

Linear Algebra

(MT-121T)

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Lecture # 25

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Symmetric Matrices

- 1 A symmetric matrix S has n **real eigenvalues** λ_i and n **orthonormal eigenvectors** q_1, \dots, q_n .
- 2 Every real symmetric S can be diagonalized: $S = Q\Lambda Q^{-1} = Q\Lambda Q^T$
- 3 The number of positive eigenvalues of S equals the number of positive pivots.
- 4 Antisymmetric matrices $A = -A^T$ have *imaginary* λ 's and *orthonormal (complex)* q 's.
- 5 Section 9.2 explains why the test $S = S^T$ becomes $S = \overline{S}^T$ for *complex matrices*.

$$S = \begin{bmatrix} 0 & i \\ -i & 0 \end{bmatrix} = \overline{S}^T \text{ has real } \lambda = 1, -1.$$

$$A = \begin{bmatrix} 0 & i \\ i & 0 \end{bmatrix} = -\overline{A}^T \text{ has } \lambda = i, -i.$$

1. A symmetric matrix has only *real eigenvalues*.
2. The *eigenvectors* can be chosen *orthonormal*.

All Symmetric Matrices are Diagonalizable

Principal Axis Theorem

(Spectral Theorem) Every symmetric matrix has the factorization $S = Q\Lambda Q^T$ with real eigenvalues in Λ and orthonormal eigenvectors in the columns of Q :

Symmetric diagonalization

$$S = Q\Lambda Q^{-1} = Q\Lambda Q^T \quad \text{with} \quad Q^{-1} = Q^T. \quad (1)$$

Example

Example 2 The eigenvectors of a 2 by 2 symmetric matrix have a special form:

Not widely known $S = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$ has $x_1 = \begin{bmatrix} b \\ \lambda_1 - a \end{bmatrix}$ and $x_2 = \begin{bmatrix} \lambda_2 - c \\ b \end{bmatrix}$.

$$x_1^T x_2 = b(\lambda_2 - c) + (\lambda_1 - a)b = b(\lambda_1 + \lambda_2 - a - c) = 0.$$

This is zero because $\lambda_1 + \lambda_2$ equals the trace $a + c$. Thus $x_1^T x_2 = 0$. Eagle eyes might notice the special case $S = I$, when b and $\lambda_1 - a$ and $\lambda_2 - c$ and x_1 and x_2 are all zero. Then $\lambda_1 = \lambda_2 = 1$ is repeated. But of course $S = I$ has perpendicular eigenvectors.

Symmetric Matrices and Q

Symmetric matrices S have orthogonal eigenvector matrices Q . Look at this again:

Symmetry $S = X\Lambda X^{-1}$ becomes $S = Q\Lambda Q^T$ with $Q^T Q = I$.

This says that every 2 by 2 symmetric matrix is (**rotation**)(**stretch**)(**rotate back**)

$$S = Q\Lambda Q^T = \begin{bmatrix} q_1 & q_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} q_1^T \\ q_2^T \end{bmatrix}. \quad (5)$$

Columns q_1 and q_2 multiply rows $\lambda_1 q_1^T$ and $\lambda_2 q_2^T$ to produce $S = \lambda_1 q_1 q_1^T + \lambda_2 q_2 q_2^T$.

Every symmetric matrix $S = Q\Lambda Q^T = \lambda_1 q_1 q_1^T + \cdots + \lambda_n q_n q_n^T$

S has correct eigenvectors
Those q 's are orthonormal $Sq_i = (\lambda_1 q_1 q_1^T + \cdots + \lambda_n q_n q_n^T) q_i = \lambda_i q_i$

Eigenvalues versus Pivots

Example 4 This symmetric matrix has one positive eigenvalue and one positive pivot:

Matching signs $S = \begin{bmatrix} 1 & 3 \\ 3 & 1 \end{bmatrix}$ has pivots 1 and -8
eigenvalues 4 and -2 .

