

# Learning Methods

Transfer Learning, Meta Learning, Domain Adaptation

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# **Learning Methods**



- Motivation
- Transfer Learning
- Meta Learning
- Domain Adaptation
- Summary



### Motivation

# Motivation



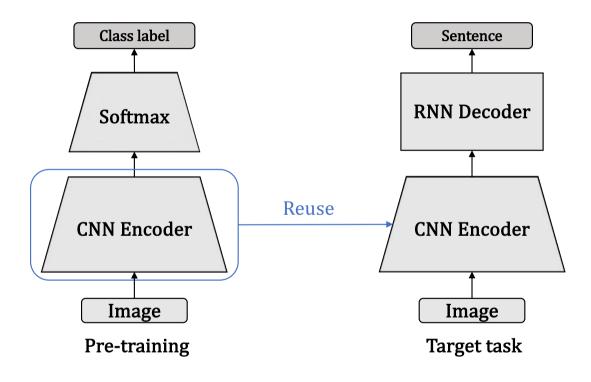




• Transfer learning, also known as inductive transfer, utilises the knowledge of one task and applies it to **related tasks**. In deep learning, pre-trained models are widely used for improving the performance of many tasks without labelling more data. The idea is to train a network on a large dataset with a general task and reuse the network for another network with the target task. **This transfer tends to work if the datasets include common features**.



Reuse Model



- OpenPose
- Show and Tell
- Word2Vec
- GloVe
- •••

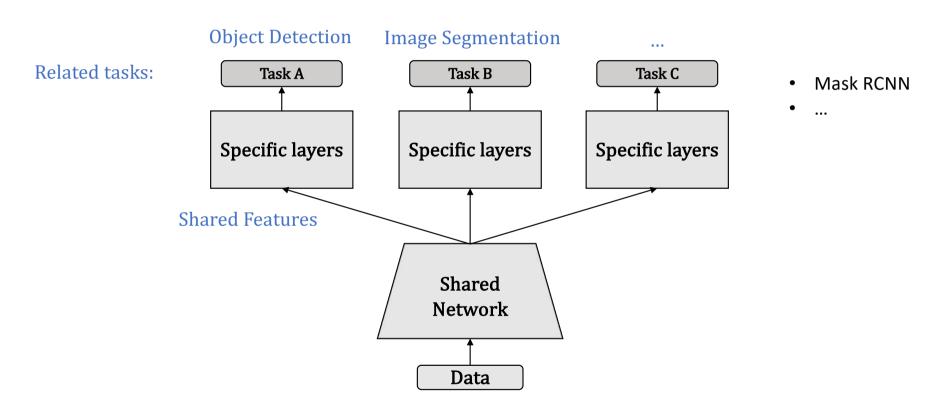
Related tasks:

**Image Classification** 

**Image Captioning** 



Multi-task Learning





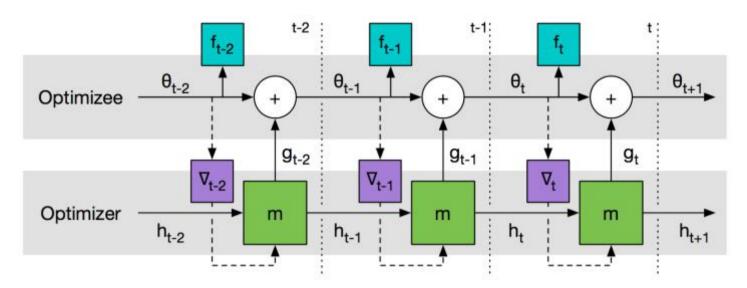


• Meta learning focuses on learning the learning process, i.e., learn to learn



### Predicting gradients

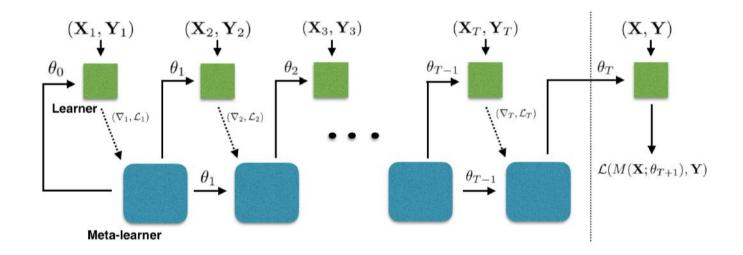
Train an extra network to predict the gradients in supervised way.





