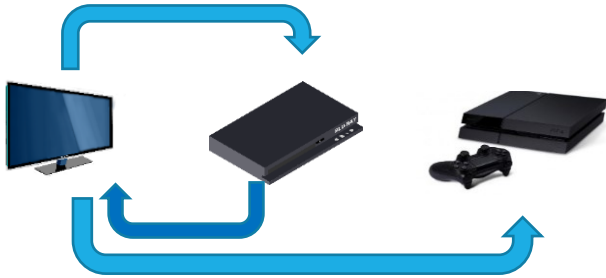


Recommender Systems

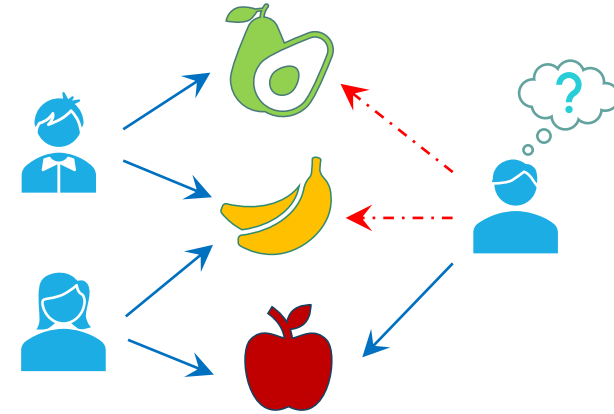
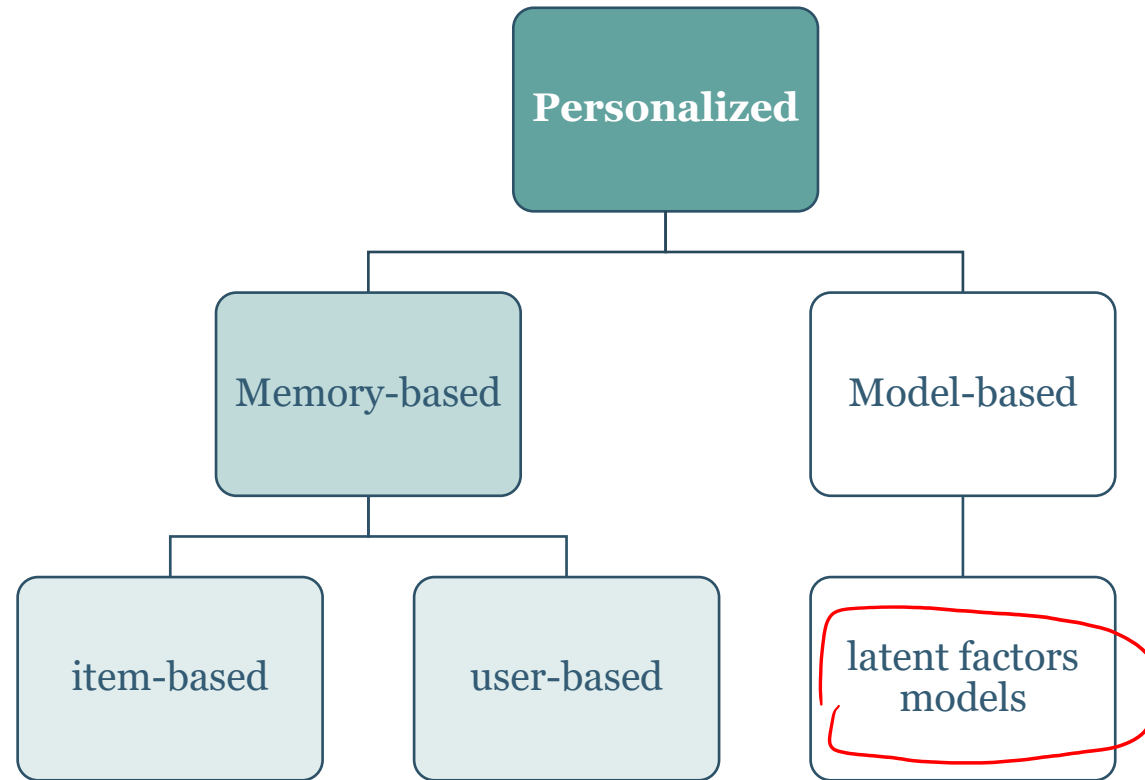
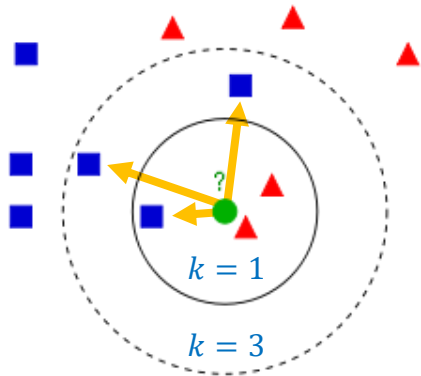
Lecture 5

