

fn service\_electric\_components()

## Tesla

fn change\_tires()

fn needs\_battery\_service()

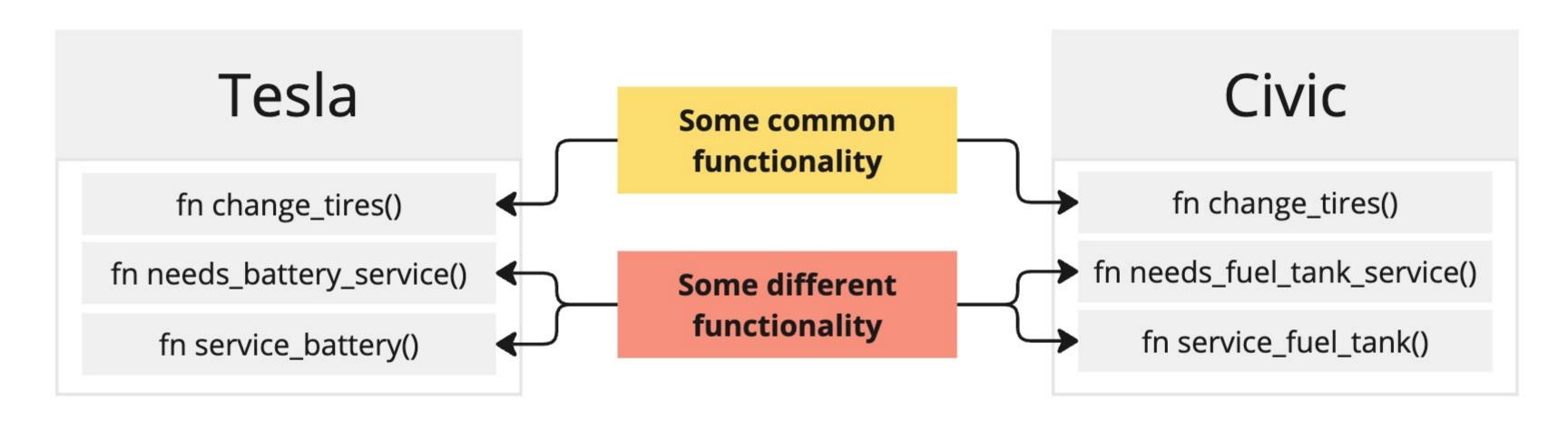
fn service\_battery()

## Civic

fn change\_tires()

fn needs\_fuel\_tank\_service()

fn service\_fuel\_tank()



#### Option #1

Use an enum to represent the different kinds of cars

#### **Downside:**

Every function has to see if the operation is appropriate for the car variant

```
pub enum Vehicle {
   Tesla,
   Civic,
impl Vehicle {
   fn change_tires(&self) {
       match self {
            Vehicle::Tesla => println!("Replacing tesla tires"),
            Vehicle::Civic => println!("Replacing civic tires"),
   fn needs_battery_service(&self) -> Result<bool, String> {
       match self {
            Vehicle::Tesla => Ok(true),
            Vehicle::Civic => {
                Err(String::from("cant service the battery of a civic!"))
```

```
fn service_car(car: ?????) {
   fn main() {
   let tesla = Tesla{};
   let civic = Civic{};
   service_car(tesla);
   service_car(civic);
```

#### Goal

Be able to call this 'service\_car' function with either a Tesla or a Civic

#### Battery powered vehicle

# **Tesla Model 3**

**Goal:** Model maintenance for each vehicle

## **Honda Civic**

Gas powered vehicle

Battery powered vehicle

# **Tesla Model 3**

# struct Tesla

km\_driven

tires\_replaced\_at

fn change\_tires()

