GAN - Theory and Applications

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Generative Adversarial Networks

"Adversarial Training (also called GAN for Generative Adversarial Networks) is the most interesting idea in the last 10 years of ML."

— Yann LeCun

Generative Adversarial Networks

Two components, the **generator** and the **discriminator**:

- The **generator** G, aim is to capture the data distribution.
- The **discriminator** D, estimates the probability that a sample came from the training data rather than from G.

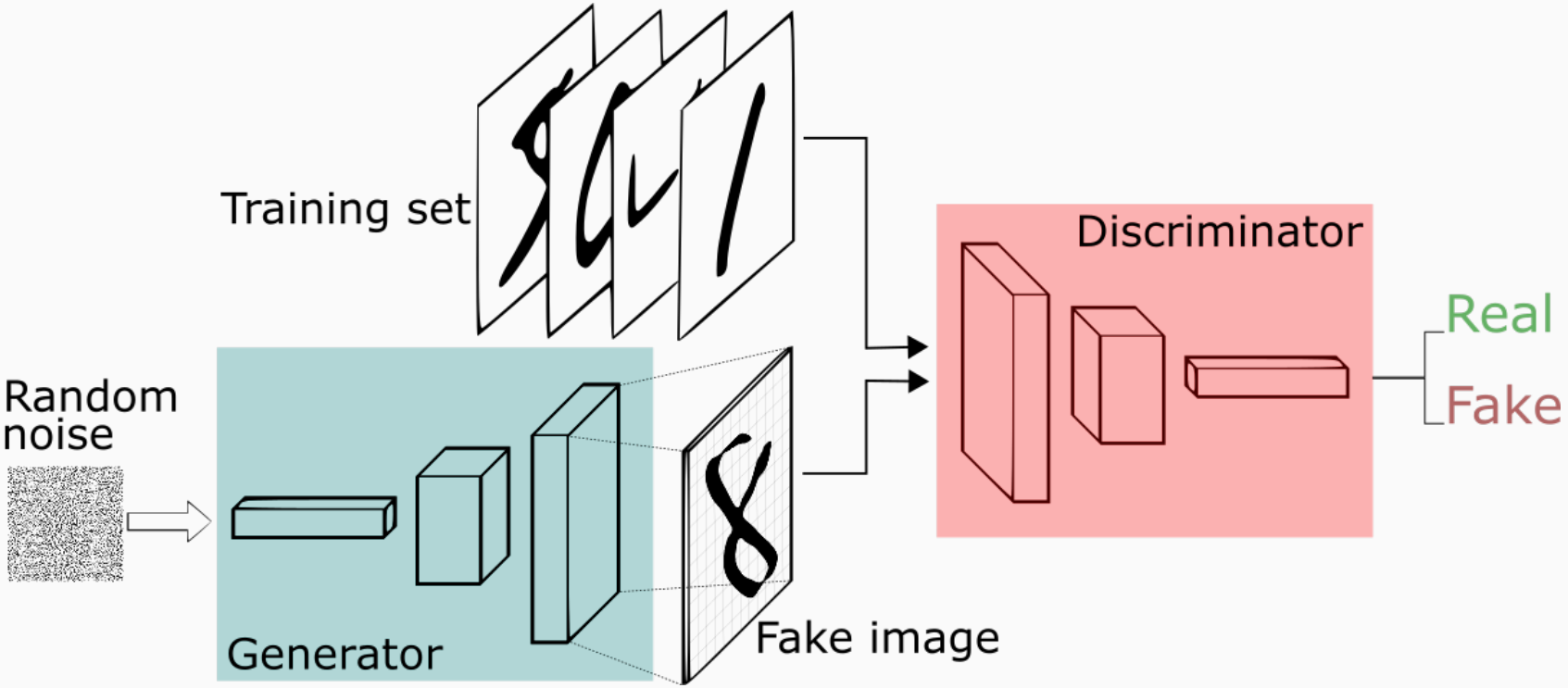

Figure 1: Credits: Reference

Generative Adversarial Networks

GANs game:

$$\min_G \max_D V_{GAN}(D, G) = \mathop{\mathbb{E}}_{x \sim p_{data}(x)}[\log D(x)] + \mathop{\mathbb{E}}_{z \sim p_z(z)}[\log(1 - D(G(z)))] \tag{1}$$

