Lemma 0.1. For $x \in (0, 1)$

$$(1-x)^{1/x} < (e^{-x})^{1/x} = e^{-1}$$

Theorem 0.2. Consider a (λ, μ) -cost minimization game with a positive potential function Φ such that $\Phi(\mathbf{s}) \leq cost(\mathbf{s})$ for every outcome \mathbf{s} . Let $\mathbf{s}^0, \mathbf{s}^1, \dots, \mathbf{s}^T$ be a sequence generated by MaxGain best response dynamics, \mathbf{s}^* a minimum cost outcome and $1 > \gamma > 0$ is a parameter, Then for all but

$$\frac{k}{\gamma(1-\mu)}\log\frac{\Phi(\mathbf{s}^0)}{\Phi_{min}}\tag{1}$$

outcomes \mathbf{s}^t satisfy

$$cost(\mathbf{s^t}) \le \left(\frac{\lambda}{(1-\mu)(1-\gamma)}\right) \cdot cost(\mathbf{s^*})$$
 (2)

Proof.

$$cost(\mathbf{s^{t}}) \leq \sum_{i} c_{i}(\mathbf{s^{t}})$$

$$= \sum_{i} \left[c_{i}(\mathbf{s_{i}^{*}}, \mathbf{s_{-i}^{t}}) + \delta_{i}(\mathbf{s^{t}}) \right], \quad \delta_{i}(\mathbf{s^{t}}) = c_{i}(\mathbf{s^{t}}) - c_{i}(\mathbf{s_{i}^{*}}, \mathbf{s_{-i}^{t}})$$

$$\leq \lambda \cdot cost(\mathbf{s^{*}}) + \mu \cdot cost(\mathbf{s^{t}}) + \sum_{i} \delta_{i}(\mathbf{s^{t}})$$

$$cost(\mathbf{s^{t}}) \leq \frac{\lambda}{1 - \mu} \cdot cost(\mathbf{s^{*}}) + \frac{1}{1 - \mu} \cdot \sum_{i} \delta_{i}(\mathbf{s^{t}})$$
(3)

we shall let $\Delta(\mathbf{s^t}) = \sum_i \delta_i(\mathbf{s^t})$ in the remaining parts of the proof. We shall now define a state $\mathbf{s^t}$ to be bad if it does not satisfy (2) and by (3), when $\mathbf{s^t}$ is bad we get

$$\Delta(\mathbf{s^t}) \ge \gamma(1-\mu) \cdot cost(\mathbf{s^t})$$

By the MaxGain definition and the inequality relating the potential function and cost,

$$\max_{i} \delta_{i}(\mathbf{s^{t}}) \geq \frac{\Delta(\mathbf{s^{t}})}{k} \geq \frac{\gamma(1-\mu)}{k} \cdot cost(\mathbf{s^{t}}) \geq \frac{\gamma(1-\mu)}{k} \cdot \Phi(\mathbf{s^{t}})$$

and we get what we desire as

$$\Phi(\mathbf{s^t}) - \Phi(s_i^*, s_{-i}^t) = c_i(\mathbf{s^t}) - c_i(s_i^*, s_{-i}^t) = \delta_i(\mathbf{s^t})$$

and hence

$$\left(1 - \frac{\gamma(1-\mu)}{k}\right)\Phi(\mathbf{s^t}) \ge \Phi(\mathbf{s^{t+1}}) \tag{4}$$

whenever $\mathbf{s^t}$ is a bad state. The equation in (4) says that for every MaxGain best response dynamics, if the state is bad, the new state $\mathbf{s^{t+1}}$ is smaller than the previous state $\mathbf{s^t}$ by a factor of $1 - \frac{\gamma(1-\mu)}{k}$. By Lemma 0.1, the potential decreases by a factor of e for every $\frac{k}{\gamma(1-\mu)}$ bad states encountered. Thus solving

$$e^{-n}\Phi(\mathbf{s^0}) > \Phi_{min}$$

shows (1).