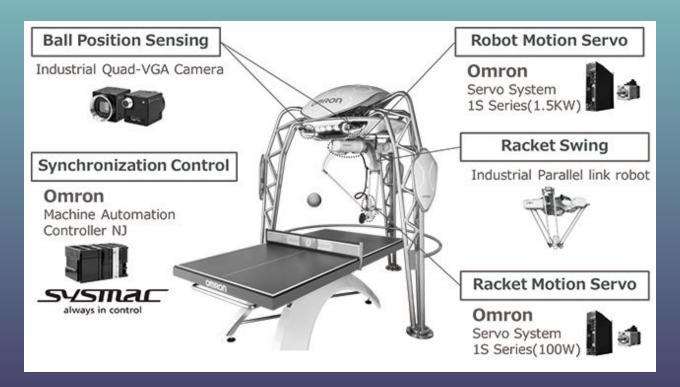
Robotics Hardware: Locomotion and Mechanical Design

NAME: MUHAMMAD ZULHAFIZ BIN ZULKIFLI

MATRIC NO: 1812661







1S Drives

Sysmac general purpose servo

Ratings: 230 VAC from 50 W to 1.5 kW, 400 VAC from 400 W to 15 kW

- 23-bit resolution encoder
- Fast and secure screw-less push-in in all connectors
- Pluggable connectors for easy pre-wiring and system maintenance
- Direct wiring of I/O signals
- Embedded relay for direct motor brake control
- Improved loop control for overshoot and quick setting time
- Safety function built-in:
 - Network Safe Torque Off: PLd (EN ISO 13849-1), SIL2 (IEC 61508)
 - Hardwired Safe Torque Off: PLe (EN ISO 13849-1), SIL3 (IEC 61508)







Machine Automation Controller NJ/NX-Series

New controller that covers functions and high-speed processing required for machine control and safety, reliability and maintainability





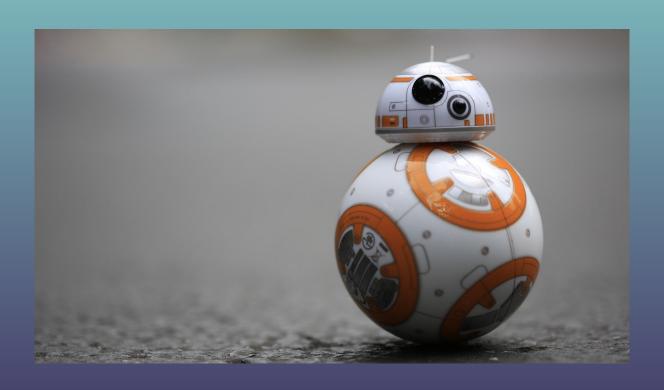
NX701-

NJ501-



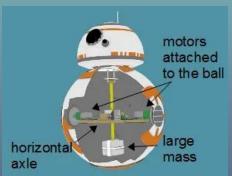


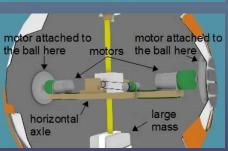
2) Wheeled & Tracked Robots : BB-8

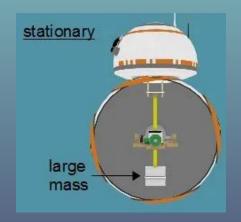


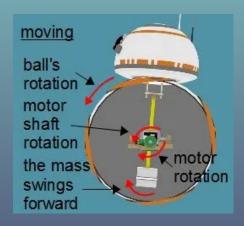
2) Wheeled & Tracked Robots : BB-8

AXLE DRIVE AKA PENDULUM DRIVE





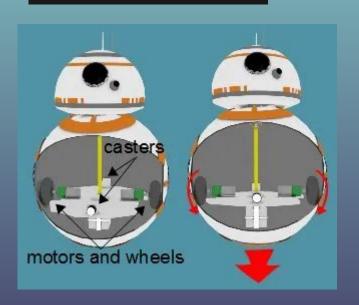


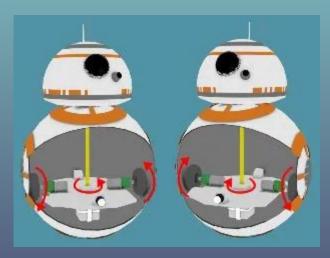


With an axle drive, an axle runs horizontally inside the ball across the middle halfway up. At one or both ends of the axle is a motor and the ball is attached to the motor's shaft. A large mass is suspended from the middle of the axle and is fixed to the axle. When the motors turn the ball, the ball rotates as expected. The large mass swings forward in the direction of the ball's motion. But you may have expected the mass to swing backward.

