

BSD 4.3 Sockets API Compliancy Wrapper for NetX

User Guide

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Chapter 1

Introduction to NetX BSD

The BSD Sockets API Compliancy Wrapper supports some of the basic BSD Sockets API calls with some limitations and utilizes NetX primitives underneath. This BSD Sockets API compatibility layer should perform as fast or slightly faster than typical BSD implementations, since this Wrapper utilizes internal NetX primitives and bypasses basic NetX error checking.

BSD Sockets API Compliancy Wrapper Source

The BSD Wrapper source code is designed for simplicity and is comprised of only two files, <u>nx_bsd.h</u> and <u>nx_bsd.c</u>. The <u>nx_bsd.h</u> file defines all the necessary BSD Sockets API Wrapper constants and subroutine prototypes, while <u>nx_bsd.c</u> contains the actual BSD Sockets API compatibility source code. These BSD Wrapper source files are common to all NetX support packages.

The package consists of:

nx_bsd.c: Wrapper source code nx bsd.h: Main header file

Sample demo programs:

bsd_demo_tcp.c

Demo with a single TCP server and client
bsd_demo_udp.c

Demo with two UDP clients and a UDP server

Chapter 2

Installation and Use of NetX BSD

This chapter contains a description of various issues related to installation, setup, and usage of the NetX BSD component.

Product Distribution

NetX BSD is shipped on a single CD-ROM compatible disk. The package includes two source files and a PDF file that contains this document, as follows:

nx_bsd.hHeader file for NetX BSDnx_bsd.cC Source file for NetX BSDnx_bsd.pdfUser Guide for NetX BSD

Demo files: bsd_demo_tcp.c

bsd_demo_udp.c

NetX BSD Installation

In order to use NetX BSD the entire distribution mentioned previously should be copied to the same directory where NetX is installed. For example, if NetX is installed in the directory "\threadx\arm7\green" then the nx_bsd.h and nx_bsd.c files should be copied into this directory.

Building the ThreadX and NetX components of a BSD Application

ThreadX

The ThreadX library must define bsd_errno in the thread local storage. We recommend the following procedure:

1. In *tx_port.h*, set one of the TX_THREAD_EXTENSION macros as follows:

2. Rebuild the ThreadX library.

Note that if TX_THREAD_EXTENSION_3 is already used, the user is free to use one of the other TX_THREAD_EXTENSION macros.

NetX

Before using NetX BSD Services, the NetX library must be built with NX_ENABLE_EXTENDED_NOTIFY_SUPPORT defined (e.g. in *nx_user.h*). By default it is not defined.

Using NetX BSD

Using BSD for NetX is easy. Basically, the application code must include $nx_bsd.h$ after it includes $tx_api.h$ and $nx_api.h$, in order to use ThreadX and NetX, respectively. Once $nx_bsd.h$ is included, the application code is then able to use the BSD services specified later in this guide. The application must also include $nx_bsd.c$ in the build process. This file must be compiled in the same manner as other application files and its object form must be linked along with the files of the application. This is all that is required to use NetX BSD.

To utilize NetX BSD services, the application must create an IP instance, a packet pool, and initialize BSD services by calling *bsd_initialize*. This is demonstrated in the "Small Example" section later in this guide. The prototype is shown below:

The last three parameters are used for creating a thread for performing periodic tasks such as checking for TCP events and define the thread stack space.

Note: in contrast to BSD sockets, which work in network bye order, NetX works in the host byte order of the host processor. For source compatibility reasons, the macros htons(), ntohs(), htonl(), ntohl() have been defined, but do not modify the argument passed.

NetX BSD Limitations

Due to performance and architecture issues, NetX BSD does not support all the BSD 4.3 socket features:

INT flags are not supported for send, recv, sendto and recvfrom calls.

NetX BSD with DNS Support

If NX_BSD_ENABLE_DNS is defined, NetX BSD can send DNS queries to obtain hostname or host IP information. This feature requires a NetX DNS Client to be previously created using the *nx_dns_create* service. One or more known DNS server IP addresses must be registered with the DNS instance using the *nx_dns_server_add* for adding server addresses.

