



# Further reduction of quantization error

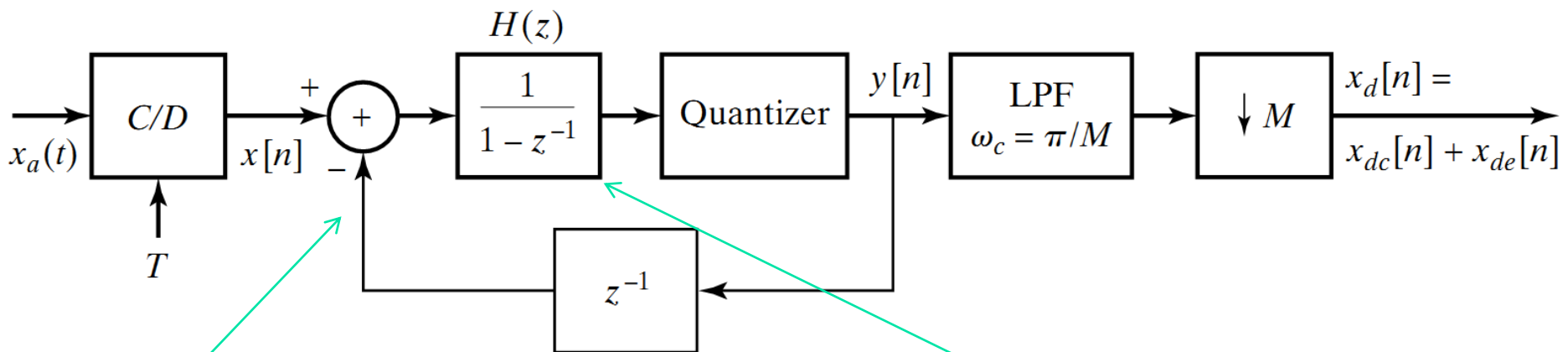
## Oversampling and Noise Shaping

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- Previously, we have shown that oversampling and decimation can improve the signal-to-quantization-noise ratio.
- The result is remarkable, but if we want to make a significant reduction, we need very large sampling ratios.
  - Eg., to reduce the number of bits from 16 to 12 would require  $M=4^4=256$ .
- The basic concept in **noise shaping** is to modify the A/D conversion procedure so that the **power density spectrum of the quantization noise is no longer uniform**.

# Oversampled Quantizer with Noise Shaping

- Can be represented by the discrete-time equivalent system as follows:
  - Discrete-time form



Minus the delayed feedback:  
**delta**

Accumulator (like an integrator):  
**Sigma**



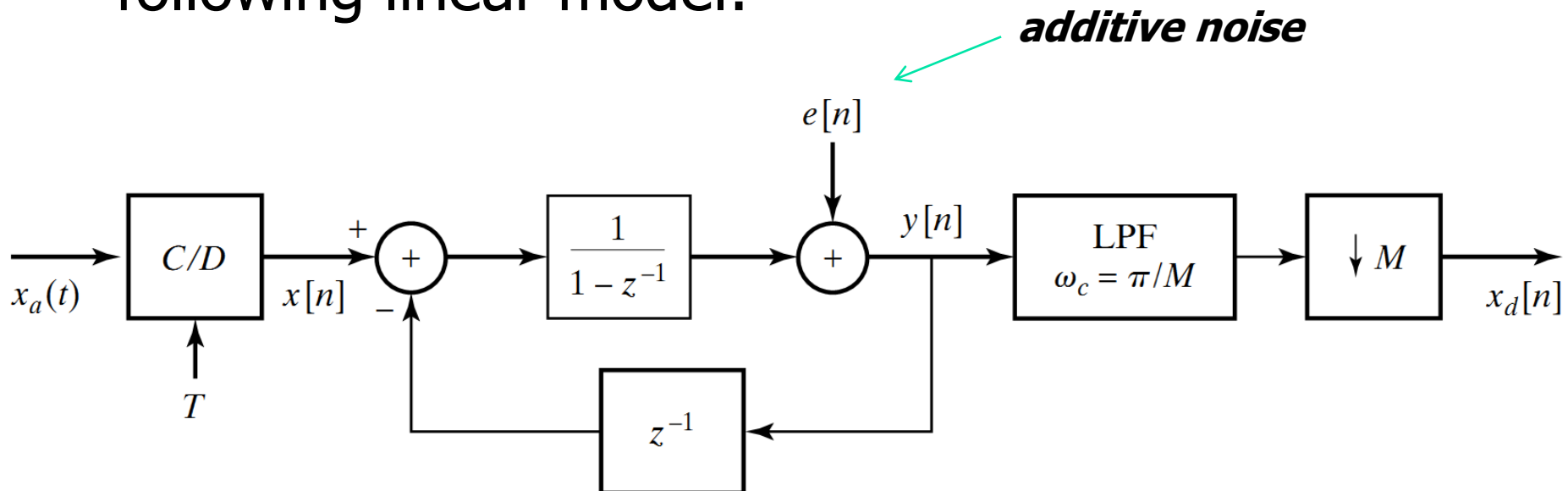
# What is $\frac{1}{1-z^{-1}}$ ?

