

## **BSD 4.3 Socket API Wrapper for NetX Duo**

# **User Guide**

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# **Chapter 1**

## Introduction to NetX Duo BSD

The BSD Socket API Compliancy Wrapper supports some of the basic BSD Socket API calls, with some limitations and utilizes NetX Duo primitives underneath.

## **BSD Socket API Compliancy Wrapper Source**

The Wrapper source code is designed for simplicity and is comprised of two files, namely  $nxd\_bsd.h$  and  $nxd\_bsd.c$ . The  $nxd\_bsd.h$  file defines all the necessary BSD Socket API wrapper constants and subroutine prototypes, while  $nxd\_bsd.c$  contains the actual BSD Socket API compatibility source code. These Wrapper source files are common to all NetX Duo support packages.

### The package consists of:

nxd\_bsd.c: Wrapper source code

nxd\_bsd.h: Main header file

### Sample demo programs:

bsd\_demo\_udp.c

Demo with two UDP peers (IPv4 only)

bsd\_demo\_tcp.c

Demo with a single TCP server and client

bsd\_demo\_raw.c

Demo with two RAW peers

## **Chapter 2**

## Installation and Use of NetX Duo BSD

This chapter contains a description of various issues related to installation, setup, and usage of the NetX Duo BSD component.

#### **Product Distribution**

NetX Duo BSD is shipped on a single CD-ROM compatible disk. The package includes two source files and a PDF file that contains this document, as follows:

nxd\_bsd.hHeader file for NetX Duo BSDnxd\_bsd.cC Source file for NetX Duo BSDnxd\_bsd.pdfUser Guide for NetX Duo BSD

Demo files:

bsd\_demo\_udp.c bsd\_demo\_tcp.c bsd\_demo\_raw.c

#### **NetX Duo BSD Installation**

In order to use NetX Duo BSD the entire distribution mentioned previously should be copied to the same directory where NetX Duo is installed. For example, if NetX Duo is installed in the directory "\threadx\arm7\green" then the nxd\_bsd.h and nxd\_bsd.c files should be copied into this directory.

## Building the ThreadX and NetX Duo components of a BSD Application

#### **ThreadX**

The ThreadX library must define bsd\_errno in the thread local storage. We recommend the following procedure:

1. In *tx\_port.h*, set one of the TX\_THREAD\_EXTENSION macros as follows:

2. Rebuild the ThreadX library.

Note that if TX\_THREAD\_EXTENSION\_3 is already used, the user is free to use one of the other TX\_THREAD\_EXTENSION macros.

#### **NetX Duo**

Before using NetX Duo BSD Services, the NetX Duo library must be built with NX\_ENABLE\_EXTENDED\_NOTIFY\_SUPPORT defined. By default it is not defined. If the BSD raw sockets are to be used, the NetX Duo library must be built with NX\_ENABLE\_IP\_RAW\_PACKET\_FILTER defined.

## **Using NetX Duo BSD**

A NetX Duo BSD application project must include  $nxd\_bsd.h$  after it includes  $tx\_api.h$  and  $nx\_api.h$  to be able to use BSD services specified later in this guide. The application must also include  $nxd\_bsd.c$  in the build process. This file must be compiled in the same manner as other application files and its object form must be linked along with the files of the application. This is all that is required to use NetX Duo BSD.

To utilize NetX Duo BSD services, the application must create an IP instance, create a packet pool for the BSD layer to allocate packets from, allocate memory space for the internal BSD thread stack, and specify the priority of the internal BSD thread. The BSD layer is initialized by calling <code>bsd\_initialize</code> and passing in the parameters. This is demonstrated in the "Small Examples" later in this document but the prototype is shown below:

The default\_ip is the IP instance the BSD layer operates on. The default\_pool is used by the BSD services to allocate packets from. The next two parameters: bsd\_thread\_stack\_area, bsd\_thread\_stack\_size defines the stack area used by the internal BSD thread, and the last parameter, bsd\_thread\_priority, sets the priority of the thread.

#### **NetX Duo BSD Raw Socket Support**

NetX Duo BSD also supports raw sockets. To use raw sockets in NetX Duo BSD, the NetX Duo library must be compiled with NX\_ENABLE\_IP\_RAW\_PACKET\_FILTER defined. By default it is not defined. The application must then enable raw socket processing for a previously created IP instance by calling *nx\_ip\_raw\_packet\_enable*.

To create a raw socket in NetX Duo BSD, the application uses the socket create service *socket* and specifies the protocol family, socket type and protocol:

sock\_1 = socket(INT protocolFamily, INT socket\_type, INT protocol)

protocolFamily is AF\_INET for IPv4 sockets, or AF\_INET6 for IPv6 sockets, assuming IPv6 is enabled on the IP instance. The socket\_type must be set to SOCK\_RAW. protocol is application specific.

To send and receive raw packets as well as close a raw socket, the application typically uses the same BSD services as for UDP e.g. *sendto, recvfrom, select* and *soc\_close*. Raw sockets do not support either *accept* or *listen* BSD services.

- By default, received IPv4 raw data includes the IPv4 header. Conversely, received IPv6 raw data does not include the IPv6 header.
- By default, when sending either raw IPv6 or IPv4 packets, the BSD wrapper layer adds the IPv6 or IPv4 header before sending the data.

NetX Duo BSD supports additional raw socket options, including IP\_RAW\_RX\_NO\_HEADER, IP\_HDRINCL and IP\_RAW\_IPV6\_HDRINCL.

If IP\_RAW\_RX\_NO\_HEADER is set, the IPv4 header is removed so that the received data does not contain the IPv4 header, and the reported message length does not include the IPv4 header. For IPv6 sockets, by default the raw socket receive does not include IPv6 header, equivalent to having the IP\_RAW\_RX\_NO\_HEADER option set. Application may use the setsockopt service to clear the IP\_RAW\_RX\_NO\_HEADER option, Once the IP\_RAW\_RX\_NO\_HEADER option is cleared, the received IPv6 raw data would include the IPv6 header, and the reported message length includes the IPv6 header.

This option has no effect on IPv4 or IPv6 transmitted data.

If IP\_HDRINCL is set, the application includes the IPv4 header when sending data. This option has no effect on IPv6 transmission and is not defined by default. If IP RAW IPv6 HDRINCL is set, the application includes

the IPv6 header when sending data. This option has no effect on IPv4 transmission and is not defined by default.

IP\_HDRINCL and IP\_RAW\_IPV6\_HDRINCL have no effect on IPv4 or IPv6 reception.

**Note!** The BSD 4.3 Socket specification specifies that the kernel must copy the raw packet to each socket receive buffer. However in NetX Duo BSD, if multiple sockets are created sharing the same protocol, the behavior is undefined.

## **NetX Duo BSD Raw Packet Support**

To enable the raw packet support for PPPoE, NetX Duo BSD wrapper needs to be built with NX\_BSD\_RAW\_PPPOE\_SUPPORT enabled.

