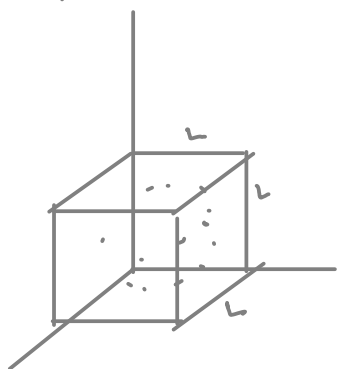


4 system study approaches

- Energy thermo
- Matter stat mech, solid state
- Waves EM, quantum
- Mathematical Modelling Diffusion, Random walk.

— X —
STAT MECH
— X —



System: N particles

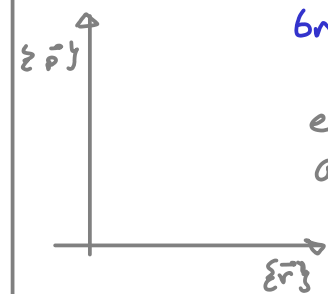
$$x_i, y_i, z_i \in [0, L] \quad \forall i$$

$$V = L^3$$

$$\{\vec{r}_i\} = (x_i, y_i, z_i)$$

$$|\{\vec{r}\}| = |\{\vec{p}\}| = 3N$$

State Space



6n dimensional space
each point defines a microstate.

Hamiltonian function Gives total energy of the system

$$H(\{\vec{r}\}, \{\vec{p}\}) = U(\{\vec{r}\}) + K(\{\vec{p}\})$$

Hamilton's Equations

Isolated System: No energy exchange with surroundings.

$$\frac{d}{dt} H(\{\vec{r}\}, \{\vec{p}\}) = 0$$

$$\Rightarrow \sum_{i=1}^N \left\{ \frac{\partial H}{\partial \vec{r}_i} \cdot \frac{d\vec{r}_i}{dt} + \frac{\partial H}{\partial \vec{p}_i} \cdot \frac{d\vec{p}_i}{dt} \right\} = 0.$$

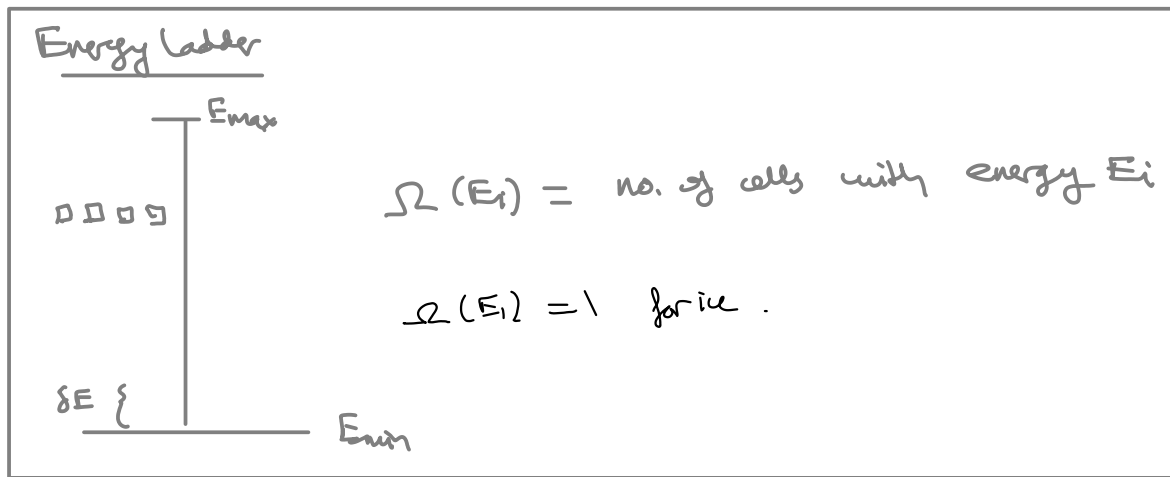
$$\frac{d\vec{r}_i}{dt} = \left(\frac{dx_i}{dt}, \frac{dy_i}{dt}, \frac{dz_i}{dt} \right)$$

$$\frac{\partial H}{\partial \vec{r}_i} = - \frac{\partial \vec{p}_i}{\partial t}$$

$$\frac{\partial H}{\partial \vec{p}_i} = \frac{d\vec{r}_i}{dt}$$

Hamilton's Equations

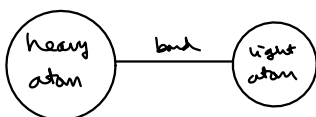
force
velocity.



