

# Zachary Nolan Sunberg

Ann and H. J. Smead Aerospace Engineering Sciences  
University of Colorado Boulder  
720-933-7799 • zachary.sunberg@colorado.edu • zachary.sunberg.net

## Academic Appointments

**Assistant Professor** [January 2020 – Present]  
*University of Colorado, Boulder, CO*  
Ann and H. J. Smead Aerospace Engineering Sciences Department

**Postdoctoral Research Scholar** [October 2018 – October 2019]  
*University of California, Berkeley, CA*  
Supervisor: Claire Tomlin, Hybrid Systems Laboratory

## Education

**Doctor of Philosophy in Aeronautics and Astronautics** [2018]  
*Stanford University, Stanford, CA*  
Advisor: Mykel Kochenderfer | Thesis: “Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty”

**Master of Science in Aerospace Engineering** [2013]  
*Texas A&M University, College Station, TX*  
Advisor: Jonathan Rogers | Thesis: “A Real Time Expert Control System for Helicopter Autorotation”

**Bachelor of Science in Aerospace Engineering** [2011]  
*Texas A&M University, College Station, TX*  
Summa cum Laude, Minor in Mathematics

## Industry Experience

**Google, Inc., Mountain View, CA** [Summer 2014]  
*Software Engineering Intern*  
Evaluated and optimized a NASA collision avoidance program for use with Google self-piloted air vehicles.

**Lockheed Martin Autonomous Systems, Littleton, CO** [Summer 2009]  
*Intern*  
Helped in testing of autonomous SMSS allterrain military transport vehicle navigation system; wrote rough terrain navigation program in C++ based on the A\* search algorithm; wrote software in C++ for analyzing the performance of an advanced video analysis tool.

## Publications

**Peer Reviewed Journal Articles**

[J1] Prashin Sharma, **Benjamin Kraske**, Joseph Kim, **Zakariya Laouar**, Ella Atkins, and **Zachary Sunberg**. “Risk-Aware Markov Decision Process Contingency Management Autonomy for Uncrewed Aircraft Systems”. In: *AIAA Journal of Aerospace Information Systems (JAIS)* (2024). URL: [🔗](#)

[J2] **Qi Heng Ho**, **Zachary N. Sunberg**, and Morteza Lahijanian. “Sampling-based Reactive Synthesis for Nondeterministic Hybrid Systems”. In: *Robotics and Automation Letters (RA-L)* (2024). URL: [🔗](#)

[J3] **Michael H. Lim**, **Tyler J. Becker**, Mykel J. Kochenderfer, Claire J. Tomlin, and **Zachary N. Sunberg**. “Optimality Guarantees for Particle Belief Approximation of POMDPs”. In: *Journal of Artificial Intelligence Research* (2023). URL: [🔗](#)

[J4] Benjamin W. Blonder, **Michael H. Lim**, **Zachary Sunberg**, and Claire Tomlin. “Navigation between initial and desired community states using shortcuts”. In: *Ecology Letters* (2023). URL: [🔗](#)