Previous lecture

Association Rules



kNN



Previous lecture: neighborhood formation

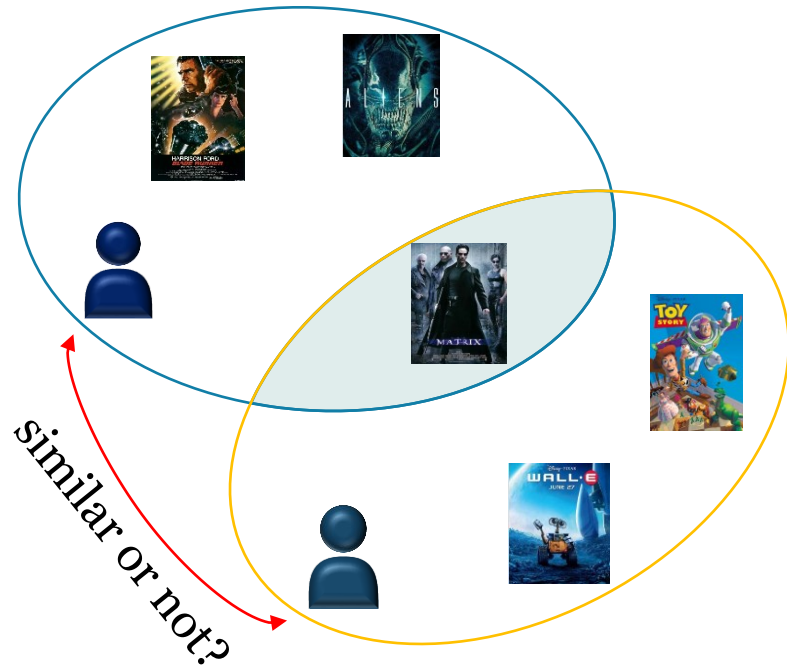
1. sample w.r.t. observed ratings: $\mathcal{N}_i(u)$ or $\mathcal{N}_u(i)$
2. sample n entities, s.t. $k \ll n \ll N$
 - randomly
 - by recency
3. select top- k most similar
 - what similarity?

Choosing between user-based and item-based:

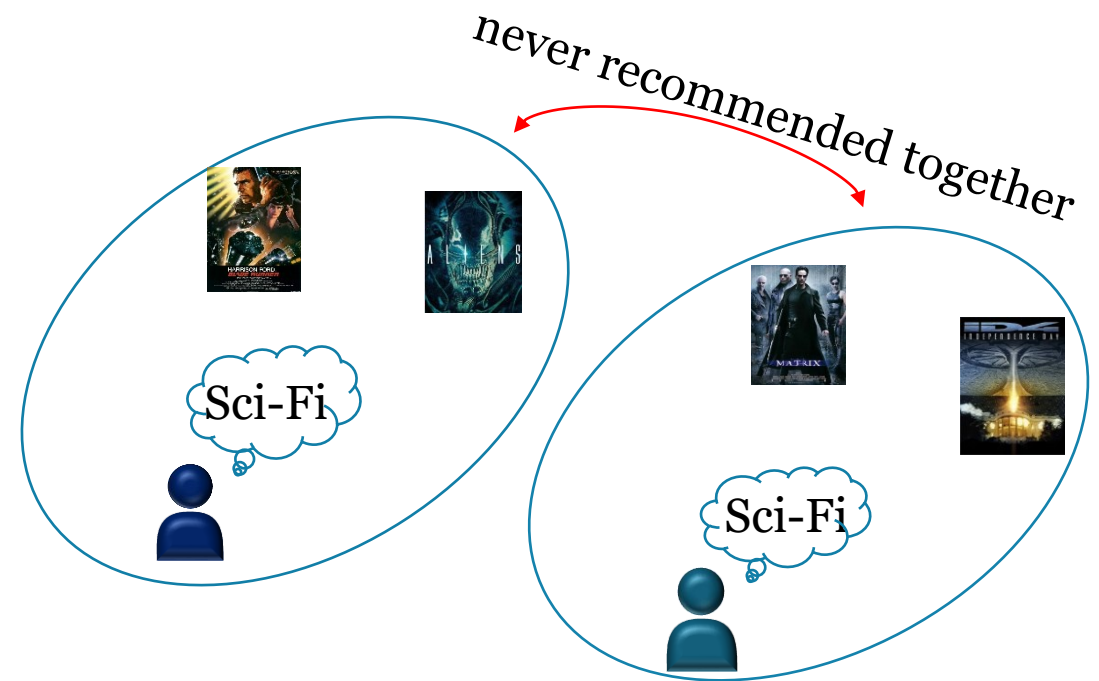
- # users vs. # items
- system dynamics
- explainability vs. serendipity