● Boltzmann entropy $S \propto \ln(\Omega(E_i))$
 Microscopic definition of entropy. $S = k_B \ln(\Omega(E_i))$

CALCULATIONS IN AN ISOLATED SYSTEM

① 1D Harmonic Oscillation (calculate $\Omega(E)$)

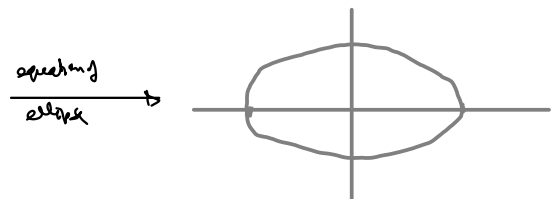


$m = \text{mass of light atom}$

$$H(x, p) = \frac{p^2}{2m} + \frac{1}{2} k(x - x_0)^2 = E$$

Rearranging,

$$\frac{p^2}{\sqrt{2mE}} + \frac{(x - x_0)^2}{\left(\sqrt{\frac{2E}{k}}\right)^2} = 1$$



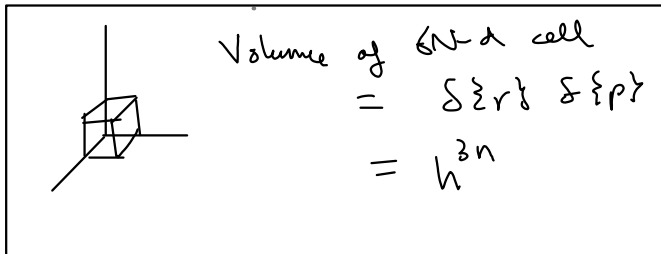
Using ellipse model,

$$\Omega(E_i) = \text{circumference of ellipse} / \delta E.$$

$$\text{or } \Omega(E) \propto \pi \left(\sqrt{\frac{2-E}{K}} + \sqrt{2mE} \right)$$

$$\text{or } \Omega(E) \propto \sqrt{E}$$

2. Ideal Gas Calculate $\Omega(E)$ dependence on N



$h = \text{arbitrary}$

$h = \text{Planck's constant}$ in QM

$$\delta(H-E) = \begin{cases} 1 & \text{if } H=E \\ 0 & \text{otherwise.} \end{cases} \quad \left. \begin{array}{l} \text{Kronecker} \\ \text{Delta} \end{array} \right\}$$

$$\Omega(N, V, E) = \frac{1}{h^{3n}} \int_{\{\vec{r}\}} \int_{\{\vec{p}\}} \delta(H-E) \delta\{\vec{r}\} \delta\{\vec{p}\}$$

$$= \frac{1}{h^{3N}} V^N \int_{\{\vec{p}\}} \delta(H-E) \delta\{\vec{p}\}$$

Hamiltonian funct.

$$H(\vec{r}, \vec{p}) = \frac{1}{2m} \sum \vec{p}_i \cdot \vec{p}_i$$

Now, $\sum p^2 = (\sqrt{2mE})^2 \Rightarrow \text{sphere.}$

surface area $\propto (\sqrt{2mE})^{3N-1}$

$$\propto E^{\frac{3N-1}{2}}$$

$$\Omega(N, V, E) \propto \frac{1}{h^{3N}} V^N E^{\frac{3N-1}{2}}$$

CALCULATIONS IN A CLOSED SYSTEM

● $P(E_i) \propto e^{-\beta E_i}$, $\beta = \frac{1}{k_B T}$

● $P(E_i) = \frac{e^{-\beta E_i}}{Z}$ $Z = \frac{e^{-\beta E_i}}{P(E_i)}$

● $Z = \frac{1}{h^{3N}} \int_{\{\vec{r}\}} \int_{\{\vec{p}\}} e^{-\beta H(\{\vec{r}\}, \{\vec{p}\})} d\{\vec{r}\} d\{\vec{p}\}$