- [J5] **Zachary Sunberg** and Mykel Kochenderfer. “Improving Automated Driving through Planning with Human Internal States”. In: *IEEE Transactions on Intelligent Transportation Systems* (2022). URL: [🔗](#)
- [J6] Shakeeb Ahmad, **Zachary N. Sunberg**, and J. Sean Humbert. “End-to-End Probabilistic Depth Perception and 3D Obstacle Avoidance using POMDP”. in: *Journal of Intelligent & Robotic Systems* 103.2 (2021), pp. 1–18
- [J7] **Patrick Slade**, **Zachary Sunberg**, and Mykel J. Kochenderfer. “Estimation and Control Using Sampling-Based Bayesian Reinforcement Learning”. In: *IET Cyber-Physical Systems: Theory and Applications* 5 (1 2020). URL: [🔗](#)
- [J8] Maxim Egorov, **Zachary N. Sunberg**, Edward Balaban, Tim A. Wheeler, Jayesh K. Gupta, and Mykel J. Kochenderfer. “POMDPs.jl: A Framework for Sequential Decision Making under Uncertainty”. In: *Journal of Machine Learning Research* 18.26 (2017), pp. 1–5. URL: [🔗](#)
- [J9] **Zachary Sunberg**, Suman Chakravorty, and Richard Scott Erwin. “Information Space Receding Horizon Control for Multisensor Tasking Problems”. In: *IEEE Transactions on Cybernetics* 46.6 (2016), pp. 1325–1336. URL: [🔗](#)
- [J10] **Zachary N. Sunberg**, Nathaniel R. Miller, and Jonathan D. Rogers. “A Real-Time Expert Control System For Helicopter Autorotation”. In: *Journal of the American Helicopter Society* 60.2 (2015), pp. 1–15. ISSN: 2161-6027. DOI: 10.4050/JAHS.60.022008. URL: [🔗](#)
- [J11] **Zachary Sunberg**, Suman Chakravorty, and Richard Scott Erwin. “Information Space Receding Horizon Control”. In: *IEEE Transactions on Cybernetics* 43.6 (2013), pp. 2255–2260. URL: [🔗](#)
- [J12] **Zachary Sunberg** and Jonathan Rogers. “A Belief Function Distance Metric for Orderable Sets”. In: *Information Fusion* 14.4 (2013), pp. 361–373. ISSN: 1566-2535. DOI: 10.1016/J.INFFUS.2013.03.003. URL: [🔗](#)

### Peer Reviewed Journal-Equivalent Conference Publications.....

Journal-equivalent conference publications, as defined by the Smead Aerospace Department, have rigorous peer review of the entire article, an acceptance rate of approximately 30% or less, and recognition in the field that these publications are as important as journal papers.

- [JC1] **Qi Heng Ho**, **Tyler Becker**, **Benjamin Kraske**, **Zakariya Laouar**, Martin S. Feather, Federico Rossi, Morteza Lahijanian, and **Zachary N Sunberg**. “Recursively-Constrained Markov Decision Processes”. In: *The 40th Conference on Uncertainty in Artificial Intelligence*. (Oral). 2024. URL: [🔗](#)

### Journal-Equivalent Peer Reviewed Conference Publications

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- [1] **Qi Heng Ho**, **Tyler Becker**, **Benjamin Kraske**, **Zakariya Laouar**, Martin S. Feather, Federico Rossi, Morteza Lahijanian, and **Zachary N Sunberg**. “Recursively-Constrained Markov Decision Processes”. In: *The 40th Conference on Uncertainty in Artificial Intelligence*. (Oral). 2024. URL: [🔗](#).
- [2] Matt-Heun Hong, **Zachary Sunberg**, and Danielle Szafir. “Cieran: Designing Sequential Colormaps with a Teachable Robot”. In: *Human Factors in Computing Systems (CHI)*. 2024.
- [3] **Himanshu Gupta**, Bradley Hayes, and **Zachary Sunberg**. “Intention-Aware Navigation in Crowds with Extended-Space POMDP Planning”. In: *Autonomous Agents and Multi-Agent Systems (AAMAS)*. 2022. URL: [🔗](#).
- [4] John Mern, Anil Yildiz, **Zachary Sunberg**, Tapan Mukerji, and Mykel J. Kochenderfer. “Bayesian Optimized Monte Carlo Planning”. In: *AAAI Conference on Artificial Intelligence (AAAI)*. 2021.
- [5] **Michael H. Lim**, Claire J. Tomlin, and **Zachary N. Sunberg**. “Sparse Tree Search Optimality Guarantees in POMDPs with Continuous Observation Spaces”. In: *International Joint Conference on Artificial Intelligence (IJCAI)*. 2020.
- [6] **Lasse Peters**, David Fridovich-Keil, Claire Tomlin, and **Zachary Sunberg**. “Inference-Based Strategy Alignment for General-Sum Differential Games”. In: *International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*. 2020. URL: [🔗](#).

- [7] **Zachary N. Sunberg** and Mykel J. Kochenderfer. “Online Algorithms for POMDPs with Continuous State, Action, and Observation Spaces”. In: *International Conference on Automated Planning and Scheduling (ICAPS)*. 2018. URL: [🔗](#).

