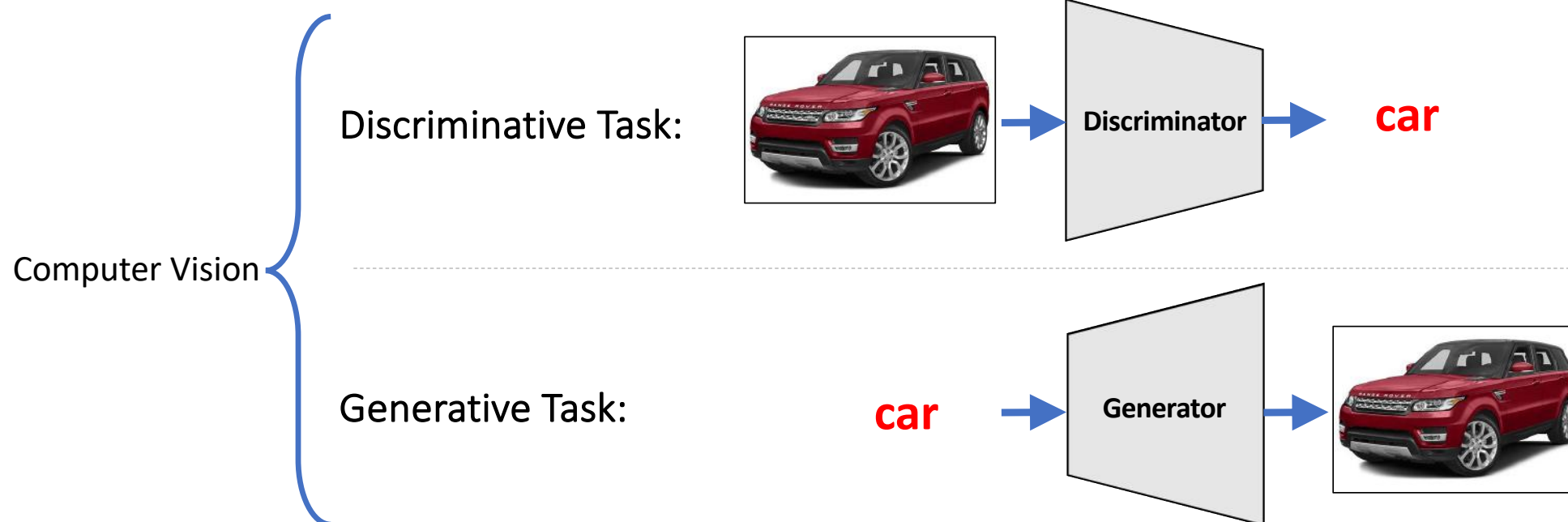


# Introduction of Generative Adversarial Networks

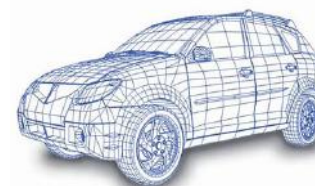
Hao Dong

2019 April 24

Peking University



Computer Graphic:

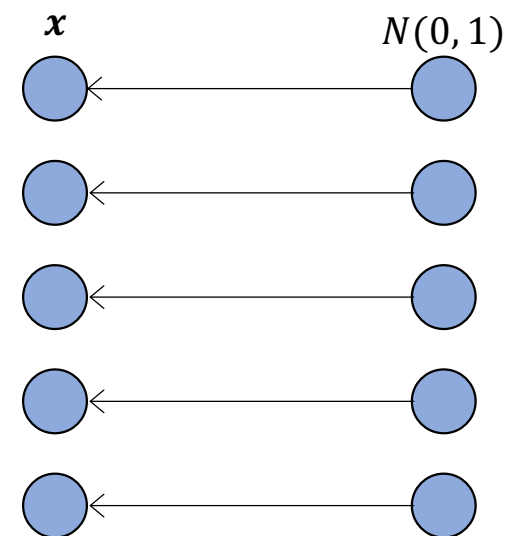
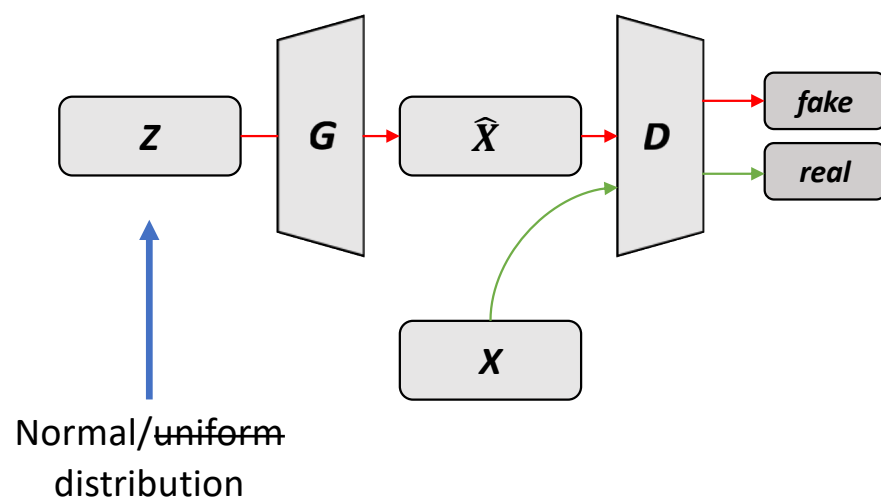


# Introduction of Generative Adversarial Networks (GAN)

- Vanilla GAN
- GAN with Encoder
- Summary

# Vanilla GAN

# Vanilla GAN



Unidirectional Mapping

**GAN: map a distribution to another distribution**

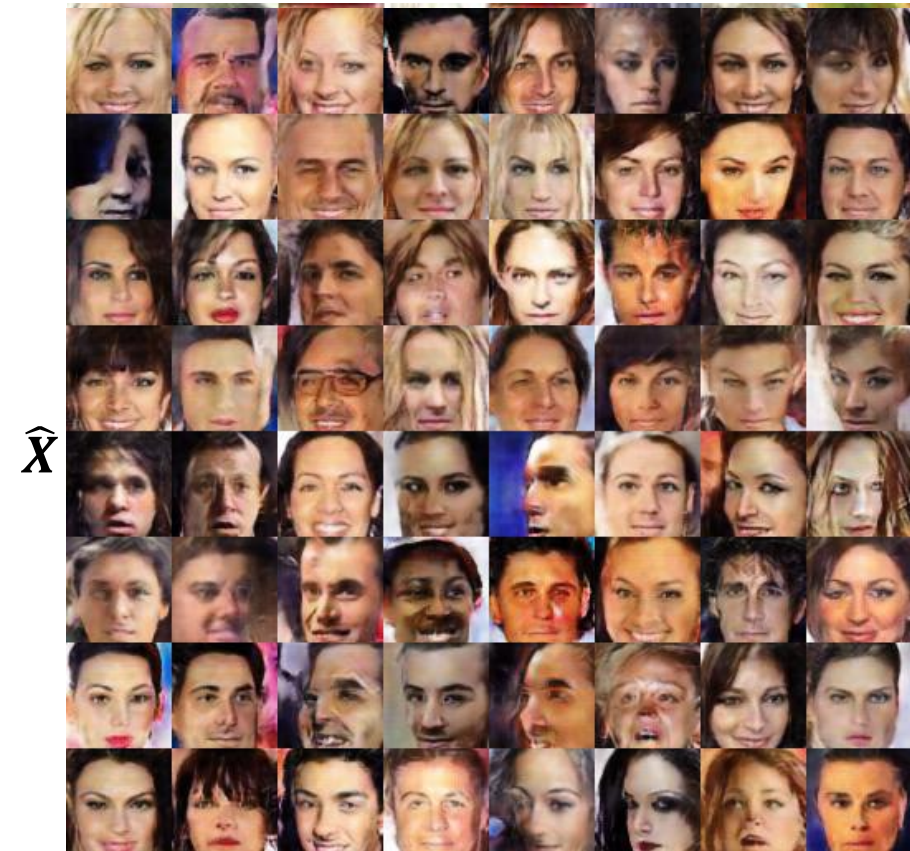
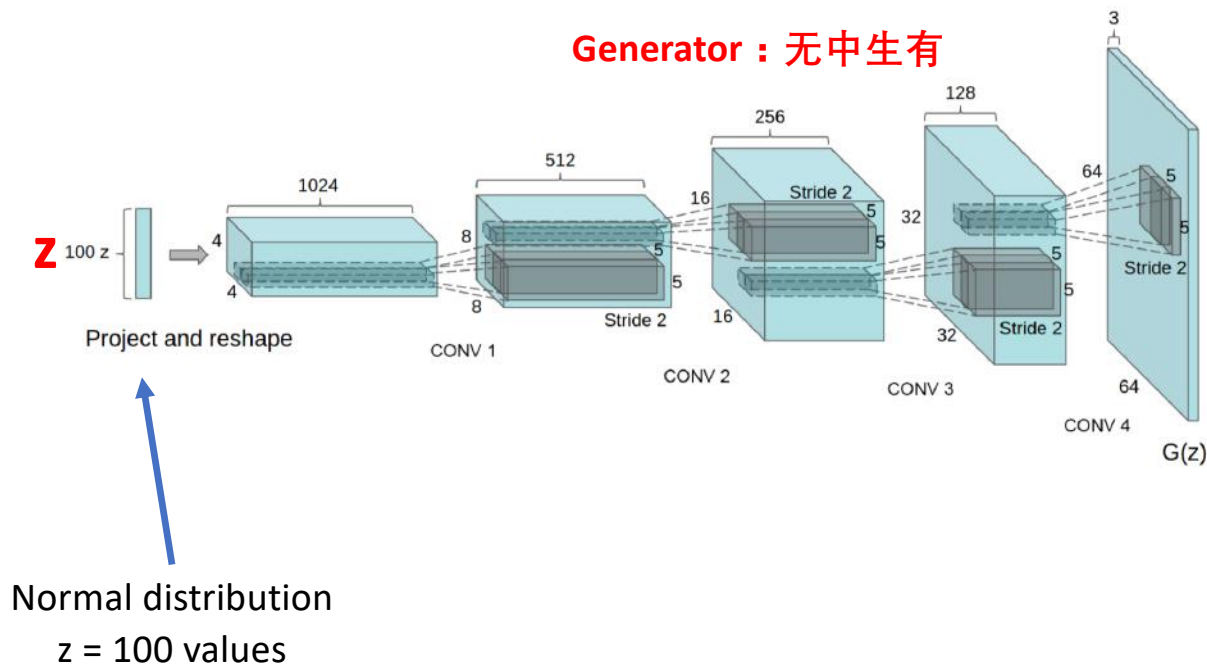
$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{data}} [\log D(x)] + \mathbb{E}_{z \sim p_z} [\log(1 - D(G(z)))]$$

