

MIDTERM EXAMINATION Winter 2018

DURATION: 1.5 HOURSNo. Of Students: 47

Department Name & Course Number: Systems and Computer Engineering SYSC 4001B

Course Instructor: Thomas Kunz

AUTHORIZED MEMORANDA:

William Stallings, *Operating Systems: Internals and Design Principles*, 9th edition, Pearson 2018, ISBN-9780134670959 (as physical book, no ebook) or earlier versions of that same book.

Students MUST count the number of pages in this examination question paper before beginning to write, and report any discrepancy to a proctor. This question paper has 5 pages + cover page = 6 pages in all.

This examination question paper MAY NOT be taken from the examination room.

In addition to this question paper, students require: an examination booklet: NO

Scantron Sheet: NO

Name:			
Student Number:			
Question 1:	/10		
Question 2:	/10		
Question 3:	/10		
Question 4:	/10		
Total·	/40		

Question 1: Process Description and Control (10 marks)

1.	Consider a computer with A	processors in a multiprocessor	configuration.
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- a. How many processes can be in each of the Ready, Running, and Blocked states at one time?
- **b.** What is the minimum number of processes that can be in each of the Ready, Running, and Blocked states at one time?

2. Consider a system in which the following states are defined for processes: Execute (running), Active (ready), Blocked, and Suspend. A process is blocked if it is waiting for permission to use a resource, and it is suspended if it is waiting for an operation to be completed on a resource it has already acquired. In many operating systems, these two states are lumped together as the blocked state, and the suspended state has the definition we have used in class/the textbook. Compare the relative merits of the two sets of definitions.

-	in which a runnable prod		rerlooked indefinitely by the scheduler, although it is able to
	A) mutual exclusion		B) deadlock
	C) starvation		D) livelock
_	_		a critical section that accesses shared resources, no other process hose shared resources is
	A) critical section		B) livelock
	C) mutual exclusion		D) atomic operation
3) A means for	two processes to exchan	ge infori	mation is with the use of
	A) spinlocks		B) event flags
	C) condition variables		D) messages
4) A semaphor semaphore.	e that does not specify th	ne order i	in which processes are removed from the queue is a
	A) weak	B) gene	eral
	C) strong	D) bina	nry
•	• •		or threads read and write data items so that the final result as in the multiple processes.
	A) atomic operation		B) race condition
	C) livelock		D) deadlock

•	•		ch a process can do nothing until it gets permission to enter its action or set of instructions that tests the appropriate variable to
	A) spin waiting		B) general semaphore
	C) critical resource		D) message passing
7) A is	a data type that is used to	o block a	a process or thread until a particular condition is true.
	A) deadlock		B) general semaphore
	C) condition variable		D) mutex
_	whose definition includ	_	olicy that the process that has been blocked the longest is released hore.
	A) general	B) stror	ng .
	C) weak	D) cour	nting
	is a programming langulis easier to control.	ıage con	struct that provides equivalent functionality to that of
	A) atomic operation		B) coroutine
	C) critical section		D) monitor
•	e most useful combinatio quickly as possible.	on,	allows a process to send one or more messages to a variety of
	A) blocking send, block	king rece	eive
	B) nonblocking send, blocking receive		
	C) nonblocking send, nonblocking receive		
	D) blocking send, nonb	olocking	receive

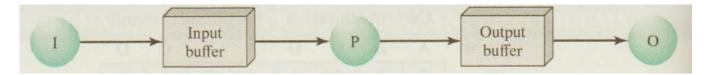
Question 3. Deadlocks (10 marks)

1. A spooling system (see picture below) consists of an input process I, a user process P, and an output process O, connected by two buffers. The processes exchange data in blocks of equal size. These blocks are buffered on a disk using a floating boundary between the input and the output buffers, depending on the speed of the processes. The communication primitives used ensure that the following resource constraint is satisfied:

max = maximum number of blocks on disk

i = number of input blocks on disk

o = number of output blocks on disk



The following is known about the processes:

- As long as the environment supplies data, process I will eventually input it to the disk (provided disk space becomes available).
- As long as input is available on the disk, process P will eventually consume it and output a finite amount of data on the disk for each block input (provided disk space becomes available).
- As long as output is available on the disk, process O will eventually consume it.

Show that this system can become deadlocked.

2. Suggest an additional resource constraint that will prevent the deadlock in the first part, but still permit the boundary between input and output buffers to vary in accordance with the present needs of the processes.

Question 4. Memory Management (10 marks)

1. Consider the following segment table:

Segment	Base	Length
0	1219	600
1	3300	14
2	90	100
3	2327	580
4	1952	96

What are the physical addresses for the following logical addresses?

a. 0, 430

b. 1, 15

c. 2, 50

d. 3, 400

e. 4, 112

2. A system uses (contiguous) dynamic partition memory management, with 110K of memory for user processes. The current memory allocation table (all numbers are in units of K) is shown below:

Job	Base Address	Length
A	20	10
В	46	18
С	90	20

A new job, D, arrives needing 15K of memory. Show the memory allocation table entry for job D for each of the following memory allocation strategies: first fit, best fit, worst fit.

- 3. Consider a logical address space of eight pages of 1024 bytes each, mapped onto a physical memory of 32 frames.
 - **a.** How many bits are there in the logical address?
 - **b.** How many bits are there in the physical address?