2) Wheeled & Tracked Robots : BB-8

THE HAMSTER DRIVE



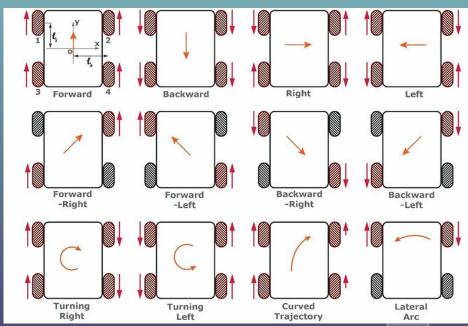




The hamster is typically a two wheeled vehicle that sits inside the ball, not physically attached to the ball in any way. Further support is usually given with casters or free turning balls extending out the front and back to contact the ball and help keep the two-wheeled hamster stable. Moving is done by rotating both wheels in the same direction.

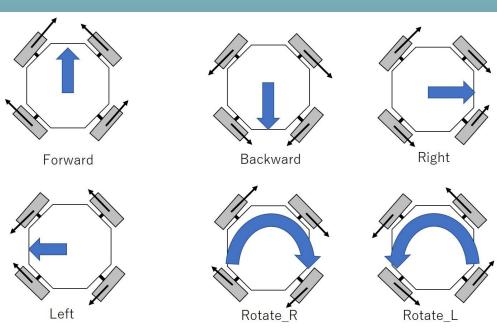
2) Wheeled & Tracked Robots: 4WD Omni Omni-Directional





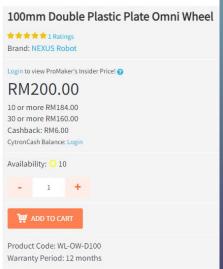
2) Wheeled & Tracked Robots: 4WD Omni-Directional

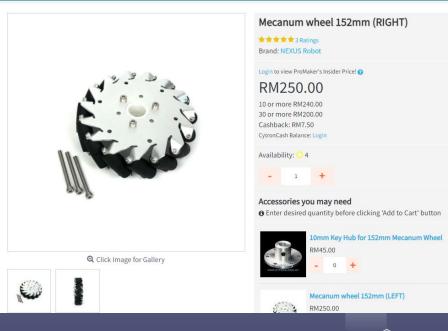




2) Wheeled & Tracked Robots: 4WD Omni-Directional





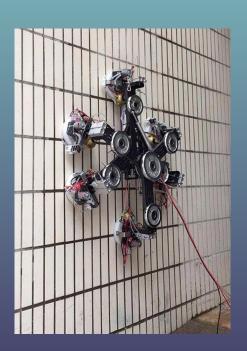


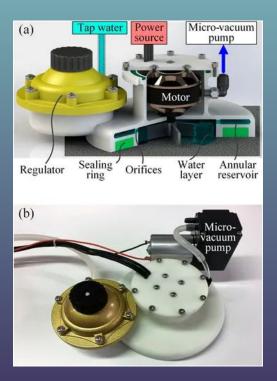




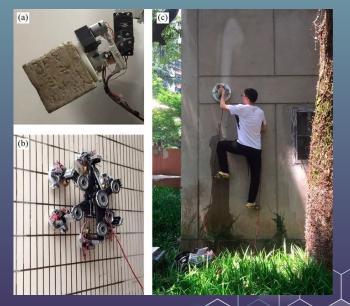
The wall-climbing robot has the following characteristics:

- (1) A wired remote control is applied, which is able to set the multipole mobile speed by pressing different keys. This helps to reduce the work intensity of manual measurement and further improves the inspection accuracy.
- (2) A length adjustment mechanism is designed and the length of crawl can be changed appropriately in accordance with the requirement.
- (3) The payload capacity is strong. Either track is installed with 66 permanent magnetic units. All of them are fixed by an aluminum plate to avoid the rust suction.
- (4) Small size and light weight with large adhesion force make the robot portable and stable. It is convenient for operators to navigate in the field.