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GANs - Discriminator

Intuitive explanation:

- **Discriminator** needs to:
  - Correctly classify real data:

$$\max_D \mathop{\mathbb{E}}_{x \sim p_{data}(x)} [\log D(x)]. \tag{2}$$

  - Correctly classify wrong data:

$$\max_D \mathop{\mathbb{E}}_{z \sim p_z(z)} [\log(1 - D(G(z)))]. \tag{3}$$

- The discriminator is an **adaptive loss function** that gets discarded once the generator has been trained.

GANs - Generator

Intuitive explanation:

- **Generator** needs to **fool** the discriminator:
  - Generate samples similar to the real one:

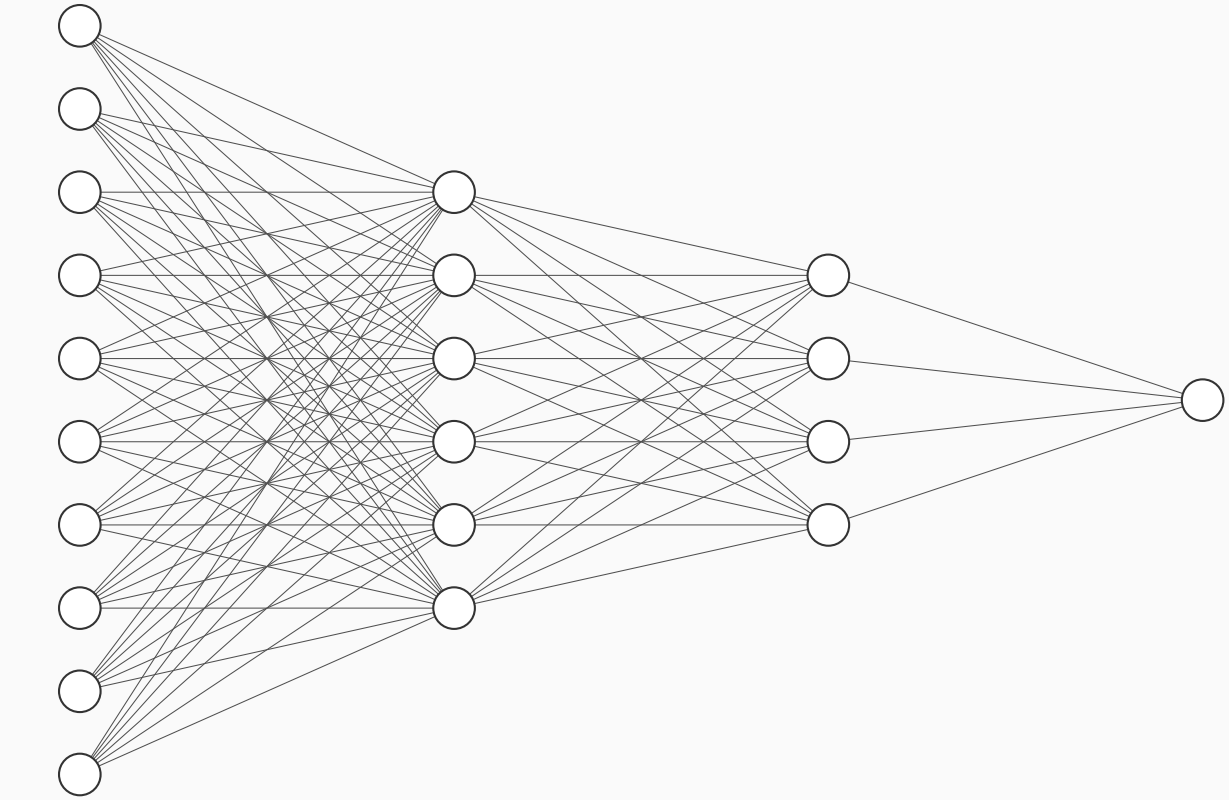
$$\min_G \mathop{\mathbb{E}}_{z \sim p_z(z)} [\log(1 - D(G(z)))]. \tag{4}$$