### Predicting parameters

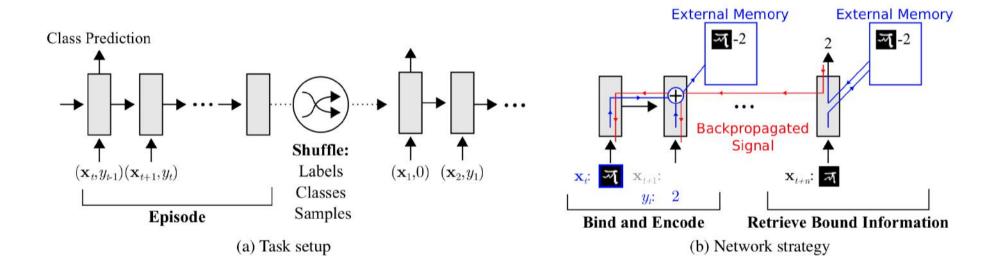
Train a LSTM network to predict the parameter of the next update





#### Memory based methods

Feed the previous output to the model and store the information in an external memory.

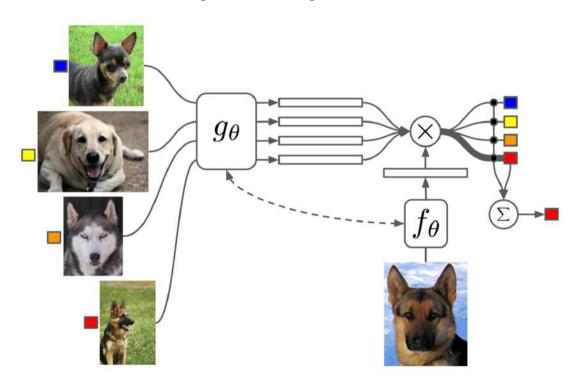


Meta-Learning with Memory-Augmented Neural Networks. *Adam Santoro, Sergey Bartunov, et al.* ICML, 2016. Meta Networks. *Munkhdalai T, Yu H.* arXiv:1703.00837, 2017.



#### Memory based methods

Feed the previous output to the model and store the information in an external memory.



The output label is obtained by "attention"

$$ar{y} = \sum_{i=1}^k a(ar{x}, x_i) y_i$$

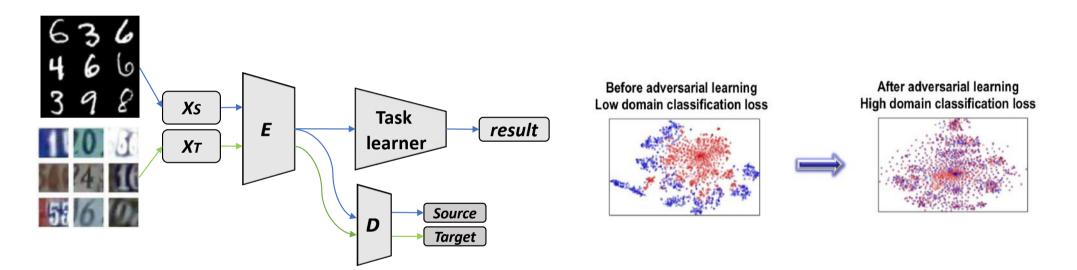




- Domain adaptation learns from a source data distribution and perform well on a different but related target data distribution.
- vs. Transfer Learning: Domain adaptation does not need labels for the target domain.