1. 1D Harmonic Oscillator $\langle E \rangle$

$$Z = \sum e^{-\beta E_i}$$

$$\ln Z = \ln \sum e^{-\beta E_i}$$

$$\frac{\partial}{\partial \beta} (\ln Z) = - \frac{1}{\sum e^{-\beta E_i}} \sum E_i e^{-\beta E_i}$$

$$= - \frac{\sum E_i (e^{-\beta E_i})}{Z}$$

$$= - \sum E_i P(E_i)$$

$$-\frac{\partial}{\partial \beta} (\ln Z) = \langle E \rangle$$

2. Covariance and C_v

$$\frac{\partial}{\partial \beta} \left(\sum E_i e^{-\beta E_i} \right) = \frac{\partial}{\partial \beta} \left(-Z \frac{\partial}{\partial \beta} (\ln Z) \right)$$

$$+ \sum E_i^2 e^{-\beta E_i} = \left[Z \frac{d^2}{d\beta^2} (\ln Z) + \frac{\partial Z}{\partial \beta} \frac{\partial}{\partial \beta} (\ln Z) \right]$$

$$\langle E_i^2 \rangle = \frac{d^2}{d\beta^2} (\ln Z) + \left[\frac{d}{d\beta} (\ln Z) \right]^2$$

$$\langle E^2 \rangle - \langle E \rangle^2 = \frac{d^2}{d\beta^2} (\ln Z)$$

Now,

$$\langle E^2 \rangle - \langle E \rangle^2 = \frac{-\frac{\partial \langle E \rangle}{\partial T}}{\frac{\partial \beta}{\partial T}} = \frac{-C_V}{-\frac{1}{k_B T^2}} = C_V k_B T^2$$

$$\frac{d^2}{d\beta^2} \ln Z = \frac{\partial}{\partial \beta} \langle E \rangle$$

$$\beta = \frac{1}{k_B T}$$

$$\frac{d\beta}{dT} = -\frac{1}{k_B T^2}$$

Entropy for a closed system

$$S = -k_B \sum P_i \ln P_i = -k_B \langle \ln P \rangle$$

3. Helmholtz free energy

$$S = -k_B \sum_i \left(\frac{e^{-\beta E_i}}{Z} \right) \left(-\beta E_i - \ln Z \right)$$

$$= \beta k_B \sum E_i P_i + k_B \ln Z \sum P_i$$

$$S = \frac{\langle E \rangle}{T} + k_B \ln Z$$

or $-k_B T \ln Z = \langle E \rangle - TS$

Lagrangian Mechanics

- Lagrangian: $L(q, \dot{q}, t)$

generalised coordinates

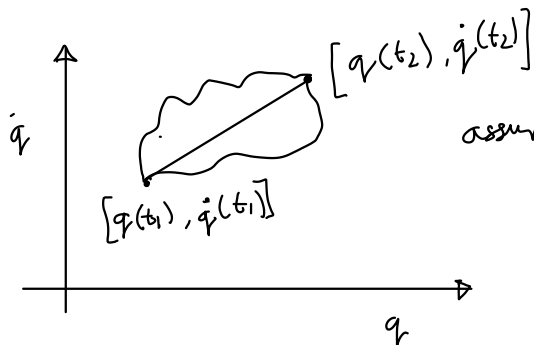
generalised velocity

$$\dot{q} = \frac{dq}{dt}$$

dependence on time is implicit.

$$L = K(\dot{q}) - U(q)$$

- In state space:



Taking the least action path.

$$Action(S) = \int_{t_1}^{t_2} L(q, \dot{q}, t) dt$$

DERIVING LAGRANGE'S EQUATIONS OF MOTION

• Consider 2 paths: least action, and something else.

$(q(t), \dot{q}(t)) \rightarrow$ least action path.

