

SI251 - Convex Optimization homework 2

Deadline: 2024-4-10 23:59:59

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2. The **report** has to be submitted as a PDF file to Gradescope, other formats are not accepted.
3. The submitted file name is **student_id+your_student_name.pdf**.
4. Late policy: You have 4 free late days for the quarter and may use up to 2 late days per assignment with no penalty. Once you have exhausted your free late days, we will deduct a late penalty of 25% per additional late day. Note: The timeout period is recorded in days, even if you delay for 1 minute, it will still be counted as a 1 late day.
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1. **(50 pts) Robust quadratic programming.** In the lecture, we have learned about robust linear programming as an application of second-order cone programming. Now we will consider a similar robust variation of the convex quadratic program

$$\begin{aligned} & \text{minimize} && (1/2)x^T P x + q^T x + r \\ & \text{subject to} && A x \preceq b. \end{aligned}$$

For simplicity, we assume that only the matrix P is subject to errors, and the other parameters (q, r, A, b) are exactly known. The robust quadratic program is defined as

$$\begin{aligned} & \text{minimize} && \sup_{P \in \mathcal{E}} ((1/2)x^T P x + q^T x + r) \\ & \text{subject to} && A x \preceq b \end{aligned}$$

where \mathcal{E} is the set of possible matrices P .

For each of the following sets \mathcal{E} , express the robust QP as a convex problem in a standard form (e.g., QP, QCQP, SOCP, SDP).

- (a) A finite set of matrices: $\mathcal{E} = \{P_1, \dots, P_K\}$, where $P_i \in S_+^n, i = 1, \dots, K$.
 (b) A set specified by a nominal value $P_0 \in S_+^n$ plus a bound on the eigenvalues of the deviation $P - P_0$:

$$\mathcal{E} = \{P \in \mathbf{S}^n \mid -\gamma I \preceq P - P_0 \preceq \gamma I\}$$

where $\gamma \in \mathbf{R}$ and $P_0 \in \mathbf{S}_+^n$.

- (c) An ellipsoid of matrices:

$$\mathcal{E} = \left\{ P_0 + \sum_{i=1}^K P_i u_i \mid \|u\|_2 \leq 1 \right\}.$$

You can assume $P_i \in \mathbf{S}_+^n, i = 0, \dots, K$.

Solution:

- (a) The objective function is a maximum of convex function, hence convex.

We can write the problem as

$$\begin{aligned} & \text{minimize} && t \\ & \text{subject to} && (1/2)x^T P_i x + q^T x + r \leq t, \quad i = 1, \dots, K \\ & && A x \preceq b, \end{aligned}$$

which is a QCQP in the variables x and t .

- (b) For given x , the supremum of $x^T \Delta P x$ over $-\gamma I \preceq \Delta P \preceq \gamma I$ is given by

$$\sup_{-\gamma I \preceq \Delta P \preceq \gamma I} x^T \Delta P x = \gamma x^T x$$

Therefore we can express the robust QP as

$$\begin{aligned} & \text{minimize} && (1/2)x^T (P_0 + \gamma I) x + q^T x + r \\ & \text{subject to} && A x \preceq b \end{aligned}$$

which is a QP.

(c) For given x , the quadratic objective function is

$$\begin{aligned} & (1/2) \left(x^T P_0 x + \sup_{\|u\|_2 \leq 1} \sum_{i=1}^K u_i (x^T P_i x) \right) + q^T x + r \\ & = (1/2) x^T P_0 x + (1/2) \left(\sum_{i=1}^K (x^T P_i x)^2 \right)^{1/2} + q^T x + r. \end{aligned}$$

