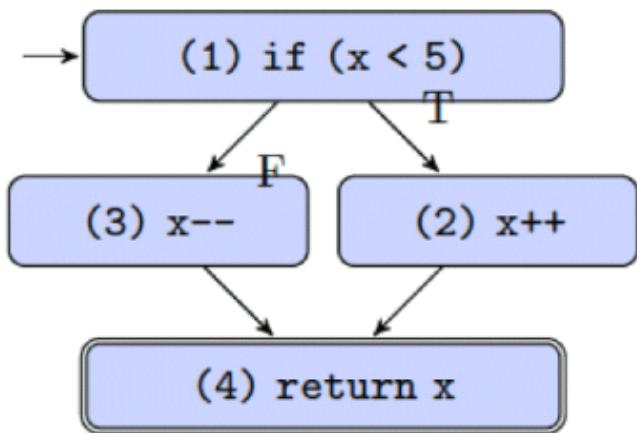


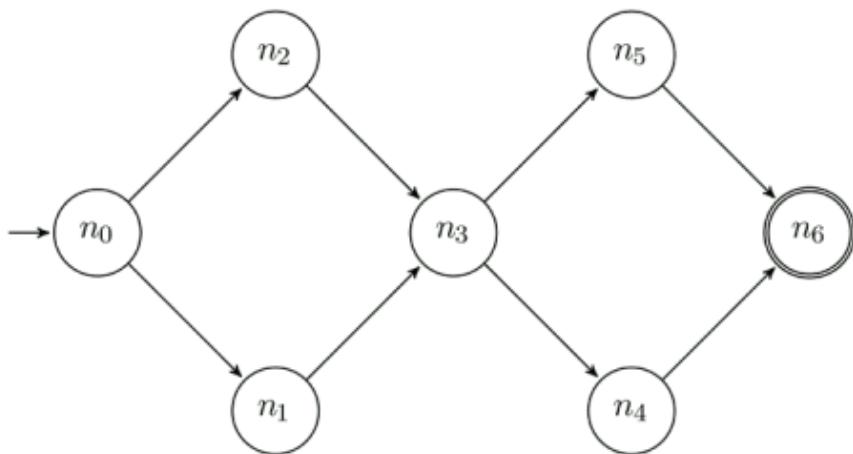
## Connecting Test Cases, Test Paths & CFG

```
int foo(int x) {  
    if (x < 5) {  
        x++;  
    } else {  
        x--;  
    }  
    return x;  
}
```



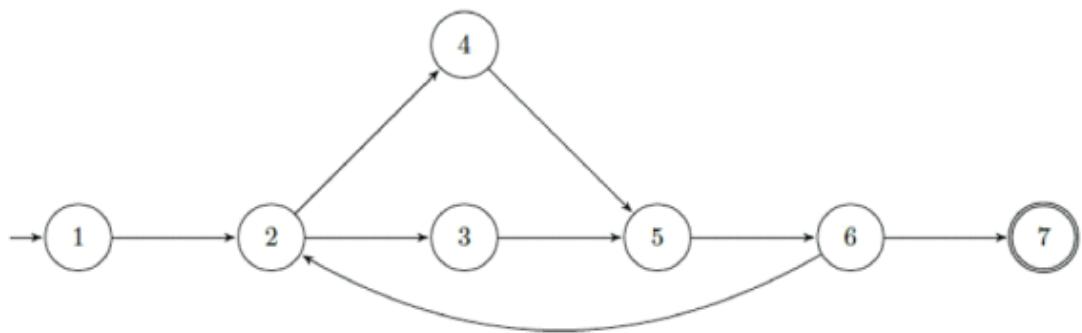
- Test case:  $x = 5$ ; test path:  $[(1), (3), (4)]$ .
- Test case:  $x = 2$ ; test path:  $[(1), (2), (4)]$ .

