

lys_instr: A Python Package for Automating Scientific Measurements

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DOI: [10.xxxxxx/draft](https://doi.org/10.xxxxxx/draft)

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Submitted: 01 January 1970

Published: unpublished

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Statement of need

Modern scientific research increasingly relies on comprehensive measurements across wide parameter spaces to understand physical phenomena. As experiments grow in complexity—with longer measurement times and a greater diversity of instruments—efficient automation has become essential. Measurement automation is evolving beyond simple parameter scans toward informatics-driven, condition-based optimization, paving the way for AI-assisted experimental workflow management. This progress demands robust software infrastructure capable of high integration and flexible logic control.

However, building such a system remains nontrivial for researchers. At the low level, specific instrument methods tightly coupled to diverse communication protocols (e.g., TCP/IP, VISA, serial, etc.) limit interchangeability and flexibility across systems. At the high level, coordinating workflows involving conditional logic, iterative processes, and advanced algorithms from different libraries can lead to redundant implementations of similar functionality across different contexts. Moreover, designing graphical user interfaces (GUIs) for these low- and high-level functionalities typically involves complex multithreading, which requires familiarity with GUI libraries and the underlying operating system (OS) event-handling mechanisms. These challenges impose significant development overhead on researchers, highlighting the need for a control framework that balances architectural flexibility with reduced implementation complexity.

State of the field

Several software frameworks address specific aspects of the issue. Open-source libraries such as QCoDeS ([Nielsen et al., 2025](#)), PyMeasure ([PyMeasure Developers, 2024](#)) and PyOpticon ([Randall & Majumdar, 2025](#)), as well as commercial platforms such as MATLAB's

40 Instrument Control Toolbox ([The MathWorks, Inc., 2024](#)), provide abstractions for instrument
 41 communication and measurement execution across hardware platforms. However, complex
 42 workflow orchestration and concurrent task management are typically implemented through
 43 user-defined procedural code, requiring explicit architectural organization by users. The
 44 commercial platform LabVIEW ([National Instruments Corporation, 2024](#)) provides robust
 45 built-in concurrency and execution management. Nevertheless, workflow logic is generally
 46 embedded within graphical block diagrams, where experiment control flow, user interface
 47 construction, and device-level implementation often coexist in the same development layer,
 48 potentially limiting modular reuse across experimental configurations.

49 In contrast, lys_instr introduces an explicit workflow layer that abstracts common control
 50 patterns from experiment-specific implementations. By structurally separating instrument
 51 interfaces, workflow coordination, and GUI components within a multi-layered architecture,
 52 it enables reusable workflow definitions, encapsulated concurrency management, and flexible
 53 system assembly, thereby reducing experiment-specific procedural code while preserving
 54 extensibility.

55 Design philosophy

56 lys_instr adopts a three-layer architecture organized by functional separation: Base Layer for
 57 device controller abstraction, Top Layer for workflow coordination, and Connection Layer in
 58 between for complete control-system assembly ([Figure 1](#)). Each layer applies object-oriented
 59 design patterns from GoF ([Gamma et al., 1994](#)), according to its responsibilities, enhancing
 60 flexibility, modularity, and usability. The framework builds on the lys platform, leveraging its
 61 powerful multidimensional data visualization capabilities.

