

# Reading Notes for

## *Elementary Topology: Problem Textbook*

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**Definition** (arithmetic progression). An **arithmetic progression** or arithmetic sequence is a sequence of numbers such that the difference between the consecutive terms is constant:

$$a_1, a_1 + d, a_1 + 2d, \dots$$

**Definition** (point). Elements in  $X$  given a topology  $(X, \Omega)$  are called **points**.

**Definition** (particular point topology). Given a discrete topology

$$(X, \mathcal{P}(X)),$$

and a singleton  $\{a\}$  disjoint with  $X$ , a **particular point topology** or **topology of everywhere dense point** is

$$(X \cup \{a\}, \{\{a\} \cup U \mid U \in \mathcal{P}(X)\} \cup \{\emptyset\}).$$

*Remark.* Let  $(Y, \Omega)$  be a particular point topology, then

$$S \in \Omega \iff S = \emptyset \vee a \in S,$$

i.e.,  $a$  belongs to any nonempty open set.

**Definition** (Sierpiński space). A particular point topology with two points is called a **Sierpiński space** or topology of connected pair of points. Explicitly, it is

$$(\{a, b\}, \{\emptyset, \{a\}, \{a, b\}\}),$$

where  $a \neq b$  and  $a$  being the element in all nonempty open sets.

**Definition** (Cantor set). Let  $K$  be the set of real numbers that are sums of series of the form

$$\sum_{k=1}^{\infty} a_k 3^{-k},$$

with  $a_k \in \{0, 2\}$ . In other words,  $K$  is the set of real numbers that are presented as  $0.a_1a_2\dots a_k\dots$  without the digit 1 in the positional system with base 3.  $K$  is called the **Cantor set**.

*Remark.* Then any real number of form  $x3^{-j} \in [0, 1]$  ( $x \in \mathbb{N}, j \in \mathbb{N}$ ) must be in  $K$ . But  $K$  contains irrational numbers as well.

$$K \cap \mathbb{Q} = \left\{ \sum_{p \in P} \frac{2 \cdot 3^p}{3^i} + \sum_{q \in Q} \frac{2 \cdot 3^q}{3^j - 3^i} \mid 0 \leq p < i \leq i + q < j, \right\}.$$

**Definition** (family). A **family** of a set  $S$  is a subset of  $\mathcal{P}(S)$ .

Equivalently, a collection  $F$  of subsets of a given set  $S$  is called a family of subsets of  $S$ , or a family of sets over  $S$ .

**Definition** (base). A **base** or basis for the topology  $\Omega$  of a topological space  $(X, \Omega)$  is a family  $B$  of open subsets of  $X$  such that every open set of the topology is equal to a union of some sub-family of  $B$ .

Equivalently,  $B$  is a base of topology  $(X, \Omega)$  if

$$S \in \Omega \iff \exists B' [B' \subseteq B \wedge S = \cup B'].$$

*Remark.* Topologies on a set  $X$  with only one base are exactly  $\mathcal{S} \in \mathcal{P}(\mathcal{P}(X))$  such that

$$\{\emptyset, X\} \subseteq \mathcal{S} \wedge \forall \mathcal{T} \subseteq \mathcal{S} [\mathcal{T} \neq \emptyset \implies \exists M \in \mathcal{T} \forall T \in \mathcal{T} (T \subseteq M)],$$

i.e., a topology whose nonempty subset  $\mathcal{T} \subseteq \mathcal{S} \subseteq \mathcal{P}(X)$  must have an element containing all other elements in  $\mathcal{T}$ .

Example:  $\mathbb{R}$  whose open sets are intervals  $(-1/n, 1/n)$  for  $n \in \mathbb{Z}^+$ ,  $\emptyset$ , and  $\mathbb{R}$ .

Example2: For any finite sequence  $\emptyset \subseteq X_1 \subseteq X_2 \subseteq \dots \subseteq X_n \subseteq X$ , the topology on  $X$  consisting of those sets provides another example.

**Definition** (subbase). Let  $(X, T)$  be a topological space. A **subbase** of  $T$  is usually defined as a  $B \subseteq T$  satisfying one of the two following equivalent conditions:

- $T$  is the smallest topology containing  $B$ : any topology  $T'$  on  $X$  containing  $B$  must also contain  $T$ .
- All finite intersections of elements of  $B$ , together with the set  $X$ , forms a basis for  $T$ , i.e.,

$$\Sigma = \left\{ \bigcap_{i=1}^n B_i \mid n \in \mathbb{Z}^+, B_i \in B \right\} \cup \{X\}$$

is a base of  $T$ .

For any  $S \subseteq \mathcal{P}(X)$ , there is a **unique** topology having  $S$  as a subbase. In particular, the intersection of all topologies on  $X$  containing  $S$  satisfies this condition. **In general, however, there is no unique subbasis for a given topology. ???**