DNS services and memory allocation are used by *getaddrinfo* and *getnameinfo* services:

INT getaddrinfo(const CHAR *node, const CHAR *service, const struct addrinfo *hints, struct addrinfo **res)

INT getnameinfo(const struct sockaddr *sa, socklen_t salen, char *host, size_t hostlen, char *serv, size_t servlen, int flags)

When the BSD application calls *getaddrinfo* with a hostname, NetX BSD will call any of the below services to obtain the IP address:

- nx_dns_ipv4_address_by_name_get
- nx_dns_cname_get

For *nx_dns_ipv4_address_by_name_get*, NetX BSD uses the ipv4_addr_buffer memory areas. The size of these buffers are defined by (NX_BSD_IPV4_ADDR_PER_HOST * 4).

For returning address information from *getaddrinfo*, NetX BSD uses the ThreadX block memory table nx_bsd_addrinfo_pool_memory, whose memory area is defined by another set of configurable options, NX_BSD_IPV4_ADDR_MAX_NUM.

See **Configuration Options** for more details on the above configuration options.

Additionally, if NX_DNS_ENABLE_EXTENDED_RR_TYPES is defined, and the host input is a canonical name, NetX BSD will allocate memory dynamically from a previously created block pool _nx_bsd_cname_block_pool

Note that after calling *getaddrinfo* the BSD application is responsible for releasing the memory pointed to by the res argument back to the block table using the *freeaddrinfo* service.

Configuration Options

User configurable options in *nx_bsd.h* allow the application to fine tune NetX BSD sockets for its particular requirements. The following is a list of these parameters:

Define	Meaning
NX_BSD_TCP_WINDOW	Used in TCP socket create calls. 65535 is a typical window size for 100Mb Ethernet. The default value is 65535.
NX_BSD_SOCKFD_START	This is the logical index for the BSD socket file descriptor start value. By default this option is 32.
NX_BSD_MAX_SOCKETS	Specifies the maximum number of total sockets available in the BSD layer and must be a multiple of 32. The value is defaulted to 32.
NX_BSD_SOCKET_QUEUE_MAX	Specifies the maximum number of UDP packets stored on the receive socket queue. The value is defaulted to 5.
NX_BSD_MAX_LISTEN_BACKLOG	This specifies the size of the listen queue ('backlog') for BSD TCP sockets. The default value is 5.
NX_MICROSECOND_PER_CPU_TICK	Specifies the number of microseconds per timer interrupt

NX_BSD_TIMEOUT

Specifies the timeout in timer ticks on NetX internal calls required by BSD. The default value is 20*NX_IP_PERIODIC_RATE.

NX_BSD_TCP_SOCKET_DISCONNECT_TIMEOUT

Specifies the timeout in timer ticks on NetX disconnect call. The default value is 1.

NX BSD PRINT ERRORS

If set, the error status return of a BSD function returns a line number and type of error e.g. NX_SOC_ERROR where the error occurs. This requires the application developer to define the debug output. The default setting is disabled and no debug output is specified in *nx_bsd.h*

NX_BSD_TIMER_RATE Interval after which BSD periodic

timer task runs. The default

value is 1 second (1 * NX_IP_PERIODIC_RATE).

NX_BSD_TIMEOUT_PROCESS_IN_TIMER If set, this option allows the BSD

timeout process to execute in the system timer context. The default behavior is disabled. This feature is described in more detail in Chapter 2 "Installation and Use of

NetX BSD".

NX BSD ENABLE DNS If enabled, NetX BSD will send a

DNS query for a hostname or host IP address. Requires a DNS Client instance to be previously created and started. By default it

is not enabled.

NX_BSD_IPV4_ADDR_MAX_NUM

Maximum number of IPv4 addresses returned by *getaddrinfo*. This along with NX_BSD_IPV4_ADDR_MAX_NUM defines the size of the NetX BSD block pool

nx_bsd_addrinfo_block_pool for dynamically allocating memory to address information storage in *getaddrinfo*. The default value is 5.