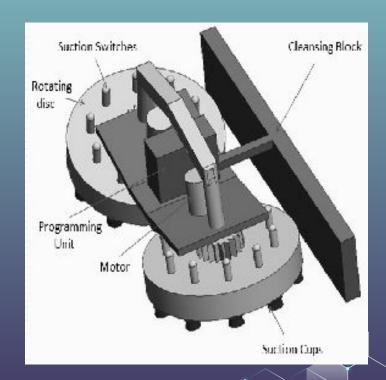


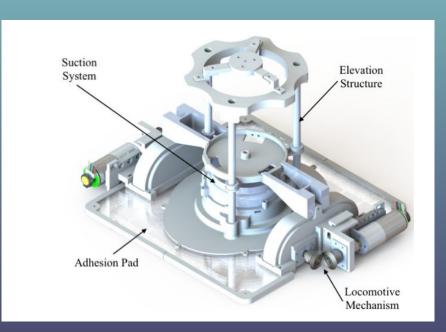


This robot has suction devices attached to each of its six arms. A ring of quickly moving water in each suction device allows this bot to climb up walls.









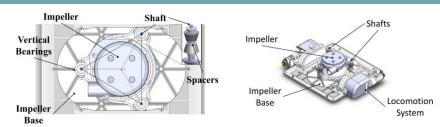


Fig. 6. Roller bearings base for the slip ring of the pad, working like a passive rotational system.

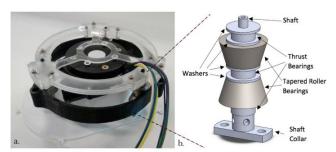
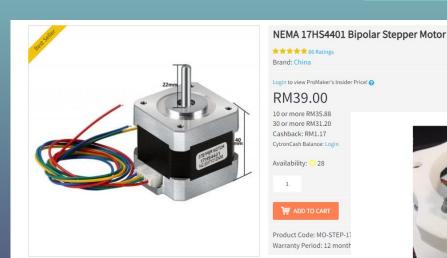


Fig. 7. a. Roller ring mechanism for free rotation of the pad; b. Bearing parts system.



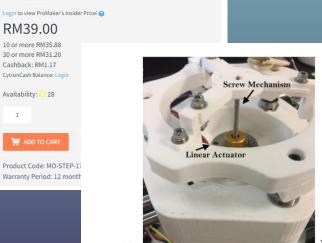




Fig. 8. a. Printed parts and lifting system; b. Linear actuator using uni-polar stepper motor.

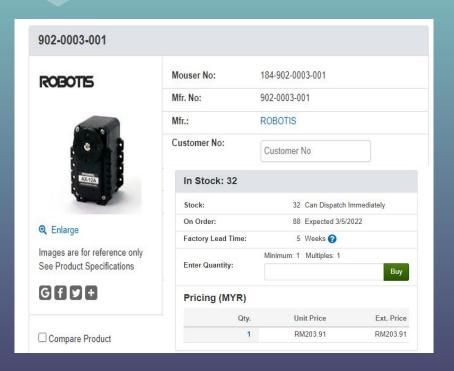
3) Legged Robots : BIOLOID Humanoid Robot