## Node Coverage



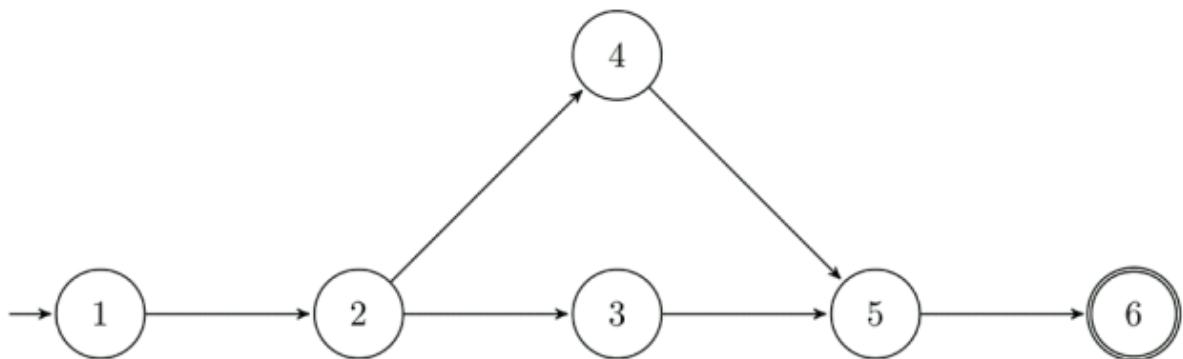
- *Node coverage:* For each node  $n \in \text{reachG}[N_0]$ , TR contains a requirement to visit node  $n$ .
- **Node Coverage [NC]:** TR contains each **reachable** node in  $G$ .
- $\text{TR} = \{n_0, n_1, n_2, n_3, n_4, n_5, n_6\}$

## Edge Coverage



- *Edge Coverage [EC]: TR contains each **reachable** path of length up to 1, inclusive, in G.*
- $TR = \{[1,2], [2,4], [2,3], [3,5], [4,5], [5,6], [6,7], [6,2]\}$

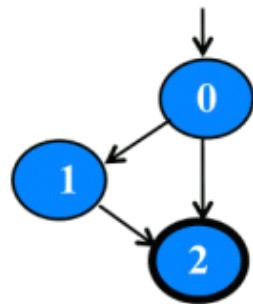
## Edge Pair Coverage



- *Edge-Pair Coverage [EPC]: TR contains each **reachable** path of length up to 2, inclusive, in G.*
- $TR = \{[1,2,3], [1,2,4], [2,3,5], [2,4,5], [3,5,6], [4,5,6]\}$

# Node and Edge Coverage

- Edge coverage is slightly stronger than node coverage.
- NC and EC are only different when there is an edge and another subpath between a pair of nodes [as in an “if-else” statement]



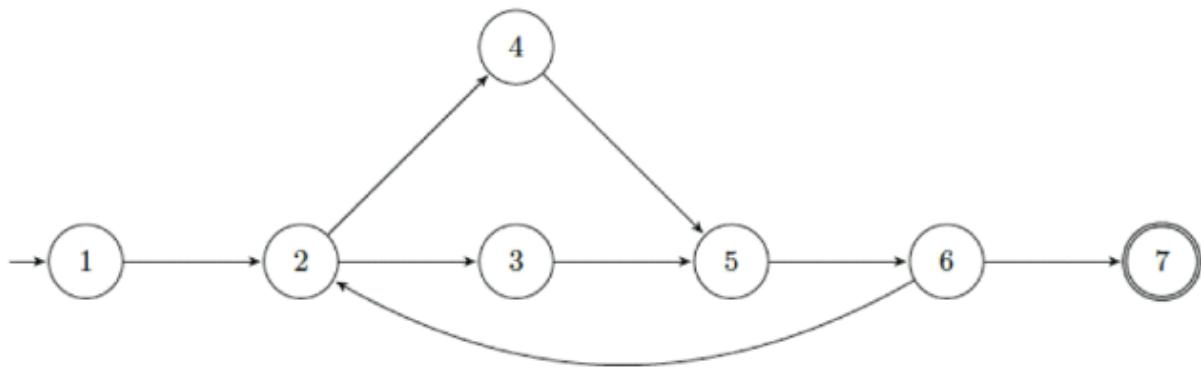
**Node Coverage :** TR = { 0, 1, 2 }  
Test Path = [ 0, 1, 2 ]

**Edge Coverage :** TR = { [0,1], [0, 2], [1, 2] }  
Test Paths = [ 0, 1, 2 ]  
[ 0, 2 ]

## Simple Path

- A path is **simple** if no node appears more than once in the path, except that the first and last nodes may be the same.
- Some properties of simple paths:
  - no internal loops;
  - can bound their length;
  - can create any path by composing simple paths; and
  - many simple paths exist [too many!]

