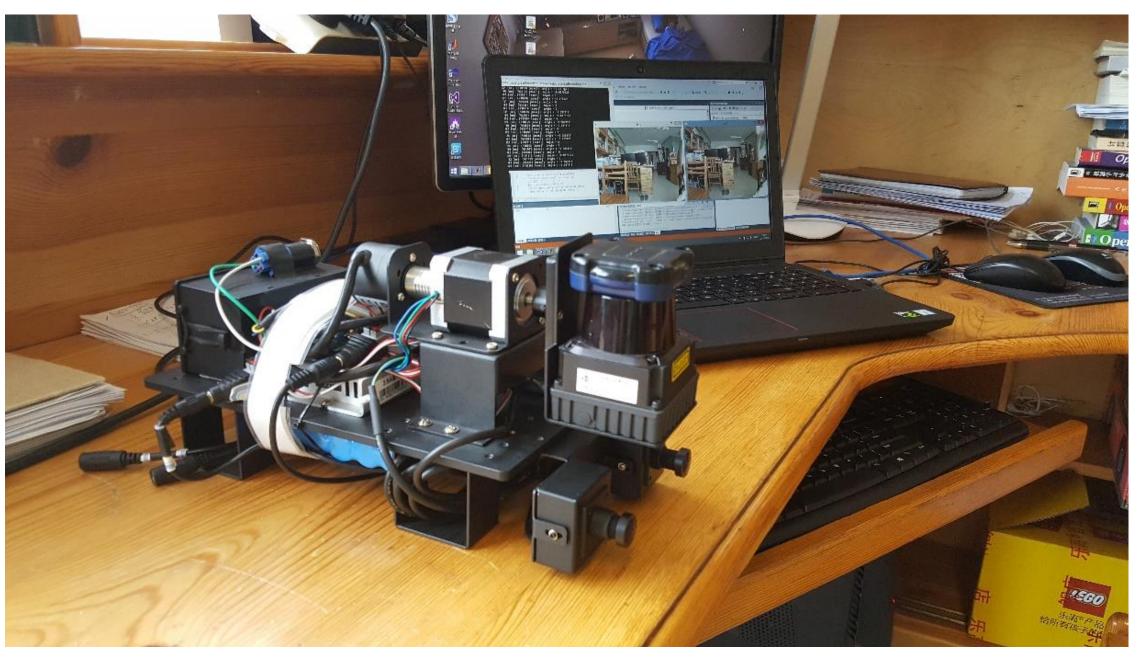
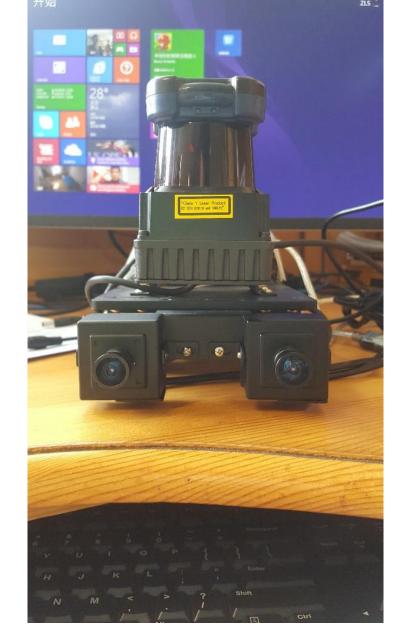