Previous lecture: limited coverage problems

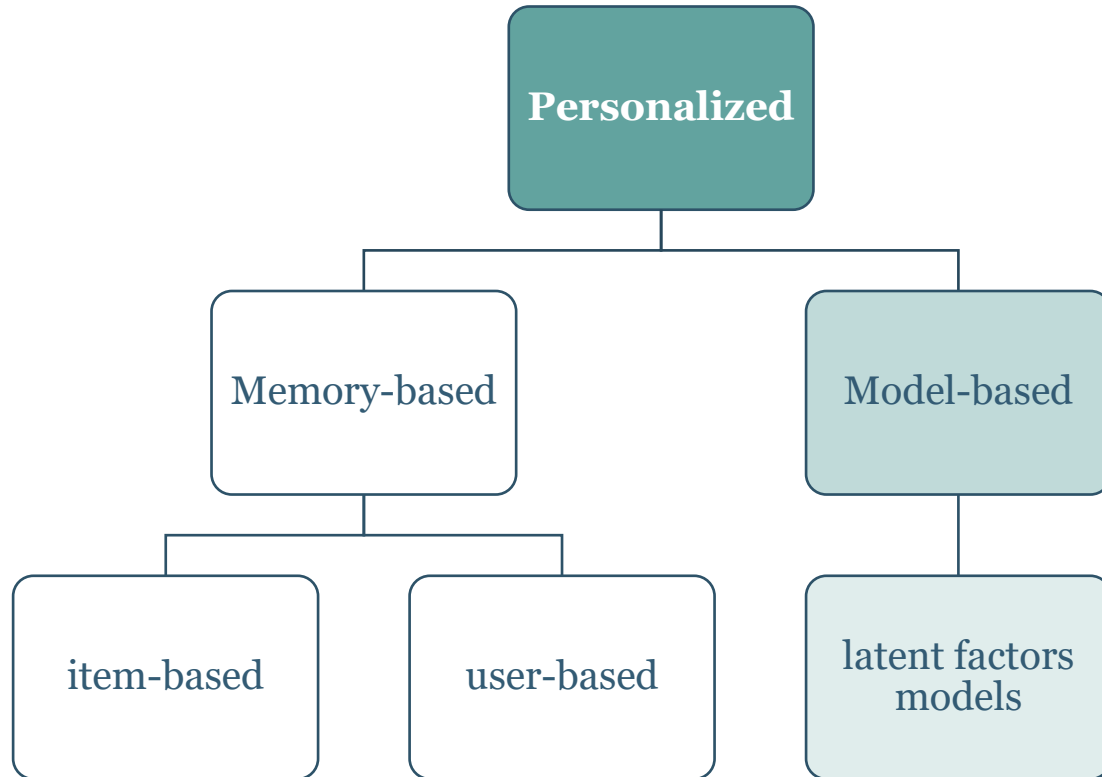
Unreliable correlations



Weak generalization



Today's Lecture



- Low-rank approximation for CF
 - PureSVD
 - Recommendation vs matrix completion
- Revisiting popularity bias

Low rank representation



	?	3	5	5
	4	?	5	5

$$A \approx PQ^T$$

$$A \approx R$$

4	3	?		
?	3	5		
4	?	5		
			4	5
			?	5

$$A \approx P a^T$$

Handwritten matrices:

$$P = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$a = \begin{bmatrix} 4 \\ 3 \\ 5 \\ 5 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$Q = \begin{bmatrix} 4 & 0 \\ 3 & 0 \\ 5 & 0 \\ 5 & 0 \end{bmatrix}$$

A general view on latent factors models

- **Task:** find utility (relevance) function f_R :

$$f_R: \text{Users} \times \text{Items} \rightarrow \text{Relevance score}$$

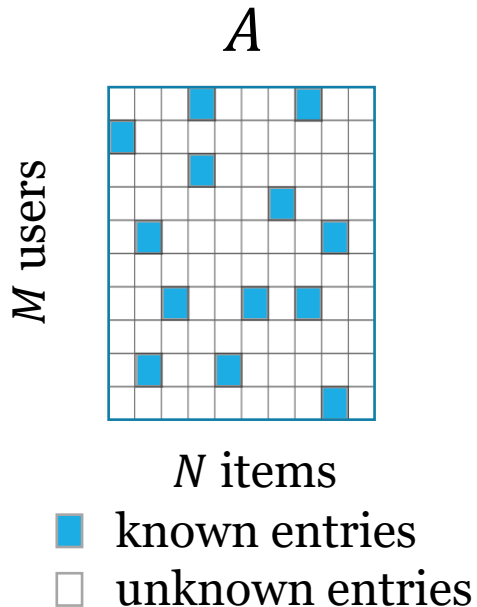
- As optimization problem with some *loss function* \mathcal{L} :

$$\mathcal{L}(A, R) \rightarrow \min$$

$$R = PQ^T$$
$$r_{ij} = p_i^T q_j$$

Components of the model:

- Utility function to generate R
- Optimization objective defined by \mathcal{L}
- Optimization method (algorithm)

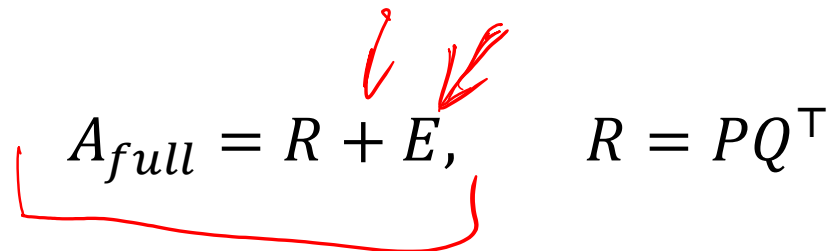


What is the form
of R and \mathcal{L} ?