## Simple Path Examples

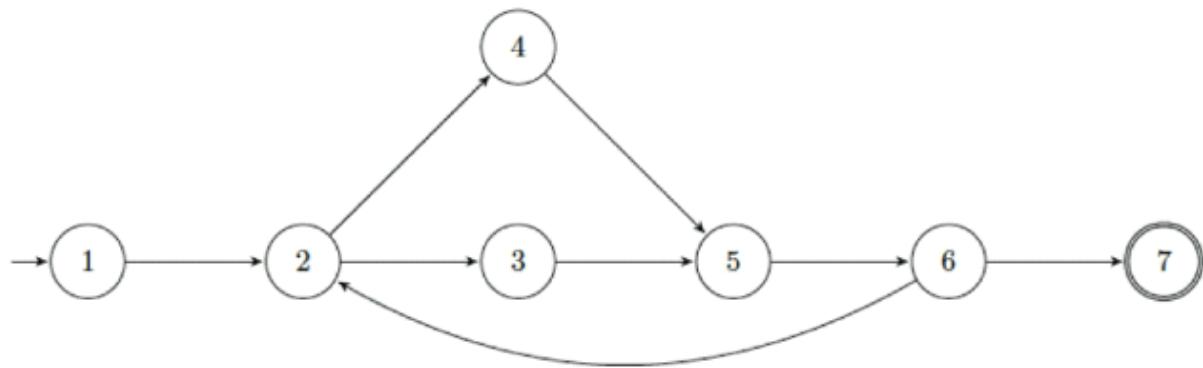


- Simple path examples:
  - [1, 2, 3, 5, 6, 7]
  - [1, 2, 4]
  - [2,3,5,6,2]
- Not simple Path: [1,2,3,5,6,2,4]

## Prime Path

- Because there are so many simple paths, let's instead consider **prime paths**, which are simple paths of maximal length.
- A path is **prime** if it is simple and does not appear as a proper subpath of any other simple path.

## Prime Path Examples



- Prime path examples:
  - [1, 2, 3, 5, 6, 7]
  - [1, 2, 4, 5, 6, 7]
  - [6, 2, 4, 5, 6]
- Not a prime path: [3, 5, 6, 7]

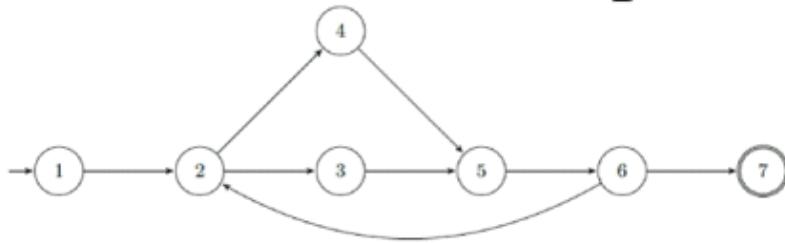
## Prime Path Coverage

- Prime Path Coverage [PPC]: TR contains each prime path in G.
- There is a problem with using PPC as a coverage criterion: a prime path may be infeasible but contains feasible simple paths.
  - How to address this issue?

## More Path Coverage Criterions

- Complete Path Coverage [CPC]: TR contains all paths in G.
- Specified Path Coverage [SPC]: TR contains a specified set S of paths.

# Prime Path Example



Simple paths

Len 0

[1]  
[2]  
[3]  
[4]  
[5]  
[6]  
[7]!

