Assignment 2

Introduction to Classes: Ray-Sphere Intersection Check

Introduction: In Computer Graphics, 'Ray Tracing' is a popular method of displaying objects with their reflective and refractive properties. The following picture has been created by ray tracing technique by continuously checking imaginary ray-sphere intersections in 3D space.

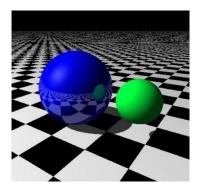


Figure 1: Objects displayed by ray tracing.

In this assignment, you will perform a simple check, whether a ray intersects a sphere. You need to implement three classes: **Point3D**, **Sphere**, and **Ray**.

Assignment Specification:

Point3D Class:

1) Constructors for the Point3D class:

A point can be defined in 3D space by its x, y, and z components. The following expression defines a Point3D object **P** with its three member variables, x, y, and z. x, y, and z are of type **double**.

Point3D P{x, y, z};(i)

You need to implement the default constructor and constructor with parameters for Point3D class. Use C++11 uniform initialization. Take a look at the uploaded example on **Point2D**.

2) Setters and getters:

Add setters and getters to set the values of member variables and access them respectively. This has been discussed in Week 1 lectures while object chaining.

3) Add two Point3Ds:

Write a public method that will add a Point3D to an existing point ('this' Point3D) and then returns the reference to it ('this' Point3D). The function declaration will look like the following:

Point3D &addPoints(const Point3D & P);(ii)

4)	Subtract one Point3D from another Point3D:
	Write a public method that will subtract a Point3D from an existing point ('this' Point3D) and then returns the reference to it ('this' Point3D). The function declaration will look like the following:
	Point3D &subtractPoints(const Point3D & P); (iii)
5)	Multiply two Point3Ds: Write a public method that multiplies \mathbf{x} , \mathbf{y} , and \mathbf{z} member variables of a Point3D \mathbf{P} with the existing Point3D's (this) \mathbf{x} , \mathbf{y} , and \mathbf{z} member variables respectively. Next, add the values and return the sum.
	double multiplyPoints(const Point3D& P)(iv)
6)	Square of a Point3D : This method will multiply x , y , and z member variables of this point with itself and return the sum.
	double squarePoints() (v)
Sp	here Class:
7)	Constructors for the Sphere class: A sphere can be defined by its center and radius. The center of a Sphere is a Point3D object; the radius is of type double. The Sphere class will include Point3D class. The following expression defines a Sphere object $\bf S$ with its center ' $\bf C$ ' and radius ' $\bf R$ '.
	Sphere S{Point3D C, double R};(vi)
	You need to implement the default constructor and constructor with parameters for Sphere class. Use C++11 uniform initialization.
8)	Setters and getters : Add setters and getters to set the values of member variables and access them respectively.
Ra	y Class:
9)	Constructors for the Ray class:
vai	ray's origin is a Point3D object. A ray has its direction in the 3D space. Hence, both member riables of a ray can be defined as Point3D objects. A Ray object 'ray' with its origin 'o' and ection 'd' has been defined below:

Ray ray{Point3D o, Point3D d };.....(vii)

You need to implement the default constructor and constructor with parameters for Ray class. Use C++11 uniform initialization.

- 10) **Setters and getters**: Add setters and getters to set the values of member variables and access them respectively.
- 11) **Friend class**: Declare Ray class as the friend of Sphere class.
- 12) **Check intersection with a sphere**: Write a member function for the Ray class that checks intersection with a sphere as follows:

where, for a ray with origin \mathbf{o} and direction \mathbf{d} , a sphere with radius \mathbf{r} and center \mathbf{c} , A, B, and C can be calculated as follows:

 $\mathbf{A} = |\mathbf{d}^2|$, which can be calculated by **squarePoints()** when called by the direction member variable (i.e., d) of the ray.

 $\mathbf{B} = (\mathbf{o} - \mathbf{c}) \cdot \mathbf{d}$, which can be calculated as follows:

- Step 1: Use **subtractPoints(Point3D &)** to subtract the center **c** from the origin **o**. This will return an updated **Point3D**;
- Step 2: Use **multiplyPoints**(**const Point3D &**) to multiply the updated Point3D from Step 1 with the direction member variable **d** of the ray.

and $C = |\mathbf{o} \cdot \mathbf{c}|^2 - \mathbf{r}^2$, which can be calculated as follows:

- Step 1: Use subtractPoints(const Point3D&) to subtract **c** from **o**; this returns an updated Point3D;
- Step 2: the updated Point3D from the Step 1 will call **squarePoints**(); this returns a double;
- Step 3: Next, subtract the square of radius **r** from Step 2 to get the value of **C**.

Now, you can calculate the value of B^2 – AC. If this value is less than zero, the program will print the following:

"Ray does not touch or intersect the sphere."

Otherwise, it will print:

"Ray either touches or intersects the sphere."

Use the attached **intersection_tester.cpp** file for testing purposes. You do not need to check invalid input in this assignment. Use the following cases for testing purpose:

Case 1:

Ray origin: (0, 2, 5)

Ray direction (1, 0, -2)

Sphere center (2, 4, 1)

Sphere radius 8

$$B*B - A*C = 300$$

The program will print: "Ray either touches or intersects the sphere."

Case 2:

Ray origin: (0, 2, 5)

Ray direction: (1, 0, -2)

Sphere center: (10, -2, -5)

Sphere radius: 10

B*B - A*C = 320

The program will print: "Ray either touches or intersects the sphere."

Below is a screenshot generated by the attached test file **intersection_tester.cpp**.

```
Constructing a sphere.
Enter the radius:

Now the center.
Enter the x coordinate of the sphere's center:

Enter the sphere's y:

Enter the sphere's z:

Constructing a ray.
First the origin.
Enter the x coordinate of the ray's origin:

Enter the ray's y:

Enter the ray's z:

Now the ray's direction.
Enter the x coordinate of the ray's direction:

Enter the direction's y:

Enter the direction's z:

Enter the direction's z:

Ray either touches or intersects the sphere.
```

Submission:

Compile and execute your program with g++ or Microsoft compiler.

Place your solution in a zipped file named with your last name followed by the first initial of your first name followed by 2 (ex: YasminS2.zip) and submit the solution via canvas.

Include at the top of your solution (in comments) your name, what compiler(s) you used.

Thus, your zip will contain the following:

• Point3D.h, Point3D.cpp, Sphere.h, Sphere.cpp, Ray.h, and Ray.cpp

Submission deadline is Tuesday, April 15, 11:59 pm.

This assignment weighs 10% of the course.