The signs of the pivots match the signs of the eigenvalues, one plus and one minus.
This could be false when the matrix is not symmetric:

Opposite signs $B = \begin{bmatrix} 1 & 6 \\ -1 & -4 \end{bmatrix}$ has pivots 1 and 2
eigenvalues -1 and -2 .

Worked Example

6.4 A What matrix A has eigenvalues $\lambda = 1, -1$ and eigenvectors $\mathbf{x}_1 = (\cos \theta, \sin \theta)$ and $\mathbf{x}_2 = (-\sin \theta, \cos \theta)$? Which of these properties can be predicted in advance?

$$A = A^T \quad A^2 = I \quad \det A = -1 \quad \text{pivot are } + \text{ and } - \quad A^{-1} = A$$

Solution All those properties can be predicted! With real eigenvalues $1, -1$ and orthonormal \mathbf{x}_1 and \mathbf{x}_2 , the matrix $A = Q\Lambda Q^T$ must be symmetric. The eigenvalues 1 and -1 tell us that $A^2 = I$ (since $\lambda^2 = 1$) and $A^{-1} = A$ (same thing) and $\det A = -1$. The two pivots must be positive and negative like the eigenvalues, since A is symmetric.

The matrix will be a reflection. Vectors in the direction of \mathbf{x}_1 are unchanged by A (since $\lambda = 1$). Vectors in the perpendicular direction are reversed (since $\lambda = -1$). The reflection $A = Q\Lambda Q^T$ is across the “ θ -line”. Write c for $\cos \theta$ and s for $\sin \theta$:

$$A = \begin{bmatrix} c & -s \\ s & c \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} c & s \\ -s & c \end{bmatrix} = \begin{bmatrix} c^2 - s^2 & 2cs \\ 2cs & s^2 - c^2 \end{bmatrix} = \begin{bmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{bmatrix}.$$

Notice that $\mathbf{x} = (1, 0)$ goes to $A\mathbf{x} = (\cos 2\theta, \sin 2\theta)$ on the 2θ -line. And $(\cos 2\theta, \sin 2\theta)$ goes back across the θ -line to $\mathbf{x} = (1, 0)$.

Complex Eigenvalues for Real Matrices

For any real matrix, $Sx = \lambda x$ gives $S\bar{x} = \bar{\lambda}\bar{x}$. For a symmetric matrix, λ and x turn out to be real. Those two equations become the same. But a *nonsymmetric* matrix can easily produce λ and x that are complex. Then $A\bar{x} = \bar{\lambda}\bar{x}$ is true but different from $Ax = \lambda x$. We get another complex eigenvalue (which is $\bar{\lambda}$) and a new eigenvector (which is \bar{x}):

For real matrices, complex λ 's and x 's come in "conjugate pairs."

$$\lambda = a + ib$$

$$\bar{\lambda} = a - ib$$

$$\text{If } Ax = \lambda x \text{ then } A\bar{x} = \bar{\lambda}\bar{x}.$$

Complex Eigenvalues for Real Matrices

Example 3 $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ has $\lambda_1 = \cos \theta + i \sin \theta$ and $\lambda_2 = \cos \theta - i \sin \theta$.

Those eigenvalues are conjugate to each other. They are λ and $\bar{\lambda}$. The eigenvectors must be x and \bar{x} , because A is real:

$$\begin{aligned} \text{This is } \lambda x \quad Ax &= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 1 \\ -i \end{bmatrix} = (\cos \theta + i \sin \theta) \begin{bmatrix} 1 \\ -i \end{bmatrix} \\ \text{This is } \bar{\lambda} \bar{x} \quad A\bar{x} &= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 1 \\ i \end{bmatrix} = (\cos \theta - i \sin \theta) \begin{bmatrix} 1 \\ i \end{bmatrix}. \end{aligned} \tag{9}$$

Those eigenvectors $(1, -i)$ and $(1, i)$ are complex conjugates because A is real.