Intuition behind MF

Assumption: observed interactions can be explained via

- a *small* number of common patterns in human behavior
- + individual variations (including random factors and “unknown unknowns”)

$$A_{full} = R + E, \quad R = PQ^T$$


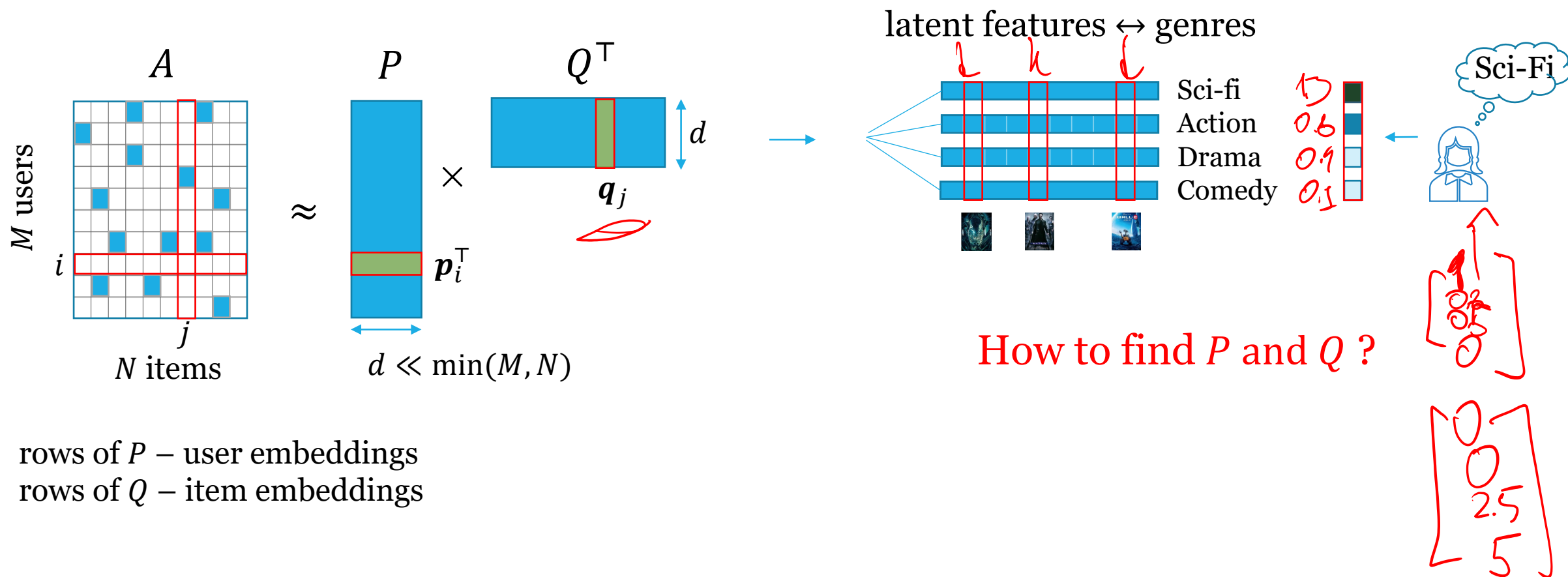
Predicted utility of item j for user i :

$$r_{ij} \approx \mathbf{p}_i^T \mathbf{q}_j = \sum_{k=1}^d p_{ik} q_{jk}$$


\mathbf{p}_i – latent factors vector for user i

\mathbf{q}_j – latent factors vector for item j

Simplistic view on latent features



Singular Value Decomposition

Quick reminder:

$$A = U \Sigma V^T$$

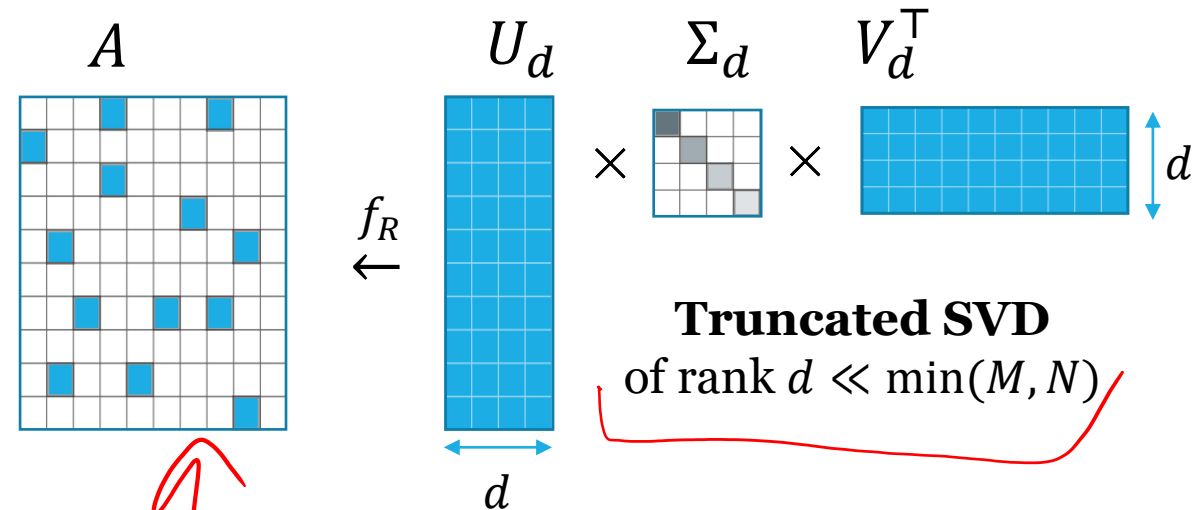
$$U \in \mathbb{R}^{M \times M}, \quad V \in \mathbb{R}^{N \times N}$$