# **Honda Civic**

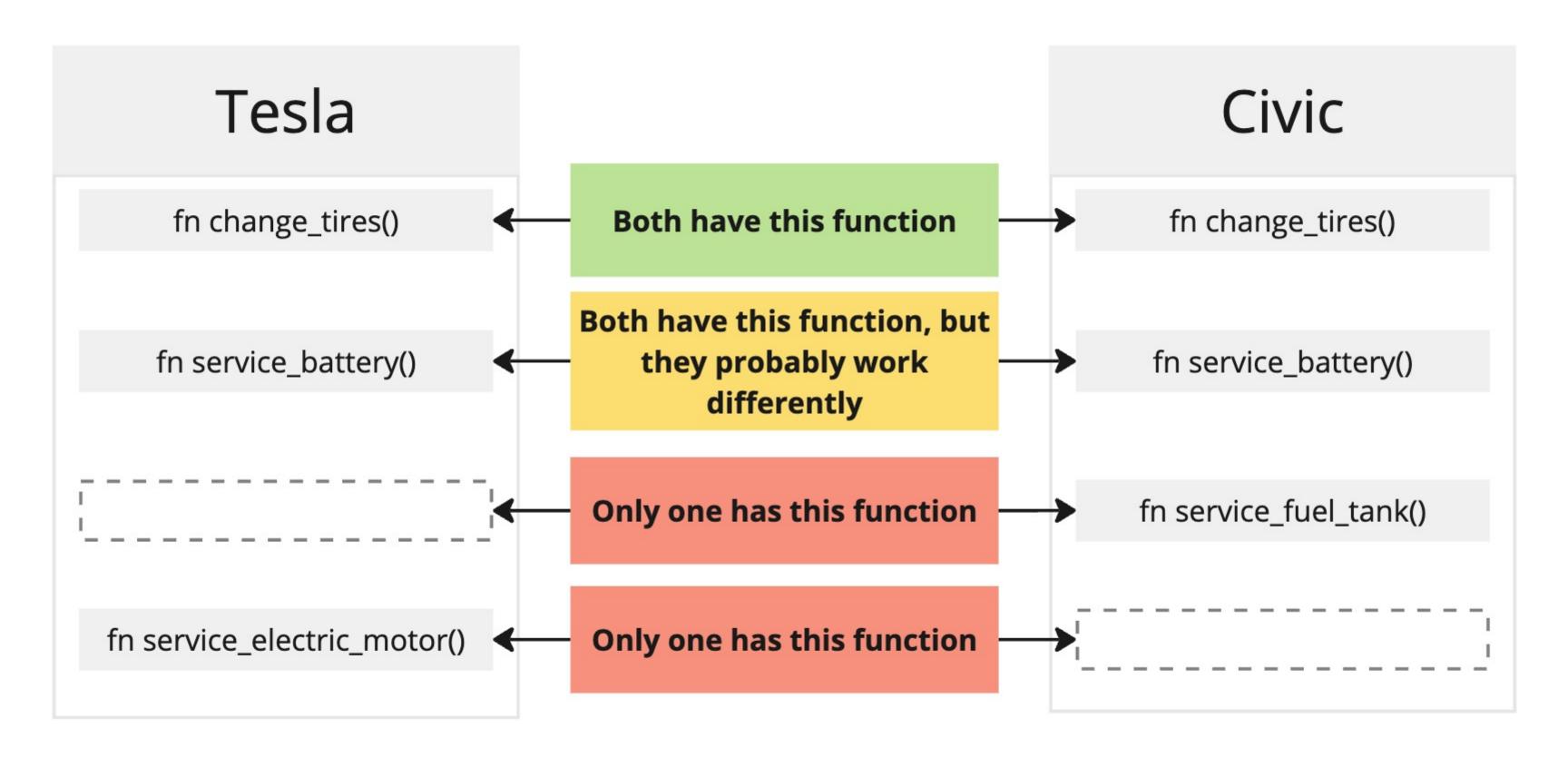
Gas powered vehicle

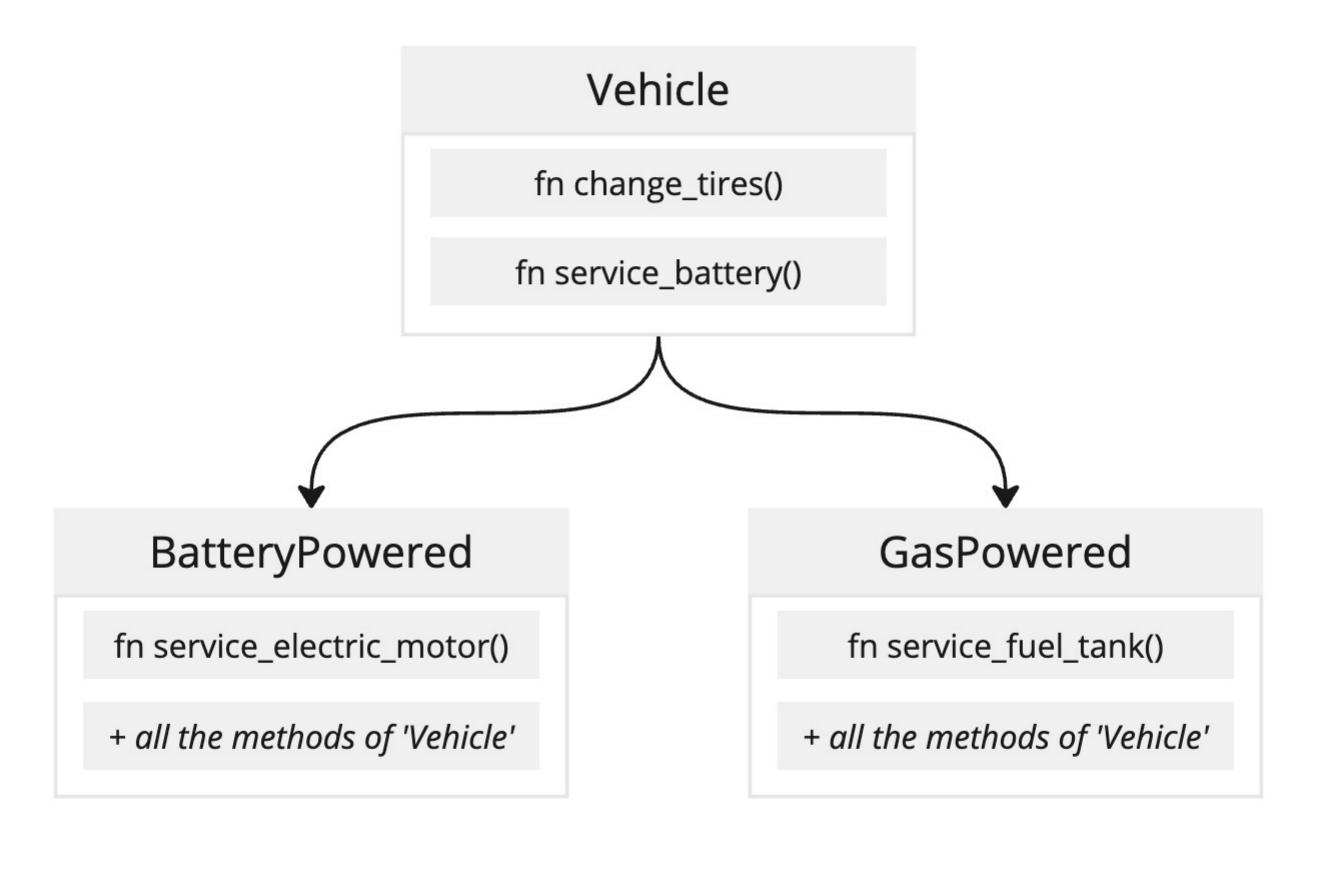
# struct Civic

km\_driven

tires\_replaced\_at

fn change\_tires()