The following command creates a BSD socket to handle PPPoE raw packets:

```
Sockfd = socket(AF PACKET, SOCK RAW, protocol);
```

The current BSD implementation only supports two protocol types in AF\_PACKET family

- ETHERTYPE\_PPPOE\_DISC PPPoE Discovery packets. In the MAC data frame, the Discovery packets have the Ethernet frame type 0x8863.
- ETHERTYPE\_PPPOE\_SESS

  PPP Session packets. In the MAC data frame, the Session packets have the Ethernet frame type 0x8864.

The structure <code>sockaddr\_ll</code> is used to specify parameters when sending or receiving PPPoE frames.

Note that not every field in the structure is used by sendto() or recvfrom(). See the description below on how to set up the  $sockaddr_ll$  for sending and receiving PPPoE packets.

Socket created in the AF\_PACKET family can be used to send either PPPoE Discovery packets or PPP session packets, regardless of the protocol specified. When transmitting a PPPoE packet, application must prepare the buffer that includes properly formatted PPPoE frame, including the MAC headers (Destination MAC address, source MAC address, and frame type.) The size of the buffer includes the 14-byte Ethernet header.

The sockaddr\_ll struct, the sll\_ifindex is used to indicate the physical interface to be used for sending this packet. The rest of the fields in the structure are not used. Values set to the unused fields are ignored by the BSD internal process.

The following code block illustrates how to transmit a PPPoE packet:

The return value indicates the number of bytes transmitted. Since PPPoE packets are message-based, on a successful transmission, the number of bytes sent matches the size of the packet, including the 14-byte Ethernet header.

PPPoE packets can be received using recvfrom(). The receive buffer must be big enough to accommodate message of Ethernet MTU size. The received PPPoE packet includes 14-byte Ethernet header. On

receiving PPPoE packets, PPPoE Discovery packets can only be received by socket created with protocol <code>ETHERTYPE\_PPPOE\_DISC</code>. Similarly, PPP session packets can only be received by socket created with protocol <code>ETHERTYPE\_PPPOE\_SESS</code>. If multiple sockets are created for the same protocol type, arriving PPPoE packets are forwarded to the socket created first. If the first socket created for the protocol is closed, the next socket in the order of creation is used for receiving these packets.

After a PPPoE packet is received, the following fields in the sockaddr 11 struct are valid:

- sll\_family: Set by the BSD internal to be AF\_PACKET
- sll\_ifindex: Indicates the interface from which the packet is received
- sll\_protocol: Set to the type of packet received: ETHERTYPE\_PPPOE\_DISC or ETHERTYPE\_PPPOE\_SESS

## **Eliminating Internal BSD Thread**

By default, BSD utilizes an internal thread to perform some of its processing. In systems with tight memory constraints, BSD can be built with NX\_BSD\_TIMEOUT\_PROCESS\_IN\_TIMER defined, which eliminates the internal BSD thread and instead uses an internal timer to perform the same processing. This eliminates the memory required for the internal BSD thread control block and stack. However, overall timer processing is significantly increased and the BSD processing may also execute at a higher priority than needed.

To configure BSD sockets to run in the ThreadX timer context, define NX\_BSD\_TIMEOUT\_PROCESS\_IN\_TIMER in *nxd\_bsd.h*. If the BSD layer is configured to execute the BSD tasks in the timer context, in the call to *bsd\_initialize*, the following three parameters are ignored, and should be set to NULL:

- bsd\_thread\_stack\_area
- bsd\_thread\_stack\_size
- bsd\_thread\_priority

### **NetX Duo BSD with DNS Support**

If NX\_BSD\_ENABLE\_DNS is defined, NetX Duo BSD can send DNS queries to obtain hostname or host IP information. This feature requires a NetX DNS Client to be previously created using the *nx\_dns\_create* service. One or more known DNS server IP addresses must be registered with the DNS instance using the *nx\_dns\_server\_add* service for adding IPv4

server addresses, or using the *nxd\_dns\_server\_add* service for adding either IPv4 or IPv6 server addresses.

DNS services and memory allocation are used by *getaddrinfo* and *getnameinfo* services:

INT getaddrinfo(const CHAR \*node, const CHAR \*service, const struct addrinfo \*hints, struct addrinfo \*\*res)

INT getnameinfo(const struct sockaddr \*sa, socklen\_t salen, char \*host, size\_t hostlen, char \*serv, size\_t servlen, int flags)

When the BSD application calls *getaddrinfo* with a hostname, NetX BSD will call any of the below services to obtain the IP address:

- nx\_dns\_ipv4\_address\_by\_name\_get
- nxd\_dns\_ipv6\_address\_by\_name\_get
- nx\_dns\_cname\_get

For nx\_dns\_ipv4\_address\_by\_name\_get and nxd\_dns\_ipv6\_address\_by\_name\_get, NetX BSD uses the ipv4\_addr\_buffer and ipv6\_addr\_buffer memory areas respectively. The size of these buffers are defined by (NX\_BSD\_IPV4\_ADDR\_PER\_HOST \* 4) and (NX\_BSD\_IPV6\_ADDR\_PER\_HOST \* 16) respectively.

For returning address information from *getaddrinfo*, NetX BSD uses the ThreadX block memory table nx\_bsd\_addrinfo\_pool\_memory, whose memory area is defined by another set of configurable options, NX\_BSD\_IPV4\_ADDR\_MAX\_NUM and NX\_BSD\_IPV6\_ADDR\_MAX\_NUM.

See **General Configuration Options** for more details on the above configuration options.

Additionally, if NX\_DNS\_ENABLE\_EXTENDED\_RR\_TYPES is defined, and the host input is a canonical name, NetX Duo BSD will allocate memory dynamically from a previously created block pool \_nx\_bsd\_cname\_block\_pool

Note that after calling *getaddrinfo* the BSD application is responsible for releasing the memory pointed to by the res argument back to the block table using the *freeaddrinfo* service.

#### **NetX Duo BSD Limitations**

Due to performance and architecture issues, NetX Duo BSD does not support all the BSD 4.3 socket features:

INT flags are not supported for send, recv, sendto and recvfrom calls.

## **General Configuration Options**

User configurable options in *nxd\_bsd.h* allow the application to fine tune NetX Duo BSD sockets for its particular application requirements.

The following is the list of configurable options that are set at compile time:

Define	Meaning
NX_BSD_TCP_WINDOW	Used in TCP socket create calls. 64k is typical window size for 100Mb Ethernet. The default value is 65535.
NX_BSD_SOCKFD_START	This is the logical index for the BSD socket file descriptor start value. By default this option is 32.
NX_BSD_MAX_SOCKETS	Specifies the maximum number of total sockets available in the BSD layer and must be a multiple of 32. The value is defaulted to 32.
NX_BSD_SOCKET_QUEUE_MAX	Specifies the maximum number of UDP packets stored on the receive socket queue. The value is defaulted to 5.
NX_BSD_MAX_LISTEN_BACKLOG	This specifies the size of the listen queue ('backlog') for BSD TCP sockets. The default value is 5.

NX\_MICROSECOND\_PER\_CPU\_TICK Specifies the number of

microseconds per scheduler

timer tick

NX\_BSD\_TIMEOUT Specifies the timeout in timer

ticks on NetX Duo internal calls required by BSD. The default value is (20 \* NX\_IP\_PERIODIC\_RATE).