$$U^T U = I_M, \quad V^T V = I_N$$

$\Sigma \in \mathbb{R}^{M \times N}$ - diagonal, with $[\Sigma]_{kk} = \sigma_k$:

$$\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_{\min(M,N)} \geq 0$$

$$\sigma_k(A) = \sqrt{\lambda_k(A^T A)} = \sqrt{\lambda_k(AA^T)}$$



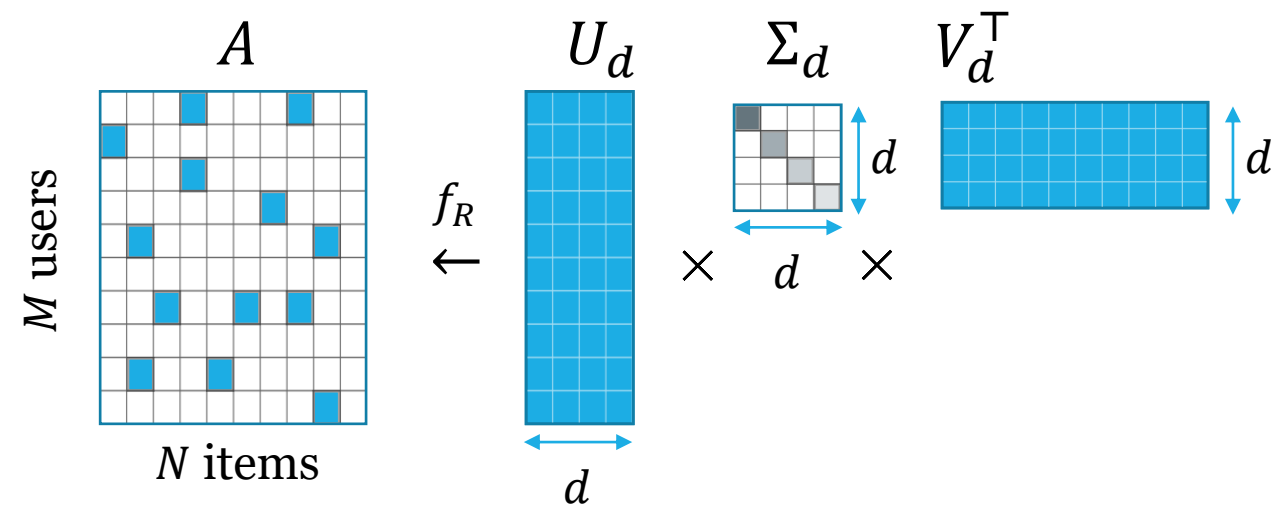
Low-rank approximation task:

$$\|A - R\|_F^2 \rightarrow \min, \text{ s.t. } \text{rank}(R) = d$$

$$R = U_d \Sigma_d V_d^T, \quad \|A - R\|_F^2 = \sum_{i=d+1}^{\infty} \sigma_i^2$$

Is it directly applicable here?

PureSVD model for CF



Relevance score prediction:

$$A_0 V_d V_d^T = U_d \Sigma_d V_d^T V_d^T = U_d \Sigma_d V_d^T = R$$

Handwritten notes: $\Sigma = \begin{bmatrix} \Sigma_d \\ 0 \end{bmatrix}$, $V = [V_d \ V_\perp]$, $V_d^T V_d = I$, $V_\perp^T V_d = 0$.

