

Perception

{ object: "cup", position: {x: 8, y:4} } { object: "cereal", position: {x: 8, y:3} }



Trigger

{ op: "insert", ts: Timestamp(1485369072, 5),

o: {object: "cereal", position: {x: 7, y:4}} }



Callback

Query:

{ object: {\$exists: true}, position.x: {\$gt: 0} }

Motion Planner