Chapter 1

Background knowledge

1.1 Configurable Software System

Almost all software systems in use today are configurable. This means, almost all software systems allow a user to customize the software system to their specific requirements. To allow for such customizability, software systems provide a number of configuration options, also called features, to specify the desired behavior of the software system. A feature is an attribute of a system that directly affects end-users [?]. Each combination of configuration options describes a variant of the software system, making configurable software systems similar to Software Product Lines (SPL) [?]. For example, a web server like the Apache HTTP Server, allows the user to select features like compression, encryption or the use of specific transport protocols like HTTP/2.

Features usually satisfy functional requirements [?] of users. Functional requirement as described by ? "[...] capture the intended behavior of the system - or what the system will do". Meaning, for the example of the web server, a functional requirement would be the use of a specific compression algorithm like Brotli¹. On the other hand, software systems also have non-functional requirements. ? describes non-functional requirements as "[...] requirements on its development or operational cost, performance, reliability, maintainability, portability, robustness, and the like."

In this work non-functional requirements, like performance or memory usage, of a software system are analyzed in regard to the configurations used. Usually the influences of configuration options on functional properties of the software are well documented and understood, but the influences on non-functional properties are unknown to the user and more often than not, to the developer.

¹Brotli is a compression algorithm developed by Google primarily used by web servers to compress HTTP content.

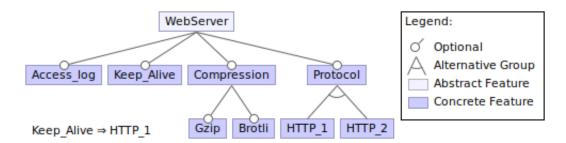


Figure 1.1: Feature diagram of an exemplary web server

Feature model

Feature models, introduced by ?], serve as a mean to convey information about the features of a system. Which features can be chosen and how those features can be combined. For this, the structural relationship between features is described. Each feature can either be optional or mandatory and each feature can have child features which are either in an or group or an alternative group. In an alternative group, only one of the child features can be selected, in an or group, at least one of the child features must be selected. There are also composition rules, also known as cross-tree constrains, which define constrains not expressible in the hierarchical structure of the features.

Feature models can be represented visually by feature diagrams or textually by formats like SXFM [?]. Feature diagrams are an intuitive way for a user to work with feature models, they visualize the feature model in a tree diagram. An example of a feature diagram can be seen in Figure 1.1. In it, the features of an exemplary web server are described. The web server has 4 features, of which 3 are optional and one is mandatory. It also includes two crosstree constrains. The feature Access_log is an optional feature, without any constrains on it. This feature can be enabled or disabled however the user likes. In this work, this kind of feature without any constrains on it is also referenced as independent feature. Even though the Keep_alive feature has no differences in the hierarchical structure to the Access_log feature, it has a cross-tree constrain. This constraint mandates, that if Keep alive is selected, the HTTP/1 feature is selected too, since the Keep alive functionality is only available in the HTTP/1 protocol. Compression and Protocol are both features with child features. Since HTTP/1 and HTTP/2 are in an alternate group, only one of these two protocols can be chosen for a valid configuration. With Compression, one or both of the child features can be chosen, since they are in an or group.

Interactions

TODO

1.2 Performance-Influence Model

The amount of possible configurations of modern software systems and the complex constrains between them can be overwhelming. Making it difficult to find an optimal configuration, that performs as desired. Performance influence models are meant to ease understanding, debugging and optimization of configurable software systems [?].

A performance influence model consists of several terms that describe the performance of a configuration based on the values of configuration options [?]. Performance, in this context, can be measurable quality attributes such as execution time, memory size or energy consumption. The model describes the influence of several independent variables X, our configuration, on a dependent variable y, our measurable quality attribute. While there are several approaches to predict performance, in general, they all work similarly. They sample a subset of configurations - this is done because it is infeasible to measure performance of all configurations if the configuration space is too big - and learn a model with the sampled configurations.