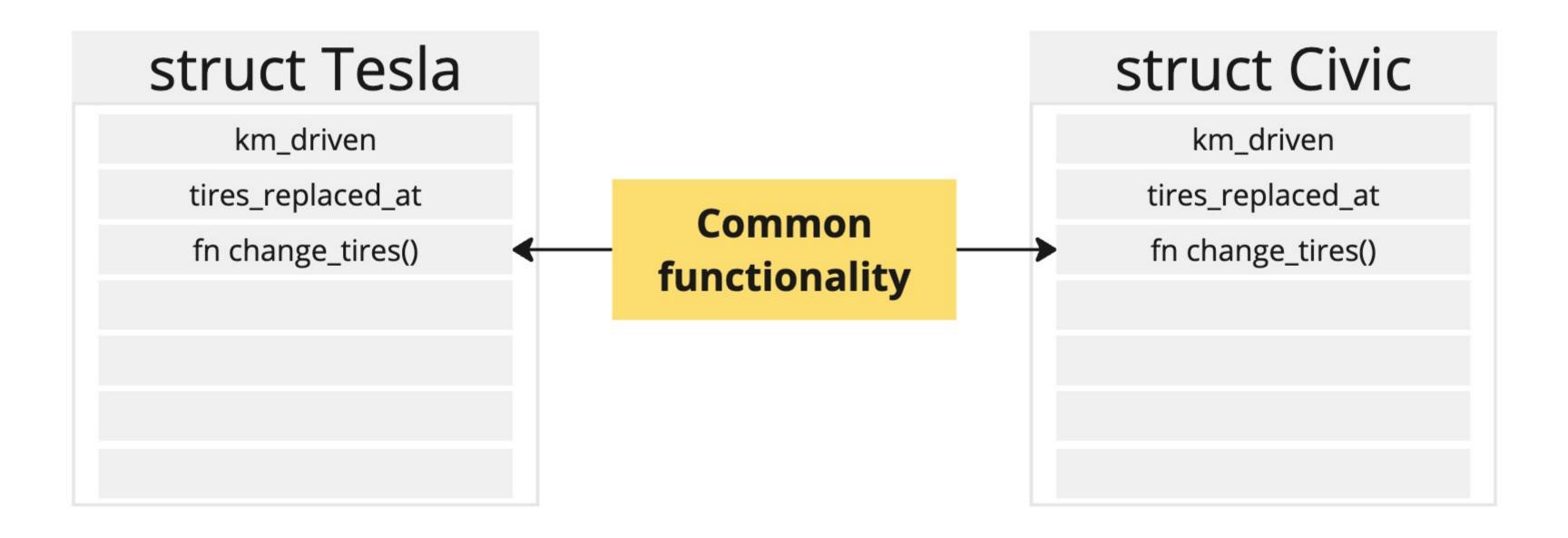


# Traits define common functionality between different types

1	Find one or more types that need to have common functionality
2	Identify which methods those types will have in common
3	Define the trait
4	Implement the trait for each type in step #1
5	Use the trait as bounds for a generic function/struct/enum/vector/etc

Find one or more types that need to have common functionality

Identify which methods those types will have in common



#### Define the trait

```
trait Vehicle {
   pub fn change_tires(&mut self) {
     /* code to change tires */
   }
}
```

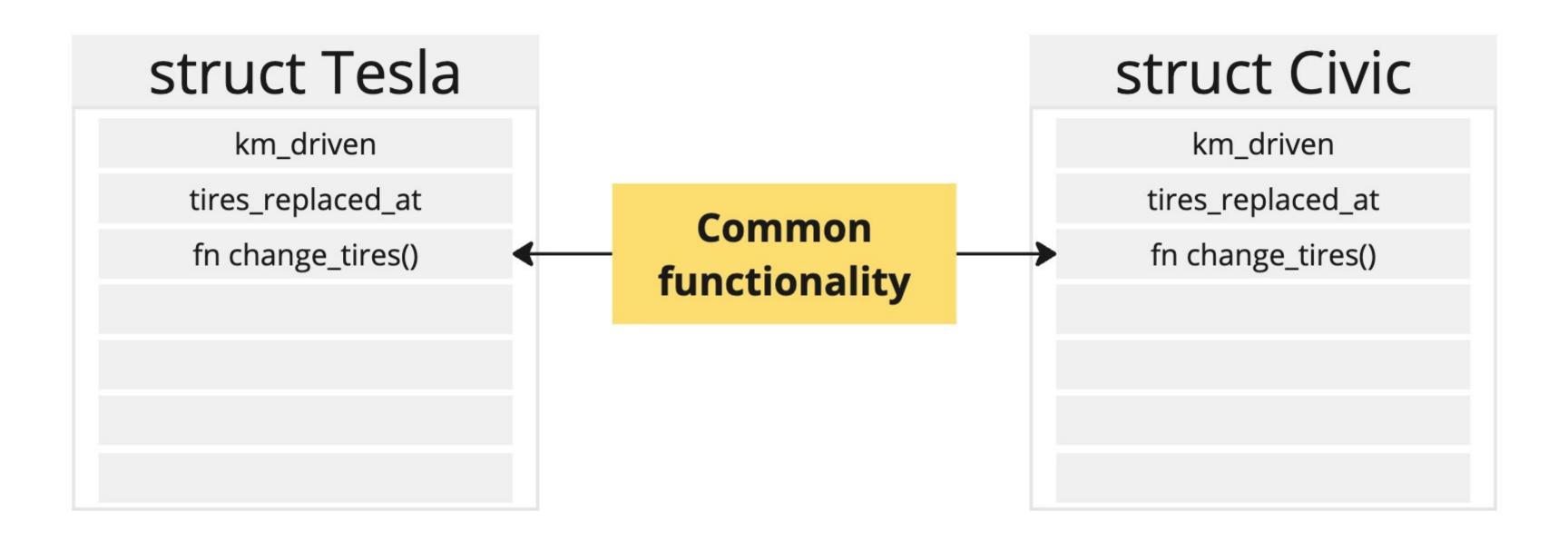
```
struct Tesla {}
                                                           impl Vehicle for Tesla {
trait Vehicle {
   pub fn change_tires(&mut self) {
       /* code to change tires */
                                                           struct Civic {}
                                                           impl Vehicle for Civic {
```

