

Discussion 11: Dynamic Programming I

(CS101 Fall 2024)

CS101 Course Team

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Recall: Bellman-Ford is dp

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What will happen if we use a scroll array?

Algorithmic paradigms

- **Greedy:** Build up a solution incrementally, myopically optimizing some local criterion.
- **Divide and conquer:** Break up a problem into a few sub-problems, solve each sub-problem independently and recursively, and combine solutions to sub-problems to form a solution to the original problem.
- **Dynamic programming:** Break up a problem into a series of overlapping sub-problems, and build up solutions to larger and larger sub-problems.
 - Very powerful and widely used technique in CS, info, and control theory.
 - Efficiently solves problems that otherwise seem intractable.
 - Name comes from the dynamic “schedule” of subproblems the algorithm produces.

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- If a_i can be joined with the previous subarray: $f_{i-1} + a_i$
- Otherwise, a_i will "be the header of subarray: a_i
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- Very simple! It's like another formulate of recursion. $\Theta(n)$.

Longest Increasing Subsequence

Given a sequence $\langle a_0, a_1, \dots, a_{n-1} \rangle$, find the longest subsequence $a_{s_0}, a_{s_1}, \dots, a_{s_{k-1}}$ ($s_0 < s_1 < \dots < s_{k-1}$) such that $a_{s_0} \leq a_{s_1} \leq \dots \leq a_{s_{k-1}}$.

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- Compared to the previous subproblem, the additional information is a_i .
- Consider the impact of a_i : it may or may not be in the longest increasing subsequence.
 - If not, then the answer is f_{i-1} .
 - If it is, then whom does it follow? How do you know if it can follow?

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- What's the time complexity?

0-1 Knapsack problem

There are n items: item i provides value $v_i > 0$ and weights $w_i > 0$. The knapsack has a weight capacity of W . How do you choose the item packed into the knapsack to maximize the sum of values?

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- Otherwise, we won't choose this item. That is

$$f(i - 1, j)$$

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$$f(i, j) = \begin{cases} \max\{f(i-1, j-w_i) + v_i, f(i-1, j)\}, & \text{if } w_i \leq j, \\ f(i-1, j), & \text{otherwise.} \end{cases}$$

- totally $\Theta(nW)$ state of f .
- Time complexity and space complexity if $\Theta(nW)$.
- Rotate the array: $f(i, \cdot)$ only depends on $f(i-1, \cdot)$. Then we can implement our algorithm in $O(W)$ space complexity.

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- W ? Knapsack is not a polynomial time problem! We will learn that this is an NPC problem.

Idea: DP is a state transfer graph.

- Consider every (i, j) is a point: There are an edge from $(i - 1, j - w_i)$ to (i, j) with edge weight v_i .
- The problem transferred to the longest-path problem.
- And mention that: this graph is a DAG! So do topological sort.
- Many DP problems can be transferred into a state transfer graph: every state can be formulated as a vertex, and the edge represents the transfer between statuses.

Complete Knapsack problem

Similar to the 0-1 knapsack problem: in the 0-1 backpack problem, every item can be selected only once. For the complete knapsack problem: it can be selected multiple times.

- Basic Idea: for item i , enumerate how many items are selected:

$$f(i, j) = \max_k \{f(i-1, j - kw_i) + kv_i\}.$$

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- Why?

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- Why?
- The reason is that, when we make this transition, $f_{i, j-w_i}$ has already been updated by $f_{i, j-2 \times w_i}$. Thus, $f_{i, j-w_i}$ fully considers the optimal result after choosing the i -th item.
- In other words, we optimize the complexity of the knapsack problem by reusing the previous knapsack results through the property of local optimal substructure.

DP problems

Requirements

- No aftereffect: Decisions after won't be affected by decisions and state before.
- Optimal substructures: Subproblem optimal \rightarrow Problem optimal.

Three Main Components of DP

- State (together with subproblems): Different (subsets of) problems.
- Transitions: The way to transfer between states.
- Initial states

Frame Title

- Structure of States(Subproblems).
 - Euclidean (1D,2D,...) OPT(i) (e.g. Weighted Interval Scheduling, Maximum Subarray), OPT(i,j) (e.g. Knapsack, Min Cost Refueling, LCS)
 - Tree/DAG (e.g. Critical Path, not required in CS101)
 - Subsets
- Structure of Transitions.
 - Linear Choice (e.g. Weighted Interval Scheduling, Knapsack, LCS)
 - Multiple Choices (e.g. House Coloring, Odd Numbers Coin Changing)
 - Interval Choices (e.g. Segmented Least Squares, Max Power)
- States and subproblems.
 - Exactly subproblem: (e.g. Exact Knapsack)
 - Intervals of subproblems: (e.g. Knapsack, LCS)