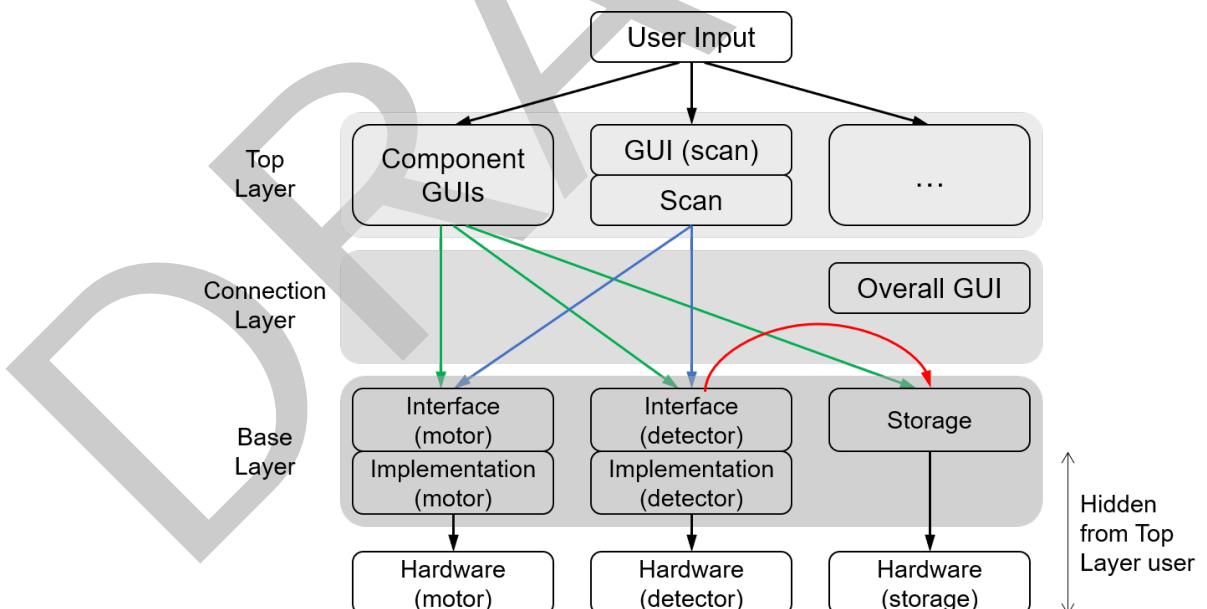


Figure 1: Schematic of the code architecture of lys_instr.

62 1. Base Layer: Device Controller Abstraction

63 This layer defines abstract interfaces that standardize core instrument controllers. The interfaces
 64 encapsulate the concrete implementations, following the *Template Method* design pattern.
 65 Typically, most measurement systems include two types of components: *controllers*, which
 66 adjust experimental parameters such as external fields, temperature, or physical positions,
 67 and *detectors*, which record experimental data, e.g., cameras, spectrometers. Accordingly,

lys_instr provides standardized *controller* and *detector* interfaces that unify instrument behavior, allowing higher layers to operate on different devices uniformly through common interfaces. Users only need to provide device-specific subclasses that inherit from these interfaces to handle communication with their respective hardware devices. Moreover, each interface manages its own thread(s), ensuring responsiveness and asynchronous operation without blocking other controllers or the GUIs in higher layers. This structure enables users to create controller objects that can be readily integrated into higher-level workflows with minimal device-specific coding.

2. Top Layer: Workflow Coordination

This layer implements workflows common across many setups. Most measurements share similar procedural structures, such as a *scan* process in which data are sequentially recorded while parameters like fields, temperature, or positions are varied. These workflows are standardized using the abstract interfaces defined in the Base Layer, independent of any specific hardware devices, following the *Bridge* and *Composite* design patterns. For example, lys_instr provides a standardized *scan* routine that calls *controller* and *detector* interface methods without requiring knowledge of the underlying concrete implementations. This abstraction allows such workflows to be reused across different hardware configurations, greatly improving coding efficiency. In addition, lys_instr includes prebuilt GUI components corresponding to each Base Layer component, enabling direct GUI-based control through the same abstract methods. This design cleanly separates workflow logic from device-specific details, simplifying extension to complex measurement systems. Moreover, the GUI communicates with Base Layer interfaces via event-driven messaging, following the *Observer* design pattern to ensure low coupling and high extensibility. With this layer, users can design measurement workflows from scratch without manually creating GUI components.

3. Connection Layer: Control-System Assembly

This layer enables flexible assembly of components from the Base and Top Layers into a complete control system by managing connections within and across layers. Following the *Mediator* design pattern, it connects abstract Base Layer interfaces (and the corresponding hardware devices) to enable automatic data flow, and links GUI components to their respective interfaces, fully hiding device-specific implementations from this layer and above. It also organizes the GUI components into a cohesive application for user interaction. This design grants users maximum freedom to construct tailored control systems without handling low-level tasks such as inter-device communication or multi-threading. Several prebuilt GUI templates for common scenarios are provided for quick hands-on use.

Overall, lys_instr provides prebuilt support for standard device controllers, common experimental workflows, and GUI components and assemblies, so users generally need to implement only device-specific subclasses to handle communication with their hardware. This enables rapid integration of new instruments into automated measurement workflows with minimal coding and design effort.