# Use the trait as bounds for a generic function/struct/enum/vector/etc

```
fn service_car(car: impl Vehicle) {
    car.change_tires();
fn main() {
    let tesla = Tesla{};
    let civic = Civic{};
    service_car(tesla);
    service_car(civic);
```

'service\_car' expects to be called with any value that implements the 'Vehicle' trait

Both Tesla and Civic implement the 'Vehicle' trait, so they can be passed into 'service\_car'



```
trait Vehicle {
    fn change_tires(&mut self) {
         println!("Changing tires!");
impl Vehicle for Tesla { }
impl Vehicle for Civic { }
    fn main() {
        let car1 = Civic::new(99999, 0);
        let car2 = Tesla::new(0, 0);
        car1.change_tires();
        car2.change_tires();
```

#### A trait is a set of methods

# A struct/enum/anything can choose to "implement" that trait.

This struct/enum/anything is called the 'implementor'

The implementor gets access to the methods defined in the trait

# trait Vehicle

fn change\_tires()

# struct Tesla

km\_driven

tires\_replaced\_at

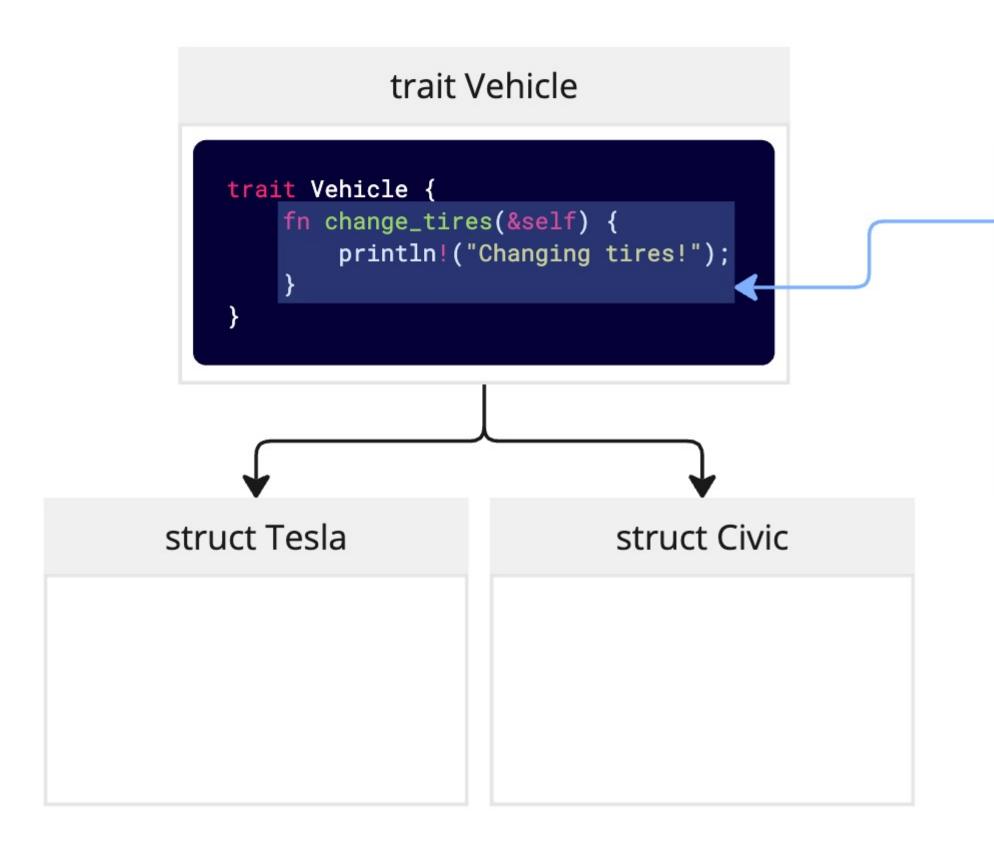
fn change\_tires()

# struct Civic

km\_driven

tires\_replaced\_at

fn change\_tires()

