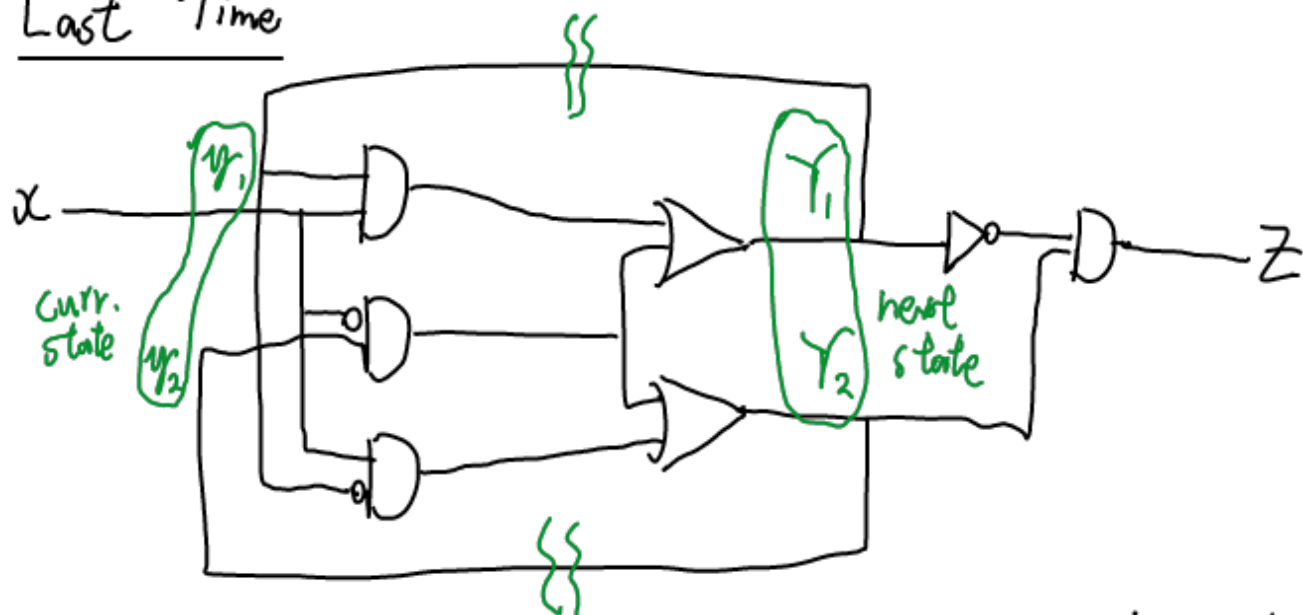


Last Time



Analysis - abstract away the actual implementation

- Steps:
- 1) Identify feedback paths, next state + curr. state.
 - 2) Write eqns for next state + outputs in terms of inputs + curr. state. *has binary patterns for states*
 - 3) Write down transition table & flowtable; *has symbolic names for states*
Identify stable states *like state table*

Stability: Given an input, a circuit is stable when $Y_i = y_i \forall i$.

Eg.,

$$Y_1 = y_1 x + y_2 \bar{x}$$

$$Y_2 = \bar{x} y_2 + x \bar{y}_1$$

$$Z = \bar{y}_1 \bar{y}_2$$

Transition Table.

curr. state $y_2 y_1$	next state, output $y_2 y_1, Z$	
	$x=0$	$x=1$
0 0	0 0, 0	1 0, 0
0 1	0 0, 0	0 1, 0
1 0	1 1, 1	1 0, 1
1 1	1 1, 0	0 1, 0

stable situations

Flow Table

Let $a=00, b=01, c=10, d=11$

curr state	next state, output	
a	a, 0	c, 0
b	a, 0	b, 0
c	d, 1	c, 1
d	d, 0	b, 0

Design: make a circuit given a verbal description.

Defns: Fundamental mode assumption: You only change one input at a time, and only do this from a stable situation.

Primitive flow table: At most one stable state per row.

Steps:

- 1) Derive a state diagram + flow table. (generally, best to assume fundamental mode + try to get a primitive flow table)
- 2) Try to reduce the flowtable to get fewer states (impl. charts + merger diagrams).
- 3) Do state assignment (*** avoid critical races)
- 4) Derive next state: output equations (*** avoid hazards + glitches)
- 5) Draw circuit.

Example: Design a circuit with inputs D & G and output Q.
Q = D when G = 1, otherwise Q should not change.

Think of
states as
the measured
values DG/Q

"hold 0"

10/0

"hold 1"

10/1

"hold 0"

00/0

"hold 1"

00/1

"follow 0"

01/0

~~01/1~~

"follow 1"

11/1

~~11/0~~