NX_BSD_IPV4_ADDR_PER_HOST

Defines maximum IPv4 addresses stored per DNS query. The default value is 5.

The following list of NetX BSD socket options can be enabled (or disabled) at run time on a per socket basis using the *setsockopt* service:

There are two different settings for option_level.

The first type of run time socket options is SOL_SOCKET for socket level options. To enable a socket level option, call *setsockopt* with option_level set to SOL_SOCKET and option_name set to the specific option e.g. SO_BROADCAST. To retrieve an option setting, call *getsockopt* for the option_name with option_level again set to SOL_SOCKET.

The list of run time socket level options is shown below.

SO_BROADCAST	If set, this enables sending and

receiving broadcast packets from Netx sockets. This is the default behavior for NetX. All sockets

have this capability.

SO ERROR Used to obtain socket status on

the previous socket operation of the specified socket, using the getsockopt service. All sockets

have this capability.

SO KEEPALIVE If set, this enables the TCP Keep

Alive feature. This requires the NetX library to be built with NX_TCP_ENABLE_KEEPALIVE

defined in *nx_user.h*. By default

this feature is disabled.

SO_RCVTIMEO This sets the wait option in

seconds for receiving packets on NetX BSD sockets. The default value is the NX_WAIT_FOREVER (0xFFFFFFFF) or, if non-blocking is enabled, NX_NO_WAIT (0x0).

SO_RCVBUF This sets the window size of the

TCP socket. The default value,

NX_BSD_TCP_WINDOW, is set to 64k for BSD TCP sockets. To set the size over 65535 requires the NetX library to be built with

the

NX_TCP_ENABLE_WINDOW_SCALING

be defined.

SO_REUSEADDR If set, this enables multiple

sockets to be mapped to one port. The typical usage is for the TCP Server socket. This is the default behavior of NetX sockets.

The second type of run time socket options is the IP option level. To enable an IP level option, call *setsockopt* with option_level set to IP_PROTO and option_name set to the option e.g. IP_MULTICAST_TTL. To retrieve an option setting, call *getsockopt* for the option_name with option_level again set to IP_PROTO.

The list of run time IP level options is shown below.

IP_MULTICAST_TTL This sets the time to live for UDP

sockets. The default value is NX_IP_TIME_TO_LIVE (0x80) when the socket is created. This value can be overridden by calling setsockopt with this socket

option.

IP_ADD_MEMBERSHIP If set, this options enables the

BSD socket (applies only to UDP sockets) to join the specified

IGMP group.

IP_DROP_MEMBERSHIP If set, this options enables the

BSD socket (applies only to UDP sockets) to leave the specified

IGMP group.

Small Example System

An example of how to use NetX BSD is shown in Figure 1.0 below. In this example, the include file $nx_bsd.h$ is brought in at line 7. Next, the IP instance bsd_ip and packet pool bsd_pool are created as global variables at line 20 and 21. Note that this demo uses a ram (virtual) network driver (line 41). The client and server will share the same IP address on single IP instance in this example.

The client and server threads are created on line 303 and 309 in $tx_application_define$ which sets up the application and is defined on lines 293-361. After IP instance successful creation on line 327, the IP instance is enabled for TCP services on line 350. The last requirement before BSD services can be used is to call $bsd_initialize$ on line 360 to set up all data structures and NetX, and ThreadX resources needed by BSD.

In the server thread entry function, *thread_1_entry*, which is defined on lines 381-397, the application waits for the driver to initialize NetX with network parameters. Once this is done, it calls *tcpServer*, defined on lines 146-253, to handle the details of setting up the TCP server socket.

tcpServer creates the master socket by calling the socket service on line 159 and binds it to the listening socket using the bind call on line 176. It is then configured for listening for connection requests on line 191. Note that the master socket does not accept a connection request. It runs in a continuous loop which calls select each time to detect connection requests. A secondary BSD socket chosen from an array of BSD sockets is assigned the connection request after calling the accept service on line 218.