  - Saturates easily Goodfellow et al. (2014).
  - Change loss for generator:

$$\max_G \mathop{\mathbb{E}}_{z \sim p_z(z)} [\log(D(G(z)))]. \tag{5}$$

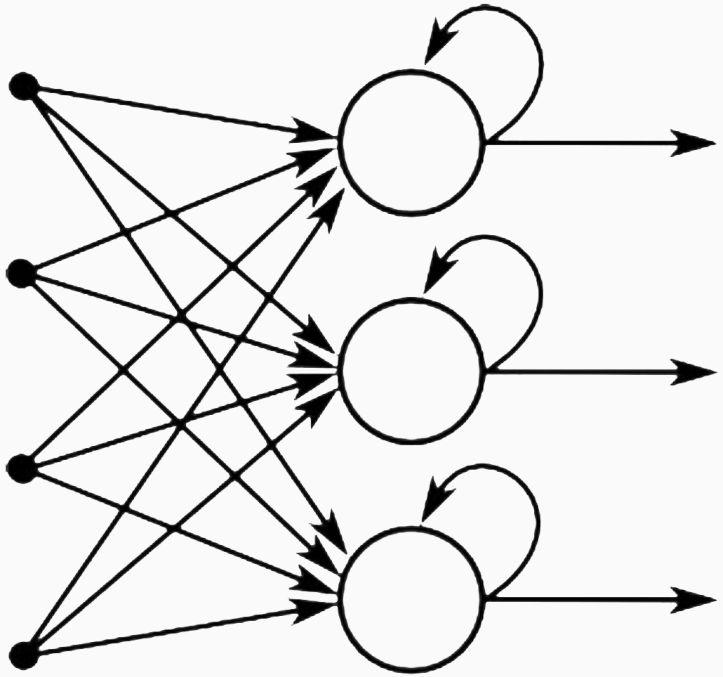
GANs - Models definition

- Both D and G can be parametrized functions (Neural Networks).
- Different architectures for different data types.
  - Tuple of numbers?