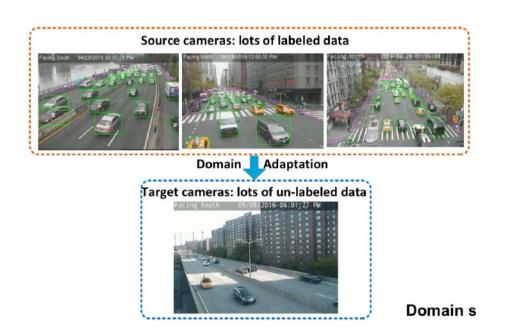
• Single Source

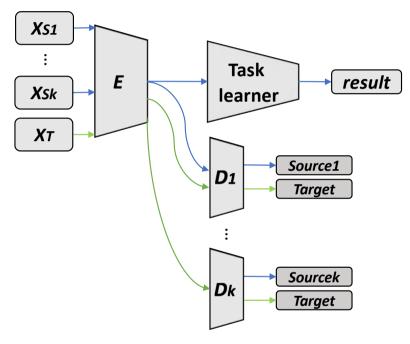


Source images have label
Target images do not have label



Multi-source





Source images have label Target images do not have label



#### Example: Learn Edge, Depth, and Surface Normal

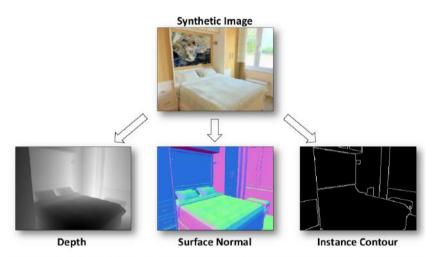


Figure 1. **Main idea.** A graphics engine can be used to easily render realistic synthetic images together with their various physical property maps. Using these images, we train a self-supervised visual representation learning algorithm in a multi-task setting that also adapts its features to real-world images.

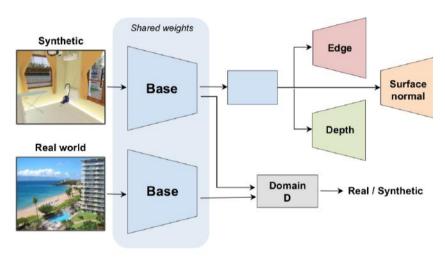
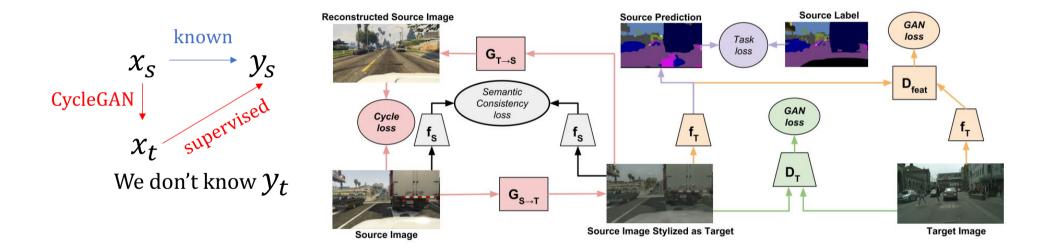


Figure 2. **Network architecture.** The upper net takes a synthetic image and predicts its depth, surface normal, and instance contour map. The bottom net extracts features from a real-world image. The domain discriminator D tries to differentiate real and synthetic features. The learned blue modules are used for transfer learning on real-world tasks.



Example: Learn Segmentation and Image-to-Image Translation





# Summary



## **Summary**

- Motivation
  - Time-series data
- Transfer Learning
  - one-hot vector, BOW, word embedding, Word2Vec, CBOW, Skip-Gram, negative sampling, NCE
- Meta Learning
  - one-to-many, many-to-one, asynchronous many-to-many, synchronous many-to-many
- Domain Adaptation
  - Hidden vector (state), long-term dependency problem



# Summary

- References
  - IJCAI13: Transfer Learning with Applications http://ijcai13.org/files/tutorial\_slides/td2.pdf

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# Summary

- Exercise 1: (Optional)
  - Reimplement "Domain-Adversarial Training of Neural Networks"

Link: https://github.com/zsdonghao/deep-learning-note/



# Questions?