NX\_BSD\_TCP\_SOCKET\_DISCONNECT\_TIMEOUT

Specifies the timeout in timer ticks on NetX Duo disconnect call. The default value is 1.

NX\_BSD\_PRINT\_ERRORS If set, the error status return of a

BSD function returns a line number and type of error e.g. NX\_SOC\_ERROR where the error occurs. This requires the application developer to define the debug output. The default setting is disabled and no debug output is specified in *nxd\_bsd.h* 

NX BSD TIMER RATE Interval after which BSD periodic

timer task runs. The default

value is 1 second (1 \* NX\_IP\_PERIODIC\_RATE).

NX\_BSD\_TIMEOUT\_PROCESS\_IN\_TIMER If set, this option allows the BSD

timeout process to execute in the system timer context. The default behavior is disabled. This feature is described in more detail in Chapter 2 "Installation and Use of

NetX Duo BSD".

NX BSD RAW PPPOE SUPPORT Enable PPPoE raw packet

support. By default this option is

not enabled.

NX\_BSD\_ENABLE\_DNS If enabled, NetX Duo BSD will

send a DNS query for a hostname or host IP address. Requires a DNS Client instance to be previously created and

started. By default it is not enabled.

#### NX\_BSD\_SOCKET\_RAW\_PROTOCOL\_TABLE\_SIZE

Defines the size of the raw socket table. The value must be a power of two. NetX BSD creates an array of sockets of type NX\_BSD\_SOCKETS for sending and receiving raw packets. NX\_ENABLE\_IP\_RAW\_PACKET\_\_FILTER must be enabled. By default it is 32.

NX BSD IPV4 ADDR MAX NUM

Maximum number of IPv4 addresses returned by *getaddrinfo*. This along with NX\_BSD\_IPv6\_ADDR\_MAX\_NUM defines the size of the NetX BSD block pool nx\_bsd\_addrinfo\_block\_pool for dynamically allocating memory to address information storage in *getaddrinfo*. The default value is 5.

NX\_BSD\_IPV6\_ADDR\_MAX\_NUM

Maximum number of IPv6 addresses returned by *getaddrinfo*. This along with NX\_BSD\_IPv4\_ADDR\_MAX\_NUM defines the size of the NetX BSD block pool nx\_bsd\_addrinfo\_block\_pool for dynamically allocating memory to address information storage in *getaddrinfo*.

NX\_BSD\_IPV4\_ADDR\_PER\_HOST

Defines maximum IPv4 addresses stored per DNS query. The default value is 5.

NX BSD IPV6 ADDR PER HOST

Defines maximum IPv6 addresses stored per DNS query. The default value is 2.

### **BSD Socket Options**

The following list of NetX Duo BSD socket options can be enabled (or disabled) at run time on a per socket basis using the *setsockopt* service:

There are two different settings for option\_level.

The first type of run time socket options is SOL\_SOCKET for socket level options. To enable a socket level option, call *setsockopt* with option\_level set to SOL\_SOCKET and option\_name set to the specific option e.g. SO\_BROADCAST. To retrieve an option setting, call *getsockopt* for the option\_name with option\_level again set to SOL\_SOCKET.

The list of run time socket level options is shown below.

SO BROADCAST	If set, this enables sending and
	,

receiving broadcast packets from Netx sockets. This is the default behavior for NetX Duo. All sockets have this capability.

SO\_ERROR Used to obtain socket status on

the previous socket operation of the specified socket, using the getsockopt service. All sockets

have this capability.

SO\_KEEPALIVE If set, this enables the TCP Keep

Alive feature. This requires the NetX Duo library to be built with NX\_TCP\_ENABLE\_KEEPALIVE defined in *nx\_user.h*. By default

this feature is disabled.

SO RCVTIMEO This sets the wait option in

seconds for receiving packets on

NetX Duo BSD sockets. The

default value is the NX\_WAIT\_FOREVER

(0xFFFFFFF) or, if non-blocking is enabled, NX\_NO\_WAIT (0x0).

SO RCVBUF

This sets the window size of the TCP socket. The default value, NX BSD TCP WINDOW, is set to 64k for BSD TCP sockets. To set the size over 65535 requires the NetX Duo library to be built

with the

NX\_TCP\_ENABLE\_WINDOW\_SCALING

be defined.

SO REUSEADDR

If set, this enables multiple sockets to be mapped to one port. The typical usage is for the TCP Server socket. This is the default behavior of NetX Duo

sockets.

The second type of run time socket options is the IP option level. To enable an IP level option, call setsockopt with option\_level set to IP\_PROTO and option\_name set to the option e.g. IP\_MULTICAST\_TTL. To retrieve an option setting, call getsockopt for the option\_name with option\_level again set to IP\_PROTO.

The list of run time IP level options is shown below.

IP\_MULTICAST\_TTL

This sets the time to live for UDP sockets. The default value is NX\_IP\_TIME\_TO\_LIVE (0x80) when the socket is created. This value can be overridden by calling setsockopt with this socket option.

IP\_RAW\_IPV6\_HDRINCL

If this option is set, the calling application must append an IPv6 header and optionally application headers to data being transmitted on raw IPv6 sockets created by BSD. To use this option, raw socket processing must be enabled on the IP task.

IP\_ADD\_MEMBERSHIP

If set, this options enables the BSD socket (applies only to UDP sockets) to join the specified IGMP group.

IP DROP MEMBERSHIP

If set, this options enables the BSD socket (applies only to UDP sockets) to leave the specified IGMP group.

IP HDRINCL

If this option is set, the calling application must append the IP header and optionally application headers to data being transmitted on raw IPv4 sockets created in BSD. To use this option, raw socket processing must be enabled on the IP task.

IP\_RAW\_RX\_NO\_HEADER

If cleared, the IPv6 header is included with the received data for raw IPv6 sockets created in BSD. IPv6 headers are removed by default in BSD raw IPv6 sockets, and the packet length does not include the IPv6 header.

If set, the IPv4 header is removed from received data on BSD raw sockets of type IPv4. IPv4 headers are included by default in BSD raw IPv4 sockets and packet length includes the IPv4 header.

This option has no effect on either IPv4 or IPv6 transmission data.

## **Small IPv4 Example**

An example of how to use NetX Duo BSD services for IPv4 networks is described below. In this example, the include file *nxd\_bsd.h* is brought in at line 8. Next, the IP instance *bsd\_ip* and packet pool *bsd\_pool* are created as global variables at line 20 and 21. Note that this demo uses a ram (virtual) network driver, *\_nx\_ram\_network\_driver*. The client and server will share the same IP address on single IP instance in this example.

The client and server threads are created on lines 62 and 68. The BSD packet pool for transmitting packets is created on line 78 and used in the IP instance creation on line 87. Note that the IP thread task is given priority 1 in the *nx\_ip\_create* call. This thread should be the highest priority task defined in the program for optimal NetX performance.

The IP instance is enabled for ARP and TCP services on lines 88 and 110 respectively. The last requirement before BSD services can be used is to call *bsd\_initialize* on line 120 to set up all data structures and NetX and ThreadX resources needed by BSD.

