

Zachary Nolan Sunberg

Ann and H. J. Smead Aerospace Engineering Sciences
University of Colorado Boulder

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Academic Appointments

Assistant Professor

[January 2020 – Present]

University of Colorado, Boulder, CO

Ann and H. J. Smead Aerospace Engineering Sciences Department

Postdoctoral Research Scholar

[October 2018 – October 2019]

University of California, Berkeley, CA

Supervisor: Claire Tomlin, Hybrid Systems Laboratory

Education

Doctor of Philosophy in Aeronautics and Astronautics

[2018]

Stanford University, Stanford, CA

Advisor: Mykel Kochenderfer | Thesis: "Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty"

Master of Science in Aerospace Engineering

[2013]

Texas A&M University, College Station, TX

Advisor: Jonathan Rogers | Thesis: "A Real Time Expert Control System for Helicopter Autorotation"

Bachelor of Science in Aerospace Engineering

[2011]

Texas A&M University, College Station, TX

Summa cum Laude, Minor in Mathematics

Peer Reviewed Journal and Highly-Selective Conference Publications

- [1] **Qi Heng Ho, Tyler Becker, Benjamin Kraske, Zakariya Laouar, Martin Feather, Federico Rossi, Morteza Lahijanian, and Zachary N. Sunberg.** "Recursively-Constrained Partially Observable Markov Decision Processes". In: *AAAI Conference on Artificial Intelligence (AAAI)*. Under review. 2024. URL: [↗](#).
- [2] **Qi Heng Ho, Zachary N. Sunberg, and Morteza Lahijanian.** "Sampling-based Reactive Synthesis for Nondeterministic Hybrid Systems". In: *Robotics and Automation Letters (RA-L)* (2024). Under Review. URL: [↗](#).
- [3] **Matt-Heun Hong, Zachary Sunberg, and Danielle Szafir.** "Cieran: Designing Sequential Colormaps with a Teachable Robot". In: *Human Factors in Computing Systems (CHI)*. Under review. 2024.
- [4] **Michael H. Lim, Tyler J. Becker, Mykel J. Kochenderfer, Claire J. Tomlin, and Zachary N. Sunberg.** "Optimality Guarantees for Particle Belief Approximation of POMDPs". In: *Journal of Artificial Intelligence Research* (2023). URL: [↗](#).
- [5] **Prashin Sharma, Benjamin Kraske, Joseph Kim, Zakariya Laouar, Ella Atkins, and Zachary Sunberg.** "Investigation of risk-aware MDP and POMDP contingency management autonomy for UAS". In: *AIAA Journal of Aerospace Information Systems (JAIS)* (2023). Under review. URL: [↗](#).
- [6] **Benjamin W. Blonder, Michael H. Lim, Zachary Sunberg, and Claire Tomlin.** "Navigation between initial and desired community states using shortcuts". In: *Ecology Letters* (2023). URL: [↗](#).
- [7] **Himanshu Gupta, Bradley Hayes, and Zachary Sunberg.** "Intention-Aware Navigation in Crowds with Extended-Space POMDP Planning". In: *Autonomous Agents and Multi-Agent Systems (AAMAS)*. 2022. URL: [↗](#).