Len 1

[1,2]  
[2,4]  
[2,3]  
[3,5]  
[4,5]  
[5,6]  
[6,7]!  
[6,2]

Len 2

Len 3

Len 4

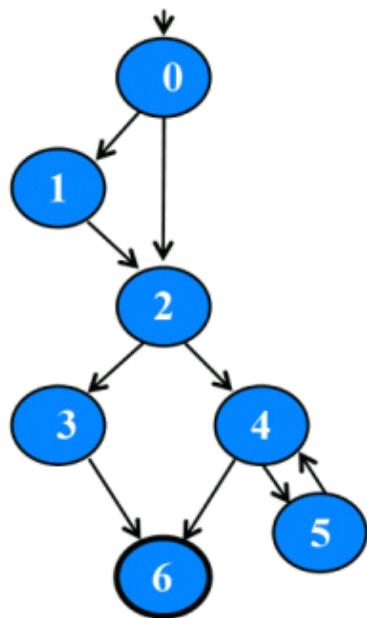
Len 5

53 Simple Paths  
12 Prime Paths

! means path terminates

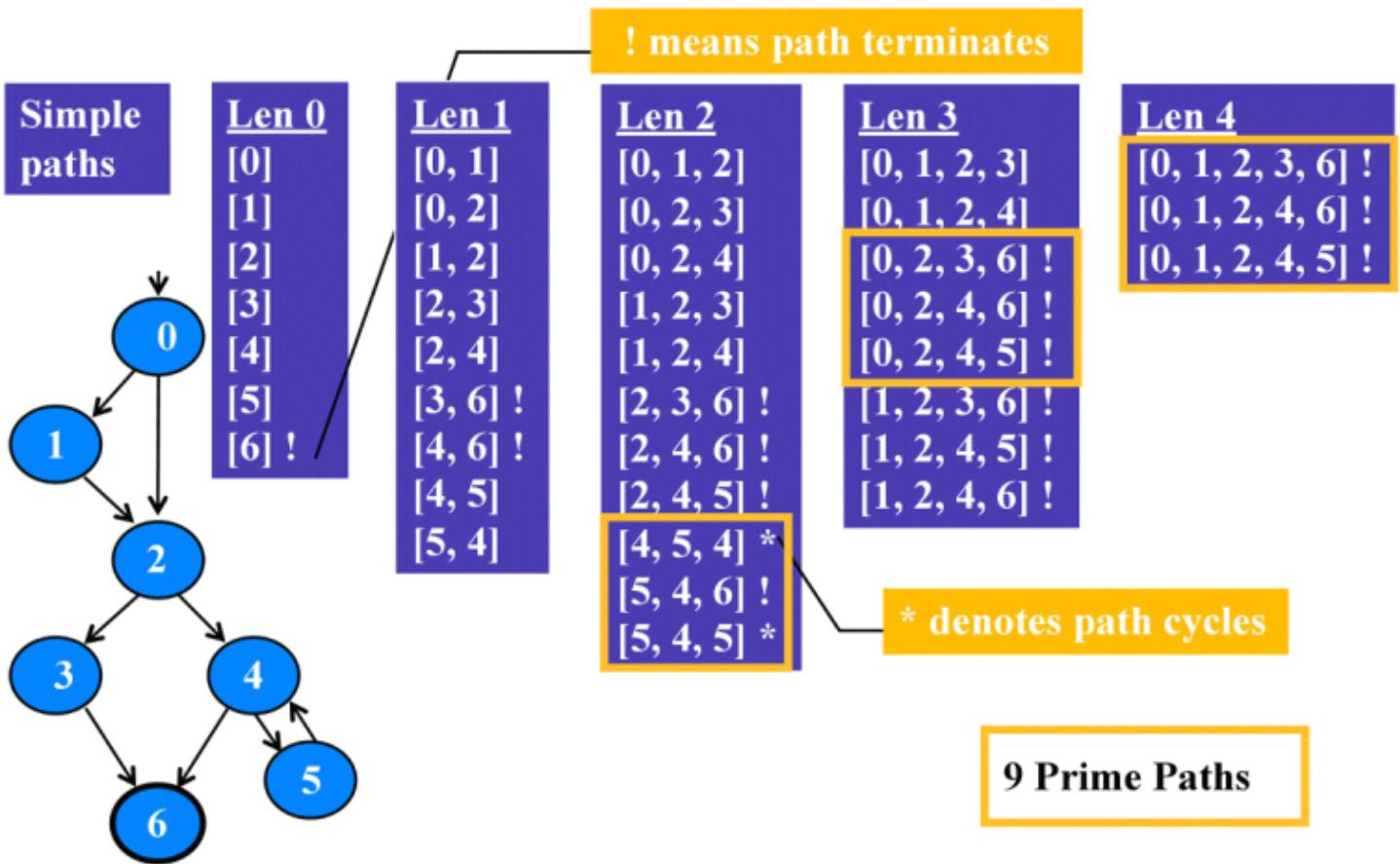
## Prime Path Example (2)