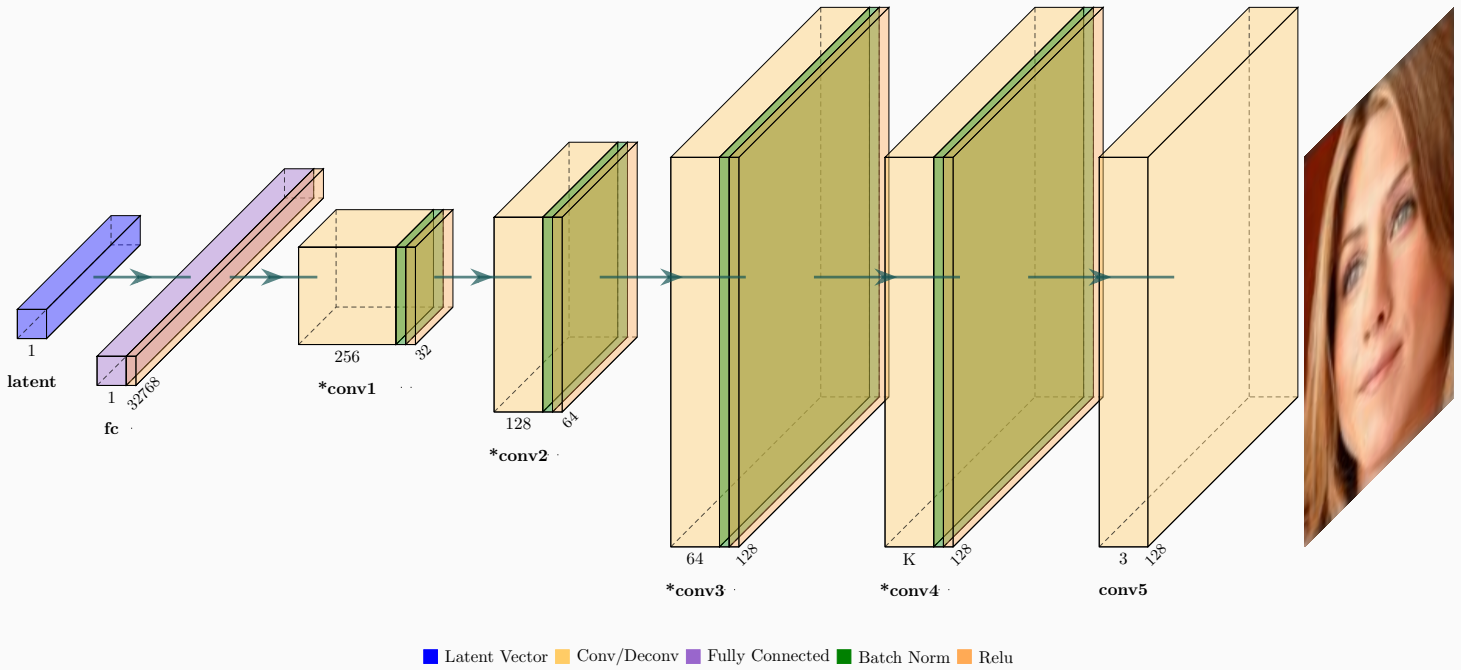
GANs - Models definition

- Both D and G can be parametrized functions (Neural Networks).
- Different architectures for different data types.
    - Text or sequences?



GANs - Models definition

- Both D and G can be parametrized functions (Neural Networks).
- Different architectures for different data types.
  - Images?



GAN Training

GANs - Training

- Discriminator and generator are **competing** against each other.
- **Alternating** execution of training steps.
- Use **minibatch stochastic gradient descent/ascent**.

GANs - Training - Discriminator

How to **train** the **discriminator**?

Repeat from 1 to **k**:

1. Sample minibatch of m noise samples $z^{(1)}, \ldots, z^{(m)}$ from noise prior $p_g(z)$
2. Sample minibatch of m examples $x^{(1)}, \ldots, x^{(m)}$ from data generating distribution $p_{data}(x)$
3. Train the **discriminator** by stochastic gradient **ascent**:

$$\Delta_{\theta_d} \frac{1}{m} \sum_{i=1}^{m} \log D(x^{(i)}) + \log(1 - D(G(z^{(i)}))$$

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GANs - Training - Generator

How to **train** the **generator**?
The update is executed **only once** and only after the turn of the discriminator is completed:

1. Sample minibatch of m noise samples $z^{(1)}, \ldots, z^{(m)}$ from noise prior $p_g(z)$
2. Train the **generator** by stochastic gradient **ascent**:

$$\Delta_{\theta_g} \frac{1}{m} \sum_{i=1}^{m} \log(D(G(z^{(i)})))$$

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GANs - Training - Generator

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1. Sample minibatch of m noise samples $z^{(1)}, \ldots, z^{(m)}$ from noise prior $p_g(z)$
2. Train the **generator** by stochastic gradient **ascent**:

$$\Delta_{\theta_g} \underbrace{\frac{1}{m} \sum_{i=1}^{m} \underbrace{\log(D(G(z^{(i)})))}_{\text{Generator loss}}}_{\text{Loss estimation using m samples}}$$

GANs - Training - Considerations

- Optimizers: Adam, Momentum, RMSProp.
- Training phase can last for an **arbitrary number** of steps or epochs.
- Training is completed when the discriminator is **completely fooled** by the generator.
- Goal: reach a **Nash Equilibrium** where the best D can do is random guessing.