On the Client side, the client thread entry function, *thread_0_entry*, defined on lines 366-377, should also wait for NetX to be initialized by the driver. Here we just wait for the server side to do so. It then calls *tcpClient* defined on line 54-142, to handle the details of setting up the TCP client socket and requesting a TCP connection.

The TCP client socket is created on line 68. The socket is bound to the specified IP address and attempts to connect to the TCP server by calling *connect* on line 84. It is now ready to begin sending and receiving packets.

```
/* This is a small demo of BSD Wrapper for the high-performance NetX TCP/IP stack.
This demo demonstrate TCP connection, disconnection, sending, and receiving using ARP and a simulated Ethernet driver. */

#include "tx_api.h"
#include "nx_api.h"
#include "nx_bsd.h"
#include "string.h>
#include <stdlib.h>
```

```
11
12
      #define
                             DEMO_STACK_SIZE
                                                        (16*1024)
13
14
      /* Define the ThreadX and NetX object control blocks... */
15
16
      TX_THREAD
                             thread_0;
17
18
      TX_THREAD
                             thread_1;
19
20
21
      NX_PACKET_POOL
                             bsd_pool;
      NX_IP
                             bsd_ip;
22
23
24
      /* Define the counters used in the demo application... */
25
26
27
      ULONG
                             error_counter;
28
29
30
       31
32
33
34
35
36
37
38
39
40
41
42
      /* Define thread prototypes. */
                             thread_0_entry(ULONG thread_input);
thread_1_entry(ULONG thread_input);
      VOTD
      VOID
      VOTD
                             tcpClient(CHAR *msg0);
                             tcpServer(VOID);
HandleClient(INT sock);
      VOID
      INT
      VOID
                             _nx_ram_network_driver(struct NX_IP_DRIVER_STRUCT *driver_req);
43
44
45
      /* Define main entry point. */
46
      int main()
47
48
49
             /* Enter the ThreadX kernel. */
50
51
52
            tx_kernel_enter();
53
54
      VOID tcpClient(CHAR *msq0)
55
56
57
58
59
60
      INT
                       status, status1, send_counter;
                      sock_tcp_1,length,length1;
sockaddr_in echoServAddr;
sockaddr_in localAddr;
sockaddr_in remoteAddr;
      INT
                                                                             /* Echo server address */
/* Local address */
      struct
      struct
61
                                                                             /* Remote address */
      struct
62
63
      UINT
                                                                             /* Echo Server Port */
                        echoServPort:
                        rcvBuffer1[32];
64
      CHAR
65
66
            /* Create BSD TCP Socket */
67
            sock_tcp_1 = socket( PF_INET, SOCK_STREAM, IPPROTO_TCP);
if (sock_tcp_1 == -1)
68
69
70
71
72
                 printf("\nError: BSD TCP Client socket create \n");
                 return:
73
74
75
76
77
78
            }
            printf("\nBSD TCP Client socket created %lu \n", sock_tcp_1); /* Fill destination port and IP address */
            echoServPort = 12;
           memset(&echoservAddr, 0, sizeof(echoservAddr));
echoservAddr.sin_family = PF_INET;
echoservAddr.sin_addr.s_addr = htonl(0x01020304);
echoservAddr.sin_port = echoservPort;
79
80
81
82
83
            ^{\primest} Now connect this client the server ^{st}/
84
            status1 = connect(sock_tcp_1, (struct sockaddr *)&echoServAddr,
                                   sizeof(echoServAddr));
            /* Check for error
if (status1 != OK)
                Check for error.
86
87
                 printf("\nError: BSD TCP Client socket Connect, %d \n",sock_tcp_1);
                 status = soc_close(sock_tcp_1);
if (status != ERROR)
```

```
91
92
                   printf("\nConnect ERROR so BSD Client Socket Closed: %d\n",sock_tcp_1);
               else
93
                   printf("\nError: BSD Client Socket close %d\n", sock_tcp_1);
               return;
94
95
          }
          /* Get and print source and destination information */
printf("\nBSD TCP Client socket: %d connected \n", soc
96
97
                   '\nBSD TCP Client socket: %d connected \n", sock_tcp_1);
98
          99
100
          status = getpeername( sock_tcp_1, (struct sockaddr *) &remoteAddr, &length1);
printf("Remote port = %lu, Remote IP = %lu \n", remoteAddr.sin_port,
101
102
                   remoteAddr.sin_addr.s_addr);
103
