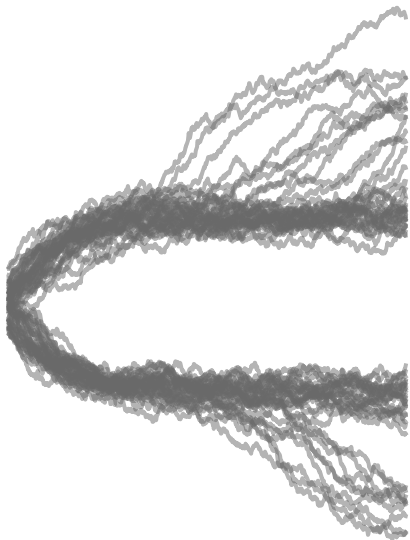


True trajectories



Sampled points