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- $Y(z) = \frac{1}{1-z^{-1}}X(z)$ , so  $Y(z) = X(z) + z^{-1}Y(z)$
- Hence,  $y[n] = x[n] + y[n-1]$ .
- That is, the system  $\frac{1}{1-z^{-1}}$  is the accumulator  
 $y[n] = \sum_{k=-\infty}^n x[k]$ . This is why it is named "Sigma."

# Modeling the quantization error

- As before, we model the quantization error as an additive noise source.
- Hence, the above figure can be replaced by the following linear model:





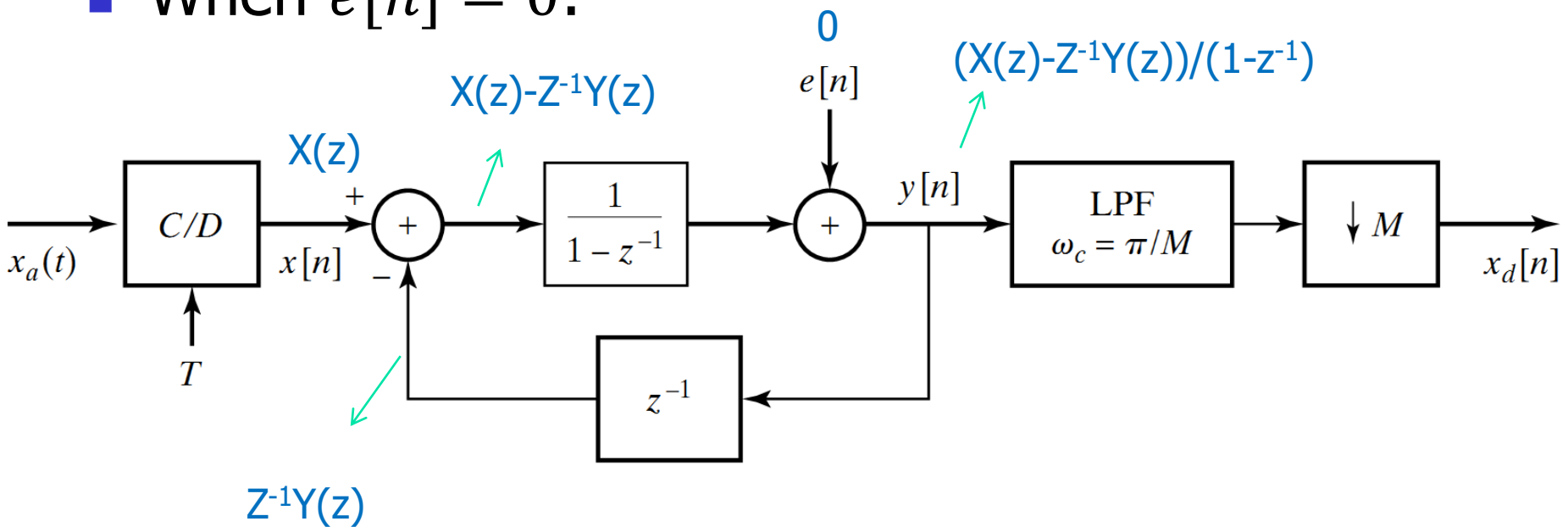
# Output of a linear system

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- This linear system has two inputs,  $x[n]$  and  $e[n]$ . According to the linearity, we can get the output  $y[n]$  by
  1. set  $x[n]=0$ , find the output  $y[n]$  w.r.t.  $e[n]$
  2. set  $e[n] =0$ , find the output  $y[n]$  w.r.t.  $x[n]$
  3. add the above two outputs.

