## COSC343: Artificial Intelligence

Lecture 7: Linear regression and Least Squares

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## In today's lecture

- Regression
- Linear vs. non-linear systems
- Linear regression
- Least squares
- Linear least squares

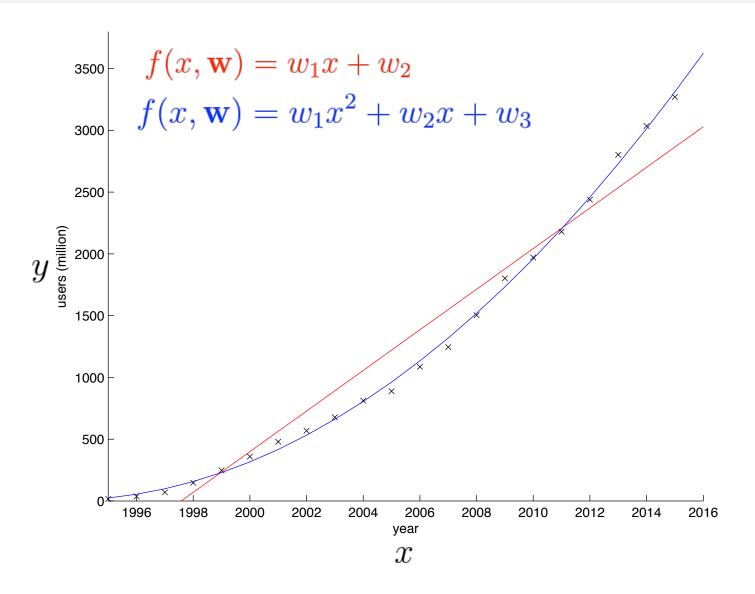
#### Regression

Regression is the problem of modelling a relationship between input variable of M dimensions,  $\mathbf{x} = \begin{bmatrix} x_1 & \dots & x_M \end{bmatrix}^T$  and continuous output variable  $y \in \mathbb{R}$ , such that  $y = f(\mathbf{x}, \mathbf{w})$ .

Attributes of the input can be discrete or continuous

Again, we're concerned with methods that learn a regression function from a set of known input-output examples:

• That is, the training data consist of N sample inputs - each a vector of dimension M for which correct output is known.



## Linear vs. non-linear systems

Linear w.r.t w

$$y = wf(x)$$

ullet Easy to solve for w

$$w = \frac{y}{f(x)}$$

• Derivative w.r.t. w doesn't depend on the value of w

$$\frac{dy}{dw} = f(x)$$

Non-linear w.r.t  $\,w\,$ 

$$y = f(x, w)$$

• Not-easy or not possible to solve for  $\boldsymbol{w}$ 

$$w = g(x, f(x, w))$$

• Derivative w.r.t.  $\boldsymbol{w}$  doesn't may depend on value of  $\boldsymbol{w}$ 

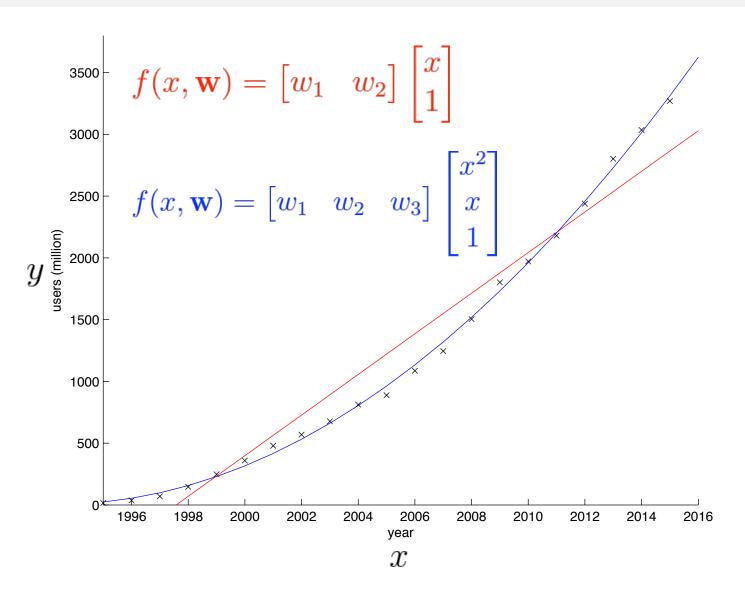
$$\frac{dy}{dw} = \frac{df(x, w)}{dw}$$

#### Linear regression

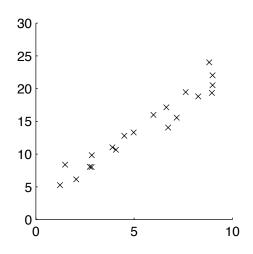
A regression problem modelled with a hypothesis function that is a weighted sum of a set of base functions is called **linear regression**.