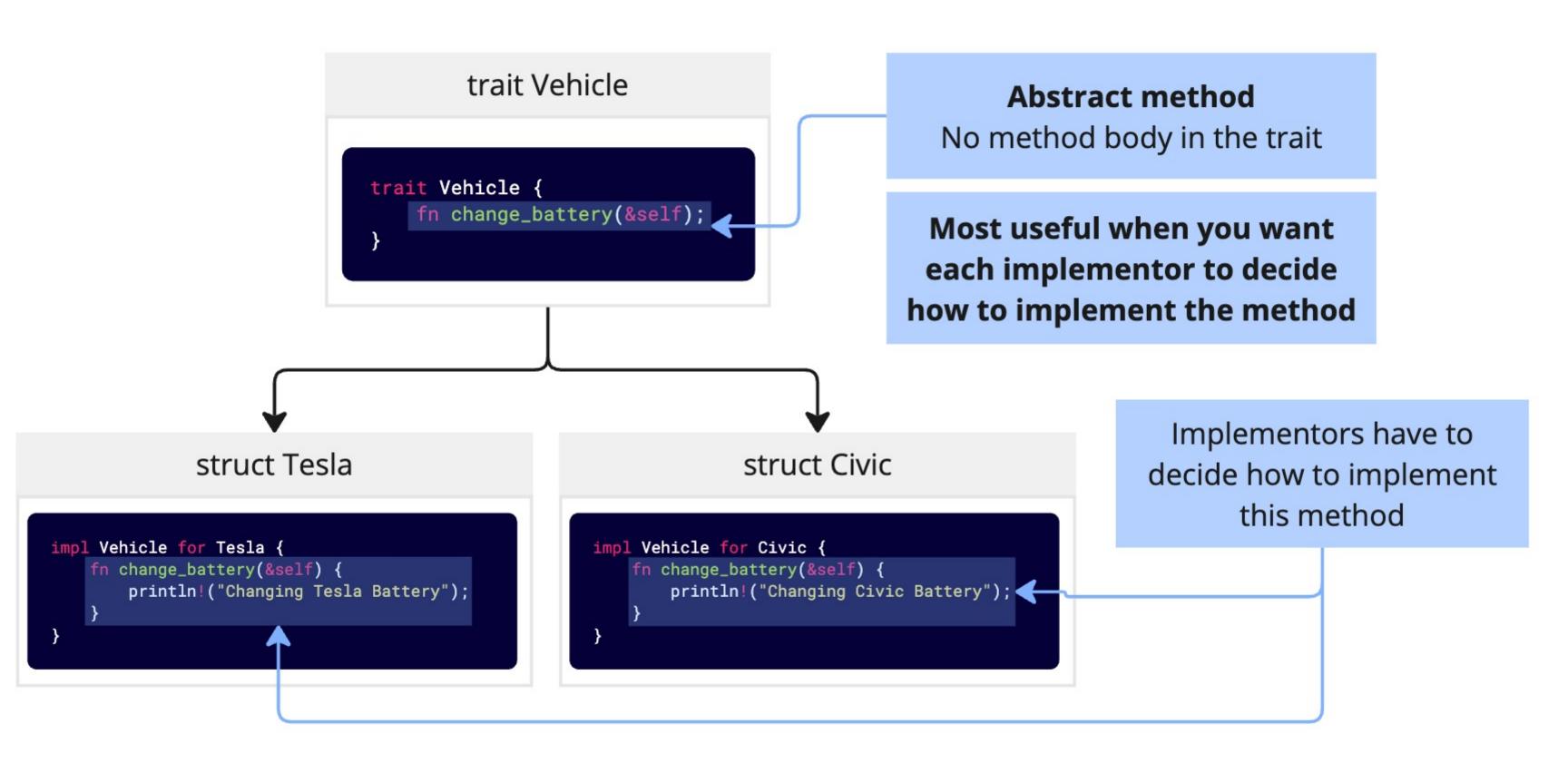


#### **Concrete methods**

Method body defined in the trait

Also known as 'default methods'

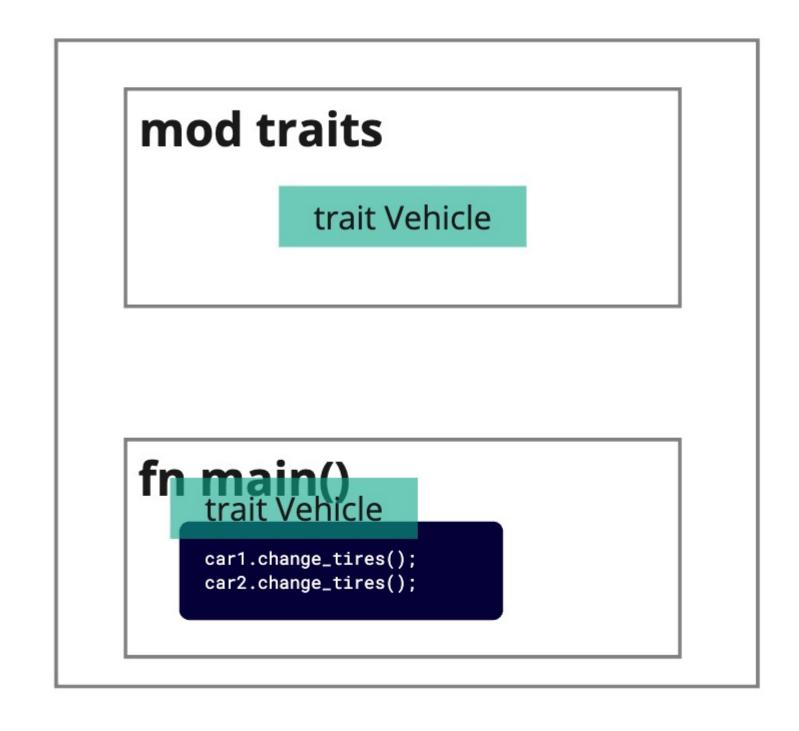
Most useful when all implementors should have the same exact method



#### Big Gotcha #1

The trait has to be in scope when a method from it is called

```
mod traits {
    pub trait Vehicle {
        fn change_tires(&mut self) {
            /* ... */
impl traits::Vehicle for Tesla { };
impl traits::Vehicle for Civic { };
fn main() {
    let mut car1 = Tesla::new();
    let mut car2 = Civic::new();
    car1.change_tires();
    car2.change_tires();
```



```
trait Vehicle {
    fn change_tires(&mut self) {
        // Bad! Traits can't assume the
        implementor has a particular field
        if self.km_driven > 0 {
        }
    }
}
```