- [8] **Zachary Sunberg** and Mykel Kochenderfer. "Improving Automated Driving through Planning with Human Internal States". In: *IEEE Transactions on Intelligent Transportation Systems* (2022). URL: [↗](#).
- [9] Shakeeb Ahmad, **Zachary N. Sunberg**, and J. Sean Humbert. "End-to-End Probabilistic Depth Perception and 3D Obstacle Avoidance using POMDP". In: *Journal of Intelligent & Robotic Systems* 103.2 (2021).
- [10] John Mern, Anil Yildiz, **Zachary Sunberg**, Tapan Mukerji, and Mykel J. Kochenderfer. "Bayesian Optimized Monte Carlo Planning". In: *AAAI Conference on Artificial Intelligence (AAAI)*. 2021.
- [11] **Michael H. Lim**, Claire J. Tomlin, and **Zachary N. Sunberg**. "Sparse Tree Search Optimality Guarantees in POMDPs with Continuous Observation Spaces". In: *International Joint Conference on Artificial Intelligence (IJCAI)*. 2020.
- [12] **Lasse Peters**, David Fridovich-Keil, Claire Tomlin, and **Zachary Sunberg**. "Inference-Based Strategy Alignment for General-Sum Differential Games". In: *International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*. 2020. URL: [↗](#).
- [13] **Patrick Slade**, **Zachary Sunberg**, and Mykel J. Kochenderfer. "Estimation and Control Using Sampling-Based Bayesian Reinforcement Learning". In: *IET Cyber-Physical Systems: Theory and Applications* 5 (1 2020). URL: [↗](#).
- [14] **Zachary N. Sunberg** and Mykel J. Kochenderfer. "Online Algorithms for POMDPs with Continuous State, Action, and Observation Spaces". In: *International Conference on Automated Planning and Scheduling (ICAPS)*. 2018. URL: [↗](#).
- [15] Maxim Egorov, **Zachary N. Sunberg**, Edward Balaban, Tim A. Wheeler, Jayesh K. Gupta, and Mykel J. Kochenderfer. "POMDPs.jl: A Framework for Sequential Decision Making under Uncertainty". In: *Journal of Machine Learning Research* 18.26 (2017). URL: [↗](#).
- [16] **Zachary Sunberg**, Suman Chakravorty, and Richard Scott Erwin. "Information Space Receding Horizon Control for Multisensor Tasking Problems". In: *IEEE Transactions on Cybernetics* 46.6 (2016). URL: [↗](#).
- [17] **Zachary N. Sunberg**, Nathaniel R. Miller, and Jonathan D. Rogers. "A Real-Time Expert Control System For Helicopter Autorotation". In: *Journal of the American Helicopter Society* 60.2 (2015). DOI: 10.4050/JAHS.60.022008. URL: [↗](#).
- [18] **Zachary Sunberg**, Suman Chakravorty, and Richard Scott Erwin. "Information Space Receding Horizon Control". In: *IEEE Transactions on Cybernetics* 43.6 (2013). URL: [↗](#).
- [19] **Zachary Sunberg** and Jonathan Rogers. "A Belief Function Distance Metric for Orderable Sets". In: *Information Fusion* 14.4 (2013). DOI: 10.1016/J.INFFUS.2013.03.003. URL: [↗](#).

Peer Reviewed Conference Publications

- [20] **Zakariya Laouar**, Rayan Mazouz, **Tyler Becker**, **Qi Heng Ho**, and **Zachary N. Sunberg**. "Feasibility-Guided Safety-Aware Model Predictive Control for Jump Markov Linear Systems". In: *IEEE American Control Conference (ACC)*. Under review. 2024.
- [21] Hunter M Ray*, **Zakariya Laouar***, **Zachary N. Sunberg**, and Nisar Ahmed. "Human-Centered Autonomy for Autonomous sUAS Target Search". In: *IEEE International Conference on Robotics and Automation (ICRA)*. Under review (* equal contribution). 2024.
- [22] Sampada Deglurkar, **Michael H. Lim**, **Johnathan Tucker**, **Zachary N. Sunberg**, Aleksandra Faust, and Claire J. Tomlin. "Compositional Learning-based Planning for Vision POMDPs". In: *Learning for Dynamics & Control (L4DC)*. 2023. URL: [↗](#).
- [23] **Qi Heng Ho**, **Zachary N. Sunberg**, and Morteza Lahijanian. "Planning with SiMBA: Motion Planning under Uncertainty for Temporal Goals using Simplified Belief Guides". In: *IEEE International Conference on Robotics and Automation (ICRA)*. May 2023. URL: [↗](#).
- [24] **Benjamin D. Kraske**, Anshu Saksena, Anna L. Buczak, and **Zachary Sunberg**. "Explanation through Reward Model Reconciliation using POMDP Tree Search". In: *IEEE International Conference on Assured Autonomy (ICAA)*. 2023. URL: [↗](#).