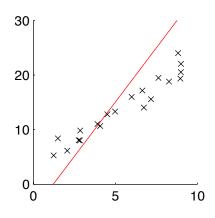
- The weight coefficients are the parameters of the model
- The model is linear in parameters
- The model can be non-linear in input

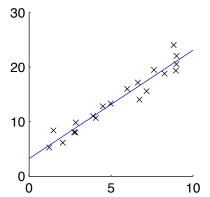
$$f(\mathbf{x}, \mathbf{w}) = \sum_{u=1}^{U} w_u f_u(\mathbf{x}) = \begin{bmatrix} w_1 & \dots & w_U \end{bmatrix} \begin{bmatrix} f_1(\mathbf{x}) \\ \vdots \\ f_U(\mathbf{x}) \end{bmatrix}$$

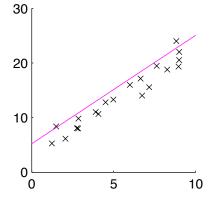


## An example: Which fit is best?









## How to describe the best fit mathematically?

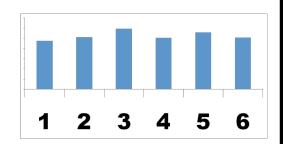
- We want to fit data well!
- We don't want to overfit!
- We want the best fit possible!

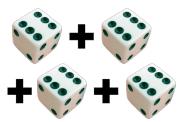
The residual error should be normally distributed!!!

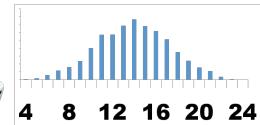


## Recall the Central Limit Theorem (CLT)

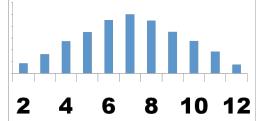


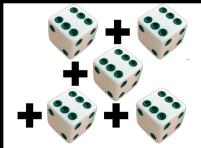


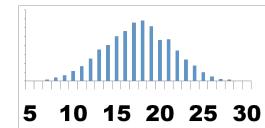




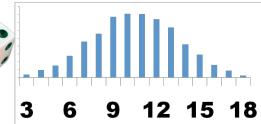


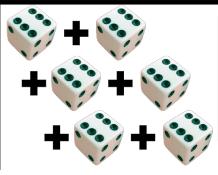


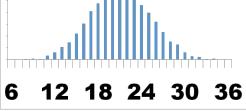












# CLT, Information Theory and the Least Squares

- The greater number of random events contributing to a result, the more Gaussian is the probability distribution of that result.
- Out of all real-valued distributions of a fixed variance, normal distribution has the maximum entropy – it's most random.
- Given a hypothesis, fit it to data so that residual error is zero on average, and otherwise as random as possible – that is, normally distributed with zero mean.
  - Least squares doesn't tell you how to pick a good hypothesis, just how to fit it to data

## Least squares from Maximum Likelihood

- Given a hypothesis function  $y = f(\mathbf{x}, \mathbf{w})$  and a training set  $f(\mathbf{x}, \mathbf{y})$  defi $f(\mathbf{x}, \mathbf{y}, \mathbf{y})$  defi $f(\mathbf{x}, \mathbf{y}, \mathbf{y})$  defies the model output and the true (target) output:
- Assuming errors from sample to sample are independent and identically distributed (i.i.d) with distribution :
  - Find parameters that maximise the overall probab $M(\mathscr{C})$  ...  $\prod p(e_i)$
  - ....which is the same as minimizing ....

$$-\sum_{i} \ln p(e_i)$$

• ...which for  $\frac{1}{1}$  is the same as minimizing:

$$p(e_i) = \frac{1}{\sqrt{2\pi}\sigma} \exp^{-\frac{e_i^2}{2\sigma^2}}$$
 cost 
$$J = \frac{1}{2} \sum_i e_i^2$$

## Least squares solution for linear regression

The least squares parameters that minimise  $J=\frac{1}{2}\sum_i e_i^2$ , where  $e_i=y_i-\tilde{y}_i$ , can be found by solving:

$$\frac{dJ}{d\mathbf{w}} = \sum_{i} \frac{de_i}{d\mathbf{w}} e_i = 0$$

For models that are linear in parameters,  $y = f(\mathbf{x}, \mathbf{w}) = \mathbf{w}^T \begin{bmatrix} f_1(\mathbf{x}) \\ \vdots \\ f_U(\mathbf{x}) \end{bmatrix}$ , where  $\mathbf{w}^T = \begin{bmatrix} w_1 & \dots & w_U \end{bmatrix}$ , there is a closed form solution:

$$\mathbf{w} = \left(\mathbf{F}\mathbf{F}^T\right)^{-1}\mathbf{F} ilde{\mathbf{y}}^T$$
 , where

$$\mathbf{F} = egin{bmatrix} f_1(\mathbf{x}_1) & \dots & f_1(\mathbf{x}_N) \ dots & \ddots & dots \ f_U(\mathbf{x}_1) & \dots & f_U(\mathbf{x}_N) \end{bmatrix} \quad ext{and} \quad ilde{\mathbf{y}} = egin{bmatrix} ilde{y}_1 & \dots & ilde{y}_N \end{bmatrix}$$

x	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014
$\tilde{y}$	16	36	70	147	248	359	479	569	677	812	888	1086	1245	1504	1802	1971	2180	2439	2802	3035

