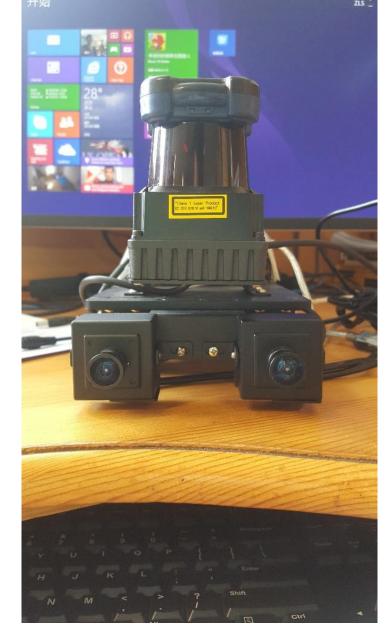
A Stereo-Lidar SLAM System

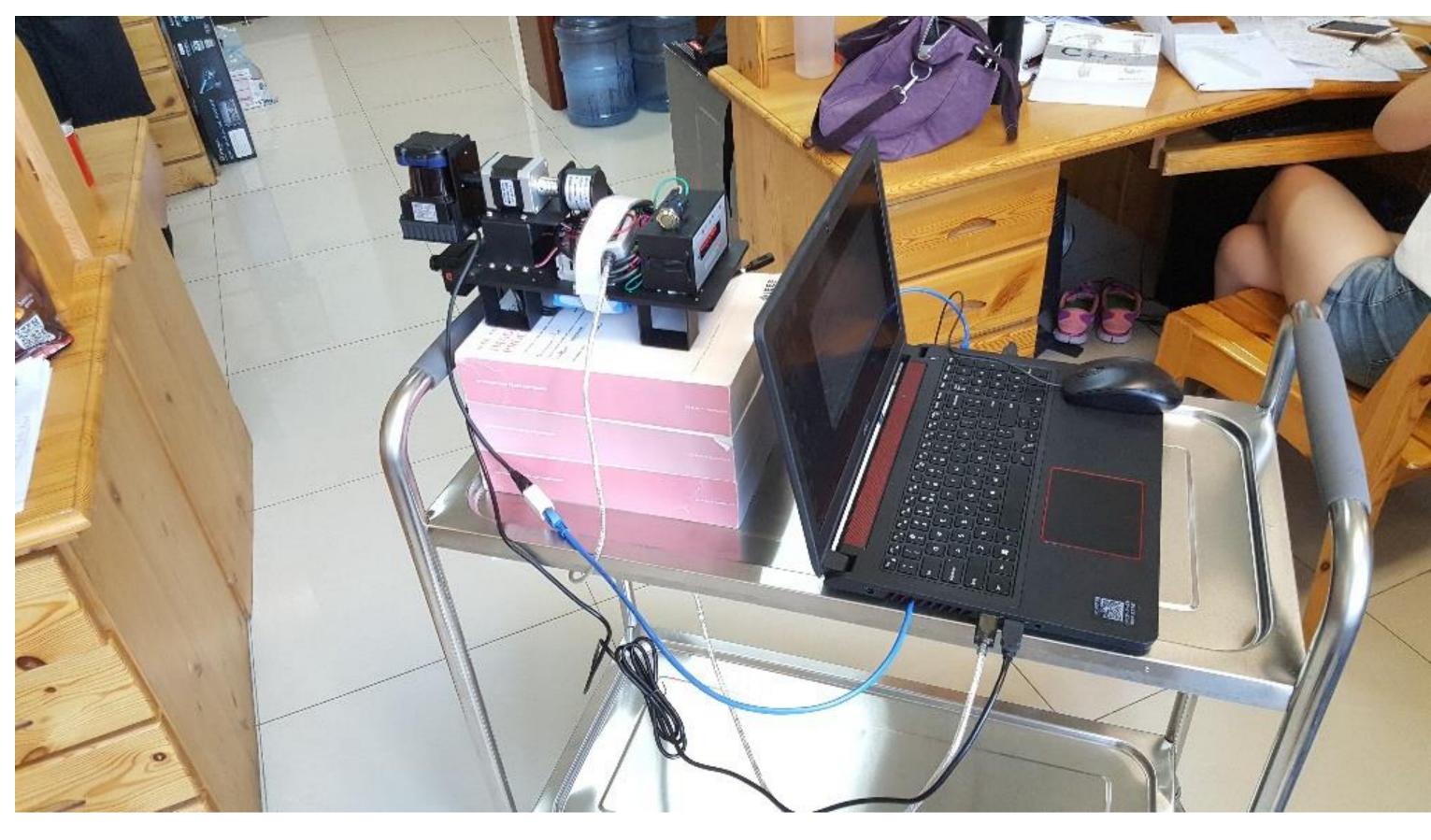