- [25] **Qi Heng Ho**, Roland B. Ilyes, **Zachary Sunberg**, and Morteza Lahijanian. “Automaton-Guided Control Synthesis for Signal Temporal Logic Specifications”. In: *IEEE Conference on Decision and Control (CDC)*. 2022. URL: [↗](#).
- [26] **Qi Heng Ho**, **Zachary N. Sunberg**, and Morteza Lahijanian. “Gaussian Belief Trees for Chance Constrained Asymptotically Optimal Motion Planning”. In: *IEEE International Conference on Robotics and Automation (ICRA)*. 2022. doi: 10.1109/ICRA46639.2022.9812343.
- [27] **Zachary Nolan Sunberg**, Kathryn Anne Wingate, and Lara Buri. “Fair Senior Capstone Project Teaming based on Skills, Preferences, and Friend Groups”. In: *ASEE Annual Conference*. 2021. URL: [↗](#).
- [28] **Michael H. Lim**, Claire J. Tomlin, and **Zachary N. Sunberg**. “Voronoi Progressive Widening: Efficient Online Solvers for Continuous Space MDPs and POMDPs with Provably Optimal Components”. In: *Conference on Decision and Control (CDC)*. 2021. URL: [↗](#).
- [29] Shakeeb G. Ahmad, **Zachary Sunberg**, and Sean Humbert. “APF-PF: Probabilistic Depth Perception for 3D Reactive Obstacle Avoidance”. In: *American Control Conference (ACC)*. 2021.
- [30] Ekhlas Sonu, **Zachary Sunberg**, and Mykel J. Kochenderfer. “Exploiting Hierarchy for Scalable Decision Making in Autonomous Driving”. In: *Intelligent Vehicles Symposium*. 2018.
- [31] **Zachary N. Sunberg**, Christopher J. Ho, and Mykel J. Kochenderfer. “The Value of Inferring the Internal State of Traffic Participants for Autonomous Freeway Driving”. In: *American Control Conference (ACC)*. 2017. URL: [↗](#).
- [32] Patrick Slade, Preston Culbertson, **Zachary Sunberg**, and Mykel J. Kochenderfer. “Simultaneous Active Parameter Estimation and Control using Sampling-based Bayesian Reinforcement Learning”. In: *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*. 2017. URL: [↗](#).
- [33] **Zachary Sunberg**, Mykel J. Kochenderfer, and Marco Pavone. “Optimized and Trusted Collision Avoidance for Unmanned Aerial Vehicles using Approximate Dynamic Programming”. In: *IEEE International Conference on Robotics and Automation (ICRA)*. 2016. URL: [↗](#).
- [34] **Zachary Sunberg**, Suman Chakravorty, and Richard Erwin. “Information space sensor tasking for Space Situational Awareness”. In: *American Control Conference (ACC)*. June 2014. doi: 10.1109/ACC.2014.6858922.
- [35] **Zachary Sunberg**, Nathaniel Miller, and Jonathan Rogers. “A Real Time Expert Control System for Helicopter Autorotation”. In: *70th Forum of the American Helicopter Society*. 2014.
- [36] **Zachary Sunberg**, Suman Chakravorty, and Richard Erwin. “Information Space Receding Horizon Control for MultiAgent Systems”. In: *American Control Conference (ACC)*. 2012. URL: [↗](#).

Conference Publications with Abstract-only Review

- [37] **Johnathan Tucker**, **Jackson Wagner**, and **Zachary Sunberg**. “Adaptive Stress Testing Applied To Space Domain Awareness Systems”. In: *Advanced Maui Optical and Space Surveillance Technologies (AMOS)*. 2022. URL: [↗](#).
- [38] **Tyler Becker** and **Zachary Sunberg**. “Imperfect Information Games and Counterfactual Regret Minimization in Space Domain Awareness”. In: *Advanced Maui Optical and Space Surveillance Technologies (AMOS)*. 2022. URL: [↗](#).
- [39] Hunter M. Ray, Nicholas Conlon, **Zachary Sunberg**, and Nisar R. Ahmed. “User Preference Elicitation for Unmanned Aircraft System Collaborative Search”. In: *AIAA SCITECH Forum*. 2022.
- [40] **Zachary Sunberg** and Jonathan Rogers. “A Fuzzy Logic-Based Controller for Helicopter Autorotation”. In: *AIAA Aerospace Sciences Meeting*. 2013.

