Problem Set #6

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Exercise 9.1

Answer:

An unconstrained linear objective function is of the form $f(\mathbf{x}) = \mathbf{c}^T \mathbf{x}$, where \mathbf{c} is vector coefficient. If $\mathbf{c} = \mathbf{0}$, then $f(\mathbf{x}) = 0$, which is constant. If $\mathbf{c} \neq \mathbf{0}$, by contradiction assume $\mathbf{x}^* = argminf(\mathbf{x})$. i.e., $\forall \mathbf{x} \in \mathbb{R}, \mathbf{c}^T \mathbf{x}^* \leq \mathbf{c}^T \mathbf{x}$. It follows that $\mathbf{c}^T \mathbf{x}^* < 0$, since if $\mathbf{c}^T \mathbf{x}^* \ge 0$, then $\mathbf{c}^T (-\mathbf{x})^* = -\mathbf{c}^T \mathbf{x}^* \le 0 \le \mathbf{c}^T \mathbf{x}^*$. Now let $y = 2\mathbf{x}^*$, then $\mathbf{c}^T\mathbf{v}^* = 2\mathbf{c}^T\mathbf{x}^* < \mathbf{c}^T\mathbf{x}^* < 0$

Exercise 9.2

Answer:

Since $\|Ax-b\|_2 \ge 0$, to minimize $\|Ax-b\|_2$ is equivalent of minimizing $\|Ax-b\|_2^2$. Now $\|Ax-b\|_2^2 = \langle Ax-b, Ax-b \rangle = (Ax-b)*T(Ax-b) = x^TA^TAx - x^TA^Tb - b^TAx + b^T = x^TA^TAx - 2x^TA^Tb + b^T$

The last term is a constant so in the minimization problem we can drop it.

Let $f(x) = x^T A^T A x - 2x^T A^T b$, then $Df(x) = 2x^T (A^T A)^T - 2b^T A$, and $D^2 f(x) = 2x^T A^T A x - 2x^T A^T b$. $2A^TA$

If A is non-singular, then $D^2 f(x) > 0$.

By FOC, let Df(x) = 0, we have $x^T(A^TA)^T = b^TA \Leftrightarrow A^TAx = A^Tb$

Exercise 9.3

Answer:

Gradient decent: slow but cheap

Newton: fast but expensive

conjugate gradient: a combination of both

Exercise 9.4

Answer:

"\(\infty\)": Suppose $Df(x_0)^T = Qx_0 - b = \mathbf{v}$ is an eigenvector of Q, then $\alpha_0 = \frac{Df(x_0)Df(x_0)^T}{Df(x_0)QDf(x_0)^T} = \frac{V^TV}{V^TQV} = \frac{V^TV}{V^T\lambda V} = \frac{1}{\lambda}$

Now by our algorithm, $x_1 = x_0 - \alpha_0 Df(x_0)^T = x_0 - \frac{1}{\lambda} \mathbf{V}$

Observe that $Q\mathbf{x_1} = Q(x_0 - \frac{1}{\lambda}\mathbf{V}) = Qx_0 - \mathbf{V} = Qx_0 - (Qx_0 - b) = \mathbf{b}$

Hence $\mathbf{x_1} = A^{-1}b$ is a minimizer and therefore the algorithm converges in one step.

"⇒":

If
$$\mathbf{x_1} = Q^{-1}\mathbf{b}$$
, then $Q\mathbf{x_1} = \mathbf{b}$
Since $x_1 = x_0 - \alpha_0 Df(x_1)^T = x_0 - \alpha_0 (Qx_0 - b)$
We have $Q[x_0 - \alpha(Qx_0 - b)] = \mathbf{b} \Rightarrow Qx_0 - \alpha Q^2x_0 + \alpha Qb - b = 0$
Observe that $(I - \alpha Q)(Qx_0 - b) = Qx_0 - b - \alpha Q^2x_0 + \alpha Qb = 0$
Let $Qx_0 - \mathbf{b} = \mathbf{v}$, we have $(I - \alpha Q)\mathbf{v} = 0$, so $\mathbf{v} = \alpha Q\mathbf{v} \Rightarrow Q\mathbf{v} = \frac{1}{\alpha}\mathbf{v}$
Hence Qx_0 is an eigenvector of Q .

Exercise 9.5

Answer:

Assume $Df(x_k) \neq \mathbf{0}$, so we haven't reached the minimum yet. Since $\mathbf{x}_{k+1} - \mathbf{x}_k = -\alpha_k Df(x_k)^T$, and $\mathbf{x}_{k+2} - \mathbf{x}_{k+1} = -\alpha_{k+1} Df(x_{k+1})^T$, we want to show $(\mathbf{x}_{k+1} - \mathbf{x}_k)^T (\mathbf{x}_{k+2} - \mathbf{x}_{k+1}) = \alpha_k \alpha_{k+1} Df(x_k)^T Df(x_{k+1})^T = 0$ i.e., $Df(x_k)^T Df(x_{k+1})^T = 0$. Now, since $\alpha_k = argminf(x_k - \alpha Df(x_k)^T)$, and $f \in \mathbb{C}'$, by First Order Necessary Condition, we have $-Df(x_k)Df(x_{k+1})^T = 0 \Rightarrow Df(x_k)Df(x_{k+1})^T = 0$

Exercise 9.10

Answer:

Observe that $Df(x) = x^TQ^T - b^T$, and $D^2f(x) = Q > 0$, By Newton's method, $x_1 = x_0 - Q^{-1}(Qx_0 - b) = Q^{-1}b$ Since $D^2f(x_1) = Q > 0$ and $Df(x_1)^T = Qx_1 - b = QQ^{-1}b - b = \mathbf{0}$ \Rightarrow we know that x_1 is the unique minimizer.

Exercise 9.12

Answer:

Suppose (λ_i, v_i) is an eigen-pari of A. Observe that $Bv_i = (A\mu I)v_i = Av_i + \mu Iv_i = \lambda_i v_i + \mu v_i = (\lambda_i + \mu)v_i$. So $(\lambda_i + \mu, v_i)$ is an eigenpair of B.

Exercise 9.15

Answer:

Observe that $BC(C^{-1} + DA^{-A}B) = B + BCDA^{-1}B = (A + BCD)A^{-1}B$ So, $(A + BCD)^{-1}BC = A^{-1}B(C^{-1} + DA^{-1}B)^{-1}$ Hence,

$$A^{-1} = (A + BCD)^{-1}(A + BCD)A^{-1}$$

$$= (A + BCD)^{-1}(1 + BCDA^{-1})$$

$$= (A + BCD)^{-1} + [(A + BCD)^{-1}BC]DA^{-1}$$

$$= (A + BCD)^{-1} + A^{-1}B(C^{-1}DA^{-1}B)^{-1}DA^{-1}$$

$$\Rightarrow (A + BCD)^{-1} = A^{-1} - A^{-1}B(C^{-1}DA^{-1}B)^{-1}DA^{-1}$$