

# Distributed Machine Learning Test Bench with Raspberry Pis

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**Project Repository** 

https://github.com/revan/RPi-distributed-ML

#### Overview

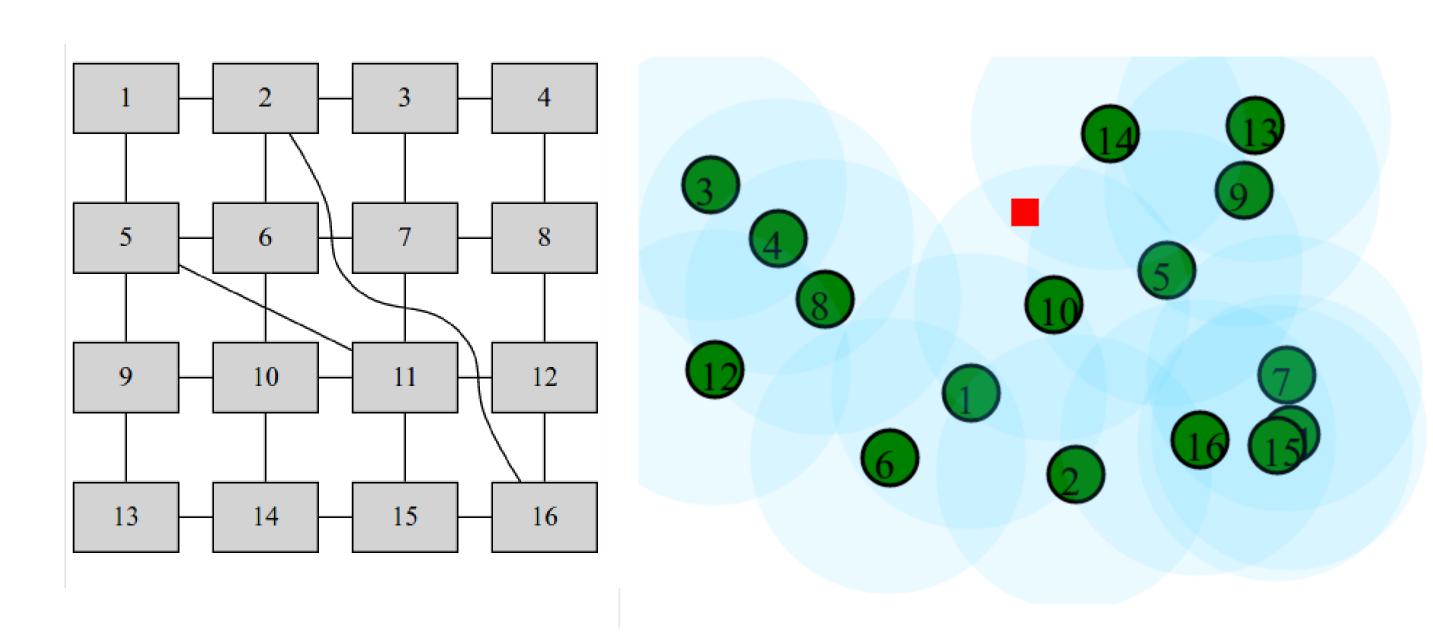
We develop a Python library facilitating the development of distributed machine learning algorithms using embedded devices. As a demonstration of the library's functionality, we present implementations of geo-routing and classifier training.

## **Design Goals**

- ☐ Create a testbed for easy, cost-effective testing of distributed and machine learning applications
- ☐ Abstraction of system-related tasks (e.g. synchronization); allows user to focus on his own application
- ☐ Implemented in Python; includes functionality from libraries such as Numpy, Scikit-learn
- ☐ Use of cheap, commonly available hardware allows for easy setup and prototyping
- ☐ Minimal Infrastructure
  - ☐ Code is deployed to cluster via "git push"
  - ☐ Nodes are addressable by name, not IP
  - ☐ Device Agnostic

## **Configurable Topology**

- ☐ Library loads JSON file to restrict node connectivity
- ☐ Web UI allows generating configurations simulating Ethernet or WiFi



#### **The Averaging Problem**

- ☐ Model: Segment data, take local action, exchange results with neighbors
- ☐ Decentralized computation (e.g. sensor networks)
- ☐ Asynchronous and synchronous
- ☐ Naturally extended to algorithms such as gradient descent and support vector machines

$$\overrightarrow{x_{t+1}} = W^{\alpha} \overrightarrow{x_t}$$

The synchronous update rule, with the x vector as each node's value at time t and  $\alpha$  as the number of iterations.

$$W = \begin{bmatrix} 1 - \frac{d_i}{d_{max}+1} & \frac{1}{d_{max}+1} & \frac{1}{d_{max}+1} \\ \frac{1}{d_{max}+1} & 1 - \frac{d_i}{d_{max}+1} & \frac{1}{d_{max}+1} \\ \frac{1}{d_{max}+1} & \frac{1}{d_{max}+1} & 1 - \frac{d_i}{d_{max}+1} \end{bmatrix}$$

A sample stochastic matrix, with  $d_i$  as node i's degree, and  $d_{max}$  as the maximum degree in the topology.