Planned Publications

- [41] **Qi Heng Ho**, **Zachary Sunberg**, and Morteza Lahijanian. “Gaussian Belief Trees: Chance Constrained Motion Planning by Planning Directly in the Belief Space”. In late stage preparation, expected submission to *IEEE Transactions on Robotics (T-RO)* in Nov. 2023.

- [42] **Benjamin Kraske**, Anna Buczak, Anshu Saksena, and **Zachary Sunberg**. “Explaining Action Discrepancies for Resource Allocation POMDPs”. In preparation, expected submission to the *Journal of Artificial Intelligence Research (JAIR)* in Dec. 2023.
- [43] **Tyler Becker** and **Zachary Sunberg**. “Bridging the gap between POMGs and sparse POMDP methods”. In preparation, expected submission to the *International Joint Conference on Artificial Intelligence (IJCAI)* in Jan. 2024.
- [44] **Tyler Becker** and **Zachary Sunberg**. “Game-theoretic sensor tasking for space domain awareness”. In preparation, expected submission to *Advances in Space Research* Spring 2024.
- [45] **Jackson Wagner**, **Benjamin Blonder**, and **Zachary Sunberg**. “Plant water use modeling through reinforcement learning”. In initial preparation, expected submission to *Ecology Letters* in Spring 2024.
- [46] **Qi Heng Ho**, Morteza Lahijanian, and **Zachary Sunberg**. “Partially Observable Markov Decision Processes with Temporal Logic Objectives and Constraints”. In preparation, expected submission to *Robotics: Science and Systems* in Jan. 2023.
- [47] **Qi Heng Ho**, JuYeop Han, **Morteza Lahijanian**, and **Zachary Sunberg**. “Sampling-based Reactive Synthesis for Nondeterministic Hybrid Systems under Bounded Perturbations”. In preparation, expected submission to the *International Conference on Intelligent Robots and Systems* in Mar. 2023.
- [48] Rayan Mazouz*, **Qi Heng Ho***, **Zachary Sunberg**, and Morteza Lahijanian. “Sampling-based Motion Planning under Uncertainty with Belief Space Barrier Functions”. In preparation, expected submission to the *Conference on Decision and Control* in Mar. 2023 (* equal contribution).
- [49] **Himanshu Gupta**, **William Pope**, and **Zachary Sunberg**. “Nonholonomic navigation in crowds using POMDP tree search and Hamilton-Jacobi-Bellman motion planning”. In initial preparation, expected submission to *Robotics: Science and Systems* in Jan. 2023.

Open Source Software

POMDPs.jl [2015 – present]
<https://github.com/JuliaPOMDP/POMDPs.jl>
 Interface for defining continuous and discrete, fully and partially observable Markov decision processes along with a suite of state-of-the-art solvers written in Julia and C++.

ProjectAssigner.jl [2020]
<https://github.com/zsunberg/ProjectAssigner.jl>
 Software for optimally assigning student teams to projects based on preferences, friend groups, and skills [27]. Used to assign senior project groups in the AES department since 2020.

Research Funding

Co-I: Collaborative Research: Alternative Leaf Water use Strategies in Hot Environments[2023 – 2024]
National Science Foundation
 \$99,976 | Subcontract from UC Berkeley (listed amount is my subcontract)

PI: Human Centered Autonomy for Dynamic sUAS Target Search Operations [2023 – 2024]
NSF Center for Autonomous Air Mobility and Sensing (CAAMS) Sub-award
 \$111,000 | PI share: \$60,000 (approx.)