$$\mathcal{L}_D = -\mathbb{E}_{x \sim p_{data}} [\log D(x)] - \mathbb{E}_{z \sim p_z} [\log(1 - D(G(z)))]$$

$$\mathcal{L}_G = -\mathbb{E}_{z \sim p_z} [\log D(G(z))]$$

# Vanilla GAN – Deep Convolutional GAN (DCGAN)

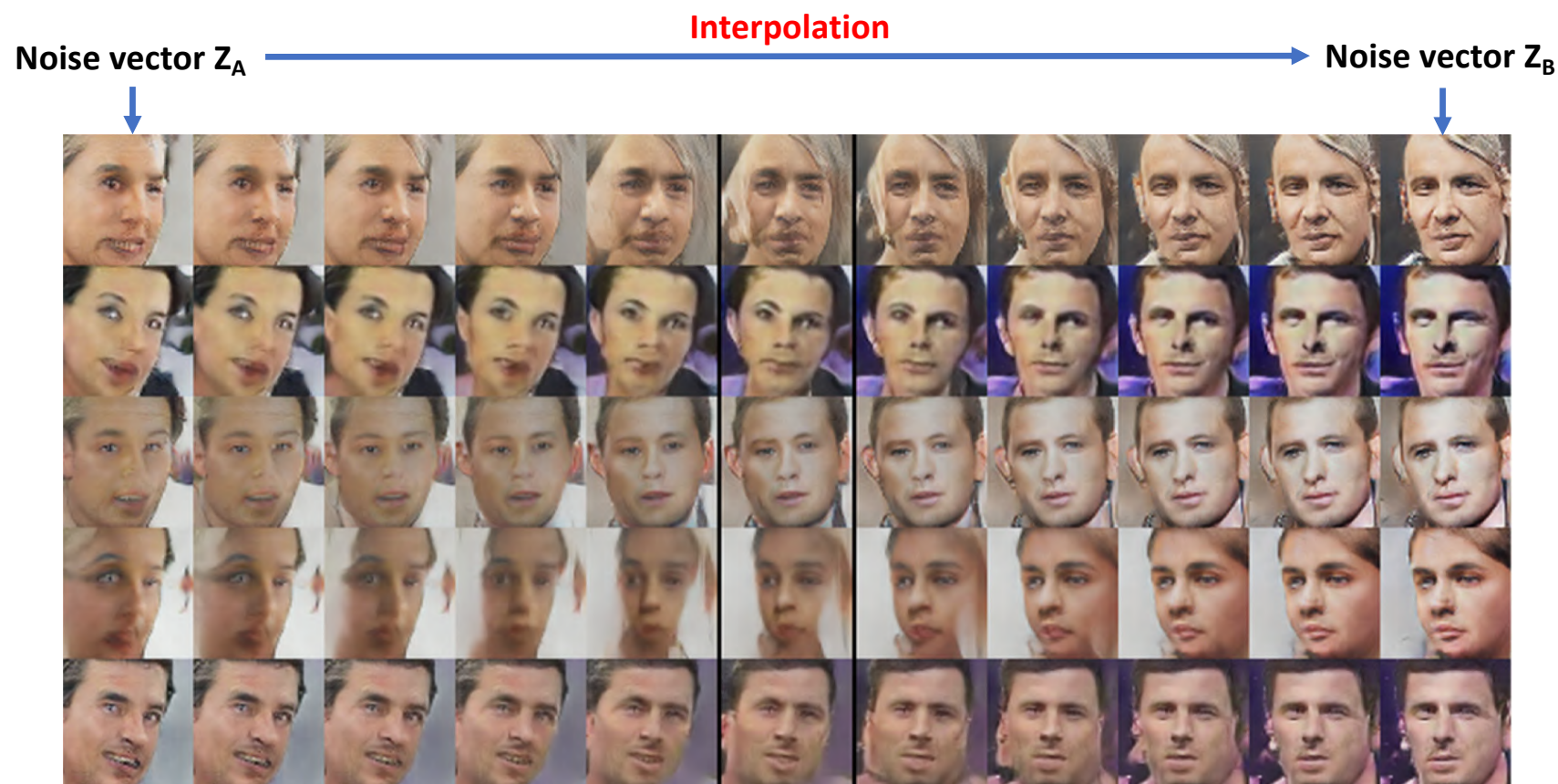
- Using the power of CNN





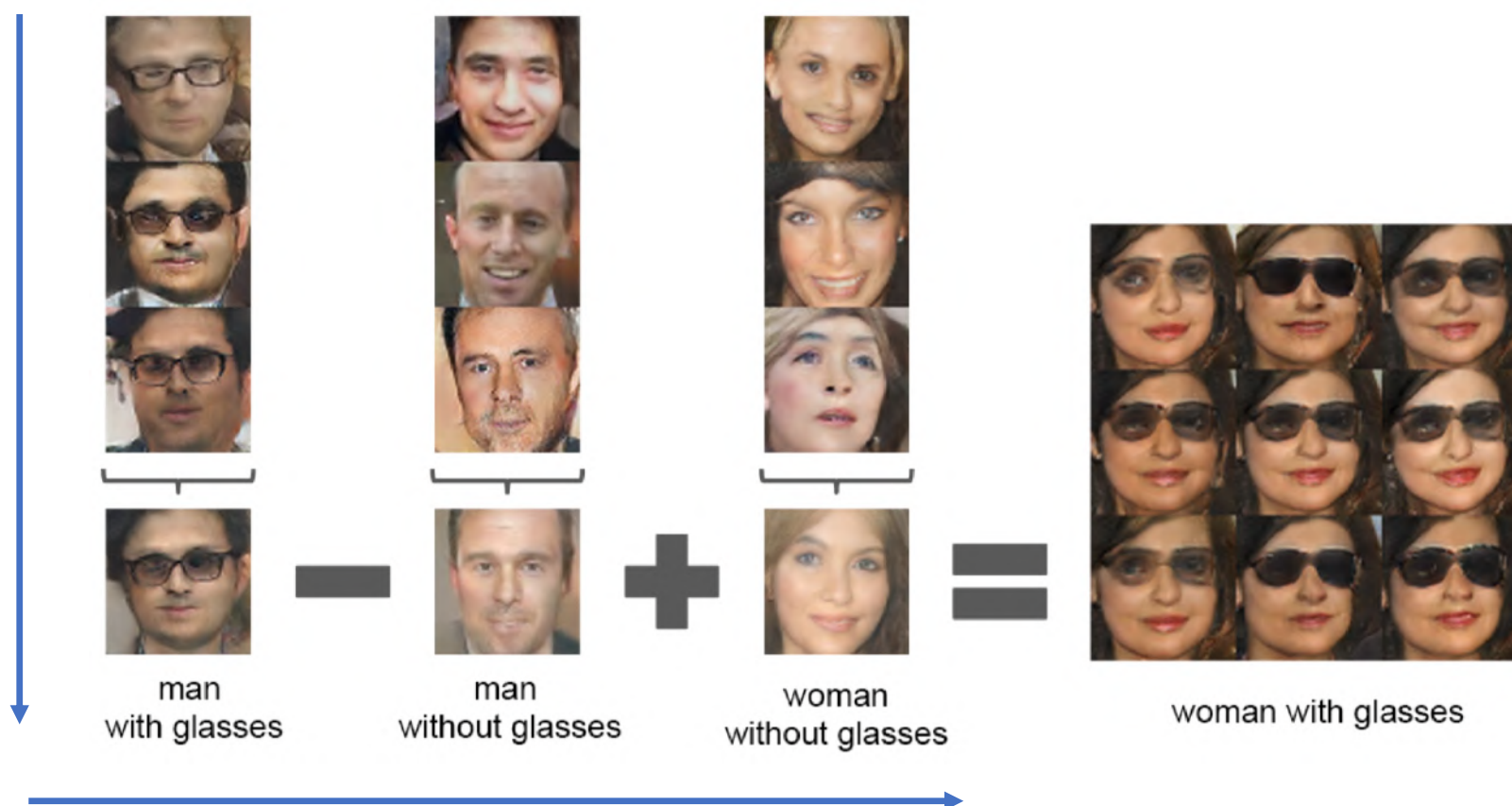
## Vanilla GAN – Deep Convolutional GAN (DCGAN)

- Latent representation  $z$



# Vanilla GAN – Deep Convolutional GAN (DCGAN)

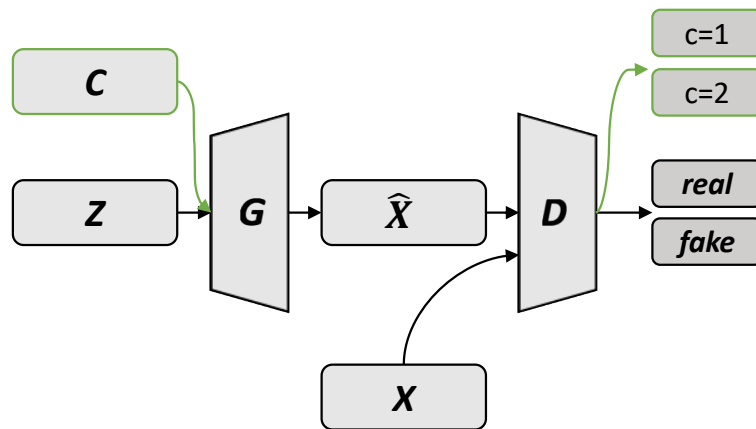
- Latent representation  $z$