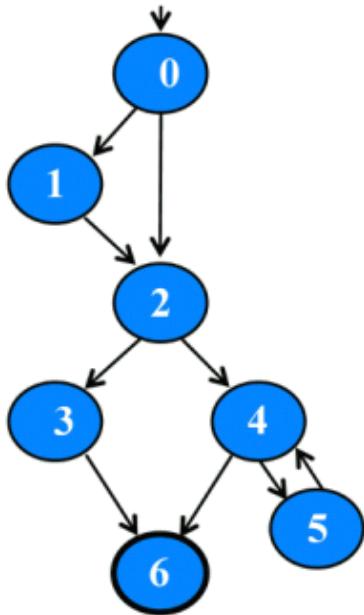
- This graph has 38 **simple** paths
- Only **9 prime paths**



<u>Prime Paths</u>
[ 0, 1, 2, 3, 6 ]
[ 0, 1, 2, 4, 5 ]
[ 0, 1, 2, 4, 6 ]
[ 0, 2, 3, 6 ]
[ 0, 2, 4, 5 ]
[ 0, 2, 4, 6 ]
[ 5, 4, 6 ]
[ 4, 5, 4 ]
[ 5, 4, 5 ]

## Prime Path Example (2)





#### Node Coverage

TR = { 0, 1, 2, 3, 4, 5, 6 }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]

#### Edge Coverage

TR = { [0,1], [0,2], [1,2], [2,3], [2,4], [3,6], [4,5], [4,6], [5,4] }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 6 ]

#### Edge-Pair Coverage

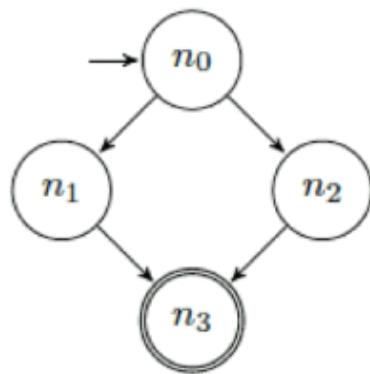
TR = { [0,1,2], [0,2,3], [0,2,4], [1,2,3], [1,2,4], [2,3,6],  
[2,4,5], [2,4,6], [4,5,4], [5,4,5], [5,4,6] }

Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 2, 3, 6 ] [ 0, 2, 4, 5, 4, 5, 4, 6 ]  
[ 0, 1, 2, 4, 6 ]

#### Complete Path Coverage

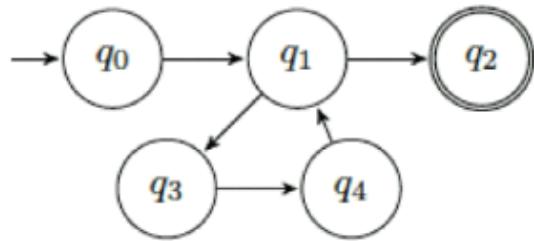
Test Paths: [ 0, 1, 2, 3, 6 ] [ 0, 1, 2, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 6 ]  
[ 0, 1, 2, 4, 5, 4, 5, 4, 6 ] [ 0, 1, 2, 4, 5, 4, 5, 4, 6 ] ...

