

## Practice Exercise 02

You may use MATLAB/python and any package within.

### P.101 Q.4.13

A lot of technology, especially most types of digital audio devices for processing sound, is based on representing a signal of time as a sum of sine functions. Say the signal is some function  $f(t)$  on the interval  $[-\pi, \pi]$  (a more general interval  $[a, b]$  can easily be treated, but leads to slightly more complicated formulas). Instead of working with  $f(t)$  directly, we approximate  $f$  by the sum :

$$S_N(t) = \sum_{n=1}^N b_n \sin(nt),$$

where the coefficients  $b_n$  must be adjusted such that  $S_N(t)$  is a good approximation to  $f(t)$ . We shall in this exercise adjust  $b_n$  by a trial-and-error process.

- Make a function `sinesum(t, b)` that returns  $S_N(t)$ , given the coefficients  $b_n$  in an array `b` and time coordinates in an array `t`. Note that if `t` is an array, the return value is also an array.
- Write a function `test_sinesum()` that calls `sinesum(t, b)` in a) and determines if the function computes a test case correctly. As test case, let `t` be an array with values  $-\pi/2$  and  $\pi/4$ , choose  $N = 2$ , and  $b_1 = 4$  and  $b_2 = -3$ . Compute  $S_N(t)$  by hand to get reference values.
- Make a function `plot_compare(f, N, M)` that plots the original function  $f(t)$  together with the sum of sines  $S_N(t)$ , so that the quality of the approximation  $S_N(t)$  can be examined visually. The argument `f` is a Python function implementing  $f(t)$ , `N` is the number of terms in the sum  $S_N(t)$ , and `M` is the number of uniformly distributed  $t$  coordinates used to plot  $f$  and  $S_N$ .
- Write a function `error(b, f, M)` that returns a mathematical measure of the error in  $S_N(t)$  as an approximation to  $f(t)$ :

$$E = \sqrt{\sum_i (f(t_i) - S_N(t_i))^2},$$

where the  $t_i$  values are  $M$  uniformly distributed coordinates on  $[-\pi, \pi]$ . The array  $b$  holds the coefficients in  $SN$  and  $f$  is a Python function implementing the mathematical function  $f(t)$ .

e) Make a function `trial(f, N)` for interactively giving  $b_n$  values and getting a plot on the screen where the resulting  $SN(t)$  is plotted together with  $f(t)$ . The error in the approximation should also be computed as indicated in d). The argument  $f$  is a Python function for  $f(t)$  and  $N$  is the number of terms  $N$  in the sum  $SN(t)$ . The trial function can run a loop where the user is asked for the  $b_n$  values in each pass of the loop and the corresponding plot is shown. You must find a way to terminate the loop when the experiments are over. Use  $M=500$  in the calls to plot compare and error.

f) Choose  $f(t)$  to be a straight-line  $f(t) = 1/\pi t$  on  $[-\pi, \pi]$ . Call `trial(f, 3)` and try to find through experimentation some values  $b_1$ ,  $b_2$ , and  $b_3$  such that the sum of sines  $SN(t)$  is a good approximation to the straight line.

g) Now we shall try to automate the procedure in f). Write a function that has three nested loops over values of  $b_1$ ,  $b_2$ , and  $b_3$ . Let each loop cover the interval  $[-1, 1]$  in steps of 0.1. For each combination of  $b_1$ ,  $b_2$ , and  $b_3$ , the error in the approximation  $SN$  should be computed. Use this to find, and print, the smallest error and the corresponding values of  $b_1$ ,  $b_2$ , and  $b_3$ . Let the program also plot  $f$  and the approximation  $SN$  corresponding to the smallest error.

SOLUTION:

[https://hplgit.github.io/prog4comp/doc/pub/.\\_p4c-bootstrap-Python014.html#2nd:exer:fitSines](https://hplgit.github.io/prog4comp/doc/pub/._p4c-bootstrap-Python014.html#2nd:exer:fitSines)