

Parallelization and analysis of all-shortest paths algorithms using OpenMP

Introduction

Applications

- Route guidance
 - Determining shortest routes dependent on a variety of weights. Constantly needs updated
- Network Router Pathing
 - Determining shortest route for network to take in order to deliver packets. Unoptimized routes increase network latency. Important for time critical applications
- Video Game Al path finding
 - Artificial Intelligence players need to react to known human players and possibly determine shortest path from a constantly moving object.

Two All-shortest paths algorithms: Floyd-Warshall and Dijkstra

<u>Implementation</u>

Floyd Warshall's Algorithm

- Runs through all possible paths from one vertex to another to find shortest
- Outer k loop is not parallelizable because k determines the intermediate vertices in order

Implementation of OpenMP algorithm

Implementation of Serial algorithm

```
for(int k = 0; k < n; k++)
  for(int i = 0; i < n; i++)
    for(int j = 0; j < n; j++)
        if(dist[i][j]>dist[i][k]+dist[k][j])
        dist[i][j]=dist[i][k]+dist[k][j].
```

Seq. running

500 Vertices

0.356 s FW

0.353 s DS

times:

Data Sets:

Input:

Randomly generated edge weights from 0-50 for V vertices Output:

Table of shortest paths for each pair

Dijkstra's Algorithm

- Determines the distance from a source vertex to each other vertex
- Checks to make sure a vertex isn't visited twice and finds the shortest path by checking if the distance to next thorough v from u is shorter than the previous shortest

Analysis:

```
Serial: \Theta(E^*V^2) -- Using adjacency matrix instead of list means E=V OpenMP: \Theta((E^*V^2)/p)
```

Implementation of Serial algorithm

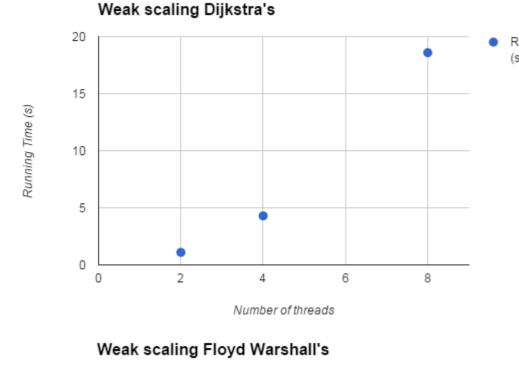
Implementation of OpenMP algorithm

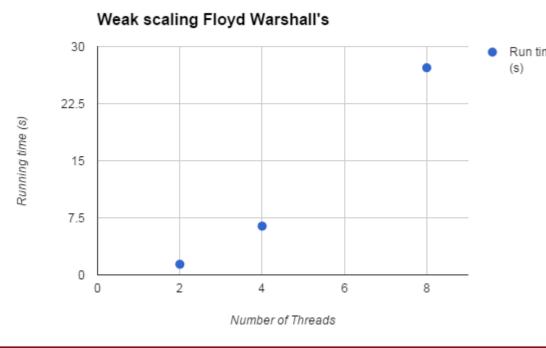
Analysis and Evaluation

- Both of the OpenMP algorithms result in a reduced running time for more than 1 thread.
- Floyd Warshall's algorithm shows excellent strong scaling average 50% reduction in run time
- Dijkstra's algorithm shows poor strong scaling with an average 35% reduction in run time
- Both show the same weak scaling performance

Weak Scaling

Weak scaling shows the effect of increasing both the problem size and the number of threads at the same time. Variables used where V=1000, 2000, and 4000 and Threads=2, 4, and 8.

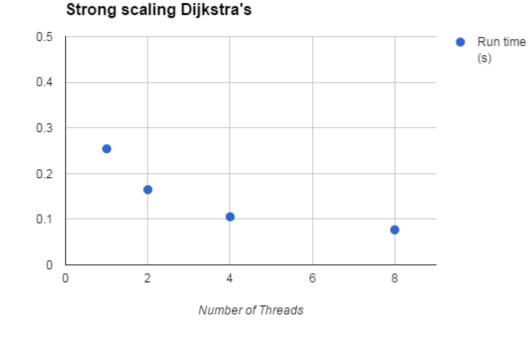


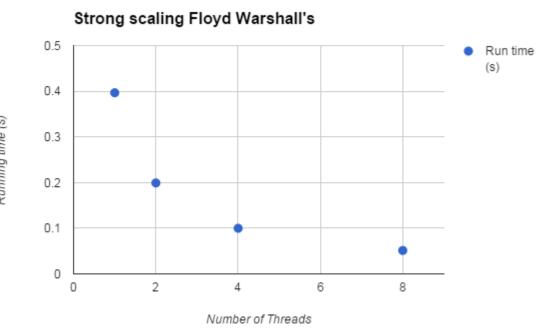


Strong Scaling

Strong scaling shows the effect of only increasing the number of threads.

Variables used where V=500 and Threads = 1, 2, 4, and 8





Future Work and Conclusion

MPI and PGAS versions

Blocking of both algorithms (parallelize inner working instead of just splitting based on vertices)

Additional Shortest path algorithms

Overall:

Both algorithms provided great speedups compared to the sequential versions. Floyd Warshall provides best speedup with

Floyd Warshall provides best speedup with completely dense graph.

Speed ups for each algorithm dependent on number of threads (Problem size at 500 vertices):

Floyd Warshall's

- 2 threads result in a 50% reduction in running time (1.7)
- o 4 threads result in a 50% reduction in running time (3.5)
- 8 threads result in a 51% reduction in running time (6.9)
 Dijkstra's
 - 2 threads result in a 40% reduction in running time (1.3)
 - 4 threads result in a 37% reduction in running time (3.3)
 - 8 threads result in a 28% reduction in running time (4.5)