104
          send_counter = 1;
105
106
          /* Now receive the echoed packet from the server */
          while(1)
107
108
109
               tx_thread_sleep(2);
110
               111
112
113
               status = send(sock_tcp_1,msg0, ( strlen(msg0)+1), 0);
               if (status == ERROR)
    printf("Error: BSD Client Socket send %d\n",sock_tcp_1);
114
115
116
                   printf("\nMessage sent: %s\n", msg0);
117
118
                    send_counter++;
119
              }
120
121
               status = recv(sock_tcp_1, (VOID *)rcvBuffer1, 31,0);
122
                   (status == 0)
123
                   break;
124
125
               rcvBuffer1[status] = 0;
126
               if (status != ERROR)
    printf("\nBSD Client Socket: %d received %lu bytes: %s ",
128
                             sock_tcp_1,strlen(rcvBuffer1),rcvBuffer1);
129
130
                   printf("\nError: BSD Client Socket receive %d \n",sock_tcp_1);
131
132
133
          }
          /* close this client socket */
status = soc_close(sock_tcp_1);
if (status != ERROR)
    printf("\nBSD Client Socket Closed %d\n",sock_tcp_1);
134
135
136
137
138
          else
139
               printf("\nError: BSD Client Socket close %d \n", sock_tcp_1);
140
141
142
          /* End */
     }
143
144
145
     void tcpServer(void)
146
147
148
149
     INT
                    status, status1, sock, sock_tcp_2, i;
                   sockaddr_in echoServAddr;
sockaddr_in ClientAddr;
                                                                  /* Echo server address */
150
     struct
151
     struct
152
153
154
                   Clientlen;
     UINT
                   echoServPort;
                                                                 /* Echo Server Port */
155
156
157
                   maxfd;
158
          /* Create BSD TCP Server Socket */
          sock_tcp_2 = socket( PF_INET, SOCK_STREAM, IPPROTO_TCP);
if (sock_tcp_2 == -1)
159
160
161
          {
162
               printf("Error: BSD TCP Server socket create\n");
163
               return;
164
          }
```

```
165
          else
               printf("BSD TCP Server socket created \n");
166
167
168
          /* Now fill server side information */
169
          echoServPort = 12;
          memset(&echoservAddr, 0, sizeof(echoServAddr));
echoServAddr.sin_family = PF_INET;
echoServAddr.sin_addr.s_addr = htonl(0x01020304);
170
171
172
173
          echoServAddr.sin_port = echoServPort;
174
175
          /* Bind this server socket */
          176
177
          if (status < 0)
178
          {
179
               printf("Error: BSD TCP Server Socket Bind \n");
180
               return:
181
182
          élse
               printf("BSD TCP Server Socket bound \n");
183
184
185
          FD_ZERO(&master_list);
186
          FD_ZERO(&read_ready)
187
          FD_SET(sock_tcp_2,&master_list);
188
          maxfd = sock_tcp_2;
189
190
          /* Now listen for any client connections for this server socket */
191
192
          status = listen(sock_tcp_2,5);
          if (status < 0)
193
               printf("Error: BSD TCP Server Socket Listen\n");
194
195
               return:
196
197
                                                                         ");
198
               printf("BSD TCP Server Socket Listen complete,
199
          /* All set to accept client connections */
printf("Now accepting client connections\n");
200
201
202
203
          /* Loop to create and establish server connections. */
204
          while(1)
205
          {
206
207
               read_ready = master_list;
208
               tx_thread_sleep(2); /* Allow some time to other threads too */
status = select(maxfd+1,&read_ready,0,0,0);
209
210
               if (status == ERROR)
211
               {
212
213
                   continue:
               }
214
215
               status = FD_ISSET(sock_tcp_2,&read_ready);
216
               if(status)
217
                   sock = accept(sock_tcp_2,(struct sockaddr*)&ClientAddr, &Clientlen);
218
219
220
221
222
                   /* Add this new connection to our master list */
FD_SET(sock,&master_list);
                   if ( sock > maxfd)
223
224
225
                        maxfd = sock;
                   }
226
227
                   continue;
228
               for (i = 0; i < (maxfd+1); i++)
229
230
231
                   if (( i != sock_tcp_2) && (FD_ISSET(i,&master_list)) &&
                        (FD_ISSET(i,&read_ready)))
232
233
                        status1 = HandleClient(i);
234
                        if (status1 == 0)
235