## Open Source Software

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**POMDPs.jl** [2015 – present]

<https://github.com/JuliaPOMDP/POMDPs.jl>

Interface for defining continuous and discrete, fully and partially observable Markov decision processes along with a suite of state-of-the-art solvers written in Julia and C++.

**ProjectAssigner.jl** [2020]

<https://github.com/zsunberg/ProjectAssigner.jl>

Software for optimally assigning student teams to projects based on preferences, friend groups, and skills [0]. Used to assign senior project groups in the AES department since 2020.

## Research Funding

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**Co-I: Collaborative Research: Alternative Leaf Water use Strategies in Hot Environments** [2023 – 2024]

*National Science Foundation*

\$99,976 | Subcontract from UC Berkeley (listed amount is my subcontract)

**PI: Human Centered Autonomy for Dynamic sUAS Target Search Operations** [2023 – 2024]

*NSF Center for Autonomous Air Mobility and Sensing (CAAMS) Sub-award*

\$111,000 | PI share: \$60,000 (approx.)

**Co-I: Multi-Phenomenological, Autonomous ... Decision Support** [2023 – 2028]

*Air Force Office of Scientific Research*

\$5,000,000 (approx., PI: Marcus Holzinger) | My share: \$500,000 (approx.) | Co-Is: K. Terry Alfriend (TAMU), Scott Palo, Kyle DeMars (TAMU), John Junkins (TAMU), Karen Feigh (Georgia Tech) | Full title: Multi-Phenomenological, Autonomous, and Understandable SDA and XDA Decision Support

**Co-I: IUCRC Phase I: Center for Autonomous Air Mobility and Sensing (CAAMS)** [2022 – 2027]

*National Science Foundation*

\$2,210,225 (PI: Eric Frew) | Co-Is: Nisar Ahmed, Morteza Lahijanian, Sriram Sankaranarayanan | This grant establishes the IUCRC and pays for administrative costs; sub-awards funded through industry contributions will be listed separately.

**Co-I: Dispersed Autonomy for Marsupial Aerial Robot Teams** [2022 – 2025]

*National Science Foundation | National Robotics Institute (Collaborative Research)*

\$1,045,429 (PI: Eric Frew) | My share: \$300,000 (approx.) | Co-Is: Brian Argrow, Adam Houston (University of Nebraska, Lincoln)

**PI: HIPPO (Human-Informed Planning with Probabilistic Observations)** [2022-2023]

*NSF Center for Autonomous Air Mobility and Sensing (CAAMS) Sub-award*

\$68,000 | PI share: full amount

**Co-I: SURP: Fast planning under uncertainty with operational and safety guarantees** [2022-2024]

*NASA Jet Propulsion Laboratory*

\$120,000 (PI: Federico Rossi, JPL) | My share: \$100,000 | Co-Is: Martin Feather (JPL), Morteza Lahijanian

**PI: Elektra: Naval Defensive Resource Allocation through POMDP Optimization** [2021 – 2023]

*Office of Naval Research (Subcontract of Johns Hopkins University Applied Physics Lab)*

\$169,805 | PI share: full amount

**Co-I: L3Harris Modern Analytics for Mission Applications (LMA2)** [2021-2023]

*L3-Harris Technologies*

\$1,495,048 (PI: Marcus Holzinger) | My share: \$350,000 (approx.)

**Co-PI: Full Stack Planning and Control under Uncertainty** [2021 – 2022]

*NSF Center for Unmanned Aircraft Systems (C-UAS) Sub-award*

\$130,000 (with Co-PI Ella Atkins, Univ. of Michigan) | My share: \$65,000

**PI: POMDP Algorithms for In-flight Learning in Emergencies**  
*NSF Center for Unmanned Aircraft Systems (C-UAS) Sub-award*  
\$60,000 | PI share: full amount

[2020 – 2021]

## Invited and Contributed Talks and Panels

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**2024**

**University of California, San Diego:** Breaking the curse of dimensionality in POMDPs with sampling-based online planning.