# Vanilla GAN -- Conditional GAN

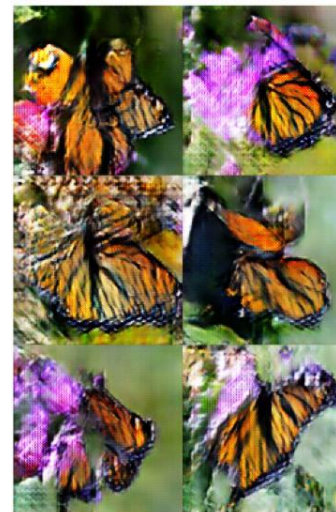
- Auxiliary Classifier GANs



$$\mathcal{L}_D = \mathbb{E}_{x \sim p_{data}} [\log D_x(x)] + \mathbb{E}_{z \sim p_z} [\log(1 - D_x(G(z, c)))]$$

$$\mathbb{E}_{x \sim p_{data}} [\log D_c(x)] + \mathbb{E}_{z \sim p_z} [\log(1 - D_c(G(z, c)))]$$

$$\mathcal{L}_G = \mathbb{E}_{x \sim p_{data}} [\log D_x(G(z, c))] + \mathbb{E}_{z \sim p_z} [\log D_c(G(z, c))]$$



monarch butterfly



goldfinch



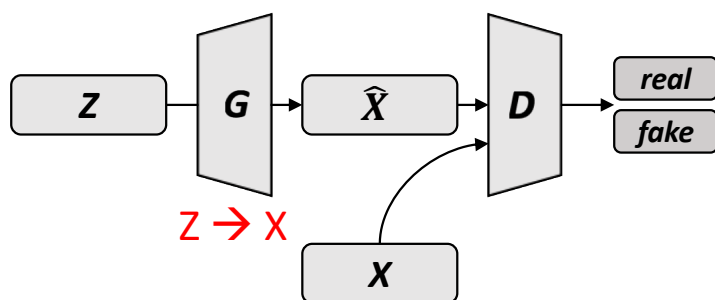
daisy

Multi-modal problem: one problem has multiple solutions  
P(z, c)