#### Big Gotcha #2

A trait can't refer to fields, only methods

```
trait Vehicle {
    fn change_tires(&mut self) {
        if self.get_km_driven() - self.tires_replaced_at() > 100 {
            self.set_tires_replaced_at(self.get_km_driven());
            println!("Tires Replaced!")
    // Implementor has to implement these methods:
    fn get_km_driven() -> u32;
    fn tires_replaced_at() -> u32;
    fn set_tires_replaced_at(km: u32);
impl Vehicle for Tesla {
    fn get_km_driven() -> u32 {
       self.km_driven
    fn tires_replaced_at() -> u32 {
        self.tires_replaced_at
    fn set_tires_replaced_at(km: u32) {
        self.tires_replaced_at = km;
```

Big Gotcha #2
A trait can't refer to fields,
only methods

#### **Workaround:**

Add methods that give access to the fields you need and require the implementor to implement them

There is a downside to this approach

The names of these methods strongly imply that an implementor will have 'km\_driven' and 'tires\_replaced\_at' fields

```
trait Vehicle {
   fn change_tires(&mut self) {
        if self.get_km_driven() - self.tires_replaced_at() > 100 {
            self.set_tires_replaced_at(self.get_km_driven());
            println!("Tires Replaced!")
    // Implementor has to implement these methods:
   fn get_km_driven() -> u32;
    fn tires_replaced_at() -> u32;
    fn set_tires_replaced_at(km: u32);
impl Vehicle for Tesla {
    fn get_km_driven() -> u32 {
        self.km_driven
   fn tires_replaced_at() -> u32 {
        self.tires_replaced_at
   fn set_tires_replaced_at(km: u32) {
        self.tires_replaced_at = km;
```

Default impl of 'change\_tires' assumes we want to change tires when a certain km has been driven

```
trait Vehicle {
    fn change_tires(&mut self) {
       if self.get_km_driven() - self.tires_replaced_at() > 100 {
            self.set_tires_replaced_at(self.get_km_driven());
            println!("Tires Replaced!")
    // Implementor has to implement these methods:
    fn get_km_driven() -> u32;
    fn tires_replaced_at() -> u32;
    fn set_tires_replaced_at(km: u32);
impl Vehicle for Tesla {
    fn get_km_driven() -> u32 {
        self.km_driven
    fn tires_replaced_at() -> u32 {
        self.tires_replaced_at
    fn set_tires_replaced_at(km: u32) {
        self.tires_replaced_at = km;
```

#### We're working on a trait called 'Vehicle'

It assumes that all vehicles have a 'km\_driven', a 'tires\_replaced\_at', and that we want to replace tires based on how long its been since the tires have been replaced

There are kinds of vehicles that don't follow these rules at all

Default impl of 'change\_tires' assumes we want to change tires when a certain km has been driven

The names of these methods strongly imply that an implementor will have 'km\_driven' and 'tires\_replaced\_at' fields

```
trait Vehicle {
    fn change_tires(&mut self) {
        if self.get_km_driven() - self.tires_replaced_at() > 100 {
            self.set_tires_replaced_at(self.get_km_driven());
            println!("Tires Replaced!")
    // Implementor has to implement these methods:
    fn get_km_driven() -> u32;
      tires_replaced_at() -> u32;
     fn set_tires_replaced_at(km: u32);
impl Vehicle for Tesla {
    fn get_km_driven() -> u32 {
        self.km_driven
    fn tires_replaced_at() -> u32 {
        self.tires_replaced_at
    fn set_tires_replaced_at(km: u32) {
        self.tires_replaced_at = km;
```

#### Bikes and planes are both vehicles

Bike

They both have tires

'km\_driven' doesn't make sense for either

Replacing tires based on distance traveled doesn't make sense for either

Plane

# Traits should have methods that are flexible and leave the details to the implementor

```
trait Vehicle {
    fn change_tires(&mut self) {
        if self.tire_change_required() {
            self.record_tire_change();
            println!("Replacing tire...");
        }
    }

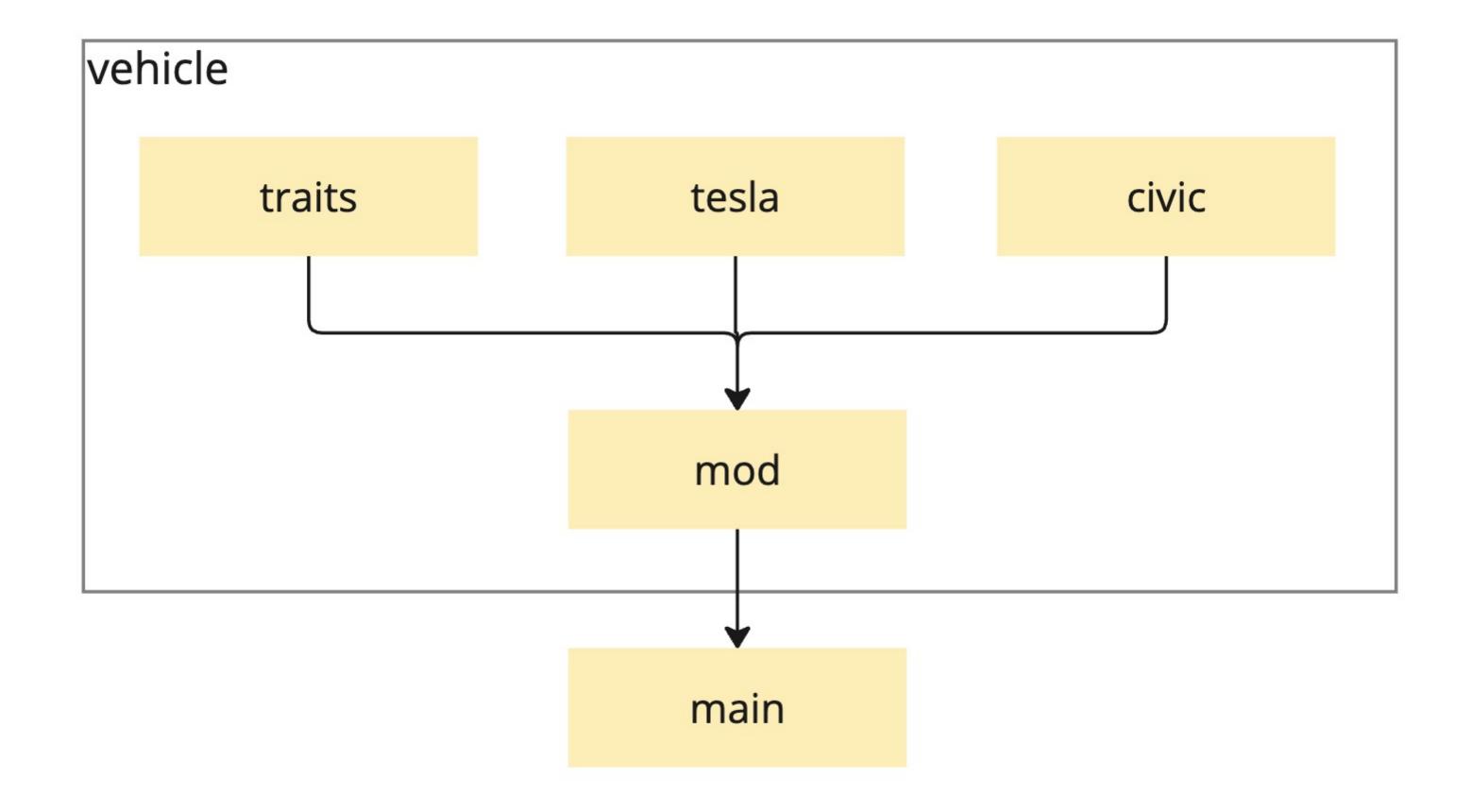
// Implementor has to implement these methods:
    fn tire_change_required(&self) -> bool;
    fn record_tire_change(&mut self);
}
```

