tokenizer = null;
  }
  public boolean hasNext() {
    while (tokenizer == null || !tokenizer.hasMoreTokens()) {
      try {
        tokenizer = new StringTokenizer(reader.readLine());
      } catch (Exception e) {
        return false;
      }
    }
    return tokenizer.hasMoreTokens();
  }
  public String next() {
    while (tokenizer == null || !tokenizer.hasMoreTokens()) {
      try {
        tokenizer = new StringTokenizer(reader.readLine());
      } catch (Exception e) {
        throw new RuntimeException(e);
      }
    }
    return tokenizer.nextToken();
  }
}
import java.*;
import java.math.*;
import java.util.*;
public class Main
{
  public static Scanner cin = new Scanner(System.in);
  public static void main(String[] args)
  {
    int n = cin.nextInt();
    BigInteger a[] = new BigInteger[200];
    for (int i = 1; i <= n; i++)
    {
      BigInteger k = cin.nextBigInteger();
      System.out.print("Case "+i+": ");
      a[0] = BigInteger.valueOf(1);
      for (int j = 1; j < 75; j++)
        a[j] = a[j-1].multiply(k);
      BigInteger ans = a[74];
      ans = ans.add(a[38].multiply(BigInteger.valueOf(9)));
      ans = ans.add(a[20].multiply(BigInteger.valueOf(6)));
      ans = ans.add(a[26].multiply(BigInteger.valueOf(8)));
      ans = ans.divide(BigInteger.valueOf(24));
```

```
      ans = ans.mod(BigInteger.valueOf(10007));
      System.out.println(ans);
    }
  }
}
```

7.7 Java Evaluate

```
import javax.script.ScriptEngineManager;
import javax.script.ScriptEngine;
public class Main {
  public static void main(String[] args) throws Exception {
    ScriptEngineManager mgr = new ScriptEngineManager();
    ScriptEngine engine = mgr.getEngineByName("JavaScript");
    String foo = "3+4";
    System.out.println(engine.eval(foo));
  }
}
```