Let's impute zeros in place of unknowns!

$$A_0 = U \Sigma V^T, \quad [A_0]_{ij} = \begin{cases} a_{ij}, & \text{if known} \\ 0, & \text{otherwise} \end{cases}$$

$$R = U_d \Sigma_d V_d^T$$

$$R = A V_d V_d^T = U_d U_d^T A_0 \downarrow \downarrow$$

$$R V = A_0 V = U \Sigma$$

Explaining recommendations

Which one is more explainable?

$$R = PQ^T$$

$$\mathbf{r}_u = Q \mathbf{p}_u$$

vs.

$$\mathbf{r}_u = \underbrace{VV^T}_{\substack{\downarrow \downarrow \\ \mathbf{v}^T \mathbf{a} = \sum_{i \in N_u} v_i}} \mathbf{a}_u$$

$$A = U \sum V^T$$

$$\mathbf{v}^T \mathbf{a} = \sum_{i \in N_u} v_i$$

$$\underbrace{v_j^T}_{\substack{\uparrow \\ \text{minmax}}} \left(\sum_{i \in N_u} v_i \right) = \sum_{i \in N_u} \underbrace{v_j^T v_i}_{\substack{\uparrow \\ \text{minmax}}}$$

Which model does PureSVD resemble?

$$Z = C \mathbf{a}$$

$$C = \bar{A}^T A - \text{diag}(\text{diag}(\bar{A}^T A))$$

$$\begin{matrix} 0.3 & 0.1 & 0.021 \\ \nearrow & \uparrow & \uparrow \\ & \text{minmax} & \end{matrix}$$

PureSVD computation

- Efficient computation with Lanczos algorithm

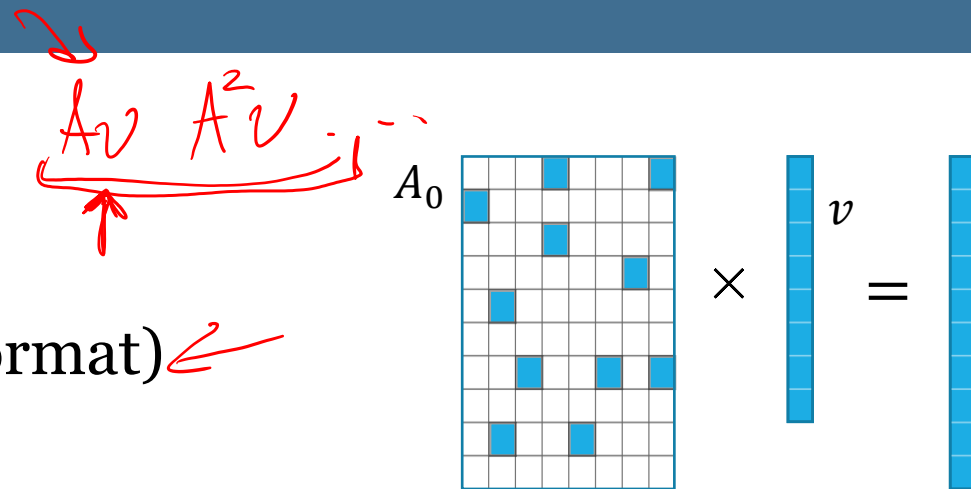
- iterative process
- requires only sparse matvec (fast with CSR format)
- complexity $O(nnz \cdot d) + O((M + N) \cdot d^2)$

nnz – number of non-zeros of A_0

- Efficient implementations in Python:

- SciPy Sparse svds,
- Scikit-Learn TruncatedSVD.

- Core functionality is also implemented in Spark.



Billion-scale computations with SVD

In practice, in distributed setups, randomized SVD is used.

Examples:

- Criteo* <https://github.com/criteo/Spark-RSVD>
- Facebook's randomized SVD implementation
<https://research.fb.com/fast-randomized-svd>

Research:

- “out-of-memory” SVD [Kabir 2017]
- communication-avoiding algebra [Demmel 2008]
- DeepMind’s attempt to adapt to modern hardware (GPU, TPU) via game-theoretic approach
<https://www.deepmind.com/blog/game-theory-as-an-engine-for-large-scale-data-analysis>

```
Generate random matrix  $\Omega \in \mathbb{R}^{n \times (k+p)}$   
 $Y \leftarrow A\Omega$   
 $Q \leftarrow \text{QR}(Y)$  ▷ QR decomposition of  $Y$   
for  $i \leftarrow 1$  to  $q$  do  
   $Y \leftarrow A^T Q$   
   $Q \leftarrow \text{QR}(Y)$   
   $Y \leftarrow A Q$   
   $Q \leftarrow \text{QR}(Y)$   
end for  
 $B \leftarrow Q^T A$   
 $\tilde{Q}, \tilde{R} \leftarrow \text{QR}(B^T)$   
SVD decomposition of  $\tilde{R} = \tilde{V} \Sigma \tilde{U}^T$   
return  $U = Q \tilde{U}$ 
```

*Read more: [SparkRSVD open-sourced by Criteo for large scale recommendation engines](#)

