## MATH 320: CLASS NOTES

## 1. Roots - Chapter 5

Let's solve the equation f(x) = 0.

## 1.1. Bracketing Methods.

**Definition 1.1.** Bracketing methods are any root-finding algorithms that start with an interval containing a root.

**Algorithm 1.2** (Incremental search). *INPUT: function* f, search interval [l, r].

- (1) Divide the interval into N sub-intervals, with points  $l = x_0 < ... < x_N = r$  evenly spaced in the interval.
- (2) Compute  $f(x_i)$  for all i.
- (3) List all i for which  $sign(f(x_i)) \neq sign(f(x_{i+1}))$ .

OUTPUT: List of brackets  $\{(x_i, x_{i+1})\}$  flagged in step 3.

Question 1.3 (Accuracy). Does this algorithm catch all the roots? What roots will this algorithm miss? Will we ever catch extra roots?

It misses roots when N is not large enough.

It does not catch roots whose neighborhood all has one sign.

If a bracket is flagged, there will be a root in it. Why?

**Theorem 1.4** (Intermediate Value Theorem). If f is a continuous function on  $[a,b] \subset \mathbb{R}$ , f(a) < 0, and f(b) > 0; then there exists a point  $c \in [a,b]$  such that f(c) = 0.

Question 1.5 (Complexity). How long does the algorithm take?

It evaluates the function N+1 times, and checks the sign on each value. The complexity is O(N).

**Question 1.6** (Error). How close to the true roots will the roots found by our algorithm be?

Take the approximation of a given root to be in the middle of the flagged bracket. Our error is then bounded by (l-r)/2N.

The bisection method is an iterative form of the incremental search.

**Algorithm 1.7** (Bisection Method). *INPUT: function* f, search interval [l, r] such that  $sign(f(l)) \neq sign(f(r))$ , desired precision  $\epsilon$ .

- (1) If  $l-r < 2\epsilon$ , stop.
- (2) Divide the interval into 2 equal sub-intervals: l < m < r.
- (3) Compute f(m).
- (4) If sign(f(m)) = sign(f(l)), repeat with interval [m, r]; else, repeat with interval [l, m].

  OUTPUT: Final bracket endpoints.

Accuracy: Catches exactly one root.

**Complexity:** Will stop when  $l-r < 2\epsilon$  since l-r shrinks by half every time, the length of the interval at iteration N is  $(1/2)^N(l-r)$ .

$$(1/2)^N(l-r) < 2\epsilon \iff N > \log_2((l-r)/2\epsilon)$$

**Error:** By design the error is at most  $\epsilon$ .

Question 1.8 (Accuracy). Does this algorithm catch all the roots? What roots will this algorithm miss? Will we ever catch extra roots?

It misses roots when N is not large enough.

It does not catch roots whose neighborhood all has one sign.

If a bracket is flagged, there will be a root in it. Why?

**Theorem 1.9** (Intermediate Value Theorem). If f is a continuous function on  $[a,b] \subset \mathbb{R}$ , f(a) < 0, and f(b) > 0; then there exists a point  $c \in [a,b]$  such that f(c) = 0.

Question 1.10 (Complexity). How long does the algorithm take?

It evaluates the function N+1 times, and checks the sign on each value. The complexity is O(N).

Question 1.11 (Error). How close to the true roots will the roots found by our algorithm be?

Take the approximation of a given root to be in the middle of the flagged bracket. Our error is then bounded by (l-r)/2N.