For this rotation matrix the absolute value is $|\lambda| = 1$, because $\cos^2 \theta + \sin^2 \theta = 1$.
This fact $|\lambda| = 1$ holds for the eigenvalues of every orthogonal matrix Q .

Positive Definite Matrices

- 1 Symmetric S : all eigenvalues $> 0 \Leftrightarrow$ all pivots $> 0 \Leftrightarrow$ all upper left determinants > 0 .
- 2 The matrix S is then **positive definite**. The energy test is $x^T S x > 0$ for all vectors $x \neq 0$.
- 3 One more test for positive definiteness : $S = A^T A$ with independent columns in A .
- 4 **Positive semidefinite** S allows $\lambda = 0$, pivot $= 0$, determinant $= 0$, energy $x^T S x = 0$.
- 5 The equation $x^T S x = 1$ gives an ellipse in \mathbf{R}^n when S is symmetric positive definite.

Definition S is *positive definite* if $x^T S x > 0$ for every nonzero vector x :

2 by 2 $x^T S x = \begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = ax^2 + 2bxy + cy^2 > 0.$

Positive Definite Matrices

A 2×2 real symmetric matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a & b \\ b & d \end{bmatrix}$ is positive definite if and only if the diagonal entries a and d are positive and the determinant $|A| = ad - bc = ad - b^2$ is positive.

Consider the following symmetric matrices:

$$A = \begin{bmatrix} 1 & 3 \\ 3 & 4 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & -2 \\ -2 & -3 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & -2 \\ -2 & 5 \end{bmatrix}$$

A is not positive definite, because $|A| = 4 - 9 = -5$ is negative. B is not positive definite, because the diagonal entry -3 is negative. However, C is positive definite, because the diagonal entries 1 and 5 are positive, and the determinant $|C| = 5 - 4 = 1$ is also positive.

Positive Definite Matrices

When a symmetric matrix S has one of these five properties, it has them all :

1. All n *pivots* of S are positive.
2. All n *upper left determinants* are positive.
3. All n *eigenvalues* of S are positive.
4. $x^T S x$ is positive except at $x = 0$. This is the *energy-based* definition.
5. S equals $A^T A$ for a matrix A with *independent columns*.

Positive Definite Matrices

$$S = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

eigenvalues 1, 1, 4

determinants 2 and 3 and 4

pivots 2 and $3/2$ and $4/3$

$S - I$ will be *semidefinite*: eigenvalues 0, 0, 3

$S - 2I$ is *indefinite* because $\lambda = -1, -1, 2$

Example

Test these symmetric matrices S and T for positive definiteness:

$$S = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} \quad \text{and} \quad T = \begin{bmatrix} 2 & -1 & b \\ -1 & 2 & -1 \\ b & -1 & 2 \end{bmatrix}.$$

Solution The pivots of S are 2 and $\frac{3}{2}$ and $\frac{4}{3}$, all positive. Its upper left determinants are 2 and 3 and 4, all positive. The eigenvalues of S are $2 - \sqrt{2}$ and 2 and $2 + \sqrt{2}$, all positive. That completes tests 1, 2, and 3. Any one test is decisive!

Example (contd...)

I have three candidates A_1, A_2, A_3 to suggest for $S = A^T A$. They all show that S is positive definite. A_1 is a first difference matrix, 4 by 3, to produce $-1, 2, -1$ in S :

$$S = A_1^T A_1 \quad \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & -1 \end{bmatrix}$$

The three columns of A_1 are independent. Therefore S is positive definite.

Example (contd...)

