1. First, I generated a vector of the temperatures in Fahrenheit from 32 to 93.2 in increments of 3.6. Then, I applied the scalar conversion of Fahrenheit to Celsius to that vector since Matlab does that for each element of the vector. I then generated a new vector for the densities for each temperature by passing in each element of the Celsius temperatures to the density formula by using arrayfun. Finally, I plotted it versus the Celsius temperatures.

```
% Vector of temperatures in fahrenheit
tempFahrenheit = 32:3.6:93.2;

% Vector of temperatures in celsius
tempCelsius = 5/9*(tempFahrenheit - 32);

% Densities for each temperature in celsius
densities = arrayfun(@(x) 5.5289*10^(-8)*x^3 ...
    - 8.5016*10^(-6)*x^2 ...
    + 6.5622*10^(-5)*x ...
+ 0.99987, tempCelsius);

% Plot of density versus temperature in celsius
plot(tempCelsius, densities)
title('Density of freshwater for temperature(C)')
```

2. First, I generated a vector of the potential values of x from 0 to  $3\pi/2$ . I arbitrarily made x increment by  $\pi/100$  since it was probably sufficiently accurate. I then generated a vector of the approximations of cosine by using the Maclaurin series expansion by passing each element of the vector of x to the series by using arrayfun. Finally, I plotted x versus y with a dashed black line.

3. In the function that I used to convert (x, y) to  $(r, \theta)$ , I calculated r right away since it would be the same regardless of what x and y were. Then, in the first branch of an if statement, I checked to see if x  $\downarrow$  0 since  $\theta$  was calculated the same way. Then, in the next branch, I checked if x  $\downarrow$  0. From there, I checked further if y  $\downarrow$  0, y  $\downarrow$  0, or y ==

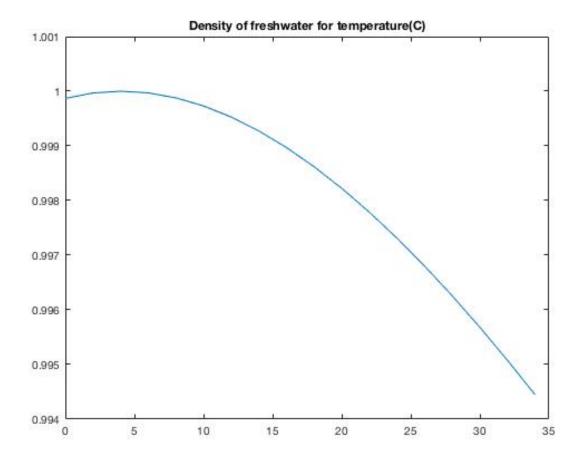


Figure 1: Problem 1

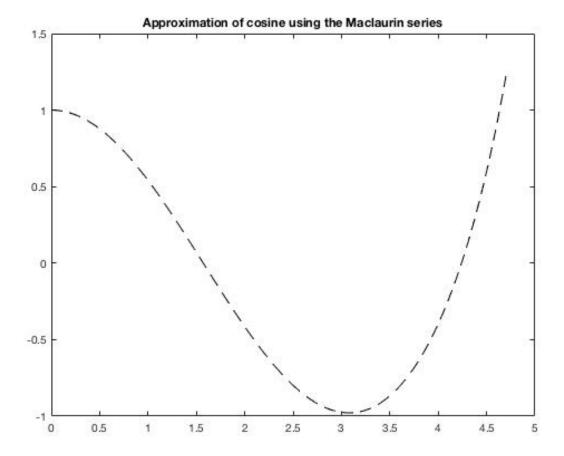


Figure 2: Problem 2

0, and I calculated  $\theta$  accordingly. I checked for y in the same way in the last branch of the if statement where x == 0.

```
function [r, theta] = calcPolar(x, y)
 r = sqrt(x^2 + y^2);
  if (x > 0)
    rad_{theta} = atan(y/x);
 elseif (x < 0)
     if (y > 0)
         rad_theta = atan(y/x) + pi;
     elseif (y < 0)
         rad_theta = atan(y/x) - pi;
     else
         rad_theta = pi;
     end
 else
     if (y > 0)
         rad_theta = pi/2;
     elseif (y < 0)
         rad_theta = -pi/2;
     else
         rad_theta = 0;
     end
  end
  theta = radtodeg(rad_theta);
end
```

4. In the funtion that I used to find the cross product between a and b, I first plotted both a and b with a helper function, which also set them both at the origin, which I did by appending a row of zeroes to the top of the matrix representing each vector. This let me also plot vector c easily later on. I calculated c by using the built-in cross function, I calculated the magnitude with the norm function, and I calculated the angle between a and b with atan2d. The plot for  $a = [-1 \ 0 \ 0]$  and  $b = [0 \ -1 \ 0]$  is shown below.

```
function [theta, c, magC] = crossProd(a, b)
hold on
view(3);
displayVector(a, '--');
displayVector(b, '--');
c = cross(a, b);
displayVector(c, '-');
magC = norm(c);
theta = atan2d(magC, dot(a, b));
end

function displayVector(vector, option)
origin = [0 0 0];
```

```
originVector = [origin;vector];
plot3(originVector(:,1)...
    , originVector(:,2)...
    , originVector(:,3), option);
end
```

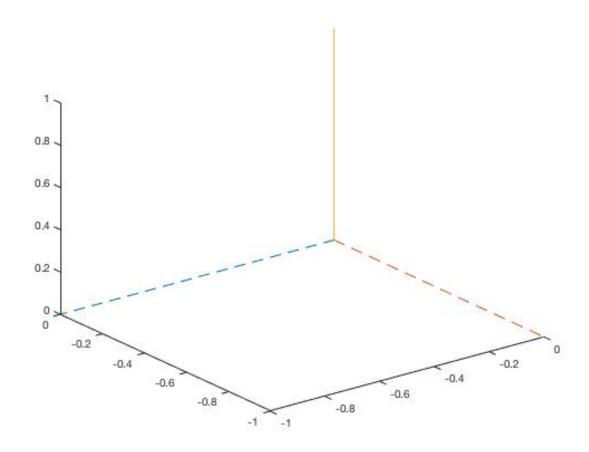


Figure 3: Problem 4