Hypothesis:  $y = f(x, \mathbf{w}) = w_1 x + w_2$ 

 $\tilde{\mathbf{y}} = \begin{bmatrix} 16 & 36 & 70 & 147 & 248 & 359 & 479 & 569 & 677 & 812 & 888 & 1086 & 1245 & 1504 & 1802 & 1971 & 2180 & 2439 & 2802 & 3035 \end{bmatrix}$ 

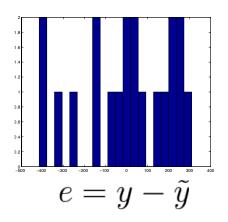
$$\mathbf{w}^T = \begin{bmatrix} w_1 & w_2 \end{bmatrix}$$

Solve:  $\mathbf{w} = \left(\mathbf{F}\mathbf{F}^T\right)^{-1}\mathbf{F} ilde{\mathbf{y}}^T$ 

$$\mathbf{w} = \begin{bmatrix} 158.00 \\ -315600.29 \end{bmatrix}$$

Root mean square (RMS) error:

$$\sqrt{E[e^2]} = 218.3$$



x	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014
$\tilde{y}$	16	36	70	147	248	359	479	569	677	812	888	1086	1245	1504	1802	1971	2180	2439	2802	3035

Hypothesis: 
$$y = f(x, \mathbf{w}) = w_1 x^2 + w_2 x + w_3$$

 $\tilde{\mathbf{y}} = \begin{bmatrix} 16 & 36 & 70 & 147 & 248 & 359 & 479 & 569 & 677 & 812 & 888 & 1086 & 1245 & 1504 & 1802 & 1971 & 2180 & 2439 & 2802 & 3035 \end{bmatrix}$ 

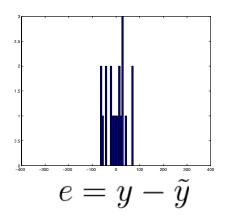
$$\mathbf{w}^T = \begin{bmatrix} w_1 & w_2 & w_3 \end{bmatrix}$$

Solve: 
$$\mathbf{w} = \left(\mathbf{F}\mathbf{F}^T\right)^{-1}\mathbf{F} ilde{\mathbf{y}}^T$$

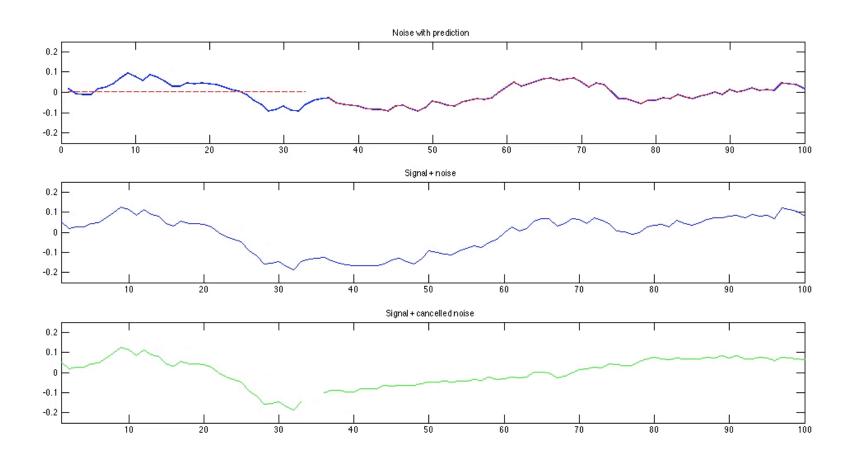
$$\mathbf{w} = \begin{bmatrix} 7.24 \\ -28868.93 \\ 28776401.68 \end{bmatrix}$$

Root mean square (RMS) error:

$$\sqrt{E[e^2]} = 40.6$$



## An example: active noise control



## An example: active noise control

Outside noise: x[n]

Signal + noise:  $s[n] = \tilde{s}[n] + x[n]$ 

Create a model, where the output is a linear combination of past M samples:

$$y[n] = \sum_{m=1}^{M} w_m x[n-m]$$

Compute parameters that predict next sample from previous M samples using saved batch of N samples:

$$e[n] = y[n] - x[n]$$

Use these parameters to predict the next sample:

$$y[n+1] = w_1x[n] + \ldots + w_Mx[n-M]$$



Send out inverted predicted signal in time to meet the next sample of the coming noise: (

$$s[n+1] - y[n+1] \approx \tilde{s}[n+1]$$
if  $y[n+1] \approx x[n+1]$ 

 $\text{if } y[n+1] \approx x[n+1] \\ \text{recovered signal.}$ 

## Summary and reading

- Regression = model output is continuous
- Linear regression model is linear in parameters (not necessarily in input)
- Least squares fit best fit that makes the error normally distributed
- Linear least squares closed form solution for parameters

Reading for the lecture: AIMA Chapter 18 Section 6
Reading for next lecture: AIMA Chapter 18 Section 4