A_2 comes from $S = LDL^T$ (the symmetric version of $S = LU$). Elimination gives the pivots $2, \frac{3}{2}, \frac{4}{3}$ in D and the multipliers $-\frac{1}{2}, 0, -\frac{2}{3}$ in L . **Just put $A_2 = L\sqrt{D}$.**

$$LDL^T = \begin{bmatrix} 1 & & \\ -\frac{1}{2} & 1 & \\ 0 & -\frac{2}{3} & 1 \end{bmatrix} \begin{bmatrix} 2 & & \\ & \frac{3}{2} & \\ & & \frac{4}{3} \end{bmatrix} \begin{bmatrix} 1 & -\frac{1}{2} & 0 \\ & 1 & -\frac{2}{3} \\ & & 1 \end{bmatrix} = (L\sqrt{D})(L\sqrt{D})^T = A_2^T A_2.$$

A_2 is the Cholesky factor of S

This triangular choice of A has square roots (not so beautiful). It is the “Cholesky factor” of S and the MATLAB command is $A = \text{chol}(S)$. In applications, the rectangular A_1 is how we build S and this Cholesky A_2 is how we break it apart.

Example (contd...)

Eigenvalues give the symmetric choice $A_3 = Q\sqrt{\Lambda}Q^T$. This is also successful with $A_3^T A_3 = Q\Lambda Q^T = S$. All tests show that the $-1, 2, -1$ matrix S is positive definite.

To see that the energy $x^T S x$ is positive, we can write it as a sum of squares. The three choices A_1, A_2, A_3 give three different ways to split up $x^T S x$:

$$x^T S x = 2x_1^2 - 2x_1x_2 + 2x_2^2 - 2x_2x_3 + 2x_3^2 \quad \text{Rewrite with squares}$$

$$\|A_1 x\|^2 = x_1^2 + (x_2 - x_1)^2 + (x_3 - x_2)^2 + x_3^2 \quad \text{Using differences in } A_1$$

$$\|A_2 x\|^2 = 2\left(x_1 - \frac{1}{2}x_2\right)^2 + \frac{3}{2}\left(x_2 - \frac{2}{3}x_3\right)^2 + \frac{4}{3}x_3^2 \quad \text{Using } S = LDL^T$$

$$\|A_3 x\|^2 = \lambda_1(q_1^T x)^2 + \lambda_2(q_2^T x)^2 + \lambda_3(q_3^T x)^2 \quad \text{Using } S = Q\Lambda Q^T$$

Example (contd...)

$$T = \begin{bmatrix} 2 & -1 & b \\ -1 & 2 & -1 \\ b & -1 & 2 \end{bmatrix}$$

Now turn to T (top of this page). The $(1, 3)$ and $(3, 1)$ entries move away from 0 to b . This b must not be too large! *The determinant test is easiest.* The 1 by 1 determinant is 2, the 2 by 2 determinant T is still 3. The 3 by 3 determinant involves b :

Test on T $\det T = 4 + 2b - 2b^2 = (1 + b)(4 - 2b)$ must be positive.

At $b = -1$ and $b = 2$ we get $\det T = 0$. *Between $b = -1$ and $b = 2$ this matrix T is positive definite.* The corner entry $b = 0$ in the matrix S was safely between -1 and 2 .

Minimum of a Function

First derivatives are zero $\frac{\partial F}{\partial x} = \frac{\partial F}{\partial y} = \frac{\partial F}{\partial z} = 0$ at the minimum point.

Next comes the linear algebra version of the usual calculus test $d^2 f / dx^2 > 0$:

Second derivative matrix S is positive definite $S = \begin{bmatrix} F_{xx} & F_{xy} & F_{xz} \\ F_{yx} & F_{yy} & F_{yz} \\ F_{zx} & F_{zy} & F_{zz} \end{bmatrix}$

Here $F_{xy} = \frac{\partial}{\partial x} \left(\frac{\partial F}{\partial y} \right) = \frac{\partial}{\partial y} \left(\frac{\partial F}{\partial x} \right) = F_{yx}$ is a ‘mixed’ second derivative.

Practice Problem

For which a and c is this matrix positive definite? For which a and c is it positive semidefinite (this includes definite)?

$$S = \begin{bmatrix} a & a & a \\ a & a + c & a - c \\ a & a - c & a + c \end{bmatrix}$$

All 5 tests are possible.