The server thread entry function is defined next. The BSD TCP socket is created on line 149. The server IP address and port are set on lines 160-163. Note the use of host to network byte order macros *htonl* and *htons* applied to the IP address and port. This is in compliance with BSD socket specification that multi byte data is submitted to the BSD services in network byte order.

Next, the master server socket is bound to the port using the *bind* service on line 166. This is the listening socket for TCP connection requests using the *listen* service on line 180. From here the server thread function, *thread\_server\_entry*, loops to check for receive events using the *select* call on line 202. If a receive event is a connection request, which is determined by comparing the read ready list, it calls *accept* on line 213. A child server socket is assigned to handle the connection request and added to the master list of TCP server sockets connected to a Client on line 223. If there are no new connection requests, the server thread then checks all the currently connected sockets for receive events in the for loop starting on line 236. When a receive event waiting is detected, it calls *send* and *recv* on that socket until no data is received (connection closed on the other side) and the socket is closed using the *soc\_close* service on line 277.

After the server thread sets up, the Client thread entry function, thread\_client\_entry, creates a socket on line 326 and connects with the TCP server socket using the connect call on line 337. It then loops to send and receive packets using the send and rece services respectively. When no more data is received, it closes the socket on line 398 using the soc\_close service. After disconnection, the client thread entry function creates a new TCP socket and makes another connection request in the while loop started on line 321.