$(q(t) + \delta q(t), \dot{q}(t) + \delta \dot{q}(t)) \rightarrow$ other path.

• The paths must meet at t_1 and t_2 .

$$\delta q(t_1) = \delta q(t_2) = 0$$

• S for least action: $\int_{t_1}^{t_2} L(q, \dot{q}, t) dt$

• Change in S:

$$\int_{t_1}^{t_2} L(q + \delta q, \dot{q} + \delta \dot{q}, t) dt - \int_{t_1}^{t_2} L(q, \dot{q}, t) dt = \delta S$$

$$= \delta \int_{t_1}^{t_2} L(q, \dot{q}, t) dt \quad \text{now?}$$

$$= \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q} \right) dt$$

$$\frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \delta \dot{q}$$

$$\delta \dot{q} = \frac{d}{dt} (\delta q)$$

$$\delta S = \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q} \delta q + \frac{\partial L}{\partial \dot{q}} \frac{d}{dt} (\delta q) \right) dt$$

$$\int_{t_1}^{t_2} \frac{\partial L}{\partial \dot{q}} \frac{d}{dt} (\delta q) dt$$

$$\int u dv = u \cdot V - \int u' V dv$$

$$V = \int v dx$$

Integrating by parts

$$0 = \left[\frac{\partial L}{\partial \dot{q}} \delta q \right]_{t_1}^{t_2} - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \delta q dt.$$

Since $\delta q = 0$ @ t_1, t_2 .

$$\left| \frac{\partial L}{\partial \dot{q}} \delta q \right|_{t_1}^{t_2} - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \delta q dt$$

$$\delta S = \int_{t_1}^{t_2} \frac{\partial L}{\partial q} \delta q dt - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \delta q dt$$

$$\delta S = \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) \right) \delta q dt$$

In path of least action:

$$\delta S = 0 \quad \forall \quad \delta q$$

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0.$$

LAGRANGE'S
EQUATION OF
MOTION.

Again, $\frac{\partial L}{\partial q} = - \frac{\partial U}{\partial q}$ (from $L = K - U$)

\downarrow
force

$$\Rightarrow \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = \text{rate of change of generalised momentum.}$$

Deriving:

► Lagrangian \rightarrow Hamiltonian

$$\frac{dL}{dt} = \sum_{i=1}^N \frac{\partial L}{\partial q_i} \dot{q}_i + \sum_{i=1}^N \frac{\partial L}{\partial \dot{q}_i} \ddot{q}_i$$

$$= \sum_{i=1}^N \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) \dot{q}_i + \sum_{i=1}^N \frac{\partial L}{\partial \dot{q}_i} \ddot{q}_i$$

$$= \sum_{i=1}^N \frac{d}{dt} \left(\dot{q}_i \frac{\partial L}{\partial \dot{q}_i} \right)$$

$$\sum_{i=1}^N \frac{d}{dt} \left(\dot{q}_i \frac{\partial L}{\partial \dot{q}_i} \right) - \frac{dL}{dt} = 0$$

$$\frac{d}{dt} \left[\sum_{i=1}^N \dot{q}_i \frac{\partial L}{\partial \dot{q}_i} - L \right] = 0$$

$$\sum_{i=1}^N \dot{q}_i \frac{\partial L}{\partial \dot{q}_i} - L = \text{const}$$

Hamiltonian

Prove:

$$\sum_{i=1}^N \dot{q}_i \frac{\partial L}{\partial \dot{q}_i} - L = H$$

$$\frac{\partial L}{\partial \dot{q}_i} = \frac{\partial K}{\partial \dot{q}_i}$$

$$= m \dot{q}_i$$

$$\Rightarrow \sum_{i=1}^N \dot{q}_i (m \dot{q}_i) - L = \text{const}$$

$$= 2K - (K - U)$$

$$= K + U$$

$$= H \quad \text{QED}$$

Eg: Simple Pendulum

Step 1: Construct L

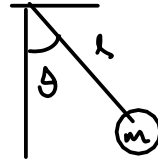
$$K(\dot{\theta}), U(\theta)$$

$$L(\theta, \dot{\theta}) = K(\dot{\theta}) - U(\theta)$$

Step 2: $\frac{\partial L}{\partial \theta}$ and $\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right)$

$$\frac{\partial L}{\partial \theta} = -mgl \sin \theta$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = mL \ddot{\theta}$$



?? Redo

Mathematical Modelling

The process: Diffusion.