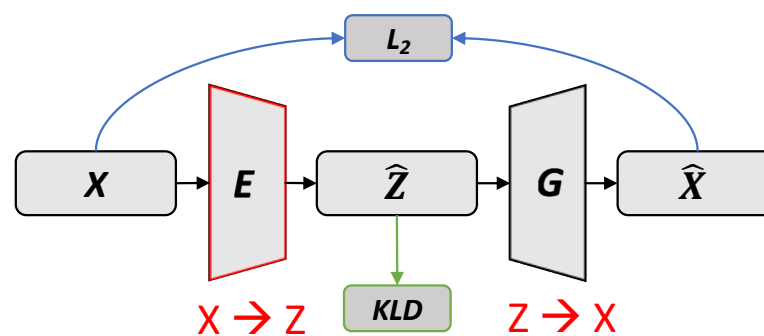
# GAN with Encoder

## GAN with Encoder – Vanilla GAN vs VAE

### Vanilla GAN

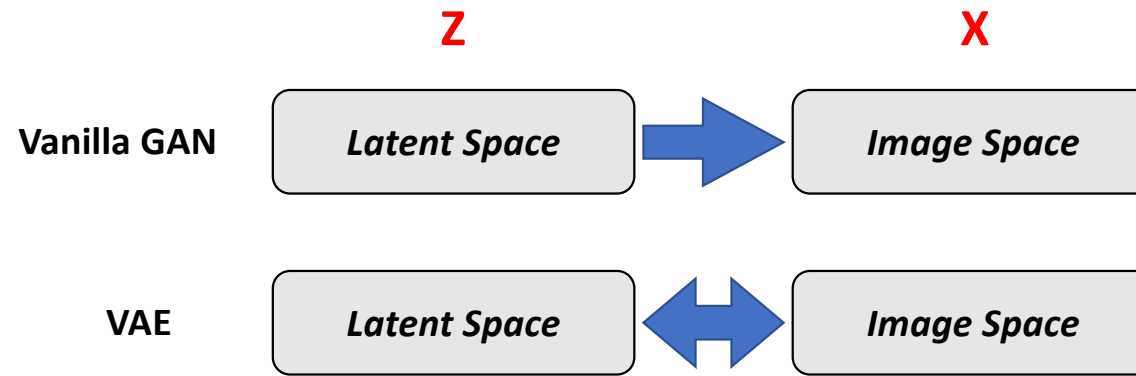


### VAE variational autoencoder



VAE has an Encoder that can map  $x$  to  $z$

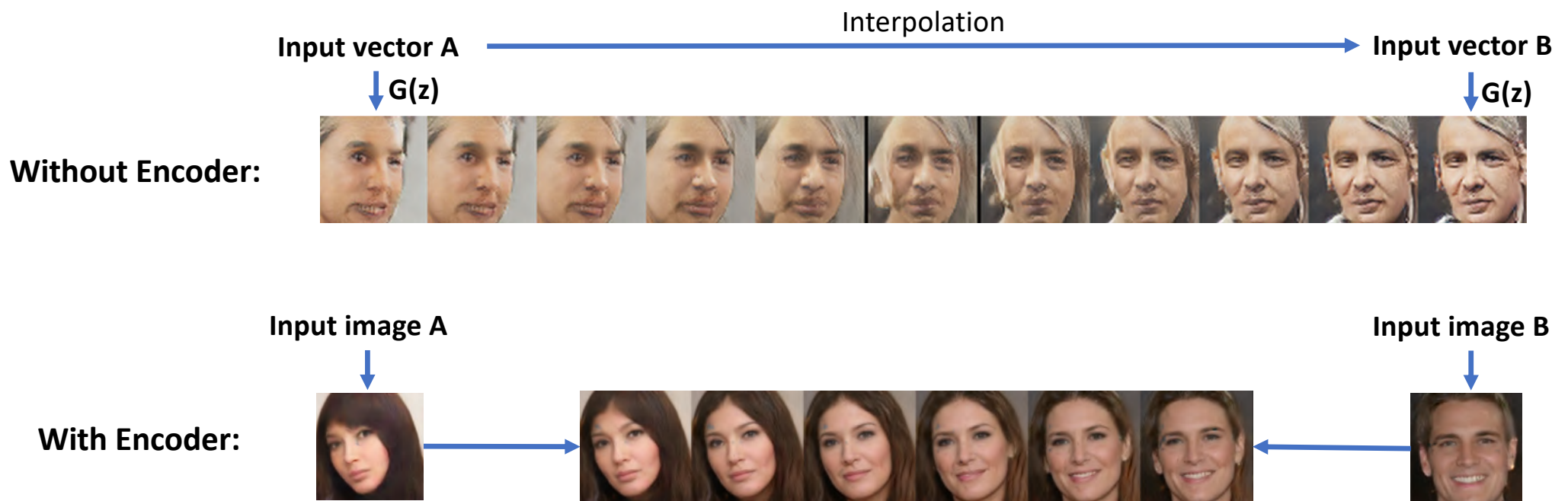
## GAN with Encoder – Vanilla GAN vs VAE



- VAE = **G**enerator + **E**ncoder
- Vanilla GAN = **G**enerator + **D**iscriminator
- Better GAN = **G**enerator + **D**iscriminator + **E**ncoder

## GAN with Encoder – Why Encoder

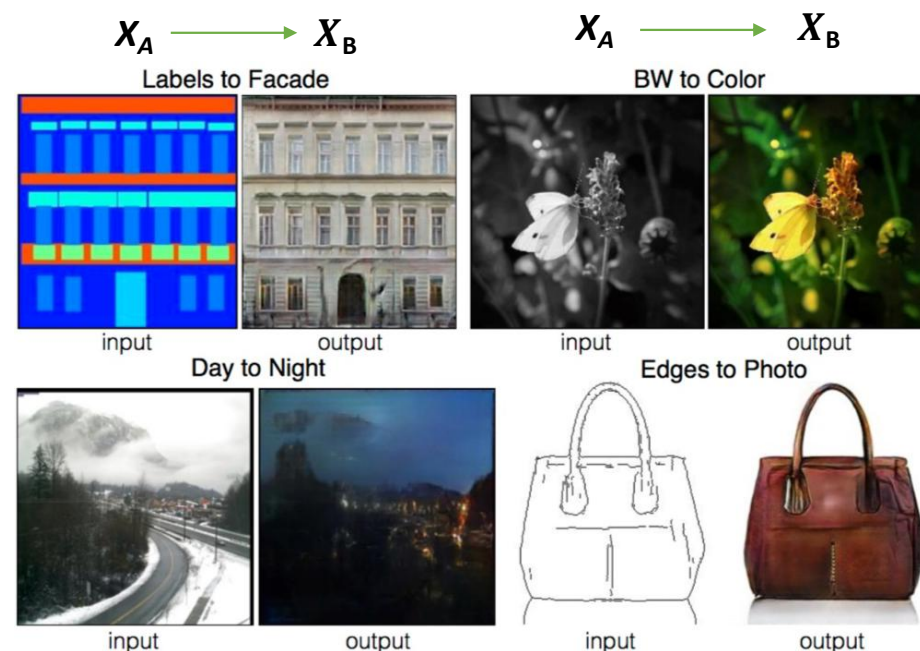
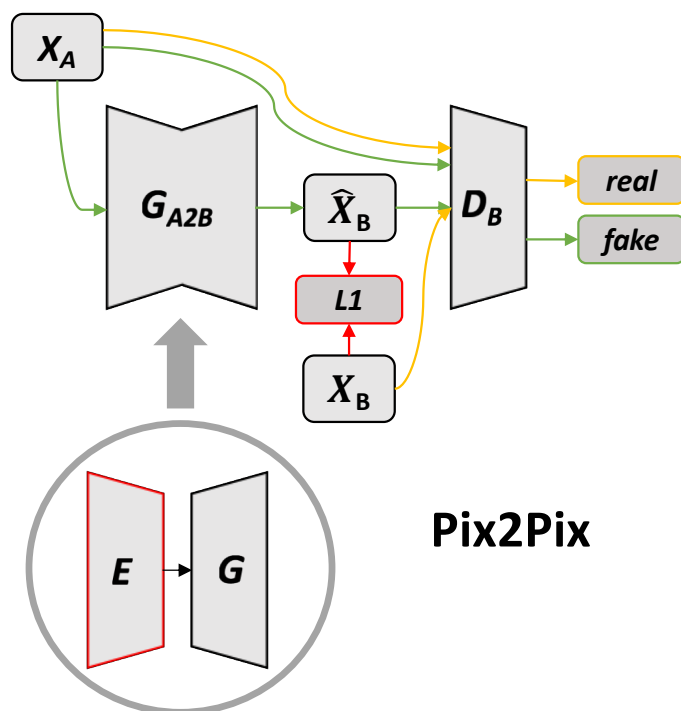
- Encoder allows GAN to receive images == More applications



# GAN with Encoder – Encoder as a part of the Generator

- Supervised image-to-image “translation”

Inputs can be images



$$\mathcal{L}_D = \mathbb{E}_{x \sim p_{data}} [\log D(x_A, x_B)] + \mathbb{E}_{x \sim p_{data}} [\log(1 - D(x_A, G(x_A)))]$$

$$\mathcal{L}_G = \mathbb{E}_{x \sim p_{data}} [\log D(x_A, G(x_A))] + \mathbb{E}_{x \sim p_{data}} \lambda \|x_B - G(x_A)\|$$

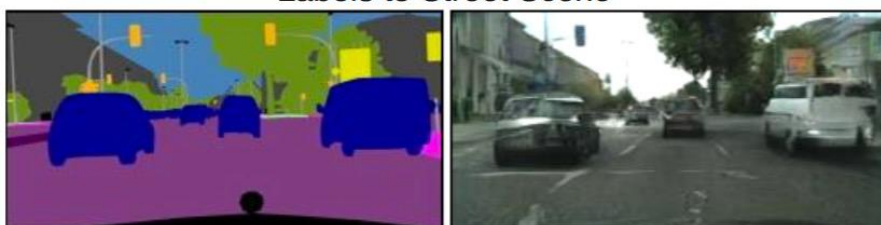
Image-to-Image Translation with Conditional Adversarial Networks. *P. Isola, J. Zhu et al. CVPR 2017.*



# GAN with Encoder – Encoder as a part of the Generator

- Supervised image-to-image “translation”

Labels to Street Scene



input

output

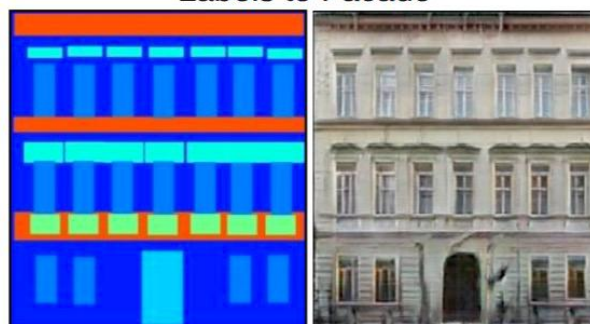
Aerial to Map



input

output

Labels to Facade



input

output

BW to Color



input

output

Day to Night



input

output

Edges to Photo



input

output

Image-to-Image Translation with Conditional Adversarial Networks. *P. Isola, J. Zhu et al. CVPR 2017.*