**Definition** (metric space). See book.

*Remark.* Consider a metric space

$$(X = \{x, y, z\}, \rho: X \times X \rightarrow \mathbb{R}_0^+),$$

where

$$\rho(x, y) = \rho(x, z) = 4, \rho(y, z) = 7.$$

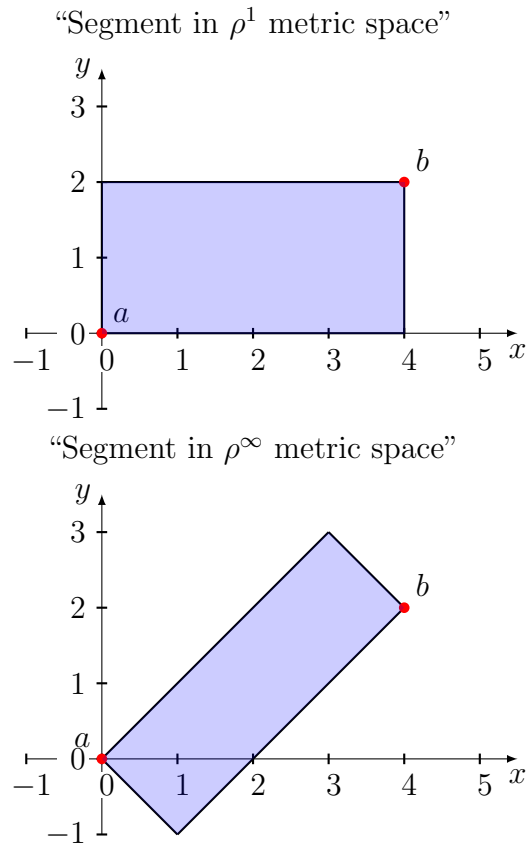
Then

$$\{x, y\} = B_6(y) \subsetneq B_5(x) = \{x, y, z\}.$$

*Remark.* Given  $a, b \in \mathbb{R}^2$ , the set

$$\{x \in \mathbb{R}^2 \mid \rho(a, x) + \rho(x, b) = \rho(a, b)\}$$

is the line segment if  $\rho$  is the Euclidean metric.



**Definition** (dense). Let  $A$  and  $B$  be two sets in a topological space  $X$ .  $A$  is **dense** in  $B$  if  $B$  is a subset of the closure of  $A$ .  $A$  is **everywhere dense** if the closure of  $A$  is  $X$ . A set is **nowhere dense** if its exterior is everywhere dense.

**Theorem.** *A set is everywhere dense iff it intersects any nonempty open set.*

**Theorem.** *A set is nowhere dense iff its closure has empty interior.*

**Definition** (limit point). A point  $b$  is a **limit point** of a set  $A$ , if each neighborhood of  $b$  intersects  $A \setminus \{b\}$ .

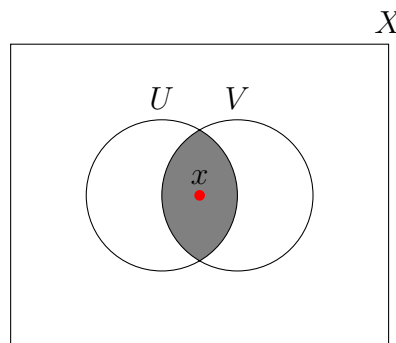
**Theorem.** *Every limit point of a set is its adherent point. The reverse is not true.*

**Theorem.** *A set is closed iff it contains all of its limit points.*

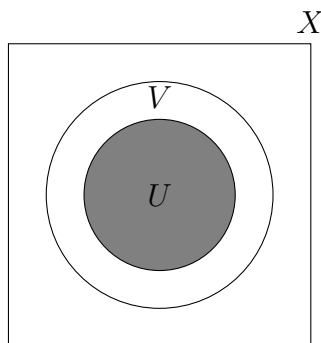
**Definition** (isolated point). A point  $b$  is an **isolated point** of a set  $A$  if  $b \in A$  and  $b$  has a neighborhood disjoint with  $A \setminus \{b\}$ .

$U$  is open in  $X$  iff

$\forall x \in U \exists V \subseteq X [x \in V \text{ and } V \text{ is open in } X \text{ and } U \cap V \text{ is open in } V].$



Therefore we can say  $U$  is locally open: a set  $U$  is open iff it is open in a neighborhood  $V$  of each of its points.



But a locally closed set is not closed.

**Definition** (locally closed set). Given a topology  $(X, \Omega)$ , below are equivalent statements

- $A$  is **locally closed** in  $X$ ;
- $A$  is an open subset of its closure;
- $A$  is the intersection of open and closed subsets of  $X$ ;
- $A$  is closed in the subspace  $(U, \Omega_U)$ , where  $U$  is an open set containing  $A$ , i.e.,  $U \in \Omega \wedge A \subseteq U$ .

**Definition** (smallest neighborhood space). A space satisfying one of the below conditions is a **smallest neighborhood space**.

The following statements are equivalent

- each point has a smallest neighborhood,
- the intersection of any collection of open sets is open,
- the union of any collection of closed sets is closed.

**Definition** (Khalimsky line). The poset topology on  $\mathbb{Z}$  with the base

$$\{ \{ 2k - 1, 2k, 2k + 1 \} \mid k \in \mathbb{Z} \}$$

is called the **digital line**, or **Khalimsky line**.

**Theorem.** *In the digital line, each even number is closed and each odd one is open.*

**Definition** (cyclic order). A finite cyclic group naturally defines a **cyclic order**.

The cyclic order topology determined by the cyclic counterclockwise order of  $S^1$  is the topology generated by the metric  $\rho(x, y) = |x - y|$  on  $S^1 \subseteq \mathbb{C}$ .

**Definition** (locally continuous). A map  $f$  from a topological space  $X$  to a topological space  $Y$  is said to be **continuous at a point**  $a \in X$  if for every neighborhood  $V$  of  $f(a)$  there exists a neighborhood  $U$  of  $a$  such that  $f(U) \subseteq V$ .

p60 isometric embedding, isometry and after skipped