

# Programming Machine Learning Algorithms for HPC

- Linear Algebra

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# Linear algebra

Introduction

# Why linear algebra is important?

- Linear algebra is one of the most fundamental and versatile subjects in mathematics.
- The practical skills learned by studying linear algebra—such as manipulating vectors and matrices—form an essential foundation for numerous applications in physics, computer science, statistics, **machine learning**, engineering, and many other fields of scientific and technological study.
- It underpins many modern advancements, from algorithms powering **artificial intelligence** to **data modeling** in **statistics**.

# Linearity

- It is the core of linear algebra.

A function  $f$  is linear if it obeys the following properties:

Additivity:  $f(x_1 + x_2) = f(x_1) + f(x_2)$

Homogeneity (scalar multiplication):  $f(a \cdot x_1) = a \cdot f(x_1)$

$$f(ax_1 + bx_2) = af(x_1) + bf(x_2)$$

- Linear functions transform a linear combination of inputs into the same linear combination of outputs.

# Why Linearity Matters

- **Simplicity:** Linear systems are much easier to solve, analyze, and understand than nonlinear systems. Linearity ensures that superpositions of solutions are also solutions, making problems more tractable.
- **Approximation:** Many complex, nonlinear systems can be approximated locally by linear systems. For instance, in calculus, nonlinear functions are approximated by their linear tangents through linearization.
- **Applications:** Linearity plays a key role in many fields. In physics, for example, linearity is central in quantum mechanics and wave theory. In machine learning, **linear models** like linear regression form the basis for more complex models.

# Definitions

- Vectors and matrices are the objects of study in linear algebra.
- A scalar is a number.
- A vector is a list of numbers.
- A matrix is a rectangular array of numbers with  $m$  rows and  $n$  columns.

Numbers can be naturals, integers, rationals, and real numbers.

# Vector operations $\vec{v}$

- Addition (denoted +)
- Subtraction, the inverse of addition (denoted -)
- Scaling (denoted implicitly)
- Dot product (denoted  $\cdot$ )
- Cross product (denoted  $\times$ )
- Length (denoted  $||\vec{v}||$ )

# Vector operations

Consider two vectors of three dimensions:

$$\vec{u} = (u_1, u_2, u_3) \text{ and } \vec{v} = (v_1, v_2, v_3)$$

$\alpha$  is an arbitrary constant

- $\vec{u} + \vec{v} = (u_1 + v_1, u_2 + v_2, u_3 + v_3)$
- $\vec{u} - \vec{v} = (u_1 - v_1, u_2 - v_2, u_3 - v_3)$
- $\alpha \vec{v} = (\alpha v_1, \alpha v_2, \alpha v_3)$
- $\vec{u} \cdot \vec{v} = (u_1 v_1 + u_2 v_2 + u_3 v_3)$
- $\vec{u} \times \vec{v} = (u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1)$
- $||\vec{v}|| = \sqrt{v_1^2 + v_2^2 + v_3^2}$



# Matrix operations

- Addition (denoted  $A + B$ )
- Subtraction, the inverse of addition (denoted  $A - B$ )
- Scaling by a constant  $\alpha$  (denoted  $\alpha A$ )
- Matrix product (denoted  $AB$ )
- Matrix-vector product (denoted  $A\vec{v}$ )
- Matrix inverse (denoted  $A^{-1}$ )
- Trace (denoted  $\text{Tr}(A)$ )
- Determinant (denoted  $\det(A)$  or  $|A|$ )

# Matrix addition and subtraction

The matrix addition and subtraction operations take pairs of matrices as inputs and produce matrices as outputs:

- $+: \mathbb{R}^{m \times n} \times \mathbb{R}^{m \times n} \rightarrow \mathbb{R}^{m \times n}$
- $-: \mathbb{R}^{m \times n} \times \mathbb{R}^{m \times n} \rightarrow \mathbb{R}^{m \times n}$

For example, addition of two 3x2 matrices a and b:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} + \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \\ b_{31} & b_{32} \end{bmatrix} = \begin{bmatrix} a_{11} + b_{11} & a_{12} + b_{12} \\ a_{21} + b_{21} & a_{22} + b_{22} \\ a_{31} + b_{31} & a_{32} + b_{32} \end{bmatrix}$$

Matrices must have the same dimensions to be added or subtracted.

# Scaling by a constant

- Multiply a matrix by a constant (scalar) value.