Lifecycle of a recsys model

Gather initial data



Train a
model



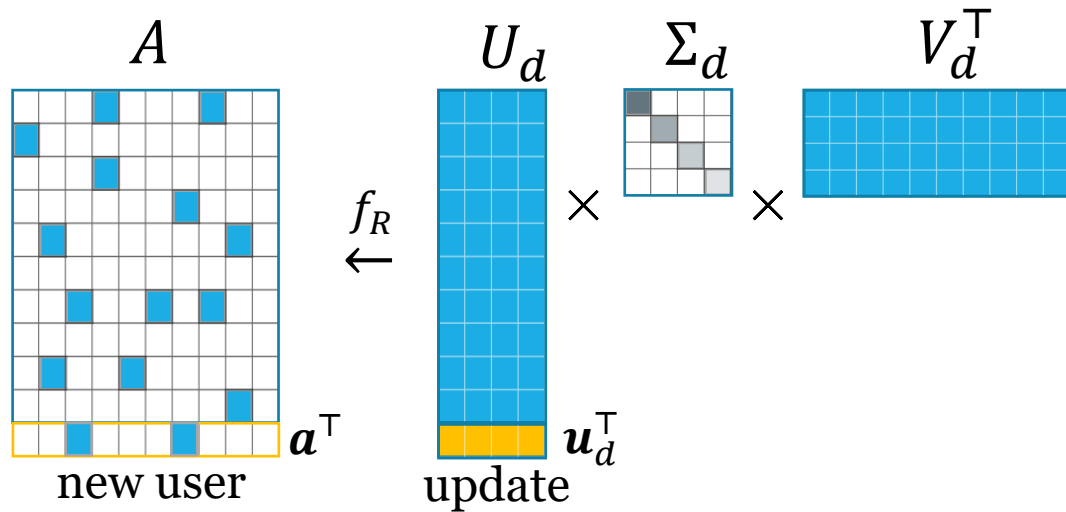
Recommend



Gather
feedback



PureSVD – recommending online



*folding-in technique**

Finding a warm-start user representation:

$$\|\mathbf{a}_0^\top - \mathbf{u}^\top \Sigma V^\top\|_2^2 \rightarrow \min$$

new user embedding

$$\mathbf{u}^\top = \mathbf{a}_0^\top V \Sigma^{-1}$$

Prediction:

$$\mathbf{r}^\top = \mathbf{u}_d^\top \Sigma_d V_d^\top = \mathbf{a}_0^\top V_d V_d^\top$$

$$\mathbf{r} = V_d V_d^\top \mathbf{a}_0$$

- convenient for evaluation
- complexity $\sim O(Nd)$
- enables real-time recommendations

*G. Furnas, S. Deerwester, and S. Dumais, "Information Retrieval Using a Singular Value Decomposition Model of Latent Semantic Structure," Proceedings of ACM SIGIR Conference, 1988

On-stream and incremental learning

Incremental learning:

- *Adding new users/items:*
 - rank-1 updates (see G. Golub, C. Van Loan, “Matrix Computations”)
 - M. Brand "Incremental singular value decomposition of uncertain data with missing values.", 2002.

Adding new interactions:

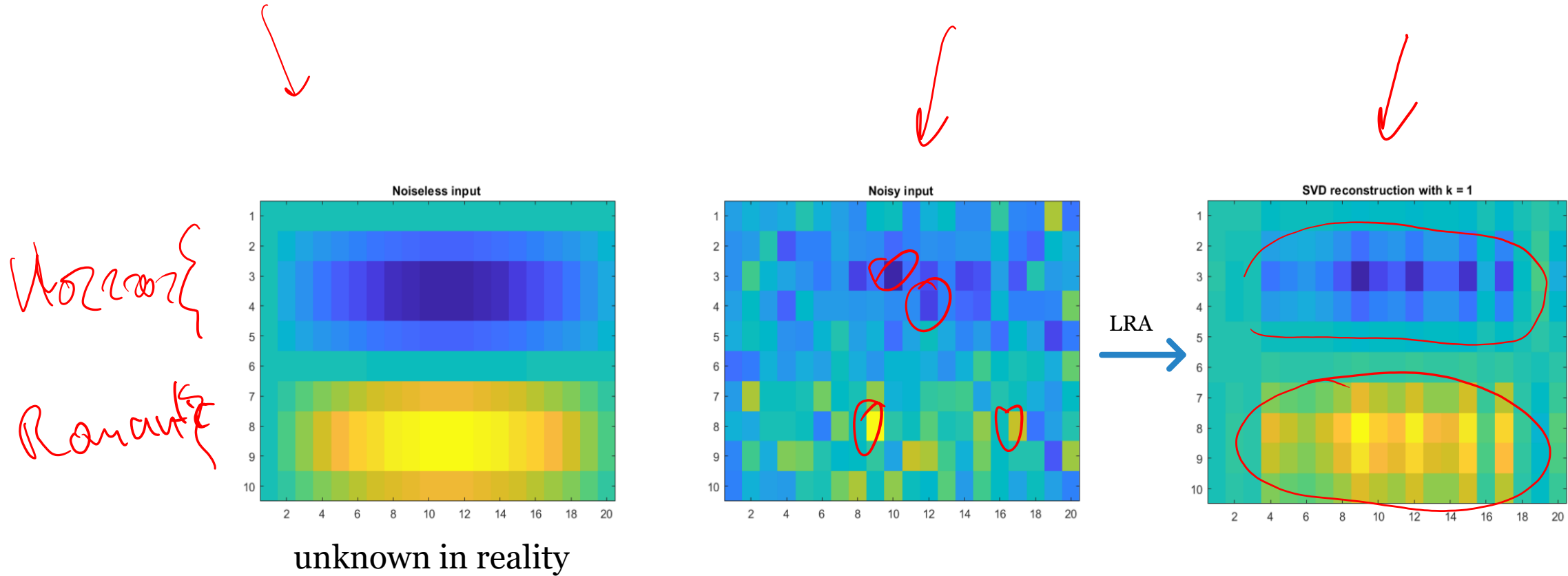
- *via projector splitting approach* [Lubich & Oseledets 2013]:
 - example in recsys: [Olaleke et al. 2021]
- *streaming:*
 - Method of frequent directions [Ghashami et al. 2016]
 - Zoom SVD [Jang et al. 2018]