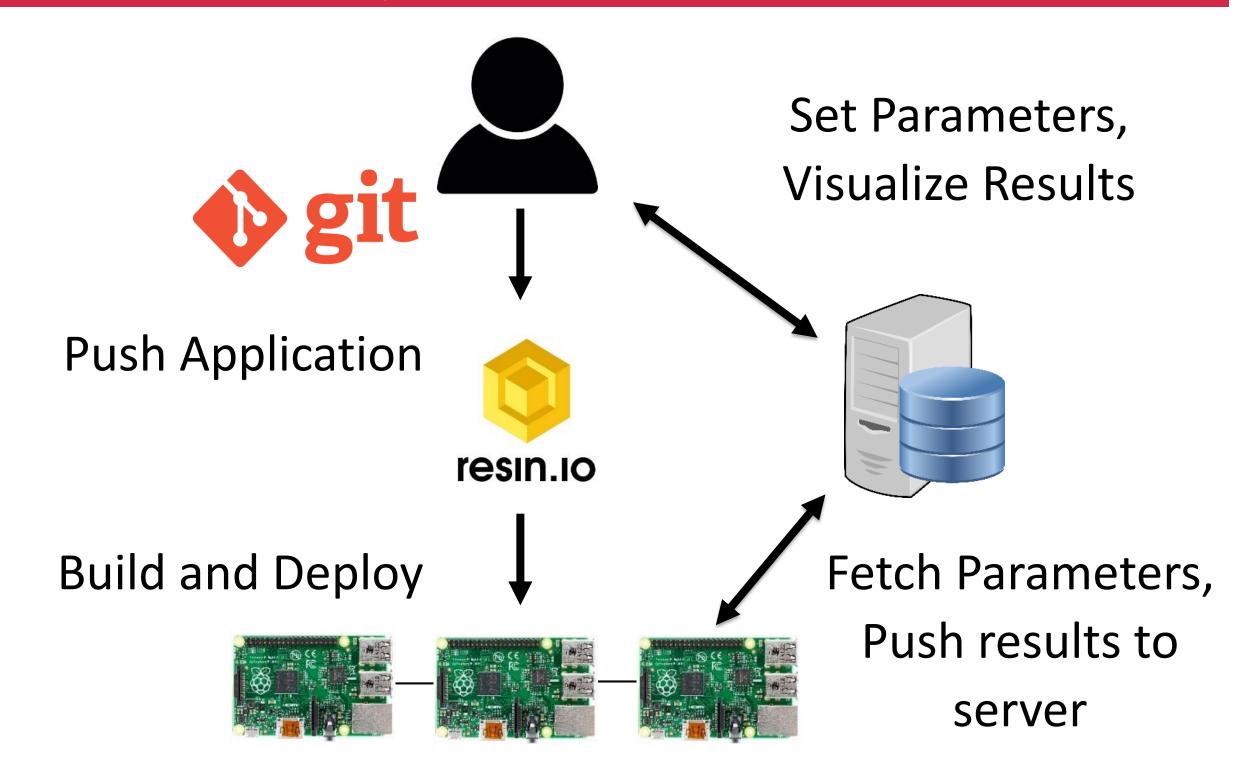
## **Geo-Routing**

- ☐ Sensor network task
- ☐ Route message to given GPS coordinates over unknown topology
- Every node only knows own and neighbors' locations
- ☐ Greedily pass to closest neighbor

### **Future Work**

- ☐ Testing with physical sensors
- ☐ Simulation of packet dropping, dying nodes
- ☐ Bandwidth/Power consumption tests for field deployments

## **System Architecture**

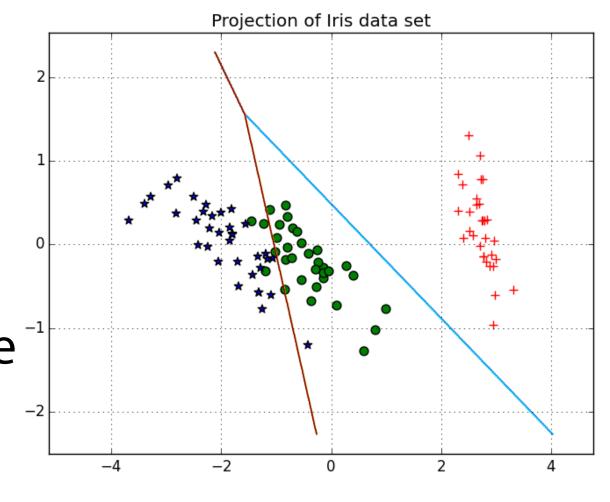


## Message Sending and Callbacks

```
m = Messager()
neighbor = '5'
message = { 'num': 42 }
m.sendMessage(neighbor, message)
    callback(message, name):
    print('Got message from %s: %s' % (name,
    message))
m.registerCallback(callback)
```

## **Classifier Training**

- ☐ Gradient Descent, SVM
- ☐ Use synchronous averaging to get feature vector
- ☐ Compute individual node errors and final classification



## Acknowledgements

We would like to thank resin.io for generously donating the Raspberry Pis, and Professor Sarwate for his guidance on this project!