<sup>/\*</sup> This is a small demo of BSD Wrapper for the high-performance NetX Duo TCP/IP stack which uses standard BSD services for TCP connection, sending, and receiving using a simulated Ethernet driver. \*/

```
"tx_api.h"
     #include
                       "nx_api.h"
     #include
                       "nxd_bsd.h"
8
     #include
9
                        <string.h>
     #include
10
     #include
                        <stdlib̄.h>
11
12
13
     #define
                       DEMO_STACK_SIZE
                                             (16*1024)
     #define
                       SERVER_PORT
                                              87
14
15
16
     #define
                       CLIENT_PORT
     /* Define the ThreadX and NetX object control blocks... */
17
18
19
                       thread_server;
thread_client;
     TX_THREAD
     TX_THREAD
                       bsd_pool;
bsd_ip;
20
     NX_PACKET_POOL
21
22
     NX_IP
      23
     CHAR
        ABCDEFGHIJKLMNOPQRSTUVWXYZ<>ABCDEFGHIJKLMNOPQRSTUVWXYZ<>ABCDEFGHIJKLMNOPQR
        STUVWXYZ<>END";
              maxfd:
26
27
28
29
30
31
32
33
34
35
36
37
     /* Define the counters used in the demo application... */
                       error counter:
     /* Define fd_sets for the BSD server socket. */
     fd_set
                  master_list, read_ready;
     /* Define thread prototypes. */
                  thread_server_entry(ULONG thread_input);
thread_client_entry(ULONG thread_input);
     VOID
     VOID
38
39
40
     void
                  _nx_ram_network_driver(struct NX_IP_DRIVER_STRUCT *driver_req);
41
     /* Define main entry point. */
42
43
     int main()
44
     {
45
46
          /* Enter the ThreadX kernel. st/
47
48
49
         tx_kernel_enter();
50
51
52
53
54
55
56
57
59
60
     /* Define what the initial system looks like. */
             tx_application_define(void *first_unused_memory)
     void
     ČHAR
              *pointer;
             status;
     UINT
         /* Setup the working pointer. */
pointer = (CHAR *) first_unused_memory;
61
          /* Create a server thread. st/
         62
63
64
65
66
         pointer = pointer + DEMO_STACK_SIZE;
67
          /* Create a Client thread.
         68
69
71
         pointer = pointer + DEMO_STACK_SIZE;
72
73
74
75
76
77
         /* Initialize the NetX system. */
         nx_system_initialize();
         /* Create a BSD packet pool. */
         status = nx_packet_pool_create(&bsd_pool, "NetX BSD Packet Pool", 128, pointer, 16384);
78
79
         pointer = pointer + 16384;
         if (status)
```

```
81
82
              error_counter++;
83
              printf("Error in creating BSD packet pool\n!");
84
85
         86
87
89
90
91
92
93
          if (status)
          error_counter++;
94
95
96
              printf("Error creating BSD IP instance\n!");
          /* Enable ARP and supply ARP cache memory for BSD IP Instance */
status = nx_arp_enable(&bsd_ip, (void *) pointer, 1024);
pointer = pointer + 1024;
97
98
99
100
101
            Check ARP enable status. */
102
          if (status)
103
          {
              error_counter++;
printf("Error in Enable ARP \n");
104
105
106
          }
107
          /* Enable TCP processing for BSD IP instances. */
108
109
          status = nx_tcp_enable(&bsd_ip);
110
111
112
          /* Check TCP enable status. */
          if (status)
113
114
          {
115
              error_counter++;
116
              printf("Error in Enable TCP \n");
117
118
119
          /* Now initialize BSD Scoket Wrapper */
120
          status = bsd_initialize (&bsd_ip, &bsd_pool,pointer, 2048, 2);
121
     }
122
123
124
     /* Define the Server thread.
125
                  Server_Rcv_Buffer[100];
     CHAR
126
127
     VOID thread_server_entry(ULONG thread_input)
128
129
                  status, sock, sock_tcp_server;
actual_status;
Clientlen;
130
     INT
131
     ULONG
132
     INT
133
     TNT
134
     UINT
                   is_set = NX_FALSE;
135
                   sockaddr_in serverAddr;
     struct
136
     struct
                  sockaddr_in ClientAddr;
137
138
139
          tx_thread_sleep(100);
          status = nx_ip_status_check(&bsd_ip, NX_IP_INITIALIZE_DONE,
140
                                          &actual_status, 100);
141
          /* Check status... */
if (status != NX_SUCCESS)
142
143
144
          {
145
              return;
146
          }
147
148
          /* Create BSD TCP Socket */
          sock_tcp_server = socket(AF_INET, SOCK_STREAM, 0);
149
150
151
          if (sock_tcp_server == -1)
152
          {
153
              printf("Error on Server socket %d create \n", sock_tcp_server);
154
155
              return;
156
157
158
          printf("Server socket %d created\n", sock_tcp_server);
          /* Set the server port and IP address */
```

```
memset(&serverAddr, 0, sizeof(serverAddr));
serverAddr.sin_family = AF_INET;
serverAddr.sin_addr.s_addr = htonl(IP_ADDRESS(1,2,3,4));
160
161
162
163
           serverAddr.sin_port = htons(SERVER_PORT);
164
165
           /* Bind this server socket */
          166
168
           if (status < 0)
169
170
171
               printf("Error on Server Socket %d Bind \n", sock_tcp_server);
172
173
174
175
           FD_ZERO(&master_list);
           FD_ZERO(&read_ready);
176
177
          FD_SET(sock_tcp_server,&master_list);
maxfd = sock_tcp_server;
178
179
          /* Now listen for any client connections for this server socket */
status = listen (sock_tcp_server, 5);
if (status < 0)</pre>
180
181
182
183
184
               printf("Error on Server Socket %d Listen\n", sock_tcp_server);
               return:
185
186
187
               printf("Server socket %d listen complete\n", sock_tcp_server);
188
           /* All set to accept client connections */
189
190
           /* Loop to create and establish server connections. */
191
192
          while(1)
193
194
195
               printf("\n");
196
197
               read_ready = master_list;
198
199
               tx_thread_sleep(20);
                                           /* Allow some time to other threads too */
200
201
202
               /* Let the underlying TCP stack determine the timeout. */
status = select(maxfd + 1, &read_ready, 0, 0, 0);
203
               if ((status == 0xffffffff) || (status == 0))
205
206
207
                    printf("Error with select. Status 0x%x\n", status);
208
209
                    continue;
210
               }
211
212
                /* Check for a connection request. */
213
               is_set = FD_ISSET(sock_tcp_server, &read_ready);
214
215
216
217
               if(is_set)
218
                    Clientlen = sizeof(ClientAddr);
219
220
                    sock = accept(sock_tcp_server,(struct sockaddr*)&ClientAddr,
                                     &Clientlen);
221
222
                     /* Add this new connection to our master list */
223
                    FD_SET(sock, &master_list);
224
225
                    if ( sock > maxfd)
226
227
228
                         maxfd = sock;
229
230
231
                    continue;
232
               }
233
234
               /* Check the set of 'ready' sockets, e.g connected to remote host and
               waiting for notice of packets received. */
for (i = NX_BSD_SOCKFD_START; i < (maxfd+1+NX_BSD_SOCKFD_START); i++)</pre>
235
```

```
239
240
                 241
242
243
244
                     while(1)
245
246
247
                          status = recv(i, (VOID *)Server_Rcv_Buffer, 100, 0);
248
249
                          if (status == 0)
250
251
                              break;
253
254
                          else if (status == NX_SOC_ERROR)
255
256
                              printf("Error on Server receiving data from Client on socket %d\n", i);
                              break;
258
259
                         }
                         260
261
262
263
                          status = send(i, "Hello\n", strlen("Hello\n")+1, 0);
264
265
                          if (status == NX_SOC_ERROR)
266
267
                              268
269
270
                         }
else
271
                              printf("Server socket %d message sent to Client: Hello\n", i);
272
                          }
274
275
                     }
276
                      /* Close this socket */
                     status = soc_close(i);
                      if (status != NX_SOC_ERROR)
281
                          printf("Server socket %d closed \n", i);
282
283
284
                     else
285
                          printf("Error on closing Server socket %d \n", i);
286
                     }
287
                 }
288
             }
289
290
             /* Loop back to check any next client connection */
291
         }
292
293
     }
294
                 Client_Rcv_Buffer[100];
     CHAR
295
296
     VOID thread_client_entry(ULONG thread_input)
297
298
299
     TNT
                 status;
                 sock_tcp_client, length;
300
     INT
                 sockaddr_in echoServAddr;
sockaddr_in localAddr;
301
     struct
302
     struct
303
304
305
         /* Let the server side get set up. */
306
         tx_thread_sleep(200);
307
308
         /* Set local port for displaying IP address and port. */
         memset(&localAddr, 0, sizeof(localAddr));
localAddr.sin_family = AF_INET;
localAddr.sin_addr.s_addr = htonl(IP_ADDRESS(1,2,3,4));
309
310
311
312
         localAddr.sin_port = htons(CLIENT_PORT);
313
         /* Set server port and IP address which we need to connect. */
         memset(&echoServAddr, 0, sizeof(echoServAddr));
```

```
echoServAddr.sin_family = AF_INET;
echoServAddr.sin_addr.s_addr = htonl(IP_ADDRESS(1,2,3,4));
316
317
318
         echoServAddr.sin_port = htons(SERVER_PORT);
319
320
         /* Now make client connections with the server. */
321
         while (1)
322
323
             printf("\n");
/* Create BSD TCP Socket */
324
325
326
             sock_tcp_client = socket( AF_INET, SOCK_STREAM, 0);
327
             if (sock_tcp_client == -1)
330
                 printf("Error on Client socket %d create \n", sock_tcp_client);
331
                 return;
332
             }
333
334
             printf("Client socket %d created\n", sock_tcp_client);
335
             336
337
338
             /* Check for error.
339
             if (status != OK)
340
341
342
343
344
345
346
                 printf("Error on Client socket %d connect\n", sock_tcp_client);
                 soc_close(sock_tcp_client);
                 return:
             /* Get and print source and destination information */
347
             printf("Client socket %d connected \n", sock_tcp_client);
348
349
350
             status = getsockname(sock_tcp_client, (struct sockaddr *)&localAddr,
                                   &length)
             351
352
353
             status = getpeername( sock_tcp_client,
                                                     (struct sockaddr *)
             &echoServAddr, &length);
printf("Remote port = %lu, Remote IP = 0x%x \n",
htonl(echoServAddr.sin_port),
354
                     htonl(echoServAddr.sin_addr.s_addr));
356
             /* Now receive the echoed packet from the server */
357
             while(1)
358
359
360
                 printf("Client sock %d sending packet to server\n",
                          sock_tcp_client);
361
                 status = send(sock_tcp_client, "Hello", (strlen("Hello")+1), 0);
362
363
364
                 if (status == ERROR)
365
366
                     printf("Error: Client Socket (%d) send \n", sock_tcp_client);
                 }
367
368
                 else
369
                     printf("Client socket %d sent message Hello\n",
370
                              sock_tcp_client);
                 }
372
373
                 status = recv(sock_tcp_client, (VOID *)Client_Rcv_Buffer,100,0);
374
375
                 if (status <= 0)
376
377
378
                     if (status < 0)
379
380
                          printf("Error on Client receiving on socket %d \n",
                                  sock_tcp_client);
382
                     élse
383
                          printf("Nothing received by Client on socket %d\n",
384
                                  sock_tcp_client);
385
                     }
386
```

```
387
388
389
390
391
                             break;
                       else
                             printf("Client socket %d received %d bytes: %s\n",
                                        sock_tcp_client,
strlen(Client_Rcv_Buffer), Client_Rcv_Buffer);
392
393
394
395
396
397
400
401
402
403
404
405
406
407
408
409
411
412
413
                        }
                  }
                  /* close this client socket */
status = soc_close(sock_tcp_client);
                  if (status != ERROR)
{
                        printf("Client Socket %d closed\n", sock_tcp_client);
                  }
else
{
                        printf("Error on Client Socket %d on close \n", sock_tcp_client);
                  }
                  /* Make another Client connection...*/
            }
      }
```

### Small IPv6 Example System

An example of how to use NetX Duo BSD services for IPv6 networks is described in the program below. This example is very similar to the IPv4 demo program previously described with a few important differences. The client and server threads, BSD packet pool, IP instance and BSD initialization happens as it does for IPv4 BSD sockets.

In the server thread entry function, *thread\_server\_entry*, defines a couple IPv6 variables using *sockaddr\_in6* and *NXD\_ADDRESS* data types on lines 145-148. The NXD\_ADDRESS data type can actually store both IPv4 and IPv6 address types.

