Linear Algebra Tutorial 11

2023.12.19

homework

Find the standard matrix for the stated composition in \mathbb{R}^3 .

- 1. (2 points) A rotation of $\frac{\pi}{6}$ about the positive x-axis, followed by a rotation of $\frac{\pi}{6}$ about the positive z-axis, followed by a contraction with factor k = 1/4.
- 2. (2 points) A reflection about the xy-plane, followed by a reflection about the xz-plane, followed by an orthogonal projection onto the yz-plane.
- 3. (2 points) A rotation of $\frac{3\pi}{2}$ about the positive x-axis, followed by a rotation of $\frac{\pi}{4}$ about the positive y-axis, followed by a rotation of π about the z-axis.

theorem

Theorem 4.51. 令 $V = \mathbb{R}^n$, $W = \mathbb{R}^m$, $T : \mathbb{R}^n \to \mathbb{R}^m$ 为线性变换, $[T] \in M_{m \times n}$ 为T的 标准矩阵。那么我们有

- 1. Ker(T) = Null([T]);
- 2. RAN(T) = Col([T]);
- 3. T是单射当且仅当 $Ker(T) = Null([T]) = \{0\}$, 当且仅当nullity([T]) = 0;
- 4. T是满射当且仅当 $Col([T]) = \mathbb{R}^m$, 当且仅当rank([T]) = m;
- 5. 如果m=n, 那么 $T:\mathbb{R}^n\to\mathbb{R}^n$ 为双射当且仅当[T]可逆, 当且仅当T是单射, 当且仅当T是满射。

homework

Problem D(6 Points)

判断以下说法是否正确。如果正确写出证明,如果错误举出反例。

- 1. (2 points) 如果n > m,那么任何矩阵变换 $T : \mathbb{R}^n \to \mathbb{R}^m$ 都不可能是一一映射(one-to-one)。
- 2. (2 points) 如果n < m,那么任何矩阵变换 $T : \mathbb{R}^n \to \mathbb{R}^m$ 都不可能是满射(surjective, onto),即不可能有 $R(T) = \mathbb{R}^m$ 。
- 3. (2 points) 令 $V = C^{1}(-\infty, \infty)$ 为所有连续可微函数的集合,令 $W = C(-\infty, \infty)$ 为所有连续函数的集合,令 $D: V \to W$ 为求导运算**:** D(f(x)) = f'(x)。那么D即是一一映射又是满射。
 - 如果 $\dim(V) > \dim(W)$,那么T必然不可能是——映射.
 - 如果 $\dim(V) < \dim(W)$,那么T必然不可能是满射.

homework

 \boldsymbol{E}

2. (3 points) Let U, V, W be vector spaces and let $T: V \to W, S: W \to U$ be linear transformations. Prove that $\operatorname{rank}(S \circ T) \leq \min(\operatorname{rank}(S), \operatorname{rank}(T)), \operatorname{rank}(S \circ T) = \operatorname{rank}(S)$ if T is surjective, $\operatorname{rank}(S \circ T) = \operatorname{rank}(T)$ if S is one-to-one.

one-to-one / injective

$$f(x_1)=f(x_2)\Rightarrow x_1=x_2$$

只有——映射才存在逆映射(反函数)

T:V o W is one-to-one $\Leftrightarrow T^{-1}$ exists

$$T^{-1}:R(T) o V$$

• onto / surjective

$$T:V o W$$
 is onto $\Leftrightarrow R(T)=W$

• bijective = injective + surjective

• 矩阵变换要从右往左看

$$T(\mathbf{x}) = (T_3(T_2(T_1(\mathbf{x})))) = (T_3 \circ T_2 \circ T_1)(\mathbf{x}) \ [T] = [T_3][T_2][T_1]$$

- $T: \mathbb{R}^n \to \mathbb{R}^m$ $[T] \in M_{m \times n}$ $\mathbf{y} = T(\mathbf{x}) = [T]\mathbf{x}, \mathbf{x} \in \mathbb{R}^n, \mathbf{y} \in \mathbb{R}^m$ 所以在使用rank-nullity theorem时, 注意是rank([T]) + nullity([T]) = n
- $T:V\to W$, W 为T的到达域(codomain),而不是值域(range)原因: T不一定是满射
 - T的值域(range)是W的子集