                        {
236
                             status1 = soc_close(i);
237
                             if (status1 == OK)
                             {
239
                                 FD_CLR(i,&master_list);
printf("\nBSD Server Socket:%d closed\n",i);
240
241
242
                             else
                                 printf("\nError:BSD Server Socket:%d close\n",i);
```

```
244
245
                    }
246
                 }
247
248
249
             /* Loop back to check any next client connection */
250
251
         } /* While(1) ends */
252
253
254
    }
255
256
257
                  rcvBuffer[128];
    CHAR
    INT
            HandleClient(INT sock)
258
    {
259
260
    INT
                 status;
261
262
        status = recv(sock, (VOID *)rcvBuffer, 128,0);
if (status == ERROR )
263
264
265
266
             printf("\n BSD Server Socket:%d receive \n", sock);
267
             return(ERROR);
268
269
270
271
272
        }
         /* a zero return from a recv() call indicates client is terminated! */ if (status == 0)  
273
274
275
             /* Done with this client , close this secondary server socket */
             return(status);
        }
276
        277
278
279
         /* And echo the same data to the client */
280
281
         status = send(sock,rcvBuffer, ( strlen(rcvBuffer)+1), 0);
282
         if (status == ERROR )
283
284
             printf("\nError: BSD Server Socket:%d send \n", sock);
285
286
             return(ERROR);
287
         return(status);
288
289
290
291
292
    /* Define what the initial system looks like. */
293
            tx_application_define(void *first_unused_memory)
    void
294
295
296
    CHAR
             *pointer;
297
    UINT
            status;
298
        /* Setup the working pointer. */
pointer = (CHAR *) first_unused_memory;
299
300
301
        302
303
304
305
306
         pointer = pointer + DEMO_STACK_SIZE;
307
         308
309
310
311
312
         pointer = pointer + DEMO_STACK_SIZE;
313
314
         /* Initialize the NetX system. */
315
         nx_system_initialize();
316
         /* Create a BSD packet pool.
         status = nx_packet_pool_create(&bsd_pool, "NetX BSD Packet Pool", 128,
318
                                         pointer, 16384);
        pointer = pointer + 16384;
if (status)
319
320
             error_counter++;
```

```
323
324
               printf("Error in creating BSD packet pool\n!");
          }
325
          326
329
          pointer = pointer + 2048;
330
331
          if (status)
332
333
          {
               error_counter++;
printf("Error creating BSD IP instance\n!");
334
335
336
337
          /* Enable ARP and supply ARP cache memory for BSD IP Instance */
status = nx_arp_enable(&bsd_ip, (void *) pointer, 1024);
pointer = pointer + 1024;
338
339
340
          /* Check ARP enable status. */
if (status)
341
342
343
344
               error_counter++;
printf("Error in Enable ARP and supply ARP cache memory to BSD IP
345
                        instance\n");
346
347
348
          /* Enable TCP processing for BSD IP instances. */
349
350
          status = nx_tcp_enable(&bsd_ip);
351
          /* Check TCP enable status. */
352
          if (status)
353
354
          {
355
               error_counter++;
printf("Error in Enable TCP \n");
356
357
358
359
          /* Now initialize BSD Scoket Wrapper */
360
          status = bsd_initialize(&bsd_ip, &bsd_pool,pointer, 2048, 1);
361
362
363
364
     /* Define the test threads. */
365
366
     void
               thread_0_entry(ULONG thread_input)
367
     {
368
               *msg0 = "Client 1:
     CHAR
                        "ABCDEFGHIJKLMNOPQRSTUVWXYZ<>ABCDEFGHIJKLMNOPQRSTUVWXYZ<> \
                        "ABCDEFGHIJKLMNOPQRSTUVWXYZ<>END";
370
371
          /* Wait till Server side is all set */
372
          tx_thread_sleep(2);
373
          while (1)
374
          {
375
               tcpClient(msg0);
376
               tx_thread_sleep(1);
          }
377
378
379
     }
     /* Define the server thread entry function. */
void thread_1_entry(ULONG thread_input)
380
381
382
383
384
     UINT
               status;
               actual_status;
385
     ULONG
386
          /* Ensure the IP instance has been initialized. */
status = nx_ip_status_check(&bsd_ip, NX_IP_INITIALIZE_DONE, &actual_status,
387
388
100);
389
390
          /* Check status... */
          if (status != NX_SUCCESS)
391
392
          {
393
               error_counter++;
394
               return;
395
396
           /* Start a TCP Server */
          tcpServer();
```