Co-I: Multi-Phenomenological, Autonomous ... Decision Support [2023 – 2028]
Air Force Office of Scientific Research
 \$5,000,000 (approx., PI: Marcus Holzinger) | My share: \$500,000 (approx.) | Co-Is: K. Terry Alfriend (TAMU), Scott Palo, Kyle DeMars (TAMU), John Junkins (TAMU), Karen Feigh (Georgia Tech) | Full title: Multi-Phenomenological, Autonomous, and Understandable SDA and XDA Decision Support

Co-I: IUCRC Phase I: Center for Autonomous Air Mobility and Sensing (CAAMS) [2022 – 2027]
National Science Foundation
 \$2,210,225 (PI: Eric Frew) | Co-Is: Nisar Ahmed, Morteza Lahijanian, Sriram Sankaranarayanan | This grant establishes the IUCRC and pays for administrative costs; sub-awards funded through industry contributions will be listed separately.

Co-I: Dispersed Autonomy for Marsupial Aerial Robot Teams <i>National Science Foundation National Robotics Institute (Collaborative Research)</i> \$1,045,429 (PI: Eric Frew) My share: \$300,000 (approx.) Co-Is: Brian Argrow, Adam Houston (University of Nebraska, Lincoln)	[2022 – 2025]
PI: HIPPO (Human-Informed Planning with Probabilistic Observations) <i>NSF Center for Autonomous Air Mobility and Sensing (CAAMS) Sub-award</i> \$68,000 PI share: full amount	[2022-2023]
Co-I: SURP: Fast planning under uncertainty with operational and safety guarantees <i>NASA Jet Propulsion Laboratory</i> \$120,000 (PI: Federico Rossi, JPL) My share: \$100,000 Co-Is: Martin Feather (JPL), Morteza Lahijanian	[2022-2024]
PI: Elektra: Naval Defensive Resource Allocation through POMDP Optimization <i>Office of Naval Research (Subcontract of Johns Hopkins University Applied Physics Lab)</i> \$169,805 PI share: full amount	[2021 – 2023]
Co-I: L3Harris Modern Analytics for Mission Applications (LMA2) <i>L3-Harris Technologies</i> \$1,495,048 (PI: Marcus Holzinger) My share: \$350,000 (approx.)	[2021-2023]
Co-PI: Full Stack Planning and Control under Uncertainty <i>NSF Center for Unmanned Aircraft Systems (C-UAS) Sub-award</i> \$130,000 (with Co-PI Ella Atkins, Univ. of Michigan) My share: \$65,000	[2021 – 2022]
PI: POMDP Algorithms for In-flight Learning in Emergencies <i>NSF Center for Unmanned Aircraft Systems (C-UAS) Sub-award</i> \$60,000 PI share: full amount	[2020 – 2021]

Research Positions

Autonomous Decision and Control Laboratory (ADCL) <i>Director</i> University of Colorado, Boulder, CO	[January 2020 – Present]
Hybrid Systems Laboratory <i>Postdoctoral Research Scholar</i> University of California, Berkeley, CA	[October 2018 – October 2019]
Stanford Intelligent Systems Laboratory (SISL) <i>Graduate Research Assistant</i> Stanford University, Stanford, CA	[2015 – 2018]
Autonomous Systems Laboratory (ASL) <i>Graduate Research Assistant</i> Stanford University, Stanford, CA	[2014 – 2016]
Hansen Experimental Physics Lab <i>Graduate Research Assistant</i> Stanford University, Stanford, CA	[2013 – 2014]
Helicopters and Unmanned Systems Laboratory (HUSL) <i>Graduate Research Assistant</i> Texas A&M University, College Station, TX	[2011 – 2013]
Air Force Research Lab Summer Faculty Program <i>Research Assistant</i> Kirtland AFB, Albuquerque, NM	[Summer 2011]

Industry Experience

Google, Inc. , Mountain View, CA <i>Software Engineering Intern</i> Evaluated and optimized a NASA collision avoidance program for use with Google self-piloted air vehicles.	[Summer 2014]
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Lockheed Martin Autonomous Systems, Littleton, CO

[Summer 2009]

Intern

Helped in testing of autonomous SMSS allterrain military transport vehicle navigation system; wrote rough terrain navigation program in C++ based on the A* search algorithm; wrote software in C++ for analyzing the performance of an advanced video analysis tool.