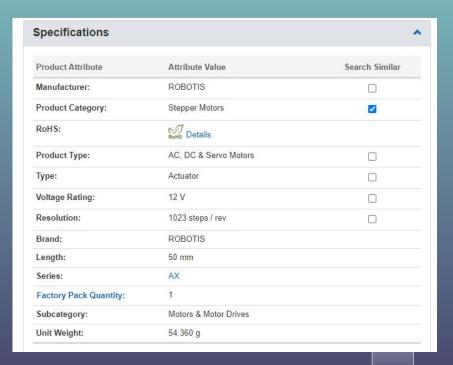


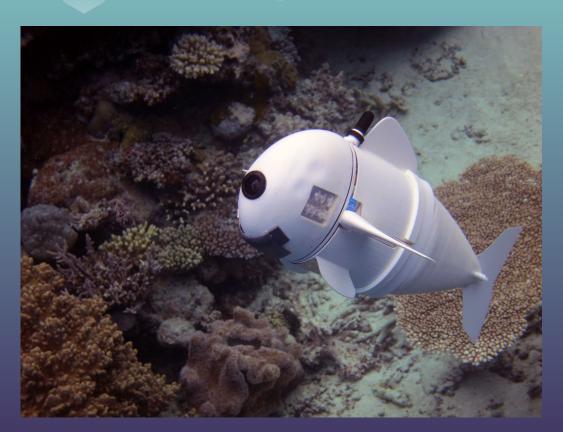
3) Legged Robots : BIOLOID Humanoid Robot

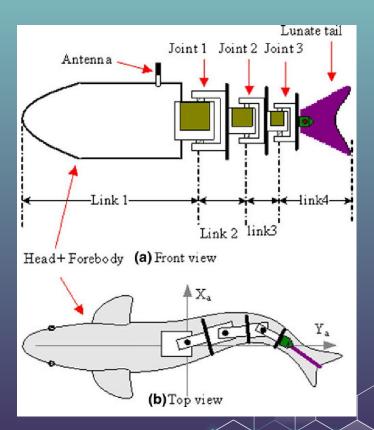


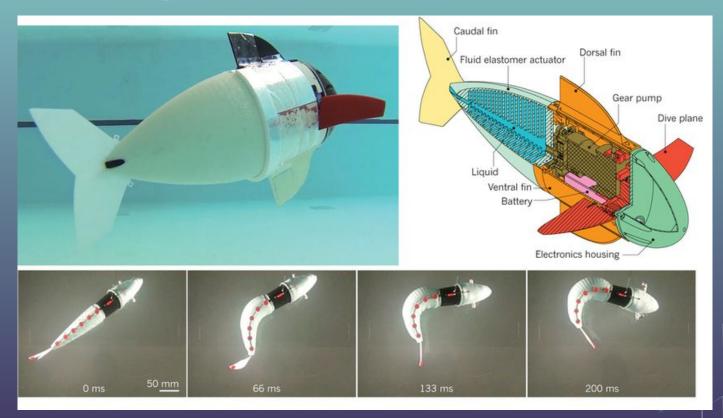
3) Legged Robots : BIOLOID Humanoid Robot











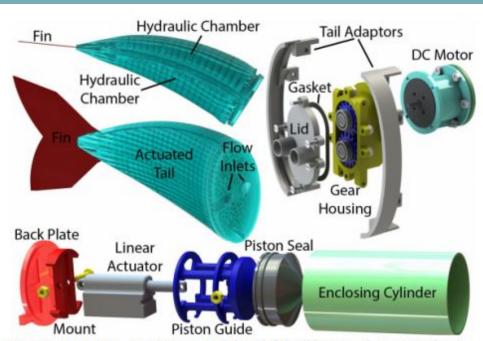
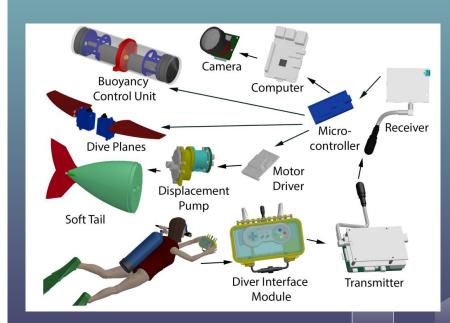
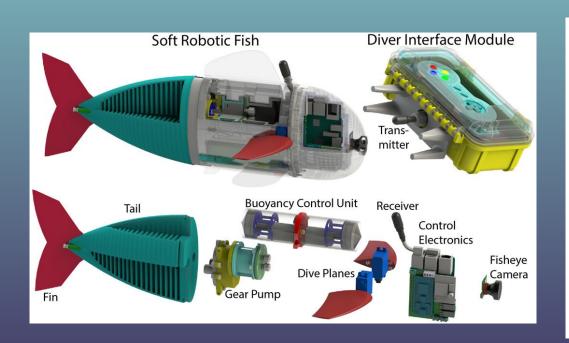
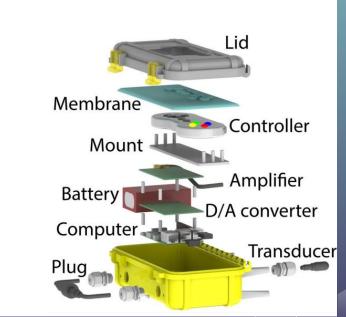