Handwritten notes in red:

✓

$$\frac{\|A - R\|_F^2}{\|\dot{A} - \dot{R}\|_F^2}$$
$$A \rightarrow \frac{A + \Delta A}{\Delta t} \approx \frac{dA}{dt}$$
$$A(t) = \int_0^t \dot{A} dt$$

CF as low-rank approximation task



Images source: Khoshrou, Abdolrahman, and Eric J. Pauwels. "Regularisation for PCA-and SVD-type matrix factorisations." *arXiv preprint arXiv:2106.12955* (2021).

Approximation with irreducible noise

$$A = \mathbf{e} \cdot \mathbf{a}^T + \epsilon B$$

$$[B]_{ij} \approx \mathcal{N}(0, 1)$$



$$\sigma_1^2(A) \leq M \|\mathbf{a}\|^2 + \epsilon^2 N$$

$$\sigma_k^2(A) \approx \epsilon^2 N, k \gg 1$$



?	3	5	5
4	?	5	5

$$\sigma_1^2(A) = \lambda_1(AA^T) = \lambda_1(\mathbf{e}\mathbf{a}\mathbf{a}^T\mathbf{e}^T + \epsilon\mathbf{a}\mathbf{a}^T\mathbf{B}^T + \epsilon\mathbf{B}\mathbf{a}\mathbf{e}^T + \epsilon^2\mathbf{B}\mathbf{B}^T)$$

$$= \lambda_1(\|\mathbf{a}\|^2\mathbf{e}\mathbf{e}^T + \epsilon^2 N \mathbf{I})$$

$$[\mathbf{B}\mathbf{B}^T]_{ij} = \sum_k \delta_{ik} \delta_{jk} \approx N$$

$$\delta_{ik} \delta_{jk} \approx \begin{cases} 1, & i=j \\ 0, & i \neq j \end{cases}$$

$$\lambda_1(G) = \max_{\|\mathbf{u}\|=1} \mathbf{u}^T G \mathbf{u}$$

$$\|\mathbf{a}\|^2 - \mathbf{u}^T \mathbf{e} \mathbf{e}^T \mathbf{u} = \|\mathbf{a}\| (\mathbf{u}^T \mathbf{e})^2 \leq \|\mathbf{a}\|^2 (\mathbf{u}^T \mathbf{u}) (\mathbf{e}^T \mathbf{e}) = M \|\mathbf{a}\|^2$$

Practical consequences

- larger # of items – harder pattern discovery task
- even in the simplest case singular values won't become 0
 - let's check it!
- no simple choice of the optimal rank of the decomposition
 - $\|A - U_d \Sigma_d V_d^T\|_F = \sqrt{\sigma_{d+1}^2 + \dots + \sigma_{\min(M,N)}^2}$
- doesn't mean you can't get close to zero RMSE on trainset

Data centering (PCA style)

Observations:

- *today*: in PureSVD, values are highly biased towards 0
- *previously*: a signal is carried mostly by baseline estimators

How does it affect rating prediction?

Strategy:

- value imputation \rightarrow mean shifted matrix
- akin to data centering in PCA

Spectrum of mean-shifted ratings matrix

$$A = \hat{A}_0 + \alpha \mathbf{e}_M \mathbf{e}_N^T$$

$$[\hat{A}_0]_{ij} = \begin{cases} a_{ij} - d_i - d_j & \text{if } ij \text{ known} \\ 0 & \text{otherwise} \end{cases}$$

$$\sigma_1^2(A) = \sigma_1^2(\hat{A}_0) + \alpha^2 MN$$

$$\sigma_k^2(A) \approx \sigma_k^2(\hat{A}_0), k \gg 1$$

u_1, u_2, u_3

u_1

Let's evaluate!

Note: we have a dense (and potentially huge) matrix

$$A = \hat{A}_0 + \alpha \mathbf{e}_M \mathbf{e}_N^T$$

Example: $M = 1_000_000$ users and $N = 100_000$ items would require ≈ 745 Gb of RAM

How to avoid explicitly forming it?

$$A v = \underbrace{\hat{A}_0 v}_{O(M)} + \underbrace{\alpha \mathbf{e}_M (\mathbf{e}_N^T v)}_{O(N)}$$

Practical consequences

- SVD for CF is:
 - NOT pure matrix completion
 - NOT pure dimensionality reduction
- common PCA-like preprocessing may spoil data representation
- rating prediction doesn't make sense
 - recommendations can still be good!
 - we can treat rating values more flexibly