# Transfer functions

- Consider the output in the z-domain. We denote the transfer function from  $x[n]$  to  $y[n]$  as  $H_x(z)$  and from  $e[n]$  to  $y[n]$  as  $H_e(z)$ .
- When  $e[n] = 0$ :





# Output when $e[n] = 0$

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- We have

$$Y[z] = \frac{X[z] - z^{-1}Y(z)}{1 - z^{-1}}$$

- So  $Y[z] - z^{-1}Y[z] = X[z] - z^{-1}Y(z)$

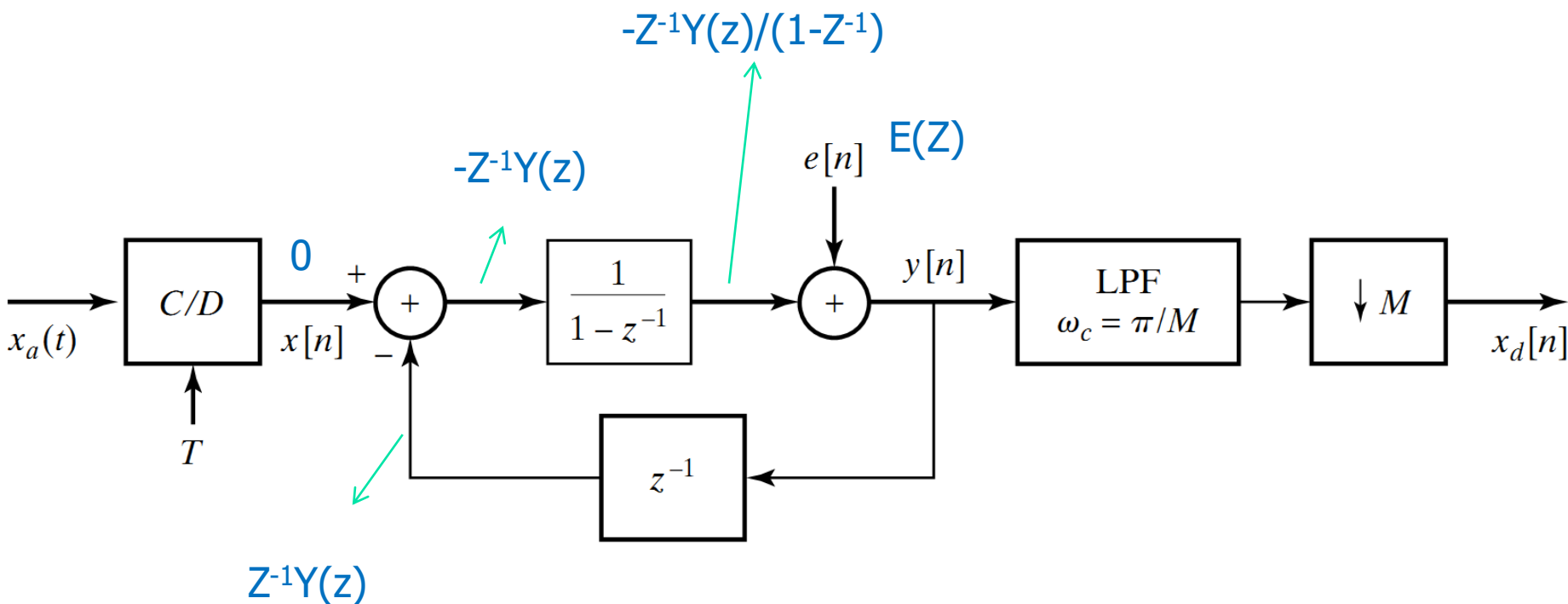
- That is

$$Y[z] = X[z]$$

when  $E[z]$  is zero.

