
Algorithm 1 Training

- 1: **repeat**
- 2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$
- 3: $t \sim \text{Uniform}(\{1, \dots, T\})$
- 4: $\boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 5: Take gradient descent step on

$$\nabla_{\theta} \left\| \boldsymbol{\epsilon} - \boldsymbol{\epsilon}_{\theta} \left(\sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \boldsymbol{\epsilon}, t \right) \right\|^2$$

- 6: **until** converged
-

Algorithm 2 Sampling

- 1: $\mathbf{x}_t \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
 - 2: **for** $t = T, \dots, 1$ **do**
 - 3: $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ *if* $t > 1$, *else* $\mathbf{z} = \mathbf{0}$
 - 4: $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1-\alpha_t}{\sqrt{1-\alpha_t}} \boldsymbol{\epsilon}_{\theta}(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$
 - 5: **end for**
 - 6: **return** \mathbf{x}_0
-