Invited and Contributed Talks and Panels

2022

University of Illinois Urbana-Champaign (UIUC): Safe and efficient autonomy in the face of uncertainty.

University of Texas at Austin: Safe and efficient autonomy in the face of uncertainty.

Korea Advanced Institute of Science and Technology (KAIST): Safe and efficient autonomy in the face of state and interaction uncertainty.

2021

AIAA Rocky Mountain Annual Technical Symposium: “Machine Learning in Aerospace Systems” (panel)

JuliaCon 2021: POMDPs.jl and Interactive Assignments in Julia

NASA Jet Propulsion Lab, Pasadena, CA: Scalable online POMDP planning for safe and efficient autonomy

Johns Hopkins University Applied Physics Lab, Laurel, MD: Some Recent Advances in Online POMDP Algorithms

2019

SRI International, Palo Alto, CA: Safety and Efficiency for Autonomous Vehicles through Online Learning

Washington State University, Pullman, WA: Safety and Efficiency for Autonomous Vehicles through Online Learning

University of Colorado, Boulder, CO: Safety and Efficiency for Autonomous Vehicles through Online Learning

2018

Renault-Nissan Research, Sunnyvale, CA: Safety and Efficiency in Autonomous Vehicles through POMDP Planning

Lyft Level 5, Palo Alto, CA: Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty

Makani, Alameda, CA: Algorithms for Uncertain, Non-convex Control Problems in the Real World

Indeed, San Francisco, CA: Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty

2017

Julia in Controls Workshop, ACC, Seattle, WA: POMDPs.jl

Open Source Software for Decision Making (OSS4DM), Stanford, CA: POMDPs.jl - Challenges and Lessons Learned

Teaching

ASEN 3128 Aircraft Dynamics

[2022 – Present]

University of Colorado Boulder

ASEN 5264 Decision Making under Uncertainty

[2020 – present]

University of Colorado Boulder

Developed new entry-level graduate course about decision making under uncertainty.

Open-source course materials: <https://github.com/zsunberg/CU-DMU-Materials>

Open-source companion software package: <https://github.com/zsunberg/DMUStudent.jl>

ASEN 6519 Advanced Survey of Sequential Decision Making

[2021, 2023]

University of Colorado Boulder

Developed new advanced graduate course that surveys recent advances in decision making under uncertainty.

ASEN 4018/4028 Senior Design Project

[2020 – 2021]

University of Colorado Boulder

Advised senior design project teams, created new optimization-based approach (see Open Source Software) for fairly creating teams based on student preferences [27].

Army High Performance Computing Summer Institute

[June 2017]

Stanford University, Stanford, CA

Developed and taught a 5 lecture course about decision making under uncertainty for college students.

Stanford Artificial Intelligence Lab OutReach Summer (SAILORS, now AI4ALL) [2015-2017]
Stanford University, Stanford, CA

Developed and taught a 2 week course and project for high school students that included programming robots for optical line following and using Dijkstra's algorithm to find the shortest path on a road network; only project mentor to serve all three years of the program. <http://ai-4-all.org/>

AA-228/CS-238 Decision Making Under Uncertainty [Autumn 2016]
Stanford University, Stanford, CA

Head course assistant for a class of around 200; developed problems for midterm project; gave guest lectures on the POMDPs.jl framework and autonomous driving research; project software was reused in a course at Iowa State University.

Advising and Mentoring

Graduated Ph.D. Thesis Advisees.....

Hyun Jae (Michael) Lim (Co-advised with Claire Tomlin at U.C. Berkeley) [2020 – 2023]
AI Scientist, C3.ai

Current Ph.D. Thesis Advisees.....

