



Congratulations! You passed!

TO PASS 80% or higher

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Module 3 Graded Quiz

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1. Which best describes the mission underlying an autonomous vehicle's mission planner?

1 / 1 point

- ☐ Compute the optimal vehicle behaviour for a given driving scenario
- ☐ Generate an optimal, collision-free path to the required destination
- ☒ Navigate a road network to the desired destination from the ego vehicle's position



Correct

Correct, this is the underlying goal of mission planning.

2. Which of these are examples of good values to optimize in a mission planner's objective function?

1 / 1 point

- ☒ Time to destination



Correct

Correct, this is a good measure of the efficiency of a global path.

- ☐ Deviation from the speed limit