Type of GANs

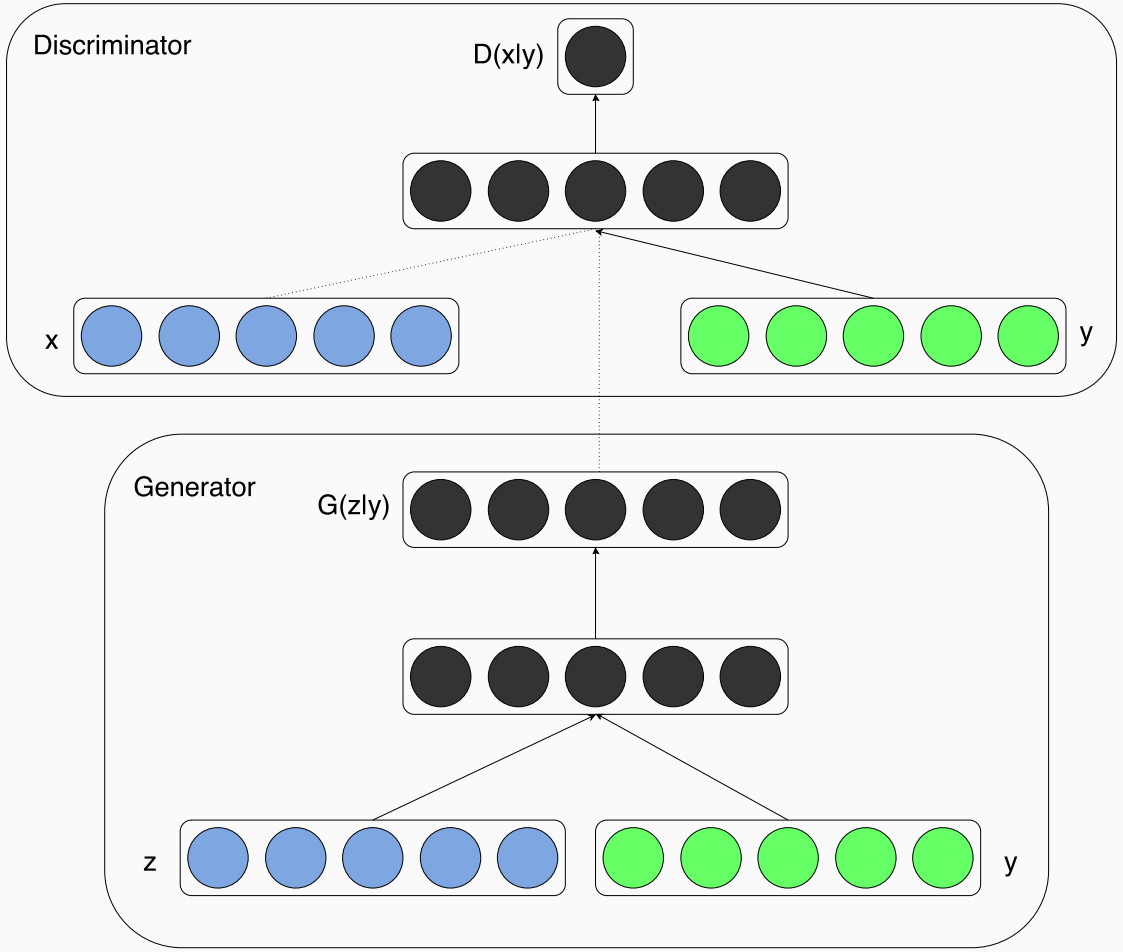
Types of GANs

Two big families:

- **Unconditional** GANs (just described).
- **Conditional** GANs (Mirza and Osindero, 2014).

Conditional GANs

- **Both** G and D are **conditioned** on some extra information y.
- In **practice**: perform conditioning by feeding y into the discriminator and generator.