Leisheng Zhong, Tsinghua University

Demo Video: <u>youtube/youku</u>

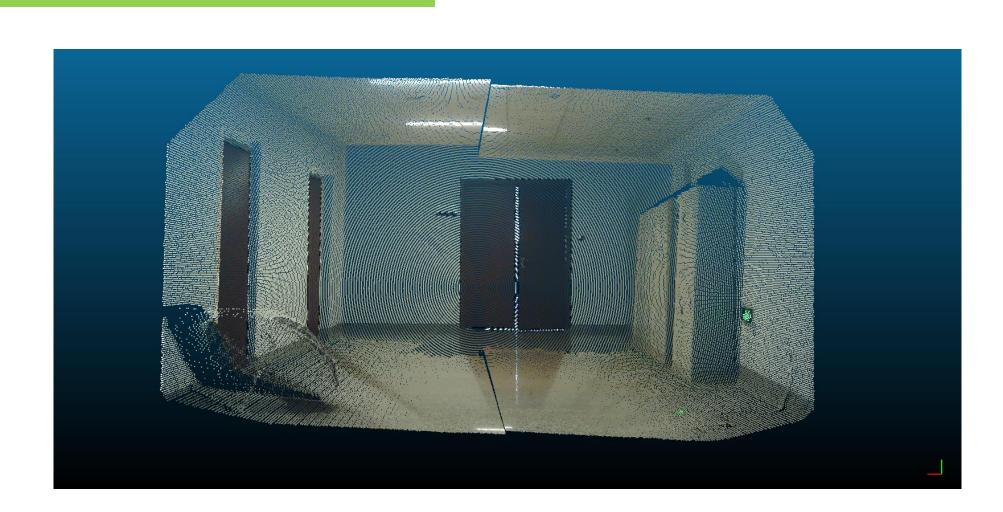
Device



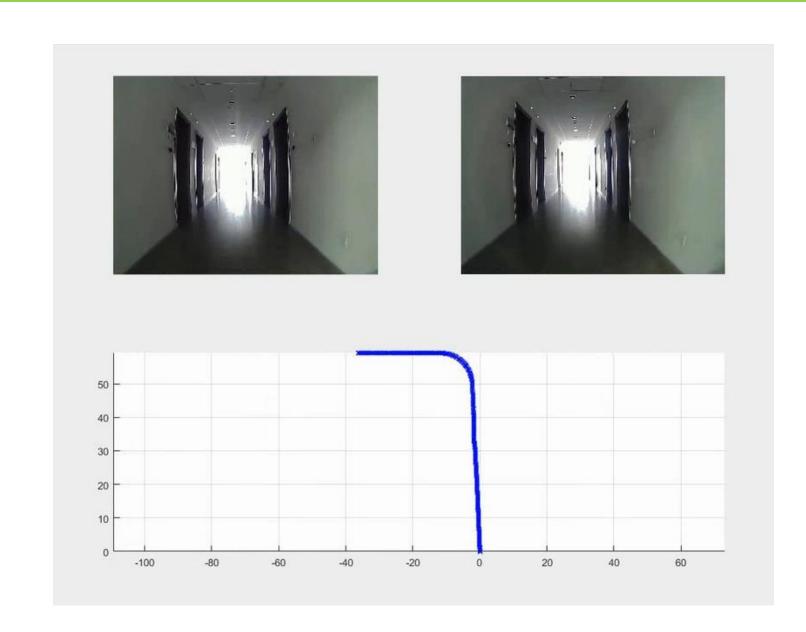