**2022**

**University of Illinois Urbana-Champaign (UIUC):** Safe and efficient autonomy in the face of uncertainty.

**University of Texas at Austin:** Safe and efficient autonomy in the face of uncertainty.

**Korea Advanced Institute of Science and Technology (KAIST):** Safe and efficient autonomy in the face of state and interaction uncertainty.

**2021**

**AIAA Rocky Mountain Annual Technical Symposium:** “Machine Learning in Aerospace Systems” (panel)

**JuliaCon 2021:** POMDPs.jl and Interactive Assignments in Julia

**NASA Jet Propulsion Lab, Pasadena, CA:** Scalable online POMDP planning for safe and efficient autonomy

**Johns Hopkins University Applied Physics Lab, Laurel, MD:** Some Recent Advances in Online POMDP Algorithms

**2019**

**SRI International, Palo Alto, CA:** Safety and Efficiency for Autonomous Vehicles through Online Learning

**Washington State University, Pullman, WA:** Safety and Efficiency for Autonomous Vehicles through Online Learning

**University of Colorado, Boulder, CO:** Safety and Efficiency for Autonomous Vehicles through Online Learning

**2018**

**Renault-Nissan Research, Sunnyvale, CA:** Safety and Efficiency in Autonomous Vehicles through POMDP Planning

**Lyft Level 5, Palo Alto, CA:** Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty

**Makani, Alameda, CA:** Algorithms for Uncertain, Non-convex Control Problems in the Real World

**Indeed, San Francisco, CA:** Safety and Efficiency in Autonomous Vehicles through Planning with Uncertainty

**2017**

**Julia in Controls Workshop, ACC, Seattle, WA:** POMDPs.jl

**Open Source Software for Decision Making (OSS4DM), Stanford, CA:** POMDPs.jl - Challenges and Lessons Learned

## Teaching

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**At CU Boulder**.....

**ASEN 3728/3128 Aircraft Dynamics**

[2022 – Present]

*University of Colorado Boulder*

**ASEN 5264 Decision Making under Uncertainty**

[2020 – present]

*University of Colorado Boulder*

Developed new entry-level graduate course about decision making under uncertainty.

Open-source course materials: <https://github.com/zsunberg/CU-DMU-Materials>

Open-source companion software package: <https://github.com/zsunberg/DMUStudent.jl>

**ASEN 6519 Advanced Survey of Sequential Decision Making**

[2021, 2023]

*University of Colorado Boulder*

Developed new advanced graduate course that surveys recent advances in decision making under uncertainty.

**ASEN 4018/4028 Senior Design Project**

[2020 – 2021]

*University of Colorado Boulder*

Advised senior design project teams, created new optimization-based approach (see Open Source Software) for fairly creating teams based on student preferences [0].

## Prior to CU Boulder

### Army High Performance Computing Summer Institute

[June 2017]

Stanford University, Stanford, CA

Developed and taught a 5 lecture course about decision making under uncertainty for college students.

### Stanford Artificial Intelligence Lab Outreach Summer (SAILORS, now AI4ALL)

[2015-2017]

Stanford University, Stanford, CA

Developed and taught a 2 week course and project for high school students that included programming robots for optical line following and using Dijkstra's algorithm to find the shortest path on a road network; only project mentor to serve all three years of the program. <http://ai-4-all.org/>

### AA-228/CS-238 Decision Making Under Uncertainty

[Autumn 2016]

Stanford University, Stanford, CA

Head course assistant for a class of around 200; developed problems for midterm project; gave guest lectures on the POMDPs.jl framework and autonomous driving research; project software was reused in a course at Iowa State University.