Linear transformation

T:V o W is linear transformation

Kernel

$$Ker(T): \{v \in V | T(v) = 0\}$$
 $Ker(T) \subseteq V$ is a subspace of V $Ker(T) \Leftrightarrow Null([T])$

range

$$RAN(T)/R(T): \{w \in W | w = T(v), v \in V\}$$
 $R(T) \subseteq W$ is a subspace of W $R(T) \Leftrightarrow Col([T])$

• $\dim(Ker(T)) + \dim(R(T)) = \dim(V)$

Isomorphism (同构)

- T:V o W is bijective linear transformation 双射的线性变换
- 则称T是一个同构 (isomorphism)
- V和W是同构的 (isomorphic)
- V和 W 是同构的 $\Leftrightarrow \dim(V) = \dim(W)$

Isomorphism (同构)

prove $T:V \to W$ is isomorphism:

• T is linear transform

$$T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$$

 $T(k\mathbf{u}) = kT(\mathbf{u})$

● *T* is bijective(双射)
injective(单射/——映射) + onto(满射)

orall V, if $\dim(V)=n\Rightarrow V,\mathbb{R}^n$ are isomorphic

Isomorphism (同构)

T:V o W is a linear transformation, $\dim(V) = \dim(W) = n$ equivalent statements:

- T is injective
- *T* is onto
- T is isomorphism
- $Ker(T) = \{0\}$
- R(T) = W

$$n = \dim(V) = rank(T) + nullity(T).$$

Inverse Transformations(逆映射)

T:V o W is a linear transformation, and T is injective/one-to-one (单射/——映射) 那么存在一个逆映射 $T^{-1}:R(T) o V$ 使得

- $T(\mathbf{v}) = \mathbf{w} \Leftrightarrow T^{-1}(\mathbf{w}) = \mathbf{v}$
- $ullet (T^{-1}\circ T)(\mathbf{v})=\mathbf{v},\mathbf{v}\in V$
- $ullet (T\circ T^{-1})(\mathbf{w})=\mathbf{w},\mathbf{w}\in R(T)$
- \bullet $\,T^{-1}$ is linear transformation, T^{-1} is onto and T^{-1} is one-to-one So R(T), V are isomorphic

Inverse Transformations(逆映射)

 $T_1:U o V$ and $T_2:V o W$ are injective

- $T_2 \circ T_1$ is injective
- ullet $(T_2\circ T_1)^{-1}:R(T_2\circ T_1) o U$ has inverse transformation $(T_2\circ T_1)^{-1}=T_1^{-1}\circ T_2^{-1}$

Matrices for general linear transformations

(线性变换的矩阵表示)

$$\mathbf{v} \in V \xrightarrow{T} T(\mathbf{v}) \in W$$

$$\downarrow^{f_B} \qquad \downarrow^{g_{B'}}$$

$$([\mathbf{v}]_B \in \mathbb{R}^n) \xrightarrow{T_A} ([T(\mathbf{v})]_{B'} \in \mathbb{R}^m)$$

- f_B : 将**v**转换成以B为基的坐标
- $g_{B'}$: 将 $T(\mathbf{v})$ 转换成以B'为基的坐标
- $T_A: \mathbb{R}^n \to \mathbb{R}^m$ 的线性变换

$$T_A(\mathbf{x}) = A\mathbf{x}$$
, s.t. $[T(\mathbf{v})]_{B'} = A[\mathbf{v}]_B = [T]_{B',B}[\mathbf{v}]_B$

Matrices for general linear transformations

为T关于基底B与B'的矩阵表示 (The matrix for T relative to B and B')

$$egin{aligned} T_A &\Rightarrow [T]_{B',B} \ B &= \{\mathbf{v}_1,\mathbf{v}_2,\cdots,\mathbf{v}_n\}, \, B' = \{\mathbf{w}_1,\mathbf{w}_2,\cdots,\mathbf{w}_m\} \ [T_A(\mathbf{v})]_{B'} &= [T]_{B',B}[\mathbf{v}]_B \ [T]_{B',B} &= [[T(\mathbf{v}_1)]_{B'} \, \cdots \, [T(\mathbf{v}_n)]_{B'}] \end{aligned}$$

Matrices for general linear transformations

Let V be the subspace in $F(-\infty, \infty)$ spanned by $B = \{\sin x, \cos x\}$. Let $T: V \to \mathbb{R}^2$ be defined by $T(f) = (f(0), f(\frac{\pi}{2}))$ for $f \in V$. Take $B' = \{(1,0), (0,1)\}$ as a basis of \mathbb{R}^2 . Then the matrix for T relative to B and B' is

$$[T]_{B',B} = ?$$