# Transfer functions when $x[n] = 0$

- When  $x[n] = 0$ :







# Output when $x[n] = 0$

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- We have

$$Y[z] = E(z) - \frac{z^{-1}Y(z)}{1 - z^{-1}}$$

- So  $Y[z] - z^{-1}Y[z] = E[z] - z^{-1}E[z] - z^{-1}Y(z)$

- That is

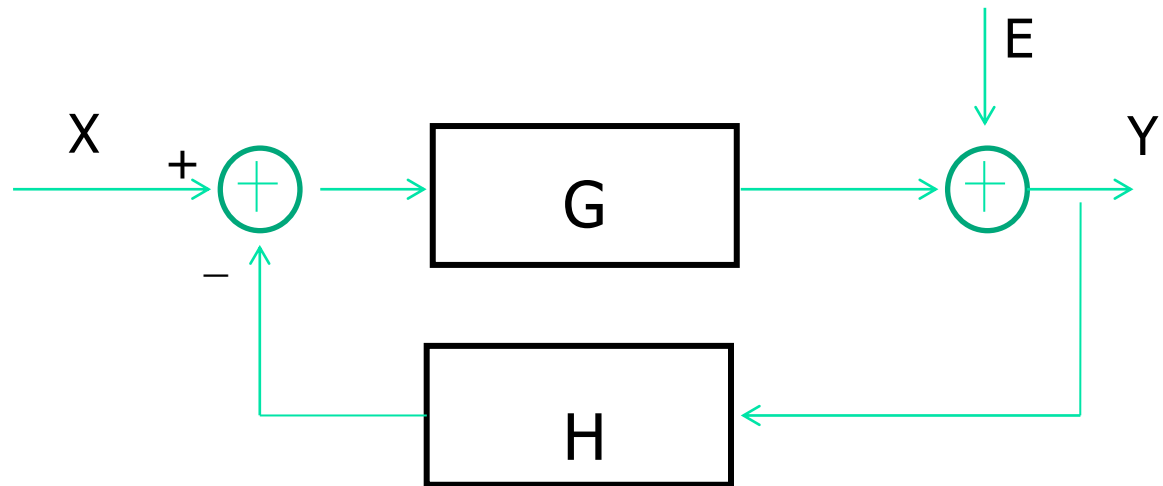
$$Y[z] = (1 - z^{-1})E[z]$$

when  $X[z]$  is zero.

# Remark: feedback system

- In fact, **feedback systems** have been widely used (serve as a fundamental architecture) in control engineering.

- Generally:



- Formula: 
$$\frac{Y(z)}{X(z)} = \frac{G(z)}{1 + G(z)H(z)}; \quad \frac{Y(z)}{E(z)} = \frac{1}{1 + G(z)H(z)}$$



# Another way of derivation

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- From the feedback system formula, we can also obtain that

$$H_x(z) = \frac{Y(z)}{X(z)} = \frac{G(z)}{1 + G(z)H(z)} = \frac{\frac{1}{1 - Z^{-1}}}{1 + \frac{Z^{-1}}{1 - Z^{-1}}} = 1$$

$$H_e(z) = \frac{Y(z)}{E(z)} = \frac{1}{1 + G(z)H(z)} = \frac{1}{1 + \frac{Z^{-1}}{1 - Z^{-1}}} = 1 - Z^{-1}$$



# Time domain relation

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- Hence, in the time domain, we have