## Advising and Mentoring

### Graduated Ph.D. Thesis Advisees

Hyun Jae (Michael) Lim (Co-advised with Claire Tomlin at U.C. Berkeley)

[2020 – 2023]

AI Scientist, C3.ai

### Current Ph.D. Thesis Advisees

Tyler Becker

[Fall 2020 – Present]

Qi Heng Ho

[Fall 2020 – Present]

Ben Kraske (Received NSF GRFP under my direction)

[Fall 2020 – Present]

Himanshu Gupta

[Fall 2020 – Present]

Zakariya Laouar

[Fall 2021 – Present]

Jackson Wagner

[Summer 2022 – Present]

### Graduated M.S. Thesis Advisees

William Pope [U.S. Space Force Officer]

[Spring 2022 – Fall 2022]

### Independent Study Advisees

Johnathan Tucker (Received NSF GRFP under my direction)

[Fall 2020 – Summer 2022]

Saurabh Mishra

[Spring 2020]

### Ph.D. Comprehensive Exam and Defense Committees

Sangwoo Moon

Prashin Sharma (Univ. of Michigan)

Charles (Luke) Burks

Shakeeb Ahmad

Neha Garg (Nat. Univ. of Singapore, External Examiner)

John Mern (Stanford Univ.)

Ramya Kanlapuli

Aastha Acharya

Katherine Glasheen

Shohei Wakayama

Andrew Mills

Marcus Lapeyrolerie (Univ. of California, Berkeley, Qualls)

Chandrakanth Venigalla

John R. Martin

Sam Fedeler

Adam Herrmann

John Jackson

### M.S. Thesis Committees

Lasse Peters (TU Hamburg)

Jamison Mcginley

Wyatt Raich

Rio McMahon

Cody Charland

Eli Kravitz

Akash Ratheesh

## Department Service and Outreach

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Undergraduate Operations Committee	[2023–present]
Graduate Program Committee	[2020–2023]
<i>Autonomous Systems Lead</i>	
Served on Preliminary Exam Subcommittee, Revised MS Admissions Criteria	
Smead aerospace career panelist	[2023]
Rising Stars in Aerospace organizing committee member	[2022]
Speaker for Tuskegee Airmen outreach event at CU	[2021, 2022]
Invited Speaker for AIAA Movie Night & Technical Discussion: 2001: A Space Odyssey	[2021]

## Conference and Workshop Organization

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Inference and Decision Making for Autonomous Vehicles (IDMAV)	[2023]
<i>Workshop at Robotics: Science and Systems (RSS)</i>	
Co-organizer with Christoffer Heckman, Han-Lim Choi (KAIST), and students	
Strategic multi-agent interactions: game theory for robot learning and decision making	[2022]
<i>Workshop at the Conference on Robotic Learning (CoRL)</i>	
Co-organizer with David Fridovich-Keil (Univ. of Texas), Negar Mehr (Univ. of Illinois), and Forrest Laine (Vanderbilt)	

## Academic Peer Review and Editing

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Guest editor for the AIAA Journal of Aerospace Information Systems	[2020 – 2022]
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**Reviewer:** I have reviewed manuscripts for the following journals and conferences:

Journal of Artificial Intelligence Research	R (programming language) Journal
AIAA Journal of Guidance, Control, and Dynamics	International Symposium on Robotics Research
AIAA Journal of Aerospace Information Systems	Intl. Conference on Robotics and Automation (ICRA)
IEEE Robotics and Automation Letters	Intl. Joint Conference on Artificial Intelligence (IJCAI)
IEEE Transactions on Cybernetics	AAAI Conference on Artificial Intelligence
IEEE Transactions on Intelligent Transportation Systems	American Control Conference (ACC)
IEEE Transactions on Intelligent Vehicles	Intelligent Transportation Systems Conference (ITSC)
Autonomous Robots	Robotics, Science and Systems (RSS)
Intl. Journal of Robotics Research (IJRR)	Learning for Decision and Control Conference (L4DC)
Journal of the American Helicopter Society	IEEE Conference on Decision and Control (CDC)
Field Robotics	

## Proposal Review

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NSF CISE Small Proposal Review Panelist	[2023]
Army Research Office (ARO) Proposal Reviewer	[2023]

## Fellowships and Awards

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IET Cyberphysical Systems Journal Premium Paper Award	[2023]
AIAA Journal of Guidance, Control, and Dynamics Excellent Reviewer	[2021,2022]
IJCAI 2019 Distinguished Program Committee member	[2019]
Association for the Advancement of Artificial Intelligence Doctoral Consortium	[February 2018]
American Control Conference Student Travel Award	[May 2017]
National Science Foundation Graduate Research Fellowship	[2012-2016]