The energy $\mathbf{x}^T S \mathbf{x}$ equals

$$a(x_1 + x_2 + x_3)^2 + c(x_2 - x_3)^2.$$

| | | |
|--|---|---|
| Symmetric: $S^T = S = Q\Lambda Q^T$ | real eigenvalues | orthogonal $x_i^T x_j = 0$ |
| Orthogonal: $Q^T = Q^{-1}$ | all $ \lambda = 1$ | orthogonal $\bar{x}_i^T x_j = 0$ |
| Skew-symmetric: $A^T = -A$ | imaginary λ 's | orthogonal $\bar{x}_i^T x_j = 0$ |
| Complex Hermitian: $\bar{S}^T = S$ | real λ 's | orthogonal $\bar{x}_i^T x_j = 0$ |
| Positive Definite: $x^T S x > 0$ | all $\lambda > 0$ | orthogonal since $S^T = S$ |
| Markov: $m_{ij} > 0, \sum_{i=1}^n m_{ij} = 1$ | $\lambda_{\max} = 1$ | steady state $x > 0$ |
| Similar: $A = BCB^{-1}$ | $\lambda(A) = \lambda(C)$ | B times eigenvector of C |
| Projection: $P = P^2 = P^T$ | $\lambda = 1; 0$ | column space; nullspace |
| Plane Rotation : cosine-sine | $e^{i\theta}$ and $e^{-i\theta}$ | $x = (1, i)$ and $(1, -i)$ |
| Reflection: $I - 2uu^T$ | $\lambda = -1; 1, \dots, 1$ | u ; whole plane u^\perp |
| Rank One: uv^T | $\lambda = v^T u; 0, \dots, 0$ | u ; whole plane v^\perp |
| Inverse: A^{-1} | $1/\lambda(A)$ | keep eigenvectors of A |
| Shift: $A + cI$ | $\lambda(A) + c$ | keep eigenvectors of A |
| Stable Powers: $A^n \rightarrow 0$ | all $ \lambda < 1$ | any eigenvectors |
| Stable Exponential: $e^{At} \rightarrow 0$ | all $\operatorname{Re} \lambda < 0$ | any eigenvectors |
| Cyclic Permutation: $P_{i,i+1} = 1, P_{n1} = 1$ | $\lambda_k = e^{2\pi i k/n} = \text{roots of } 1$ | $x_k = (1, \lambda_k, \dots, \lambda_k^{n-1})$ |
| Circulant: $c_0 I + c_1 P + \dots$ | $\lambda_k = c_0 + c_1 e^{2\pi i k/n} + \dots$ | $x_k = (1, \lambda_k, \dots, \lambda_k^{n-1})$ |
| Tridiagonal: $-1, 2, -1$ on diagonals | $\lambda_k = 2 - 2 \cos \frac{k\pi}{n+1}$ | $x_k = \left(\sin \frac{k\pi}{n+1}, \sin \frac{2k\pi}{n+1}, \dots \right)$ |
| Diagonalizable: $A = X\Lambda X^{-1}$ | diagonal of Λ | columns of X are independent |
| Schur: $A = QTQ^{-1}$ | diagonal of triangular T | columns of Q if $A^T A = A A^T$ |
| Jordan: $A = BJB^{-1}$ | diagonal of J | each block gives 1 eigenvector |
| SVD: $A = U\Sigma V^T$ | r singular values in Σ | eigenvectors of $A^T A, A A^T$ in V, U |

Singular Value Decomposition

- 1 An image is a large matrix of grayscale values, one for each pixel and color.
- 2 When nearby pixels are correlated (not random) the image can be compressed.
- 3 The SVD separates any matrix A into rank one pieces $uv^T = (\text{column})(\text{row})$.
- 4 The columns and rows are eigenvectors of symmetric matrices AA^T and $A^T A$.