$$y_x[n] = x[n]$$

$$y_e[n] = \hat{e}[n] = e[n] - e[n-1]$$

- The output  $y[n]$  can be represented as

$$y[n] = y_x[n] + y_e[n]$$

- The quantization noise  $e[n]$  has been modified as  $\hat{e}[n]$



# Power spectral density of the modified noise

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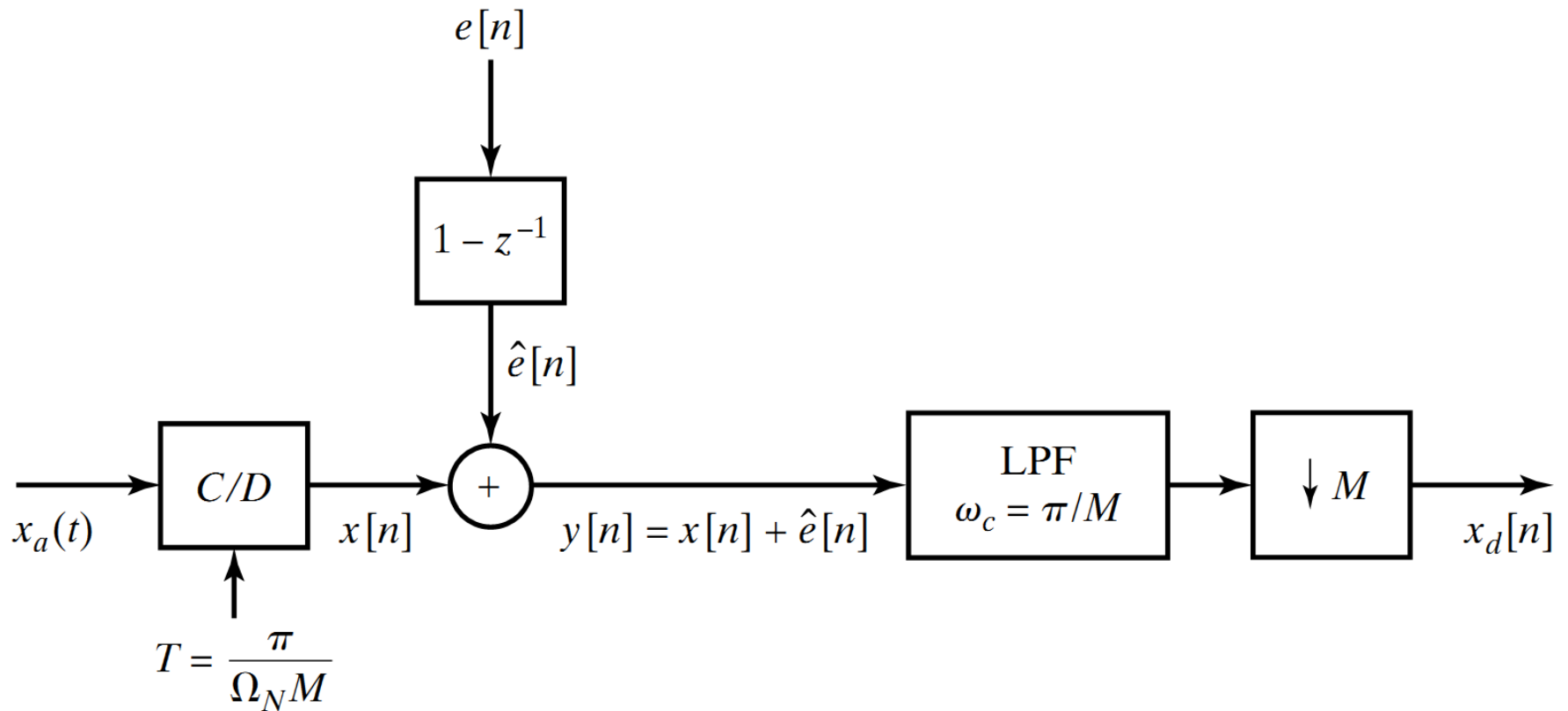
- To show the reduction of the quantization noise, let's consider the power spectral density of  $\hat{e}[n]$
- Since we have the input-output relationship between  $e[n]$  and  $\hat{e}[n]$  as

$$Y_e(z) = (1 - Z^{-1})E(z)$$

- In the frequency domain, we have

$$\hat{E}(e^{j\omega}) = Y_e(e^{j\omega}) = (1 - e^{-j\omega})E(e^{j\omega})$$

# Equivalent system



# Power spectral density of the modified noise

- The power-spectral-density relation between the modified and original quantization noises is thus

$$\begin{aligned}\Phi_{\hat{e}\hat{e}}(e^{jw}) &= \|1 - e^{-jw}\|^2 \Phi_{ee}(e^{jw}) && \text{Model the original} \\ &= \|1 - e^{-jw}\|^2 \sigma_e^2 && \text{quantization error as white} \\ &= (1 - e^{-jw})(1 - e^{jw})\sigma_e^2 = (1 - e^{-jw} - e^{-jw} + 1)\sigma_e^2 && \text{noise with this variance} \\ &= (2 - (e^{-jw} + e^{-jw}))\sigma_e^2 = (2 - 2\cos(w))\sigma_e^2 \\ &= (2\sin(w/2))^2 \sigma_e^2 \\ &\underbrace{\hspace{10em}}_{\text{p.s.d. of the modified noise}} && \text{p.s.d. of the original noise}\end{aligned}$$