## Prime Path Coverage vs. Complete Path Coverage



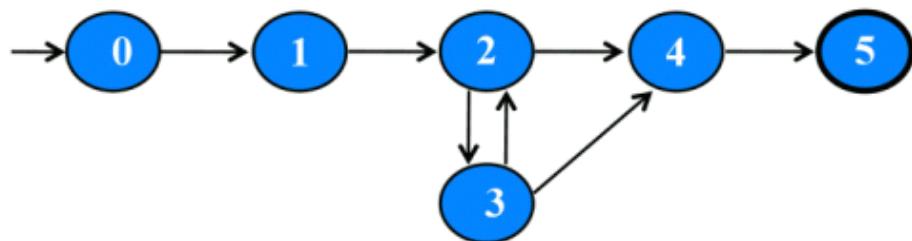
- Prime paths:
- $\text{path}(t_1) =$
- $\text{path}(t_2) =$
- $T_1 = \{t_1, t_2\}$  satisfies both PPC and CPC.

## Prime Path Coverage vs. Complete Path Coverage (2)



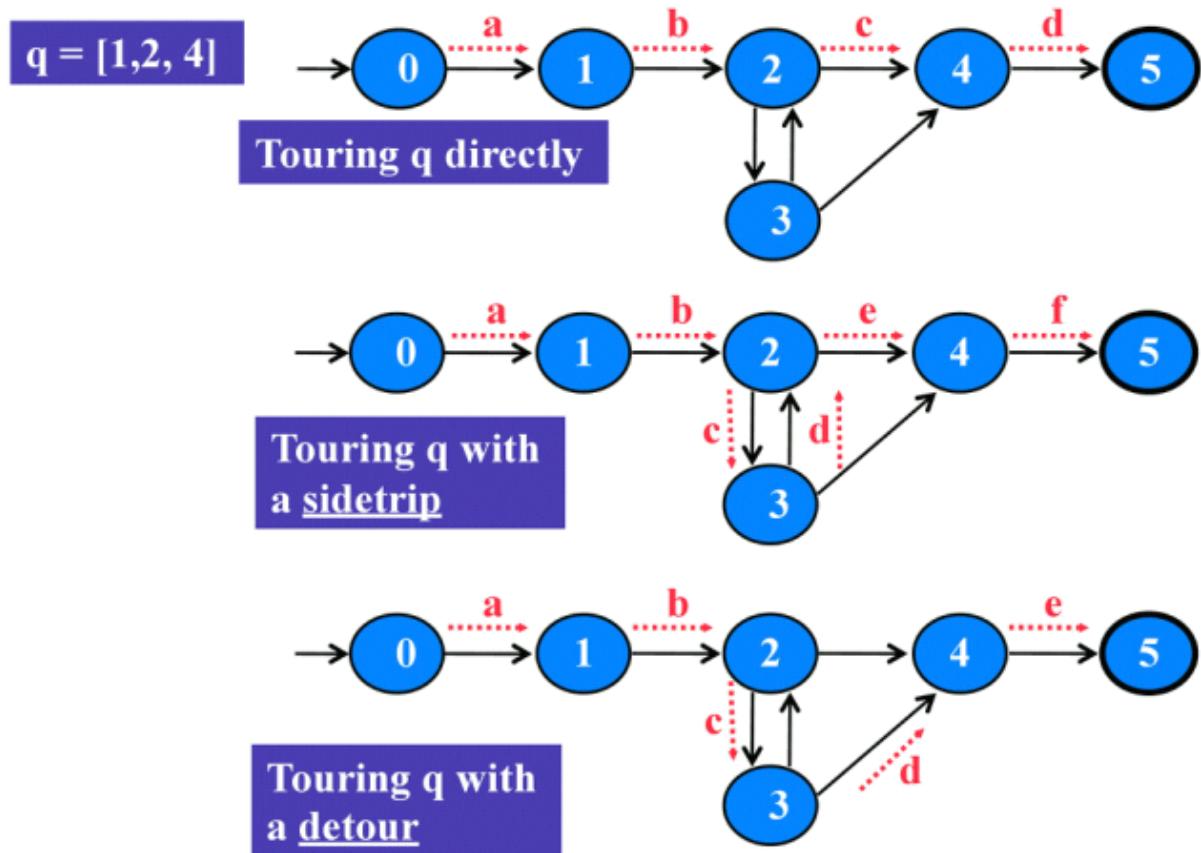
- Prime paths:
- $\text{path}(t_3) =$
- $\text{path}(t_4) =$
- $T_1 = \{t_3, t_4\}$  satisfies      PPC but not CPC.