Model: Random walk.

1D Random Walk:



$P(\text{finding at point } r \text{ after } t \text{ steps})$ is a gaussian distribution

N = total steps

n_1 = " " \rightarrow

n_2 = " " \leftarrow

Displacement, $m = (n_1 - n_2)l$

l = length of each step

$$P(n_1 \text{ steps to the right}) = \frac{N!}{n_1! n_2!} p^{n_1} q^{n_2} = W_N(n_1)$$

$$P_N(m) = \frac{N!}{\left(\frac{N+m}{2}\right)! \left(\frac{N-m}{2}\right)!} p^{\frac{N+m}{2}} q^{\frac{N-m}{2}}$$

$$\langle n_1 \rangle = \sum_{n_1=0}^N W_N(n_1) n_1$$

$$= \sum_{n_1=0}^N \frac{N!}{n_1! (N-n_1)!} p^{n_1} q^{(N-n_1)} n_1$$

$$= \sum_{n_1=0}^N \frac{N!}{n_1! (N-n_1)!} q^{(N-n_1)} \left[p \frac{\partial}{\partial p} p^{n_1} \right]$$

$$= p \frac{\partial}{\partial p} \left[\sum_{n_1=0}^N \frac{N!}{n_1! (N-n_1)!} q^{N-n_1} p^{n_1} \right]$$

$$= p \frac{\partial}{\partial p} (p+q)^N = pN(p+q)^{N-1}$$

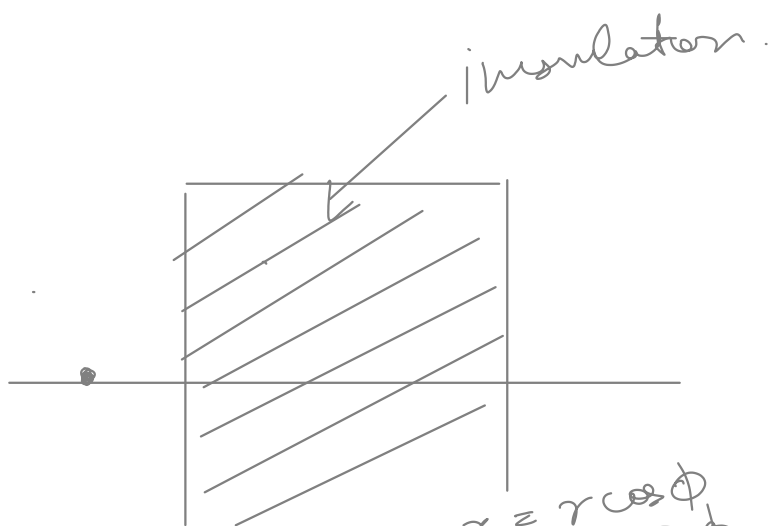
$$\begin{aligned} \langle n_1 \rangle &= Np \\ \langle n_2 \rangle &= Nq \end{aligned}$$

$$n_1 p^{n_1} = p \frac{\partial}{\partial p} p^{n_1}$$

Quantum Mechanics

Motivations

1. Black Body Radiation
2. Photoelectric effect
3. Hydrogen Spectrum
4. Heat capacity of solids (at low temps)
5. Diffraction of electrons by crystals
6. Spin Angular Momentum.



$$y = r \sin \phi$$

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial r} \cos \phi + \frac{\partial f}{\partial \phi} \times \frac{\partial \phi}{\partial x}$$

$$f(x, y) = f(r, \phi)$$

$$\frac{\partial \phi}{\partial x} = \frac{1}{r} (-\sin \phi)$$

=

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial r} \cos \phi - \frac{\partial f}{\partial \phi} \frac{\sin \phi}{r}$$