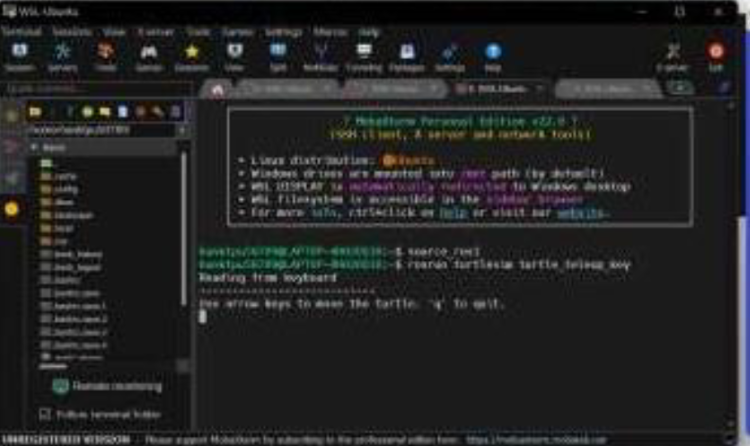
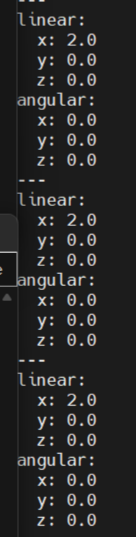
ROS1







Ros2