398 }

Chapter 3

NetX BSD Services

This chapter contains a description of all NetX BSD basic services listed below in alphabetic order.

```
INT accept(INT sockID, struct sockaddr *ClientAddress, INT *addressLength);
INT bind (INT sockID, struct sockaddr *localAddress, INT addressLength);
INT bsd_initialize(NX_IP *default_ip, NX_PACKET_POOL *default_pool, CHAR
                 *bsd thread stack area, ULONG bsd thread stack size,
                 UINT bsd thread priority);
INT connect(INT sockID, struct sockaddr *remoteAddress, INT addressLength);
INT getpeername(INT sockID, struct sockaddr *remoteAddress, INT *addressLength);
INT getsockname(INT sockID, struct sockaddr *localAddress, INT *addressLength);
INT ioctl(INT sockID, INT command, INT *result);
in addr tinet addr(const CHAR *buffer);
INT inet_aton(const CHAR *cp_arg, struct in_addr *addr);
CHAR inet_ntoa(struct in_addr address_to_convert);
const CHAR *inet_ntop(INT af, const VOID *src, CHAR *dst, socklen_t size);
INT inet_pton(INT af, const CHAR *src, VOID *dst);
INT listen(INT sockID, INT backlog);
INT recvfrom(INT sockID, CHAR *buffer, INT buffersize, INT flags,
             struct sockaddr *fromAddr, INT *fromAddrLen);
INT recv(INT sockID, VOID *rcvBuffer, INT bufferLength, INT flags);
INT sendto(INT sockID, CHAR *msg, INT msgLength, INT flags,
            struct sockaddr *destAddr, INT destAddrLen);
INT send(INT sockID, const CHAR *msg, INT msgLength, INT flags);
INT select(INT nfds, fd_set *readfds, fd_set *writefds, fd_set *exceptfds,
           struct timeval *timeout):
INT soc_close ( INT sockID);
```

INT socket(INT protocolFamily, INT type, INT protocol);

INT fcntl(INT sock_ID, UINT flag_type, UINT f_options);

INT getaddrinfo(const CHAR *node, const CHAR *service, const struct addrinfo *hints, struct addrinfo **res);

VOID freeaddrinfo(struct addrinfo *res);

VOID nx_bsd_set_service_list(struct NX_BSD_SERVICE_LIST *serv_list_ptr, ULONG serv_list_len);

VOID FD_SET(INT fd, fd_set *fdset);

VOID FD_CLR(INT fd, fd_set *fdset);

INT FD_ISSET(INT fd, fd_set *fdset);

VOID FD_ZERO (fd_set *fdset);