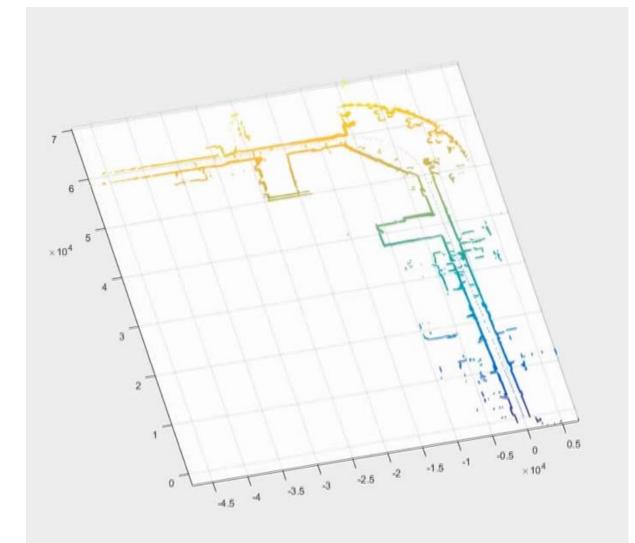


Texture Mapping



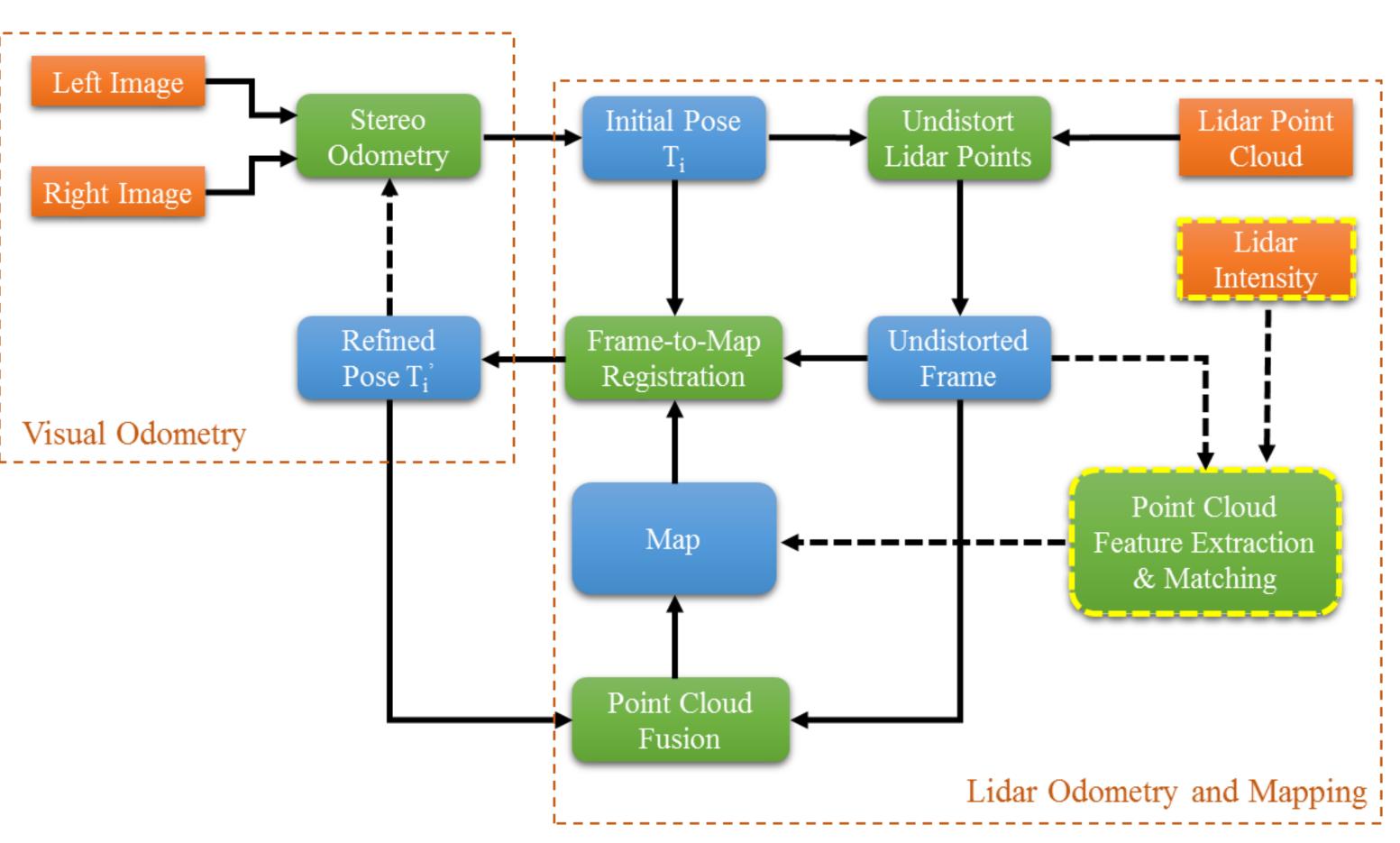