## Sidetrips and Detours



- It may not be possible for any test path to tour path  $q = [1, 2, 4]$ .
  - Why?
- Any path that visits 3 does not tour path  $q$ .
  - $p_1 = [0, 1, 2, 3, 2, 4, 5]$
  - $p_2 = [0, 1, 2, 3, 4, 5]$
- But  $p_1$  and  $p_2$  tour  $q$  in a more general sense.

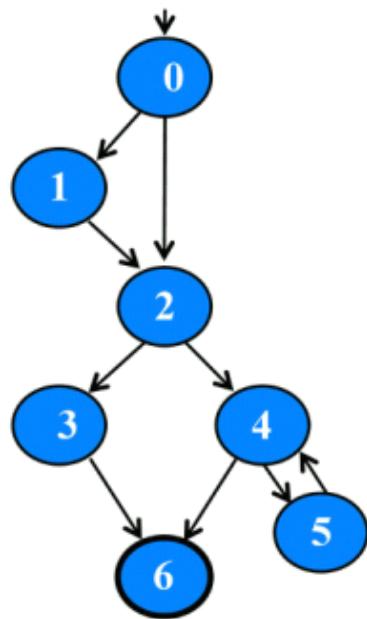
## Sidetrips and Detours Example



## Tour with Sidetrips and Detours

- For the following definitions, assume that q is simple.
- **Tour (directly)**: Test path p tours subpath q iff q is a **subpath** of p.
- **Tour with sidetrips**: Test path p tours subpath q with sidetrips iff every **edge** in q is also in p, in the same order.
- **Tour with detours**: Test path p tours subpath q with detours iff every **node** in q is also in p, in the same order.

## Sidetrips and Detours Example (2)



- $p = [0, 1, 2, 4, 5, 4, 6]$
- $p1 = [0, 1, 2, 4, 6]$
- $p2 = [0, 2, 4, 5, 4, 6]$
- **$p$  tours  $p1$  with a sidetrip.**
- **$p$  tours  $p2$  with a detour.**

## Refining Coverage Criteria

- We could define each graph coverage criterion and explicitly include the kinds of tours allowed, e.g.
  - prime paths, with direct tours;
  - prime paths, sidetrips allowed;
  - prime paths, detours allowed.
- Detours seem less practical, so we do not include detours further.
- We do need sidetrips sometimes, or too many TRs are infeasible.