Conditional GANs

The GANs game becomes:

$$\min_G \max_D \mathop{\mathbb{E}}_{x \sim p_{data}(x|y)} [\log D(x, y)] + \mathop{\mathbb{E}}_{z \sim p_z(z)} [\log(1 - D(G(z|y), y))]$$

Notice: the same representation of the condition has to be presented to both network.

GANs Applications

GANs Applications

GANs can be applied to lot of different tasks:

- Face generation

Figure 2: From Karras et al.

GANs Applications

GANs can be applied to lot of different tasks:

- Domain Translation

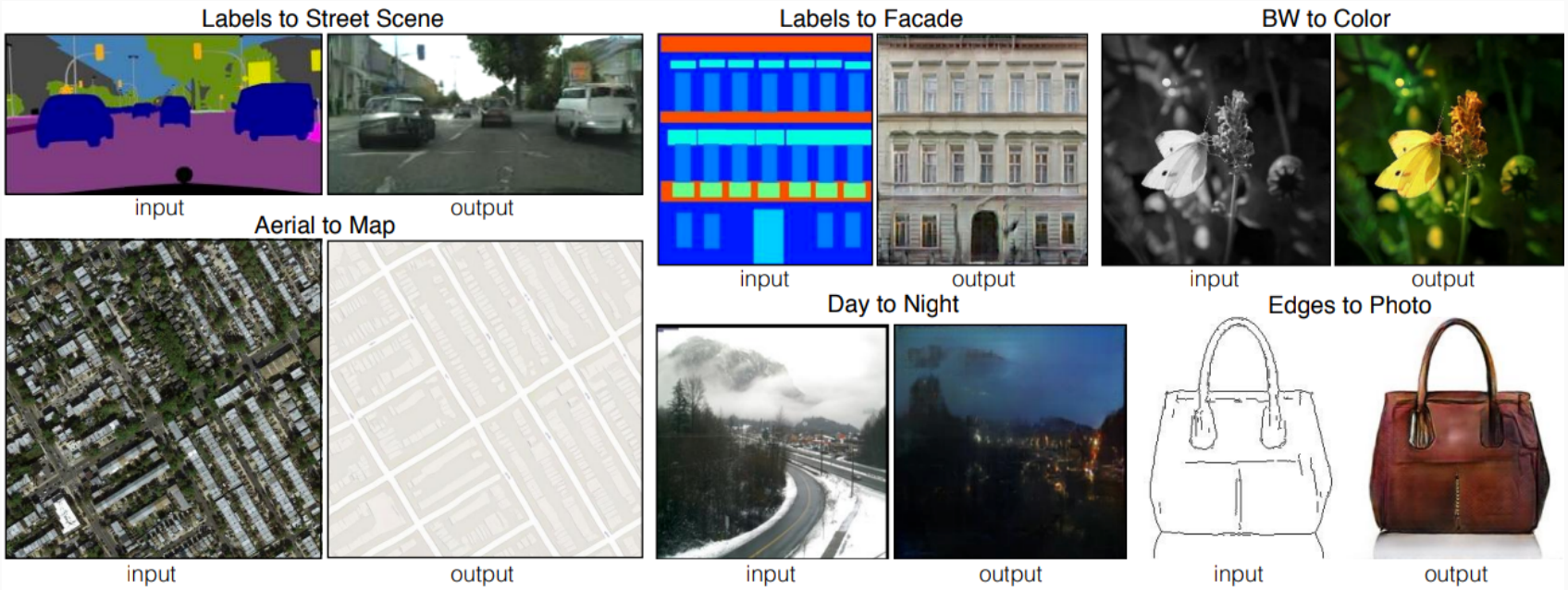


Figure 2: From Isola et al.