Next, the server thread enables IPv6 and ICMPv6 on the IP instance using the *nxd\_ipv6\_enable* and *nxd\_icmpv6\_enable* service respectively on line 161 and 169. Next, the link local and global IP addresses are registered with the IP instance. This is done using the *nxd\_ipv6\_address\_set* service on lines 180 and 195. It then sleeps long enough for the IP thread task to complete the Duplicate Address Detection protocol and register these addresses as valid addresses on the *tx\_thread\_sleep* call on line 201.

Next, the TCP server socket is created with the AF\_INET6 socket type input argument on line 204. The socket IPv6 address and port are set on lines 216-221, again noting the use of *htonl* and *htons* macros to put data in network byte order for BSD socket services. From here on, the server thread entry function is virtually identical to the IPv4 example.

The client thread entry function, *thread\_client\_entry*, is defined next. Note that because the TCP client in this example shares the same IP instance and IPv6 address as the TCP server, we do not need to enable IPv6 or ICMPv6 services on the IP instance again. Further, the IPv6 address is also already registered with the IP instance. Instead, the client thread entry function simply waits on line 368 for the server to set up. The server address and port are set, using the host to network byte order macros on lines 387-392, and then the Client can connect with the TCP server on line 412. Note that the local IP address data types in lines 378-383 are used only to demonstrate the *getsockname* and *getpeername* services on lines 425 and 434 respectively. Because the data is coming from the network, the network to host byte order macros as used in lines 378-383.

Next the client thread entry function enters a loop in which it creates a TCP socket, makes a TCP connection and sends and receives data with the TCP server until no more data is received virtually the same as the IPv4 example. It then closes the socket on line 483, pauses briefly and creates another TCP socket and requests a TCP server connection.