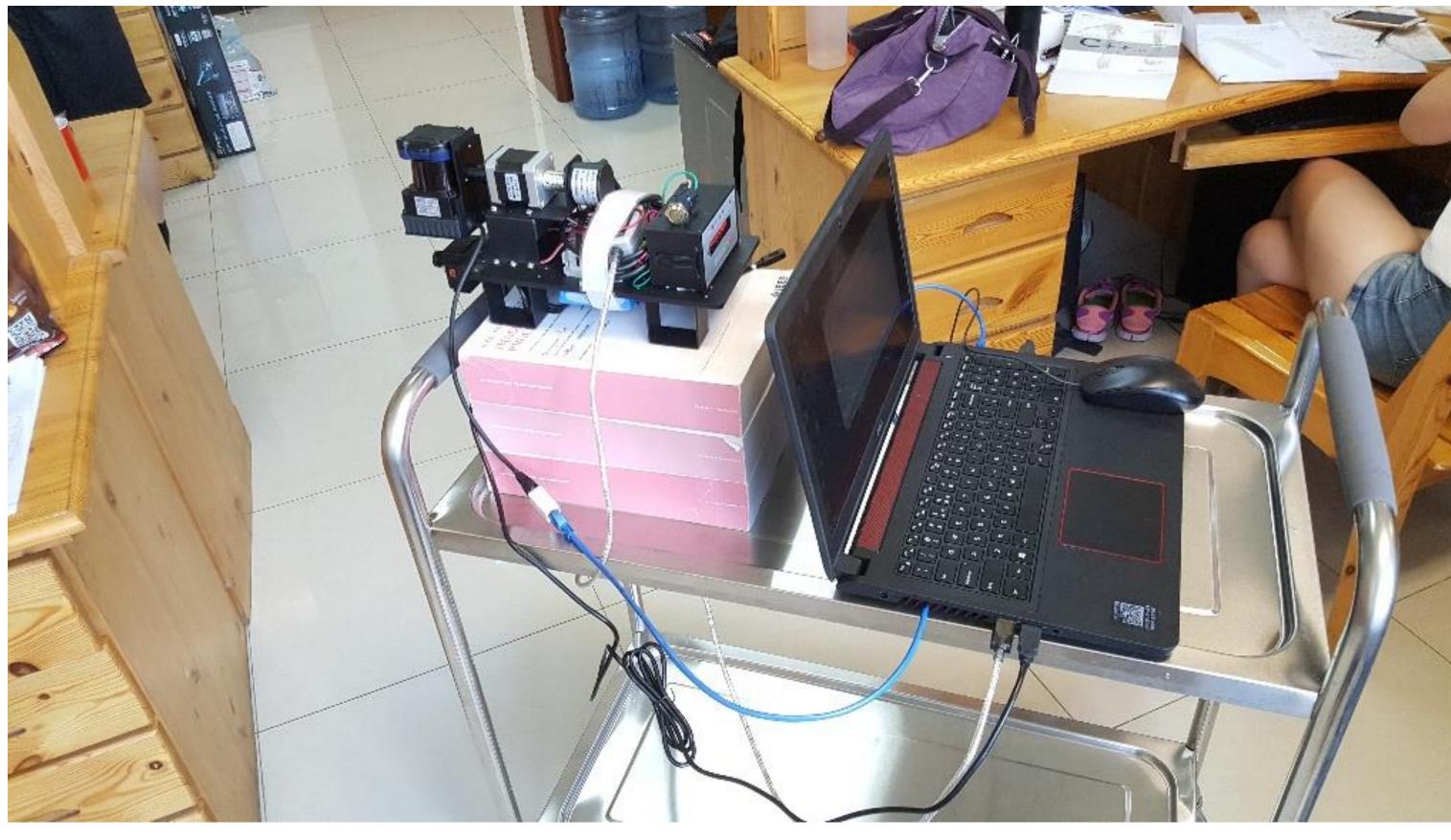
A Stereo-Lidar SLAM System