## GAN with Encoder – Encoder as a part of the Generator

- Supervised image-to-image “translation”

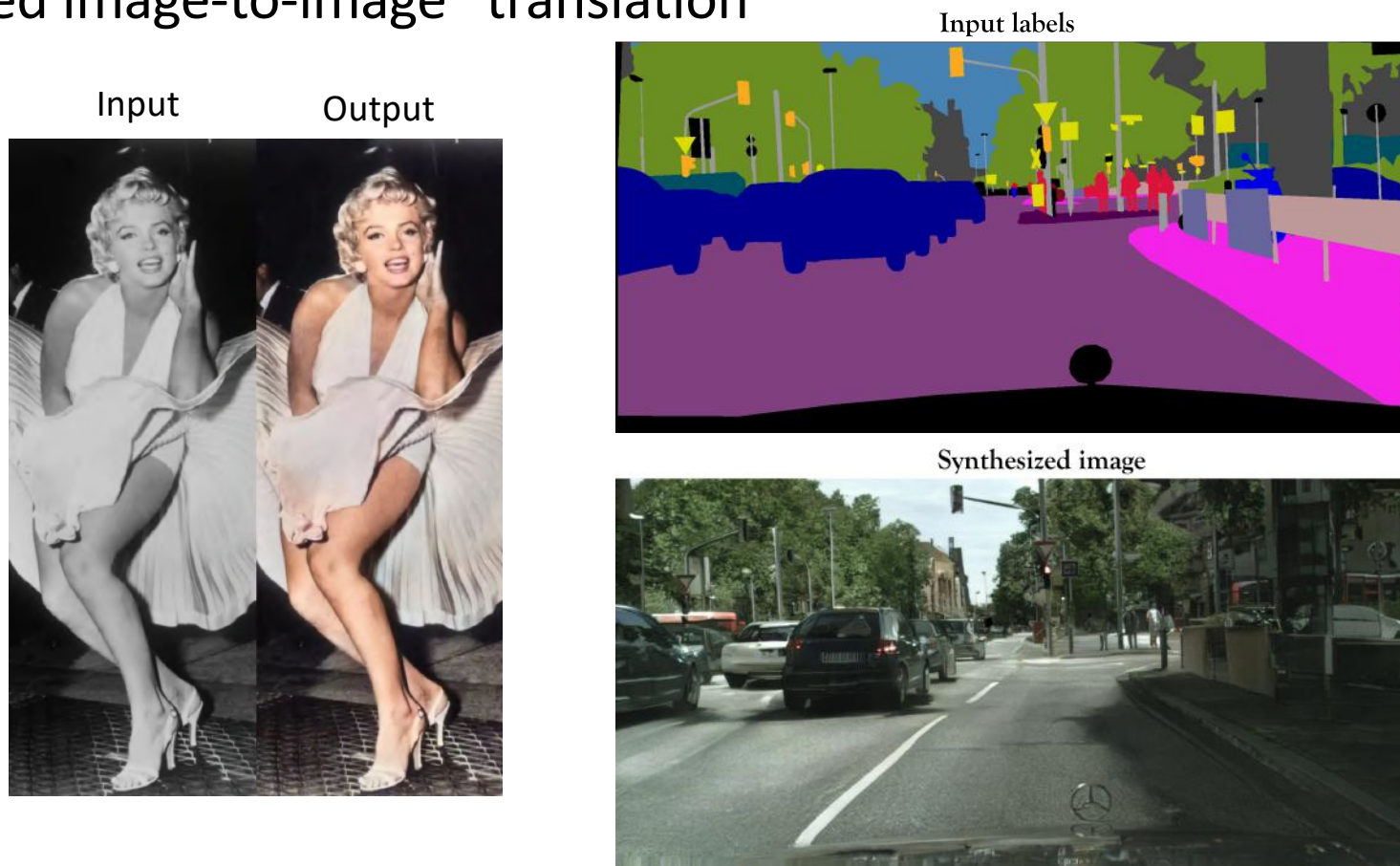
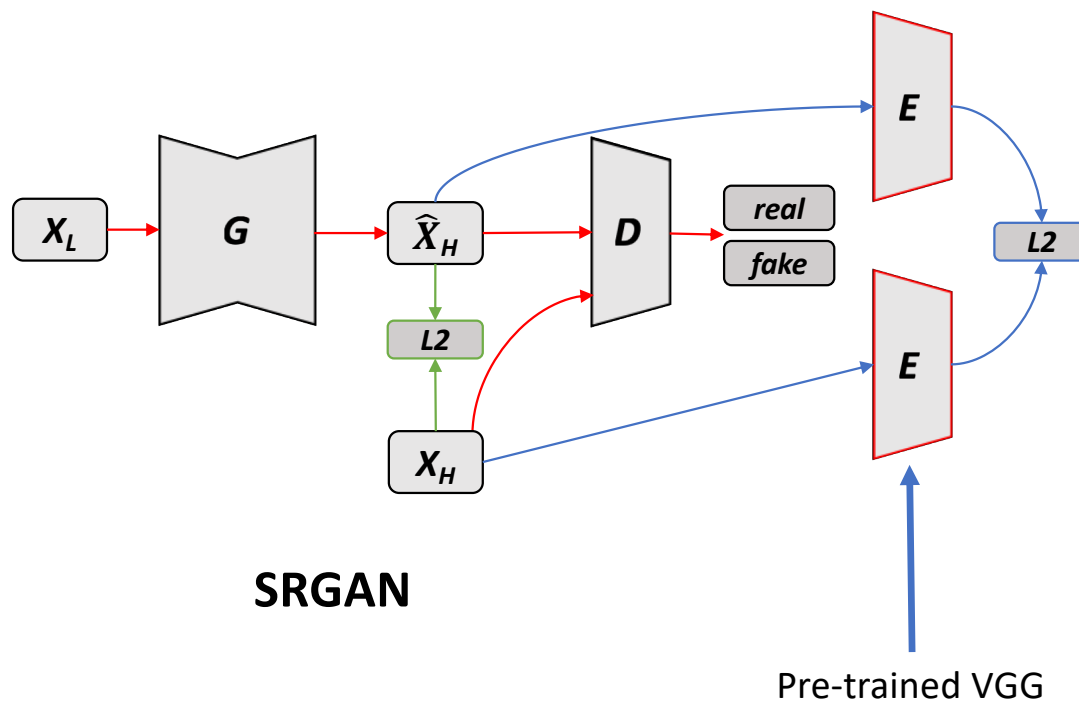


Image-to-Image Translation with Conditional Adversarial Networks. *P. Isola, J. Zhu et al. CVPR 2017.*