# Quantization-noise power

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- Remember that the downsampler does not remove any of the signal power, the signal power in  $x_{da}[n]$  is

$$P_{da} = \mathcal{E}\{x_{da}^2[n]\} = \mathcal{E}\{x^2[n]\} = \mathcal{E}\{x_a^2(t)\}$$

- The quantization-noise power in the final output is

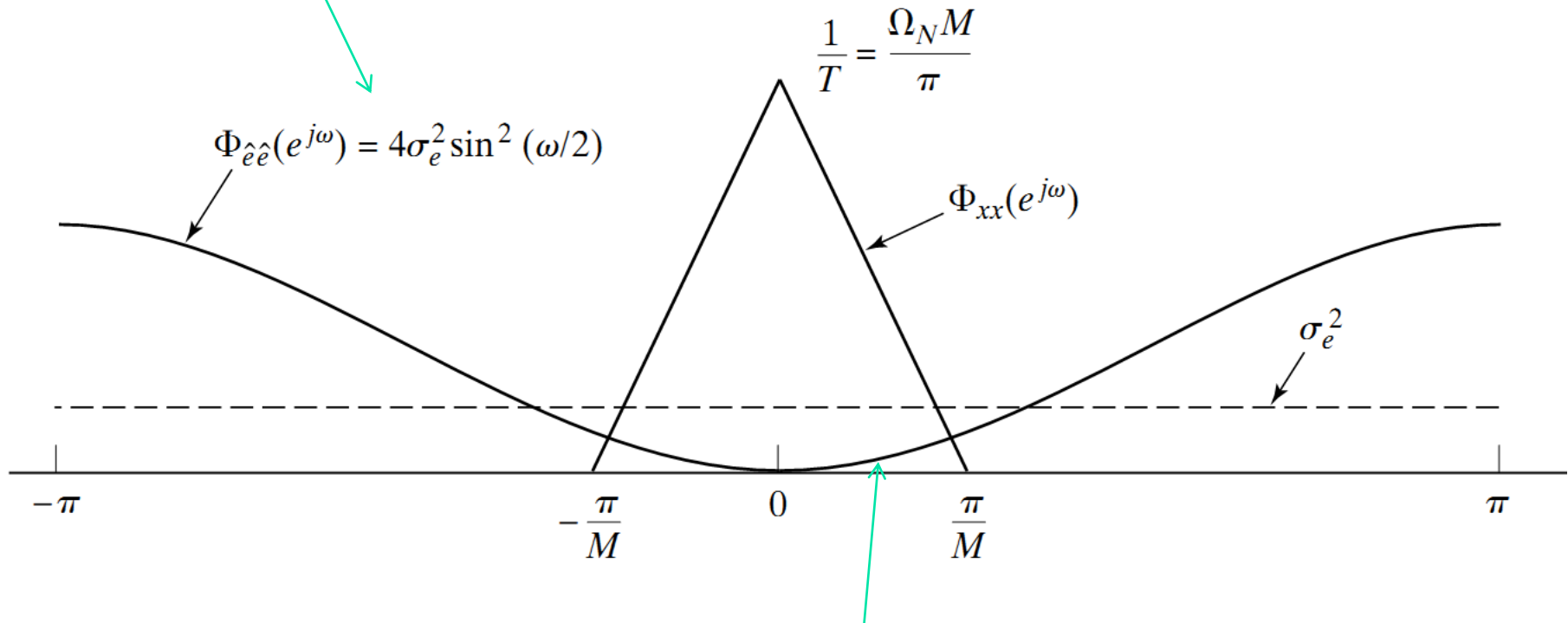
$$P_{de} = \frac{1}{2\pi} \int_{-\pi}^{\pi} \Phi_{x_{de}x_{de}}(e^{jw})$$