One important difference with the IPv4 example is the *socket* calls specify an IPv6 socket using the AF\_INET6 input argument. Another important difference is that the TCP Client *connect* call takes an *sockaddr\_in6* data type and a length argument set to the size of the *sockaddr\_in6* data type.

```
/* This is a small demo of BSD Wrapper for the high-performance NetX Duo
      TCP/IP stack which uses standard BSD services for TCP connection,
      disconnection, sending, and receiving using a simulated Ethernet driver. */
5
6
7
     #include
                          "tx_api.h"
                          "nx_api.h"
     #include
,
8
9
                          "nxd_bsd.h"
     #include
                          <string.h>
<stdlib.h>
     #include
10
     #include
11
12
13
14
15
16
17
18
19
20
21
22
23
24
      #define
                          DEMO_STACK_SIZE
                                                   (16*1024)
      #define
                          SERVER_PORT
     #define
                          CLIENT PORT
      /* Define the ThreadX and NetX object control blocks... */
                          thread_server;
thread_client;
     TX THREAD
      TX_THREAD
     NX_PACKET_POOL
                          bsd_pool;
     NX_IP
                          bsd_ip;
      /* Define some global data. */
CHAR   *msg0 = "Client 1:
      CHAR
                           ABCDEFGHIJKLMNOPQRSTUVWXYZ<>ABCDEFGHIJKLMNOPQRSTUVWXYZ<>ABC
                           DEFGHIJKLMNOPQRSTUVWXYZ<>END";
     INT
                 maxfd;
25
26
27
28
29
      /* Define the counters used in the demo application... */
     ULONG
                          error_counter;
30
31
32
33
34
35
36
37
38
40
41
42
43
      /* Define fd_sets for the BSD server socket.
      fd_set
                          master_list, read_ready;
      /* Define thread prototypes. */
                    thread_server_entry(ULONG thread_input);
thread_client_entry(ULONG thread_input);
      VOID
                    _nx_ram_network_driver(struct NX_IP_DRIVER_STRUCT *driver_req);
     void
      /* Define main entry point. */
44
      int main()
45
46
47
           /* Enter the ThreadX kernel.
48
49
50
51
52
53
54
55
56
57
58
60
           tx_kernel_enter();
      /* Define what the initial system looks like. */
     void
               tx_application_define(void *first_unused_memory)
      ČHAR
               *pointer;
     UINT
               status;
           /* Setup the working pointer.
                        (CHAR *) first_unused_memory;
61
62
           /* Create a server thread. \,\,^*/
          tx_thread_create(&thread_server, "Server", thread_server_entry, 0, pointer, DEMO_STACK_SIZE, 8, 8,
63
64
                                TX_NO_TIME_SLICE, TX_AUTO_START);
66
67
          pointer = pointer + DEMO_STACK_SIZE;
           /* Create a Client thread. */
```

```
69
70
                             TX_NO_TIME_SLICE, TX_AUTO_START);
71
72
         pointer = pointer + DEMO_STACK_SIZE;
73
74
75
76
77
78
          /* Initialize the NetX system. */
         nx_system_initialize();
          /* Create a BSD packet pool. */
79
         status = nx_packet_pool_create(&bsd_pool, "NetX BSD Packet Pool",
                                            128, pointer, 16384);
80
          pointer = pointer + 16384;
81
          if (status)
82
83
         error_counter++;
84
              printf("Error in creating BSD packet pool\n!");
85
86
         87
88
89
90
91
92
93
94
95
96
97
         if (status)
              error_counter++;
              printf("Error creating BSD IP instance\n!");
98
         /* Enable ARP and supply ARP cache memory for BSD IP Instance */
status = nx_arp_enable(&bsd_ip, (void *) pointer, 1024);
99
100
         pointer = pointer + 1024;
101
102
          /* Check ARP enable status. */
         if (status)
103
104
         {
105
              error_counter++;
106
              print\overline{f}("Error in enable ARP on BSD IP instance\n");
107
108
109
         /* Enable TCP processing for BSD IP instances. */
110
111
         status = nx_tcp_enable(&bsd_ip);
112
         /* Check TCP enable status. */
if (status)
113
114
115
          {
              error_counter++;
printf("Error in Enable TCP \n");
116
117
118
         }
119
120
121
         /* Now initialize BSD Scoket Wrapper */
status = bsd_initialize(&bsd_ip, &bsd_pool,pointer, 2048, 2);
122
123
124
          /* Check BSD initialize status. */
         if (status)
125
126
127
         {
              error_counter++;
printf("Error in BSD initialize \n");
128
129
130
         pointer = pointer + 2048;
     }
131
132
133
134
     /* Define the Server thread. *,
                  Server_Rcv_Buffer[100];
135
     CHAR
136
137
     VOID thread_server_entry(ULONG thread_input)
138
139
140
                  status, sock,
actual_status;
141
     INT
                           sock, sock_tcp_server;
     ULONG
143
                  Clientlen;
     INT
144
     INT
145
     UINT
                   is_set = NX_FALSE;
     NXD_ADDRESS ip_address;
```

```
sockaddr_in6 serverAddr;
sockaddr_in6 ClientAddr;
      struct
148
      struct
149
      UINT
                       iface_index, address_index;
150
151
152
            status = nx_ip_status_check(&bsd_ip, NX_IP_INITIALIZE_DONE,
                                                   &actual_status, 100);
153
            /* Check status... */
if (status != NX_SUCCESS)
154
155
156
            {
157
158
159
                 return;
            }
160
            /* Enable IPv6 */
            status = nxd_ipv6_enable(&bsd_ip);
if((status != NX_SUCCESS) && (status != NX_ALREADY_ENABLED))
161
162
163
164
                  printf("Error with IPv6 enable 0x%x\n", status);
165
                  return;
166
            }
167
168
            /* Enable ICMPv6 */
169
170
            status = nxd_icmp_enable(&bsd_ip);
            if(status)
171
172
                  printf("Error with ECMPv6 enable 0x%x\n", status);
173
174
                  return;
            }
175
             /st Set the primary interface for our DNS IPv6 addresses. st/
176
            iface_index = 0;
177
178
            179
180
182
            if (status)
183
                 return;
184
185
            /* Set ip_0 interface address. */
ip_address.nxd_ip_version = NX_IP_VERSION_V6;
ip_address.nxd_ip_address.v6[0] = hton1(0x20010db8);
ip_address.nxd_ip_address.v6[1] = hton1(0x0000f101);
ip_address.nxd_ip_address.v6[2] = 0;
ip_address.nxd_ip_address.v6[3] = hton1(0x101);
186
187
188
189
190
191
192
            193
194
195
196
197
            if (status)
198
                  return;
199
200
            /* Wait for IPv6 stack to finish DAD process. */
tx_thread_sleep(400);
201
202
203
             /* Create BSD TCP Socket */
204
205
            sock_tcp_server = socket(AF_INET6, SOCK_STREAM, 0);
206
            if (sock_tcp_server == -1)
207
208
                  printf("\nError: BSD TCP Server socket create \n");
209
                  return;
210
211
212
            printf("\nBSD TCP Server socket created %lu \n", sock_tcp_server);
213
214
             ^{\prime st} Set the server port and IP address st
            memset(&serverAddr, 0, sizeof(serverAddr));
serverAddr.sin6_addr._S6_un._S6_u32[0] = htonl(0x20010db8);
serverAddr.sin6_addr._S6_un._S6_u32[1] = htonl(0xf101);
serverAddr.sin6_addr._S6_un._S6_u32[2] = 0x0;
serverAddr.sin6_addr._S6_un._S6_u32[3] = htonl(0x0101);
serverAddr.sin6_port = htons(SERVER_PORT);
215
216
217
218
219
220
221
            serverAddr.sin6_family = AF_INET6;
222
            /* Bind this server socket */
            status = bind(sock_tcp_server, (struct sockaddr *) &serverAddr,
```

```
sizeof(serverAddr));
225
226
          if (status < 0)
227
228
              printf("Error: Server Socket Bind \n");
229
230
231
232
          FD_ZERO(&master_list);
233
234
          FD_ZERO(&read_ready);
          FD_SET(sock_tcp_server,&master_list);
235
236
237
          maxfd = sock_tcp_server;
          /* Now listen for any client connections for this server socket */
238
          status = listen(sock_tcp_server, 5);
239
          if (status < 0)
240
241
              printf("Error: Server Socket Listen\n");
242
              return;
243
244
          else
245
              printf("Server Listen complete\n");
246
247
248
249
250
251
252
253
254
255
          /* All set to accept client connections */
printf("Now accepting client connections\n");
           * Loop to create and establish server connections. */
          while(1)
              printf("\n");
256
              read_ready = master_list;
257
258
              tx_thread_sleep(20); /* Allow some time to other threads too */
259
              /* Let the underlying TCP stack determine the timeout. */
status = select(maxfd + 1, &read_ready, 0, 0, 0);
260
261
262
263
              if ( (status == 0xffffffff) || (status == 0) )
264
265
266
267
                   printf("Error with select? Status 0x%x. Try again\n", status);
268
                   continue;
269
              }
271
               /* Detected a connection request. */
              is_set = FD_ISSET(sock_tcp_server,&read_ready);
274
              if(is_set)
275
276
277
                   Clientlen = sizeof(ClientAddr);
278
                   sock = accept(sock_tcp_server)
                                 (struct sockaddr*)&ClientAddr,
&Clientlen);
280
281
282
283
                   /* Add this new connection to our master list */
                   FD_SET(sock, &master_list);
284
                   if ( sock > maxfd)
285
                       printf("New connection %d\n", sock);
286
287
288
                       maxfd = sock;
                   }
289
290
291
                   continue;
292
              }
293
              /* Check the set of 'ready' sockets, e.g connected to remote host and
294
295
                 waiting for notice of packets received.
296
              for (i = NX_BSD_SOCKFD_START; i < (maxfd+1+NX_BSD_SOCKFD_START); i++)
297
298
                   299
301
                   {
```

```
304
                     while(1)
305
306
307
                         status = recv(i, (VOID *)Server_Rcv_Buffer, 100, 0);
308
309
                         if (status == 0)
310
311
                             printf("(Server socket %d received no data from
                                      Client)\n", i);
312
                             break;
313
314
                         else if (status == 0xffffffff)
315
                             317
                             break;
318
                         }
319
                         320
321
322
323
324
                         status = send(i, "Hello\n", strlen("Hello\n")+1, 0);
325
326
327
                         if (status == ERROR)
328
                             printf("Error on Server socket %d sending data to
                                      Client \n", i);
329
                         }
                         else
330
331
                             printf("Server socket %d message sent to Client:
332
                                     Hello\n", i);
333
                         }
334
                     }
335
336
                     /* Close this socket */
337
                     status = soc_close(i);
338
339
                     if (status != ERROR)
340
341
                         printf("Server socket %d closing\n", i);
                     }
                     élse
                     {
345
                         printf("Error on Server socket %d closing\n", i);
347
348
                 }
349
            }
350
351
352
             /* Loop back to check any next client connection */
         }
353
354
355
    }
    #define
                 CLIENT_BUFFER_SIZE
                                          100
356
357
358
    CHAR
                 Client_Rcv_Buffer[CLIENT_BUFFER_SIZE];
    VOID thread_client_entry(ULONG thread_input)
359
360
361
    TNT
                 status;
362
    INT
                 sock_tcp_client, length;
                 sockaddr_in6 echoServAddr6;
sockaddr_in6 localAddr6; address */
363
     struct
364
     struct
365
366
         /* Wait for the server side to get set up, including the DAD process. */
367
368
         tx_thread_sleep(500);
369
370
         /* ICMPv6 and IPv6 should already be enabled on the IP instance
371
            by the server thread entry function. */
372
373
        /* Further the IPv6 address is already established with the IP instance.
           so no need to wait for DAD completion. */
375
         /* Set local port and IP address (used only for getsockname call). */
         memset(&localAddr6, 0, sizeof(localAddr6));
```

```
localAddr6.sin6_addr._S6_un._S6_u32[0] = hton1(0x20010db8);
localAddr6.sin6_addr._S6_un._S6_u32[1] = hton1(0xf101);
localAddr6.sin6_addr._S6_un._S6_u32[2] = 0x0;
localAddr6.sin6_addr._S6_un._S6_u32[3] = hton1(0x0101);
localAddr6.sin6_port = htons(CLIENT_PORT);
378
379
380
381
382
383
              localAddr6.sin6_family = AF_INET6;
384
385
               /st Set Server port and IP address to connect to the TCP server. st/
             /* Set Server port and IP address to Connect to the ICP Server memset(&echoServAddr6, 0, sizeof(echoServAddr6)); echoServAddr6.sin6_addr._s6_un._s6_u32[0] = htonl(0x20010db8); echoServAddr6.sin6_addr._s6_un._s6_u32[1] = htonl(0xf101); echoServAddr6.sin6_addr._s6_un._s6_u32[2] = 0x0; echoServAddr6.sin6_addr._s6_un._s6_u32[3] = htonl(0x0101); echoServAddr6.sin6_port = htons(SERVER_PORT); echoServAddr6.sin6_family = AF_INET6;
386
387
388
389
390
391
392
393
394
               /* Now make client connections with the server. */
395
              while (1)
396
397
                    printf("\n");
/* Create BSD TCP Socket */
398
399
400
401
                    sock_tcp_client = socket(AF_INET6, SOCK_STREAM, 0);
402
403
                    if (sock_tcp_client == -1)
404
405
                           printf("Error on Client socket %d create \n");
406
                           return:
407
                    }
408
                    printf("Client socket %d created \n", sock_tcp_client);
409
410
                    /* Now connect this client to the server */
status = connect(sock_tcp_client, (struct sockaddr *)&echoServAddr6,
411
412
                                               sizeof(echoServAddr6));
413
414
                     /* Check for error.
415
                    if (status != NX_SOC_OK)
416
417
                           printf("Error on Client socket %d connect\n");
418
                           soc_close(sock_tcp_client);
419
420
421
                    }
/* Get and print source and destination information */
printf("Client socket %d connected \n", sock_tcp_client);
422
423
424
425
                    status = getsockname(sock_tcp_client, (struct sockaddr *)&localAddr6,
                                                     &length)
                    426
427
                                 ntohl(localAddr6.sin6_addr._s6_un._s6_u32[0]),
ntohl(localAddr6.sin6_addr._s6_un._s6_u32[1]),
ntohl(localAddr6.sin6_addr._s6_un._s6_u32[2]),
ntohl(localAddr6.sin6_addr._s6_un._s6_u32[3]));
428
429
430
431
432
                    433
434
435
436
                                 ntohl(echoservAddr6.sin6_addr._s6_un._s6_u32[0]),
ntohl(echoservAddr6.sin6_addr._s6_un._s6_u32[1]),
ntohl(echoservAddr6.sin6_addr._s6_un._s6_u32[2]),
ntohl(echoservAddr6.sin6_addr._s6_un._s6_u32[3]));
437
438
439
440
441
                     /* Now receive the echoed packet from the server */
442
443
                    while(1)
444
445
446
                           printf("Client sock %d sending packet to server\n",
                                       sock_tcp_client);
447
448
                           status = send(sock_tcp_client, "Hello", (strlen("Hello")+1), 0);
449
450
                           if (status == NX_SOC_ERROR)
451
                                 printf("Error on Client Socket (%d) send \n",
452
                                             sock_tcp_client);
453
                          }
```

```
454
455
                  else
{
                      printf("Client socket %d sent message: Hello\n",
456
                             sock_tcp_client);
457
                  }
458
459
                  if (status <= 0) {
460
461
462
463
464
                      if (status < 0)
465
                           \begin{array}{c} printf("\texttt{Error on Client receiving on socket \%d } \\ & \texttt{sock\_tcp\_client)}; \end{array} 
466
467
                      else
{
468
469
470
                          printf("Client received no data on socket %d\n",
                                   sock_tcp_client);
471
                      }
472
473
474
475
                      break;
                  }
else
{
476
477
                      478
479
480
481
                  }
              /* close this client socket */
482
483
             status = soc_close(sock_tcp_client);
484
485
             if (status != NX_SOC_ERROR)
486
              {
                  printf("Client Socket %d closed\n", sock_tcp_client);
487
             }
488
489
             else
490
491
             {
                  printf("Error on Client Socket %d on close \n", sock_tcp_client);
492
             }
493
494
              /* Make another Client connection...*/
495
496
         }
497
     }
498
499
```