Leisheng Zhong, Tsinghua University

Device



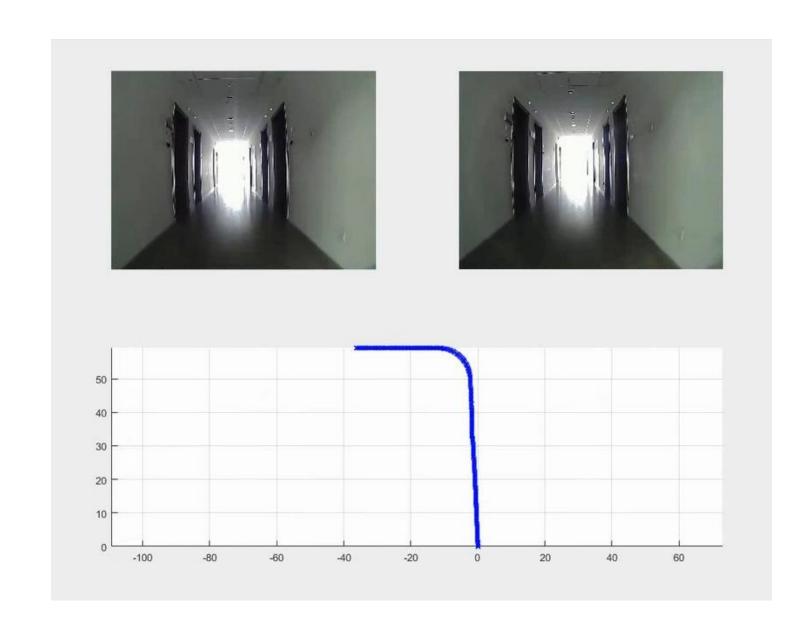


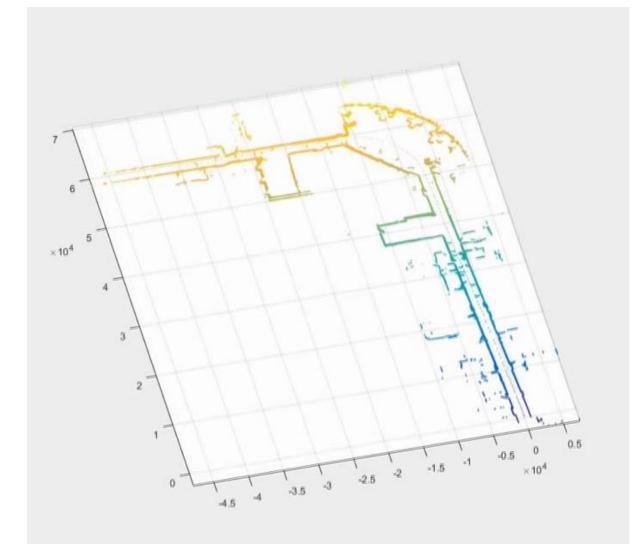


Texture Mapping