GANs Applications

GANs can be applied to lot of different tasks:

- Super resolution applications

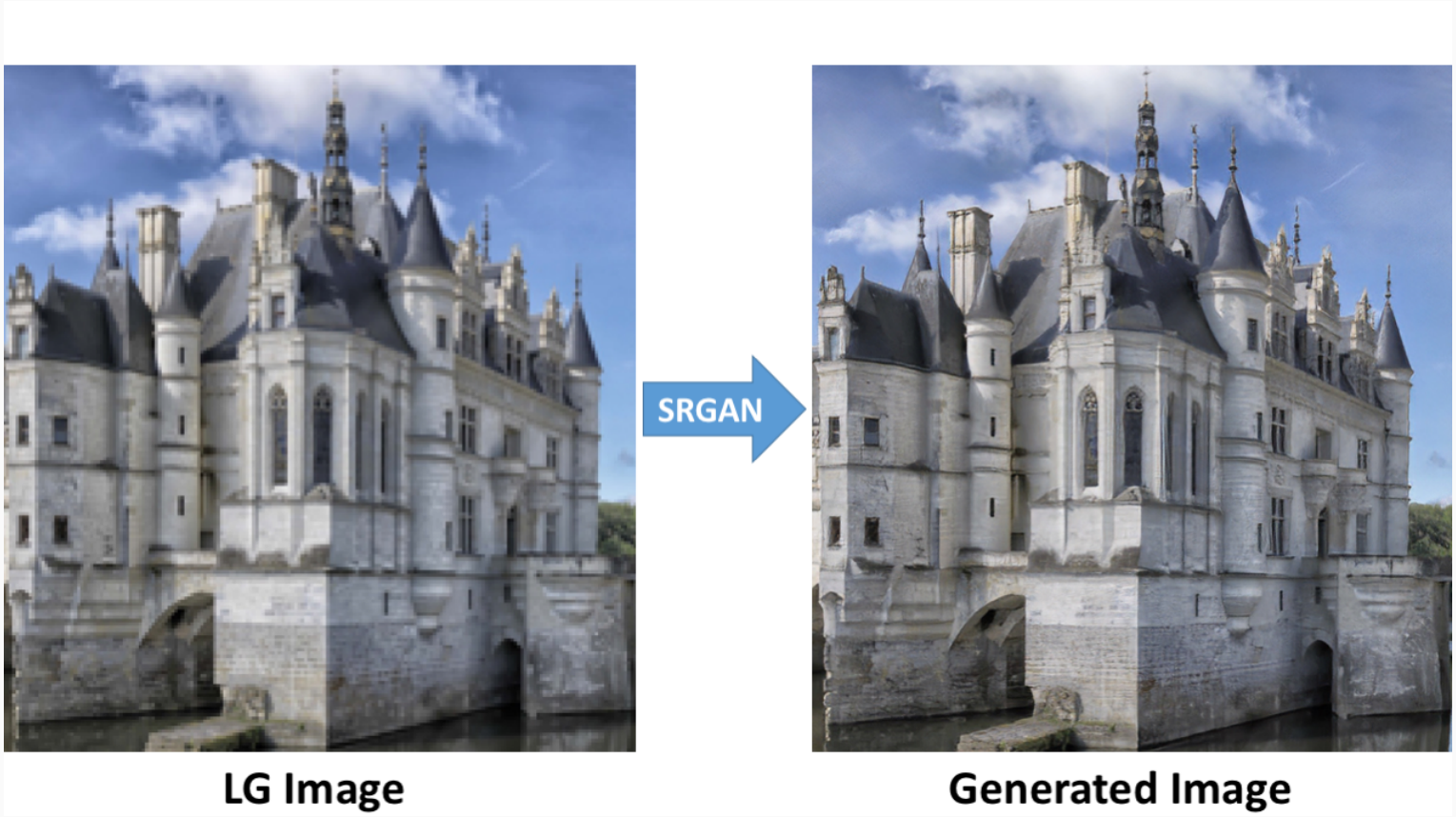


Figure 2: From Ledig et al.

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