- ?] introduces a variability-aware approach to predict a configuration's performance based on random sampling. They use a Classification-And-Regression-Tree [?] to recursively partition the configuration space into smaller segments until they can fit a simple local prediction model into each segment.
- ?] describes how to create human understandable models based on previous work [?]. They combined binary sampling strategies such as option-wise, negative option-wise and pair-wise, with numerical sampling strategies, such as the Placket-Burman-Design. They then used stepwise linear regression to learn the influence model.

1.2.1 Sampling

The selection of a subset of configurations plays an integral role in almost all methods to predict the performance of a software system. If a configuration option is not present in the sampled subset of configuration a model can not learn the influence of this option. The random selection, random sampling, as used by most machine learning applications proves difficult with configurations. Mainly due to the constraints on the configuration options. Near uniform random sampling in the presence of constraints, although possible, is

infeasible [?]. This resulted in developing dedicated sampling strategies for configuration spaces.

Distance based sampling

?] describe a way to randomly sample a configuration space based on a distance metric and a portability distribution, called distance-based sampling. For this, they rely on a distance metric, like the Mannhatten-Distance, to assign each configuration a distance value. By selecting a distance value through a discrete probability distribution and then picking a configuration with the corresponding distance value, they achieve a spread over the configurations resembling the given probability distribution. This allows for uniform random like sampling if the chosen probability distribution is the uniform distribution.

Binary decision diagram-sampling

Although?] do not create a model to predict the performance of a system, they implement a way of random sampling configuration spaces through a binary decision diagrams (BDD)[?]. They transform a given feature model into BDD, this makes it easy to count the number of valid configuration and thus easy to randomly sample from them. While a BDD allows for random sampling, a major drawback is the creation of it, which may exceed time or memory constrains for some use cases.

• Combining Multi-Objective Search and Constraint Solving for Configuring Large Software Product Lines [?]

1.3 Sensitivity analysis

- Sensitivity Analysisa
 - Einfluss mehrere Parameter auf Variable
 - Dani Seminararbeit beispiel?

1.4 SAT-Solver

The satisfiability prophlem in propositional logic (SAT) is the problem of determining the existens of any solution, that satisfies a given boolean formula. A boolean formula is called satisfiable, if we can assign the varibales in the formula true or false values in such a way, that the formula evalutes to true.

As an example, the formula $A \vee B$ is satisfiable. We can prove this by assigning A = true and B = false. The resulting forumla would be $true \vee false$, which evalutes to true, meaning the forumla is satisfiable. If a forumla is not satisfiable, the forumla is called unsatisfiable. An example of this would be the forumla $A \wedge \neg A$. No possible assignment of A would result in the forumla beeing evaluted to true. SAT-Problems arise in many application domains and, most notably for this work, can be used in validating configurations for SPLs.

SAT-Solvers are programms, which aim to solve the SAT-Problem. Even though the SAT-problem is NP-complete [?], modern SAT-Solvers can can often handle problems with hundreds of thousands of variable and millions of constraints [?]. They often use algorithms such as DPLL [?] or variations of it at thier core and thier optimization is a large field of research on its own. Many free and open source implimentations of SAT-Solvers exist [???]. In this work we use Z3 [?], which is an SMT-Solver. Satisfiability modulo theories (SMT) generalizes the SAT-Problem to formulas involving real numbers and various data structures. The use of an SMT-Solver, instead of a SAT-Solver, allows us to define cost-functions to optimize the solution of the SMT-Solver for.

In this work, we make use of the SMT-Solver Z3 to generate valid configurations for a configurable software system. Like ?] defined it, we define our feature model as a set of boolean features with a set of constraints over them. A configuration is a set of features, where all features in that set are selected and features which are not in the set are unselected. A configuration is valid if it satisfies all the constraints of the feature model, otherwise it is called invalid. ?] shows, that a feature model can be defined as a propositional formula. This not only allows the feature model to be stored in file formats like DIMACS, it also allows the use of of-the-shelf SAT-Solvers for feature models.