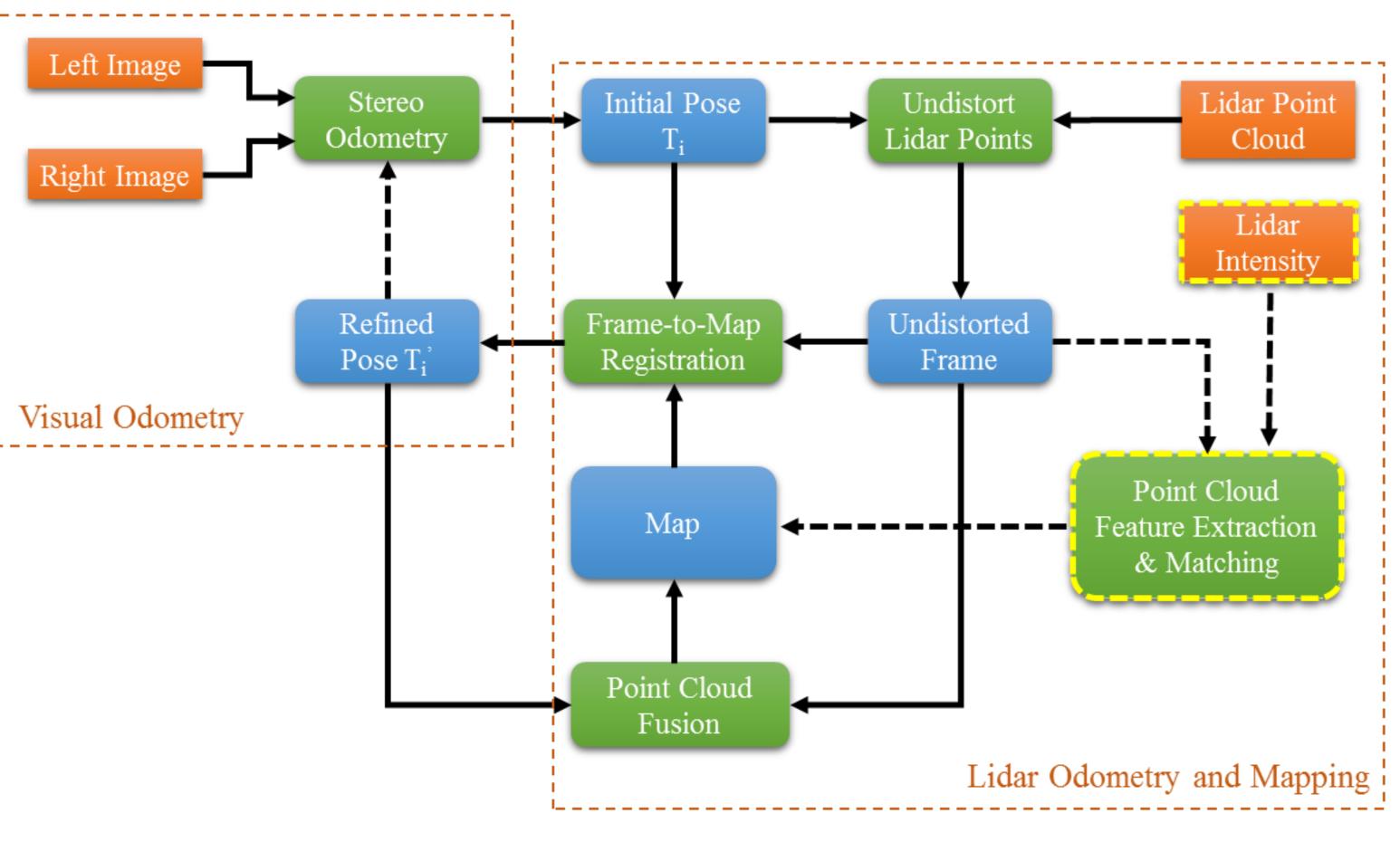
Dynamic Localization

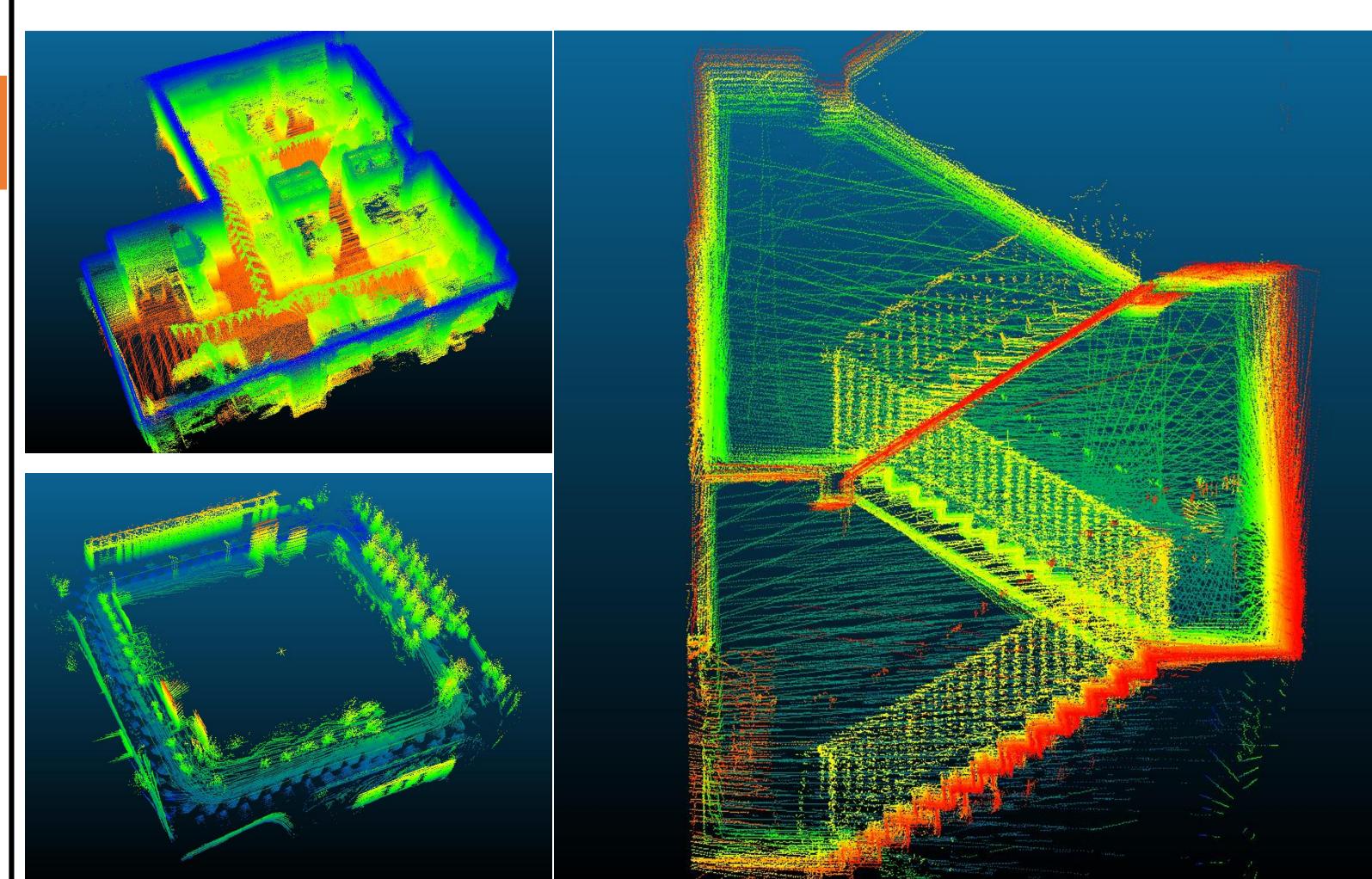




Dynamic Reconstruction







3D Scene Reconstruction

Static Scan