Singular Value Decomposition

- SVD enables us to factor any $m \times n$ matrix A into the product of three matrices, $A = U \Sigma V^T$ where
 - U is an orthogonal $m \times m$ matrix
 - V is an orthogonal $n \times n$ matrix.
 - Σ is an $m \times n$ matrix with a diagonal upper left submatrix D of positive entries decreasing in magnitude, the remaining entries being zeros.

$$\Sigma = \begin{bmatrix} D & \vdots & 0 \\ \dots & \dots & \dots \\ 0 & \vdots & 0 \end{bmatrix}, \text{ where } D = \begin{bmatrix} \sigma_1 & \dots & \vdots \\ \vdots & \ddots & \vdots \\ \dots & \dots & \sigma_r \end{bmatrix} \text{ with } \sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_r > 0,$$

for $r \leq m, n$

Examples of Σ

$$\begin{bmatrix} 9 & 0 & 0 \\ 0 & 3 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 6 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 8 & 0 & 0 & 0 \\ 0 & 7 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sigma_1 = 9, \sigma_2 = 3, \quad \sigma_1 = 6, \sigma_2 = 2, \quad \sigma_1 = 7, \sigma_2 = 5, \sigma_3 = 2, \quad \sigma_1 = 8, \sigma_2 = 7, \sigma_3 = 1$$

$$r = 2$$

$$r = 2$$

$$r = 3$$

$$r = 3$$

Example 1

Find a singular value decomposition of the following matrix A .

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \end{bmatrix}$$

We want to find the matrices U, Σ, V such that $A = U\Sigma V^t$. It is useful to keep track of the sizes of the various matrices. We get

$$\begin{array}{ccccccc} A & = & U & & \Sigma & & V^t \\ m \times n & & m \times m & & m \times n & & n \times n \\ & & & & \text{(general } m \times n \text{ matrix } A) & & \end{array}$$

$$\begin{array}{ccccccc} A & = & U & & \Sigma & & V^t \\ 2 \times 3 & & 2 \times 2 & & 2 \times 3 & & 3 \times 3 \\ & & & & \text{(our } 2 \times 3 \text{ matrix } A) & & \end{array}$$

Example 1 (contd...)

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \end{bmatrix}$$

Finding V: The columns of V will be eigenvectors of $A^t A$. We get

$$A^t A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 4 \end{bmatrix}$$

The eigenvalues of $A^t A$ are computed and found to be $\lambda = 5, 1, 0$ (in descending order of magnitude).

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{5} \\ 0 \\ 2/\sqrt{5} \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} -2/\sqrt{5} \\ 0 \\ 1/\sqrt{5} \end{bmatrix} \quad V = \begin{bmatrix} 1/\sqrt{5} & 0 & -2/\sqrt{5} \\ 0 & 1 & 0 \\ 2/\sqrt{5} & 0 & 1/\sqrt{5} \end{bmatrix}$$

$(\lambda = 5) \qquad (\lambda = 1) \qquad (\lambda = 0)$

Finding the Singular Values: The *singular values* of A are the positive square roots of the eigenvalues of $A^t A$. The singular values are

$$\sigma_1 = \sqrt{5}, \sigma_2 = 1, \sigma_3 = 0$$

Example 1 (contd...)

Finding Σ : Σ is to be a 2×3 matrix with upper left block being a diagonal matrix D with diagonal elements $\sigma_1 = \sqrt{5}, \sigma_2 = 1$.

$$D = \begin{bmatrix} \sqrt{5} & 0 \\ 0 & 1 \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \sqrt{5} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Finding U : U is a 2×2 matrix. The column vectors of U are selected to be the vectors $\mathbf{u}_1 = \frac{1}{\sigma_1} A \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, and $\mathbf{u}_2 = \frac{1}{\sigma_2} A \mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. These vectors are orthonormal. U is the orthogonal matrix

$$U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A = U \Sigma V^t = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \sqrt{5} & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1/\sqrt{5} & 0 & 2/\sqrt{5} \\ 0 & 1 & 0 \\ -2/\sqrt{5} & 0 & 1/\sqrt{5} \end{bmatrix}$$