Example of Constructed GUI

With lys_instr, users can easily construct a GUI like the one shown in Figure 2. In this example, the lys_instr window is embedded in the lys platform, with Sector A for storage, Sector B for detector, and Sector C for controllers. Multi-dimensional, nested scan sequences can be defined via the visual interface in the Scan tab in Sector C. lys tools in the outer window tabs allow customization of data display, enabling advanced, on-the-fly customization of data visualization.

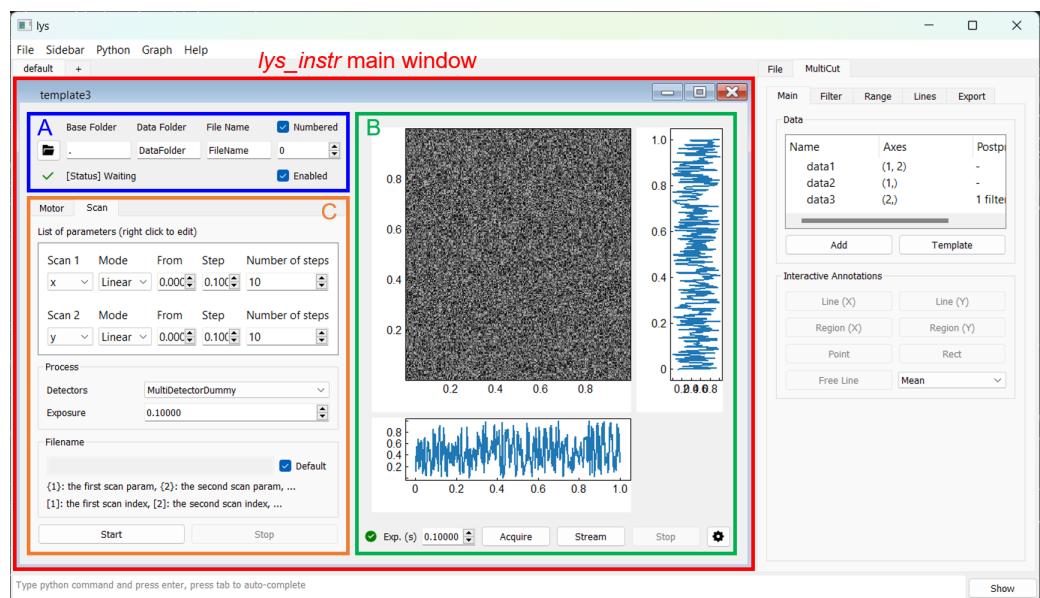


Figure 2: Example GUI of `lys_instr`. The main window, embedded in the `lys` window, contains three sectors: Storage panel (A), Detector panel (B), and controller panel (C). The Scan tab in (C) enables dynamic configuration of multi-dimensional, nested experimental workflows.

114 Research impact statement

115 `lys_instr` has been deployed in complex, real-world scientific experiments, supporting multiple
 116 peer-reviewed publications. It automates ultrafast electron diffraction (UED) and ultrafast
 117 transmission electron microscopy (UTEM) systems, coordinating ultrafast laser excitation and
 118 pulsed electron beam detection in pump–probe experiments (Koga et al., 2024; Nakamura
 119 et al., 2020, 2021, 2022, 2023; Shimojima et al., 2021, 2023a, 2023b). It enables precise
 120 control of electromagnetic lenses and electron deflectors for advanced microscopy involving
 121 electron-beam precession, a capability that would be difficult to achieve without `lys_instr`
 122 (Hayashi et al., 2026; Shiratori et al., 2024).

123 The software has demonstrated seamless control of transmission electron microscopes from
 124 different manufacturers across multiple institutes (RIKEN Center for Emergent Matter Science
 125 and Nagoya University), illustrating its reproducible performance and hardware-independent
 126 workflow management capability. Through integration with sister packages in the `lys` family,
 127 such as `lys_em` (lys_em Developers, 2026) and `lys_fem` (lys_fem Developers, 2026), `lys_instr`
 128 facilitates complex multi-instrument automation in a research-driven ecosystem, allowing
 129 advanced workflows to be deployed efficiently while maintaining modular, extensible design.

130 Acknowledgements

131 We acknowledge valuable comments from Takahiro Shimojima and Kyoko Ishizaka. This
 132 work was partially supported by Grant-in-Aid for Scientific Research (KAKENHI) Grants
 133 No. 21K13889 and No. 25K00057, and JST PRESTO Grant No. JPMJPR24JA.

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