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} \alpha = \begin{bmatrix} a_{11}\alpha & a_{12}\alpha \\ a_{21}\alpha & a_{22}\alpha \\ a_{31}\alpha & a_{32}\alpha \end{bmatrix}$$

# Matrix Product

- Done by taking the dot product between each row of matrix A and each column of matrix B to produce matrix C.

$$\begin{array}{l} \vec{r}_1 \rightarrow \\ \vec{r}_2 \rightarrow \end{array} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{array}{l} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \\ \begin{array}{cc} \uparrow & \uparrow \\ \vec{c}_1 & \vec{c}_2 \end{array} \end{array} = \begin{bmatrix} \vec{r}_1 \cdot \vec{c}_1 & \vec{r}_1 \cdot \vec{c}_2 \\ \vec{r}_2 \cdot \vec{c}_1 & \vec{r}_2 \cdot \vec{c}_2 \end{bmatrix}$$

The rows of A must have the same dimension as the columns of B, and the rows of B must have the same dimension as the columns of C.

# Matrix Product rules

- The rows of  $A$  must have the same dimension as the columns of  $B$ , and the rows of  $B$  must have the same dimension as the columns of  $C$ .
- Given two matrices  $A \in \mathbb{R}^{m \times n}$  and  $B \in \mathbb{R}^{n \times k}$ , the product  $AB$  is an  $m \times k$  matrix.
- Matrix multiplication is not a commutative operation:  $AB \neq BA$

# Matrix-vector product

- Product between matrix  $A$  and vector  $\vec{v}$ . We need to view the vector as a column matrix.
- Dot product of  $\vec{v}$  with every row of  $A$ .
- The number of columns in  $A$  equals the number of columns in  $\vec{v}$ .

For example:

$$\begin{matrix} \vec{r}_1 \rightarrow \\ \vec{r}_2 \rightarrow \end{matrix} \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \vec{r}_1 \cdot \vec{v} \\ \vec{r}_2 \cdot \vec{v} \end{bmatrix}$$

# Matrix Inverse

- The formula for the inverse of a square matrix:

$$A^{-1} = \frac{1}{|A|} \cdot Adj A$$

- A is the square matrix (n x n).
  - Adj(A) is the adjoint matrix of A.
  - |A| is the determinant of A.
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- Note: the matrix should be square, and the determinant should not be equal to zero.

# Matrix Trace

- The sum of elements on the main diagonal from the upper left to the lower right of A.
- Can only be for a square matrix.
- Example:

$$\begin{bmatrix} \mathbf{a_{11}} & a_{12} & a_{13} \\ a_{21} & \mathbf{a_{22}} & a_{23} \\ a_{31} & a_{32} & \mathbf{a_{33}} \end{bmatrix}$$



# Matrix Determinant

- The determinant of matrix A, is an operation that give us useful information about the linear independence of the rows of the matrix.
- The determinant of a triangular matrix is the product of its diagonal entries.
- The determinant of 2x2 matrix:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

# Matrix Determinant Example

- The determinant of 3x3 matrix:

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{13}a_{22}a_{31} - a_{12}a_{21}a_{33} - a_{11}a_{23}a_{32}$$

- Pattern:

$$\begin{bmatrix} a_{11} \times & & \\ & a_{22} & a_{23} \\ & a_{32} & a_{33} \end{bmatrix} - \begin{bmatrix} & a_{12} \times & \\ a_{21} & & a_{23} \\ a_{31} & & a_{33} \end{bmatrix} + \begin{bmatrix} & & a_{13} \times \\ a_{21} & a_{22} & \\ a_{31} & a_{32} & \end{bmatrix}$$

# Homework

Develop Python code for:

- Vector: dot product and cross product.
- Matrix: Addition, subtraction, matrix product, matrix-vector product.

Rules:

- Use only Python (no libraries).
- Put in comments the complexity of the code (O notation).
- Use Numpy as well and compare the time it takes to run with both of them.
- Send it to us by mail in a zip file (no .py code).

# Homework function descriptions

1. `vector_dot_product(v1, v2)`: Computes the dot product of two vectors.
2. `vector_cross_product(v1, v2)`: Computes the cross product of two 3D vectors.
3. `matrix_addition(A, B)`: Adds two matrices of the same size.
4. `matrix_subtraction(A, B)`: Subtracts matrix B from matrix A, element-wise.
5. `matrix_product(A, B)`: Multiplies two matrices.
6. `matrix_vector_product(A, v)`: Multiplies a matrix by a vector.

# Use case

- Logistic Regression algorithm:

The training process using gradient descent follows these steps:

**1. Initialize the weights:** Start with random values for  $w_0, w_1, w_2$ .

**2. For each epoch** (iteration over the entire dataset):

1. For each training example  $(x_1, x_2, y)$  :

1. Compute  $z = w_0 + w_1x_1 + w_2x_2$

2. Apply the sigmoid function to get the predicted probability  $\hat{y} = \sigma(z)$ .

3. Compute the loss using binary cross-entropy.

4. Compute the gradients for each weight  $w_0, w_1, w_2$ .

5. Update the weights using gradient descent.

2. After the epoch, evaluate the performance of the model (optional).

**3. Repeat** until the loss converges (i.e., stops changing significantly).