# **Chapter 3**

## **NetX Duo BSD Services**

This chapter contains a description of all NetX Duo BSD basic services (listed below) in alphabetic order.

```
INT accept(INT sockID, struct sockaddr *ClientAddress, INT *addressLength);
INT bind (INT sockID, struct sockaddr *localAddress, INT addressLength);
INT bsd_initialize(NX_IP *default_ip, NX_PACKET_POOL *default_pool, CHAR
                 *bsd_thread_stack_area, ULONG bsd_thread_stack_size,
                 UINT bsd_thread_priority);
INT connect(INT sockID, struct sockaddr *remoteAddress, INT addressLength);
INT getpeername(INT sockID, struct sockaddr *remoteAddress, INT *addressLength);
INT getsockname(INT sockID, struct sockaddr *localAddress, INT *addressLength);
INT ioctl(INT sockID, INT command, INT *result);
in addr tinet addr(const CHAR *buffer);
INT inet_aton(const CHAR *cp_arg, struct in_addr *addr);
CHAR inet_ntoa(struct in_addr address_to_convert);
const CHAR *inet_ntop(INT af, const VOID *src, CHAR *dst, socklen_t size);
INT inet_pton(INT af, const CHAR *src, VOID *dst);
INT listen(INT sockID, INT backlog);
INT recvfrom(INT sockID, CHAR *buffer, INT buffersize, INT flags,
             struct sockaddr *fromAddr, INT *fromAddrLen);
INT recv(INT sockID, VOID *rcvBuffer, INT bufferLength, INT flags);
INT sendto(INT sockID, CHAR *msg, INT msgLength, INT flags,
            struct sockaddr *destAddr, INT destAddrLen);
INT send(INT sockID, const CHAR *msg, INT msgLength, INT flags);
INT select(INT nfds, fd set *readfds, fd set *writefds, fd set *exceptfds,
           struct timeval *timeout);
```

```
INT soc_close ( INT sockID);
INT socket(INT protocolFamily, INT type, INT protocol);
INT fcntl(INT sock_ID, UINT flag_type, UINT f_options);
INT getsockopt(INT sockID, INT option_level, INT option_name, VOID *option_value,
                INT *option_length);
INT setsockopt(INT sockID, INT option_level, INT option_name,
               const VOID *option_value, INT option_length);
INT getaddrinfo(const CHAR *node, const CHAR *service, const struct addrinfo *hints,
               struct addrinfo **res);
VOID freeaddrinfo(struct addrinfo *res);
INT getnameinfo(const struct sockaddr *sa, socklen_t salen, char *host,
                 size_t hostlen, char *serv, size_t servlen, int flags);
VOID nx_bsd_set_service_list(struct NX_BSD_SERVICE_LIST *serv_list_ptr,
                              ULONG serv_list_len);
VOID FD_SET(INT fd, fd_set *fdset);
VOID FD_CLR(INT fd, fd_set *fdset);
INT FD_ISSET(INT fd, fd_set *fdset);
VOID FD_ZERO (fd_set *fdset);
```