Tyler Becker	[Fall 2020 – Present]
Qi Heng Ho	[Fall 2020 – Present]
Ben Kraske (Received NSF GRFP under my direction)	[Fall 2020 – Present]
Himanshu Gupta	[Fall 2020 – Present]
Zakariya Laouar	[Fall 2021 – Present]
Jackson Wagner	[Summer 2022 – Present]

Graduated M.S. Thesis Advisees.....

William Pope [*U.S. Space Force Officer*] [Spring 2022 – Fall 2022]

Independent Study Advisees.....

Johnathan Tucker (Received NSF GRFP under my direction) [Fall 2020 – Summer 2022]
Saurabh Mishra [Spring 2020]

Ph.D. Comprehensive Exam and Defense Committees.....

Sangwoo Moon	Prashin Sharma (Univ. of Michigan)
Charles (Luke) Burks	Shakeeb Ahmad
Neha Garg (Nat. Univ. of Singapore, External Examiner)	John Mern (Stanford Univ.)
Ramya Kanlapuli	Aastha Acharya
Katherine Glasheen	Shohei Wakayama
Andrew Mills	Marcus Lapeyrolerie (Univ. of California, Berkeley, Qualls)
Chandranth Venigalla	John R. Martin
Sam Fedeler	Adam Herrmann
John Jackson	

M.S. Thesis Committees.....

Lasse Peters (TU Hamburg)	Akash Ratheesh
Wyatt Raich	Jamison McGinley
Cody Charland	Rio McMahon

Department Service and Outreach

Undergraduate Operations Committee	[2023–present]
Graduate Program Committee	[2020–2023]
<i>Autonomous Systems Lead</i>	
Served on Preliminary Exam Subcommittee, Revised MS Admissions Criteria	
Smead aerospace career panelist	[2023]
Rising Stars in Aerospace organizing committee member	[2022]
Speaker for Tuskegee Airmen outreach event at CU	[2021, 2022]
Invited Speaker for AIAA Movie Night & Technical Discussion: 2001: A Space Odyssey	[2021]

Conference and Workshop Organization

Strategic multi-agent interactions: game theory for robot learning and decision making	[2022]
<i>Workshop at the Conference on Robotic Learning (CoRL)</i>	
Co-organizer with David Fridovich-Keil (Univ. of Texas), Negar Mehr (Univ. of Illinois), and Forrest Laine (Vanderbilt)	
Inference and Decision Making for Autonomous Vehicles (IDMAV)	[2023]
<i>Workshop at Robotics: Science and Systems (RSS)</i>	
Co-organizer with Christoffer Heckman, Han-Lim Choi (KAIST), and students	

Academic Peer Review and Editing

Guest editor for the AIAA Journal of Aerospace Information Systems	[2020 – 2022]
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Reviewer: I have reviewed manuscripts for the following journals and conferences:

Journal of Artificial Intelligence Research	International Symposium on Robotics Research
AIAA Journal of Guidance, Control, and Dynamics	Intl. Conference on Robotics and Automation (ICRA)
IEEE Robotics and Automation Letters	Intl. Joint Conference on Artificial Intelligence (IJCAI)
IEEE Transactions on Cybernetics	AAAI Conference on Artificial Intelligence
IEEE Transactions on Intelligent Transportation Systems	American Control Conference (ACC)
IEEE Transactions on Intelligent Vehicles	Intelligent Transportation Systems Conference (ITSC)
Journal of Aerospace Information Systems	Robotics, Science and Systems (RSS)
Autonomous Robots	Learning for Decision and Control Conference (L4DC)
Intl. Journal of Robotics Research	
Journal of the American Helicopter Society	

Fellowships and Awards

AIAA Journal of Guidance, Control, and Dynamics Excellent Reviewer	[2021,2022]
IJCAI 2019 Distinguished Program Committee member	[2019]
Association for the Advancement of Artificial Intelligence Doctoral Consortium	[February 2018]
American Control Conference Student Travel Award	[May 2017]
National Science Foundation Graduate Research Fellowship	[2012-2016]