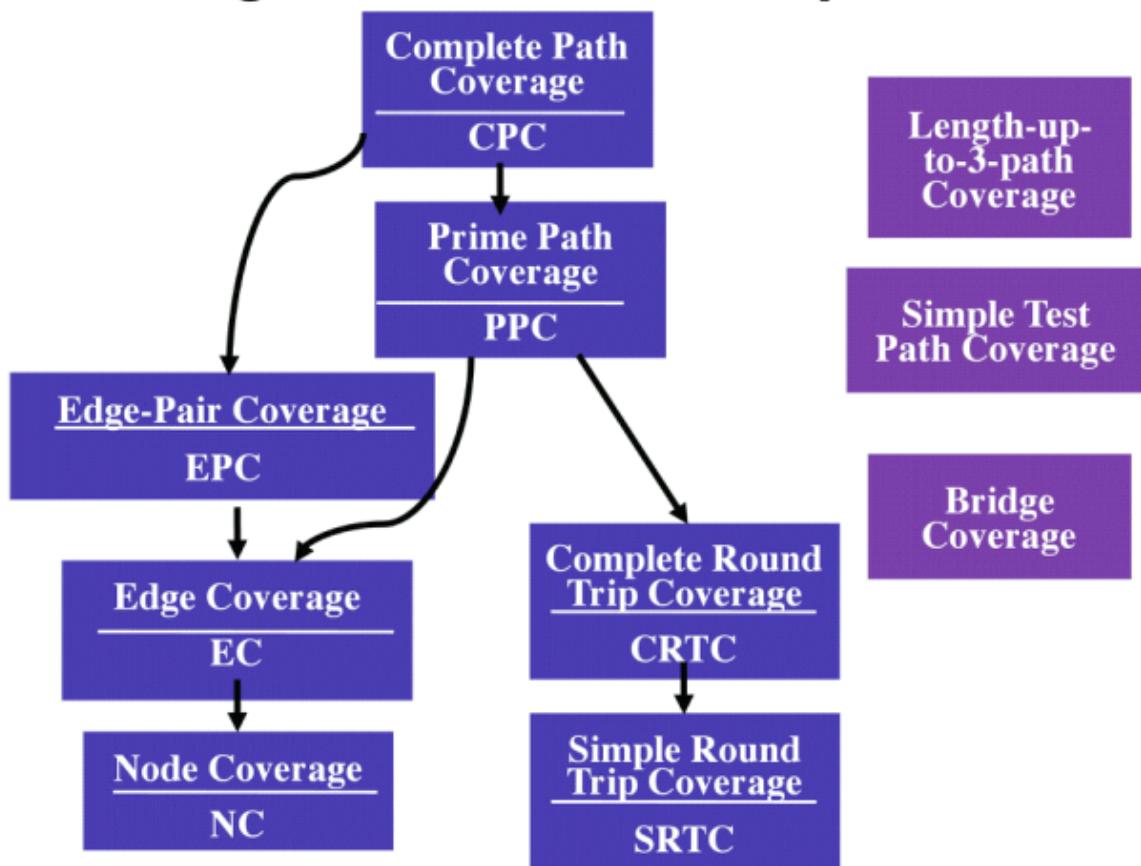
## Best Effort Touring

- We'd rather not use sidetrips when we don't have to.
- $TR_{tour}$ : the subset of test requirements that can be toured [directly]
- $TR_{sidetrip}$ : the subset of test requirements that can be toured with sidetrips.
- **Best Effort Touring**: A set  $T$  of test paths achieves best effort touring if for every path  $p$  in  $TR_{tour}$ , some path in  $T$  tours  $p$  [directly], and for every path  $p$  in  $TR_{sidetrip}$ , some path in  $T$  tours  $p$  either directly or with a sidetrip.
- Best-effort touring meets as many TRs as possible, each in the strictest possible way. Best-effort touring has desirable theoretical properties with respect to subsumption.

## Round trip path

- A **round trip path** is a prime path of nonzero length that starts and ends at the same node.
- **Simple Round Trip Coverage [SRTC]:** TR contains at least one round-trip path for each reachable node in G that begins and ends a round-trip path.
- **Complete Round Trip Coverage [CRTC]:** TR contains all round-trip paths for each reachable node in G.

# Graph Coverage Criteria Subsumption



## Exercise

- Answer questions [a]-[g] for the graph defined by the following sets:
  - $N = \{1, 2, 3, 4, 5, 6, 7\}$
  - $N_0 = \{1\}$
  - $N_f = \{7\}$
  - $E = \{[1, 2], [1, 7], [2, 3], [2, 4], [3, 2], [4, 5], [4, 6], [5, 6], [6, 1]\}$
- Also consider the following test paths:
  - $t_0 = [1, 2, 4, 5, 6, 1, 7]$
  - $t_1 = [1, 2, 3, 2, 4, 6, 1, 7]$

## **Exercise - cont.**

- [a] Draw the graph.
- [b] List the test requirements for EPC. [Hint: You should get 12 requirements of length 2].
- [c] Does the given set of test paths satisfy EPC? If not, identify what is missing.
- [d] Consider the simple path [3,2,4,5,6] and test path [1,2,3,2,4,6,1,2,4,5,6,1,7]. Does the test path tour the simple path directly? With a sidetrip? Is so, identify the sidetrip.
- [e] List the test requirements for NC, EC and PPC on the graph.
- [f] List a test path that achieve NC but not EC on the graph.
- [g] List a test path that achieve EC but not PPC on the graph.