This is a convex function of x : each of the functions $x^T P_i x$ is convex since $P_i \succeq 0$. The second term is a composition $h(g_1(x), \dots, g_K(x))$ of $h(y) = \|y\|_2$ with $g_i(x) = x^T P_i x$. The functions g_i are convex and nonnegative. The function h is convex and, for $y \in \mathbf{R}_+^K$, nondecreasing in each of its arguments. Therefore the composition is convex. The resulting problem can be expressed as

$$\begin{aligned} & \text{minimize} && (1/2) x^T P_0 x + \|y\|_2 + q^T x + r \\ & \text{subject to} && (1/2) x^T P_i x \leq y_i, \quad i = 1, \dots, K \\ & && Ax \preceq b \end{aligned}$$

which can be further reduced to a SOCP

$$\begin{aligned} & \text{minimize} && u + t \\ & \text{subject to} && \left\| \begin{bmatrix} P_0^{1/2} x \\ 2u - 2q^T x - 1/4 \end{bmatrix} \right\|_2 \leq 2u - 2q^T x + 1/4 \\ & && \left\| \begin{bmatrix} P_i^{1/2} x \\ 2y_i - 1/4 \end{bmatrix} \right\|_2 \leq 2y_i + 1/4, \quad i = 1, \dots, K \\ & && \|y\|_2 \leq t \\ & && Ax \preceq b. \end{aligned}$$

The variables are x, u, t , and $y \in \mathbf{R}^K$. Note that if we square both sides of the first inequality, we obtain

$$x^T P_0 x + (2u - 2q^T x - 1/4)^2 \leq (2u - 2q^T x + 1/4)^2,$$

i.e., $x^T P_0 x + 2q^T x \leq 2u$. Similarly, the other constraints are equivalent to $(1/2)x^T P_i x \leq y_i$.

2. **(50 pts) Water-filling.** Please consider the convex optimization problem and calculate its solution

$$\begin{aligned} & \text{minimize} && -\sum_{i=1}^n \log(\alpha_i + x_i) \\ & \text{subject to} && x \succeq 0, \quad \mathbf{1}^T x = 1, \end{aligned}$$

Solution:

Introducing Lagrange multipliers $\lambda^* \in \mathbf{R}^n$ for the inequality constraints $x^* \succeq 0$, and a multiplier $\nu^* \in \mathbf{R}$ for the equality constraint $\mathbf{1}^T x = 1$, we obtain the KKT conditions

$$\begin{aligned} & x^* \succeq 0, \quad \mathbf{1}^T x^* = 1, \quad \lambda^* \succeq 0, \quad \lambda_i^* x_i^* = 0, \quad i = 1, \dots, n, \\ & -1/(\alpha_i + x_i^*) - \lambda_i^* + \nu^* = 0, \quad i = 1, \dots, n. \end{aligned}$$

We can directly solve these equations to find x^*, λ^* , and ν^* . We start by noting that λ^* acts as a slack variable in the last equation, so it can be eliminated, leaving

$$\begin{aligned} & x^* \succeq 0, \quad \mathbf{1}^T x^* = 1, \quad x_i^* (\nu^* - 1/(\alpha_i + x_i^*)) = 0, \quad i = 1, \dots, n \\ & \nu^* \geq 1/(\alpha_i + x_i^*), \quad i = 1, \dots, n. \end{aligned}$$

If $\nu^* < 1/\alpha_i$, this last condition can only hold if $x_i^* > 0$, which by the third condition implies that $\nu = 1/(\alpha_i + x_i^*)$. Solving for x_i^* , we conclude that $x_i^* = 1/\nu^* - \alpha_i$ if $\nu^* < 1/\alpha_i$. If $\nu^* \geq 1/\alpha_i$, then $x_i^* > 0$ is impossible, because it would imply $\nu^* \geq 1/\alpha_i > 1/(\alpha_i + x_i^*)$, which violates the complementary slackness condition. Therefore, $x_i^* = 0$ if $\nu^* \geq 1/\alpha_i$. Thus we have

$$x_i^* = \begin{cases} 1/\nu^* - \alpha_i & \nu^* < 1/\alpha_i \\ 0 & \nu^* \geq 1/\alpha_i, \end{cases}$$

or, put more simply, $x_i^* = \max\{0, 1/\nu^* - \alpha_i\}$. Substituting this expression for x_i^* into the condition $\mathbf{1}^T x^* = 1$ we obtain

$$\sum_{i=1}^n \max\{0, 1/\nu^* - \alpha_i\} = 1.$$

The lefthand side is a piecewise-linear increasing function of $1/\nu^*$, with breakpoints at α_i , so the equation has a unique solution which is readily determined.