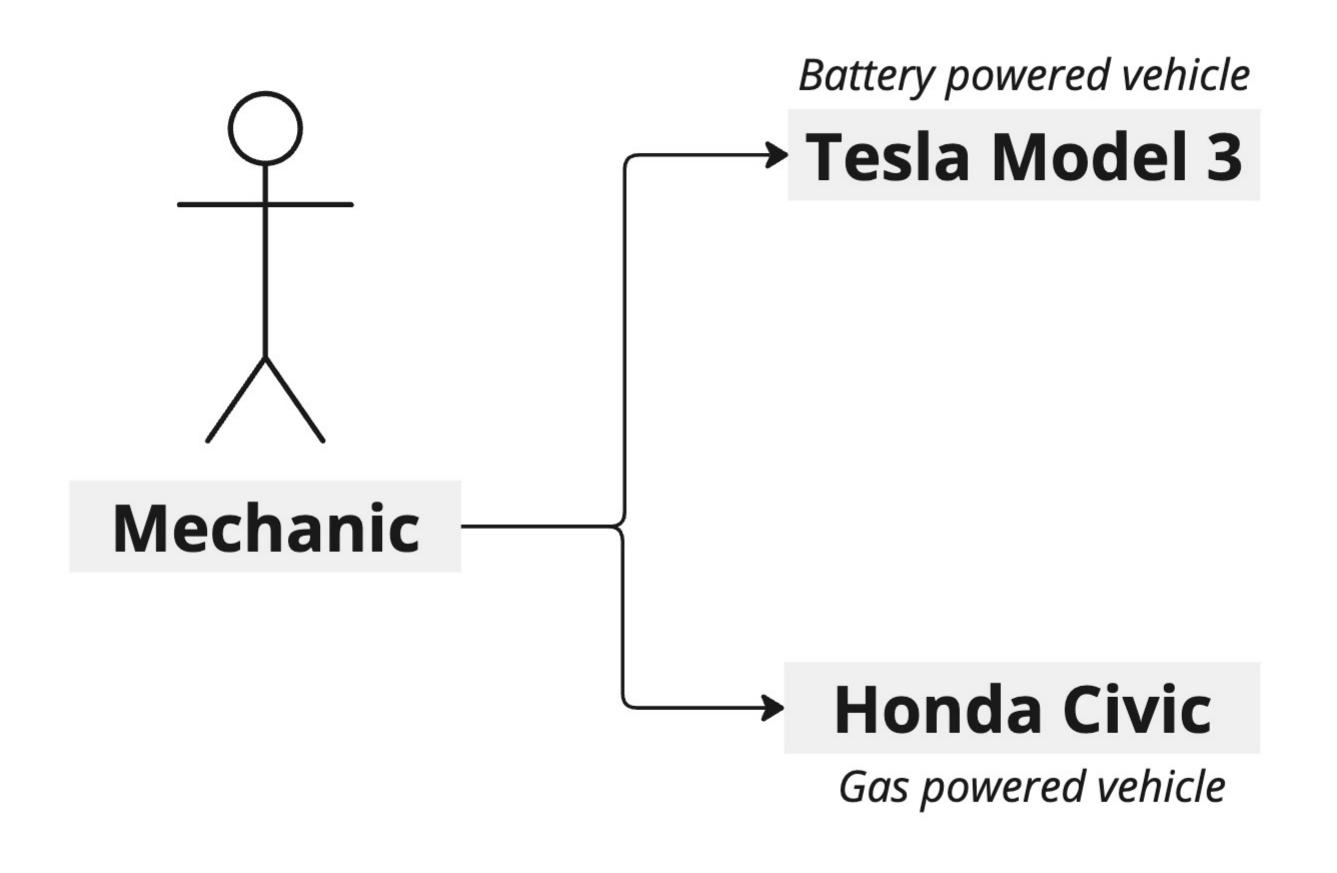
#### **Vehicle Trait**

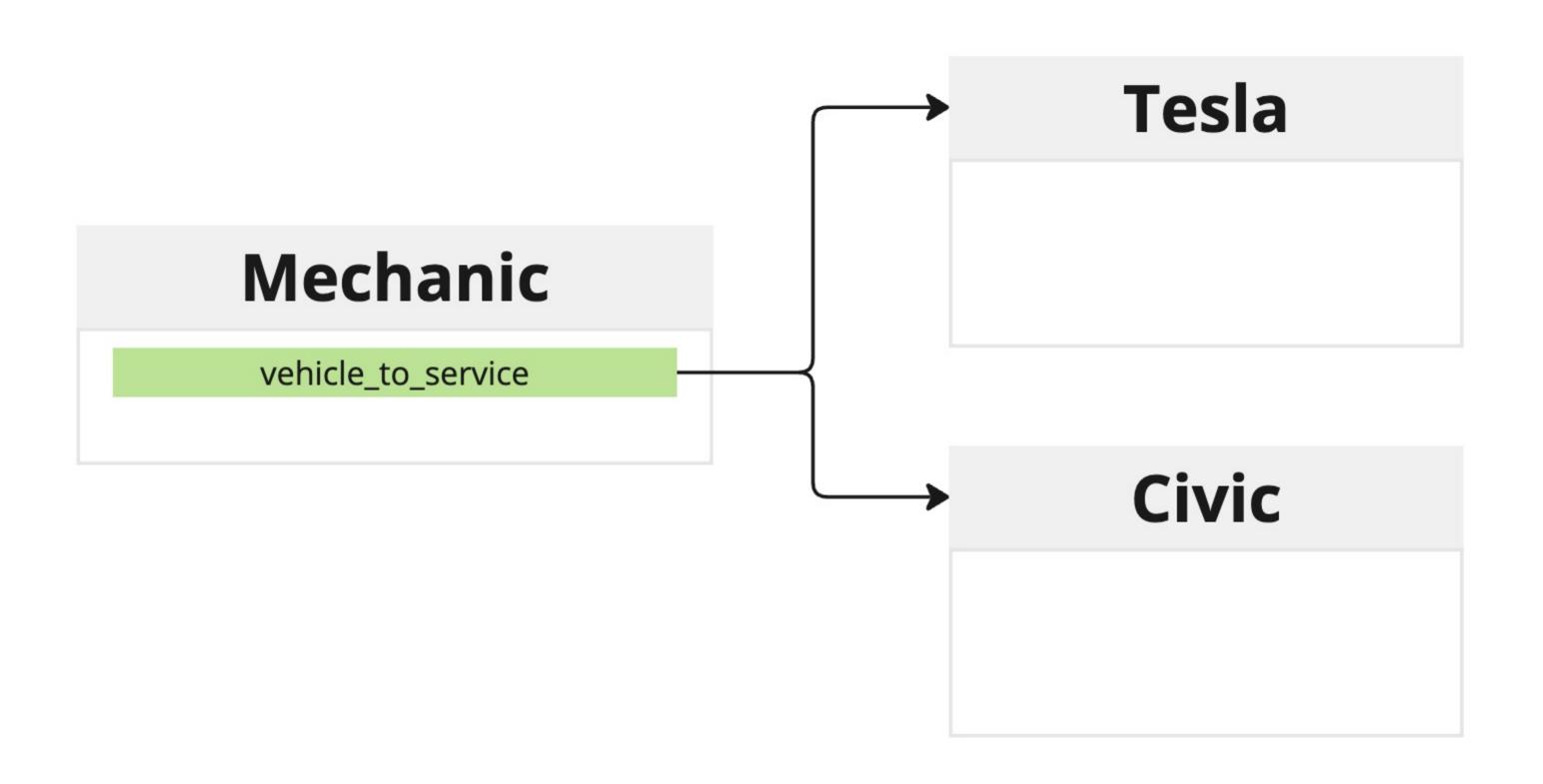
```
impl Vehicle for Tesla {
    fn tire_change_required(&self) -> bool {
        self.km_driven - self.tires_replaced_at > 10000
    }
    fn record_tire_change(&mut self) {
        self.tires_replaced_at = self.km_driven;
    }
}
```

```
impl Vehicle for Plane {
    fn tire_change_required(&self) -> bool {
        self.landing_on_current_tires > 10
    }
    fn record_tire_change(&mut self) {
        self.landing_on_current_tires = 0;
    }
}
```

```
impl Vehicle for Bike {
    fn tire_change_required(&self) -> bool {
        self.tire_is_flat
    }
    fn record_tire_change(&mut self) {
        self.tire_is_flat = false;
    }
}
```







# **Tesla**

fn service\_electric\_motor()

# Civic

fn service\_fuel\_tank()

## Electric Vehicles

# **Tesla**

fn service\_electric\_motor()

# **Rivian R1S**

fn service\_electric\_motor()

# Hyundai Ioniq

fn service\_electric\_motor()

# Civic

fn service\_fuel\_tank()

# **Hyndai Elantra**

fn service\_fuel\_tank()

# **BMW M3**

fn service\_fuel\_tank()

### Gas Vehicles

```
pub trait Vehicle {
    fn change_tires(&mut self) {
        /* code */
    fn tire_change_required(&self) -> bool;
    fn record_tire_change(&mut self);
pub trait BatteryPowered: Vehicle {
    fn service_electric_motor(&self);
pub trait GasPowered: Vehicle {
    fn service_fuel_tank(&self);
```

# Vehicle

fn change\_tires()

fn change\_tires()

fn record\_tire\_change()

#### BatteryPowered

fn service\_electric\_motor()

#### GasPowered

fn service\_fuel\_tank()