- See the following illustration for its computation



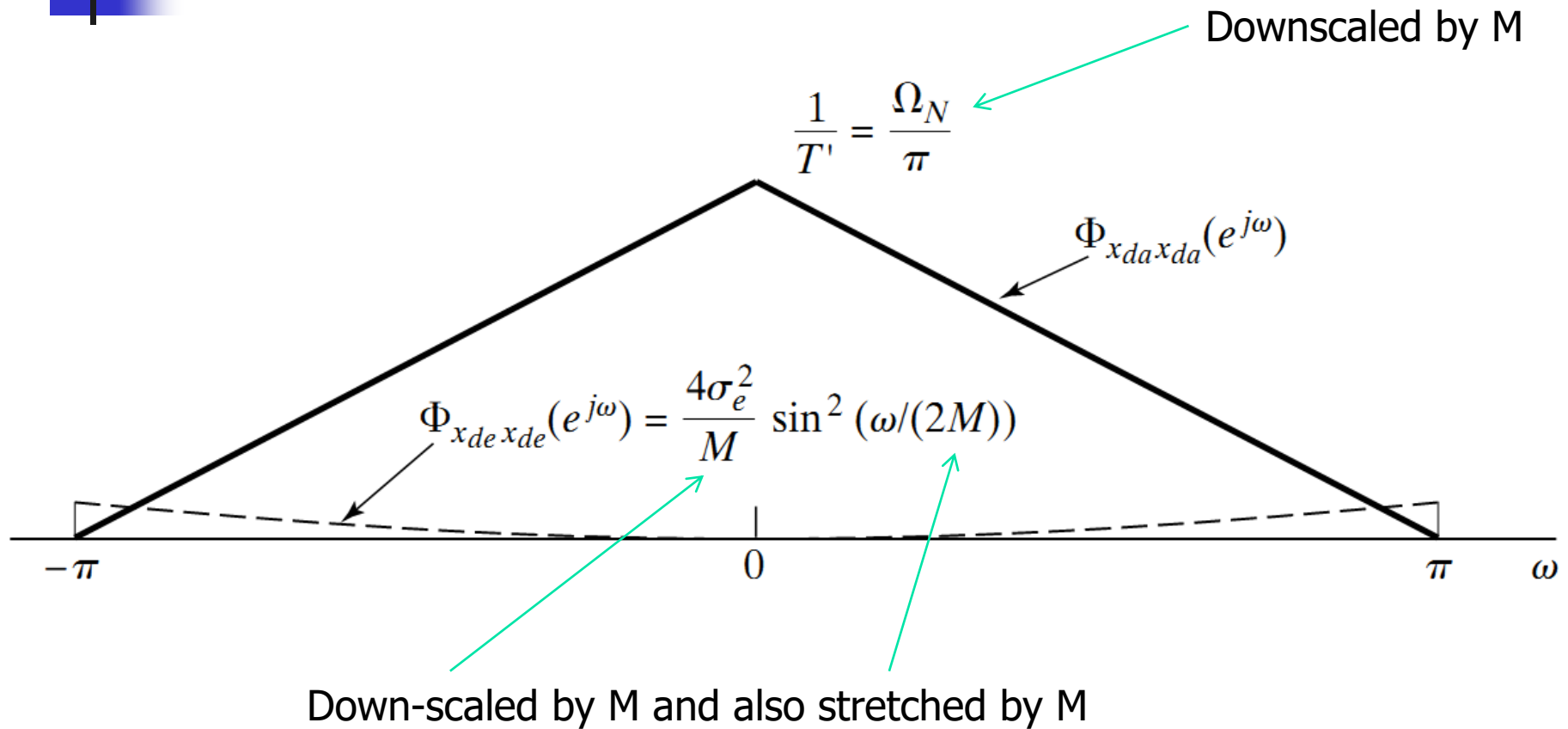
# Before decimation

Power spectral density  
of modified noise



The modified noise density is non-uniform and lower in the effective band region

# After decimation





# Quantization-noise power

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- Hence, the quantization-noise power in the final output is

$$\begin{aligned} P_{de} &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \Phi_{x_{de}x_{de}}(e^{jw}) = \frac{1}{2\pi} \frac{4\Delta^2}{12M} \int_{-\pi}^{\pi} \sin\left(\frac{w}{2M}\right)^2 dw \\ &= \frac{1}{2\pi} \frac{\Delta^2}{12M} \int_{-\pi}^{\pi} \left(2 \sin\left(\frac{w}{2M}\right)\right)^2 dw \end{aligned}$$