Dynamic Localization

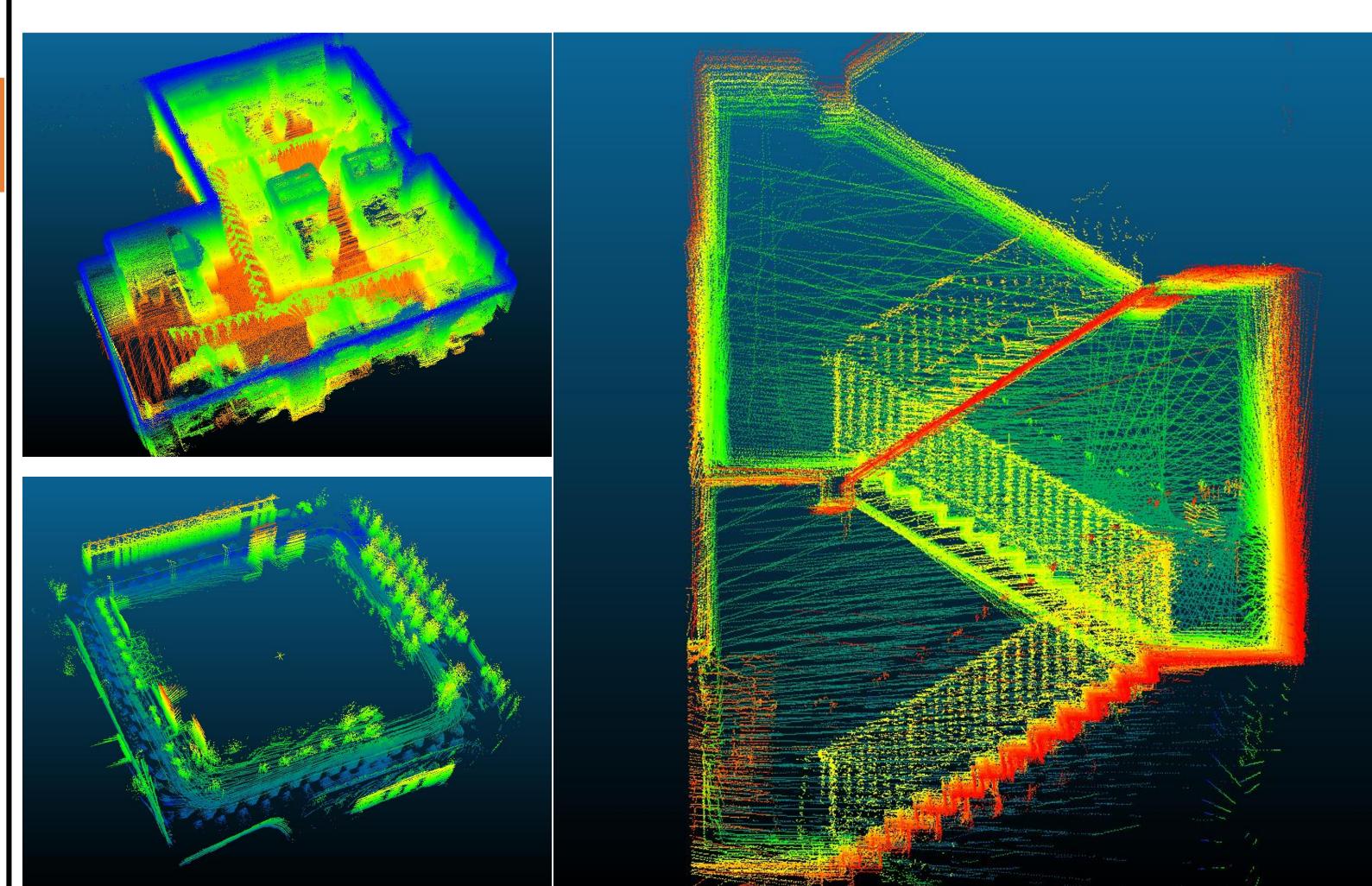




Dynamic Reconstruction







3D Scene Reconstruction

Static Scan