# GAN with Encoder – Encoder as the Feature Extractor

- Supervised image super resolution

Better feature reconstruction





## GAN with Encoder – Encoder as the Feature Extractor

- Supervised image super resolution

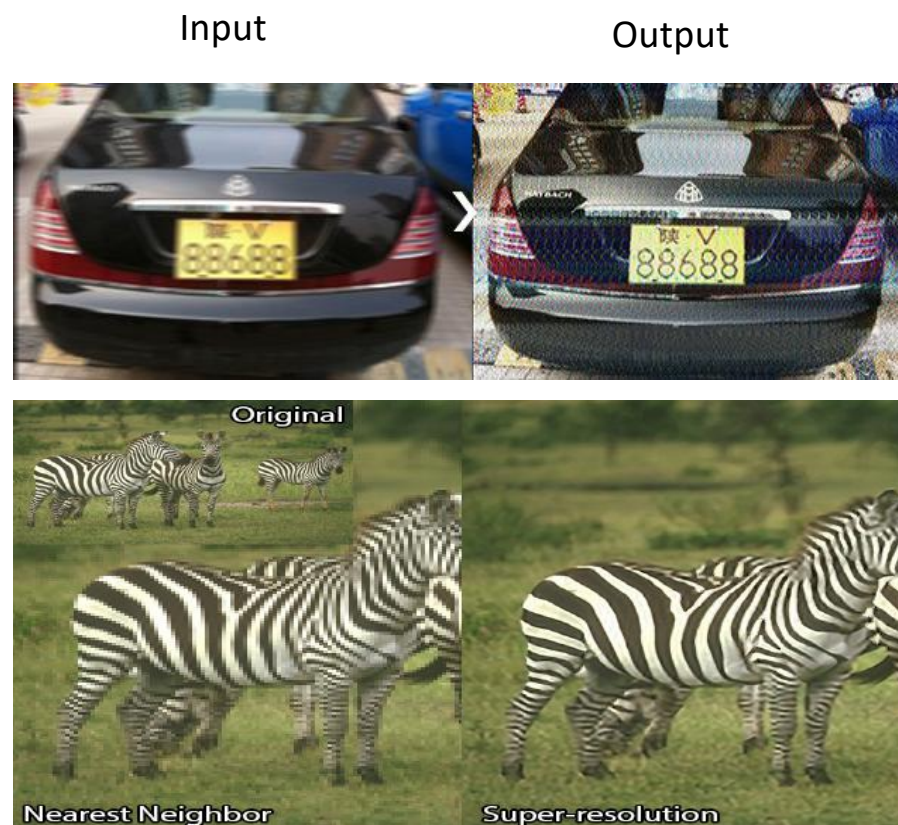
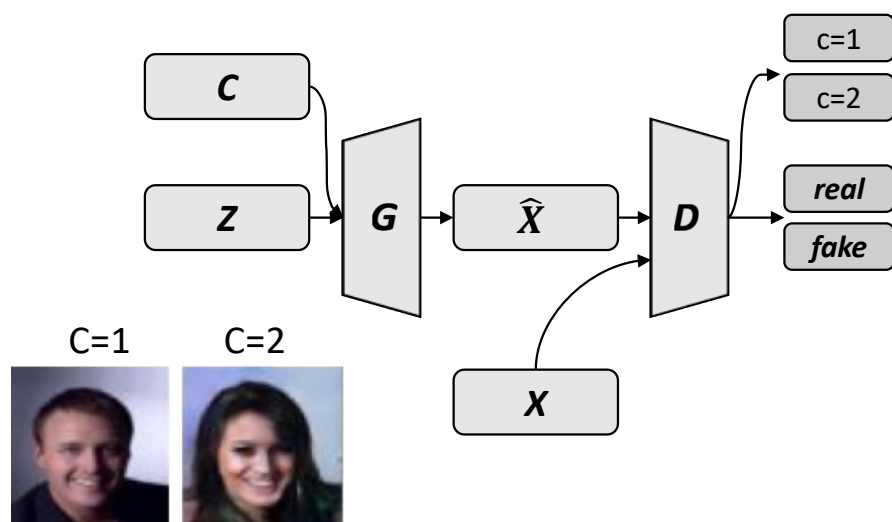


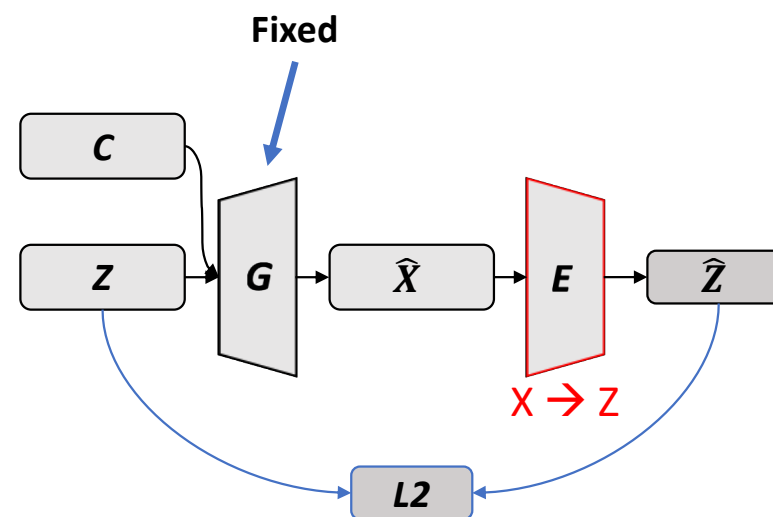
Photo-Realistic Single Image Super-Resolution Using a Generative Adversarial Network. *C. Ledig, L. Theis et al. CVPR 2017.*

# GAN with Encoder – Learn the mapping from $x$ to $z$ like VAE

- Unsupervised image-to-image translation



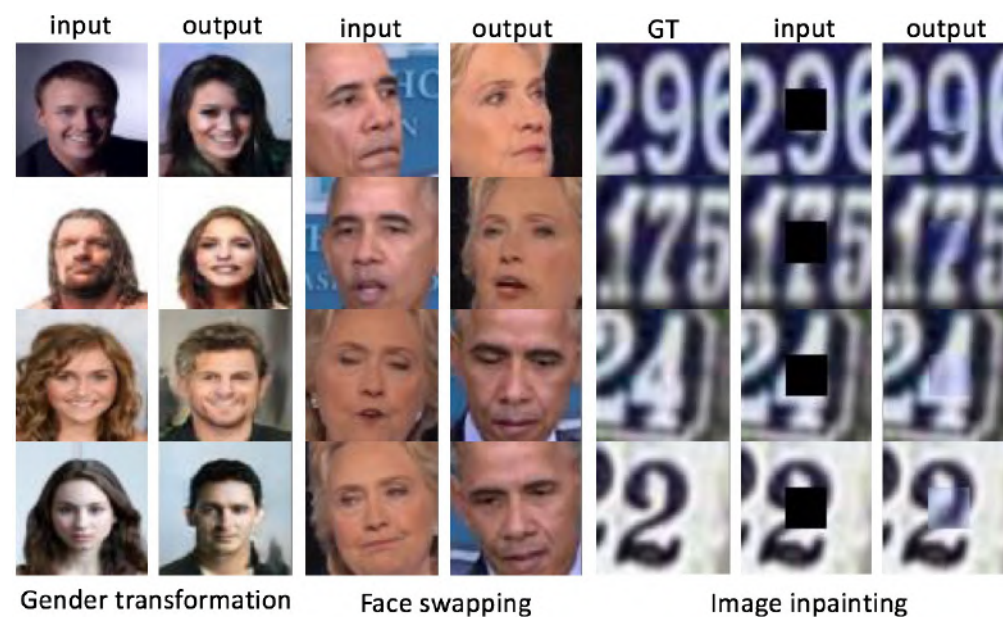
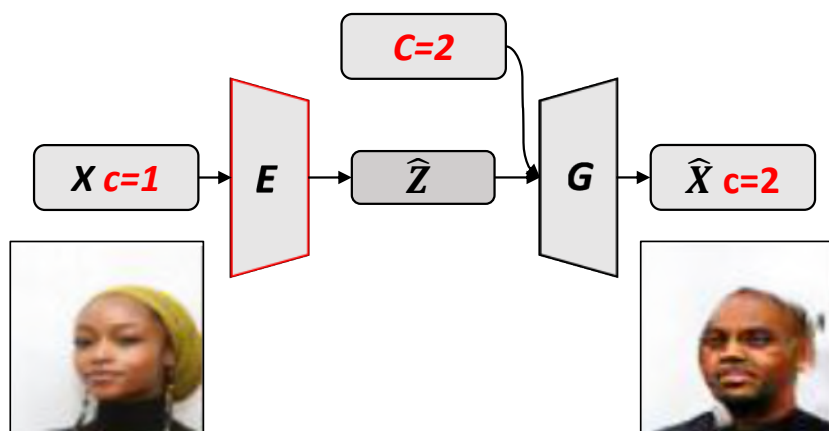
Given an ACGAN



Learning the Encoder in a Brute Force Way

## GAN with Encoder – Learn the mapping from $x$ to $z$

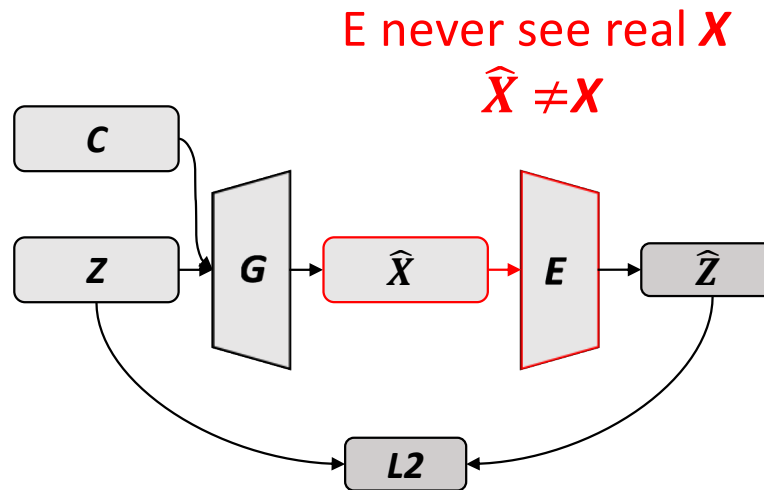
- **Unsupervised** image-to-image translation