Fig. 7. Soft Tail, Pump, and BCU. Top left: Soft fish tail in actuated state (two views). Top right: Custom external gear pump in an exploded view. Bottom: One of two identical BCU modules in an exploded view.









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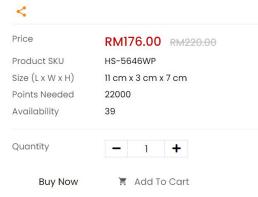






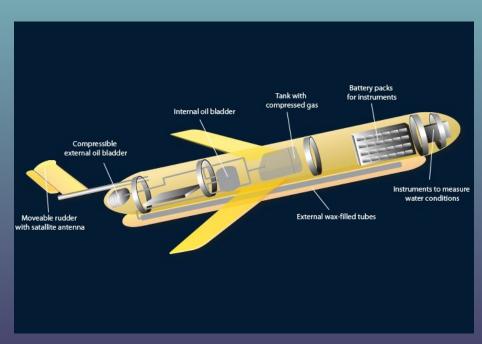


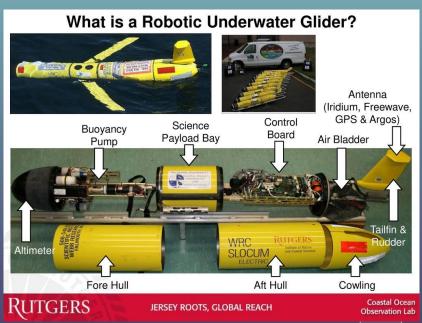
HS-5646WP HITEC DIGITAL WATERPROOF RC SERVO MOTOR



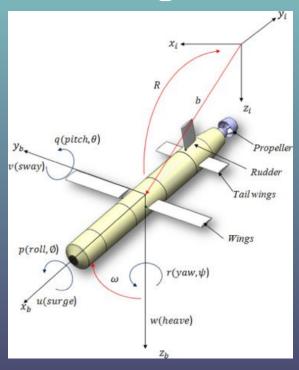


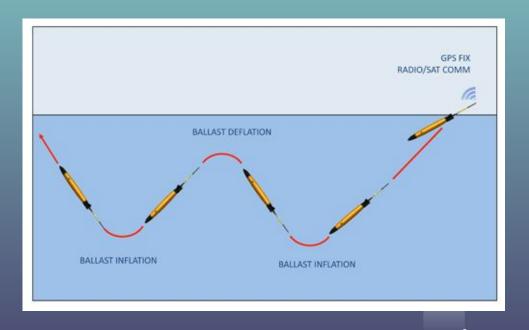
4) Swimming Robots : Underwater Glider Robot



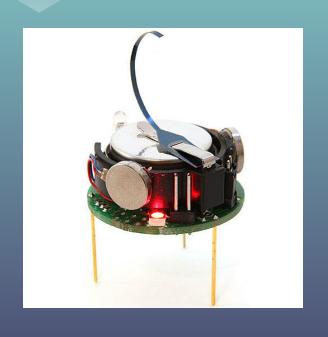


4) Swimming Robots : Underwater Glider Robot





5) Others : Kilobot





5) Others : Kilobot