- Assume that M is sufficiently large, we can approximate that

$$\sin\left(\frac{w}{2M}\right) \approx \frac{w}{2M}$$

# Bits and quantization tradeoff in noise shaping

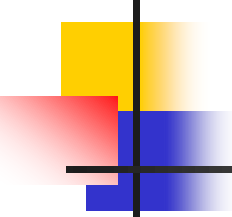
- With this approximation,

$$P_{de} = \frac{1}{36} \frac{\Delta^2 \pi^2}{M^3}$$

- For a (B+1)-bit quantizer and maximum input signal level between plus and minus  $X_m$ ,  $\Delta = X_m/2^B$ . To achieve a given quantization-noise power  $P_{de}$ , we have

$$B = -\frac{3}{2} \log_2 M + \frac{1}{2} \log_2 (\pi / 6) - \frac{1}{2} \log_2 P_{de} + \log_2 X_m$$

- We see that, whereas with direct quantization a doubling of the oversampling ratio  $M$  gained  $1/2$  bit in quantization, the use of noise shaping results in a gain of 1.5 bits.

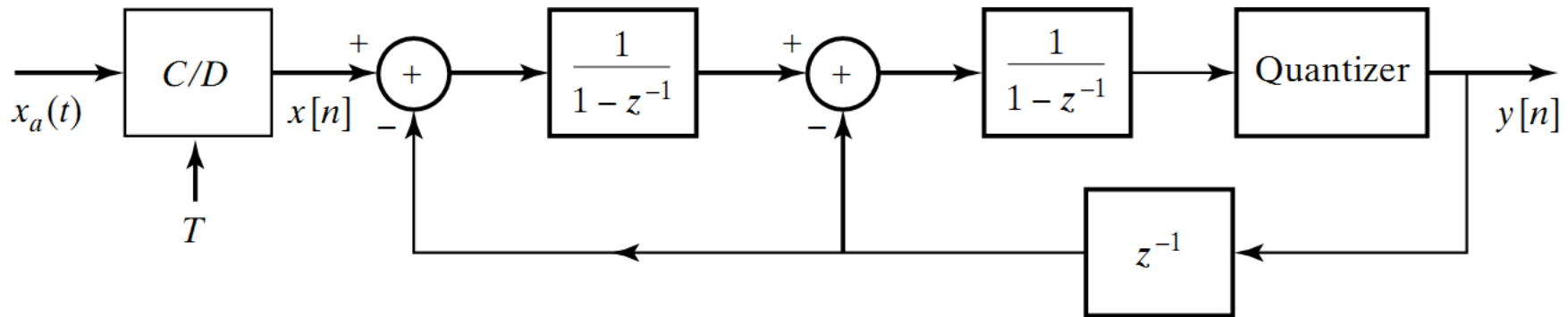


**TABLE 4.1** EQUIVALENT SAVINGS IN  
QUANTIZER BITS RELATIVE TO  $M = 1$  FOR  
DIRECT QUANTIZATION AND FIRST-ORDER  
NOISE SHAPING

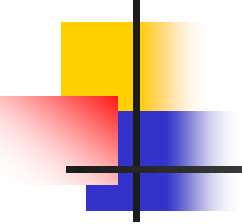
M	Direct quantization	Noise shaping
4	1	2.2
8	1.5	3.7
16	2	5.1
32	2.5	6.6
64	3	8.1

# Second-order noise shaping

- The noise-shaping strategy can be extended by incorporating a second stage of accumulation, as shown in the following:



**Figure 4.66** Oversampled quantizer with second-order noise shaping.



# Second-order (i.e., 2-stage) noise shaping

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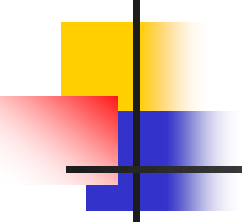
- In the two-stage case, it can be derived that

$$H_e(z) = (1 - z^{-1})^2$$

$$\phi_{\hat{e}\hat{e}}(e^{jw}) = \sigma_e^2 (2 \sin(w/2))^4$$

- In general, if we extend the case to p-stages, the corresponding noise shaping is given by

$$\phi_{\hat{e}\hat{e}}(e^{jw}) = \sigma_e^2 (2 \sin(w/2))^{2p}$$

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- By evaluation, with  $p=2$  and  $M=64$ , we obtain almost 13 bits of increase in accuracy, suggesting that a 1-bit quantizer could achieve about 14-bit accuracy at the output of the decimator.
  - Noise shaping can be employed for audio signal recording.
  - Although multiple feedback loops promise greatly increased quantization-noise reduction, for large values of  $p$ , there is an increased potential for instability and oscillations to occur.