## GAN with Encoder – Learn the mapping from $x$ to $z$

- Limitation of the brute force method : Encoder never see real data samples

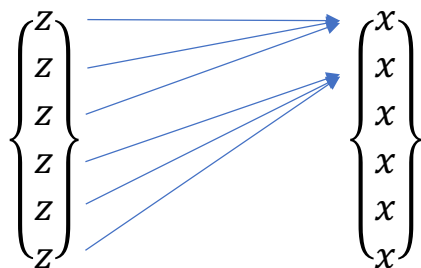


## GAN with Encoder – Learn the mapping from $x$ to $z$

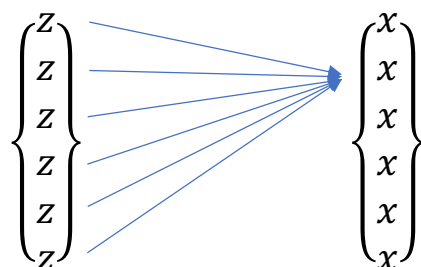
- Limitation of the brute force method : GAN Collapse

E never see real  $X$

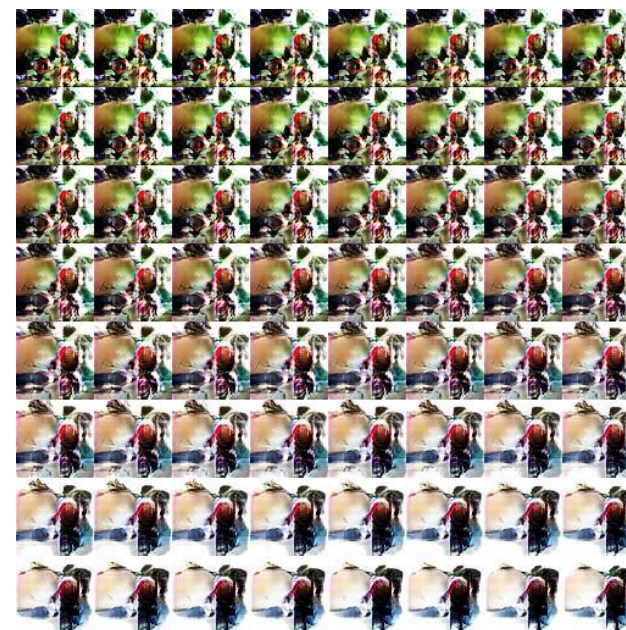
$$\hat{X} \neq X$$



G can only synthesis some part of the dataset  $x$



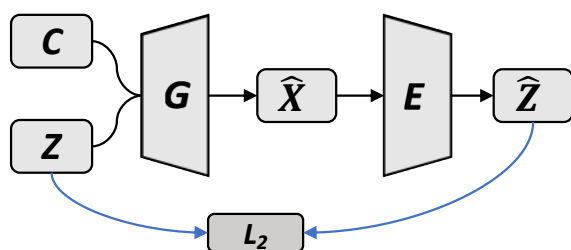
G can only synthesis one data



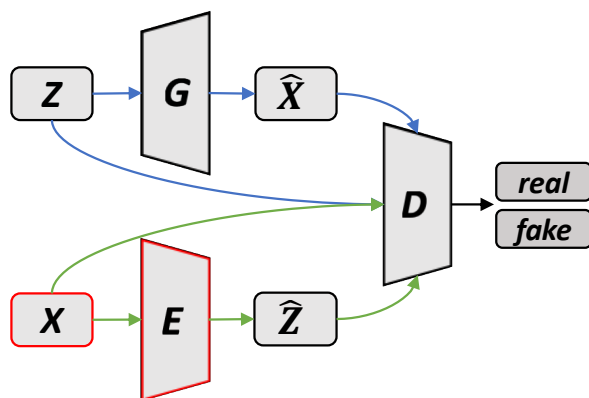
Examples of GAN collapse

# GAN with Encoder -- Learn the Encoder from Real Data

- Learn the Encoder

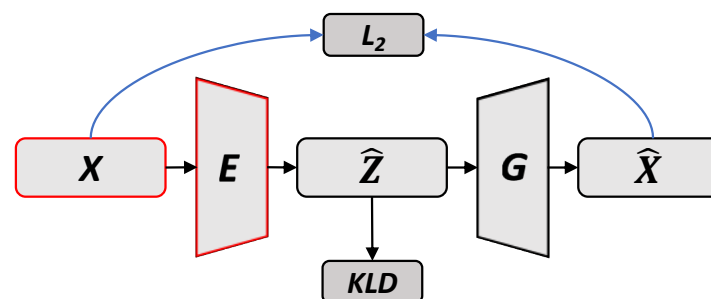


Brute Force

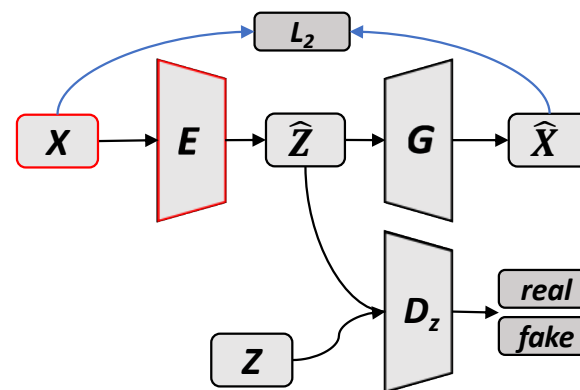


BiGAN

Bidirectional GAN



VAE

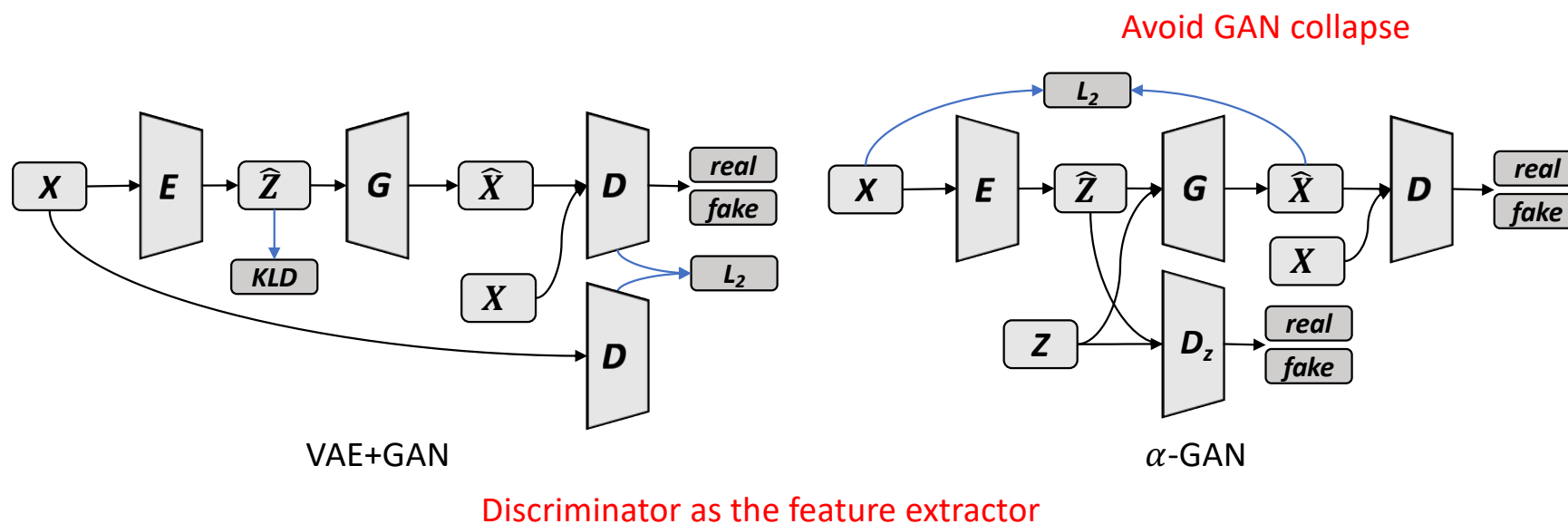


AAE

Adversarial Autoencoder

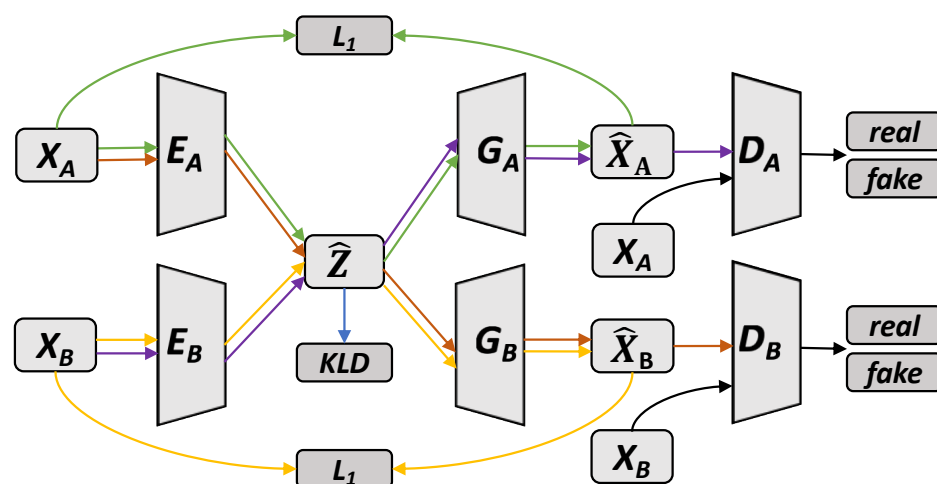
# GAN with Encoder -- Learn the Encoder from Real Data

- Learn the Encoder



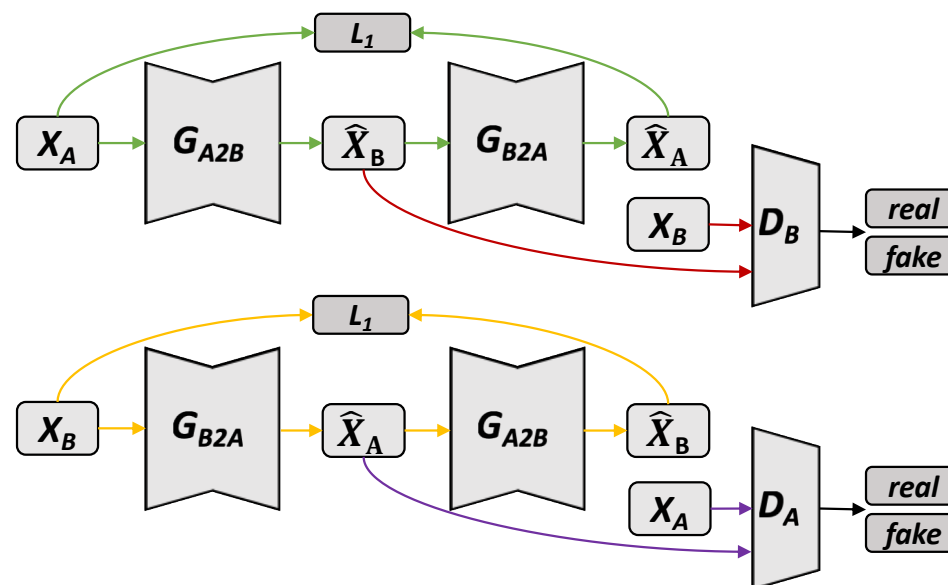
- Training the  $G$  and  $E$  in Autoencoder way can force the  $G$  to be able to generate all  $X$ , *avoiding GAN collapse*

# GAN with Encoder -- Unsupervised Image-to-Image Translation



Liu et al.

Learn the Encoder **Explicitly**



CycleGAN

Learn the Encoder **Implicitly**

Unsupervised image-to-image translation networks. M.Y. Liu, T. Breuel, J. Kautz. NIPS. 2017

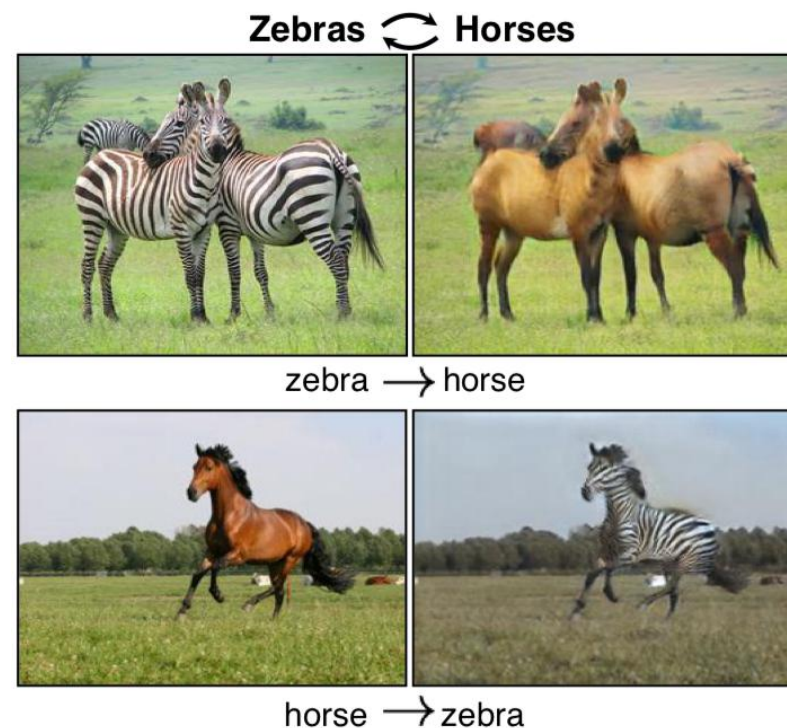
Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. J. Zhu, T. Park et al. ICCV 2017.

# GAN with Encoder -- Unsupervised Image-to-Image Translation



*Liu et al.*

Learn the Encoder **Explicitly**



CycleGAN

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Unsupervised image-to-image translation networks. *M.Y. Liu, T. Breuel, J. Kautz. NIPS. 2017*

Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. *J. Zhu, T. Park et al. ICCV 2017.*



# GAN with Encoder -- Unsupervised Image-to-Image Translation



Input GTA5 CG

<https://blog.csdn.net/gdymind>



Output image with German street view style

[blog.csdn.net/gdymind](https://blog.csdn.net/gdymind)

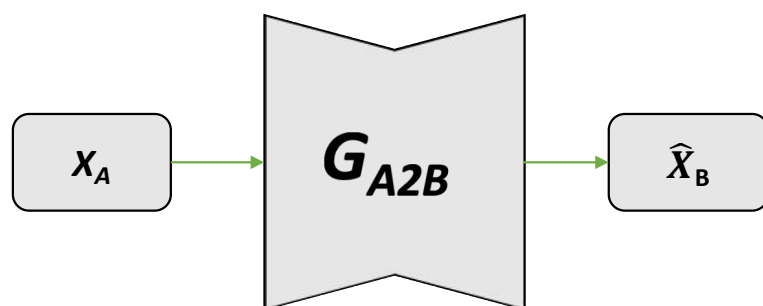
Unsupervised image-to-image translation networks. *M.Y. Liu, T. Breuel, J. Kautz. NIPS. 2017*

Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. *J. Zhu, T. Park et al. ICCV 2017.*



## GAN with Encoder – Learn Encoder in **Implicit or Explicit** Ways?

- Simple normal distribution is difficult to model complex images
- 3D tensors can contain more spatial information than vectors
- Many applications do not need interpolation



- Image inpainting
- Image super resolution
- Image-to-image translation
- ....

# Summary

## Summary

This talk:

- GAN :  $G + D \rightarrow G + D + E$
- Learning E from real data is important
- Autoencoder can help to avoid GAN collapse
- Learning E implicitly is becoming more and more popular
- The E can be extended to text and any other data type

GAN applications:

- Image-to-image: Pix2Pix  $\rightarrow$  CycleGAN  $\rightarrow$  Attention CycleGAN
- Text-to-image: GAN-CLS  $\rightarrow$  StackGAN  $\rightarrow$  StackGAN++
- Text+image to image: ...
- Video-to-video: ...

# Questions

## Questions

- Q1. 如何解决GAN中，输入的normal distribution太简单的问题？
- Q2. 为什么G、D要来回对抗训练，而不是完全训练好D后再训练G？
- Q3. G是不是真的能创造出训练数据中没有的数据？